Ants Assembly Instructions

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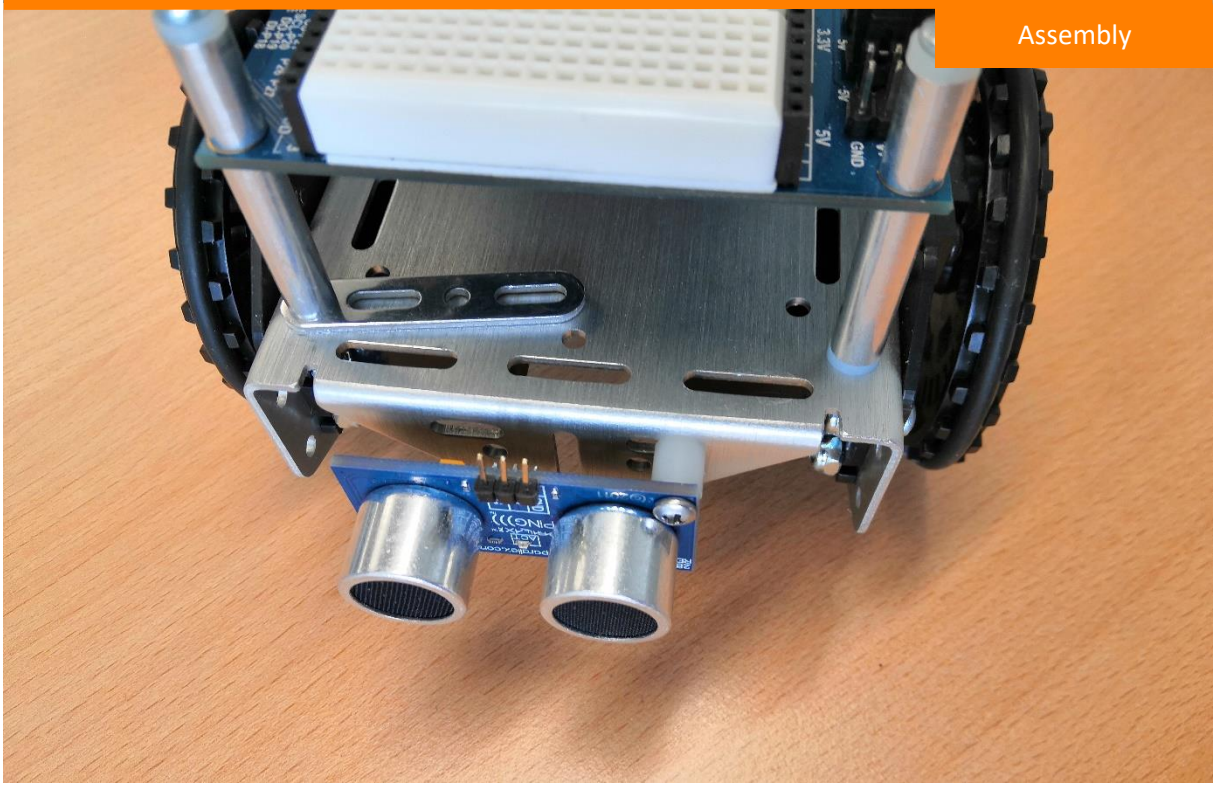
Bot in default state (incl. Pull-Up Resistor)

