

SymPy: Symbolic Computing in Python

April 19, 2016

1 Introduction

2 Architecture

2.1 The Core

Every symbolic expression in SymPy is an instance of a Python class. Expressions are represented by expression trees. The operators are represented by the type of an expression and the child nodes are stored in the `args` attribute. A leaf node in the expression tree has an empty `args`. The `args` attribute is provided by the class `Basic`, which is a superclass of all SymPy objects and provides common methods to all SymPy tree-elements. For example, take the expression $xy + 2$.

```
>>> from sympy import *
>>> x, y = symbols('x y')
>>> expr = x*y + 2
```

The expression `expr` is an addition, so it is of type `Add`. The child nodes of `expr` are `x*y` and `2`.

```
>>> type(expr)
<class 'sympy.core.add.Add'>
>>> expr.args
(2, x*y)
```

We can dig further into the expression tree to see the full expression. For example, the first child node, given by `expr.args[0]` is `2`. Its class is `Integer`, and it has empty `args`, indicating that it is a leaf node.

```
>>> expr.args[0]
2
>>> type(expr.args[0])
<class 'sympy.core.numbers.Integer'>
>>> expr.args[0].args
()
```

The function `srepr` gives a string representing a valid Python code, containing all the nested class constructor calls to create the given expression.

```
>>> srepr(expr)
"Add(Mul(Symbol('x'), Symbol('y')), Integer(2))"
```

Every SymPy expression satisfies a key invariant, namely, `expr.func(*expr.args) == expr`. This means that expressions are rebuildable from their `args`¹. Here, we note that in SymPy, the `==` operator represents exact structural equality, not mathematical equality. This allows one to test if any two expressions are equal to one another as expression trees.

Python allows classes to overload operators. The Python interpreter translates the above `x*y + 2` to, roughly, `(x.__mul__(y)).__add__(2)`. `x` and `y`, returned from the `symbols` function, are `Symbol` instances. The `2` in the expression is processed by Python as a literal, and is stored as Python's builtin `int` type. When `2` is called by the `__add__` method, it is converted to the SymPy type `Integer(2)`. In this way, SymPy expressions can be built in the natural way using Python operators and numeric literals.

One must be careful in one particular instance. Python does not have a builtin rational literal type. Given a fraction of integers such as `1/2`, Python will perform floating point division and produce `0.5`². Python uses eager evaluation, so expressions like `x + 1/2` will produce `x + 0.5`, and by the time any SymPy function sees the `1/2` it has already been converted to `0.5` by Python. However, for a CAS like SymPy, one typically wants to work with exact rational numbers whenever possible. Working around this is simple, however: one can wrap one of the integers with `Integer`, like `x + Integer(1)/2`, or using `x + Rational(1, 2)`. SymPy provides a function `S` which can be used to convert objects to SymPy types with minimal typing, such as `x + S(1)/2`. This gotcha is a small downside to using Python directly instead of a custom domain specific language (DSL), and we consider it to be worth it for the advantages listed above.

2.2 Assumptions

An important feature of the SymPy core is the assumptions system. The assumptions system allows users to specify that symbols have certain common mathematical properties, such as being positive, imaginary, or integer. SymPy is careful to never perform simplifications on an expression unless the assumptions allow them. For instance, the identity $\sqrt{x^2} = x$ holds if x is nonnegative ($x \geq 0$). If x is real, the identity $\sqrt{x^2} = |x|$ holds. However, for general complex x , no such identity holds.

By default, SymPy performs all calculations assuming that variables are complex valued. This assumption makes it easier to treat mathematical problems in full generality.

¹`expr.func` is used instead of `type(expr)` to allow the function of an expression to be distinct from its actual Python class. In most cases the two are the same.

²This is the behavior in Python 3. In Python 2, `1/2` will perform integer division and produce `0`, unless one uses `from __future__ import division`.

```
>>> x = Symbol('x')
>>> sqrt(x**2)
sqrt(x**2)
```

By assuming symbols are complex by default, SymPy avoids performing mathematically invalid operations. However, in many cases users will wish to simplify expressions containing terms like $\sqrt{x^2}$.

