

For a symmetric matrix S

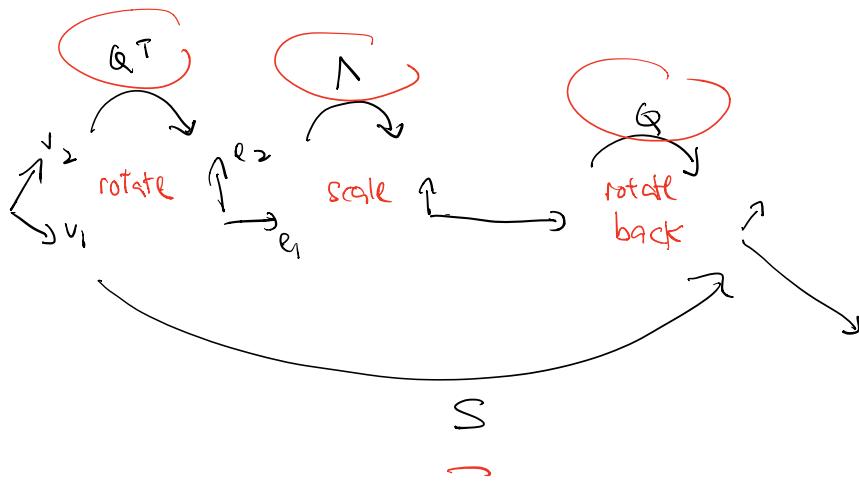
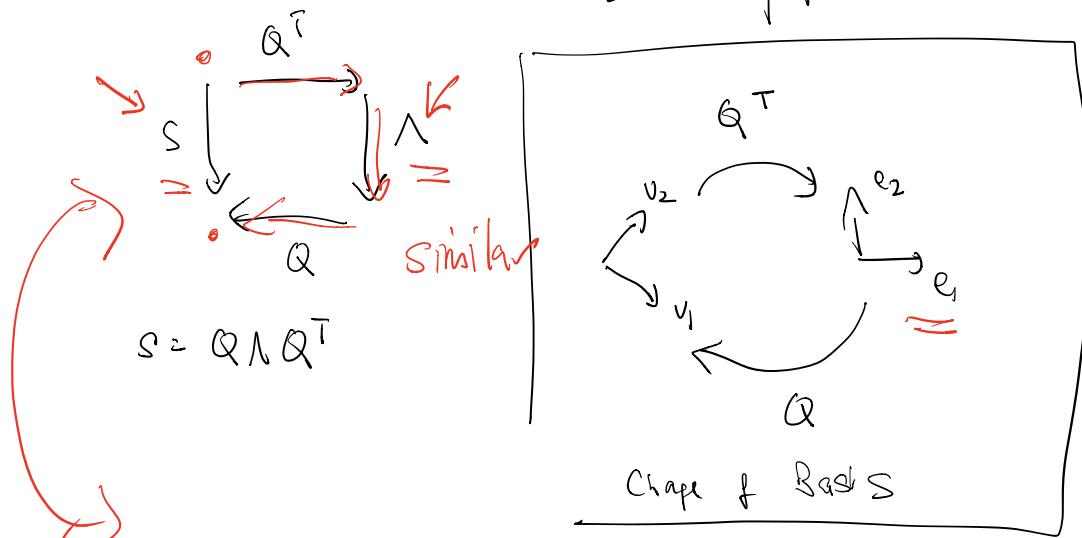
$$S = Q \Lambda Q^T$$

Q orthogonal

Λ diagonal

$$\Lambda = \begin{bmatrix} \lambda_1 & & 0 \\ 0 & \ddots & \\ & & \lambda_r \end{bmatrix} \rightarrow \text{eigenvalues}$$

$$Q = \begin{bmatrix} v_1 & \dots & v_r \end{bmatrix} \quad V \text{ eigenvectors}$$



$S \rightarrow$ symmetric ||
square

SVD works for ANY matrix A

$$A = U \Sigma V^T$$

U : $m \times m$ rectangular

Σ : $m \times n$

V^T : $n \times n$

U, V orthogonal

Σ is "diagonal"

LU, Cholesky

QR Orthogonal

QNQT spectral

$U \Sigma V^T$ SVD

$$\Sigma \approx \begin{bmatrix} \sigma_1 & & & \\ & \ddots & & \\ & & \sigma_r & \\ & & & 0 \end{bmatrix}$$

