

Tutorial Week 4: Hierarchical Planning

Guidelines

- You can discuss the content of the questions with your classmates.
- However, everyone should work on and be ready to present ALL the solutions.
- Your attendance is marked in the tutorial and participation noted to award class participation marks.

Package delivery

You have a number of trucks with which to deliver a set of packages. Each package starts at some location on a grid map, and has a destination somewhere else. Each truck is directly controlled by moving forward and turning. The package can be loaded to the truck and unloaded from the truck.

1) *Forward* action:

If you model the *Forward* action as a primitive action, what would be the precondition and effect? Assume that addition is defined and available as an operator. State any assumptions you make in the modeling.

- 2) What other primitive actions are needed define the planning problem? (no need to write the PDDL definition)
- 3) Construct a hierarchy of high-level actions for this problem.
- 4) What knowledge about the solution does your hierarchy encode?
- 5) What are some shortcomings (in terms of real-life implementation) of the hierarchy defined above?

Air cargo problem

Consider the air-cargo problem that we have seen in the lecture.

$Init(At(C_1, SFO) \wedge At(C_2, JFK) \wedge At(P_1, SFO) \wedge At(P_2, JFK)$
 $\wedge Cargo(C_1) \wedge Cargo(C_2) \wedge Plane(P_1) \wedge Plane(P_2)$
 $\wedge Airport(JFK) \wedge Airport(SFO))$
 $Goal(At(C_1, JFK) \wedge At(C_2, SFO))$
 $Action(Load(c, p, a),$
 $\quad PRECOND: At(c, a) \wedge At(p, a) \wedge Cargo(c) \wedge Plane(p) \wedge Airport(a)$
 $\quad EFFECT: \neg At(c, a) \wedge In(c, p))$
 $Action(Unload(c, p, a),$
 $\quad PRECOND: In(c, p) \wedge At(p, a) \wedge Cargo(c) \wedge Plane(p) \wedge Airport(a)$
 $\quad EFFECT: At(c, a) \wedge \neg In(c, p))$
 $Action(Fly(p, from, to),$
 $\quad PRECOND: At(p, from) \wedge Plane(p) \wedge Airport(from) \wedge Airport(to)$
 $\quad EFFECT: \neg At(p, from) \wedge At(p, to))$

- 1) Write the successor state axiom for the fluent $At(P_1, SFO)$.
- 2) Describe how you will modify the problem so that each plane can carry only one cargo.