Assumptions are set on `Symbol` objects when they are created. For instance `Symbol('x', positive=True)` will create a symbol named `x` that is assumed to be positive.

```
>>> x = Symbol('x', positive=True)
>>> sqrt(x**2)
x
```

Some common assumptions that SymPy allows are `positive`, `negative`, `real`, `nonpositive`, `nonnegative`, `integer`, and `commutative`³. Assumptions on any object can be checked with the `is_`*assumption* attributes, like `x.is_positive`.

Assumptions are only needed to restrict a domain so that certain simplifications can be performed. It is not required to make the domain match the input of a function. For instance, one can create the object $\sum_{n=0}^m f(n)$ as `Sum(f(n), (n, 0, m))` without setting `integer=True` when creating the `Symbol` object `n`.

The assumptions system additionally has deductive capabilities. The assumptions use a three-valued logic using the Python builtin objects `True`, `False`, and `None`. `None` represents the “unknown” case. This could mean that the given assumption could be either true or false under the given information, for instance, `Symbol('x', real=True).is_positive` will give `None` because a real symbol might be positive or it might not. It could also mean not enough is implemented to compute the given fact, for instance, `(pi + E).is_irrational` gives `None`, because SymPy does not know how to determine if $\pi + e$ is rational or irrational, indeed, it is an open problem in mathematics.

Basic implications between the facts are used to deduce assumptions. For instance, the assumptions system knows that being an integer implies being rational, so `Symbol('x', integer=True).is_rational` returns `True`. Furthermore, expressions compute the assumptions on themselves based on the assumptions of their arguments. For instance, if `x` and `y` are both created with `positive=True`, then `(x + y).is_positive` will be `True`.

SymPy also has an experimental assumptions system where facts are stored separate from objects, and deductions are made with a SAT solver. We will not discuss this system here.

³If A and B are Symbols created with `commutative=False` then SymPy will keep $A \cdot B$ and $B \cdot A$ distinct.

2.3 Extensibility

Extensibility is an important feature for SymPy. Because the same language, Python, is used both for the internal implementation and the external usage by users, all the extensibility capabilities available to users are also used by functions that are part of SymPy.

The typical way to create a custom SymPy object is to subclass an existing SymPy class, generally either `Basic`, `Expr`, or `Function`. All SymPy classes used for expression trees⁴ should be subclasses of the base class `Basic`, which defines some basic methods for symbolic expression trees. `Expr` is the subclass for mathematical expressions that can be added and multiplied together. Instances of `Expr` are typically complex numbers, but may also include other “rings” like matrix expressions. Not all SymPy classes are `Expr`. For instance, logic expressions, such as `And(x, y)` are `Basic` but not `Expr`.

The `Function` class is a subclass of `Expr` which makes it easier to define mathematical functions called with arguments. This includes named functions like $\sin(x)$ and $\log(x)$ as well as undefined functions like $f(x)$. Subclasses of `Function` should define a class method `eval`, which returns values for which the function should be automatically evaluated, and `None` for arguments that shouldn’t be automatically evaluated.

The behavior of classes in SymPy with various other SymPy functions is defined by defining a relevant `_eval_*` method on the class. For instance, an object can tell SymPy’s `diff` function how to take the derivative of itself by defining the `_eval_derivative(self, x)` method. The most common `_eval_*` methods relate to the assumptions. `_eval_is_assumption` defines the assumptions for *assumption*.

Here is a stripped down version of the gamma function $\Gamma(x)$ from SymPy, which evaluates itself on positive integer arguments, has the positive and real assumptions defined, can be rewritten in terms of factorial with `gamma(x).rewrite(factorial)`, and can be differentiated. `fdiff` is a convenience method for subclasses of `Function`. `fdiff` returns the derivative of the function without worrying about the chain rule. `self.func` is used throughout instead of referencing `gamma` explicitly so that potential subclasses of `gamma` can reuse the methods.

```
from sympy import Integer, Function, floor, factorial, polygamma

class gamma(Function)
    @classmethod
    def eval(cls, arg):
        if isinstance(arg, Integer) and arg.is_positive:
            return factorial(arg - 1)

    def _eval_is_real(self):
        x = self.args[0]
```

