

SYMPY: SYMBOLIC COMPUTING IN PYTHON

AARON MEURER^{*}, CHRISTOPHER P. SMITH[†], MATEUSZ PAPROCKI[‡], ONDŘEJ
ČERTÍK[§], SERGEY B. KIRPICHEV[¶], MATTHEW ROCKLIN^{||}, AMIT KUMAR[#], SERGIU
IVANOV^{††}, JASON K. MOORE^{‡‡}, SARTAJ SINGH^{§§}, THILINA RATHNAYAKE^{¶¶}, SEAN VIG^{|||}
, BRIAN E. GRANGER^{##}, RICHARD P. MULLER¹, FRANCESCO BONAZZI², HARSH
GUPTA³, SHIVAM VATS⁴, FREDRIK JOHANSSON⁵, FABIAN PEDREGOSA⁶, MATTHEW
J. CURRY⁷, ASHUTOSH SABOO⁸, ISURU FERNANDO⁹, SUMITH KULAL¹⁰, ROBERT
CIMRMAN¹¹, AND ANTHONY SCOPATZ¹²

Abstract. SymPy is an open source computer algebra system written in pure Python. It is built with a focus on extensibility and ease of use, through both interactive and programmatic applications. These characteristics have led SymPy to become the standard symbolic library for the scientific Python ecosystem. This paper presents the architecture of SymPy, a description of its features, and a discussion of select domain specific submodules.

^{*}University of South Carolina, Columbia, SC 29201 (asmeurer@gmail.com).

[†]Polar Semiconductor, Inc., Bloomington, MN 55425 (smichr@gmail.com).

[‡]Continuum Analytics, Inc., Austin, TX 78701 (mattpap@gmail.com).

[§]Los Alamos National Laboratory, Los Alamos, NM 87545 (certik@lanl.gov).

[¶]Moscow State University, Faculty of Physics, Leninskie Gory, Moscow, 119991, Russia (skirpichev@gmail.com).

^{||}Continuum Analytics, Inc., Austin, TX 78701 (mrocklin@gmail.com).

[#]Delhi Technological University, Shahbad Daultpur, Bawana Road, New Delhi 110042, India (dtu.amit@gmail.com).

^{††}Université Paris Est Créteil, 61 av. Général de Gaulle, 94010 Créteil, France (sergiu.ivanov@upec.fr).

^{‡‡}University of California, Davis, Davis, CA 95616 (jkm@ucdavis.edu).

^{§§}Indian Institute of Technology (BHU), Varanasi, Uttar Pradesh 221005, India (singhsartaj94@gmail.com).

^{¶¶}University of Moratuwa, Bandaranayake Mawatha, Katubedda, Moratuwa 10400, Sri Lanka (thilinarmtb.10@cse.mrt.ac.lk).

^{|||}University of Illinois at Urbana-Champaign, Urbana, IL 61801 (sean.v.775@gmail.com).

^{##}California Polytechnic State University, San Luis Obispo, CA 93407 (ellisonbg@gmail.com).

¹Center for Computing Research, Sandia National Laboratories, Albuquerque, NM 87185 (rmuller@sandia.gov).

²Max Planck Institute of Colloids and Interfaces, Department of Theory and Bio-Systems, Am Mühlenberg 1, 14424 Potsdam, Germany (francesco.bonazzi@mpikg.mpg.de).

³Indian Institute of Technology Kharagpur, Kharagpur, West Bengal 721302, India (hargup@protonmail.com).

⁴Indian Institute of Technology Kharagpur, Kharagpur, West Bengal 721302, India (shivamvats.iitkgp@gmail.com).

⁵INRIA Bordeaux-Sud-Ouest – LFANT project-team, 200 Avenue de la Vieille Tour, 33405 Talence, France (fredrik.johansson@gmail.com).

⁶INRIA – SIERRA project-team, 2 Rue Simone IFF, 75012 Paris, France (f@bianp.net).

⁷Department of Physics and Astronomy, University of New Mexico, Albuquerque, NM 87131 (mattjcurry@gmail.com).

⁸Birla Institute of Technology and Science, Pilani, K.K. Birla Goa Campus, NH 17B Bypass Road, Zuarinagar, Sancoale, Goa 403726, India (ashutosh.saboo@gmail.com).

⁹University of Moratuwa, Bandaranayake Mawatha, Katubedda, Moratuwa 10400, Sri Lanka (isuru.11@cse.mrt.ac.lk).

¹⁰Indian Institute of Technology Bombay, Powai, Mumbai, Maharashtra 400076, India (sumith@cse.iitb.ac.in).

¹¹New Technologies – Research Centre, University of West Bohemia, Univerzitní 8, 306 14 Plzeň, Czech Republic (cimrman3@ntc.zcu.cz).

¹²University of South Carolina, Columbia, SC 29201 (scopatz@cec.sc.edu).

1. Introduction. SymPy is a full featured computer algebra system (CAS) written in the Python programming language [24]. It is free and open source software, being licensed under the 3-clause BSD license [36]. The SymPy project was started by Ondřej Čertík in 2005, and it has since grown to over 500 contributors. Currently, SymPy is developed on GitHub using a bazaar community model [32]. The accessibility of the codebase and the open community model allow SymPy to rapidly respond to the needs of users and developers.

Python is a dynamically typed programming language that has a focus on ease of use and readability. Due in part to this focus, it has become a popular language for scientific computing and data science, with a broad ecosystem of libraries [27]. SymPy is itself used by many libraries and tools to support research within a variety of domains, such as Sage [39] (pure mathematics), yt [44] (astronomy and astrophysics), PyDy [15] (multibody dynamics), and SfePy [10] (finite elements).

Unlike many CASs, SymPy does not invent its own programming language. Python itself is used both for the internal implementation and end user interaction. The exclusive usage of a single programming language makes it easier for people already familiar with that language to use or develop SymPy. Simultaneously, it enables developers to focus on mathematics, rather than language design.

SymPy is designed with a strong focus on usability as a library. Extensibility is important in its application program interface (API) design. Thus, SymPy makes no attempt to extend the Python language itself. The goal is for users of SymPy to be able to include SymPy alongside other Python libraries in their workflow, whether that be in an interactive environment or as a programmatic part in a larger system.

As a library, SymPy does not have a built-in graphical user interface (GUI). However, SymPy exposes a rich interactive display system, including registering printers with Jupyter [29] frontends, including the Notebook and Qt Console, which will render SymPy expressions using MathJax [9] or \LaTeX .

