

# SymPy: Symbolic Computing in Python

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## 55 **ABSTRACT**

56 SymPy is an open source computer algebra system written in pure Python. It is built with a focus on  
57 extensibility and ease of use, through both interactive and programmatic applications. These characteristics  
58 have led SymPy to become a popular symbolic library for the scientific Python ecosystem. This paper  
59 presents the architecture of SymPy, a description of its features, and a discussion of select domain specific  
60 submodules. The supplementary materials provide additional examples and further outline details of the  
61 architecture and features of SymPy.

62 **Keywords:** symbolic, Python, computer algebra system

## 63 **1 INTRODUCTION**

64 SymPy is a full featured computer algebra system (CAS) written in the Python [28] programming  
65 language. It is free and open source software, licensed under the 3-clause BSD license [40].  
66 The SymPy project was started by Ondřej Čertík in 2005, and it has since grown to over 500  
67 contributors. Currently, SymPy is developed on GitHub using a bazaar community model [36].  
68 The accessibility of the codebase and the open community model allow SymPy to rapidly respond  
69 to the needs of users and developers.

70 Python is a dynamically typed programming language that has a focus on ease of use and  
71 readability.<sup>1</sup> Due in part to this focus, it has become a popular language for scientific computing  
72 and data science, with a broad ecosystem of libraries [31]. SymPy is itself used by many libraries  
73 and tools to support research within a variety of domains, such as SageMath [46] (pure and  
74 applied mathematics), yt [49] (astronomy and astrophysics), PyDy [16] (multibody dynamics),  
75 and SfePy [10] (finite elements).

76 Unlike many CASs, SymPy does not invent its own programming language. Python itself  
77 is used both for the internal implementation and end user interaction. By using the operator  
78 overloading functionality of Python, SymPy follows the embedded domain specific language  
79 paradigm proposed by Hudak [21]. The exclusive usage of a single programming language makes  
80 it easier for people already familiar with that language to use or develop SymPy. Simultaneously,  
81 it enables developers to focus on mathematics, rather than language design. SymPy officially  
82 supports Python 2.6, 2.7 and 3.2–3.5.

83 SymPy is designed with a strong focus on usability as a library. Extensibility is important in  
84 its application program interface (API) design. Thus, SymPy makes no attempt to extend the  
85 Python language itself. The goal is for users of SymPy to be able to include SymPy alongside  
86 other Python libraries in their workflow, whether that be in an interactive environment or as a  
87 programmatic part in a larger system.

88 As a library, SymPy does not have a built-in graphical user interface (GUI). However,  
89 SymPy exposes a rich interactive display system, and supports registering display formatters  
90 with Jupyter [25] frontends, including the Notebook and Qt Console, which will render SymPy  
91 expressions using MathJax [9] or  $\text{\LaTeX}$ .

92 The remainder of this paper discusses key components of the SymPy library. Section 2  
93 discusses the architecture of SymPy. Section 3 enumerates the features of SymPy and takes  
94 a closer look at some of the important ones. The section 4 looks at the numerical features of  
95 SymPy and its dependency library, mpmath. Section 5 looks at the domain specific physics  
96 submodules for performing symbolic and numerical calculations in classical mechanics and  
97 quantum mechanics. Conclusions and future directions for SymPy are given in section 6. All  
98 examples in this paper use SymPy version 1.0 and mpmath version 0.19.

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<sup>1</sup>This paper assumes a moderate familiarity with the Python programming language.

99 The following statement imports all SymPy functions into the global Python namespace.<sup>2</sup>  
100 From here on, all examples in this paper assume that this statement has been executed.<sup>3</sup>

```
101 >>> from sympy import *
```

102 All examples could be tested on the SymPy Live instance, that is an online Python shell,  
103 which uses the Google App Engine to execute SymPy code.

## 104 2 ARCHITECTURE

105 Software architecture is of central importance in any large software project because it establishes  
106 predictable patterns of usage and development [42]. This section describes the essential structural  
107 components of SymPy, provides justifications for the design decisions that have been made, and  
108 gives example user-facing code as appropriate.

### 109 2.1 Basic Usage

110 Symbolic variables, called symbols, must be defined and assigned to Python variables before they  
111 can be used. This is typically done through the `symbols` function, which may create multiple  
112 symbols in a single function call. For instance,

```
113 >>> x, y, z = symbols('x y z')
```

114 creates three symbols representing variables named  $x$ ,  $y$ , and  $z$ . In this particular instance, these  
115 symbols are all assigned to Python variables of the same name. However, the user is free to  
116 assign them to different Python variables, while representing the same symbol, such as `a`, `b`,  
117 `c = symbols('x y z')`. In order to minimize potential confusion, though, all examples in this  
118 paper will assume that the symbols  $x$ ,  $y$ , and  $z$  have been assigned to Python variables identical  
119 to their symbolic names.

120 Expressions are created from symbols using Python's mathematical syntax. For instance, the  
121 following Python code creates the expression  $(x^2 - 2x + 3)/y$ . Note that the expression remains  
122 unevaluated: it is represented symbolically.

```
123 >>> (x**2 - 2*x + 3)/y  
124 (x**2 - 2*x + 3)/y
```

125 Importantly, SymPy expressions are immutable. This simplifies the design of SymPy by  
126 allowing expression interning. It also enables expressions to be hashed, that is used to implement  
127 caching in SymPy.

### 128 2.2 The Core

129 A computer algebra system stores mathematical expressions as data structures. For example,  
130 the mathematical expression  $x + y$  is represented as a tree with three nodes,  $+$ ,  $x$ , and  $y$ ,  
131 where  $x$  and  $y$  are ordered children of  $+$ . As users manipulate mathematical expressions  
132 with traditional mathematical syntax, the CAS manipulates the underlying data structures.  
133 Automated optimizations and computations such as integration, simplification, etc. are all  
134 functions that consume and produce expression trees.