⁴Some internal classes, such as those used in the polynomial module, do not follow this rule.

```

        # noninteger means real and not integer
        if x.is_positive or x.is_noninteger:
            return True

def _eval_is_positive(self):
    x = self.args[0]
    if x.is_positive:
        return True
    elif x.is_noninteger:
        return floor(x).is_even

def _eval_rewrite_as_factorial(self, z):
    return factorial(z - 1)

def fdiff(self, argindex=1):
    from sympy.core.function import ArgumentIndexError
    if argindex == 1:
        return self.func(self.args[0])*polygamma(0, self.args[0])
    else:
        raise ArgumentIndexError(self, argindex)

```

The actual gamma function defined in SymPy has much more implemented than this, such as evaluation at rational points and series expansion.

3 Algorithms

3.1 Numerics

3.2 Polynomials

3.3 The Risch Algorithm

3.4 The Gruntz Algorithm

The limit module implements the Gruntz algorithm [?].

Examples:

```

In [1]: limit(sin(x)/x, x, 0)
Out[1]: 1

```

```

In [2]: limit((2*E**((1-cos(x))/sin(x))-1)*(sinh(x)/atan(x)**2), x, 0)
Out[2]: E

```

3.4.1 Details

We first define comparability classes by calculating L :

$$L \equiv \lim_{x \rightarrow \infty} \frac{\log |f(x)|}{\log |g(x)|} \quad (1)$$

And then we define the $<$, $>$ and \sim operations as follows: $f > g$ when $L = \pm\infty$ (f is more rapidly varying than g , i.e. f goes to ∞ or 0 faster than g , f is greater than any power of g), $f < g$ when $L = 0$ (f is less rapidly varying than g) and $f \sim g$ when $L \neq 0, \pm\infty$ (both f and g are bounded from above and below by suitable integral powers of the other).

Examples:

$$\begin{aligned} 2 &< x < e^x < e^{x^2} < e^{e^x} \\ 2 &\sim 3 \sim -5 \\ x &\sim x^2 \sim x^3 \sim \frac{1}{x} \sim x^m \sim -x \\ e^x &\sim e^{-x} \sim e^{2x} \sim e^{x+e^{-x}} \\ f(x) &\sim \frac{1}{f(x)} \end{aligned}$$

The Gruntz algorithm, on an example:

$$\begin{aligned} f(x) &= e^{x+2e^{-x}} - e^x + \frac{1}{x} \\ \lim_{x \rightarrow \infty} f(x) &=? \end{aligned}$$

Strategy: mrv set: the set of most rapidly varying subexpressions $\{e^x, e^{-x}, e^{x+2e^{-x}}\}$, the same comparability class. Take an item ω from mrv, converging to 0 at infinity. Here $\omega = e^{-x}$. If not present in the mrv set, use the relation $f(x) \sim \frac{1}{f(x)}$.

Rewrite the mrv set using ω : $\{\frac{1}{\omega}, \omega, \frac{1}{\omega}e^{2\omega}\}$, substitute back into $f(x)$ and expand in ω :

$$f(x) = \frac{1}{x} - \frac{1}{\omega} + \frac{1}{\omega}e^{2\omega} = 2 + \frac{1}{x} + 2\omega + O(\omega^2)$$

The core idea of the algorithm: ω is from the mrv set, so in the limit $\omega \rightarrow 0$:

$$f(x) = \frac{1}{x} - \frac{1}{\omega} + \frac{1}{\omega}e^{2\omega} = 2 + \frac{1}{x} + 2\omega + O(\omega^2) \rightarrow 2 + \frac{1}{x}$$

We iterate until we get just a number, the final limit. Gruntz proved this algorithm always works and converges in his Ph.D. thesis [?].

Generally:

$$f(x) = \underbrace{O\left(\frac{1}{\omega^3}\right)}_{\infty} + \underbrace{\frac{C_{-2}(x)}{\omega^2}}_{\infty} + \underbrace{\frac{C_{-1}(x)}{\omega}}_{\infty} + C_0(x) + \underbrace{C_1(x)\omega}_0 + \underbrace{O(\omega^2)}_0$$

we look at the lowest power of ω . The limit is one of: 0, $\lim_{x \rightarrow \infty} C_0(x)$, ∞ .