1. Preparation of the Ping-Sensor + Assembly

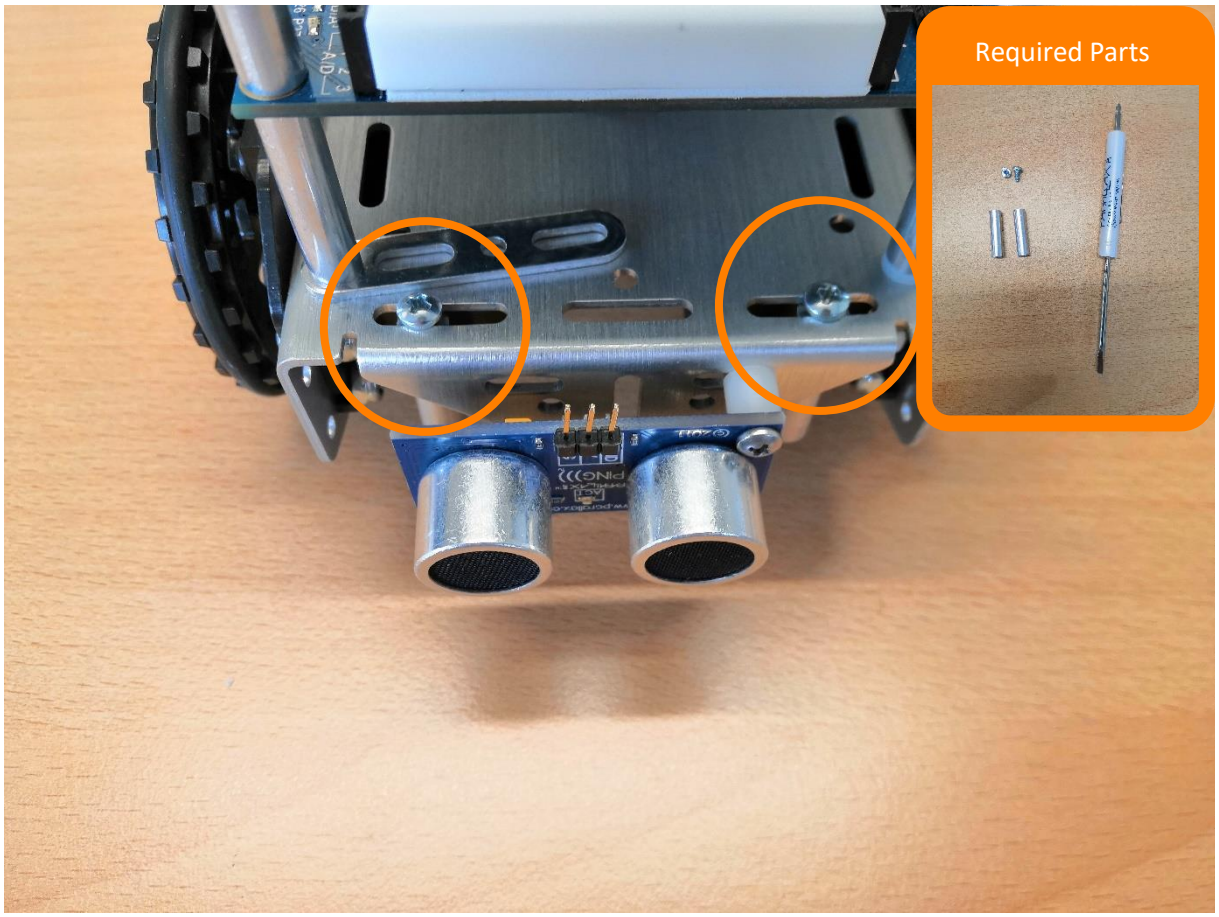
Required Parts



Assembly

