## The Delay Lines Experiment

Xitian Huang

10432171

School of Physics and Astronomy

University of Manchester

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#### Abstract

The signal through a delay line composed of inductors and capacitors transmits like waves and reflection occurs at the termination. The various parameters such as the voltage in the circuit and the frequency of the input signal at varying terminating impedances were measured to find the time delay  $\alpha$ , attenuation  $\tau$ , cut-off frequency  $\omega_0$ , whose relations are closely connected to the inductor and capacitor in the delay line. Sine signal wave was injected at the input of the line.  $\alpha = 0.98 \pm 0.01$ ,  $\tau = 1.0 \pm 10\% \,\mu s$ ,  $\omega_0 = 2.06 \times 10^6 \pm 3\% \, rad/s$ , are the computed values of the line. Besides, this report investigated the rationale behind the sinusoidal look of the graph of voltage against changing frequency.

#### 1 Introduction

Fundamental to different transmission lines, a lumped-element delay line, which is constituted by more fundamental elements: inductors and capacitors in the circuit, provides more insight into the properties of other similarly structured lines. This includes but not limited to twin-lead cable and coaxial cable, both of which are analogous to the delay line when time delay of the line can be ignored and when the line is infinitely long [1]. In this experiment, the delay line used consists of inductors  $L = 1mH \pm 5\%$  and capacitors  $C = 1nF \pm 1\%$ , as shown in Figure 1. On the left side is the input wave of some frequency. On the right side, the line is terminated by some impedance, the wave is then reflected with an attenuated amplitude and rejoin with the input wave.

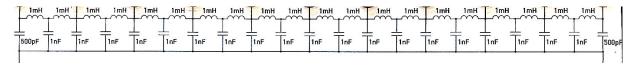


Figure 1: The delay line used in the experiment is composed of inductors and capacitors that are arranged as duplicates of one single unit section. There are 20 sections in this delay line. At two sides of the line, the capacitors are L/2 = 500pF.

## 2 Theory

The cut-off frequency of the line is defined as [2]

$$\omega_0 = 2/\sqrt{LC} \tag{1}$$

The wave can only transmit through the line when the frequency of the wave is below the cut-off frequency. The characteristic impedance of the line is [2]

$$Z_{\pi} = \frac{\sqrt{L/C}}{\sqrt{1 - \omega^2/\omega_0^2}} \simeq \sqrt{L/C} (\omega \ll \omega_0)$$
 (2)

The time delay per section  $\tau$  is [2]

$$\tau = \phi/\omega \approx 2/\omega_0 = \sqrt{LC}(\omega \ll \omega_0) \tag{3}$$

At section n, two waves are travelling in opposite direction, one is from left to right, with voltage and current defined as [3]

$$V_n = Ae^{i(\omega t - n\phi)}, I_n = V_n/Z_{\pi}$$
(4)

whereas the other wave is travelling from right to left with a reflection coefficient r,

$$V_n = r * Ae^{i(\omega t + n\phi)}, I_n = -r * V_n / Z_{\pi}$$

$$\tag{5}$$

Add Eq. 4 and Eq. 5 together, and plug in  $Z_L = V_n/I_n$ , where  $Z_L$  is the terminating impedance(load) connected on the right end of the line,

$$r = \frac{Z_L - Z_\pi}{Z_L + Z_\pi} \tag{6}$$

The inductors and capacitors are not ideal electronics in practice, thus the waves transmitting along will be attenuated with attenuation per section  $\alpha$  [2]

$$\alpha = 1 - \frac{R}{2Z_{\pi}} \tag{7}$$

where R is the resistance of the inductors.  $R \simeq 20\Omega$ .

## 3 Experimental approach & results

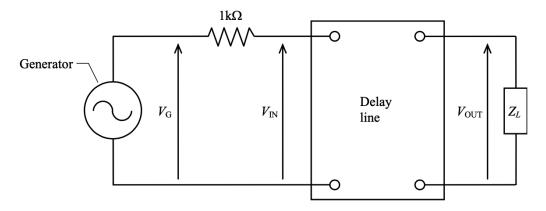


Figure 2: Schematic diagram showing the overall structure of the apparatus, including the function generator,  $1k\Omega$  resistor at the input, a terminating impedance  $Z_L$  at the end, three voltage measuring positions and most importantly, the delay line of Figure 1 connected.

The setup is illustrated in Figure 2. Note that the voltages  $V_G$ ,  $V_{IN}$  and  $V_{OUT}$  were measured with an oscilloscope showing the corresponding peak to peak value from its waveform displayed on the screen. The frequency of the wave from the generator was shown directly on the equipment. Sine wave was injected into the circuit.

