

SYMPY: SYMBOLIC COMPUTING IN PYTHON

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1. Introduction. SymPy is a full featured computer algebra system (CAS) written in the Python programming language. It is a free and open source software, being licensed under the 3-clause BSD license. SymPy was started by Ondřej Čertík in 2005, and it has since grown into a large project with over 500 contributors. SymPy is developed on GitHub using a bazaar community model [43]. The accessibility of the codebase and the open community model allows SymPy to rapidly respond to the needs of the community of users, and has made the large contributor count possible.

Python is a popular dynamically typed programming language that has a focus on ease of use and readability. It also a very popular language for scientific computing and data science, with a wide range of useful libraries [38]. SymPy is itself used by many libraries and tools across many domains, such as Sage [48] (pure mathematics), yt [52] (astronomy and astrophysics), PyDy [25] (multibody dynamics), and SfePy [19]

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(finite elements).

Unlike many CASs, SymPy does not invent its own programming language. Python itself is used both for the internal implementation and the end user interaction. The exclusive usage of one programming language makes it easier for people already familiar with it to use or develop SymPy and at the same time allows developers to focus on mathematics, rather than language design.

SymPy is designed with a strong focus on usability as a library. This means that extensibility is important in its application program interface (API) design. This is also one of the reasons SymPy makes no attempt to extend the Python language itself. The goal is for users of SymPy to be able to import SymPy alongside other Python libraries in their workflow, whether that is an interactive workflow or programmatic use as part of a larger system.

Being developed as a library, SymPy does not have a built-in graphical user interface (GUI). However, SymPy exposes a rich interactive display system, including registering printers with Jupyter [40] frontends, including the Notebook and Qt Console, which will pretty print SymPy expressions using MathJax [18] or L^AT_EX rendering.

Section 2 discusses the architecture of SymPy. Section 3 enumerates the features of SymPy and takes a closer look at some of the important ones. Following that, section 4 looks at the numerical features of SymPy and its dependency library, mpmath. Section 5 looks at the domain specific physics submodules for doing classical mechanics and quantum mechanics. Finally, section 6 concludes the paper and discusses future work.

2. Architecture.

2.1. Basic Usage. Because SymPy is built on Python, it requires that all variable names be defined before they can be used. The following statement imports all SymPy functions into the global Python namespace. All examples in this paper assume that this has been run.

```
>>> from sympy import *
```

Symbolic variables, called symbols, must be defined and assigned to Python variables before they can be used. This is typically done through the `symbols` function, which creates multiple symbols at once. For instance,

```
>>> x, y, z = symbols('x y z')
```

creates three symbols representing variables named x , y , and z , assigned to Python variables of the same name. The Python variable names that symbols are assigned to are immaterial — one could have just as well have written `a, b, c = symbols('x y z')`. All examples in this paper will assume that the symbols x , y , and z have been assigned to a variable identical to their names.

Expressions are created from symbols using Python syntax through operator overloading, which mirrors usual mathematical notation. Note that in Python, exponentiation is `**`. For instance, the following creates the expression $(x^2 - 2x + 3)/y$.

```
>>> (x**2 - 2*x + 3)/y
```

```
(x**2 - 2*x + 3)/y
```

SymPy expressions are immutable. This simplifies the design by allowing interning. It also allows expressions to be hashed and stored in Python dictionaries, thereby enabling caching and other features.

2.2. The Core. A computer algebra system (CAS) represents mathematical expressions as data structures. For example the mathematical expression $x + y$ is represented as a tree with three nodes, $+$, x , and y , where x and y are ordered

children of $+$. As users of the computer algebra system manipulate mathematical expressions with traditional mathematical syntax the CAS manipulates the underlying data structures. Automated optimizations and computations such as integration, simplification, etc. are all functions that consume and produce expression trees.

In SymPy every symbolic expression is an instance of a Python `Basic` class, a superclass of all SymPy types providing common methods to all SymPy tree-elements such as traversals, caching, etc. The children of a node in the tree are held in the `args` attribute. A leaf node in the expression tree has empty `args`.

For example, consider the expression $xy + 2$:

```
>>> expr = x*y + 2
```

By order of operations, the parent of the expression tree for `expr` is an addition, so it is of type `Add`. The child nodes of `expr` are 2 and `x*y`.

```
>>> type(expr)
```

```
<class 'sympy.core.add.Add'>
```

```
>>> expr.args
```

```
(2, x*y)
```

One can dig further into the expression tree to see the full expression. For example, the first child node, given by `expr.args[0]`, is 2. Its class is `Integer`, and it has empty `args`, indicating that it is a leaf node.

```
>>> expr.args[0]
```

```
2
```

```
>>> type(expr.args[0])
```

```
<class 'sympy.core.numbers.Integer'>
```

```
>>> expr.args[0].args
```

```
()
```

A useful way to view an expression tree is with the `srepr` function, which returns a string representation of an expression as valid Python code with all the nested class constructor calls to create the given expression.

```
>>> srepr(expr)
```

```
"Add(Mul(Symbol('x'), Symbol('y')), Integer(2))"
```

Every SymPy expression satisfies a key invariant:

```
expr.func(*expr.args) == expr
```

This means that expressions are rebuildable from their `args`.¹ We note that in SymPy, the `==` operator represents exact structural equality, not mathematical equality. This allows one to test if any two expressions are equal to one another as expression trees.

Python allows classes to override mathematical operators. The Python interpreter translates the above `x*y + 2` to, roughly, `(x.__mul__(y)).__add__(2)`. Both `x` and `y`, returned from the `symbols` function, are `Symbol` instances. The 2 in the expression is processed by Python as a literal, and is stored as Python's builtin `int` type. When 2 is passed to the `__add__` method of `Symbol`, it is converted to the SymPy type `Integer(2)` before being stored in the resulting expression tree. In this way, SymPy expressions can be built in the natural way using Python operators and numeric literals.

2.3. Logical Inference and Assumptions. SymPy performs logical inference through its assumptions system. The assumptions system allows users to specify that symbols have certain common mathematical properties, such as being positive, imaginary, or integral. SymPy is careful to never perform simplifications on an expression unless the assumptions allow them. For instance, the identity $\sqrt{t^2} = t$ holds if t is

¹`expr.func` is used instead of `type(expr)` to allow the function of an expression to be distinct from its actual Python class. In most cases the two are the same.

nonnegative ($t \geq 0$). If t is real, the identity $\sqrt{t^2} = |t|$ holds. However, for general complex t , no such identity holds.

By default, SymPy performs all calculations assuming that symbols are complex valued. This assumption makes it easier to treat mathematical problems in full generality.

```
>>> t = Symbol('t')
>>> sqrt(t**2)
sqrt(t**2)
```

By assuming the most general case, that symbols are complex by default, SymPy avoids performing mathematically invalid operations. However, in many cases users will wish to simplify expressions containing terms like $\sqrt{t^2}$.

Assumptions are set on `Symbol` objects when they are created. For instance `Symbol('t', positive=True)` will create a symbol named `t` that is assumed to be positive.

```
>>> t = Symbol('t', positive=True)
>>> sqrt(t**2)
t
```

Some of the common assumptions that SymPy allows are `positive`, `negative`, `real`, `nonpositive`, `nonnegative`, `real`, `integer`, and `commutative`.² Assumptions on any object can be checked with the `is_assumption` attributes, like `t.is_positive`.

Assumptions are only needed to restrict a domain so that certain simplifications can be performed. It is not required to make the domain match the input of a function. For instance, one can create the object $\sum_{n=0}^m f(n)$ as `Sum(f(n), (n, 0, m))` without setting `integer=True` when creating the `Symbol` object `n`.

The assumptions system additionally has deductive capabilities. The assumptions use a three-valued logic using the Python builtin objects `True`, `False`, and `None`. `None` represents the “unknown” case. This could mean that the given assumption could be either true or false under the given information, for instance, `Symbol('x', real=True).is_positive` will give `None` because a real symbol might be positive or it might not. It could also mean not enough is implemented to compute the given fact. For instance, `(pi + E).is_irrational` gives `None`, because SymPy does not know how to determine if $\pi + e$ is rational or irrational, indeed, it is an open problem in mathematics.

Basic implications between the facts are used to deduce assumptions. For instance, the assumptions system knows that being an integer implies being rational, so `Symbol('x', integer=True).is_rational` returns `True`. Furthermore, expressions compute the assumptions on themselves based on the assumptions of their arguments. For instance, if `x` and `y` are both created with `positive=True`, then `(x + y).is_positive` will be `True`.

SymPy also has an experimental assumptions system where facts are stored separately from objects, and deductions are made with a SAT solver. We will not discuss this system here.

2.4. Extensibility. While the core of SymPy is quite small it has been extended to a broad variety of domains by a broad variety of contributors. This is due in part because the same language, Python, is used both for the internal implementation and the external usage by users. All of the extensibility capabilities available to users are also used by functions that are part of SymPy. It is easy for most SymPy users to

²If A and B are Symbols created with `commutative=False` then SymPy will keep $A \cdot B$ and $B \cdot A$ distinct.

162 transition to development.

163 The typical way to create a custom SymPy object is to subclass an existing SymPy
164 class, generally one of `Basic`, `Expr`, or `Function`. All SymPy classes used for expression
165 trees³ should be subclasses of the base class `Basic`, which defines some basic methods
166 for symbolic expression trees. `Expr` is the subclass for mathematical expressions that
167 can be added and multiplied together. Instances of `Expr` typically represent complex
168 numbers, but may also include other “rings” like matrix expressions. Not all SymPy
169 classes are subclasses of `Expr`. For instance, logic expressions such as `And(x, y)` are
170 subclasses of `Basic` but not of `Expr`.