The remainder of this paper discusses key components of the SymPy software. Section 2 discusses the architecture of SymPy. Section 3 enumerates the features of SymPy and takes a closer look at some of the important ones. The section 4 looks at the numerical features of SymPy and its dependency library, mpmath. Section 5 looks at the domain specific physics submodules for performing symbolic and numerical calculations in classical mechanics and quantum mechanics. Conclusions and future directions for SymPy are given in section 6.

2. Architecture. Software architecture is of central importance in any large software project because it establishes predictable patterns of usage and development [38]. This section describes the essential structural components of SymPy, provides justifications for the design decisions that have been made, and gives example user-facing code as appropriate.

2.1. Basic Usage. The following statement imports all SymPy functions into the global Python namespace. From here on, all examples in this paper assume that this statement has been executed.

```
>>> from sympy import *
```

Symbolic variables, called symbols, must be defined and assigned to Python variables before they can be used. This is typically done through the `symbols` function, which may create multiple symbols in a single function call. For instance,

```
>>> x, y, z = symbols('x y z')
```

creates three symbols representing variables named x , y , and z . In this particular instance, these symbols are all assigned to Python variables of the same name. However,

the user is free to assign them to different Python variables, while representing the same symbol, such as `a, b, c = symbols('x y z')`. In order to minimize potential confusion, though, all examples in this paper will assume that the symbols `x`, `y`, and `z` have been assigned to Python variables identical to their symbolic names.

Expressions are created from symbols using Python's mathematical syntax. Note that in Python, exponentiation is represented by the `**` binary infix operator. For instance, the following Python code creates the expression $(x^2 - 2x + 3)/y$.

```
>>> (x**2 - 2*x + 3)/y
(x**2 - 2*x + 3)/y
```

Importantly, SymPy expressions are immutable. This simplifies the design of SymPy by allowing expression interning. It also enables expressions to be hashed and stored in Python dictionaries, thereby permitting features such as caching.

2.2. The Core. A computer algebra system (CAS) represents mathematical expressions as data structures. For example, the mathematical expression $x + y$ is represented as a tree with three nodes, `+`, `x`, and `y`, where `x` and `y` are ordered children of `+`. As users manipulate mathematical expressions with traditional mathematical syntax, the CAS manipulates the underlying data structures. Automated optimizations and computations such as integration, simplification, etc. are all functions that consume and produce expression trees.

In SymPy every symbolic expression is an instance of a Python `Basic` class, a superclass of all SymPy types providing common methods to all SymPy tree-elements, such as traversals. The children of a node in the tree are held in the `args` attribute. A terminal or leaf node in the expression tree has empty `args`.

For example, consider the expression $xy + 2$:

```
>>> expr = x*y + 2
```

By order of operations, the parent of the expression tree for `expr` is an addition, so it is of type `Add`. The child nodes of `expr` are `2` and `x*y`.

```
>>> type(expr)
<class 'sympy.core.add.Add'>
>>> expr.args
(2, x*y)
```

Descending further down into the expression tree yields the full expression. For example, the next child node (given by `expr.args[0]`) is `2`. Its class is `Integer`, and it has an empty `args` tuple, indicating that it is a leaf node.

```
>>> expr.args[0]
2
>>> type(expr.args[0])
<class 'sympy.core.numbers.Integer'>
>>> expr.args[0].args
()
```

A useful way to view an expression tree is using the `srepr` function, which returns a string representation of an expression as valid Python code with all the nested class constructor calls to create the given expression.

```
>>> srepr(expr)
"Add(Mul(Symbol('x'), Symbol('y')), Integer(2))"
```

Every SymPy expression satisfies a key identity invariant:

```
expr.func(*expr.args) == expr
```

This means that expressions are rebuildable from their `args`.¹ Note that in SymPy

¹`expr.func` is used instead of `type(expr)` to allow the function of an expression to be distinct from

111 the `==` operator represents exact structural equality, not mathematical equality. This
 112 allows testing if any two expressions are equal to one another as expression trees. For
 113 example, even though $(x + 1)^2$ and $x^2 + 2x + 1$ are equal mathematically, SymPy gives
 114 `>>> (x + 1)**2 == x**2 + 2*x + 1`
 115 `False`
 116 because they are different as expression trees (the former is a `Pow` object and the latter
 117 is an `Add` object).

118 Python allows classes to override mathematical operators. The Python interpreter
 119 translates the above `x*y + 2` to, roughly, `(x.__mul__(y)).__add__(2)`. Both `x` and `y`,
 120 returned from the `symbols` function, are `Symbol` instances. The `2` in the expression is
 121 processed by Python as a literal, and is stored as Python's built in `int` type. When `2` is
 122 passed to the `__add__` method of `Symbol`, it is converted to the SymPy type `Integer(2)`
 123 before being stored in the resulting expression tree. In this way, SymPy expressions
 124 can be built in the natural way using Python operators and numeric literals.

125 **2.3. Assumptions.** SymPy performs logical inference through its assumptions
 126 system. The assumptions system allows users to specify that symbols have cer-
 127 tain common mathematical properties, such as being positive, imaginary, or integral.
 128 SymPy is careful to never perform simplifications on an expression unless the assump-
 129 tions allow them. For instance, the identity $\sqrt{t^2} = t$ holds if t is nonnegative ($t \geq 0$).
 130 If t is real, the identity $\sqrt{t^2} = |t|$ holds. However, for general complex t , no such
 131 identity holds.

132 By default, SymPy performs all calculations assuming that symbols are com-
 133 plex valued. This assumption makes it easier to treat mathematical problems in full
 134 generality.

```
135 >>> t = Symbol('t')
136 >>> sqrt(t**2)
137 sqrt(t**2)
```

138 By assuming the most general case, that symbols are complex by default, SymPy
 139 avoids performing mathematically invalid operations. However, in many cases users
 140 will wish to simplify expressions containing terms like $\sqrt{t^2}$.

141 Assumptions are set on `Symbol` objects when they are created. For instance
 142 `Symbol('t', positive=True)` will create a symbol named `t` that is assumed to be
 143 positive.

```
144 >>> t = Symbol('t', positive=True)
145 >>> sqrt(t**2)
146 t
```

147 Some of the common assumptions that SymPy allows are `positive`, `negative`,
 148 `real`, `nonpositive`, `integer`, `prime` and `commutative`.² Assumptions on any object can
 149 be checked with the `is_assumption` attributes, like `t.is_positive`.

150 Assumptions are only needed to restrict a domain so that certain simplifications
 151 can be performed. They are not required to make the domain match the input of a
 152 function. For instance, one can create the object $\sum_{n=0}^m f(n)$ as `Sum(f(n), (n, 0, m))`
 153 without setting `integer=True` when creating the `Symbol` object `n`.