135 In SymPy every symbolic expression is an instance of a Python `Basic` class,<sup>4</sup> a superclass  
136 of all SymPy types providing common methods to all SymPy tree-elements, such as traversals.  
137 The children of a node in the tree are held in the `args` attribute. A terminal or leaf node in the  
138 expression tree has empty `args`.

139 For example, consider the expression  $xy + 2$ :

---

<sup>2</sup>`import *` has been used here to aid the readability of the paper, but is best to avoid such wildcard import statements in production code, as they make it unclear which names are present in the namespace. Furthermore, imported names could clash with already existing imports from another package. For example, SymPy, the standard Python `math` library, and NumPy all define the `exp` function, but only the SymPy one will work with SymPy symbolic expressions.

<sup>3</sup>The three greater-than signs denote the user input for the Python interactive session, with the result, if there is one, shown on the next line.

<sup>4</sup>Some internal classes, such as those used in the polynomial submodule, do not follow this rule for efficiency reasons.

```
140 >>> expr = x*y + 2
```

141 By order of operations, the parent of the expression tree for `expr` is an addition, so it is of type  
142 `Add`. The child nodes of `expr` are 2 and `x*y`.

```
143 >>> type(expr)
144 <class 'sympy.core.add.Add'>
145 >>> expr.args
146 (2, x*y)
```

147 Descending further down into the expression tree yields the full expression. For example,  
148 the next child node (given by `expr.args[0]`) is 2. Its class is `Integer`, and it has an empty `args`  
149 tuple, indicating that it is a leaf node.

```
150 >>> expr.args[0]
151 2
152 >>> type(expr.args[0])
153 <class 'sympy.core.numbers.Integer'>
154 >>> expr.args[0].args
155 ()
```

156 Symbols or symbolic constants, like  $e$  or  $\pi$ , are examples of leaf nodes.

```
157 >>> exp(1)
158 E
159 >>> exp(1).args
160 ()
161 >>> x.args
162 ()
```

163 A useful way to view an expression tree is using the `srepr` function, which returns a string  
164 representation of an expression as valid Python code<sup>5</sup> with all the nested class constructor calls  
165 to create the given expression.

```
166 >>> srepr(expr)
167 "Add(Mul(Symbol('x'), Symbol('y')), Integer(2))"
```

168 Every SymPy expression satisfies a key identity invariant:

```
169 expr.func(*expr.args) == expr
```

170 This means that expressions are rebuildable from their `args`.<sup>6</sup> Note that in SymPy the `==`  
171 operator represents exact structural equality, not mathematical equality. This allows testing if  
172 any two expressions are equal to one another as expression trees. For example, even though  
173  $(x+1)^2$  and  $x^2+2x+1$  are equal mathematically, SymPy gives

```
174 >>> (x + 1)**2 == x**2 + 2*x + 1
175 False
```

176 because they are different as expression trees (the former is a `Pow` object and the latter is an `Add`  
177 object).

178 Python allows classes to override mathematical operators. The Python interpreter translates  
179 the above `x*y + 2` to, roughly, `(x.__mul__(y)).__add__(2)`. Both `x` and `y`, returned from the  
180 `symbols` function, are `Symbol` instances. The 2 in the expression is processed by Python as a  
181 literal, and is stored as Python's built in `int` type. When 2 is passed to the `__add__` method  
182 of `Symbol`, it is converted to the SymPy type `Integer(2)` before being stored in the resulting  
183 expression tree. In this way, SymPy expressions can be built in the natural way using Python  
184 operators and numeric literals.

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<sup>5</sup> The `dotprint` function from the `sympy.printing.dot` submodule prints output to dot format, which can be rendered with `Graphviz` to visualize expression trees graphically.

<sup>6</sup>`expr.func` is used instead of `type(expr)` to allow the function of an expression to be distinct from its actual Python class. In most cases the two are the same.

## 2.3 Assumptions

SymPy performs logical inference through its assumptions system. The assumptions system allows users to specify that symbols have certain common mathematical properties, such as being positive, imaginary, or integral. SymPy is careful to never perform simplifications on an expression unless the assumptions allow them. For instance, the identity  $\sqrt{t^2} = t$  holds if  $t$  is nonnegative ( $t \geq 0$ ). However, for general complex  $t$ , no such identity holds.

By default, SymPy performs all calculations assuming that symbols are complex valued. This assumption makes it easier to treat mathematical problems in full generality.

```
>>> t = Symbol('t')
>>> sqrt(t**2)
sqrt(t**2)
```

By assuming the most general case, that  $t$  is complex by default, SymPy avoids performing mathematically invalid operations. However, in many cases users will wish to simplify expressions containing terms like  $\sqrt{t^2}$ .

Assumptions are set on `Symbol` objects when they are created. For instance `Symbol('t', positive=True)` will create a symbol named  $t$  that is assumed to be positive.

```
>>> t = Symbol('t', positive=True)
>>> sqrt(t**2)
t
```

Some of the common assumptions that SymPy allows are `positive`, `negative`, `real`, `nonpositive`, `integer`, `prime` and `commutative`.<sup>7</sup> Assumptions on any object can be checked with the `is_assumption` attributes, like `t.is_positive`.

Assumptions are only needed to restrict a domain so that certain simplifications can be performed. They are not required to make the domain match the input of a function. For instance, one can create the object  $\sum_{n=0}^m f(n)$  as `Sum(f(n), (n, 0, m))` without setting `integer=True` when creating the `Symbol` object  $n$ .

The assumptions system additionally has deductive capabilities. The assumptions use a three-valued logic using the Python built in objects `True`, `False`, and `None`. Note that `False` is returned if the SymPy object doesn't or can't have the assumption. For example, both `I.is_real` and `I.is_prime` return `False` for the imaginary unit  $I$ .