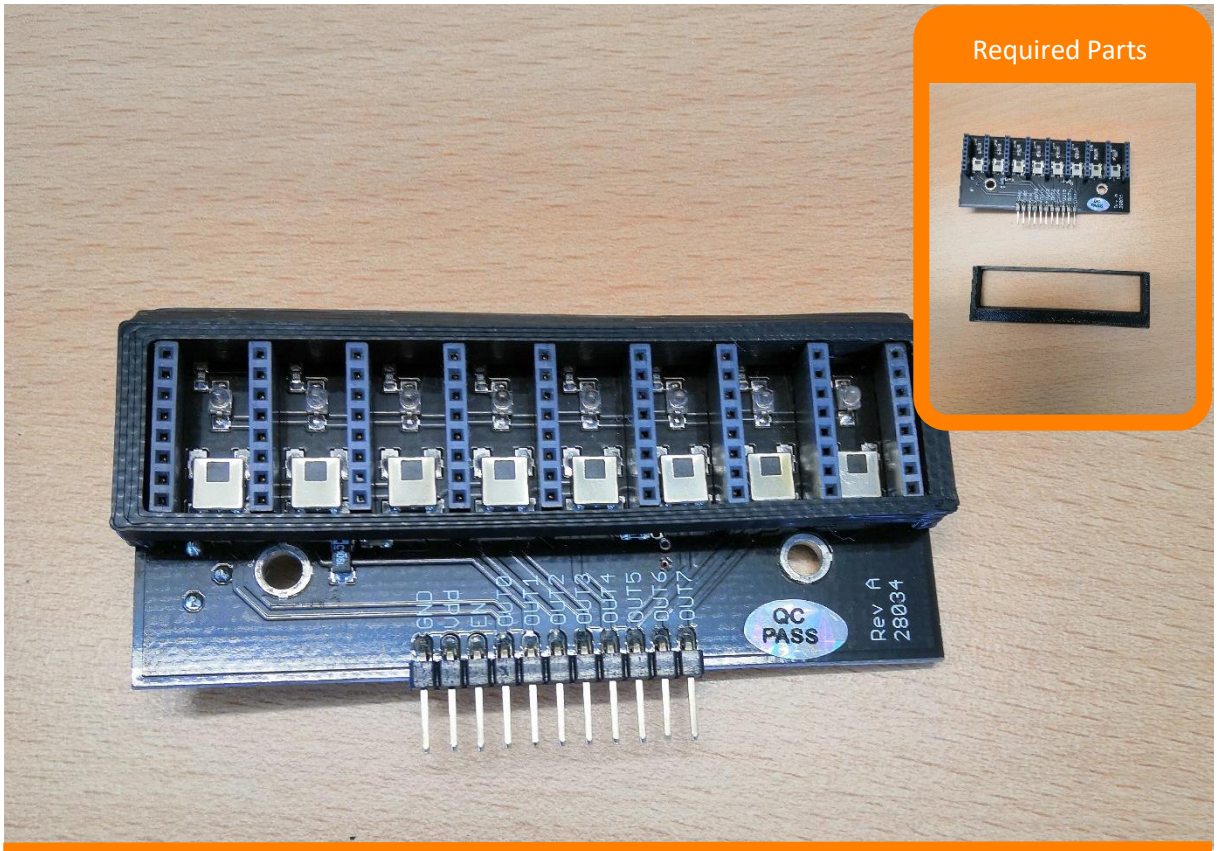
2. Bracket for Line-Follower

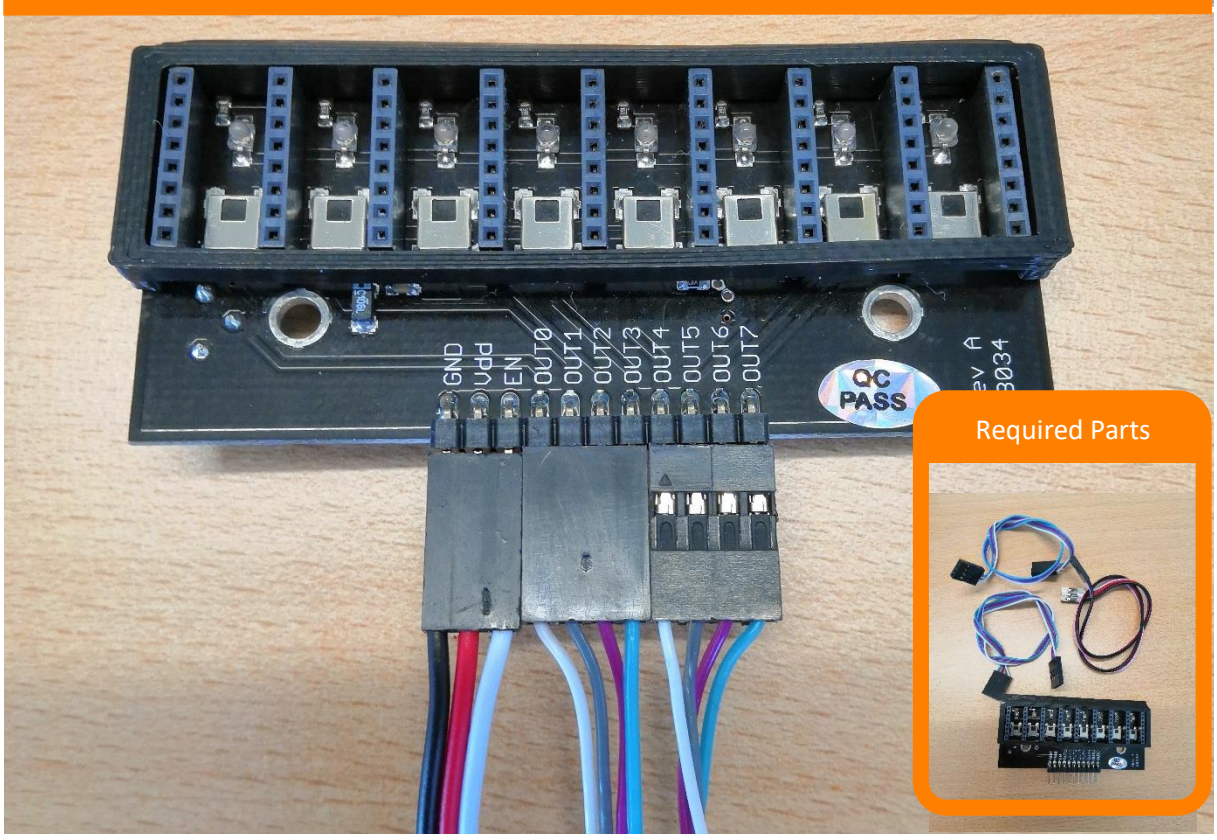
Don’t fully tighten screws yet!