#### 3.1

 $V_{IN}$  was measured as a function of frequency f ranging from 1 to 100kHz when  $Z_L = \infty$  (open circuit at  $Z_L$ ),  $Z_L = 0$ (short circuit),  $Z_L = 0.03\mu F$ ,  $Z_L = 0.5k\Omega$ ,  $Z_L = 1k\Omega$  or  $Z_L = 1.5k\Omega$  respectively.

Figures 3 and 4 show the two separate plots of the  $V_{IN}$  against f in different  $Z_L$ .

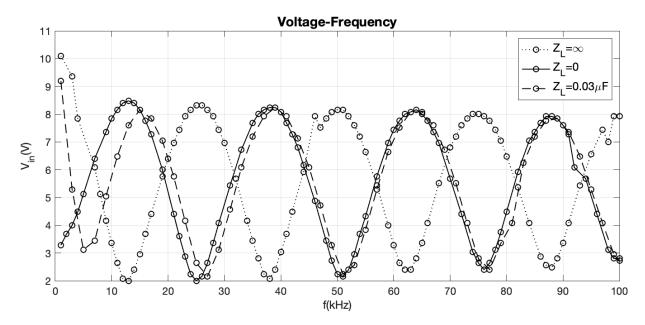


Figure 3: Combined input voltage response to frequency when  $Z_L = \infty$ ,  $Z_L = 0$ ,  $Z_L = 0.03 \mu F$ . The graphs seem to be periodic and look sinusoidal. Further analysis regarding this is in Section 4.

#### 3.2

 $V_{IN}$  and  $V_{OUT}$  were measured as a function of frequency f ranging from 1 to 1MHz when  $Z_{\pi} = Z_{L}$ .

The measurements were used to plot  $V_{OUT}/V_{IN}$  against f in logarithmic scale as shown in Figure 5.

## 4 Analysis

**Periodicity of**  $V_{IN}-f$  **curves** As seen from Figures 3 and 4, the  $V_{IN}-f$  curves are in periodic shape. The periodicity can be deduced by examining the property of the wave transmission. The propagation of waves in the delay lines has interference between the input wave(from the generator) and the reflected wave(reflected by the termination). At max(min) points, the waves are in(exactly out) phase, which constitutes constructive(destructive) interference that results in max(min) voltage at input [2]. As long as there exists the creation of the waves from the generator, one can observe such a periodic behaviour of  $V_{IN}$  over increasing frequency.

**Time delay** To find the time delay, one can take advantage of the extremum points from curves in Figure 3 in which the successive max or min points have a phase difference of the waves exactly at  $\phi = 2\pi$ . Hence, according to Eq. 3,

$$\tau = \Delta \phi / \Delta \omega = 2\pi / 2\pi \Delta f = 1 / \Delta f(\omega \ll \omega_0)$$
 (8)

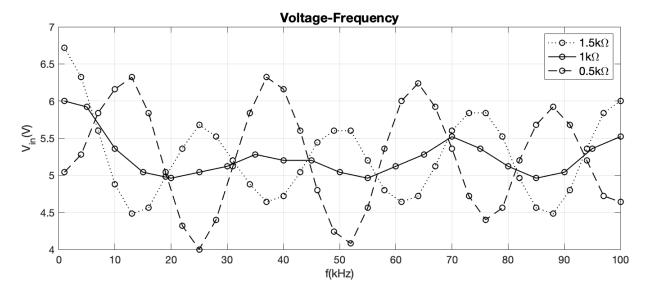


Figure 4: Combined input voltage response to frequency when  $Z_L = 0.5k\Omega$ ,  $Z_L = 1k\Omega$ ,  $Z_L = 1.5k\Omega$ . Same as in Figure 3, the curves look periodic and sinusoidal.

Apparently,  $\Delta f$  represents the frequency difference on consecutive max/min points.

**Attenuation** Finding attenuation factor employs the same logic as in finding  $\tau$ . At peaks, the amplitude of  $V_{IN}$  should be a simple addition of the input and reflected wave. Twice of the amplitude of the input wave is expected. However, with the introduction of the attenuation, amplitudes at the peaks and dips A w.r.t.  $A_0$  (input voltage) are,

$$A = A_0(1 + \alpha^{40}), A = A_0(1 - \alpha^{40}) \tag{9}$$

The appearance of "40" as exponents is due the  $2 \times 20 = 40$  sections through which the reflected wave has transmitted.