`None` represents the “unknown” case. This could mean that given assumptions do not unambiguously specify the truth of an attribute. For instance, `Symbol('x', real=True).is_positive` will give `None` because a real symbol might be positive or negative. The `None` could also mean that not enough is known or implemented to compute the given fact. For instance, `(pi + E).is_irrational` gives `None`, because determining whether  $\pi + e$  is rational or irrational is an open problem in mathematics [27].

Basic implications between the facts are used to deduce assumptions. For instance, the assumptions system knows that being an integer implies being rational.

```
>>> i = Symbol('i', integer=True)
>>> i.is_rational
True
```

Furthermore, expressions compute the assumptions on themselves based on the assumptions of their arguments. For instance, if  $x$  and  $y$  are both created with `positive=True`, then `(x + y).is_positive` will be `True` whereas `(x - y).is_positive` will be `None`.

## 2.4 Extensibility

While the core of SymPy is relatively small, it has been extended to a wide variety of domains by a broad range of contributors. This is due, in part, to the fact that the same language, Python, is used both for the internal implementation and the external usage by users. All of

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<sup>7</sup>SymPy assumes that two expressions  $A$  and  $B$  commute with each other multiplicatively, that is,  $A \cdot B = B \cdot A$ , unless they both have `commutative=False`. Many algorithms in SymPy require special consideration to work correctly with noncommutative products.

the extensibility capabilities available to users are also utilized by SymPy itself. This eases the transition pathway from SymPy user to SymPy developer.

The typical way to create a custom SymPy object is to subclass an existing SymPy class, usually `Basic`, `Expr`, or `Function`. As it was stated before, all SymPy classes used for expression trees should be subclasses of the base class `Basic`. `Expr` is the `Basic` subclass for mathematical that can be added and multiplied together. The most commonly seen classes in SymPy are subclasses of `Expr`, including `Add`, `Mul`, and `Symbol`. Instances of `Expr` typically represent complex numbers, but may also include other “rings”, like matrix expressions. Not all SymPy classes are subclasses of `Expr`. For instance, logic expressions, such as `And(x, y)`, are subclasses of `Basic` but not of `Expr`.

The `Function` class is a subclass of `Expr` which makes it easier to define mathematical functions called with arguments. This includes named functions like  $\sin(x)$  and  $\log(x)$  as well as undefined functions like  $f(x)$ . Subclasses of `Function` should define a class method `eval`, which returns a canonical form of the function application (usually an instance of some other class, i.e. a `Number`) or `None`, if for given arguments that function should not be automatically evaluated.

Many SymPy functions perform various evaluations down the expression tree. Classes define their behavior in such functions by defining a relevant `_eval_*` method. For instance, an object can indicate to the `diff` function how to take the derivative of itself by defining the `_eval_derivative(self, x)` method, which may in turn call `diff` on its `args`. (Subclasses of `Function` should implement `fdiff` method instead, it returns the derivative of the function without considering the chain rule.) The most common `_eval_*` methods relate to the assumptions: `_eval_is_assumption` is used to deduce *assumption* on the object.

As an example of the notions presented in this section, Listing 1 presents a minimal version of the gamma function  $\Gamma(x)$  from SymPy, which evaluates itself on positive integer arguments, has the positive and real assumptions defined, can be rewritten in terms of factorial with `gamma(x).rewrite(factorial)`, and can be differentiated. `self.func` is used throughout instead of referencing `gamma` explicitly so that potential subclasses of `gamma` can reuse the methods.

**Listing 1.** A minimal implementation of `sympy.gamma`.

```
from sympy import Integer, Function, floor, factorial, polygamma

class gamma(Function)
    @classmethod
    def eval(cls, arg):
        if isinstance(arg, Integer) and arg.is_positive:
            return factorial(arg - 1)

    def _eval_is_positive(self):
        x = self.args[0]
        if x.is_positive:
            return True
        elif x.is_noninteger:
            return floor(x).is_even

    def _eval_is_real(self):
        x = self.args[0]
        # noninteger means real and not integer
        if x.is_positive or x.is_noninteger:
            return True

    def _eval_rewrite_as_factorial(self, z):
        return factorial(z - 1)

    def fdiff(self, argindex=1):
        from sympy.core.function import ArgumentIndexError
```

```

286         if argindex == 1:
287             return self.func(self.args[0])*polygamma(0, self.args[0])
288         else:
289             raise ArgumentIndexError(self, argindex)

```

290 The gamma function implemented in SymPy has many more capabilities than the above listing,  
291 such as evaluation at rational points and series expansion.

## 292 2.5 Speed

293 Due to being written in pure Python, SymPy's speed is generally slower compared with its  
294 commercial competitors. For many applications and uses of SymPy, that is not a problem, as  
295 SymPy is able to return the answer quickly enough, but for some applications that require  
296 handling of very long expressions and/or lots of small expressions, the speed becomes a problem.

297 For this reason, a new library called SymEngine [47] was started. It is a pure C++ library  
298 with thin wrappers to other languages (Python, Ruby, Julia, ...) whose aim is to be the fastest  
299 manipulation library. Preliminary benchmarks suggest that SymEngine is as fast or faster than  
300 the commercial or open source competitors.

301 SymPy recently started to use SymEngine as an optional backend, initially in `sympy.mechanics`  
302 only. The plan is to allow more algorithms in SymPy to take advantage of the speed of  
303 SymEngine.

## 304 3 FEATURES

305 Although SymPy's extensive feature set cannot be covered in-depth in this paper, calculus and  
306 other bedrock areas are discussed in their own subsections. Additionally, Table 1 gives a compact  
307 listing of all major capabilities present in the SymPy codebase. This grants a sampling from the  
308 breadth of topics and application domains that SymPy services. Unless stated otherwise, all  
309 features noted in Table 1 are symbolic in nature. Numeric features are discussed in Section 4.