171 The `Function` class is a subclass of `Expr` which makes it easier to define mathe-
172 matical functions called with arguments. This includes named functions like `sin(x)`
173 and `log(x)` as well as undefined functions like `f(x)`. Subclasses of `Function` should
174 define a class method `eval`, which returns values for which the function should be
175 automatically evaluated, and `None` for arguments that should not be automatically
176 evaluated.

177 Many SymPy functions perform various evaluations down the expression tree.
178 Classes define their behavior in such functions by defining a relevant `_eval_*` method.
179 For instance, an object can indicate to the `diff` function how to take the derivative
180 of itself by defining the `_eval_derivative(self, x)` method, which may in turn call
181 `diff` on its args. The most common `_eval_*` methods relate to the assumptions.
182 `_eval_is_assumption` defines the assumptions for *assumption*.

183 As an example of the notions presented in this section, Listing 1 presents a
184 stripped down version of the gamma function $\Gamma(x)$ from SymPy, which evaluates
185 itself on positive integer arguments, has the positive and real assumptions defined,
186 can be rewritten in terms of factorial with `gamma(x).rewrite(factorial)`, and can
187 be differentiated. `fdiff` is a convenience method for subclasses of `Function`. `fdiff`
188 returns the derivative of the function without considering the chain rule. `self.func`
189 is used throughout instead of referencing `gamma` explicitly so that potential subclasses
190 of `gamma` can reuse the methods.

Listing 1: A stripped down version of `sympy.gamma`.

```
191 from sympy import Integer, Function, floor, factorial, polygamma
192
193 class gamma(Function)
194     @classmethod
195     def eval(cls, arg):
196         if isinstance(arg, Integer) and arg.is_positive:
197             return factorial(arg - 1)
198
199     def _eval_is_positive(self):
200         x = self.args[0]
201         if x.is_positive:
202             return True
203         elif x.is_noninteger:
204             return floor(x).is_even
205
206     def _eval_is_real(self):
```

³Some internal classes, such as those used in the polynomial module, do not follow this rule for efficiency reasons.

```

207         x = self.args[0]
208         # noninteger means real and not integer
209         if x.is_positive or x.is_noninteger:
210             return True
211
212     def _eval_rewrite_as_factorial(self, z):
213         return factorial(z - 1)
214
215     def fdiff(self, argindex=1):
216         from sympy.core.function import ArgumentIndexError
217         if argindex == 1:
218             return self.func(self.args[0])*polygamma(0, self.args[0])
219         else:
220             raise ArgumentIndexError(self, argindex)

```

221 The actual gamma function defined in SymPy has many more capabilities, such as
222 evaluation at rational points and series expansion.

223 **3. Features.** SymPy has an extensive feature set that encompasses too much
224 to cover in-depth here. Bedrock areas, such as calculus, receive their own subsections below. Table 1 gives a compact listing of all major capabilities present in the
225 SymPy codebase. This gives a sampling from the breadth of topics and application
226 domains that SymPy services. Unless stated otherwise, all features noted in Table 1
227 are symbolic in nature. Numeric features are discussed in Section 4.
228

Table 1: SymPy Features and Descriptions

Feature	Description
Calculus	Algorithms for computing derivatives, integrals, and limits.
Category Theory	Representation of objects, morphisms, and diagrams. Tools for drawing diagrams with Xy-pic.
Code Generation	Enables generation of compilable and executable code in a variety of different programming languages directly from expressions. Target languages include C, Fortran, Julia, JavaScript, Mathematica, Matlab and Octave, Python, and Theano.
Combinatorics & Group Theory	Implements permutations, combinations, partitions, subsets, various permutation groups (such as polyhedral, Rubik, symmetric, and others), Gray codes [37], and Prufer sequences [13].
Concrete Math	Summation, products, tools for determining whether summation and product expressions are convergent, absolutely convergent, hypergeometric, and other properties. May also compute Gosper’s normal form [42] for two univariate polynomials.
Cryptography	Represents block and stream ciphers, including shift, Affine, substitution, Vigenere’s, Hill’s, bifid, RSA, Kid RSA, linear-feedback shift registers, and Elgamal encryption

Differential Geometry	Classes to represent manifolds, metrics, tensor products, and coordinate systems in Riemannian and pseudo-Riemannian geometries [49].
Geometry	Allows the creation of 2D geometrical entities, such as lines and circles. Enables queries on these entities, such as asking the area of an ellipse, checking for collinearity of a set of points, or finding the intersection between two lines.
Lie Algebras	Represents Lie algebras and root systems.
Logic	Boolean expression, equivalence testing, satisfiability, and normal forms.
Matrices	Tools for creating matrices of symbols and expressions. This is capable of both sparse and dense representations and performing symbolic linear algebraic operations (e.g., inversion and factorization).
Matrix Expressions	Matrices with symbolic dimensions (unspecified entries). Block matrices.
Number Theory	Prime number generation, primality testing, integer factorization, continued fractions, Egyptian fractions, modular arithmetic, quadratic residues, partitions, binomial and multinomial coefficients, prime number tools, and integer factorization.
Plotting	Hooks for visualizing expressions via matplotlib [30] or as text drawings when lacking a graphical back-end. 2D function plotting, 3D function plotting, and 2D implicit function plotting are supported.
Polynomials	Computes polynomial algebras over various coefficient domains. Functionality ranges from the simple (e.g., polynomial division) to the advanced (e.g., Gröbner bases [10] and multivariate factorization over algebraic number domains).
Printing	Functions for printing SymPy expressions in the terminal with ASCII or Unicode characters and converting SymPy expressions to L ^A T _E X and MathML.
Quantum Mechanics	Quantum states, bra-ket notation, operators, basis sets, representations, tensor products, inner products, outer products, commutators, anticommutators.
Series	Implements series expansion, sequences, and limit of sequences. This includes Taylor, Laurent, and Puiseux series as well as special series, such as Fourier and formal power series.
Sets	Representations of empty, finite, and infinite sets. This includes special sets such as for all natural, integer, and complex numbers. Operations on sets such as union, intersection, Cartesian product, and building sets from other sets.
Simplification	Functions for manipulating and simplifying expressions. Includes algorithms for simplifying hypergeometric functions, trigonometric expressions, rational functions, combinatorial functions, square root denesting, and common subexpression elimination.

Solvers	Functions for symbolically solving equations algebraically, systems of equations, both linear and non-linear, inequalities, ordinary differential equations, partial differential equations, Diophantine equations, and recurrence relations.
Special Functions	Implements a number of well known special functions, including Dirac delta, Gamma, Beta, Gauss error functions, Fresnel integrals, Exponential integrals, Logarithmic integrals, Trigonometric integrals, Bessel, Hankel, Airy, B-spline, Riemann Zeta, Dirichlet eta, polylogarithm, Lerch transcendent, hypergeometric, elliptic integrals, Mathieu, Jacobi polynomials, Gegenbauer polynomial, Chebyshev polynomial, Legendre polynomial, Hermite polynomial, Laguerre polynomial, and spherical harmonic functions.
Statistics	Support for a random variable type as well as the ability to declare this variable from prebuilt distribution functions such as Normal, Exponential, Coin, Die, and other custom distributions [44].
Tensors	Symbolic manipulation of indexed objects.
Vectors	Provides basic vector math and differential calculus with respect to 3D Cartesian coordinate systems.

3.1. Simplification. The generic way to simplify an expression is by calling the `simplify` function. It must be emphasized that simplification is not an unambiguously defined mathematical operation [17]. The `simplify` function applies several simplification routines along with some heuristics to make the output expression as “simple” as possible.

It is often preferable to apply more directed simplification functions. These apply very specific rules to the input expression and are often able to make guarantees about the output (for instance, the `factor` function, given a polynomial with rational coefficients in several variables, is guaranteed to produce a factorization into irreducible factors). Table 2 lists some common simplification functions.

Table 2: Some SymPy Simplification Functions

<code>expand</code>	expand the expression <pre>>>> expand((x + y)**3) x**3 + 3*x**2*y + 3*x*y**2 + y**3</pre>
<code>factor</code>	factor a polynomial into irreducibles <pre>>>> factor(x**3 + 3*x**2*y + 3*x*y**2 + y**3) (x + y)**3</pre>
<code>collect</code>	collect polynomial coefficients <pre>>>> collect(y*x**2 + 3*x**2 - x*y + x - 1, x) x**2*(y + 3) + x*(-y + 1) - 1</pre>


```

cancel    rewrite a rational function as  $p/q$  with common factors canceled
>>> cancel((x**2 + 2*x + 1)/(x**2 - 1))
(x + 1)/(x - 1)

apart     compute the partial fraction decomposition of a rational function
>>> apart((x**3 + 4*x - 1)/(x**2 - 1))
x + 3/(x + 1) + 2/(x - 1)

trigsimp  simplify trigonometric expressions [23]
>>> trigsimp(cos(x)**2*tan(x) - sin(2*x))
-sin(2*x)/2

```

Substitutions are performed through the `.subs` method.

```

>>> (sin(x) + x**2 + 1).subs(x, y + 1)
(y + 1)**2 + sin(y + 1) + 1

```

3.2. Calculus. Integrals are calculated with the `integrate` function. SymPy implements a combination of the Risch algorithm [16], table lookups, a reimplementation of Manuel Bronstein’s “Poor Man’s Integrator” [15], and an algorithm for computing integrals based on Meijer G-functions. These allow SymPy to compute a wide variety of indefinite and definite integrals.

```

>>> integrate(sin(x), x)
-cos(x)
>>> integrate(sin(x), (x, 0, 1))
-cos(1) + 1

```

Derivatives are computed with the `diff` function. Derivatives are computed recursively using the various differentiation rules.

```

>>> diff(sin(x)*exp(x), x)
exp(x)*sin(x) + exp(x)*cos(x)

```

Summations and products are computed with `summation` and `product`, respectively. Summations are computed using a combination of Gosper’s algorithm, an algorithm that uses Meijer G-functions, and heuristics. Products are computed via some heuristics.

