

Solving Soft Constraint Problems in MiniBrass

Alexander Schiendorfer et al.



Decision Problems





"How many muffins of each kind?"



"Who performs which tasks?"



"When does which lecture take place?"



"What's up on the weekend?"



Decisions

- The number of chocolate or banana muffins
- The lectures in the curriculum.
- Friday and saturday activity



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Possibilities

- Chocolate muffins: $\{0, \dots, 20\}$
- Lecture "Algorithms 101": {LH1, LH2, LH3, ...}



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- There can only be one class per room (at a time).
- There can only be one all-you-can-eat buffet per weekend.



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- \bullet Bernd would like to have steaks, Ada prefers sushi \to Ada's preference is more important
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and/or

Goals

- Maximize the revenue of our chocolate/banana mix
- Maximize the number of lecture-free days
 - a constraint satisfaction (optimization) problem (CSP/COP), discrete if some decisions are over integers



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Goals (utility functions)

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- Maximize the number of lecture-free days

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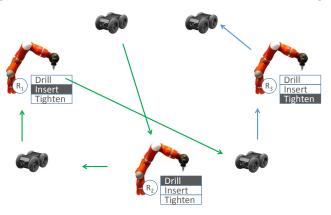


Adaptive production cells





Goal: Assign tasks to robots such that a correct resource flow emerges



(Seebach et al., 2010), SASO

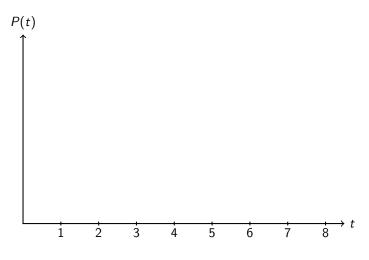


Decentralized energy management



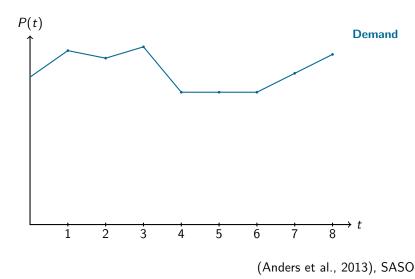


Goal: Schedule power plants such that they meet the demand

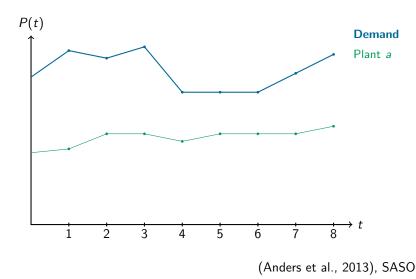


(Anders et al., 2013), SASO

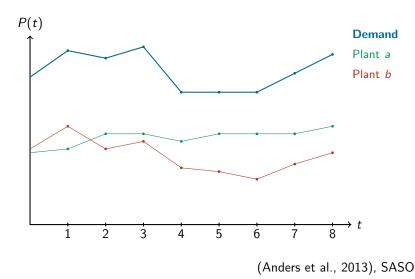




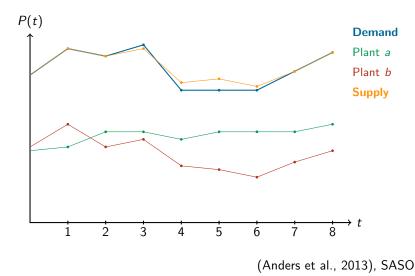




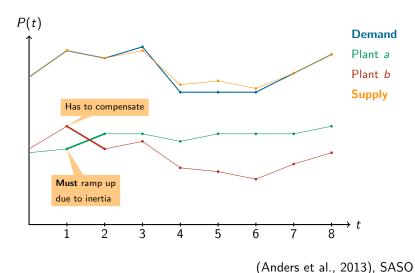




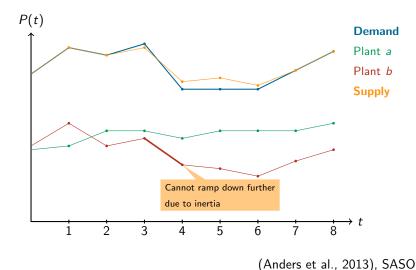




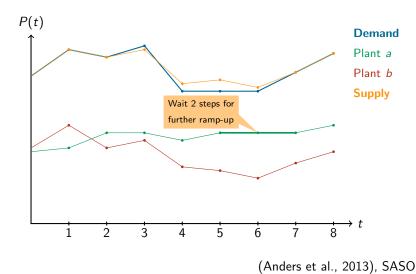






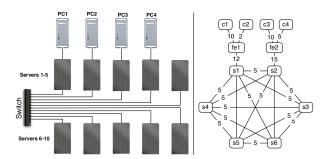








ESDS Deployment Problem (eventually serializable data services)



(Michel et al., 2008), CPAIOR

Why is it useful to you?