**Table 1.** SymPy Features and Descriptions

Feature(submodules)	Description
Calculus (core, series, integrals)	Algorithms for computing derivatives, integrals, and limits.
Category Theory (categories)	Representation of objects, morphisms, and diagrams. Tools for drawing diagrams with Xy-pic.
Code Generation (printing, codegen)	Generation of compilable and executable code in a variety of different programming languages from expressions directly. Target languages include C, Fortran, Julia, JavaScript, Mathematica, MATLAB and Octave, Python, and Theano.
Combinatorics & Group Theory (combinatorics)	Permutations, combinations, partitions, subsets, various permutation groups (such as polyhedral, Rubik, symmetric, and others), Gray codes [30], and Prufer sequences [4].
Concrete Math (concrete)	Summation, products, tools for determining whether summation and product expressions are convergent, absolutely convergent, hypergeometric, and for determining other properties; computation of Gosper's normal form [35] for two univariate polynomials.
Cryptography (crypto)	Block and stream ciphers, including shift, Affine, substitution, Vigenère's, Hill's, bifid, RSA, Kid RSA, linear-feedback shift registers, and Elgamal encryption.
Differential Geometry (diff-geom)	Representations of manifolds, metrics, tensor products, and coordinate systems in Riemannian and pseudo-Riemannian geometries [43].

Geometry (geometry)	Representations of 2D geometrical entities, such as lines and circles. Enables queries on these entities, such as asking the area of an ellipse, checking for collinearity of a set of points, or finding the intersection between objects.
Lie Algebras (liealgebras)	Representations of Lie algebras and root systems.
Logic (logic)	Boolean expressions, equivalence testing, satisfiability, and normal forms.
Matrices (matrices)	Tools for creating matrices of symbols and expressions. Both sparse and dense representations, as well as symbolic linear algebraic operations (e.g., inversion and factorization), are supported.
Matrix Expressions (matrixes.expressions)	Matrices with symbolic dimensions (unspecified entries). Block matrices.
Number Theory (nththeory)	Prime number generation, primality testing, integer factorization, continued fractions, Egyptian fractions, modular arithmetic, quadratic residues, partitions, binomial and multinomial coefficients, prime number tools, hexadecimal digits of $\pi$ , and integer factorization.
Plotting (plotting)	Hooks for visualizing expressions via matplotlib [22] or as text drawings when lacking a graphical back-end. 2D function plotting, 3D function plotting, and 2D implicit function plotting are supported.
Polynomials (polys)	Polynomial algebras over various coefficient domains. Functionality ranges from simple operations (e.g., polynomial division) to advanced computations (e.g., Gröbner bases [1] and multivariate factorization over algebraic number domains).
Printing (printing)	Functions for printing SymPy expressions in the terminal with ASCII or Unicode characters and converting SymPy expressions to $\text{\LaTeX}$ and MathML.
Quantum Mechanics (physics.quantum)	Quantum states, bra-ket notation, operators, basis sets, representations, tensor products, inner products, outer products, commutators, anticommutators, and specific quantum system implementations.
Series (series)	Series expansion, sequences, and limits of sequences. This includes Taylor, Laurent, and Puiseux series as well as special series, such as Fourier and formal power series.
Sets (sets)	Representations of empty, finite, and infinite sets (including special sets such as the natural, integer, and complex numbers). Operations on sets such as union, intersection, Cartesian product, and building sets from other sets are supported.
Simplification (simplify)	Functions for manipulating and simplifying expressions. Includes algorithms for simplifying hypergeometric functions, trigonometric expressions, rational functions, combinatorial functions, square root denesting, and common subexpression elimination.
Solvers (solvers)	Functions for symbolically solving equations, systems of equations, both linear and non-linear, inequalities, ordinary differential equations, partial differential equations, Diophantine equations, and recurrence relations.



Special Functions (functions)	Implementations of a number of well known special functions, including Dirac delta, Gamma, Beta, Gauss error functions, Fresnel integrals, Exponential integrals, Logarithmic integrals, Trigonometric integrals, Bessel, Hankel, Airy, B-spline, Riemann Zeta, Dirichlet eta, polylogarithm, Lerch transcendent, hypergeometric, elliptic integrals, Mathieu, Jacobi polynomials, Gegenbauer polynomial, Chebyshev polynomial, Legendre polynomial, Hermite polynomial, Laguerre polynomial, and spherical harmonic functions.
Statistics (stats)	Support for a random variable type as well as the ability to declare this variable from prebuilt distribution functions such as Normal, Exponential, Coin, Die, and other custom distributions [39].
Tensors (tensor)	Symbolic manipulation of indexed objects.
Vectors (vector)	Basic operations on vectors and differential calculus with respect to 3D Cartesian coordinate systems.

### 3.1 Simplification

The generic way to simplify an expression is by calling the `simplify` function. It must be emphasized that simplification is not a rigorously defined mathematical operation [8]. The `simplify` function applies several simplification routines along with heuristics to make the output expression “simple”.<sup>8</sup>

It is often preferable to apply more directed simplification functions. These apply very specific rules to the input expression and are typically able to make guarantees about the output. For instance, the `factor` function, given a polynomial with rational coefficients in several variables, is guaranteed to produce a factorization into irreducible factors. Table 2 lists common simplification functions.

**Table 2.** Some SymPy Simplification Functions

<code>expand</code>	expand the expression
<code>factor</code>	factor a polynomial into irreducibles
<code>collect</code>	collect polynomial coefficients
<code>cancel</code>	rewrite a rational function as $p/q$ with common factors canceled
<code>apart</code>	compute the partial fraction decomposition of a rational function
<code>trigsimp</code>	simplify trigonometric expressions [15]
<code>hyperexpand</code>	expand hypergeometric functions [37, 38]

### 3.2 Calculus

SymPy provides all the basic operations of calculus, such as calculating limits, derivatives, integrals, or summations.