Limits are computed with the `limit` function. The limit module implements the Gruntz algorithm [27] for computing symbolic limits. For example, the following computes $\lim_{x \rightarrow \infty} x \sin(\frac{1}{x}) = 1$ (note that ∞ is `oo` in SymPy).

```

>>> limit(x*sin(1/x), x, oo)
1

```

As a more complicated example, SymPy computes $\lim_{x \rightarrow 0} \left(2e^{\frac{1-\cos(x)}{\sin(x)}} - 1 \right)^{\frac{\sinh(x)}{\operatorname{atan}^2(x)}} = e$.

```

>>> limit((2*E**((1-cos(x))/sin(x))-1)**(sinh(x)/atan(x)**2), x, 0)
E

```

Integrals, derivatives, summations, products, and limits that cannot be computed return unevaluated objects. These can also be created directly if the user chooses.

```

>>> integrate(x**x, x)
Integral(x**x, x)

```

3.3. Polynomials. SymPy implements a wide variety of algorithms for polynomial manipulation, which ranges from relatively simple algorithms for doing arithmetics of polynomials, to advanced methods for factoring multivariate polynomials

into irreducibles, symbolically determining real and complex root isolation intervals, or computing Gröbner bases.

Polynomial manipulation is useful on its own, but in SymPy, it is mostly used indirectly as a tool in other areas of the library. In fact, many mathematical problems in symbolic computing are first expressed using entities from the symbolic core, preprocessed, and then transformed into a problem in the polynomial algebra, where generic and efficient algorithms are used to solve the problem and, in the end, solutions to the original one are recovered. For example, this is a common scheme in symbolic integration or summation algorithms.

SymPy implements dense and sparse polynomial representations. Both are used in the univariate and multivariate cases. The dense representation is the default for univariate polynomials. For multivariate polynomials, the choice of representation is based on the application. The most common case for the sparse representation is algorithms for computing Gröbner bases (Buchberger, F4, and F5), because different monomial orderings can be expressed easily in this representation. However, algorithms for computing multivariate GCDs or factorizations, at least those currently implemented in SymPy, are better expressed when the representation is dense. The dense multivariate representation is specifically a recursively dense representation, where polynomials in $K[x_0, x_1, \dots, x_n]$ are viewed as a polynomials in $K[x_0][x_1] \dots [x_n]$. Note that despite this, the coefficient domain K , can be a multivariate polynomial domain as well. The dense recursive representation in Python gets inefficient when the number of variables gets high.

Here are some examples of the `sympy.polys` submodule.

Factorization:

```
>>> t = symbols("t")
>>> f = (2115*x**4*y + 45*x**3*z**3*t**2 - 45*x**3*t**2 - 423*x*y**4 -
...      47*x*y**3 + 141*x*y*z**3 + 94*x*y*z*t - 9*y**3*z**3*t**2 +
...      9*y**3*t**2 - y**2*z**3*t**2 + y**2*t**2 + 3*z**6*t**2 +
...      2*z**4*t**3 - 3*z**3*t**2 - 2*z*t**3)
>>> factor(f)
(t**2*z**3 - t**2 + 47*x*y)*(2*t*z + 45*x**3 - 9*y**3 - y**2 + 3*z**3)
```

Gröbner bases:

```
>>> x0, x1, x2 = symbols('x:3')
>>> I = [x0 + 2*x1 + 2*x2 - 1,
...      x0**2 + 2*x1**2 + 2*x2**2 - x0,
...      2*x0*x1 + 2*x1*x2 - x1]
>>> groebner(I, order='lex')
GroebnerBasis([7*x0 - 420*x2**3 + 158*x2**2 + 8*x2 - 7,
7*x1 + 210*x2**3 - 79*x2**2 + 3*x2,
84*x2**4 - 40*x2**3 + x2**2 + x2], x0, x1, x2, domain='ZZ', order='lex')
```

Root isolation:

```
>>> f = 7*z**4 - 19*z**3 + 20*z**2 + 17*z + 20
>>> intervals(f, all=True, eps=0.001)
([],
 [((-425/1024 - 625*I/1024, -1485/3584 - 2185*I/3584), 1),
 ((-425/1024 + 2185*I/3584, -1485/3584 + 625*I/1024), 1),
 ((3175/1792 - 2605*I/1792, 1815/1024 - 10415*I/7168), 1),
 ((3175/1792 + 10415*I/7168, 1815/1024 + 2605*I/1792), 1)])
```

3.4. Printers. SymPy has a rich collection of expression printers for displaying expressions to the user. By default, an interactive Python session will render the `str` form of an expression, which has been used in all the examples in this paper so far. The `str` form of an expression is valid Python and roughly matches what a user would type to enter the expression.

```
>>> phi0 = Symbol('phi0')
>>> str(Integral(sqrt(phi0), phi0))
'Integral(sqrt(phi0), phi0)'
```

Expressions can be printed with 2D monospace text with `pprint`. This uses Unicode characters to render mathematical symbols such as integral signs, square roots, and parentheses. Greek letters and subscripts in symbol names are rendered automatically.

```
>>> pprint(Integral(sqrt(phi0 + 1), phi0))
```

$$\int \sqrt{\varphi_0 + 1} \, d(\varphi_0)$$

Alternately, the `use_unicode=False` flag can be set, which causes the expression to be printed using only ASCII characters.

```
>>> pprint(Integral(sqrt(phi0 + 1), phi0), use_unicode=False)
```

$$\int \sqrt{\text{phi0} + 1} \, d(\text{phi0})$$

The function `latex` returns a \LaTeX representation of an expression.

```
>>> print(latex(Integral(sqrt(phi0 + 1), phi0)))
\int \sqrt{\phi_0 + 1} \, d\phi_0
```

Users are encouraged to run the `init_printing` function at the beginning of interactive sessions, which automatically enables the best pretty printing supported by their environment. In the Jupyter Notebook or Qt Console [40], the \LaTeX printer is used to render expressions using MathJax or \LaTeX , if it is installed on the system. The 2D text representation is used otherwise.

Other printers such as MathML are also available. SymPy uses an extensible printer subsystem which allows users to customize the printing for any given printer, and for custom objects to define their printing behavior for any printer. SymPy's code generation capabilities, which we will not discuss in-depth here, use this subsystem to convert expressions into code in various languages.

3.5. Solvers. SymPy has a module of equation solvers for symbolic equations. There are two functions for solving algebraic equations in SymPy. `solve`, which has existed in SymPy for many years, and `solveset`, which is new in SymPy 1.0. `solveset` has several design changes with respect to the old `solve` function to resolve some of the issues with the old `solve` function. For example, the input API of `solve` has many flags, which complicate it for both users and developers. In contrast, `solveset` has a cleaner input API: it only asks for the necessary information from the user. The function signatures of `solve` and `solveset` are

```
solve(f, *symbols, **flags)
solveset(f, symbol, domain=S.Complexes)
```

367 The `domain` parameter is typically either `S.Complexes` (the default) or `S.Reals`, which
368 causes it to only return real solutions.

369 Additionally, `solve` has an inconsistent output API for various types of inputs. For
370 instance, depending on the input, sometimes it returns a Python list and sometimes it
371 returns a Python dictionary. On the other hand, the `solveset` has a canonical output
372 API. `solveset` always returns a SymPy set object.

373 Both functions implicitly assume that expressions are equal to 0. For instance,
374 `solveset(x - 1, x)` solves $x - 1 = 0$ for x .
375 Single solution:
376 `>>> solveset(x - 1, x)`
377 `{1}`
378 Finite solution set, quadratic equation:
379 `>>> solveset(x**2 - pi**2, x)`
380 `{-pi, pi}`
381 No solution:
382 `>>> solveset(1, x)`
383 `EmptySet()`
384 Interval solution:
385 `>>> solveset(x**2 - 3 > 0, x, domain=S.Reals)`
386 `(-oo, -sqrt(3)) U (sqrt(3), oo)`
387 Infinitely many solutions:
388 `>>> solveset(sin(x) - 1, x, domain=S.Reals)`
389 `ImageSet(Lambda(_n, 2*_n*pi + pi/2), Integers())`
390 `>>> solveset(x - x, x, domain=S.Reals)`
391 `(-oo, oo)`
392 `>>> solveset(x - x, x, domain=S.Complexes)`
393 `S.Complexes`

394 Linear systems are solved with `linsolve`. Finite and infinite solution for deter-
395 mined, under determined, and over determined problems are supported.
396 `>>> A = Matrix([[1, 2, 3], [4, 5, 6], [7, 8, 10]])`
397 `>>> b = Matrix([3, 6, 9])`
398 `>>> linsolve((A, b), x, y, z)`
399 `{(-1, 2, 0)}`
400 `>>> linsolve(Matrix([[1, 1, 1, 1], [1, 1, 2, 3]]), (x, y, z))`
401 `{(-y - 1, y, 2)}`

402 `solveset` is under active development as a planned replacement for `solve`. There
403 are some features which are implemented in `solve` that are not yet implemented in
404 `solveset`. Below are some of the examples of `solve`, which are not yet supported by
405 `solveset`.