154 The assumptions system additionally has deductive capabilities. The assumptions
 155 use a three-valued logic using the Python built in objects `True`, `False`, and `None`. `True`
 156 is returned if the SymPy object has the property and `False` is returned if it doesn't

its actual Python class. In most cases the two are the same.

²If A and B are Symbols created with `commutative=False` then SymPy will keep $A \cdot B$ and $B \cdot A$ distinct.

or can't. For example, `I.is_real` and `I.is_prime` return `False` for imaginary unit `I`. `None` represents the “unknown” case. This could mean that given assumptions do not unambiguously specify the truth of an attribute. For instance, `Symbol('x', real=True).is_positive` will give `None` because a real symbol might be positive or negative. The `None` could also mean that not enough is known or implemented to compute the given fact. For instance, `(pi + E).is_irrational` gives `None`, because determining whether $\pi + e$ is rational or irrational is an open problem in mathematics [23].

Basic implications between the facts are used to deduce assumptions. For instance, the assumptions system knows that being an integer implies being rational, so `Symbol('x', integer=True).is_rational` returns `True`. Furthermore, expressions compute the assumptions on themselves based on the assumptions of their arguments. For instance, if `x` and `y` are both created with `positive=True`, then `(x + y).is_positive` will be `True` whereas `(x - y).is_positive` will be `None`.

2.4. Extensibility. While the core of SymPy is relatively small, it has been extended to a wide variety of domains by a broad range of contributors. This is due in part because the same language, Python, is used both for the internal implementation and the external usage by users. All of the extensibility capabilities available to users are also utilized by SymPy itself. This eases the transition pathway from SymPy user to SymPy developer.

The typical way to create a custom SymPy object is to subclass an existing SymPy class, usually `Basic`, `Expr`, or `Function`. All SymPy classes used for expression trees³ should be subclasses of the base class `Basic`, which defines some basic methods for symbolic expression trees. `Expr` is the subclass for mathematical expressions that can be added and multiplied together. Instances of `Expr` typically represent complex numbers, but may also include other “rings” like matrix expressions. Not all SymPy classes are subclasses of `Expr`. For instance, logic expressions such as `And(x, y)` are subclasses of `Basic` but not of `Expr`.

The `Function` class is a subclass of `Expr` which makes it easier to define mathematical functions called with arguments. This includes named functions like `sin(x)` and `log(x)` as well as undefined functions like `f(x)`. Subclasses of `Function` should define a class method `eval`, which returns values for which the function should be automatically evaluated, and `None` for arguments that should not be automatically evaluated.

Many SymPy functions perform various evaluations down the expression tree. Classes define their behavior in such functions by defining a relevant `_eval_*` method. For instance, an object can indicate to the `diff` function how to take the derivative of itself by defining the `_eval_derivative(self, x)` method, which may in turn call `diff` on its args. The most common `_eval_*` methods relate to the assumptions. `_eval_is_assumption` defines the assumptions for *assumption*.

As an example of the notions presented in this section, Listing 1 presents a minimal version of the gamma function $\Gamma(x)$ from SymPy, which evaluates itself on positive integer arguments, has the positive and real assumptions defined, can be rewritten in terms of factorial with `gamma(x).rewrite(factorial)`, and can be differentiated. `fdiff` is a convenience method for subclasses of `Function`. `fdiff` returns the derivative of the function without considering the chain rule. `self.func` is used throughout instead of referencing `gamma` explicitly so that potential subclasses of `gamma` can reuse the methods.

³Some internal classes, such as those used in the polynomial module, do not follow this rule for efficiency reasons.

Listing 1: A minimal implementation of `sympy.gamma`.

```

204 from sympy import Integer, Function, floor, factorial, polygamma
205
206 class gamma(Function)
207     @classmethod
208     def eval(cls, arg):
209         if isinstance(arg, Integer) and arg.is_positive:
210             return factorial(arg - 1)
211
212     def _eval_is_positive(self):
213         x = self.args[0]
214         if x.is_positive:
215             return True
216         elif x.is_noninteger:
217             return floor(x).is_even
218
219     def _eval_is_real(self):
220         x = self.args[0]
221         # noninteger means real and not integer
222         if x.is_positive or x.is_noninteger:
223             return True
224
225     def _eval_rewrite_as_factorial(self, z):
226         return factorial(z - 1)
227
228     def fdiff(self, argindex=1):
229         from sympy.core.function import ArgumentIndexError
230         if argindex == 1:
231             return self.func(self.args[0])*polygamma(0, self.args[0])
232         else:
233             raise ArgumentIndexError(self, argindex)

```

The gamma function implemented in SymPy has many more capabilities than the above listing, such as evaluation at rational points and series expansion.

3. Features. Although SymPy’s extensive feature set cannot be covered in-depth in this paper, calculus and other bedrock areas are discussed in their own subsections. Additionally, Table 1 gives a compact listing of all major capabilities present in the SymPy codebase. This grants a sampling from the breadth of topics and application domains that SymPy services. Unless stated otherwise, all features noted in Table 1 are symbolic in nature. Numeric features are discussed in Section 4.

Table 1: SymPy Features and Descriptions

Feature	Description
Calculus	Algorithms for computing derivatives, integrals, and limits.
Category Theory	Representation of objects, morphisms, and diagrams. Tools for drawing diagrams with Xy-pic.

Code Generation	Generation of compilable and executable code in a variety of different programming languages from expressions directly. Target languages include C, Fortran, Julia, JavaScript, Mathematica, MATLAB and Octave, Python, and Theano.
Combinatorics & Group Theory	Permutations, combinations, partitions, subsets, various permutation groups (such as polyhedral, Rubik, symmetric, and others), Gray codes [26], and Prufer sequences [4].
Concrete Math	Summation, products, tools for determining whether summation and product expressions are convergent, absolutely convergent, hypergeometric, and for determining other properties; computation of Gosper's normal form [31] for two univariate polynomials.
Cryptography	Block and stream ciphers, including shift, Affine, substitution, Vigenère's, Hill's, bifid, RSA, Kid RSA, linear-feedback shift registers, and Elgamal encryption.
Differential Geometry	Representations of manifolds, metrics, tensor products, and coordinate systems in Riemannian and pseudo-Riemannian geometries [40].
Geometry	Representations of 2D geometrical entities, such as lines and circles. Enables queries on these entities, such as asking the area of an ellipse, checking for collinearity of a set of points, or finding the intersection between objects.
Lie Algebras	Representations of Lie algebras and root systems.
Logic	Boolean expressions, equivalence testing, satisfiability, and normal forms.
Matrices	Tools for creating matrices of symbols and expressions. Both sparse and dense representations, as well as symbolic linear algebraic operations (e.g., inversion and factorization), are supported.
Matrix Expressions	Matrices with symbolic dimensions (unspecified entries). Block matrices.
Number Theory	Prime number generation, primality testing, integer factorization, continued fractions, Egyptian fractions, modular arithmetic, quadratic residues, partitions, binomial and multinomial coefficients, prime number tools, hexadecimal digits of π , and integer factorization.
Plotting	Hooks for visualizing expressions via matplotlib [20] or as text drawings when lacking a graphical back-end. 2D function plotting, 3D function plotting, and 2D implicit function plotting are supported.
Polynomials	Polynomial algebras over various coefficient domains. Functionality ranges from simple operations (e.g., polynomial division) to advanced computations (e.g., Gröbner bases [1] and multivariate factorization over algebraic number domains).
Printing	Functions for printing SymPy expressions in the terminal with ASCII or Unicode characters and converting SymPy expressions to L ^A T _E X and MathML.