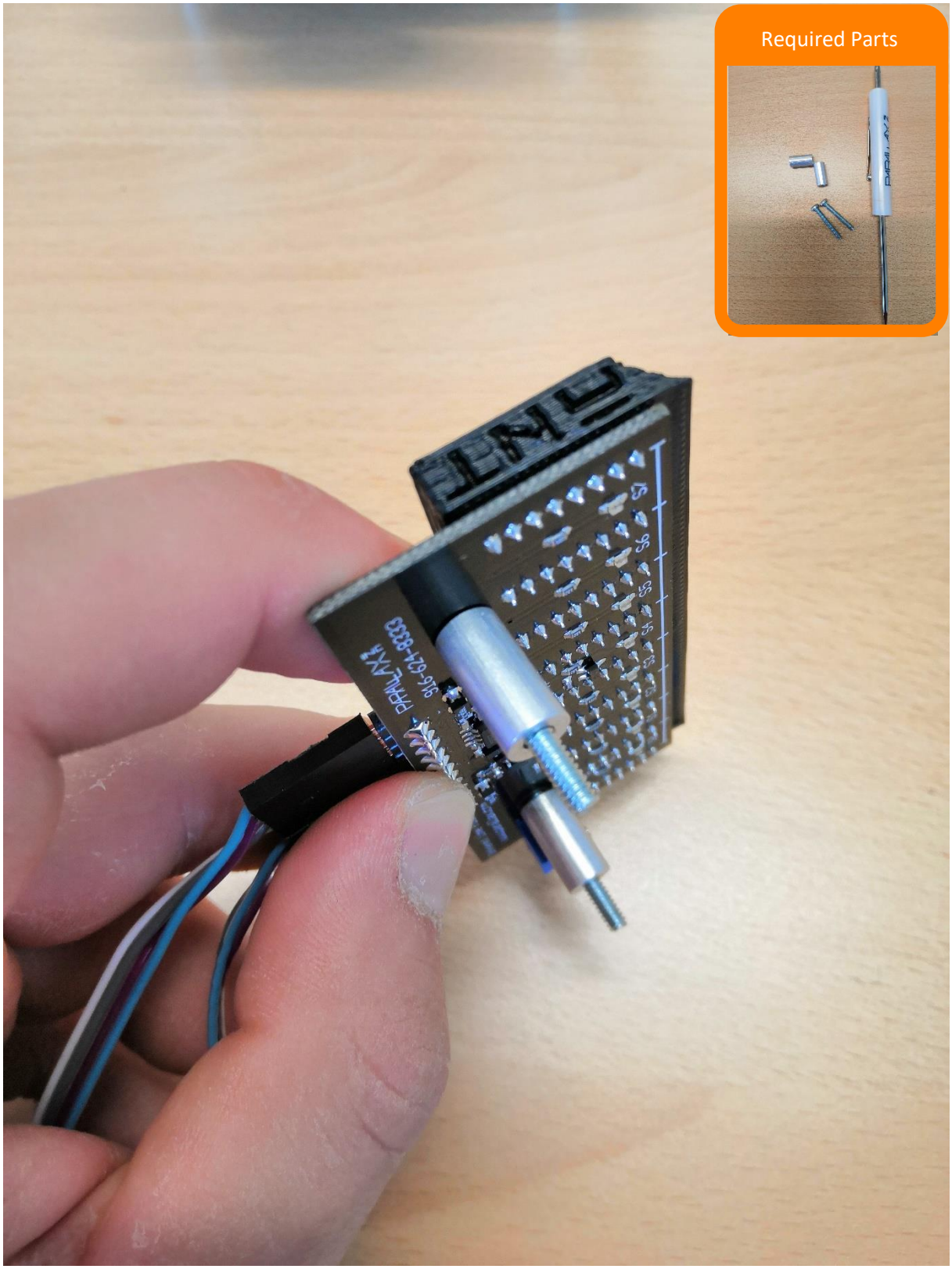
3. Preparation of the Line Follower

STL-file for 3D-printing the schield can be found in the *antshield*-directory

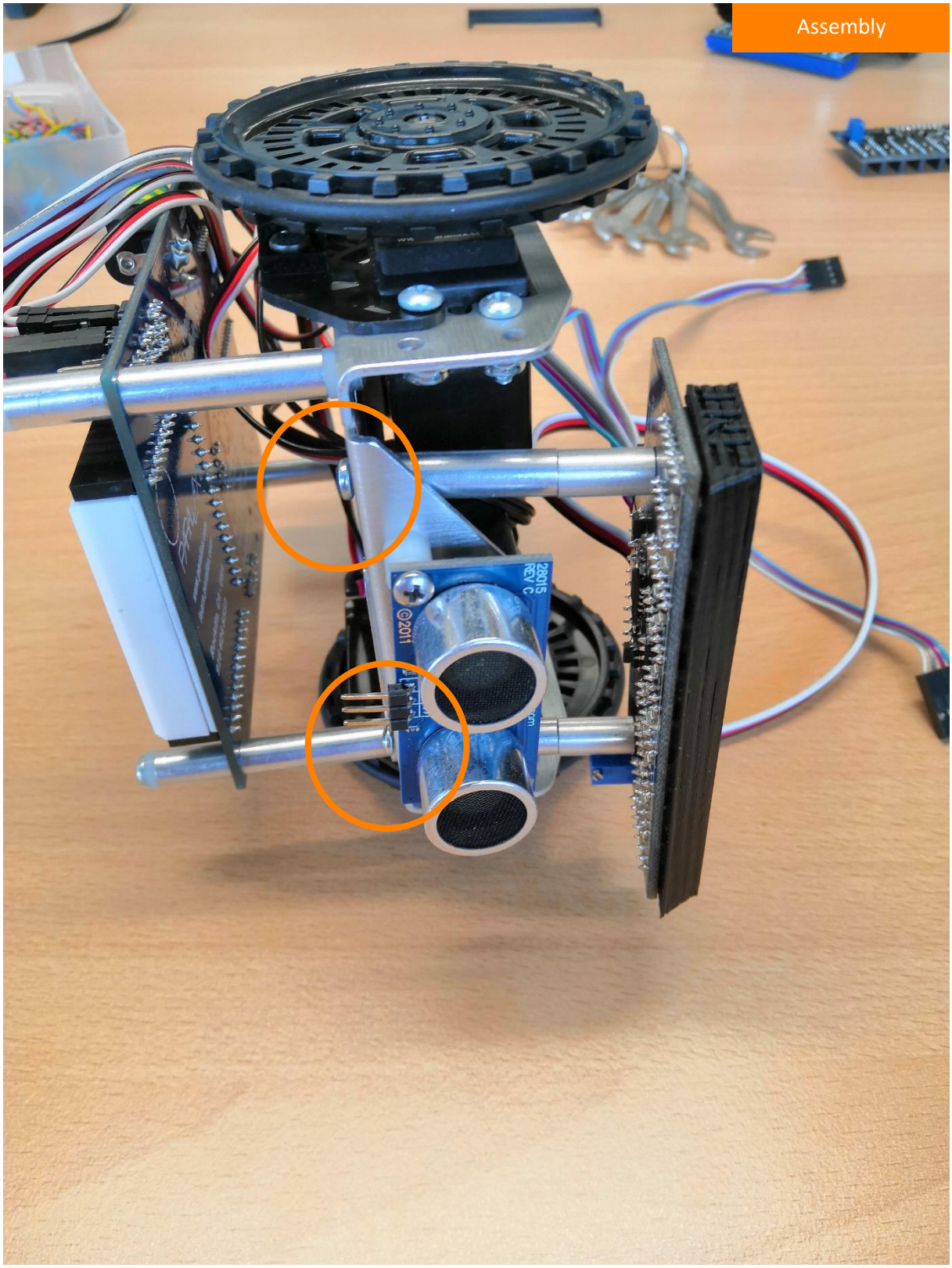