406 Nonlinear (multivariate) system of equations (the intersection of a circle and a parabola):
407 `>>> solve([x**2 + y**2 - 16, 4*x - y**2 + 6], x, y)`
408 `[(-2 + sqrt(14), -sqrt(-2 + 4*sqrt(14))),`
409 `(-2 + sqrt(14), sqrt(-2 + 4*sqrt(14))),`
410 `(-sqrt(14) - 2, -I*sqrt(2 + 4*sqrt(14))),`
411 `(-sqrt(14) - 2, I*sqrt(2 + 4*sqrt(14)))]`

412 Transcendental equations:
413 `>>> solve((x + log(x))**2 - 5*(x + log(x)) + 6, x)`
414 `[LambertW(exp(2)), LambertW(exp(3))]`
415 `>>> solve(x**3 + exp(x))`
416 `[-3*LambertW((-1)**(2/3)/3)]`

417 **3.6. Matrices.** SymPy supports matrices with symbolic expressions as elements.■

```
418 >>> x, y = symbols('x y')
419 >>> A = Matrix(2, 2, [x, x + y, y, x])
420 >>> A
421 Matrix([
422 [x, x + y],
423 [y, x]])
```

424 All SymPy matrix types perform linear algebra including matrix addition, multi-
425 plication, exponentiation, computing determinants, solving linear systems, and com-
426 puting inverses using LU decomposition, LDL decomposition, Gauss-Jordan elimina-
427 tion, Cholesky decomposition, Moore-Penrose pseudoinverse, and adjugate matrix.

428 All operations are computed symbolically. For example eigenvalues are computed
429 by generating the characteristic polynomial using the Berkowitz algorithm and then
430 solving it using polynomial routines. Diagonalizable matrices can be diagonalized first
431 to compute the eigenvalues.

```
432 >>> A.eigenvals()
433 {x - sqrt(y*(x + y)): 1, x + sqrt(y*(x + y)): 1}
```

434 Internally these matrices store the elements as a list, making it a dense repre-
435 sentation. For storing sparse matrices, the `SparseMatrix` class can be used. Sparse
436 matrices store the elements in a dictionary of keys (DoK) format.

437 SymPy also supports matrices with symbolic dimension values. `MatrixSymbol`
438 represents a matrix with dimensions $m \times n$, where m and n can be symbolic. Ma-
439 trix addition and multiplication, scalar operations, matrix inverse, and transpose are
440 stored symbolically as matrix expressions.

```
441 >>> m, n, p = symbols("m, n, p", integer=True)
442 >>> R = MatrixSymbol("R", m, n)
443 >>> S = MatrixSymbol("S", n, p)
444 >>> T = MatrixSymbol("T", m, p)
445 >>> U = R*S + 2*T
446 >>> U.shape
447 (m, p)
448 >>> U[0, 1]
449 2*T[0, 1] + Sum(R[0, _k]*S[_k, 1], (_k, 0, n - 1))
```

450 Block matrices are also supported in SymPy. `BlockMatrix` elements can be any
451 matrix expression which includes explicit matrices, matrix symbols, and block matri-
452 ces. All functionalities of matrix expressions are also present in `BlockMatrix`.

```
453 >>> n, m, l = symbols('n m l')
454 >>> X = MatrixSymbol('X', n, n)
455 >>> Y = MatrixSymbol('Y', m, m)
456 >>> Z = MatrixSymbol('Z', n, m)
457 >>> B = BlockMatrix([[X, Z], [ZeroMatrix(m, n), Y]])
458 >>> B
459 Matrix([
460 [X, Z],
461 [0, Y]])
462 >>> B[0, 0]
463 X[0, 0]
464 >>> B.shape
465 (m + n, m + n)
```


converge numerically).

Due to this generic approach, particular combinations of hypergeometric functions can be specified easily. The implementation of the Meijer G-function takes only a few dozen lines of code, yet covers the whole input domain in a robust way. The Meijer G-function instance $G_{1,3}^{3,0}(0; \frac{1}{2}, -1, -\frac{3}{2}|x)$ is a good test case [51]; past versions of both Maple and Mathematica produced incorrect numerical values for large $x > 0$. Here, mpmath automatically removes the internal singularity and compensates for cancellations (amounting to 656 bits of precision when $x = 10000$), giving correct values:

```
>>> mpmath.mp.dps = 15
>>> mpmath.meijerg([[[]],[0]], [[-0.5, -1, -1.5], []], 10000)
2.4392576907199564e-94
```

Equivalently, with SymPy's interface this function can be evaluated as:

```
>>> meijerg([[[]],[0]], [[-S(1)/2, -1, -S(3)/2], []], 10000).evalf()
2.43925769071996e-94
```

We highlight the generalized hypergeometric functions and the Meijer G-function, due to those functions' frequent appearance in closed forms for integrals and sums (see section 3.2). Via mpmath, SymPy has relatively good support for evaluating sums and integrals numerically, using two complementary approaches: direct numerical evaluation, or first computing a symbolic closed form involving special functions.

4.2. Numerical simplification. The `nsimplify` function in SymPy (a wrapper of `identify` in mpmath) attempts to find a simple symbolic expression that evaluates to the same numerical value as the given input. It works by applying a few simple transformations (including square roots, reciprocals, logarithms and exponentials) to the input and, for each transformed value, using the PSLQ algorithm [21] to search for a matching algebraic number or optionally a linear combination of user-provided base constants (such as π).

```
>>> t = 1 / (sin(pi/5)+sin(2*pi/5)+sin(3*pi/5)+sin(4*pi/5))**2
>>> nsimplify(t)
-2*sqrt(5)/5 + 1
>>> nsimplify(pi, tolerance=0.01)
22/7
>>> nsimplify(1.783919626661888, [pi], tolerance=1e-12)
pi/(-1/3 + 2*pi/3)
```

5. Domain Specific Submodules. SymPy includes several packages that allow users to solve domain specific problems. For example, a comprehensive physics package is included that is useful for solving problems in mechanics, optics, and quantum mechanics along with support for manipulating physical quantities with units.

5.1. Classical Mechanics.

5.1.1. Vector Algebra. The `sympy.physics.vector` package provides reference frame, time, and space aware vector and dyadic objects that allow for three dimensional operations such as addition, subtraction, scalar multiplication, inner and outer products, cross products, etc. Both of these objects can be written in very compact notation that make it easy to express the vectors and dyadics in terms of multiple reference frames with arbitrarily defined relative orientations. The vectors are used to specify the positions, velocities, and accelerations of points, orientations, angular velocities, and angular accelerations of reference frames, and force and torques. The dyadics are essentially reference frame aware 3×3 tensors. The vector and dyadic

objects can be used for any one-, two-, or three-dimensional vector algebra and they provide a strong framework for building physics and engineering tools.

The following Python interpreter session shows how a vector is created using the orthogonal unit vectors of three reference frames that are oriented with respect to each other and the result of expressing the vector in the A frame. The B frame is oriented with respect to the A frame using Z-X-Z Euler Angles of magnitude π , $\frac{\pi}{2}$, and $\frac{\pi}{3}$ rad, respectively whereas the C frame is oriented with respect to the B frame through a simple rotation about the B frame's X unit vector through $\frac{\pi}{2}$ rad.

```
>>> from sympy import pi
>>> from sympy.physics.vector import ReferenceFrame
>>> A = ReferenceFrame('A')
>>> B = ReferenceFrame('B')
>>> C = ReferenceFrame('C')
>>> B.orient(A, 'body', (pi, pi / 3, pi / 4), 'zxz')
>>> C.orient(B, 'axis', (pi / 2, B.x))
>>> v = 1 * A.x + 2 * B.z + 3 * C.y
>>> v
A.x + 2*B.z + 3*C.y
>>> v.express(A)
A.x + 5*sqrt(3)/2*A.y + 5/2*A.z
```

5.1.2. Mechanics. The `sympy.physics.mechanics` package utilizes the `sympy.physics.vector` package to populate time aware particle and rigid body objects to fully describe the kinematics and kinetics of a rigid multi-body system. These objects store all of the information needed to derive the ordinary differential or differential algebraic equations that govern the motion of the system, i.e., the equations of motion. These equations of motion abide by Newton's laws of motion and can handle any arbitrary kinematic constraints or complex loads. The package offers two automated methods for formulating the equations of motion based on Lagrangian Dynamics [32] and Kane's Method [31]. Lastly, there are automated linearization routines for constrained dynamical systems based on [41].

5.2. Quantum Mechanics. The `sympy.physics.quantum` package has extensive capabilities for performing symbolic quantum mechanics, using Python objects to represent the different mathematical objects relevant in quantum theory [45]: states (bras and kets), operators (unitary, hermitian, etc.), and basis sets, as well as operations on these objects such as representations, tensor products, inner products, outer products, commutators, anticommutators, etc. The base objects are designed in the most general way possible to enable any particular quantum system to be implemented by subclassing the base operators and defining the relevant class methods to provide system specific logic.