3.5 Logic

3.6 Other

4 Features

SymPy has an extensive feature set that encompasses too much to cover in-depth here. Bedrock areas, such as Calculus, receive their own sub-sections below. Additionally, Table 4 describes other capabilities present in the SymPy code base. This gives a sampling from the breadth of topics and application domains that SymPy services.

4.1 Basic Operations

4.1.1 Expression manipulation

4.1.2 Assumptions system

SymPy has two assumptions systems, referred to as new-style and old-style assumptions.

In the old-style assumptions system propositions are assigned to symbols upon class construction, for example, to declare the symbol i as positive integer, one would call

```
i = Symbol("i", integer=True, positive=True)
```

querying the assumptions is handled through attributes

```
i.is_positive  
i.is_integer
```

These methods return either a boolean, indicating whether the proposition is true or false, or a None, when it is impossible to determine the truth value of the queried proposition.

Despite the fact that assumptions can only be declared on symbols, querying can happen on every expression.

```
In [1]: x,y = symbols('x y', positive=True)
```

```
In [2]: (x*y).is_positive  
Out[2]: True
```

```
In [3]: z = symbols('z')
```

```
In [4]: (x*z).is_positive
```

```
In [5]: w = symbols('w', positive=False)
```

```
In [6]: (x*w).is_positive  
Out[6]: False
```

Table 1: SymPy Features and Descriptions

Feature	Description
Discrete Math	Summations, products, binomial coefficients, prime number tools, integer factorization, Diophantine equation solving, and boolean logic representation, equivalence testing, and inference.
Concrete Math	Tools for determining whether summation and product expressions are convergent, absolutely convergent, hypergeometric, and other properties. May also compute Gosper’s normal form [1] for two univariate polynomials.
Plotting	Hooks for visualizing expressions via matplotlib [?] or as text drawings when lacking a graphical back-end.
Geometry	Allows the creation of 2D geometrical entities, such as lines and circles. Enables queries on these entities, including asking the area of an ellipse, checking for collinearity of a set of points, or finding the intersection between two lines.
Statistics	Support for a random variable type as well as the ability to declare this variable from prebuilt distribution functions such as Normal, Exponential, Coin, Die, and other custom distributions.
Polynomials	Computes polynomial algebras over various coefficient domains ranging from the simple (e.g. polynomial division) to the advanced (e.g. Gröbner bases [2] and multivariate factorization over algebraic number domains).
Sets	Representations of empty, finite, and infinite sets. This includes special sets such as for all natural, integer, and complex numbers.
Series	Implements series expansion, sequences, and limit of sequences. This includes special series, such as Fourier and power series.
Vectors	Provides basic vector math and differential calculus with respect to 3D Cartesian coordinate systems.
Matrices	Tools for creating matrices of symbols and expressions. This is capable of both sparse and dense representations and performing symbolic linear algebraic operations (e.g. inversion and factorization).
Combinatorics & Group Theory	Implements permutations, combinations, partitions, subsets, various permutation groups (such as polyhedral, Rubik, symmetric, and others), Gray codes [?], and Prufer sequences [3].
Code Generation	Enables generation of compilable and executable code in a variety of different programming languages directly from expressions. Target languages include C, Fortran, Julia, JavaScript, Mathematica, Matlab and Octave, Python, and Theano.
Tensors	Symbolic manipulation of indexed objects.
Lie Algebras	Represents Lie algebras and root systems.
Cryptography	Represents block and stream ciphers, including shift, Affine, substitution, Vigenere’s, Hill’s, bifid, RSA, Kid RSA, linear-feedback shift registers, and Elgamal encryption
Special Functions	Implements a number of well known special functions, including Dirac delta, Gamma, Beta, Gauss error func-

The output 2 is true because SymPy's algorithms can deduce that the product of two positive numbers is positive, while there is no output for input 4, as the symbol z doesn't have any information about its sign, and the product $x \cdot z$ may be positive as well as negative. Finally, output 6 is false as the product of positive and negative numbers is negative.