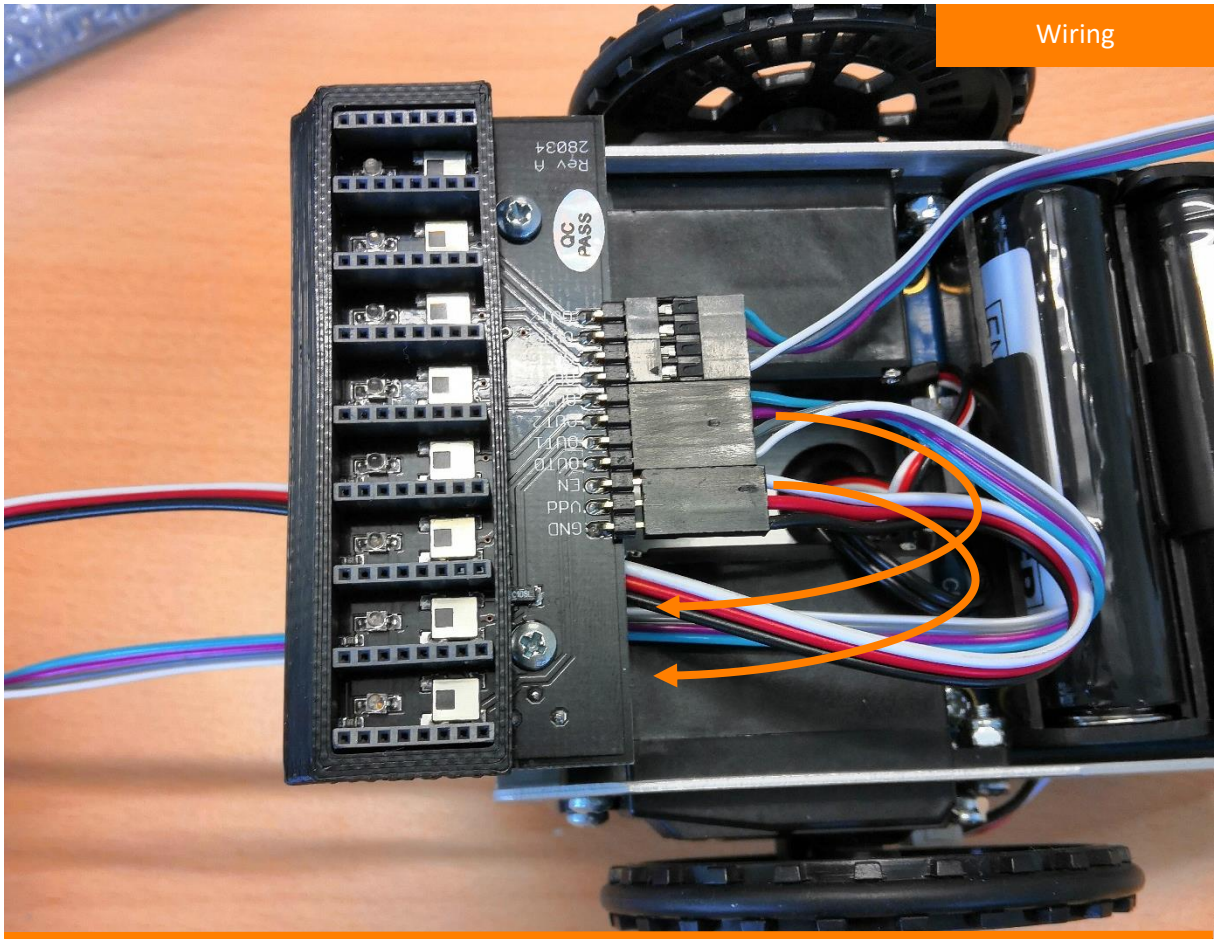
4. Assembly of the Line Follower

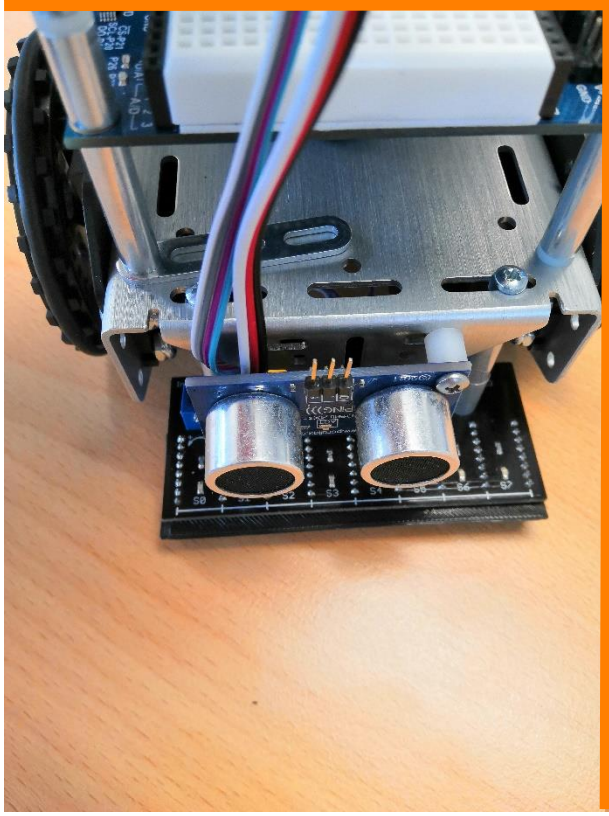


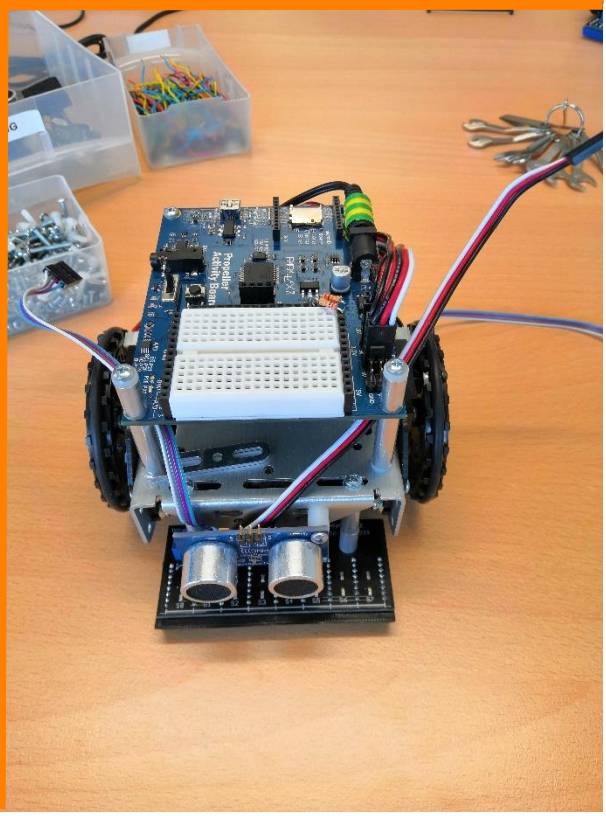
After the assembly the highlighted screws from step 2 can be fully tightened.