Limits are computed with the `limit` function, using the Gruntz algorithm [19] for computing symbolic limits and heuristics (a description of the Gruntz algorithm may be found in the supplement). For example, the following computes  $\lim_{x \rightarrow \infty} x \sin(\frac{1}{x}) = 1$ . Note that SymPy denotes  $\infty$  as `oo`.

```
>>> limit(x*sin(1/x), x, oo)
1
```

As a more complex example, SymPy computes

$$\lim_{x \rightarrow 0} \left( 2e^{\frac{1 - \cos(x)}{\sin(x)}} - 1 \right)^{\frac{\sinh(x)}{\operatorname{atan}^2(x)}} = e.$$

<sup>8</sup>The measure parameter of the `simplify` function lets the user specify the Python function used to determine how complex an expression is. The default measure function returns the total number of operations in the expression.

```

329 >>> limit((2*E**((1-cos(x))/sin(x))-1)**(sinh(x)/atan(x)**2), x, 0)
330 E

```

Derivatives are computed with the `diff` function, which recursively uses the various differentiation rules.

```

333 >>> diff(sin(x)*exp(x), x)
334 exp(x)*sin(x) + exp(x)*cos(x)

```

Integrals are calculated with the `integrate` function. SymPy implements a combination of the Risch algorithm [6], table lookups, a reimplement of Manuel Bronstein’s “Poor Man’s Integrator” [5], and an algorithm for computing integrals based on Meijer G-functions [37, 38]. These allow SymPy to compute a wide variety of indefinite and definite integrals. The Meijer G-function algorithm and the Risch algorithm are respectively demonstrated below by the computation of

$$\int_0^\infty e^{-st} \log(t) dt = -\frac{\log(s) + \gamma}{s}$$

and

$$\int \frac{-2x^2(\log(x) + 1)e^{x^2} + (e^{x^2} + 1)^2}{x(e^{x^2} + 1)^2(\log(x) + 1)} dx = \log(\log(x) + 1) + \frac{1}{e^{x^2} + 1}.$$

```

335 >>> s, t = symbols('s t', positive=True)
336 >>> integrate(exp(-s*t)*log(t), (t, 0, oo)).simplify()
337 -(log(s) + EulerGamma)/s
338 >>> integrate((-2*x**2*(log(x) + 1)*exp(x**2) +
339 ... (exp(x**2) + 1)**2)/(x*(exp(x**2) + 1)**2*(log(x) + 1)), x)
340 log(log(x) + 1) + 1/(exp(x**2) + 1)

```

Summations are computed with `summation` using a combination of Gosper’s algorithm [18], an algorithm that uses Meijer G-functions [37, 38], and heuristics. Products are computed with `product` function via a suite of heuristics.

```

344 >>> i, n = symbols('i n')
345 >>> summation(2**i, (i, 0, n - 1))
346 2**n - 1
347 >>> summation(i*factorial(i), (i, 1, n))
348 n*factorial(n) + factorial(n) - 1

```

Integrals, derivatives, summations, products, and limits that cannot be computed return unevaluated objects. These can also be created directly if the user chooses.

```

351 >>> integrate(x**x, x)
352 Integral(x**x, x)
353 >>> Sum(2**i, (i, 0, n - 1))
354 Sum(2**i, (i, 0, n - 1))

```

### 3.3 Polynomials

SymPy implements a suite of algorithms for polynomial manipulation, which ranges from relatively simple algorithms for doing arithmetic of polynomials, to advanced methods for factoring multivariate polynomials into irreducibles, symbolically determining real and complex root isolation intervals, or computing Gröbner bases.

Polynomial manipulation is useful in its own right. Within SymPy, though, it is mostly used indirectly as a tool in other areas of the library. In fact, many mathematical problems in symbolic computing are first expressed using entities from the symbolic core, preprocessed, and then transformed into a problem in the polynomial algebra, where generic and efficient

algorithms are used to solve the problem. The solutions to the original problem are subsequently recovered from the results. This is a common scheme in symbolic integration or summation algorithms.

SymPy implements dense and sparse polynomial representations.<sup>9</sup> Both are used in the univariate and multivariate cases. The dense representation is the default for univariate polynomials. For multivariate polynomials, the choice of representation is based on the application. The most common case for the sparse representation is algorithms for computing Gröbner bases (Buchberger, F4, and F5) [7, 11, 12]. This is because different monomial orderings can be expressed easily in this representation. However, algorithms for computing multivariate GCDs or factorizations, at least those currently implemented in SymPy [32], are better expressed when the representation is dense. The dense multivariate representation is specifically a recursively-dense representation, where polynomials in  $K[x_0, x_1, \dots, x_n]$  are viewed as a polynomials in  $K[x_0][x_1] \dots [x_n]$ . Note that despite this, the coefficient domain  $K$ , can be a multivariate polynomial domain as well. The dense recursive representation in Python gets inefficient as the number of variables increases.

Some examples for the `sympy.polys` submodule can be found in the supplement.