Quantum mechanics	Me-	Quantum states, bra-ket notation, operators, basis sets, representations, tensor products, inner products, outer products, commutators, anticommutators, and specific quantum system implementations.
Series		Series expansion, sequences, and limits of sequences. This includes Taylor, Laurent, and Puiseux series as well as special series, such as Fourier and formal power series.
Sets		Representations of empty, finite, and infinite sets. This includes special sets such as for all natural, integer, and complex numbers. Operations on sets such as union, intersection, Cartesian product, and building sets from other sets are supported.
Simplification		Functions for manipulating and simplifying expressions. Includes algorithms for simplifying hypergeometric functions, trigonometric expressions, rational functions, combinatorial functions, square root denesting, and common subexpression elimination.
Solvers		Functions for symbolically solving equations, systems of equations, both linear and non-linear, inequalities, ordinary differential equations, partial differential equations, Diophantine equations, and recurrence relations.
Special functions	Func-	Implementations of a number of well known special functions, including Dirac delta, Gamma, Beta, Gauss error functions, Fresnel integrals, Exponential integrals, Logarithmic integrals, Trigonometric integrals, Bessel, Hankel, Airy, B-spline, Riemann Zeta, Dirichlet eta, polylogarithm, Lerch transcendent, hypergeometric, elliptic integrals, Mathieu, Jacobi polynomials, Gegenbauer polynomial, Chebyshev polynomial, Legendre polynomial, Hermite polynomial, Laguerre polynomial, and spherical harmonic functions.
Statistics		Support for a random variable type as well as the ability to declare this variable from prebuilt distribution functions such as Normal, Exponential, Coin, Die, and other custom distributions [35].
Tensors		Symbolic manipulation of indexed objects.
Vectors		Basic operations on vectors and differential calculus with respect to 3D Cartesian coordinate systems.

3.1. Simplification. The generic way to simplify an expression is by calling the `simplify` function. It must be emphasized that simplification is not an unambiguously defined mathematical operation [8]. The `simplify` function applies several simplification routines along with heuristics to make the output expression as “simple” as possible.

It is often preferable to apply more directed simplification functions. These apply very specific rules to the input expression and are typically able to make guarantees about the output. For instance, the `factor` function, given a polynomial with rational coefficients in several variables, is guaranteed to produce a factorization into irreducible factors. Table 2 lists common simplification functions.

Table 2: Some SymPy Simplification Functions

<code>expand</code>	expand the expression
<code>factor</code>	factor a polynomial into irreducibles
<code>collect</code>	collect polynomial coefficients
<code>cancel</code>	rewrite a rational function as p/q with common factors canceled
<code>apart</code>	compute the partial fraction decomposition of a rational function
<code>trigsimp</code>	simplify trigonometric expressions [14]

Substitutions are performed using the `.subs` method.

```
>>> (sin(x) + x**2 + 1).subs(x, y + 1)
(y + 1)**2 + sin(y + 1) + 1
```

3.2. Calculus. Integrals are calculated with the `integrate` function. SymPy implements a combination of the Risch algorithm [6], table lookups, a reimplementaion of Manuel Bronstein’s “Poor Man’s Integrator” [5], and an algorithm for computing integrals based on Meijer G-functions [33, 34]. These allow SymPy to compute a wide variety of indefinite and definite integrals. The Meijer G-function algorithm and the Risch algorithm are respectively demonstrated below by the computation of

$$\int_0^{\infty} e^{-st} \log(t) dt = -\frac{\log(s) + \gamma}{s}$$

and

$$\int \frac{-2x^2 (\log(x) + 1) e^{x^2} + (e^{x^2} + 1)^2}{x(e^{x^2} + 1)^2 (\log(x) + 1)} dx = \log(\log(x) + 1) + \frac{1}{e^{x^2} + 1}.$$

```
>>> s, t = symbols('s t', positive=True)
>>> integrate(exp(-s*t)*log(t), (t, 0, oo)).simplify()
-(log(s) + EulerGamma)/s
>>> integrate((-2*x**2*(log(x) + 1)*exp(x**2) +
... (exp(x**2) + 1)**2)/(x*(exp(x**2) + 1)**2*(log(x) + 1)), x)
log(log(x) + 1) + 1/(exp(x**2) + 1)
```

Derivatives are computed with the `diff` function, which recursively uses the various differentiation rules.

```
>>> diff(sin(x)*exp(x), x)
exp(x)*sin(x) + exp(x)*cos(x)
```

Summations and products are computed with `summation` and `product`, respectively. Summations are computed using a combination of Gosper’s algorithm [17], an algorithm that uses Meijer G-functions [33, 34], and heuristics. Products are computed via a suite of heuristics.

```
>>> i, n = symbols('i n')
>>> summation(2**i, (i, 0, n - 1))
2**n - 1
>>> summation(i*factorial(i), (i, 1, n))
n*factorial(n) + factorial(n) - 1
```

Limits are computed with the `limit` function. The limit module implements the Gruntz algorithm [18] for computing symbolic limits. For example, the following computes $\lim_{x \rightarrow \infty} x \sin(\frac{1}{x}) = 1$. Note that SymPy denotes ∞ as `oo`.

```
286 >>> limit(x*sin(1/x), x, oo)
```

```
287 1
```

```
288 As a more complex example, SymPy computes
```

```
289
```

$$\lim_{x \rightarrow 0} \left(2e^{\frac{1 - \cos(x)}{\sin(x)}} - 1 \right)^{\frac{\sinh(x)}{\operatorname{atan}^2(x)}} = e.$$

```
290 >>> limit((2*E**((1-cos(x))/sin(x))-1)**(sinh(x)/atan(x)**2), x, 0)
```

```
291 E
```

```
292 Integrals, derivatives, summations, products, and limits that cannot be computed
293 return unevaluated objects. These can also be created directly if the user chooses.
```

```
294 >>> integrate(x**x, x)
```

```
295 Integral(x**x, x)
```

```
296 >>> Sum(2**i, (i, 0, n - 1))
```

```
297 Sum(2**i, (i, 0, n - 1))
```

```
298
```