As a tool ...

- If you identify discrete optimization problems in your (self-organizing, autonomic, cloud) application, you can solve them with reliable tools.
- Modeling languages provide easy access to powerful solvers
- ullet o independent of the concrete technology (SAT, CSP, Mathematical Programming)

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As a research opportunity . . .

- Studying interactions of complex networks of optimizing agents offers interesting problems (*global systems science*)
- Integration of optimization problems into architectures for decision-making
- Solving large-scale problems by decomposition through self-organization

Soft Constraint Programming in MiniBrass



Constraint programming (first half of the tutorial)

- Declarative programming (similar to SQL, Prolog)
- Separation of model and algorithm
- Suitable for combinatorial problems with hard constraints (e.g. physics!)
- Modeling language MiniZinc

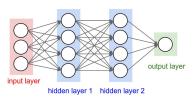
Soft constraint programming (second half of the tutorial)

- Modeling of user preferences
- Find solutions that are as good as possible
- What does "good" mean?
- Modeling language MiniBrass

Artificial Intelligence: Categories

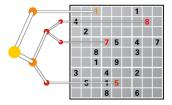


Data-driven Al



- Machine Learning
- Signal Processing
- Computer Vision

Decision-driven Al



- Constraint Programming
- Combinatorial Optimization
- Heuristic Optimization
- Planning / Scheduling

Our first model



```
var 0..2: x;
var 0..2: y;
constraint x < y;
solve maximize x + y;
```

http://www.minizinc.org

```
x = 1;
y = 2;
-----
```



```
var 0..2: x; % this notation is shorthand for the set {0,1,2}
var 0..2: y;
var 0..1: z; % {0,1}

% c1
constraint x != y /\ y != z /\ x != z;
% c2
constraint x + 1 = y;
solve satisfy;
```



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•
$$\Theta = \{(x \to 1, y \to 2, z \to ?), (x \to 0, y \to 1, z \to ?)\}$$
 satisfy c_2 ;



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- $(x \to 0, y \to 1, z \to ?)$ cannot be extended to a solution since z has to be 0 or $1 \to$ has to violate c_1



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- $\Theta = \{(x \to 1, y \to 2, z \to ?), (x \to 0, y \to 1, z \to ?)\}$ satisfy c_2 ;
- $(x \to 0, y \to 1, z \to ?)$ cannot be extended to a solution since z has to be 0 or $1 \to$ has to violate c_1
- Hence, the only solution is $(x \to 1, y \to 2, z \to 0)$

Why modeling?



- Once stated (formally) solved many times
 - · Constraint-Solving
 - SAT Boolean Satisfiability
 - MIP Mixed Integer Programming
 - Heuristic Optimization Genetic etc.
- 2 Efficient and reliable algorithms provided by solvers
 - · Same algorithms for a variety of different problems
 - Dedicated algorithms for recurring combinatorial substructures (alldifferent)
- Prototyping
 - Specification becomes much clearer
 - Bespoke algorithm for concrete problem can be developed later

Modeling in other CS domains



```
SELECT firstname, lastname
FROM employees
WHERE age < 30
```

instead of

```
Collection<Person> youngs = new ArrayList<>();
for(Person p : allEmployees) {
  if(p.getAge() < 30)
    youngs.add(p);
}</pre>
```

Motivation

Constraint modeling for optimization problems \approx SQL for database access

NP-Completeness



Theorem

The decision problem associated to a constraint satisfaction/optimization problem is NP-complete.

MY HOBBY: EMBEDDING NP-COMPLETE PROPLEMS IN RESTAURANT ORDERS





https://xkcd.com/287/

Why MiniZinc?