$\sigma_i > 0$

$\sigma_1 \geq \sigma_2 \geq \dots$

$\sigma_1, \sigma_2, \dots, \sigma_r$ are ordered $\sigma_1 \geq \sigma_2 \dots$

$$\frac{\sigma_1}{\sigma_r} = \boxed{\frac{\sigma_{\max}}{\sigma_{\min}}} = \boxed{\text{Condition number}}$$

σ_i 's are singular values

Can also write

$$A_{m \times n} = U_{m \times r} \Sigma_{n \times r} V^T_{r \times n}$$

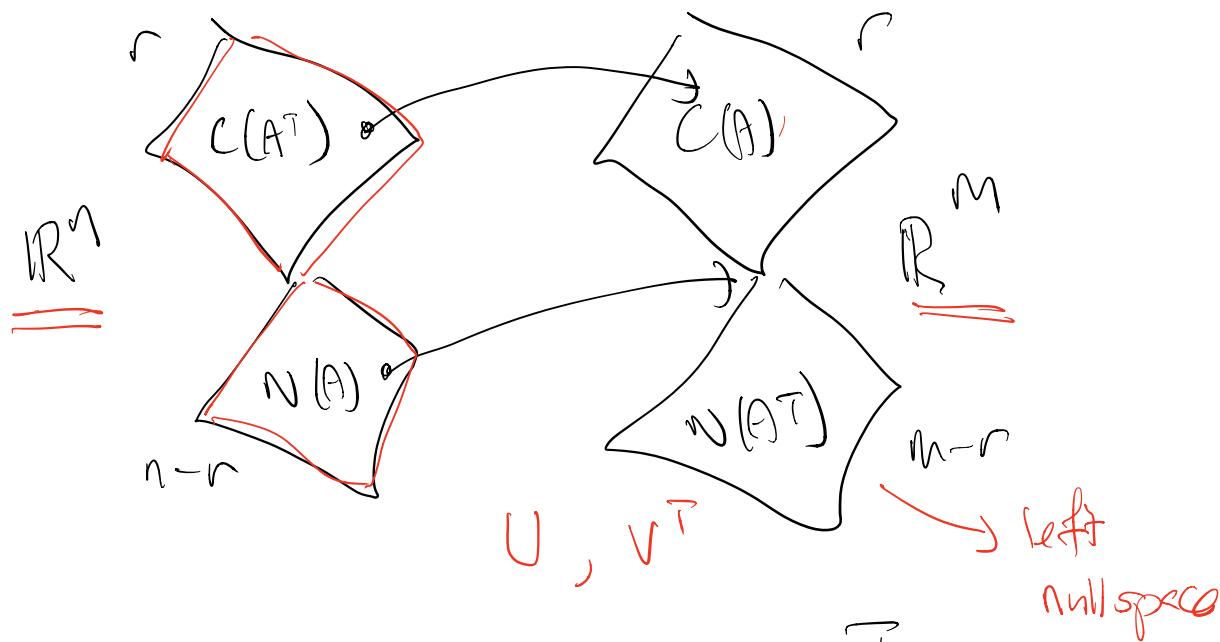
U eigenvalues of $A^T A$ } Symmetric
 V eigenvalues of $A A^T$

$A^T A$ & $A A^T$ have same set of
r eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_r$

where

$$\lambda_i = \sigma_i^2$$

↓
eigenvalue of
 $A^T A$ & $A A^T$



$$A \underset{m \times n}{=} \underset{m \times m}{U} \underset{m \times n}{\sum} \underset{n \times n}{V^T}$$

- $\{u_1, \dots, u_r\}$ Basis for $C(A)$
 $\underset{R^m}{}$ $\underset{R^n}{}$
- $\{u_{r+1}, \dots, u_m\}$ Basis for $N(A^T)$
 $\underset{R^n}{}$
- $\{v_1, \dots, v_r\}$ Basis for $C(A^T)$
 $\underset{R^n}{}$
- $\{v_{r+1}, \dots, v_n\}$ Basis for $N(A)$