3.3. Polynomials. SymPy implements a suite of algorithms for polynomial manipulation, which ranges from relatively simple algorithms for doing arithmetic of polynomials, to advanced methods for factoring multivariate polynomials into irreducibles, symbolically determining real and complex root isolation intervals, or computing Gröbner bases.

```
303
```

Polynomial manipulation is useful in its own right. Within SymPy, though, it is mostly used indirectly as a tool in other areas of the library. In fact, many mathematical problems in symbolic computing are first expressed using entities from the symbolic core, preprocessed, and then transformed into a problem in the polynomial algebra, where generic and efficient algorithms are used to solve the problem. The solutions to the original problem are subsequently recovered from the results. This is a common scheme in symbolic integration or summation algorithms.

```
310
```

SymPy implements dense and sparse polynomial representations.⁴ Both are used in the univariate and multivariate cases. The dense representation is the default for univariate polynomials. For multivariate polynomials, the choice of representation is based on the application. The most common case for the sparse representation is algorithms for computing Gröbner bases (Buchberger, F4, and F5) [7, 11, 12]. This is because different monomial orderings can be expressed easily in this representation. However, algorithms for computing multivariate GCDs or factorizations, at least those currently implemented in SymPy [28], are better expressed when the representation is dense. The dense multivariate representation is specifically a recursively-dense representation, where polynomials in $K[x_0, x_1, \dots, x_n]$ are viewed as a polynomials in $K[x_0][x_1] \dots [x_n]$. Note that despite this, the coefficient domain K , can be a multivariate polynomial domain as well. The dense recursive representation in Python gets inefficient as the number of variables increases.

```
323
```

3.4. Printers. SymPy has a rich collection of expression printers. By default, an interactive Python session will render the `str` form of an expression, which has been used in all the examples in this paper so far. The `str` form of an expression is valid Python and roughly matches what a user would type to enter the expression.

```
327 >>> phi0 = Symbol('phi0')
```

```
328 >>> str(Integral(sqrt(phi0), phi0))
```

```
329 'Integral(sqrt(phi0), phi0)'
```

⁴In a dense representation, the coefficients for all terms up to the degree of each variable are stored in memory. In a sparse representation, only the nonzero coefficients are stored.

Expressions can be printed with 2D, monospace fonts via `pprint`. Unicode characters are used for rendering mathematical symbols such as integral signs, square roots, and parentheses. Greek letters and subscripts in symbol names that have Unicode code points associated are also rendered automatically.

```
>>> pprint(Integral(sqrt(phi0 + 1), phi0))
```

$$\int \sqrt{\varphi_0 + 1} \, d(\varphi_0)$$

Alternately, the `use_unicode=False` flag can be set, which causes the expression to be printed using only ASCII characters.

```
>>> pprint(Integral(sqrt(phi0 + 1), phi0), use_unicode=False)
```

$$\int \sqrt{\text{phi0} + 1} \, d(\text{phi0})$$

The function `latex` returns a \LaTeX representation of an expression.

```
>>> print(latex(Integral(sqrt(phi0 + 1), phi0)))
```

```
\int \sqrt{\phi_0 + 1}\, d\phi_0
```

Users are encouraged to run the `init_printing` function at the beginning of interactive sessions, which automatically enables the best pretty printing supported by their environment. In the Jupyter Notebook or Qt Console [29], the \LaTeX printer is used to render expressions using MathJax or \LaTeX , if it is installed on the system. The 2D text representation is used otherwise.

Other printers such as MathML are also available. SymPy uses an extensible printer subsystem for customizing any given printer, and allows custom objects to define their printing behavior for any printer. The code generation functionality of SymPy relies on this subsystem to convert expressions into code in various target programming languages.

3.5. Solvers. SymPy has a module of equation solvers that can handle ordinary differential equations, recurrence relationships, Diophantine equations, and algebraic equations. There is also rudimentary support for simple partial differential equations.

There are two functions for solving algebraic equations in SymPy: `solve` and `solveset`. `solveset` has several design changes with respect to the older `solve` function. This distinction is present in order to resolve the usability issues with the previous `solve` function API while maintaining backward compatibility with earlier versions of SymPy. `solveset` only requires essential input information from the user. The function signatures of `solve` and `solveset` are

```
solve(f, *symbols, **flags)
```

```
solveset(f, symbol, domain=S.Complexes)
```

The `domain` parameter is typically either `S.Complexes` (the default) or `S.Reals`; the latter causes `solveset` to only return real solutions.

An important difference between the two functions is that the output API of `solve` varies with input (sometimes returning a Python list and sometimes a Python dictionary) whereas `solveset` always returns a SymPy set object.

Both functions implicitly assume that expressions are equal to 0. For instance, `solveset(x - 1, x)` solves $x - 1 = 0$ for x .

`solveset` is under active development as a planned replacement for `solve`. There

The double exponential (tanh-sinh) quadrature is used for numerical integration by default. For smooth integrands, this algorithm usually converges extremely rapidly, even when the integration interval is infinite or singularities are present at the endpoints [42, 2]. However, for good performance, singularities in the middle of the interval must be specified by the user. To evaluate slowly converging limits and infinite series, mpmath automatically tries Richardson extrapolation and the Shanks transformation (Euler-Maclaurin summation can also be used) [3]. A function to evaluate oscillatory integrals by means of convergence acceleration is also available.

A wide array of higher mathematical functions are implemented with full support for complex values of all parameters and arguments, including complete and incomplete gamma functions, Bessel functions, orthogonal polynomials, elliptic functions and integrals, zeta and polylogarithm functions, the generalized hypergeometric function, and the Meijer G-function. The Meijer G-function instance $G_{1,3}^{3,0}(0; \frac{1}{2}, -1, -\frac{3}{2}|x)$ is a good test case [43]; past versions of both Maple and Mathematica produced incorrect numerical values for large $x > 0$. Here, mpmath automatically removes an internal singularity and compensates for cancellations (amounting to 656 bits of precision when $x = 10000$), giving correct values:

```
>>> mpmath.mp.dps = 15
>>> mpmath.meijerg([[], [0]], [[-0.5, -1, -1.5], []], 10000)
mpf('2.4392576907199564e-94')
```

Equivalently, with SymPy's interface this function can be evaluated as:

```
>>> meijerg([[], [0]], [[-S(1)/2, -1, -S(3)/2], []], 10000).evalf()
2.43925769071996e-94
```

Symbolic integration and summation often produces hypergeometric and Meijer G-function closed forms (see Subsection 3.2); numerical evaluation of such special functions is a useful complement to direct numerical integration and summation.