The new-style assumptions are an assumptions system that exists alongside with the old-style, but is significantly different in the way predicates are used. Predicates in the new-style assumptions system are located under the `Q` namespace, they appear as `Q.positive`, `Q.integer` and so on.

Querying is provided through the `ask` functions. The previous example in the new-style assumptions can be written as

```
In [1]: ask(Q.positive(x*y), Q.positive(x) & Q.positive(y))
Out[1]: True
```

```
In [2]: ask(Q.positive(x*y), Q.positive(x))
```

```
In [3]: ask(Q.positive(x*y), Q.positive(x) & Q.negative(y))
Out[3]: False
```

That is, `ask` returns the truth value of its first parameter assuming that its latter argument is true.

Expressions like `Q.positive` are instances of the class `Predicate`, while the same expression with a parameter, such as `Q.positive(x)` is an instance of `AppliedPredicate`.

Logical connectors can be expressed through operator overloading, such as in `Q.positive(x) & Q.positive(y)`, or by directly constructing the identical expression through the logical connector class, in this case `And(Q.positive(x), Q.positive(y))`.

4.1.3 Calculus

Derivations can be computed with the `diff` function, or using the method with the same name on the expressions:

```
In [1]: diff(sin(x), x)
Out[1]: cos(x)
```

```
In [2]: sin(x).diff(x)
Out[2]: cos(x)
```

The class `Derivative` is a container for unevaluated derivatives

```
In [3]: expr = Derivative(sin(x), x)
```

```
In [4]: expr
Out[4]:
d
(sin(x))
dx
```

To evaluate such a held expression, simply call the `doit` method:

```
In [5]: expr.doit()
Out[5]: cos(x)
```

Integrals can be analogously calculated either with the `integrate` function or with the method with the same name on expressions:

```
>>> integrate(sin(x), x)
-cos(x)
```

This expression returns an expression whose derivative is the original expression. Notice that integrals are defined up to an integration constant, for the sake of simplicity SymPy will not display the full generic expression.

Definite integration can be calculated with the same method, by specifying a range of the integration variable:

```
>>> integrate(sin(x), (x, 0, 1))
-cos(1) + 1
```

To express unevaluated integrals, the class `Integral` may help

```
Integral(sin(x), x)
```

as in the case of derivatives, the method `doit` will cause such an expression to be evaluated.

Limits:

```
In [9]: limit(sin(x)/x, x, 0)
Out[9]: 1
```

for unevaluated expressions, `Limit`.

TODO: Sums and products.

4.1.4 Expression outputs

4.2 Calculus

4.3 Solvers

Diophantine equations play a central and an important role in number theory. A Diophantine equation has the form, $f(x_1, x_2, \dots, x_n) = 0$ where $n \geq 2$ and x_1, x_2, \dots, x_n are integer variables. If we can find n integers a_1, a_2, \dots, a_n such that $x_1 = a_1, x_2 = a_2, \dots, x_n = a_n$ satisfies the above equation, we say that the equation is solvable.

Currently, following five types of Diophantine equations can be solved using SymPy's Diophantine module.

- Linear Diophantine equations: $a_1x_1 + a_2x_2 + \dots + a_nx_n = b$
- General binary quadratic equation: $ax^2 + bxy + cy^2 + dx + ey + f = 0$

- Homogeneous ternary quadratic equation: $ax^2 + by^2 + cz^2 + dxy + eyz + fzx = 0$
- Extended Pythagorean equation: $a_1x_1^2 + a_2x_2^2 + \dots + a_nx_n^2 = a_{n+1}x_{n+1}^2$
- General sum of squares: $x_1^2 + x_2^2 + \dots + x_n^2 = k$