### 3.4 Printers

SymPy has a rich collection of expression printers. By default, an interactive Python session will render the `str` form of an expression, which has been used in all the examples in this paper so far. The `str` form of an expression is valid Python and roughly matches what a user would type to enter the expression.<sup>10</sup>

```
>>> phi0 = Symbol('phi0')
>>> str(Integral(sqrt(phi0), phi0))
'Integral(sqrt(phi0), phi0)'
```

A two-dimensional (2D) textual representation of the expression can be printed with monospace fonts via `pprint`. Unicode characters are used for rendering mathematical symbols such as integral signs, square roots, and parentheses. Greek letters and subscripts in symbol names that have Unicode code points associated are also rendered automatically.

```
>>> pprint(Integral(sqrt(phi0 + 1), phi0))

$$\int \sqrt{\varphi_0 + 1} \, d(\varphi_0)$$

```

Alternately, the `use_unicode=False` flag can be set, which causes the expression to be printed using only ASCII characters.

```
>>> pprint(Integral(sqrt(phi0 + 1), phi0), use_unicode=False)
/
|
| _____
| \ / phi0 + 1 d(phi0)
|
/
```

The function `latex` returns a  $\text{\LaTeX}$  representation of an expression.

```
>>> print(latex(Integral(sqrt(phi0 + 1), phi0)))
\int \sqrt{\phi_{0} + 1}\, d\phi_{0}
```

<sup>9</sup>In a dense representation, the coefficients for all terms up to the degree of each variable are stored in memory. In a sparse representation, only the nonzero coefficients are stored.

<sup>10</sup>Many Python libraries distinguish the `str` form of an object, which is meant to be human-readable, and the `repr` form, which is meant to be valid Python that recreates the object. In SymPy, `str(expr) == repr(expr)`. In other words, the string representation of an expression is designed to be compact, human-readable, and valid Python code that could be used to recreate the expression. As it was noted in section 2.2, the `srepr` function prints the exact, verbose form of an expression.

Users are encouraged to run the `init_printing` function at the beginning of interactive sessions, which automatically enables the best pretty printing supported by their environment. In the Jupyter Notebook or Qt Console [33], the `LATEX` printer is used to render expressions using MathJax or `LATEX`, if it is installed on the system. The 2D text representation is used otherwise.

Other printers such as MathML are also available. SymPy uses an extensible printer subsystem for customizing any given printer, and allows custom objects to define their printing behavior for any printer. The code generation functionality of SymPy relies on this subsystem to convert expressions into code in various target programming languages.

### 3.5 Solvers

SymPy has equation solvers that can handle ordinary differential equations, recurrence relationships, Diophantine equations, and algebraic equations. There is also rudimentary support for simple partial differential equations.

There are two functions for solving algebraic equations in SymPy: `solve` and `solveset`. `solveset` has several design changes with respect to the older `solve` function. This distinction is present in order to resolve the usability issues with the previous `solve` function API while maintaining backward compatibility with earlier versions of SymPy. `solveset` only requires essential input information from the user. The function signatures of `solve` and `solveset` are

```
solve(f, *symbols, **flags)
solveset(f, symbol, domain=S.Complexes)
```

The `domain` parameter is typically either `S.Complexes` (the default) or `S.Reals`; the latter causes `solveset` to only return real solutions.

An important difference between the two functions is that the output API of `solve` varies with input (sometimes returning a Python list and sometimes a Python dictionary) whereas `solveset` always returns a SymPy set object.

Both functions implicitly assume that expressions are equal to 0. For instance, `solveset(x - 1, x)` solves  $x - 1 = 0$  for  $x$ .

`solveset` is under active development as a planned replacement for `solve`. There are certain features which are implemented in `solve` that are not yet implemented in `solveset`, including multivariate systems, and some transcendental equations.

More examples of `solveset` and `solve` can be found in the supplement.

### 3.6 Matrices

Besides being an important feature in its own right, computations on matrices with symbolic entries are important for many algorithms within SymPy. The following code shows some basic usage of the `Matrix` class.

```
>>> A = Matrix([[x, x + y], [y, x]])
>>> A
Matrix([
[x, x + y],
[y,      x]])
```

SymPy matrices support common symbolic linear algebra manipulations, including matrix addition, multiplication, exponentiation, computing determinants, solving linear systems, and computing inverses using LU decomposition, LDL decomposition, Gauss-Jordan elimination, Cholesky decomposition, Moore-Penrose pseudoinverse, singular values, and adjugate matrix.

All operations are performed symbolically. For instance, eigenvalues are computed by generating the characteristic polynomial using the Berkowitz algorithm and then solving it using polynomial routines.

```
>>> A.eigenvals()
{x - sqrt(y*(x + y)): 1, x + sqrt(y*(x + y)): 1}
```

Internally these matrices store the elements as Lists of Lists (LIL), meaning the matrix is stored as a list of lists of entries (effectively, the input format used to create the matrix **A** above), making it a dense representation.<sup>11</sup> For storing sparse matrices, the **SparseMatrix** class can be used. Sparse matrices store their elements in Dictionary of Keys (DOK) format, meaning entries are stored as (**row**, **column**) pairs mapping to the elements.

SymPy also supports matrices with symbolic dimension values. `MatrixSymbol` represents a matrix with dimensions  $m \times n$ , where  $m$  and  $n$  can be symbolic. Matrix addition and multiplication, scalar operations, matrix inverse, and transpose are stored symbolically as matrix expressions.

Block matrices are also implemented in SymPy. `BlockMatrix` elements can be any matrix expression, including explicit matrices, matrix symbols, and other block matrices. All functionalities of matrix expressions are also present in `BlockMatrix`.

When symbolic matrices are combined with the assumptions submodule for logical inference, they provide powerful reasoning over invertibility, semi-definiteness, orthogonality, etc., which are valuable in the construction of numerical linear algebra systems.

More examples for `Matrix` and `BlockMatrix` may be found in the supplement.

## 4 NUMERICS

Floating point numbers in SymPy are implemented by the `Float` class, which represents an arbitrary-precision binary floating-point number by storing its value and precision (in bits). This representation is distinct from the Python built-in `float` type, which is a wrapper around machine `double` types and uses a fixed precision (53-bit).