For example, you can define symbolic quantum operators and states and perform a full range of operations with them:

```
>>> from sympy.physics.quantum import Commutator, Dagger, Operator
>>> from sympy.physics.quantum import Ket, qapply
>>> A = Operator('A')
>>> B = Operator('B')
>>> C = Operator('C')
>>> D = Operator('D')
>>> a = Ket('a')
>>> comm = Commutator(A, B)
```

```

658 >>> comm
659 [A,B]
660 >>> qapply(Dagger(comm*a)).doit()
661 -<a|*(Dagger(A)*Dagger(B) - Dagger(B)*Dagger(A))
662 Commutators can be expanded using common commutator identities:
663 >>> Commutator(C+B, A*D).expand(commutator=True)
664 -[A,B]*D - [A,C]*D + A*[B,D] + A*[C,D]
665 On top of this set of base objects, a number of specific quantum systems have
666 been implemented in a fully symbolic framework. These include:
667     • Many of the exactly solvable quantum systems, including simple harmonic
668       oscillator states and raising/lowering operators, infinite square well states,
669       and 3D position and momentum operators and states.
670     • Second quantized formalism of non-relativistic many-body quantum mechan-
671       ics [22].
672     • Quantum angular momentum [53]. Spin operators and their eigenstates can
673       be represented in any basis and for any quantum numbers. A rotation opera-
674       tor representing the Wigner-D matrix, which may be defined symbolically or
675       numerically, is also implemented to rotate spin eigenstates. Functionality for
676       coupling and uncoupling of arbitrary spin eigenstates is provided, including
677       symbolic representations of Clebsch-Gordon coefficients and Wigner symbols.
678     • Quantum information and computing [36]. Multidimensional qubit states,
679       and a full set of one- and two-qubit gates are provided and can be represented
680       symbolically or as matrices/vectors. With these building blocks it is possible
681       to implement a number of basic quantum algorithms including the quantum
682       Fourier transform, quantum error correction, quantum teleportation, Grover's
683       algorithm, dense coding, etc.
684 Here are a few short examples of the quantum information and computing capa-
685 bilities in sympy.physics.quantum. We start with a simple 4 qubit state and flip one
686 of the qubits:
687 >>> from sympy.physics.quantum.qubit import Qubit
688 >>> q = Qubit('0101')
689 >>> q
690 |0101>
691 >>> q.flip(1)
692 |0111>
693 Qubit states can also be used in adjoint operations, tensor products, inner/outer
694 products:
695 >>> Dagger(q)
696 <0101|
697 >>> ip = Dagger(q)*q
698 >>> ip
699 <0101|0101>
700 >>> ip.doit()
701 1
702 Quantum gates (unitary operators) can be applied to transform these states and then
703 classical measurements can be performed on the results:
704 >>> from sympy.physics.quantum.qubit import Qubit, measure_all
705 >>> from sympy.physics.quantum.gate import H, X, Y, Z
706 >>> from sympy.physics.quantum.qapply import qapply
707 >>> c = H(0)*H(1)*Qubit('00')

```

```

708 >>> c
709 H(0)*H(1)*|00>
710 >>> q = qapply(c)
711 >>> measure_all(q)
712 [(|00>, 1/4), (|01>, 1/4), (|10>, 1/4), (|11>, 1/4)]

```

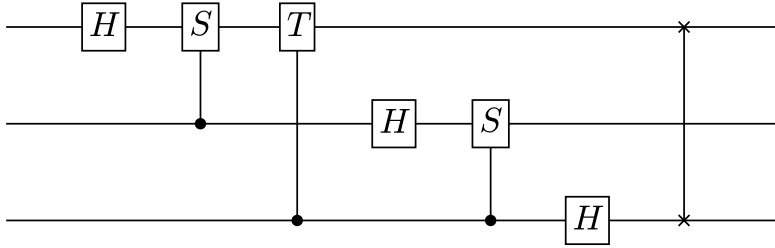


Fig. 1: The circuit diagram for a 3-qubit quantum fourier transform generated by SymPy.

```

713 Here is a final example of creating a 3-qubit quantum fourier transform, decomposing
714 it into one- and two-qubit gates, and then generating a circuit plot for the sequence
715 of gates (see Figure 1).
716 >>> from sympy.physics.quantum.qft import QFT
717 >>> from sympy.physics.quantum.circuitplot import circuit_plot
718 >>> fourier = QFT(0,3).decompose()
719 >>> fourier
720 SWAP(0,2)*H(0)*C((0),S(1))*H(1)*C((0),T(2))*C((1),S(2))*H(2)
721 >>> c = circuit_plot(fourier, nqubits=3)

```

6. Conclusion and future work. SymPy is a robust computer algebra system that provides a wide array of features both in traditional computer algebra and in broad scientific disciplines. It is written in the general purpose Python language which allows it to be used in a first-class way with other Python projects, including the scientific Python stack. SymPy is designed to be used in an extensible way and, unlike many other CASs, both as an end-user application and as a library.

SymPy expressions are immutable trees of Python objects. SymPy uses Python both as the internal language and the user language, meaning users can use the same methods that the library implements to extend it. SymPy has an assumptions system for declaring and deducing mathematical properties on expressions.

SymPy has submodules for many areas of mathematics. It has functions for simplifying expressions, doing common calculus operations, pretty printing expressions, solving equations, and symbolic matrices. Other included areas are discrete math, concrete math, plotting, geometry, statistics, polynomials, sets, series, vectors, combinatorics, group theory, code generation, tensors, Lie algebras, cryptography, and special functions. Additionally, SymPy contains submodules targeting certain specific domains, such as classical mechanics and quantum mechanics. This breadth of domains is due to a strong and vibrant user community that were attracted to SymPy

because of its ease of access.

Some of the planned future work for SymPy includes work on improving code generation, improvements to the speed of SymPy, and improving the solvers module.

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9. Supplement.

9.1. Limits: The Gruntz Algorithm. SymPy calculates limits using the Gruntz algorithm, as described in [27]. The basic idea is as follows: any limit can be converted to a limit $\lim_{x \rightarrow \infty} f(x)$ by substitutions like $x \rightarrow \frac{1}{x}$. Then the most varying subexpression ω (that converges to zero as $x \rightarrow \infty$ the fastest from all subexpressions) is identified in $f(x)$, and $f(x)$ is expanded into a series with respect to ω . Any positive powers of ω converge to zero. If there are negative powers of ω , then the limit is infinite. The constant term (independent of ω , but could depend on x) then determines the limit (one might need to recursively apply the Gruntz algorithm on this term to determine the limit).

To determine the most varying subexpression, the comparability classes must first be defined, by calculating L :

$$(1) \quad L \equiv \lim_{x \rightarrow \infty} \frac{\log |f(x)|}{\log |g(x)|}$$

And then operations $<$, $>$ and \sim are defined as follows: $f > g$ when $L = \pm\infty$ (it is said that f is more rapidly varying than g , i.e., f goes to ∞ or 0 faster than g , f is greater than any power of g), $f < g$ when $L = 0$ (f is less rapidly varying than g) and $f \sim g$ when $L \neq 0, \pm\infty$ (both f and g are bounded from above and below by suitable integral powers of the other). Here are some examples of comparability classes:

$$\begin{aligned} 2 &< x < e^x < e^{x^2} < e^{e^x} \\ 2 &\sim 3 \sim -5 \\ x &\sim x^2 \sim x^3 \sim \frac{1}{x} \sim x^m \sim -x \\ e^x &\sim e^{-x} \sim e^{2x} \sim e^{x+e^{-x}} \\ f(x) &\sim \frac{1}{f(x)} \end{aligned}$$

The Gruntz algorithm is now illustrated on the following example:

$$(2) \quad f(x) = e^{x+2e^{-x}} - e^x + \frac{1}{x}.$$

The goal is to calculate $\lim_{x \rightarrow \infty} f(x)$. First the set of most rapidly varying subexpressions is determined, the so called *mrsv set*. For (2), the following mrsv set $\{e^x, e^{-x}, e^{x+2e^{-x}}\}$ is obtained. These are all subexpressions of (2) and they all belong to the same comparability class. This calculation can be done using SymPy as follows:

```
>>> from sympy.series.gruntz import mrsv
>>> mrsv(exp(x+2*exp(-x))-exp(x) + 1/x, x)[0].keys()
dict_keys([exp(x + 2*exp(-x)), exp(x), exp(-x)])
```

Next any item ω is taken from mrsv that converges to zero for $x \rightarrow \infty$. The item $\omega = e^{-x}$ is obtained. If such a term is not present in the mrsv set (i.e., all terms converge to infinity instead of zero), the relation $f(x) \sim \frac{1}{f(x)}$ can be used.

Next step is to rewrite the mrsv in terms of ω : $\{\frac{1}{\omega}, \omega, \frac{1}{\omega}e^{2\omega}\}$. Then the original subexpressions are substituted back into $f(x)$ and expanded with respect to ω :

$$(3) \quad f(x) = \frac{1}{x} - \frac{1}{\omega} + \frac{1}{\omega}e^{2\omega} = 2 + \frac{1}{x} + 2\omega + O(\omega^2)$$

886 Since ω is from the mrv set, then in the limit $x \rightarrow \infty$ it is $\omega \rightarrow 0$ and so
887 $2\omega + O(\omega^2) \rightarrow 0$ in (3):

$$888 \quad (4) \quad f(x) = \frac{1}{x} - \frac{1}{\omega} + \frac{1}{\omega} e^{2\omega} = 2 + \frac{1}{x} + 2\omega + O(\omega^2) \rightarrow 2 + \frac{1}{x}$$

889 Since the result $(2 + \frac{1}{x})$ still depends on x , the above procedure is iterated on the
890 result until just a number (independent of x) is obtained, which is the final limit. In
891 the above case the limit is 2, as can be verified by SymPy:

```
892 >>> limit(exp(x+2*exp(-x))-exp(x) + 1/x, x, oo)
893 2
```

894 In general, when $f(x)$ is expanded in terms of ω , it is obtained:

$$895 \quad (5) \quad f(x) = \underbrace{O\left(\frac{1}{\omega^3}\right)}_{\infty} + \underbrace{\frac{C_{-2}(x)}{\omega^2}}_{\infty} + \underbrace{\frac{C_{-1}(x)}{\omega}}_{\infty} + \underbrace{C_0(x)}_0 + \underbrace{C_1(x)\omega}_{0} + \underbrace{O(\omega^2)}_0$$

896 The positive powers of ω are zero. If there are any negative powers of ω , then the
897 result of the limit is infinity, otherwise the limit is equal to $\lim_{x \rightarrow \infty} C_0(x)$. The expression
898 $C_0(x)$ is simpler than $f(x)$ and so the algorithm always converges. A proof of this, as
899 well as further details are given in Gruntz's Ph.D. thesis [27].