$$A = U\Sigma V^T$$

$$\Rightarrow \boxed{AV = U\Sigma}$$

$$\Rightarrow Av_i = \sigma_i \underline{v_i}$$

$$\begin{aligned} \underbrace{AA^T}_\text{symmetric} &= U\Sigma V^T (U\Sigma V^T)^T \\ &= U\Sigma V^T V\Sigma^T U^T \\ &= \boxed{U\Sigma\Sigma^T V^T} \end{aligned} \quad \left. \begin{array}{l} \{ \\ \{ \\ \{ \end{array} \right. \begin{array}{l} U \text{ is} \\ \text{eigenvec} \\ \text{matr. for} \\ AA^T \end{array}$$

$$\begin{aligned} A^TA &= (U\Sigma V^T)^T U\Sigma V^T \\ &= V\Sigma^T U^T U\Sigma V^T \\ &= \boxed{V\Sigma^T\Sigma V^T} \end{aligned} \quad \left. \begin{array}{l} \{ \\ \{ \\ \{ \end{array} \right. \begin{array}{l} V \text{ is} \\ \text{eigenvec} \\ \text{matr. for} \\ A^TA \end{array}$$

Also AA^T & A^TA have same r eigenvalues

$$\lambda_i = \sigma_i^2$$

$$\boxed{\quad}$$

$$\boxed{A^TA, AA^T}$$

low rank version

$$A = U \Sigma V^T$$
$$= \sum \sigma_i u_i v_i^T$$

u_i is $m \times 1$
 v_i^T is $1 \times n$

$$m \times n \quad m \times n \quad \underline{\underline{u_i v_i^T}}$$

$u_i v_i^T$ is $m \times 1$

So A is a sum of rank 1 matrices $u_i v_i^T$

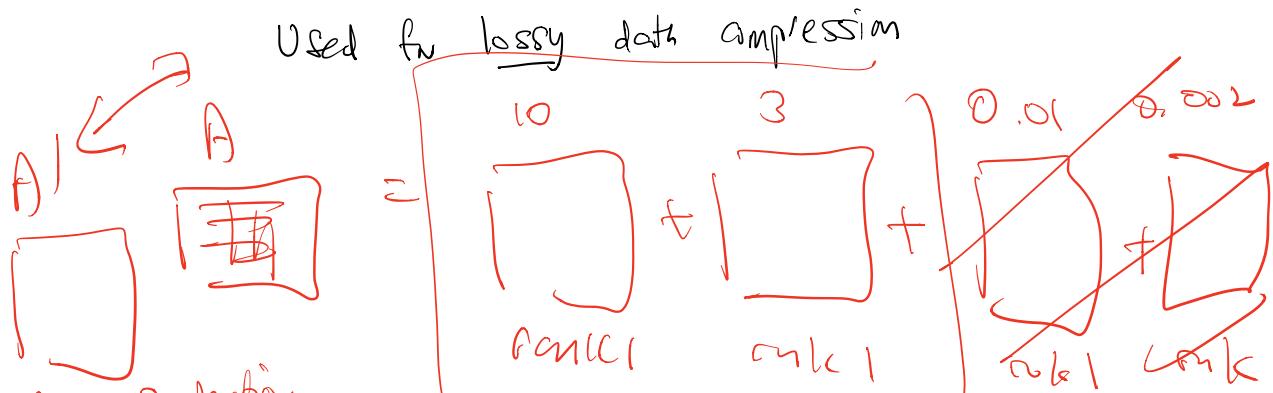
whose contribution to A is weighted by σ_i

⇒ we can drop rank 1 matrices where $\sigma_i \ll 1$

Suppose A is $1000 \times 1000 = 10^6$ values

Suppose only 100 σ_i 's are non-negligible

Store 100 σ_i — 100 values
100 u_i — 10⁹ values
100 v_i — 10⁹ values } 200,100 values



rank-2 matrix

$$\Sigma = \begin{bmatrix} \sigma_1 & & & & \\ & \sigma_2 & & & \\ & & \ddots & & \\ & & & \sigma_r & \\ & & & & 0 \end{bmatrix}$$

$$\Sigma^+ = \begin{bmatrix} \frac{1}{\sigma_1} & & & & \\ & \frac{1}{\sigma_2} & & & \\ & & \ddots & & \\ & & & \frac{1}{\sigma_r} & \\ & & & & 0 \end{bmatrix}$$

Σ^+ = Take reciprocals
of non-zero values of
 Σ

Note $(\Sigma^+)^+ = \Sigma$ even though Σ is NOT invertible.