Characteristic impedance  $Z_{\pi}$  The reflection coefficient r=0 when  $Z_{\pi}=Z_L$  according to Eq. 6, indicating that no reflection occurs.  $V_{IN}$  would therefore stay constant. From Figure 4, when  $Z_L=1k\Omega$ , it tends to follow this requirement. Based on the other two curves,  $Z_{\pi}=1\pm0.5~k\Omega$ , agreeing with the theoretical ones that  $Z_{\pi}=1k\Omega\pm25\Omega$ . Nevertheless, the  $1k\Omega$  curve still exists some fluctuation probably resulted from the periodic change in  $Z_{\pi}$  over f.

**Cut-off frequency** From Figure 5, a sharp drop in  $log(V_{OUT}/V_{IN})$  indicates the location of cut-off frequency  $f_0$ , as explained in Section 2, beyond  $f_0$ , the wave can no longer propagate in the line.

Computed values of  $\tau$ ,  $\alpha$ ,  $f_0$  By applying the methods and the discussions above, Eqs. 8 and 9 and Figures 3, 4, 5, time delay per section, attenuation per section, cut-off frequency, are found to be  $\alpha = 0.98 \pm 0.01$ ,  $\tau = 1.0 \pm 10\% \,\mu s$ ,  $\omega_0 = 2.06 \times 10^6 \pm 3\% \, rad/s$ . The theoretical values

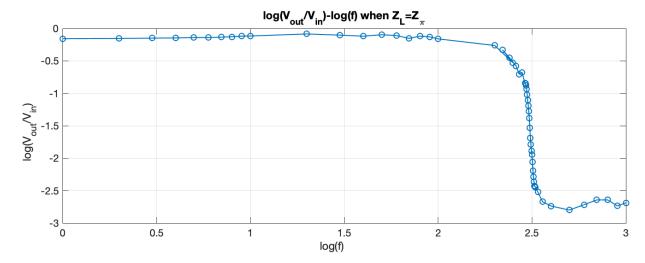


Figure 5: Plot of  $log(V_{OUT}/V_{IN})$  over log(f) The curve has a sharp decrease in the curve around  $log(f) \simeq 2.5$  and is flat elsewhere. More points were recorded near the huge drop around  $log(f) \simeq 2.5$  to make the graph less ambiguous and more practical to use.

of these are obtained from Eqs. 1, 3, 7 as  $\alpha \approx 0.99$ ,  $\tau = 1.0 \pm 2.5\% \,\mu s$ ,  $\omega_0 = 2 \times 10^6 \pm 2.5\% \,rad/s$ . The measured values do agree with the theoretical ones within the uncertainty.

Error Since the computation of these values largely relies on the figures plotted, which were made by repetitive measurements of similar variables, the random error by far is contributed from the locating process of either max/min points or the limiting points of the curves.  $\pm 0.1kHz$  is a reasonable error to f when locating the extremum points. Repetitious measurements were made in successive points to avoid a systematic error.

**Verify the hypothesis** As mentioned before in Section 3, the V-f curves look like sinusoidal curves, however, this is only a postulate which needs proof. The following illustrates a compact picture of this proof. Wave on delay lines can be expressed as [4]

$$a(z,t) = Re[A(0)e^{az}e^{j(\omega t - kz)}] = Re[A(z)e^{j\omega t}]$$
(10)

where  $\omega, k, z, t, i$  are angular frequency, wave number, position and time, imaginary unit.  $e^{-\alpha z}$  represents attenuation.  $\delta = \alpha/k$ .

Define operator P(z) [4],

$$P(z) = e^{-(jk+\alpha)z} \tag{11}$$

This is useful because A(x+d) = P(d)A(x). Using the following identities,

$$a(0) = c + \Gamma_0 b(0), \ b(0) = P(1)b(1)$$

$$a(1) = P(1)a(0), \ b(1) = \Gamma_1 a(1),$$

$$a(x) = P(x)a(0), \ b(x) = P(1-x)b(1) = b(0)P(-x)$$
(12)

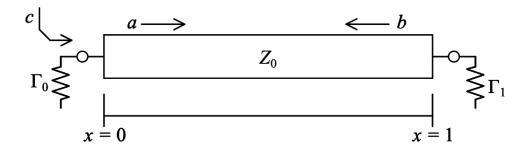


Figure 6: Unit length delay line  $Z_0$ .  $\Gamma_0$ ,  $\Gamma_1$  are reflection coefficients on the ends defined in Eq. 6, a, b, c are the input, output voltage and wave from the generator [4].