Because Python `float` literals are limited in precision, strings should be used to input precise decimal values:

```
>>> Float(1.1)
1.1000000000000000
>>> Float(1.1, 30) # precision equivalent to 30 digits
1.1000000000000000008881784197001
>>> Float("1.1", 30)
1.1000000000000000000000000000000000000000
```

The `evalf` method converts a constant symbolic expression to a `Float` with the specified precision, here 25 digits:

```
>>> (pi + 1).evalf(25)
4.141592653589793238462643
```

Float numbers do not track their accuracy, and should be used with caution within symbolic expressions since familiar dangers of floating-point arithmetic apply [17]. A notorious case is that of catastrophic cancellation:

```
>>> cos(exp(-100)).evalf(25) - 1
0
```

Applying the `evalf` method to the whole expression solves this problem. Internally, `evalf` estimates the number of accurate bits of the floating-point approximation for each sub-expression, and adaptively increases the working precision until the estimated accuracy of the final result matches the sought number of decimal digits:

```
>>> (cos(exp(-100)) - 1).evalf(25)
-6.919482633683687653243407e-88
```

The `evalf` method works with complex numbers and supports more complicated expressions, such as special functions, infinite series, and integrals. The internal error tracking does not provide rigorous error bounds (in the sense of interval arithmetic) and cannot be used to accurately track uncertainty in measurement data; the sole purpose is to mitigate loss of accuracy that typically occurs when converting symbolic expressions to numerical values.

<sup>11</sup>Similar to the polynomials submodule, dense here means that all entries are stored in memory, contrasted with a sparse representation where only nonzero entries are stored.

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## 5 DOMAIN SPECIFIC SUBMODULES

SymPy includes several submodules that allow users to solve domain specific problems. For example, a comprehensive physics submodule is included that is useful for solving problems in mechanics, optics, and quantum mechanics along with support for manipulating physical quantities with units.

### 5.1 Classical Mechanics

One of the core domains that SymPy supports is the physics of classical mechanics. This is in turn separated into two distinct components: vector algebra and mechanics.

#### 5.1.1 Vector Algebra

The `sympy.physics.vector` submodule provides reference frame-, time-, and space-aware vector and dyadic objects that allow for three-dimensional operations such as addition, subtraction, scalar multiplication, inner and outer products, and cross products. Both of these objects can be written in very compact notation that make it easy to express the vectors and dyadics in terms of multiple reference frames with arbitrarily defined relative orientations. The vectors are used to specify the positions, velocities, and accelerations of points; orientations, angular velocities, and angular accelerations of reference frames; and forces and torques. The dyadics are essentially reference frame-aware  $3 \times 3$  tensors [44]. The vector and dyadic objects can be used for any one-, two-, or three-dimensional vector algebra, and they provide a strong framework for building physics and engineering tools.

The following Python code demonstrates how a vector is created using the orthogonal unit vectors of three reference frames that are oriented with respect to each other, and the result of expressing the vector in the  $A$  frame. The  $B$  frame is oriented with respect to the  $A$  frame using Z-X-Z Euler Angles of magnitude  $\pi$ ,  $\frac{\pi}{2}$ , and  $\frac{\pi}{3}$ , respectively, whereas the  $C$  frame is oriented with respect to the  $B$  frame through a simple rotation about the  $B$  frame's  $X$  unit vector through  $\frac{\pi}{2}$ .

```
>>> from sympy.physics.vector import ReferenceFrame
>>> A = ReferenceFrame('A')
>>> B = ReferenceFrame('B')
>>> C = ReferenceFrame('C')
>>> B.orient(A, 'body', (pi, pi/3, pi/4), 'zxz')
>>> C.orient(B, 'axis', (pi/2, B.x))
>>> v = 1*A.x + 2*B.z + 3*C.y
>>> v
A.x + 2*B.z + 3*C.y
>>> v.express(A)
A.x + 5*sqrt(3)/2*A.y + 5/2*A.z
```

#### 5.1.2 Mechanics

The `sympy.physics.mechanics` submodule utilizes the `sympy.physics.vector` submodule to populate time-aware particle and rigid-body objects to fully describe the kinematics and kinetics of a rigid multi-body system. These objects store all of the information needed to derive the ordinary differential or differential algebraic equations that govern the motion of the system, i.e., the equations of motion. These equations of motion abide by Newton's laws of motion and can handle arbitrary kinematic constraints or complex loads. The submodule offers two automated methods for formulating the equations of motion based on Lagrangian Dynamics [26] and Kane's Method [24]. Lastly, there are automated linearization routines for constrained dynamical systems [34].

### 5.2 Quantum Mechanics

The `sympy.physics.quantum` submodule has extensive capabilities to solve problems in quantum mechanics, using Python objects to represent the different mathematical objects relevant in quantum theory [41]: states (bras and kets), operators (unitary, Hermitian, etc.), and basis sets, as well as operations on these objects such as representations, tensor products, inner products, outer products, commutators, and anticommutators. The base objects are designed in the most

606 general way possible to enable any particular quantum system to be implemented by subclassing  
 607 the base operators and defining the relevant class methods to provide system-specific logic.