5. Domain Specific Submodules. SymPy includes several packages that allow users to solve domain specific problems. For example, a comprehensive physics package is included that is useful for solving problems in mechanics, optics, and quantum mechanics along with support for manipulating physical quantities with units.

5.1. Classical Mechanics. One of the core domains that SymPy supports is the physics of classical mechanics. This is in turn separated into two distinct components: vector algebra symbolics and mechanics.

5.1.1. Vector Algebra. The `sympy.physics.vector` package provides reference frame-, time-, and space-aware vector and dyadic objects that allow for three-dimensional operations such as addition, subtraction, scalar multiplication, inner and outer products, and cross products. Both of these objects can be written in very compact notation that make it easy to express the vectors and dyadics in terms of multiple reference frames with arbitrarily defined relative orientations. The vectors are used to specify the positions, velocities, and accelerations of points; orientations, angular velocities, and angular accelerations of reference frames; and forces and torques. The dyadics are essentially reference frame-aware 3×3 tensors [41]. The vector and dyadic objects can be used for any one-, two-, or three-dimensional vector algebra, and they provide a strong framework for building physics and engineering tools.

The following Python code demonstrates how a vector is created using the orthogonal unit vectors of three reference frames that are oriented with respect to each other, and the result of expressing the vector in the A frame. The B frame is oriented with respect to the A frame using Z-X-Z Euler Angles of magnitude π , $\frac{\pi}{2}$, and $\frac{\pi}{3}$ rad,

519 respectively, whereas the C frame is oriented with respect to the B frame through a
520 simple rotation about the B frame's X unit vector through $\frac{\pi}{2}$ rad.

```
521 >>> from sympy.physics.vector import ReferenceFrame
522 >>> A = ReferenceFrame('A')
523 >>> B = ReferenceFrame('B')
524 >>> C = ReferenceFrame('C')
525 >>> B.orient(A, 'body', (pi, pi/3, pi/4), 'zxyz')
526 >>> C.orient(B, 'axis', (pi/2, B.x))
527 >>> v = 1*A.x + 2*B.z + 3*C.y
528 >>> v
529 A.x + 2*B.z + 3*C.y
530 >>> v.express(A)
531 A.x + 5*sqrt(3)/2*A.y + 5/2*A.z
```

532 **5.1.2. Mechanics.** The `sympy.physics.mechanics` package utilizes the `sympy.`
533 `physics.vector` package to populate time-aware particle and rigid-body objects to
534 fully describe the kinematics and kinetics of a rigid multi-body system. These objects
535 store all of the information needed to derive the ordinary differential or differential
536 algebraic equations that govern the motion of the system, i.e., the equations of mo-
537 tion. These equations of motion abide by Newton's laws of motion and can handle
538 arbitrary kinematic constraints or complex loads. The package offers two automated
539 methods for formulating the equations of motion based on Lagrangian Dynamics [22]
540 and Kane's Method [21]. Lastly, there are automated linearization routines for con-
541 strained dynamical systems [30].

542 **5.2. Quantum Mechanics.** The `sympy.physics.quantum` package has extensive
543 capabilities for performing symbolic quantum mechanics, using Python objects to rep-
544 resent the different mathematical objects relevant in quantum theory [37]: states (bras
545 and kets), operators (unitary, Hermitian, etc.), and basis sets, as well as operations
546 on these objects such as representations, tensor products, inner products, outer prod-
547 ucts, commutators, and anticommutators. The base objects are designed in the most
548 general way possible to enable any particular quantum system to be implemented
549 by subclassing the base operators and defining the relevant class methods to provide
550 system-specific logic.

551 Symbolic quantum operators and states may be defined, and one can perform a
552 full range of operations with them.

```
553 >>> from sympy.physics.quantum import Commutator, Dagger, Operator
554 >>> from sympy.physics.quantum import Ket, qapply
555 >>> A = Operator('A')
556 >>> B = Operator('B')
557 >>> C = Operator('C')
558 >>> D = Operator('D')
559 >>> a = Ket('a')
560 >>> comm = Commutator(A, B)
561 >>> comm
562 [A,B]
563 >>> qapply(Dagger(comm*a)).doit()
564 -<a|*(Dagger(A)*Dagger(B) - Dagger(B)*Dagger(A))
565 Commutators can be expanded using common commutator identities:
566 >>> Commutator(C+B, A*D).expand(commutator=True)
567 -[A,B]*D - [A,C]*D + A*[B,D] + A*[C,D]
```


On top of this set of base objects, a number of specific quantum systems have been implemented in a fully symbolic framework. These include:

- Many of the exactly solvable quantum systems, including simple harmonic oscillator states and raising/lowering operators, infinite square well states, and 3D position and momentum operators and states.
- Second quantized formalism of non-relativistic many-body quantum mechanics [13].
- Quantum angular momentum [45]. Spin operators and their eigenstates can be represented in any basis and for any quantum numbers. A rotation operator representing the Wigner-D matrix, which may be defined symbolically or numerically, is also implemented to rotate spin eigenstates. Functionality for coupling and uncoupling of arbitrary spin eigenstates is provided, including symbolic representations of Clebsch-Gordon coefficients and Wigner symbols.
- Quantum information and computing [25]. Multidimensional qubit states, and a full set of one- and two-qubit gates are provided and can be represented symbolically or as matrices/vectors. With these building blocks, it is possible to implement a number of basic quantum algorithms including the quantum Fourier transform, quantum error correction, quantum teleportation, Grover's algorithm, dense coding, etc. In addition, any quantum circuit may be plotted using the `circuit_plot` function (Figure 1).