When an equation is fed into Diophantine module, it factors the equation (if possible) and solves each factor separately. Then all the results are combined to create the final solution set. Following examples illustrate some of the basic functionalities of the Diophantine module.

```
>>> from sympy import symbols
>>> x, y, z = symbols("x, y, z", integer=True)

>>> diophantine(2*x + 3*y - 5)
set([(3*t_0 - 5, -2*t_0 + 5)])

>>> diophantine(2*x + 4*y - 3)
set()

>>> diophantine(x**2 - 4*x*y + 8*y**2 - 3*x + 7*y - 5)
set([(2, 1), (5, 1)])

>>> diophantine(x**2 - 4*x*y + 4*y**2 - 3*x + 7*y - 5)
set([(-2*t**2 - 7*t + 10, -t**2 - 3*t + 5)])

>>> diophantine(3*x**2 + 4*y**2 - 5*z**2 + 4*x*y - 7*y*z + 7*z*x)
set([(-16*p**2 + 28*p*q + 20*q**2, 3*p**2 + 38*p*q - 25*q**2, 4*p**2 - 24*p*q + 68*q**2)])

>>> from sympy.abc import a, b, c, d, e, f
>>> diophantine(9*a**2 + 16*b**2 + c**2 + 49*d**2 + 4*e**2 - 25*f**2)
set([(70*t1**2 + 70*t2**2 + 70*t3**2 + 70*t4**2 - 70*t5**2, 105*t1*t5, 420*t2*t5, 60*t3*t5,

>>> diophantine(a**2 + b**2 + c**2 + d**2 + e**2 + f**2 - 112)
set([(8, 4, 4, 4, 0, 0)])
```

4.4 Matrices

SymPy supports matrices with symbolic expressions as elements. There are two types of matrices, Mutable and Immutable. Mutable classes are the default in SymPy as mutability is important for performance, but it means that standard matrices can not interact well with the rest of SymPy. This is because the Basic object, from which most SymPy classes inherit, is immutable.

Immutable matrix classes inherit from Basic and can thus interact more naturally with the rest of SymPy.

```
In [1]: from sympy import Matrix, symbols, MatrixSymbol
```

```
In [2]: x, y = symbols('x y', positive=True)
```

```
In [3]: t = Matrix(2, 2, [x, x + y, y, x])
```

```
In [4]: t
```

```
Out[4]:  
Matrix(  
[  x, x + y],  
[  y,  x])
```

```
In [5]: t[0, 1] = y
```

```
In [6]: t
```

```
Out[6]:  
Matrix(  
[x, y],  
[y, x])
```

All SymPy matrix types can do linear algebra including matrix addition, multiplication, exponentiation, computing determinant, solving linear systems and computing inverses using LU decomposition, LDL decomposition, Gauss-Jordan elimination, Cholesky decomposition, Moore-Penrose pseudoinverse, adjugate matrix.

Eigenvalues are computed symbolically as well. Eigenvalues are computed by generating the characteristic polynomial using the Berkowitz algorithm and then solving it using polynomial routines. Diagonalizable matrices can be diagonalized first to compute the eigenvalues.

```
In [10]: t.eigenvals()
```

```
Out[10]: {x - y: 1, x + y: 1}
```

Internally these matrices store the elements as a list making it a dense representation. For storing sparse matrices, SparseMatrix and ImmutableSparseMatrix classes can be used. Sparse matrix classes store the elements in Dictionary of Keys (DoK) format.

SymPy also supports matrices with unknown dimension values. MatrixSymbol represents a matrix with dimensions `m`, `n` where `m` and `n` can be symbols or integers. Matrix addition and multiplication, scalar operations, matrix inverse and transpose are stored symbolically as matrix expressions. Mutable matrices are converted to corresponding immutable types before interacting with matrix expressions

```
In [11]: m, n, p = symbols("m, n, p", integer=True)
```

```

In [12]: r, s = MatrixSymbol("r", m, n), MatrixSymbol("s", n, p)

In [13]: u = r * s + 2*MatrixSymbol("t", m, p)

In [14]: u.shape
Out[14]: (m, p)

In [15]: u[0, 1]
Out[15]: 2*t[0, 1] + Sum(r[0, _k]*s[_k, 1], (_k, 0, n - 1))