Rationale

One modeling language – many solvers

Supported solvers (selection)

- Gecode (CP)
- JaCoP (CP)
- Google Optimization Tools (CP)
- Choco (CP)
- G12 (CP/LP/MIP)



A relevant example . . .



```
var 0..100: b; % no. of banana muffins
var 0..100: c; % no. of chocolate muffins
% flour
constraint 250*b + 200*c <= 4000;
% bananas
constraint 2*b <= 6;</pre>
% sugar
constraint 75*b + 150*c <= 2000:
% butter
constraint 100*b + 150*c <= 500;</pre>
% cocoa
constraint 75*c <= 500;</pre>
% maximize our profit
solve maximize 400*b + 450*c;
output ["no. of banana muffins = ", show(b), "\n", \% b = 2
        "no. of chocolate muffins = ", show(c), "\n"]; % c = 2
```

Basic MiniZinc: Parameters and Variables



Parameters: input data for the problem, constants

```
int: n;
n = 3;
% equivalent to:
int: n = 3;
par int: n = 3;
% or with bounded domains
0..10: m; % a fixed value (input by a user) between 0 and 10
% set types
set of int: AGENTS = 1..n; % {1, ..., n}
```

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Decision Variables: variables to be assigned by a solver

```
var int: n;
var 0..10: x;
% immediate declaration (useful for dependent expressions)
var int: y = 2*x;
```

Basic MiniZinc: Arrays and Sets



Arrays: for parameters/variables of different sizes

```
int: n;
array[1..n] of int: height; % height[i] denotes the height of truck i
% also for decisions
array[1..n] of var bool: x; % x[i] holds if we select item i
% typical usage
set of int: ITEMS = 1..n;
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set of int: ITEMS = 1..n;
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Sets: set type for parameters and decisions (only set of int/subtype int)

```
set of int: AGENTS = 1..n;
set of int: CAP = 1..m;
array[AGENTS] of set of CAP: offers; % [{1}, {2}, {1,2}]

var set of AGENT: selectedTeam;
```

Basic MiniZinc: Types



Allowed primitive types for variables/parameters are

- Integer int or subtypes:
 - range 1..n
 - explicit set {1,5,7}
- Floating point number float or subtypes:
 - range 0.0 .. 1.0
 - explicit set {1.0, 2.5, 3.7}
- Boolean bool
- Arrays, Sets

Constraints, Objective and Output



Constraints: to restrict assignments

```
var 0..10: x; var 0..10: y; var 0..10: z;
constraint x + y = z;
constraint x mod 2 = 0;
% 'forall' concept for arrays
par int: n; array[1..n] of var 0..10: t;
% each t[i] should be even:
constraint forall(i in 1..n) (t[i] mod 2 = 0);
```

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Solve Item: provides the objective (one per model)

```
solve satisfy; % for a satisfaction problem
solve maximize sum(i in 1..n) (t[i]);
solve minimize x + y;
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String Output: one output item per model

```
var 0..10: x;
output ["The value of x is: \(x)"]
```

MiniZinc: HelloWorld



Exercise 1

Build a MiniZinc model xopt.mzn with a decision variable x taking values from 0 to 10, with constraints to ensures that x is divisible by 4, which outputs the value of x that gives the minimum value of $(x-7)^2$.

Test it using the precompiled IDE-bundle. Suppose you cannot use the mod function, how would you alternatively model that x is divisible by 4?

MiniZinc: Arrays



Exercise 2 Define a MiniZinc model array.mzn which takes an integer parameter *n* defining the length of an array of numbers *x* taking values from 0 to 9. Constrain the array so the sum of the numbers in the array is equal to the product of the numbers in the array. Output the resulting array. Test your model using the "all solutions" setting active in the IDE.

Add a constraint to ensure that the numbers in the array are non-decreasing, i.e. $x[1] \leq x[2] \leq \ldots \leq x[n]$. This should reduce the number of similar solutions. How big a number can you solve with your model? Why do you think this happens?

Deciding functions



- A very important, recurring problem is deciding a finite function.
- Given
 - Domain DOM
 - Codomain COD
- Find a function $f: DOM \to COD$
- Satisfying some criteria (e.g. injectivity)

Deciding functions



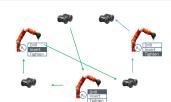
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Examples:

- Task allocation (maps tasks to workers, exactly one worker per task)
- Exam schedules (map students to appointments, certainly different appointments)

Task allocation in practice





- Task allocation problem
 - n robots
 - m tasks
 - Assign each robot a different task and maximize the profit
- Example:

$$- n = 4, m = 5$$

	t1	t2	t3	t4	t5
r1	7	1	3	4	6
r2	8	2	5	1	4
r3	4	3	7	2	5
r4	3	1	6	3	6

Task allocation: Model



```
% problem data
int: n; set of int: ROBOTS = 1..n;
int: m; set of int: TASKS = 1..m;
array[ROBOTS,TASKS] of int: profit;
% decisions
array[ROBOTS] of var TASKS: allocation;
% goal
solve maximize sum(r in ROBOTS) (profit[r, allocation[r]] );
% have robots work on different tasks
constraint forall(r1 in ROBOTS, r2 in ROBOTS where r1 < r2)</pre>
  ( allocation[r1] != allocation[r2] );
```