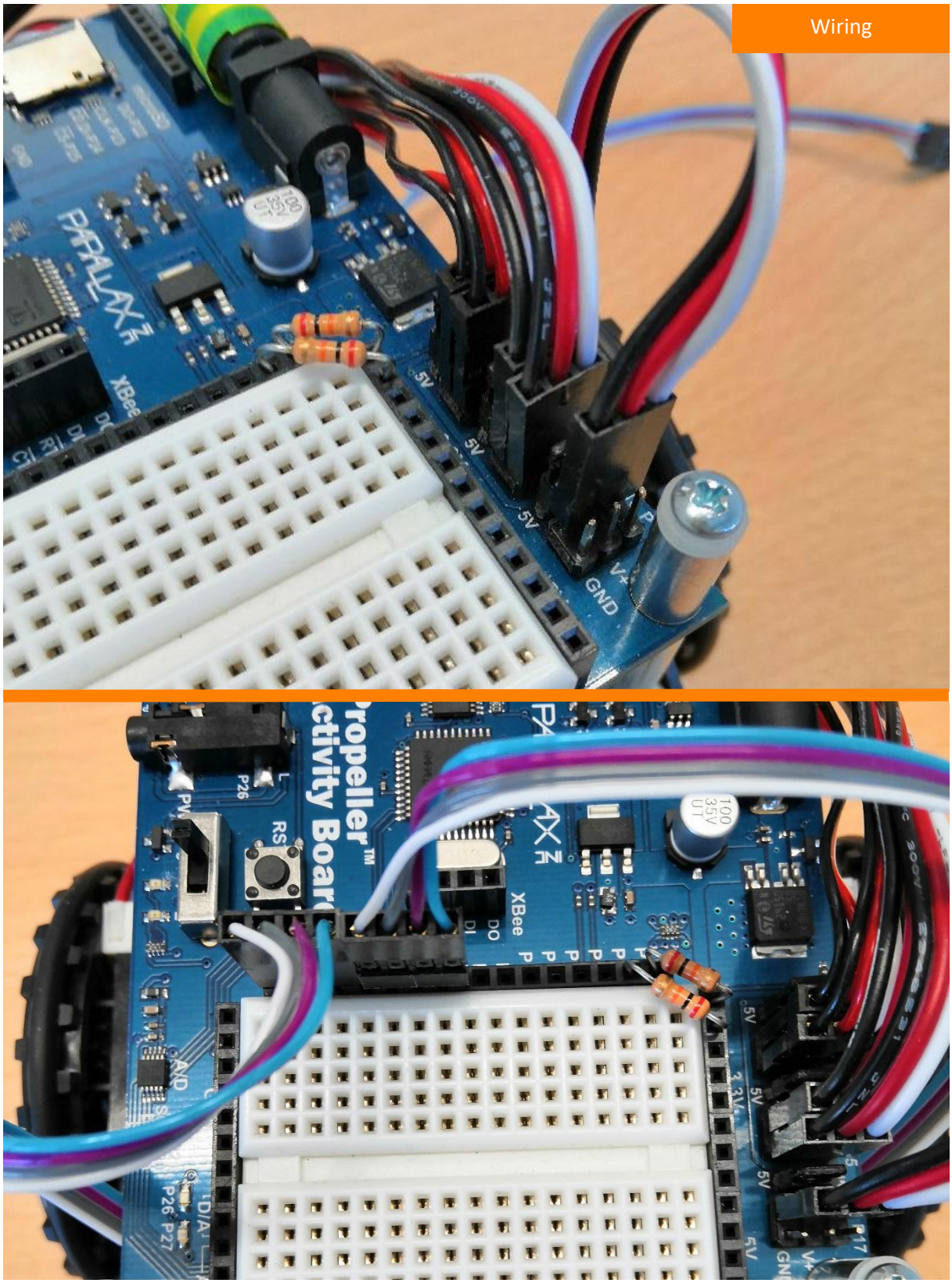
5. Wiring of the Line Follower





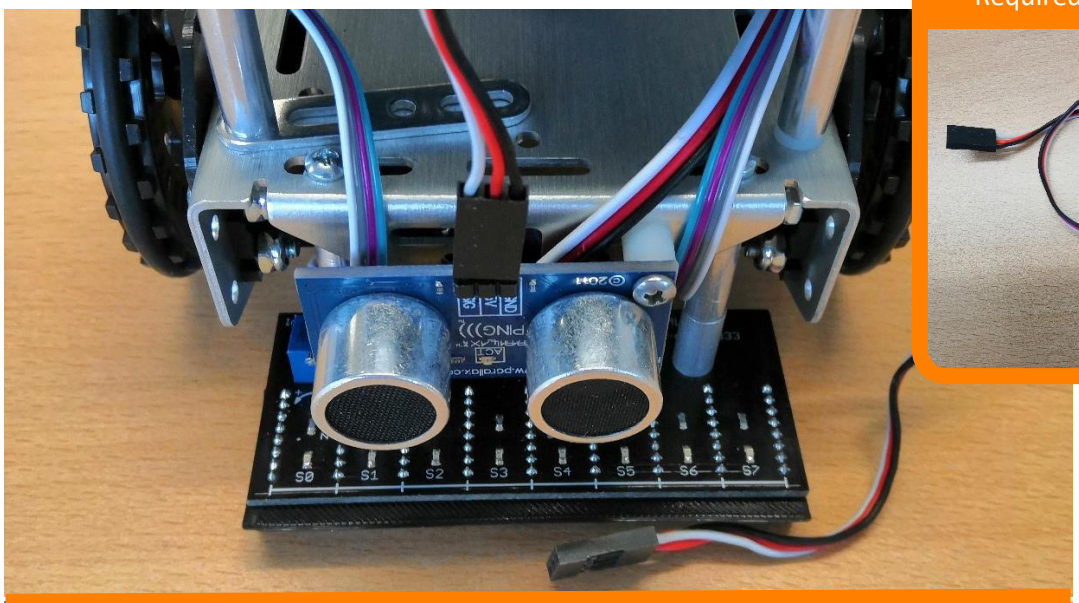


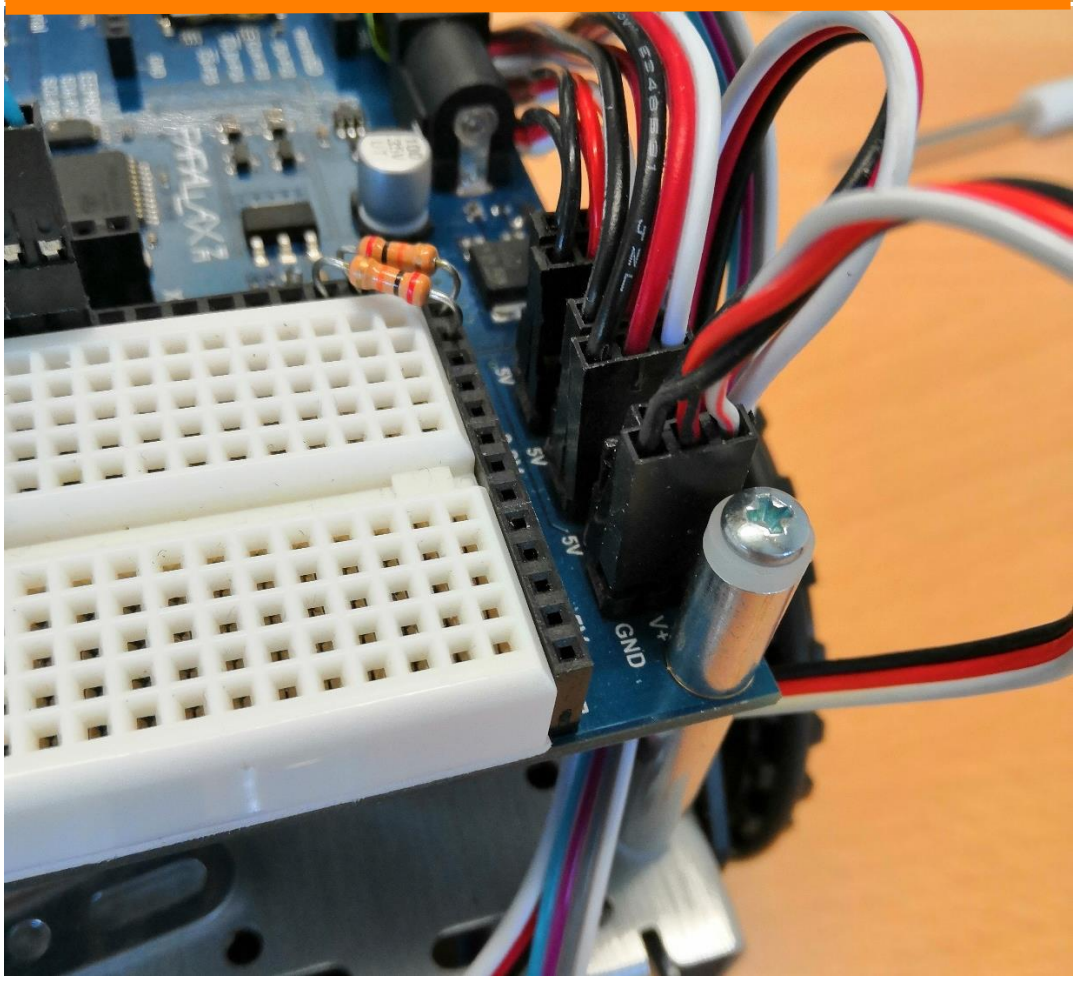
1. Connect powercable with 3pin wire to 5V delivery (Jumper has to be set to 5V)
2. Connect datacable to ports P0-P7 (S0 of the Line Followers into P0)