```

Block matrices are also supported in SymPy. BlockMatrix elements can be any matrix expression which includes immutable matrices, matrix symbols and block matrices. All functionalities of matrix expressions are also present in BlockMatrix.

```

>>> from sympy import (MatrixSymbol, BlockMatrix, symbols,
...     Identity, ZeroMatrix, block_collapse)
>>> n, m, l = symbols('n m l')
>>> X = MatrixSymbol('X', n, n)
>>> Y = MatrixSymbol('Y', m, m)
>>> Z = MatrixSymbol('Z', n, m)
>>> B = BlockMatrix([[X, Z], [ZeroMatrix(m, n), Y]])
>>> print(B)
Matrix([
[X, Z],
[0, Y]])
>>> print(B[0, 0])
X[0, 0]

```

4.5 Physics

SymPy includes several packages that allow users to solve domain specific problems. For example, a comprehensive physics package is included that is useful for solving problems in classical mechanics, optics, and quantum mechanics along with support for manipulating physical quantities with units.

4.6 Vector Algebra

The `sympy.physics.vector` package provides reference frame, time, and space aware vector and dyadic objects that allow for three dimensional operations such as addition, subtraction, scalar multiplication, inner and outer products, cross products, etc. Both of these objects can be written in very compact notation that make it easy to express the vectors and dyadics in terms of multiple reference frames with arbitrarily defined relative orientations. The vectors are used to specify the positions, velocities, and accelerations of points, orientations, angular velocities, and angular accelerations of reference frames, and force and

torques. The dyadics are essentially reference frame aware 3×3 tensors. The vector and dyadic objects can be used for any one-, two-, or three-dimensional vector algebra and they provide a strong framework for building physics and engineering tools.

```
>>> from sympy import pi
>>> from sympy.physics.vector import ReferenceFrame
>>> A = ReferenceFrame('A')
>>> B = ReferenceFrame('B')
>>> C = ReferenceFrame('C')
>>> B.orient(A, 'body', (pi, pi / 3, pi / 4), 'zxz')
>>> C.orient(B, 'axis', (pi / 2, B.x))
>>> v = 1 * A.x + 2 * B.z + 3 * C.y
>>> v
A.x + 2*B.z + 3*C.y
>>> v.express(A)
A.x + 5*sqrt(3)/2*A.y + 5/2*A.z
```

Listing 1: Python interpreter session showing how a vector is created using the orthogonal unit vectors of three reference frames that are oriented with respect to each other and the result of expressing the vector in the A frame. The B frame is oriented with respect to the A frame using Z-X-Z Euler Angles of magnitude π , $\frac{\pi}{2}$, and $\frac{\pi}{3}$ rad, respectively whereas the C frame is oriented with respect to the B frame through a simple rotation about the B frame's X unit vector through $\frac{\pi}{2}$ rad.

4.7 Classical Mechanics

The `physics.mechanics` package utilizes the `physics.vector` package to populate time aware particle and rigid body objects to fully describe the kinematics and kinetics of a rigid multi-body system. These objects store all of the information needed to derive the ordinary differential or differential algebraic equations that govern the motion of the system, i.e. the equations of motion. These equations of motion abide by Newton's laws of motion and can handle any arbitrary kinematical constraints or complex loads. The package offers two automated methods for formulating the equations of motion based on Lagrangian Dynamics [4] and Kane's Method [5]. Lastly, there are automated linearization routines for constrained dynamical systems based on [6].

4.8 Quantum Mechanics

The `sympy.physics.quantum` package provides quantum functions, states, operators, and computation of standard quantum models.

4.9 Optics

The `physics.optics` package provides Gaussian optics functions.

4.10 Units

The `physics.units` module provides around two hundred predefined prefixes and SI units that are commonly used in the sciences. Additionally, it provides the `Unit` class which allows the user to define their own units. These prefixes and units are multiplied by standard SymPy objects to make expressions unit aware, allowing for algebraic and calculus manipulations to be applied to the expressions while the units are tracked in the manipulations. The units of the expressions can be easily converted to other desired units. There is also a new units system in `sympy.physics.unitsystems` that allows the user to work in specified unit systems.