The above is obvious by the definition of the operator. The voltage along the line is then V(x) = a(x) + b(x), combines with Eq. 12 [5],

$$V(x) = \frac{P(x-1) + \Gamma_1 P(1-x)}{P(-1) - \Gamma_0 \Gamma_1 P(1)}$$
(13)

To get  $V_{IN}$ , simply let x=0 and  $\Gamma_0=0$ , the latter is because the  $1k\Omega$  resistor placed at the input equal to the characteristic impedance  $Z_{\pi}$ . Hence,

$$V_{IN} = c \frac{P(-1) - P(1)}{P(-1)} = \frac{e^{jk(1-j\delta)} - e^{-jk(1-j\delta)}}{e^{jk(1-j\delta)}}$$
(14)

Let  $\Gamma_1 = -1$  so it represents a short circuit  $Z_L = 0$ . Take the real part,

$$V_{IN} = c[1 - e^{-2\alpha}\cos(2k)] \tag{15}$$

Since wave number k is a function of frequency f, we conclude that  $V_{IN}$  is a sinusoidal function of f. Further analysis shows a high relevance of the data  $V_{IN}$ , f and the fitting function of form  $f(x) = A + B\cos(Kx)$  with  $R^2 = 0.9593$ .

#### 5 Conclusions

The inspection through the wave transmission properties in the lumped delay lines gives an idea of how the frequency of the corresponding wave and the loaded impedance of the line influence the propagation of signals. It provides the implicit verification that the signals transmit through the line with wave-like properties. A deep dive into the principles behind the sinusoidal look of the  $V_{IN} - f$  curves from postulate to actual proof gives a glance at the in-depth theoretical background of this experiment.

### References

[1] B. Bleaney and B. Bleaney, *Electricity and Magnetism*, *Volume 1: Third Edition*. Electricity and Magnetism, Oxford University Press, 2013.

- [2] F. R. Connor, Wave transmission. Introductory topics in electronics and telecommunication, London: Edward Arnold, 1972.
- [3] F. T. Ulaby and U. Ravaioli, Fundamentals of applied electromagnetics. Boston: Pearson, 2015.
- [4] F. R. Rice, "Transmission line resonance due to reflections (1-d cavity resonances)."
- [5] F. R. Rice, "Lumped-parameter delay line."

Reasoning behind the Simusoidal Look of the Vin-f curve in expaniment with sine wave, wowe on delay lines can be expressed as  $\alpha(z,t) = \text{Re}[A(0)e^{-\alpha^2}e^{j(\omega t - \kappa z)}] = \text{Re}[A(z)e^{j(\omega t)}]$ W; angular frequency  $A(z)=A(0)e^{(jk+\alpha)z}$ 6; vave number. Od represents attenuation. to Lines Zo
x=0 To, T, are refuection coefficient on both ends C is the wave from generator. a is input wave voltage also ct Folto der', botton b is cutput wave Voltage USe. aw)=c+Tob(0); ac1)=pc1)a(0) http://www.sophphx.caltech.edu/  $b(0) = \Gamma(a(1))$  b(0) = P(1) b(1)a(x) = p(x)a(x) b(x) = p(1-x)b(x) = b(x)p(-x)Voltage along the line can be deduced as V(x)=a(x)+b(x) =>V(x)=c <u>p(x-1)+T, p(1-x)</u>, to get Vin, Let x=0. p(-1)-ToT, p(1) since the ha

Gince we have 1 kD flegstor place at input and  $Z_{ij} = Z_{ij}$ .

To=D.

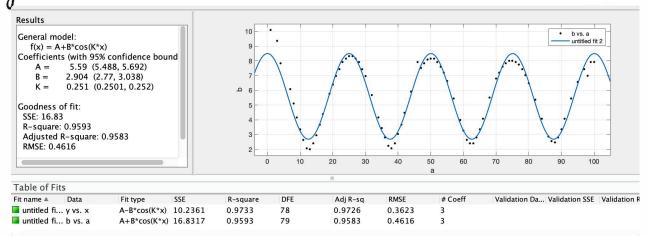
Hence  $V_{in} = C \cdot \frac{P(-1) - P(1)}{P(-1)} = \frac{e^{j \times (1-j\delta)}}{e^{j \times (1-j\delta)}} = \frac{e^{j \times (1-j\delta)}}{e^{j \times (1-j\delta)}}$ Let  $V_{ij} = -1$ , represents short circuit,  $Z_{ij} = 0$ .

Take the Real part using Nethematica,

we found  $V_{in} = e^{i \times (1-j\delta)} = e^{i \times (1-j\delta)}$ As  $KO = \alpha$ . K (is a function of frequency.

We conclude that  $V_{in} = i \times a$  sinusodial curve.  $V_{in} = C \cdot [1 + e^{-2KO} \cos(2K)]$  when  $\Gamma_{ij} = 1$ .

Fitting with our data, we found It had a high relation.



# computation as shown below.