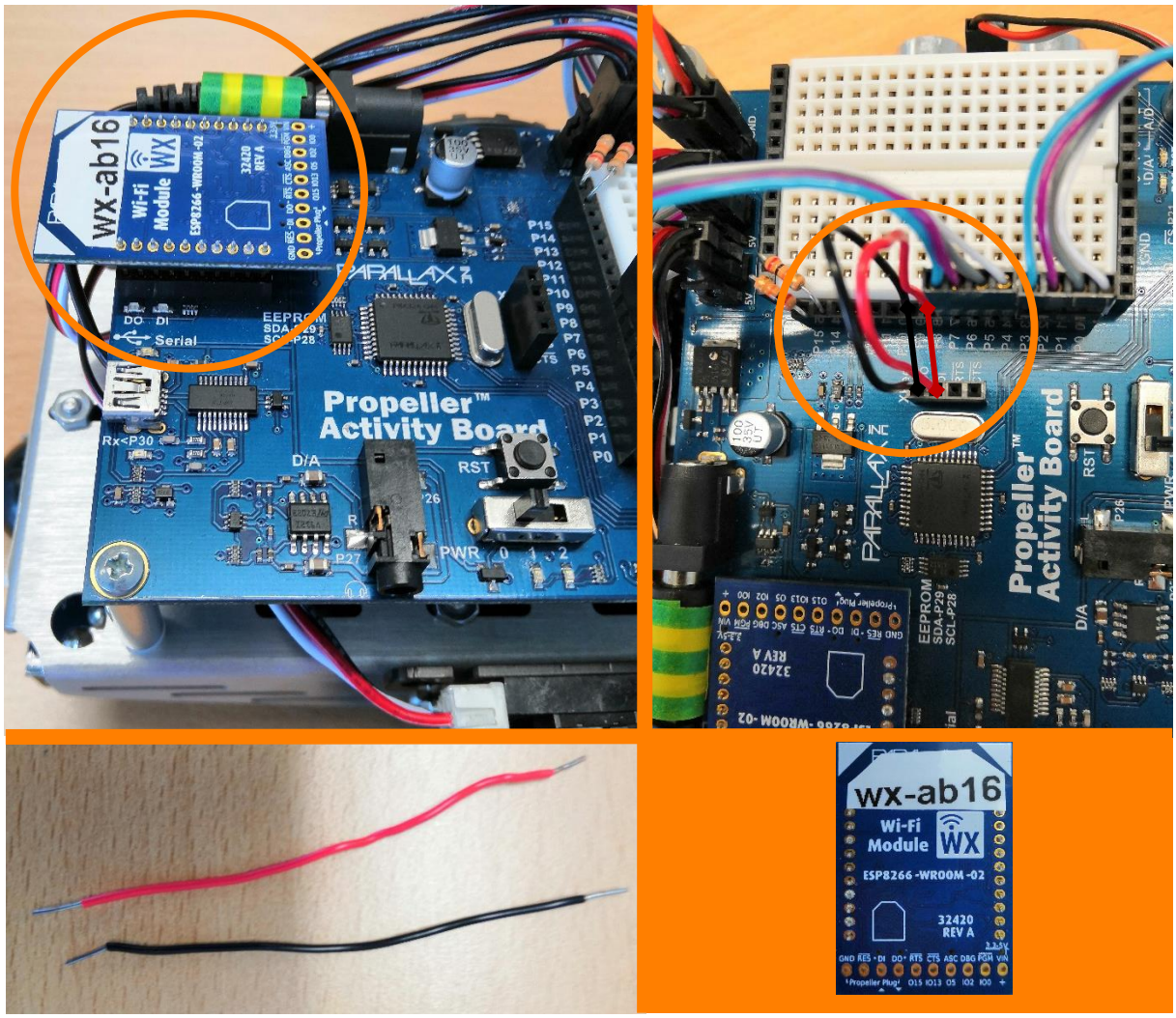


6. Wiring of the Ultrasonic Distance Sensor

Required Parts





7. Connection of the WiFi-Modul (ESP-8266)

1. WiFi-Module gets plugged on
2. Connect `DI` to `P8` and `DO` to `P9`
3. Change the settings oft he WiFi-Moduls to AP-Mode with the name & password of the WiFi-Network in the web-interface