5 Other Projects that use SymPy

There are several projects that use SymPy as a library for implementing a part of their project, or even as a part of back-end for their application as well. Some of them are listed below-:

- **Cadabra:** Cadabra is a symbolic computer algebra system (CAS) designed specifically for the solution of problems encountered in field theory.
- **Octave Symbolic:** The Octave-Forge Symbolic package adds symbolic calculation features to GNU Octave. These include common Computer Algebra System tools such as algebraic operations, calculus, equation solving, Fourier and Laplace transforms, variable precision arithmetic and other features.
- **SymPy.jl:** Provides a Julia interface to SymPy using PyCall.
- **Mathics:** Mathics is a free, general-purpose online CAS featuring Mathematica compatible syntax and functions. It is backed by highly extensible Python code, relying on SymPy for most mathematical tasks.
- **Mathpix:** An iOS App, that uses Artificial Intelligence to detect hand-written math as input, and uses SymPy Gamma, to evaluate the math input and generate the relevant steps to solve the problem.
- **Sage:** A CAS, visioned to be a viable free open source alternative to Magma, Maple, Mathematica and Matlab.
- **SageMathCloud:** SageMathCloud is a web-based cloud computing and course management platform for computational mathematics.
- **PyDy:** Multibody Dynamics with Python.

- **galgebra**: Geometric algebra (previously sympy.galgebra).
- **yt**: Python package for analyzing and visualizing volumetric data (yt.units uses SymPy).
- **SfePy**: Simple finite elements in Python.
- **Quameon**: Quantum Monte Carlo in Python.
- **Lcapy**: Experimental Python package for teaching linear circuit analysis.
- **Quantum Programming in Python**: Quantum 1D Simple Harmonic Oscillator and Quantum Mapping Gate.
- **LaTeX Expression project**: Easy LaTeX typesetting of algebraic expressions in symbolic form with automatic substitution and result computation).
- **Symbolic statistical modeling**: Adding statistical operations to complex physical models.

6 Comparison with other CAS

6.1 Mathematica

Wolfram Mathematica is a popular proprietary CAS. It features highly advanced algorithms. Mathematica has a core implemented in C++ [7] which interprets its own programming language (known as Wolfram language).

Analogously to Lisp's S-expressions, Mathematica uses its own style of M-expressions, which are arrays of either atoms or other M-expression. The first element of the expression identifies the type of the expression and is indexed by zero, whereas the first argument is indexed by one. Notice that SymPy expression arguments are stored in a Python tuple (that is, an immutable array), while the expression type is identified by the type of the object storing the expression.

Mathematica can associate attributes to its atoms.

Unlike SymPy, Mathematica's expressions are mutable, that is one can change parts of the expression tree without the need of creating a new object. The reactivity of Mathematica allows for a lazy updating of any references to that data structure.

Products in Mathematica are determined by some builtin node types, such as **Times**, **Dot**, and others. **Times** is overloaded by the `*` operator, and is always meant to represent a commutative operator. The other notable product is **Dot**, overloaded by the `.` operator. This product represents matrix multiplication, it is not commutative. SymPy uses the same node for both scalar and matrix multiplication, the only exception being with abstract matrix symbols. Unlike Mathematica, SymPy determines commutativity with respect to multiplication

from the factor’s expression type. Mathematica puts the `Orderless` attribute on the expression type.

Regarding associative expressions, SymPy handles associativity by making associative expressions inherit the class `AssocOp`, while Mathematica specifies the `Flat` attribute on the expression type.

7 Conclusion and future work

8 References

References

- [1] Marko Petkovšek, Herbert S Wilf, and Doron Zeilberger. *A= bak peters. Wellesley, MA*, 1996.
- [2] William Wells Adams and Philippe Loustau. *An introduction to Gröbner bases*. Number 3. American Mathematical Soc., 1994.
- [3] Norman Biggs, E Keith Lloyd, and Robin J Wilson. *Graph Theory, 1736-1936*. Oxford University Press, 1976.
- [4] J.L. Lagrange. *Mécanique analytique*. Number v. 1 in Mécanique analytique. Ve Courcier, 1811.
- [5] Thomas R. Kane and David A. Levinson. *Dynamics, Theory and Applications*. McGraw Hill, 1985.
- [6] Dale L. Peterson, Gilbert Gede, and Mont Hubbard. Symbolic linearization of equations of motion of constrained multibody systems. *Multibody System Dynamics*, 33(2):143–161, 2014.
- [7] The software engineering of the wolfram system, 2016.