Here are a few short examples of the quantum information and computing capabilities in `sympy.physics.quantum`. Start with a simple four-qubit state and flip the second qubit from the right using a Pauli-X gate:

```
>>> from sympy.physics.quantum.qubit import Qubit
>>> from sympy.physics.quantum.gate import XGate
>>> q = Qubit('0101')
>>> q
|0101>
>>> X = XGate(1)
>>> qapply(X*q)
|0111>
Qubit states can also be used in adjoint operations, tensor products, inner/outer
products:
>>> Dagger(q)
<0101|
>>> ip = Dagger(q)*q
>>> ip
<0101|0101>
>>> ip.doit()
1
Quantum gates (unitary operators) can be applied to transform these states and then
classical measurements can be performed on the results:
>>> from sympy.physics.quantum.qubit import measure_all
>>> from sympy.physics.quantum.gate import H, X, Y, Z
>>> c = H(0)*H(1)*Qubit('00')
>>> c
H(0)*H(1)*|00>
>>> q = qapply(c)
>>> measure_all(q)
[ (|00>, 1/4), (|01>, 1/4), (|10>, 1/4), (|11>, 1/4) ]
```



Fig. 1: The circuit diagram for a three-qubit quantum Fourier transform generated by SymPy.

```

618 Lastly, the following example demonstrates creating a three-qubit quantum Fourier
619 transform, decomposing it into one- and two-qubit gates, and then generating a circuit
620 plot for the sequence of gates (see Figure 1).
621 >>> from sympy.physics.quantum.qft import QFT
622 >>> from sympy.physics.quantum.circuitplot import circuit_plot
623 >>> fourier = QFT(0,3).decompose()
624 >>> fourier
625 SWAP(0,2)*H(0)*C((0),S(1))*H(1)*C((0),T(2))*C((1),S(2))*H(2)
626 >>> c = circuit_plot(fourier, nqubits=3)

```

6. Conclusion and future work. SymPy is a robust computer algebra system that provides a wide spectrum of features both in traditional computer algebra and in a plethora of scientific disciplines. This allows SymPy to be used in a first-class way with other Python projects, including the scientific Python stack. Unlike many other CASs, SymPy is designed to be used in an extensible way: both as an end-user application and as a library.

SymPy expressions are immutable trees of Python objects. SymPy uses Python both as the internal language and the user language. This permits users to access to the same methods that the library implements in order to extend it for their needs. Additionally, SymPy has a powerful assumptions system for declaring and deducing mathematical properties of expressions.

SymPy has submodules for many areas of mathematics. This includes functions for simplifying expressions, performing common calculus operations, pretty printing expressions, solving equations, and representing symbolic matrices. Other included areas are discrete math, concrete math, plotting, geometry, statistics, polynomials, sets, series, vectors, combinatorics, group theory, code generation, tensors, Lie algebras, cryptography, and special functions. Additionally, SymPy contains submodules targeting certain specific domains, such as classical mechanics and quantum mechanics. This breadth of domains has been engendered by a strong and vibrant user community. Anecdotally, these users likely chose SymPy because of its ease of access.

Some of the planned future work for SymPy includes work on improving code generation, improvements to the speed of SymPy (one area of work in this direction is [SymEngine](#), a C++ symbolic manipulation library that is planned to be usable as a alternative core for SymPy), improving the assumptions system, and improving the

651 solvers module.

652 **7. Acknowledgements.** The Los Alamos National Laboratory is operated by
653 Los Alamos National Security, LLC, for the National Nuclear Security Administration
654 of the U.S. Department of Energy under Contract No. DE-AC52-06NA25396.

655 Sandia is a multiprogram laboratory operated by Sandia Corporation, a Lockheed
656 Martin Company, for the United States Department of Energy's National Nuclear
657 Security Administration under Contract DE-AC04-94AL85000.

658 Google Summer of Code is an international annual program in which Google
659 awards stipends to all students who successfully complete a requested free and open-
660 source software coding project during the summer.

661 The author of this paper Francesco Bonazzi thanks the Deutsche Forschungsge-
662 meinschaft (DFG) for its financial support via the International Research Training
663 Group 1524 "Self-Assembled Soft Matter Nano-Structures at Interfaces."

664 8. References.

665 REFERENCES

- 666 [1] W. W. ADAMS AND P. LOUSTAUNAU, *An introduction to Gröbner bases*, no. 3, American Math-
667 ematical Society, 1994.
- 668 [2] D. H. BAILEY, K. JEYABALAN, AND X. S. LI, *A comparison of three high-precision quadrature*
669 *schemes*, Experimental Mathematics, 14 (2005), pp. 317–329.
- 670 [3] C. M. BENDER AND S. A. ORSZAG, *Advanced Mathematical Methods for Scientists and Engi-*
671 *neers*, Springer, 1st ed., October 1999.
- 672 [4] N. BIGGS, E. K. LLOYD, AND R. J. WILSON, *Graph Theory, 1736-1936*, Oxford University
673 Press, 1976.
- 674 [5] M. BRONSTEIN, *Poor Man's Integrator*, <http://www-sop.inria.fr/cafe/Manuel.Bronstein/pmint>.
- 675 [6] M. BRONSTEIN, *Symbolic Integration I: Transcendental Functions*, Springer-Verlag, New York,
676 NY, USA, 2005.
- 677 [7] B. BUCHBERGER, *Ein Algorithmus zum Auffinden der Basis Elemente des Restklassenrings*
678 *nach einem nulldimensionalen Polynomideal*, PhD thesis, University of Innsbruck, Inns-
679 bruck, Austria, 1965.
- 680 [8] J. CARETTE, *Understanding Expression Simplification*, in ISSAC '04: Proceedings of the
681 2004 International Symposium on Symbolic and Algebraic Computation, New York,
682 NY, USA, 2004, ACM Press, pp. 72–79, [http://dx.doi.org/http://doi.acm.org/10.1145/](http://dx.doi.org/http://doi.acm.org/10.1145/1005285.1005298)
683 [1005285.1005298](http://dx.doi.org/http://doi.acm.org/10.1145/1005285.1005298).
- 684 [9] D. CERVONE, *Mathjax: a platform for mathematics on the web*, Notices of the AMS, 59 (2012),
685 pp. 312–316.
- 686 [10] R. CIMRMAN, *SfePy - write your own FE application*, in Proceedings of the 6th European
687 Conference on Python in Science (EuroSciPy 2013), P. de Buyl and N. Varoquaux, eds.,
688 2014, pp. 65–70. <http://arxiv.org/abs/1404.6391>.
- 689 [11] J. C. FAUGÈRE, *A New Efficient Algorithm for Computing Gröbner Bases (F4)*, Journal of
690 Pure and Applied Algebra, 139 (1999), pp. 61–88, [http://www-calfor.lip6.fr/~jcf/Papers/](http://www-calfor.lip6.fr/~jcf/Papers/F99a.pdf)
691 [F99a.pdf](http://www-calfor.lip6.fr/~jcf/Papers/F99a.pdf).
- 692 [12] J. C. FAUGÈRE, *A New Efficient Algorithm for Computing Gröbner Bases Without Reduc-*
693 *tion To Zero (F5)*, in ISSAC '02: Proceedings of the 2002 International Symposium on
694 Symbolic and Algebraic Computation, New York, NY, USA, 2002, ACM Press, pp. 75–
695 83, <http://dx.doi.org/http://doi.acm.org/10.1145/780506.780516>, [http://www-calfor.lip6.](http://www-calfor.lip6.fr/~jcf/Papers/F02a.pdf)
696 [fr/~jcf/Papers/F02a.pdf](http://www-calfor.lip6.fr/~jcf/Papers/F02a.pdf).
- 697 [13] A. FETTER AND J. WALECKA, *Quantum Theory of Many-Particle Systems*, Dover Publications,
698 2003.
- 699 [14] H. FU, X. ZHONG, AND Z. ZENG, *Automated and Readable Simplification of Trigonometric*
700 *Expressions*, Mathematical and Computer Modelling, 55 (2006), pp. 1169–1177.
- 701 [15] G. GEDE, D. L. PETERSON, A. S. NANJANGUD, J. K. MOORE, AND M. HUBBARD, *Constrained*
702 *multibody dynamics with Python: From symbolic equation generation to publication*, in
703 ASME 2013 International Design Engineering Technical Conferences and Computers and
704 Information in Engineering Conference, American Society of Mechanical Engineers, 2013,
705 pp. V07BT10A051–V07BT10A051.