608 Symbolic quantum operators and states may be defined, and one can perform a full range of  
 609 operations with them.

```
610 >>> from sympy.physics.quantum import Commutator, Dagger, Operator
611 >>> from sympy.physics.quantum import Ket, qapply
612 >>> A = Operator('A')
613 >>> B = Operator('B')
614 >>> C = Operator('C')
615 >>> D = Operator('D')
616 >>> a = Ket('a')
617 >>> comm = Commutator(A, B)
618 >>> comm
619 [A,B]
620 >>> qapply(Dagger(comm*a)).doit()
621 -<a|*(Dagger(A)*Dagger(B) - Dagger(B)*Dagger(A))
```

622 Commutators can be expanded using common commutator identities:

```
623 >>> Commutator(C+B, A*D).expand(commutator=True)
624 -[A,B]*D - [A,C]*D + A*[B,D] + A*[C,D]
```

625 On top of this set of base objects, a number of specific quantum systems have been implemented  
 626 in a fully symbolic framework. These include:

- 627 • Many of the exactly solvable quantum systems, including simple harmonic oscillator states  
 628 and raising/lowering operators, infinite square well states, and 3D position and momentum  
 629 operators and states.
- 630 • Second quantized formalism of non-relativistic many-body quantum mechanics [13].
- 631 • Quantum angular momentum [50]. Spin operators and their eigenstates can be represented  
 632 in any basis and for any quantum numbers. A rotation operator representing the Wigner-D  
 633 matrix, which may be defined symbolically or numerically, is also implemented to rotate  
 634 spin eigenstates. Functionality for coupling and uncoupling of arbitrary spin eigenstates is  
 635 provided, including symbolic representations of Clebsch-Gordon coefficients and Wigner  
 636 symbols.
- 637 • Quantum information and computing [29]. Multidimensional qubit states, and a full  
 638 set of one- and two-qubit gates are provided and can be represented symbolically or as  
 639 matrices/vectors. With these building blocks, it is possible to implement a number of basic  
 640 quantum algorithms including the quantum Fourier transform, quantum error correction,  
 641 quantum teleportation, Grover's algorithm, dense coding, etc. In addition, any quantum  
 642 circuit may be plotted using the `circuit_plot` function (Figure 1).

643 Here are a few short examples of the quantum information and computing capabilities in  
 644 `sympy.physics.quantum`. Start with a simple four-qubit state and flip the second qubit from the  
 645 right using a Pauli-X gate:

```
646 >>> from sympy.physics.quantum.qubit import Qubit
647 >>> from sympy.physics.quantum.gate import XGate
648 >>> q = Qubit('0101')
649 >>> q
650 |0101>
651 >>> X = XGate(1)
652 >>> qapply(X*q)
653 |0111>
```

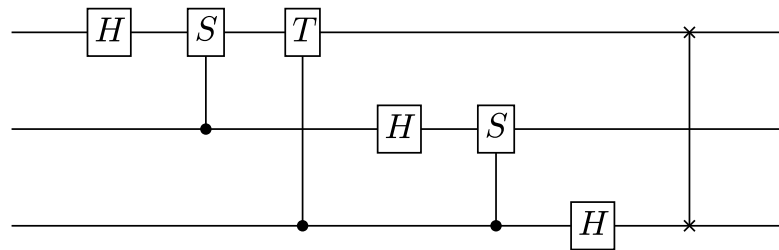


654 Qubit states can also be used in adjoint operations, tensor products, inner/outer products:

```
655 >>> Dagger(q)
656 <0101|
657 >>> ip = Dagger(q)*q
658 >>> ip
659 <0101|0101>
660 >>> ip.doit()
661 1
```

662 Quantum gates (unitary operators) can be applied to transform these states and then classical  
663 measurements can be performed on the results:

```
664 >>> from sympy.physics.quantum.qubit import measure_all
665 >>> from sympy.physics.quantum.gate import H, X, Y, Z
666 >>> c = H(0)*H(1)*Qubit('00')
667 >>> c
668 H(0)*H(1)*|00>
669 >>> q = qapply(c)
670 >>> measure_all(q)
671 [(|00>, 1/4), (|01>, 1/4), (|10>, 1/4), (|11>, 1/4)]
```



**Figure 1.** The circuit diagram for a three-qubit quantum Fourier transform generated by SymPy.

672 Lastly, the following example demonstrates creating a three-qubit quantum Fourier transform,  
673 decomposing it into one- and two-qubit gates, and then generating a circuit plot for the sequence  
674 of gates (see Figure 1).

```
675 >>> from sympy.physics.quantum.qft import QFT
676 >>> from sympy.physics.quantum.circuitplot import circuit_plot
677 >>> fourier = QFT(0,3).decompose()
678 >>> fourier
679 SWAP(0,2)*H(0)*C((0),S(1))*H(1)*C((0),T(2))*C((1),S(2))*H(2)
680 >>> c = circuit_plot(fourier, nqubits=3)
```

## 681 6 CONCLUSION AND FUTURE WORK

682 SymPy is a robust computer algebra system that provides a wide spectrum of features both in  
683 traditional computer algebra and in a plethora of scientific disciplines. This allows SymPy to be  
684 used in a first-class way with other Python projects, including the scientific Python stack. Unlike  
685 many other CASs, SymPy is designed to be used in an extensible way: both as an end-user  
686 application and as a library.

SymPy expressions are immutable trees of Python objects. SymPy uses Python both as the internal language and the user language. This permits users to access to the same methods that the library implements in order to extend it for their needs. Additionally, SymPy has a powerful assumptions system for declaring and deducing mathematical properties of expressions.

SymPy supports a wide array of mathematical facilities. This includes functions for simplifying expressions, performing common calculus operations, pretty printing expressions, solving equations, and representing symbolic matrices. Other supported facilities include discrete math, concrete math, plotting, geometry, statistics, polynomials, sets, series, vectors, combinatorics, group theory, code generation, tensors, Lie algebras, cryptography, and special functions. Additionally, SymPy contains submodules targeting certain specific domains, such as classical mechanics and quantum mechanics. This breadth of domains has been engendered by a strong and vibrant user community. Anecdotaly, these users likely chose SymPy because of its ease of access.

Some of the planned future work for SymPy includes work on improving code generation, improvements to the speed of SymPy using SymEngine, improving the assumptions system, and improving the solvers submodule.

## 7 ACKNOWLEDGEMENTS

The author of this paper Francesco Bonazzi thanks the Deutsche Forschungsgemeinschaft (DFG) for its financial support via the International Research Training Group 1524 "Self-Assembled Soft Matter Nano-Structures at Interfaces."

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