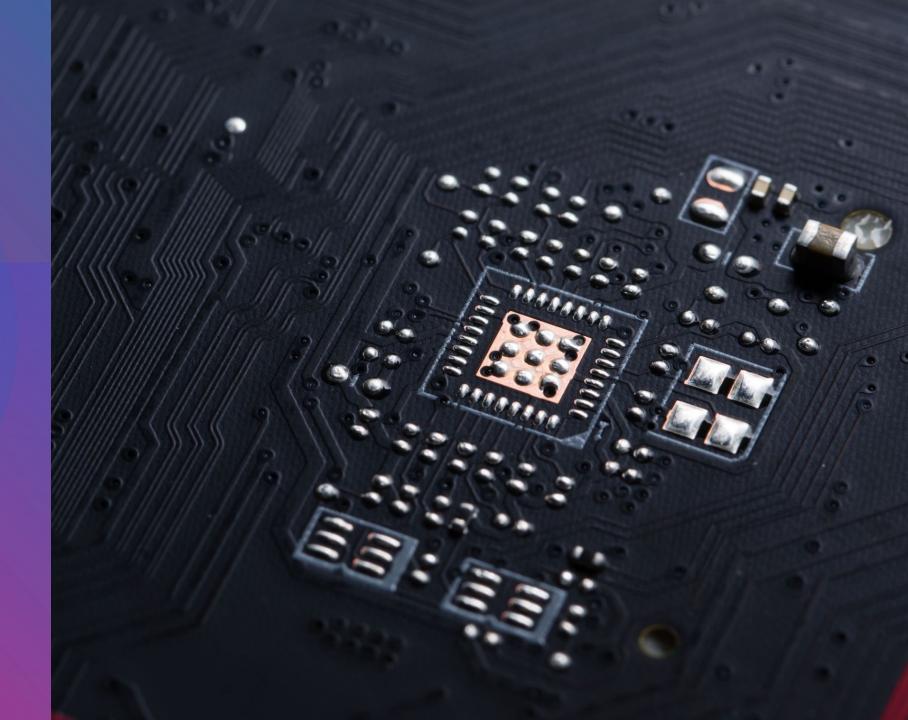
SENSORE DI PARCHEGGIO

## PROGETTO ARDUINO

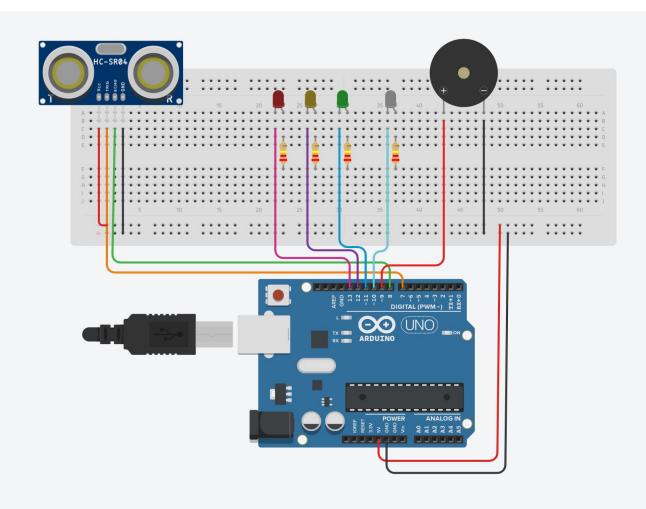




## COSA ABBIAMO UTILIZZATO

- Arduino uno
- breadboard
- Pin
- Led
- Buzzer
- Sensore ultrasuoni

## IL CIRCUITO



```
int triggerPort = 7;
int echoPort = 8;
                                                                                             // Controllo pericolo e suono buzzer
int cicalino = 9;
                                                                                             if (r < 100) {
int ledPin1 = 10;
int ledPin2 = 11;
                                                                                              analogWrite(cicalino, map(r, 0, 100, 0, 255)); // Modifica l'intensità del suono in base alla distanza
int ledPin3 = 12;
                                                                                             } else {
int ledPin4 = 13;
                                                                                               digitalWrite(cicalino, LOW); // Spegni il buzzer se non c'è pericolo
#include <LiquidCrystal.h>
const int pot = A0;
float value;
                                                                                            // Accensione dei LED in base alla distanza
                                                                                             if (r < 400) {
// Initialize the LCD library
                                                                                              digitalWrite(ledPin1, HIGH);
const int rs = 12, en = 11, d4 = 5, d5 = 4, d6 = 3, d7 = 2;
                                                                                              digitalWrite(ledPin2, LOW);
LiquidCrystal lcd(rs, en, d4, d5, d6, d7);
                                                                                              digitalWrite(ledPin3, LOW);
                                                                                              digitalWrite(ledPin4, LOW);
void setup() {
                                                                                             } else if (400 <= r < 700) {
  pinMode(triggerPort, OUTPUT);
                                                                                               digitalWrite(ledPin1, LOW);
  pinMode(echoPort, INPUT);
                                                                                              digitalWrite(ledPin2, HIGH);
  pinMode(cicalino, OUTPUT);
                                                                                              digitalWrite(ledPin3, LOW);
  pinMode(ledPin1, OUTPUT);
                                                                                              digitalWrite(ledPin4, LOW);
  pinMode(ledPin2, OUTPUT);
                                                                                             } else if (700<= r < 1000) {
  pinMode(ledPin3, OUTPUT);
                                                                                              digitalWrite(ledPin1, LOW);
  pinMode(ledPin4, OUTPUT);
                                                                                              digitalWrite(ledPin2, LOW);
  Serial.begin(9600);
                                                                                              digitalWrite(ledPin3, HIGH);
  Serial.println("Sensore ultrasuoni:");
                                                                                              digitalWrite(ledPin4, LOW);
                                                                                             } else {
                                                                                              digitalWrite(ledPin1, LOW);
                                                                                              digitalWrite(ledPin2, LOW);
void loop() {
                                                                                              digitalWrite(ledPin3, LOW);
  digitalWrite(triggerPort, LOW);
                                                                                               digitalWrite(ledPin4, HIGH);
  digitalWrite(triggerPort, HIGH);
  delayMicroseconds(10);
  digitalWrite(triggerPort, LOW);
  long duration = pulseIn(echoPort, HIGH);
  long r = 0.034 * duration / 2;
  Serial.print("durata: ");
  Serial.print(duration);
  Serial.print(" , ");
  Serial.print("distanza: ");
  if (duration > 38000)
    Serial.println("fuori portata");
  else {
    Serial.print(r);
   Serial.println("cm");
```

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## GRAZIE PER L'ATTENZIONE