900 9.2. Series.

901 **9.2.1. Series Expansion.** SymPy is able to calculate the symbolic series expansion
902 of an arbitrary series or expression involving elementary and special functions and
903 multiple variables. For this it has two different implementations- the `series` method
904 and Ring Series.

905 The first approach stores a series as an object of the `Basic` class. Each function
906 has its specific implementation of its expansion which is able to evaluate the Puiseux
907 series expansion about a specified point. For example, consider a Taylor expansion
908 about 0:

```
909 >>> from sympy import symbols, series
910 >>> x, y = symbols('x, y')
911 >>> series(sin(x+y) + cos(x*y), x, 0, 2)
912 1 + sin(y) + x*cos(y) + 0(x**2)
```

913 The newer and much faster[1] approach called Ring Series makes use of the ob-
914 servation that a truncated Taylor series, is in fact a polynomial. Ring Series uses the
915 efficient representation and operations of sparse polynomials. The choice of sparse
916 polynomials is deliberate as it performs well in a wider range of cases than a dense
917 representation. Ring Series gives the user the freedom to choose the type of coeffi-
918 cients he wants to have in his series, allowing the use of faster operations on certain
919 types.

920 For this, several low level methods for expansion of trigonometric, hyperbolic and
921 other elementary functions like inverse of a series, calculating n th root, etc, are imple-
922 mented using variants of the Newton Method [14]. All these support Puiseux series
923 expansion. The following example demonstrates the use of an elementary function
924 that calculates the Taylor expansion of the sine of a series.

```
925 >>> from sympy import ring
926 >>> from sympy.polys.ring_series import rs_sin
927 >>> R, t = ring('t', QQ)
928 >>> rs_sin(t**2 + t, t, 5)
929 -1/2*t**4 - 1/6*t**3 + t**2 + t
```

930 The function `sympy.polys.rs_series` makes use of these elementary functions to
 931 expand an arbitrary SymPy expression. It does so by following a recursive strategy
 932 of expanding the lower most functions first and then composing them recursively to
 933 calculate the desired expansion. Currently, it only supports expansion about 0 and
 934 is under active development. Ring Series is several times faster than the default
 935 implementation with the speed difference increasing with the size of the series. The
 936 `sympy.polys.rs_series` takes as input any SymPy expression and hence there is no
 937 need to explicitly create a polynomial ring. An example:

```
938 >>> from sympy.polys.ring_series import rs_series
939 >>> from sympy.abc import a, b
940 >>> from sympy import sin, cos
941 >>> rs_series(sin(a + b), a, 4)
942 -1/2*(sin(b))*a**2 + (sin(b)) - 1/6*a**3*(cos(b)) + a*(cos(b))
```

943 **9.2.2. Formal Power Series.** SymPy can be used for computing the Formal
 944 Power Series of a function. The implementation is based on the algorithm described
 945 in the paper on Formal Power Series [28]. The advantage of this approach is that an
 946 explicit formula for the coefficients of the series expansion is generated rather than
 947 just computing a few terms.

948 The following example shows how to use `fps`:

```
949 >>> f = fps(sin(x), x, x0=0)
950 >>> f.truncate(6)
951 x - x**3/6 + x**5/120 + O(x**6)
952 >>> f[15]
953 -x**15/1307674368000
```

954 **9.2.3. Fourier Series.** SymPy provides functionality to compute Fourier se-
 955 ries of a function using the `fourier_series` function. Under the hood, this function
 956 computes a_0 , a_n , b_n coefficients using standard integration formulas.

957 Here's an example on how to compute Fourier series in SymPy:

```
958 >>> L = symbols('L')
959 >>> expr = 2 * (Heaviside(x/L) - Heaviside(x/L - 1)) - 1
960 >>> f = fourier_series(expr, (x, 0, 2*L))
961 >>> f.truncate(3)
962 4*sin(pi*x/L)/pi + 4*sin(3*pi*x/L)/(3*pi) + 4*sin(5*pi*x/L)/(5*pi)
```

963 **9.3. Logic.** SymPy supports construction and manipulation of boolean expres-
 964 sions through the `logic` module. SymPy symbols can be used as propositional vari-
 965 ables and also be substituted as `True` or `False`. A good number of manipulation
 966 features for boolean expressions have been implemented in the `logic` module.

967 **9.3.1. Constructing boolean expressions.** A boolean variable can be de-
 968 clared as a SymPy symbol. Python operators `&`, `|` and `~` are overloaded to use the
 969 SymPy functionality for logical `And`, `Or`, and `negate`. Other logic functions are also
 970 integrated into SymPy, including `Xor` and `Implies`, which are constructed with `^` and
 971 `>>`, respectively. The above are just a shorthand, expressions can also be constructed
 972 by directly creating the relevant objects: `And()`, `Or()`, `Not()`, `Xor()`, `Nand()`, `Nor()`,
 973 etc.

```
974 >>> from sympy import *
975 >>> x, y, z = symbols('x y z')
976 >>> e = (x & y) | z
977 >>> e.subs({x: True, y: True, z: False})
```

978 True

979 **9.3.2. CNF and DNF.** Any boolean expression can be converted to conjunctive
980 normal form, disjunctive normal form, and negation normal form. The API also
981 exposes methods to check if a boolean expression is in any of the above mentioned
982 forms.

```
983 >>> from sympy.logic.boolalg import is_dnf, is_cnf
984 >>> x, y, z = symbols('x y z')
985 >>> to_cnf((x & y) | z)
986 And(Or(x, z), Or(y, z))
987 >>> to_dnf(x & (y | z))
988 Or(And(x, y), And(x, z))
989 >>> is_cnf((x | y) & z)
990 True
991 >>> is_dnf((x & y) | z)
992 True
```

993 **9.3.3. Simplification and Equivalence.** The module supports simplification
994 of given boolean expression by making deductions from the expression. Equivalence
995 of two logical expressions can also be checked. In the case of equivalence, it is possible
996 to return the mapping of variables in two expressions so as to represent the same
997 logical behaviour.

```
998 >>> from sympy import *
999 >>> a, b, c, x, y, z = symbols('a b c x y z')
1000 >>> e = a & (~a | ~b) & (a | c)
1001 >>> simplify(e)
1002 And(Not(b), a)
1003 >>> e1 = a & (b | c)
1004 >>> e2 = (x & y) | (x & z)
1005 >>> bool_map(e1, e2)
1006 (And(Or(b, c), a), {a: x, b: y, c: z})
```

1007 **9.3.4. SAT solving.** The module also supports satisfiability (SAT) checking of
1008 a given boolean expression. If satisfiable, it is possible to return a model for which the
1009 expression is satisfiable. The API also supports returning all possible models. The
1010 SAT solver has a clause learning DPLL algorithm implemented with a watch literal
1011 scheme and VSIDS heuristic[35].

```
1012 >>> from sympy import *
1013 >>> a, b, c = symbols('a b c')
1014 >>> satisfiable(a & (~a | b) & (~b | c) & ~c)
1015 False
1016 >>> satisfiable(a & (~a | b) & (~b | c) & c)
1017 {a: True, b: True, c: True}
```

1018 **9.4. Diophantine Equations.** Diophantine equations play a central and an im-
1019 portant role in number theory. A Diophantine equation has the form, $f(x_1, x_2, \dots, x_n) =$
1020 0 where $n \geq 2$ and x_1, x_2, \dots, x_n are integer variables. If we can find n integers
1021 a_1, a_2, \dots, a_n such that $x_1 = a_1, x_2 = a_2, \dots, x_n = a_n$ satisfies the above equation, we
1022 say that the equation is solvable.

1023 Currently, the following five types of Diophantine equations can be solved using
1024 SymPy's Diophantine module.

1025 • Linear Diophantine equations: $a_1x_1 + a_2x_2 + \dots + a_nx_n = b$

```

1026     • General binary quadratic equation:  $ax^2 + bxy + cy^2 + dx + ey + f = 0$ 
1027     • Homogeneous ternary quadratic equation:  $ax^2 + by^2 + cz^2 + dxy + eyz + fzx = 0$ 
1028     • Extended Pythagorean equation:  $a_1x_1^2 + a_2x_2^2 + \cdots + a_nx_n^2 = a_{n+1}x_{n+1}^2$ 
1029     • General sum of squares:  $x_1^2 + x_2^2 + \cdots + x_n^2 = k$ 
1030     When an equation is fed into Diophantine module, it factors the equation (if
1031     possible) and solves each factor separately. Then, all the results are combined to
1032     create the final solution set. The following examples illustrate some of the basic
1033     functionalities of the Diophantine module.
1034     >>> from sympy import symbols
1035     >>> x, y, z = symbols("x, y, z", integer=True)
1036
1037     >>> from sympy.solvers.diophantine import *
1038     >>> diophantine(2*x + 3*y - 5)
1039     set([(3*t_0 - 5, -2*t_0 + 5)])
1040
1041     >>> diophantine(2*x + 4*y - 3)
1042     set()
1043
1044     >>> diophantine(x**2 - 4*x*y + 8*y**2 - 3*x + 7*y - 5)
1045     set([(2, 1), (5, 1)])
1046
1047     >>> diophantine(x**2 - 4*x*y + 4*y**2 - 3*x + 7*y - 5)
1048     set([(-2*t**2 - 7*t + 10, -t**2 - 3*t + 5)])
1049
1050     >>> diophantine(3*x**2 + 4*y**2 - 5*z**2 + 4*x*y - 7*y*z + 7*z*x)
1051     set([(-16*p**2 + 28*p*q + 20*q**2,
1052     3*p**2 + 38*p*q - 25*q**2,
1053     4*p**2 - 24*p*q + 68*q**2)])
1054
1055     >>> from sympy.abc import a, b, c, d, e, f
1056     >>> diophantine(9*a**2 + 16*b**2 + c**2 + 49*d**2 + 4*e**2 - 25*f**2)
1057     set([(70*t1**2 + 70*t2**2 + 70*t3**2 + 70*t4**2 - 70*t5**2, 105*t1*t5,
1058     420*t2*t5, 60*t3*t5, 210*t4*t5,
1059     42*t1**2 + 42*t2**2 + 42*t3**2 + 42*t4**2 + 42*t5**2)])
1060
1061     >>> diophantine(a**2 + b**2 + c**2 + d**2 + e**2 + f**2 - 112)
1062     set([(8, 4, 4, 4, 0, 0)])

```

1063 **9.5. Sets.** SymPy supports representation of a wide variety of mathematical
1064 sets. This is achieved by first defining abstract representations of atomic set classes
1065 and then combining and transforming them using various set operations.