Judgement



```
constraint forall(r1 in ROBOTS, r2 in ROBOTS where r1 < r2)
  ( allocation[r1] != allocation[r2] );</pre>
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- In principle, fine, but . . .
 - Not very concise can be messed up
 - $O(n^2)$ individual constraints between two variables

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- In principle, fine, but . . .
 - Not very concise can be messed up
 - $O(n^2)$ individual constraints between two variables
- But in fact, this substructure is so common that it deserves a name
 - alldifferent

```
constraint alldifferent(allocation);
```

- all different ($[x_1, \ldots, x_n]$ is true if and only if all variables x_1 to x_n take a different value
- e.g. all different([2,3,5]) holds but all different([2,2,3]) does not.

Task allocation: Improved Model

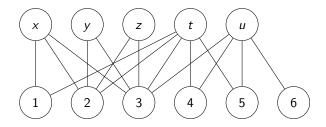


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% decisions
array[ROBOTS] of var TASKS: allocation;
% goal
solve maximize sum(r in ROBOTS) (profit[r, allocation[r]] );
include "alldifferent.mzn"; % we have to import from the library
% have robots work on different tasks
constraint alldifferent(allocation);
```

AllDifferent - Propagation



```
var {1,2,3}: x; var {2,3}: y; var {2,3}: z;
var {1,2,3,4,5}: t; var {3,4,5,6}: u;
constraint alldifferent([x,y,z,t,u]);
```

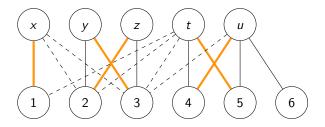


```
var {1}: x;     var {2,3}: y;     var {2,3}: z;
var {4,5}: t;     var {4,5,6}: u;
constraint alldifferent([x,y,z,t,u]);
```

AllDifferent - Propagation



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var {1,2,3}: x; var {2,3}: y; var {2,3}: z;
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constraint alldifferent([x,y,z,t,u]);
```





Assume an employee scheduling problem (rostering) (Shifts: 1 = morning, 2 = afternoon, 3 = night):

	Monday	Tuesday	Wednesday	Thursday	Friday
Nurse 1	off	1	2	3	2
Nurse 2	1	off	1	1	1
Nurse 3	1	2	off	1	2
Nurse 4	2	2	2	off	3
Nurse 5	3	3	2	3	off





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 - At least one nurse has to be assigned to every shift per day





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- Consider work regulations
 - At least one nurse has to be assigned to every shift per day
 - Each nurse may at most work two night shifts
 - Each nurse needs to have one day off

Cardinality Constraint



Software & Syetems Engineering

worksShift	Monday	Tuesday	Wednesday	Thursday	Friday
Nurse 1	off	1	2	3	2
Nurse 2	1	off	1	1	1

- cardinality($X \mid v, l, u$)
 - $X = \{x_1, \dots, x_n\}$
 - $v = (v_1, \ldots, v_m)$
 - $I=(I_1,\ldots,I_m)$ contain *lower* and $u=(u_1,\ldots,u_m)$ upper bounds for values v_i

Cardinality Constraint



					Engineering	
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 - $X = \{x_1, \dots, x_n\}$
 - $v = (v_1, \ldots, v_m)$
 - $I = (I_1, ..., I_m)$ contain *lower* and $u = (u_1, ..., u_m)$ upper bounds for values v_i
- For instance, for each nurse i:
 - cardinality([worksShift[i, \cdot]] | (0, 1, 2, 3), (1, 0, 0, 0), (5, 5, 5, 2))
- In MiniZinc:

MiniZinc: Group Photo



Exercise 3

Given a group of n people, we must arrange them for a photo. The best photo is when people are next to their friends, so the aim is to arrange them so that each person is next to (to the left or right) with as many friends as possible. The data for the problem is given as

```
n = <size of problem>;
array[1..n,1..n] of par bool: friend;
```

where friend[f1, f2] means f1 and f2 are friends. You can assume that the friend array is symmetric. You should output a list of the people in their position to maximize the number of adjacent friends. For example given the data groupphoto1.dzn, you should output the placement of the guests as well as the objective value, i.e.,

$$Obj = 7; [4, 3, 5, 6, 8, 7, 1, 2]$$

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