- [16] D. GOLDBERG, *What every computer scientist should know about floating-point arithmetic*, ACM Computing Surveys (CSUR), 23 (1991), pp. 5–48.
- [17] R. W. GOSPER, *Decision procedure for indefinite hypergeometric summation*, Proceedings of the National Academy of Sciences, 75 (1978), pp. 40–42.
- [18] D. GRUNTZ, *On Computing Limits in a Symbolic Manipulation System*, PhD thesis, Swiss Federal Institute of Technology, Zürich, Switzerland, 1996.
- [19] C. V. HORSSEN, *GMPY*. <https://pypi.python.org/pypi/gmpy2>, 2015.
- [20] J. D. HUNTER, *Matplotlib: A 2d graphics environment*, Computing In Science & Engineering, 9 (2007), pp. 90–95.
- [21] T. R. KANE AND D. A. LEVINSON, *Dynamics, Theory and Applications*, McGraw Hill, 1985.
- [22] J. LAGRANGE, *Mécanique analytique*, no. v. 1 in *Mécanique analytique*, Ve Courcier, 1811.
- [23] S. LANG, *Introduction to transcendental numbers*, Reading, Mass, (1966).
- [24] M. LUTZ, *Learning Python*, O'Reilly Media, Inc., 2013.
- [25] M. NIELSEN AND I. CHUANG, *Quantum Computation and Quantum Information*, Cambridge University Press, 2011.
- [26] A. NIJENHUIS AND H. S. WILF, *Combinatorial Algorithms: For Computers and Calculators*, Academic Press, New York, NY, USA, second ed., 1978.
- [27] T. E. OLIPHANT, *Python for scientific computing*, Computing in Science & Engineering, 9 (2007), pp. 10–20.
- [28] M. PAPROCKI, *Design and implementation issues of a computer algebra system in an interpreted, dynamically typed programming language*, master's thesis, University of Technology of Wrocław, Poland, 2010.
- [29] F. PÉREZ AND B. E. GRANGER, *IPython: a system for interactive scientific computing*, Computing in Science & Engineering, 9 (2007), pp. 21–29.
- [30] D. L. PETERSON, G. GEDE, AND M. HUBBARD, *Symbolic linearization of equations of motion of constrained multibody systems*, Multibody System Dynamics, 33 (2014), pp. 143–161, <http://dx.doi.org/10.1007/s11044-014-9436-5>.
- [31] M. PETKOVŠEK, H. S. WILF, AND D. ZEILBERGER, *A = BAK peters*, Wellesley, MA, (1996).
- [32] E. RAYMOND, *The cathedral and the bazaar*, Knowledge, Technology & Policy, 12 (1999), pp. 23–49.
- [33] K. ROACH, *Hypergeometric function representations*, in ISSAC '96: Proceedings of the 1996 International Symposium on Symbolic and Algebraic Computation, New York, NY, USA, 1996, ACM Press, pp. 301–308, <http://dx.doi.org/http://doi.acm.org/10.1145/236869.237088>, <http://www.planetquantum.com/TheMission/Papers/Issac96.pdf>.
- [34] K. ROACH, *Meijer G function representations*, in ISSAC '97: Proceedings of the 1997 international symposium on Symbolic and algebraic computation, New York, NY, USA, 1997, ACM, pp. 205–211, <http://dx.doi.org/http://doi.acm.org/10.1145/258726.258784>.
- [35] M. ROCKLIN AND A. R. TERREL, *Symbolic statistics with SymPy*, Computing in Science and Engineering, 14 (2012), <http://dx.doi.org/10.1109/MCSE.2012.56>.
- [36] L. ROSEN, *Open source licensing*, vol. 692, Prentice Hall, 2005.
- [37] J. SAKURAI AND J. NAPOLITANO, *Modern Quantum Mechanics*, Addison-Wesley, 2010.
- [38] M. SHAW AND D. GARLAN, *Software Architecture: Perspectives on an Emerging Discipline*, Prentice Hall, 1996. Prentice Hall Ordering Information.
- [39] W. STEIN AND D. JOYNER, *SAGE: System for Algebra and Geometry Experimentation*, Communications in Computer Algebra, 39 (2005).
- [40] G. J. SUSSMAN AND J. WISDOM, *Functional Differential Geometry*, Massachusetts Institute of Technology Press, 2013.
- [41] C.-T. TAI, *Generalized vector and dyadic analysis: applied mathematics in field theory*, vol. 9, Wiley-IEEE Press, 1997.
- [42] H. TAKAHASI AND M. MORI, *Double exponential formulas for numerical integration*, Publications of the Research Institute for Mathematical Sciences, 9 (1974), pp. 721–741.
- [43] V. T. TOTH, *Maple and Meijer's G-function: a numerical instability and a cure*. <http://www.vttoth.com/CMS/index.php/technical-notes/67>, 2007.
- [44] M. J. TURK, B. D. SMITH, J. S. OISHI, S. SKORY, S. W. SKILLMAN, T. ABEL, AND M. L. NORMAN, *yt: A Multi-code Analysis Toolkit for Astrophysical Simulation Data*, The Astrophysical Journal Supplement Series, 192 (2011), pp. 9–+, <http://dx.doi.org/10.1088/0067-0049/192/1/9>, arXiv:1011.3514.
- [45] R. ZARE, *Angular Momentum: Understanding Spatial Aspects in Chemistry and Physics*, Wiley, 1991.