1066 Each of the set classes inherits from the base class `Set` and defines methods to
1067 check membership and calculate unions, intersections, and set differences. When these
1068 methods are not able to evaluate to atomic set classes, they are represented as abstract
1069 unevaluated objects.

1070 SymPy has the following atomic set classes:

- 1071 • `EmptySet` represents the empty set \emptyset .
- 1072 • `UniversalSet` is an abstract “universal set” for which everything is a member.
1073 The union of the universal set with any set gives the universal set and the
1074 intersection gives the other set itself.

- **FiniteSet** is functionally equivalent to Python's built in `set` object. Its members can be any SymPy object including other sets.
- **Integers** represents the set of integers \mathbb{Z} .
- **Naturals** represents the set of natural numbers \mathbb{N} , i.e., the set of positive integers.
- **Naturals0** represents the set of whole numbers \mathbb{N}^0 , which are all the non-negative integers.
- **Range** represents a range of integers. A range is defined by specifying a start value, an end value, and a step size. The enumeration of a **Range** object is functionally equivalent to Python's `range` except it supports infinite endpoints, allowing the representation of infinite ranges.
- **Interval** represents an interval of real numbers. It is specified by giving the start and end point and specifying if it is open or closed in the respective ends.

Other than unevaluated classes of **Union**, **Intersection**, and **Complement** operations, we have following set classes.

- **ProductSet** defines the Cartesian product of two or more sets. The product set is useful when representing higher dimensional spaces. For example, to represent a three-dimensional space, we simply take the Cartesian product of three real sets.
- **ImageSet** represents the image of a function when applied to a particular set. The image set of a function F with respect to a set S is $\{F(x)|x \in S\}$. SymPy uses image sets to represent sets of infinite solutions equations such as $\sin(x) = 0$.
- **ConditionSet** represents a subset of a set whose members satisfies a particular condition. The condition set of the set S with respect to the condition H is $\{x|H(x), x \in S\}$. SymPy uses condition sets to represent the set of solutions of equations and inequalities, where the equation or the inequality is the condition and the set is the domain being solved over.

A few other classes are implemented as special cases of the classes described above. The set of real numbers, **Reals**, is implemented as a special case of **Interval** over the interval $(-\infty, \infty)$. **ComplexRegion** is implemented as a special case of **ImageSet**. **ComplexRegion** supports both polar and rectangular representation of regions on the complex plane.

9.6. Category Theory. SymPy includes a basic version of the module for dealing with categories — abstract mathematical objects representing classes of structures as classes of objects (points) and morphisms (arrows) between the objects. This version of the module was designed with the following two goals in mind:

1. automatic typesetting of diagrams given by a collection of objects and of morphisms between them, and
2. specification and (semi-)automatic derivation of properties using commutative diagrams.

At of version 1.0, SymPy only implements the first goal, while a (very partially working) draft of implementation of the second goal is available at [2].

In order to achieve the two goals, the module **categories** defines several classes representing some of the essential concepts: objects, morphisms, categories, and diagrams. In category theory, the inner structure of objects is often discarded in the favour of studying the properties of morphisms, so the class **Object** is essentially a synonym of the class **Symbol**. There are several morphism classes which do not have a

particular internal structure either, though an exception is `CompositeMorphism`, which essentially stores a list of morphisms.

To capture the properties of morphisms, the class `Diagram` is expected to be used. This class stores a family of morphisms, the corresponding source and target objects, and, possibly, some properties of the morphisms. Generally, no restrictions are imposed on what the properties may be — for example, one might use strings of the form “forall”, “exists”, “unique”, etc. Furthermore, the morphisms of a diagram are grouped into *premises* and *conclusions*, in order to be able to represent logical implications of the form “for a collection of morphisms P with properties $p : P \rightarrow \Omega$ (the premises), there exists a collection of morphisms C with properties $c : C \rightarrow \Omega$ (the conclusions),” where Ω is the universal collection of properties. Finally, the class `Category` includes a collection of diagrams which are deemed commutative and which therefore define the properties of this category.

Automatic typesetting of diagrams takes a `Diagram` and produces L^AT_EX code using the `Xy-pic` package. Typesetting is done in two stages: layout and generation of `Xy-pic` code. The layout stage is taken care of by the class `DiagramGrid`, which takes a `Diagram` and lays out the objects in a grid, trying to reduce the average length of the arrows in the final picture. By default, `DiagramGrid` uses a series of triangle-based heuristics to produce a rectangular grid. A linear layout can also be imposed. Furthermore, groups of objects can be given; in this case, the groups will be treated as atomic cells, and the member objects will be typeset independently of the other objects.

The second phase of diagram typesetting consists of actually drawing the picture and is carried out by the class `XypicDiagramDrawer`. An example of a diagram automatically typeset by `DiagramGrid` and `XypicDiagramDrawer` is given in Figure 2.

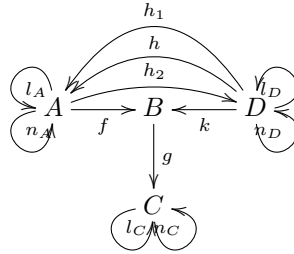


Fig. 2: An automatically typeset commutative diagram

As far as the second main goal of the module is concerned, a (non-working) draft of an implementation is at [2]. The principal idea consists of automatically deciding whether a diagram is commutative or not, given a collection of “axioms” — diagrams *known* to be commutative. The implementation is based on graph embeddings (injective maps): whenever an embedding of a commutative diagram into a given diagram is found, one concludes that the subdiagram is commutative. Deciding commutativity of the whole diagram is therefore based (theoretically) on finding a “cover” of the target diagram by embeddings of the axioms. The naïve implementation proved to be prohibitively slow; a better optimised version is therefore in order, as well as application of heuristics.

Contributions to automatic inference of commutativity of diagrams are welcome. The source code (both the one in master and in `ct4-commutativity`) is extensively documented. Even more extensive explanations (including some literary chatter) are given at [3].

9.7. SymPy Gamma. SymPy Gamma is a simple web application that runs on Google App Engine. It executes and displays the results of SymPy expressions as well as additional related computations, in a fashion similar to that of Wolfram|Alpha. For instance, entering an integer will display its prime factors, digits in the base-10 expansion, and a factorization diagram. Entering a function will display its docstring; in general, entering an arbitrary expression will display its derivative, integral, series expansion, plot, and roots.

SymPy Gamma also has several additional features than just computing the results using SymPy.

- SymPy Gamma displays integration and differentiation steps in detail, which can be viewed in Figure 3:

Integral Steps:
`integrate(tan(x), x)`

Fullscreen

- Rewrite the integrand:
$$\tan(x) = \frac{\sin(x)}{\cos(x)}$$
- Let $u = \cos(x)$.
Then let $du = -\sin(x)dx$ and substitute du :
$$\int -\frac{1}{u} du$$

A. The integral of a constant times a function is the constant times the integral of the function:

$$\int -\frac{1}{u} du = - \int \frac{1}{u} du$$

I. The integral of $\frac{1}{u}$ is $\log(u)$.

So, the result is: $-\log(u)$

Now substitute u back in:

$$-\log(\cos(x))$$
- Add the constant of integration:
$$-\log(\cos(x)) + \text{constant}$$

The answer is:

$$-\log(\cos(x)) + \text{constant}$$

Fig. 3: Integral steps of $\tan(x)$

- SymPy Gamma displays the factor tree diagrams for different numbers.
- SymPy Gamma saves user search queries, and offers many such similar features for free, which Wolfram|Alpha only offers to its paid users.

Every input query from the user on SymPy Gamma is first parsed by its own parser, which handles several different forms of function names, which SymPy as a library does not support. For instance, SymPy Gamma supports queries like `sin x`, whereas SymPy does not support this, and supports only `sin(x)`.

This parser converts the input query to the equivalent SymPy readable code, which is then eventually processed by SymPy, and the result is finally printed with the built-in LaTeX output and rendered on the SymPy Gamma web-application.

9.8. SymPy Live. SymPy Live is an online Python shell, which runs on Google App Engine, that executes SymPy code. It is integrated in the SymPy documentation examples, located at this [link](#).

This is accomplished by providing a HTML/JavaScript GUI for entering source code and visualization of output, and a server that evaluates the requested source code. It is an interactive AJAX shell that runs SymPy code using Python on the server.

