

1. Instalation

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2. Configuration: Setup the environment in the `.bashrc` file:

```
source /opt/ros/<ros-version>/setup.bash
```

2. Colcon

- Instalation
- Cofiguration: Setup in the `.bashrc` file

```
source /usr/share/colcon_cd/function/colcon_cd.sh
export _colcon_cd_root=/opt/ros/<ros-version>/
source /usr/share/colcon_argcomplete/hook/colcon-
argcomplete.bash
```