

ZHAOZHAN YAO

<https://iszyao.github.io>

Google Scholar profile

iszyao@163.com

+86 155 2128 4904

EDUCATION

with the School of Automation, Guangdong University of Technology

M.Sc.in Control Science and Engineering

B.Eng. in Automation, GPA: 4.0/5.0 (rank 1st in the major)

supervised by Prof. Yong Xu

Sept 2020 to present

Sept 2016 to Jun 2020

RESEARCH INTERESTS

Multiagent systems; Consensus/Synchronization; Formation and attitude synchronization; Social networks.

PUBLICATIONS

1. Yong Xu, **Zhaozhan Yao**, Renquan Lu, Bijoy K. Ghosh, A novel fixed-time protocol for first-order consensus tracking with disturbance rejection, *IEEE Trans. Autom. Control*, doi:10.1109/TAC.2021.3131549.
2. **Zhaozhan Yao**, Ye Kuang, Chang Liu, Yuru Guo, Hongxia Rao, A discontinuous finite-time consensus tracking algorithm for single integrator multi-agent system with external disturbance, *Proc. Chin. Control Conf.*, 657-661, 2021.

RECENT RESEARCH

First-order predefined-time consensus under digraphs

Zhaozhan Yao, Yong Xu, Chang Liu, Renquan Lu, Bijoy K. Ghosh

Automatica

under review

- This paper considers a group of scalar agents subject to nonlinear dynamics and bounded disturbances under strongly connected graphs, and describes two novel controllers to achieve consensus within an arbitrarily prespecified time.
- **A shortcoming of existing controller designs:** Most existing papers design controllers using some eigenvalue information of the Laplacian or its variants associated with the communication topology, which, however, is global information since each agent has to own the knowledge of the communication topology as to compute the eigenvalue.
- **An unorthodox controller design:** In the proposed controller, the magnitude of control inputs is designed via the self-states of the agents, instead of the relative states of the agents w.r.t. their neighbors. This unorthodox practice, together with a matching Lyapunov function, removes the use of any eigenvalue information of the Laplacian or its variants in the consensus analysis, following a favored result that the control gains do not depend on any eigenvalue information and agents achieve consensus in a fully distributed manner.

Finite-time multiconsensus with disturbance rejection in signed digraphs

Zhaozhan Yao, Yong Xu, Zijiang Xiao, Hui Peng, Peng Shi

IEEE Trans. Autom. Control

under review

- This paper considers a group of scalar agents with bounded disturbances, and describes a discontinuous controller to achieve multiconsensus with disturbance rejection within a finite time.
- **A new multiconsensus scheme:** Agents won't achieve consensus when the underlying communication topology is weakly connected and, therefore, are partitioned into multiple cells. So, multiconsensus arises. Most recent papers study multiconsensus using external equivalent partitions that require all agents inside a cell to have the same indegree w.r.t. another one. However, this paper classifies the cells into independent ones and dependent ones, and finds that only a portion of agents inside each dependent cell obeys the external equivalence rule is already sufficient to guarantee multiconsensusability.
- **Easy-to-tune control gains:** An aesthetically pleasing tuning condition is derived and presents that the minimum control gain has to be twice as large as the upper bound of disturbances as to guarantee disturbance rejection. Also, the control gains do not depend on any eigenvalue information.

A novel fixed-time protocol for first-order consensus tracking with disturbance rejection

Yong Xu, **Zhaozhan Yao**, Renquan Lu, Bijoy K. Ghosh

IEEE Trans. Autom. Control

- **This paper overcomes such a problem:** Given a group of scalar followers with bounded disturbances, a scalar leader without disturbances, and a directed communication topology, how to achieve consensus tracking within a fixed time, in the presence of a moving leader with bounded control input, instead of a static leader.

AWARDS AND HONORS

- First Class Graduate Scholarship, awarded to the top 20% graduates of the school
- **National Scholarship**, awarded to the top undergraduate in the major
- Second Prize at China Undergraduate Mathematical Contest in Modeling
- honored Top Ten Undergraduate Graduates of the school

PROFESSIONAL SERVICE

- **Technical Manuscript Reviewer:** *Automatica* and *Neurocomputing*.

SKILLS

- **Programming:** Matlab: good; Python: familiar.