Certain Features of SymPy Live:

- It supports the exact same syntax as SymPy, hence it can be used easily to test for outputs from various SymPy expressions.
- It can be run as a standalone app or in an existing app as an admin-only handler, and can also be used for system administration tasks, as an interactive way to try out APIs, or as a debugging aid during development.
- It can also be used to plot figures ([link](#)), and execute all kinds of expressions that SymPy can evaluate.
- SymPy Live also renders the output in LaTeX for pretty-printing the output.

9.9. Comparison with Mathematica. Wolfram Mathematica is a popular proprietary CAS. It features highly advanced algorithms. Mathematica has a core implemented in C++ [8] which interprets its own programming language (known as Wolfram language).

Analogous to Lisp's S-expressions, Mathematica uses its own style of M-expressions, which are arrays of either atoms or other M-expression. The first element of the expression identifies the type of the expression and is indexed by zero, whereas the first argument is indexed by one. Notice that SymPy expression arguments are stored in a Python tuple (that is, an immutable array), while the expression type is identified by the type of the object storing the expression.

Mathematica can associate attributes to its atoms. Attributes may define mathematical properties and behavior of the nodes associated to the atom. In SymPy, the usage of static class fields is roughly similar to Mathematica's attributes, though other programming patterns may also be used to achieve an equivalent behavior, such as class inheritance.

Unlike SymPy, Mathematica's expressions are mutable, that is one can change parts of the expression tree without the need of creating a new object. The mutability of Mathematica allows for a lazy updating of any references to that data structure.

Products in Mathematica are determined by some builtin node types, such as `Times`, `Dot`, and others. `Times` is a representation of the `*` operator, and is always meant to represent a commutative product operator. The other notable product is `Dot`, which represents the `.` operator. This product represents matrix multiplication, it is not commutative. In general, SymPy uses the same node for both scalar and matrix multiplication, the only exception being with abstract matrix symbols. Unlike Mathematica, SymPy determines commutativity with respect to multiplication from the factor's expression type. Mathematica puts the `Orderless` attribute on the

expression type.

Regarding associative expressions, SymPy handles associativity by making associative expressions inherit the class `AssocOp`, while Mathematica specifies the `Flat` [4] attribute on the expression type.

Mathematica relies heavily on pattern matching — even the so-called equivalent of function declaration is in reality the definition of a pattern matching generating an expression tree transformation on input expressions. Mathematica’s pattern matching is sensitive to associative [4], commutative [5], and one-identity [6] properties of its expression tree nodes [7]. SymPy has various ways to perform pattern matching. All of them play a lesser role in the CAS than in Mathematica and are basically available as a tool to rewrite expressions. The differential equation solver in SymPy somewhat relies on pattern matching to identify the kind of differential equation, but it is envisaged to replace that strategy with analysis of Lie symmetries in the future. Mathematica’s real advantage is the ability to add new overloading to the expression builder at runtime, or for specific subnodes. Consider for example:

```
In[1]:= Unprotect[Plus]
Out[1]= {Plus}
In[2]:= Sin[x_]^2 + Cos[y_]^2 := 1
In[3]:= x + Sin[t]^2 + y + Cos[t]^2
Out[3]= 1 + x + y
```

This expression in Mathematica defines a substitution rule that overloads the functionality of the `Plus` node (the node for additions in Mathematica). The trailing underscore after a symbol means that it is to be considered a wildcard. This example may not be practical, one may wish to keep this identity unevaluated. Nevertheless, it clearly illustrates the potential to define one’s own immediate transformation rules. In SymPy, the operations constructing the addition node in the expression tree are Python class constructors and cannot be modified at runtime.⁴ The way SymPy deals with extending the missing runtime overloadability functionality is by subclassing the node types. Subclasses may overload the class constructor to yield the proper extended functionality.

Unlike SymPy, Mathematica does not support type inheritance or polymorphism [20]. SymPy relies heavily on class inheritance, but for the most part, class inheritance is used to make sure that SymPy objects inherit the proper methods and implement the basic hashing system. Associativity of expressions can be achieved by inheriting the class `AssocOp`, which may appear a more cumbersome operation than Mathematica’s attribute setting.

Matrices in SymPy are types on their own. In Mathematica, nested lists are interpreted as matrices whenever the sublists have the same length. The main difference to SymPy is that ordinary operators and functions do not get generalized the same way as used in traditional mathematics. Using the standard multiplication in Mathematica performs an elementwise product, this is compatible with Mathematica’s convention of commutativity of `Times` nodes. Matrix product is expressed by the *dot* operator, or the `Dot` node. The same is true for the other operators, and

⁴In reality, Python supports monkey patching, nonetheless, it is a discouraged programming pattern.

even functions, most notably calling the exponential function `Exp` on a matrix returns an elementwise exponentiation of its elements. The real matrix exponentiation is available through the `MatrixExp` function.

Unevaluated expressions in Mathematica can be achieved in various ways, most commonly with the `HoldForm` or `Hold` nodes, that block the evaluation of subnodes by the parser. Note that such a node cannot be expressed in Python, because of greedy evaluation. Whenever needed in SymPy, it is necessary to add the parameter `evaluate=False` to all subnodes, or put the input expression in a string.

In Mathematica, the operator `==` returns a boolean whenever it is able to immediately evaluate the truth of the equality, otherwise it returns an `Equal` expression. In SymPy, `==` means structural equality and is always guaranteed to return a boolean expression. To express an equality in SymPy it is necessary to explicitly construct an object of the `Equality` class.

SymPy, in accordance with Python and unlike the usual programming convention, uses `**` to express the power operator, while Mathematica uses the more common `^`.

9.10. Other Projects that use SymPy. There are several projects that use SymPy as a library for implementing a part of their project, or even as a part of back-end for their application as well.

Some of them are listed below:

- **Cadabra:** Cadabra is a symbolic computer algebra system (CAS) designed specifically for the solution of problems encountered in field theory.
- **Octave Symbolic:** The Octave-Forge Symbolic package adds symbolic calculation features to GNU Octave. These include common Computer Algebra System tools such as algebraic operations, calculus, equation solving, Fourier and Laplace transforms, variable precision arithmetic and other features.
- **SymPy.jl:** Provides a Julia interface to SymPy using PyCall.
- **Mathics:** Mathics is a free, general-purpose online CAS featuring Mathematica compatible syntax and functions. It is backed by highly extensible Python code, relying on SymPy for most mathematical tasks.
- **Mathpix:** An iOS App, that uses Artificial Intelligence to detect handwritten math as input, and uses SymPy Gamma, to evaluate the math input and generate the relevant steps to solve the problem.
- **IKFast:** IKFast is a robot kinematics compiler provided by **OpenRAVE**. It analytically solves robot inverse kinematics equations and generates optimized C++ files. It uses SymPy for its internal symbolic mathematics.
- **Sage:** A CAS, visioned to be a viable free open source alternative to Magma, Maple, Mathematica and Matlab.
- **SageMathCloud:** SageMathCloud is a web-based cloud computing and course management platform for computational mathematics.
- **PyDy:** Multibody Dynamics with Python.
- **galgebra:** Geometric algebra (previously `sympy.galgebra`).
- **yt:** Python package for analyzing and visualizing volumetric data (`yt.units` uses SymPy).
- **SfePy:** Simple finite elements in Python, see section 9.11.1.
- **Quameon:** Quantum Monte Carlo in Python.
- **Lcapy:** Experimental Python package for teaching linear circuit analysis.
- **Quantum Programming in Python:** Quantum 1D Simple Harmonic Oscillator and Quantum Mapping Gate.

- **LaTeX Expression project:** Easy LaTeX typesetting of algebraic expressions in symbolic form with automatic substitution and result computation.
- **Symbolic statistical modeling:** Adding statistical operations to complex physical models.

9.11. Project Details. Below we provide particular examples of SymPy use in some of the projects listed above.

9.11.1. SfePy. **SfePy** (Simple finite elements in Python), cf. [19]. is a Python package for solving partial differential equations (PDEs) in 1D, 2D and 3D by the finite element (FE) method [54]. SymPy is used within this package mostly for code generation and testing, namely:

- generation of the hierarchical FE basis module, involving generation and symbolic differentiation of 1D Legendre and Lobatto polynomials, constructing the FE basis polynomials [47] and generating the C code;
- generation of symbolic conversion formulas for various groups of elastic constants [24] – provide any two of the Young’s modulus, Poisson’s ratio, bulk modulus, Lamé’s first parameter, shear modulus (Lamé’s second parameter) or longitudinal wave modulus and get the other ones;
- simple physical unit conversions, generation of consistent unit sets;
- testing FE solutions using method of manufactured (analytical) solutions – the differential operator of a PDE is symbolically applied and a symbolic right-hand side is created, evaluated in quadrature points, and subsequently used to obtain a numerical solution that is then compared to the analytical one;
- testing accuracy of 1D, 2D and 3D numerical quadrature formulas (cf. [9]) by generating polynomials of suitable orders, integrating them, and comparing the results with those obtained by the numerical quadrature.

9.12. Tensors. Ongoing work to provide the capabilities of tensor computer algebra has so far produced the `tensor` module. It is composed of three separated submodules, whose purposes are quite different: `tensor.indexed` and `tensor.indexed_methods` support indexed symbols, `tensor.array` contains facilities to operator on symbolic N -dimensional arrays, and finally `tensor.tensor` is used to define abstract tensors. The abstract tensors subsection is inspired by xAct [34] and Cadabra [39]. Canonicalization based on the Butler-Portugal [33] algorithm is supported in SymPy. It is currently limited to polynomial tensor expressions.