Pseudoinverse

$$A^{-1} = V \Sigma^{-1} U^T$$

$$A = U \Sigma V^T$$

if A square

$$A^+ = V \Sigma^+ U^T$$

General solution $Ax = b$ $\hat{x} = (A^T A)^+ A^T b$

$$Ax^+ = b$$

CN ↑.

$$x^+ = A^+ b = V \Sigma^+ U^T b$$

Works even if A has dependent columns \Rightarrow normal equations fail
because $A^T A$ is not invertible.

→ shortest least squares solution

$$A = \underbrace{U}_{m \times r} \underbrace{\sum}_{r \times r} \underbrace{V^T}_{r \times 1}$$

Basis
factorisation

$$V^T V = I$$

$$A = \underbrace{\left(\underbrace{U}_{m \times r} \underbrace{\begin{pmatrix} V^T \\ r \times n \end{pmatrix}}_{\text{---}} \right)}_{\text{---}} \underbrace{\left(\underbrace{V}_{n \times r} \underbrace{\begin{pmatrix} \sum_{r \times r} & V^T \\ r \times n & \text{---} \end{pmatrix}}_{\text{---}} \right)}_{\text{---}}$$

$$= Q \quad \begin{matrix} \text{rotation} \\ \swarrow \end{matrix} \quad S \quad \begin{matrix} \text{scaling} \\ \rightarrow \end{matrix} \quad A = LQ$$

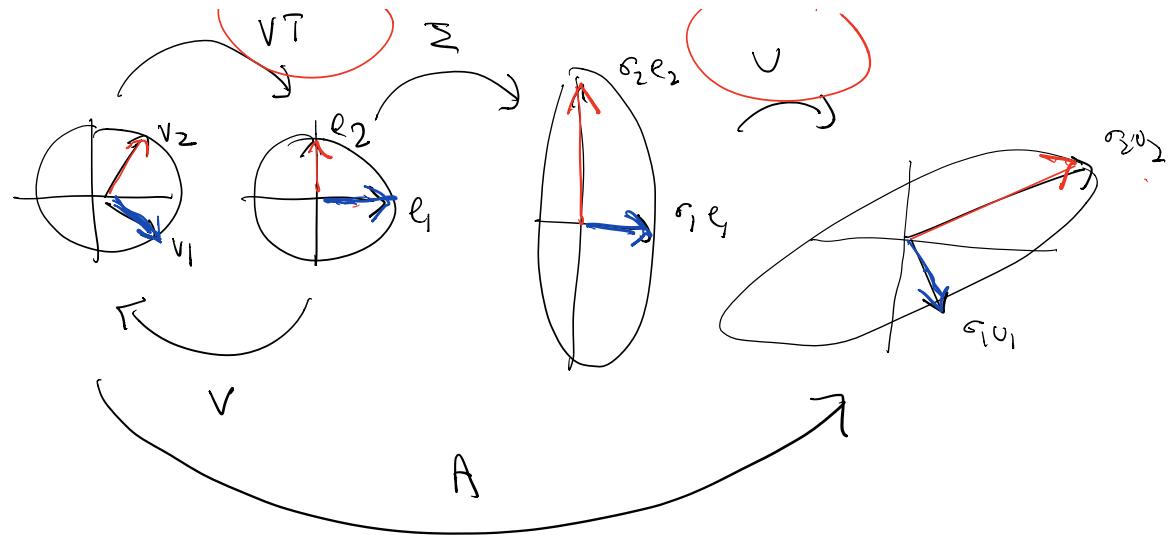
$$A = QR$$



$$Q^T Q = (UV^T)^T (UV) \quad Q Q^T = (UV^T)(UV^T)^T$$

$$= V U^T U V^T \quad = U V^T V U^T$$

$$= I \quad = I$$



$$\begin{array}{ccc}
 & V^T & \\
 \xrightarrow{\quad} & & \xrightarrow{\quad} \\
 A & \downarrow & \downarrow \Sigma \\
 & U &
 \end{array}
 \quad
 \begin{aligned}
 A &= U \Sigma V^T \\
 A v &= U \Sigma
 \end{aligned}$$

PCA Let X be a matrix of features with mean ≈ 0 (centered)

Then $C = \frac{1}{n-1} \underline{\underline{XX^T}} = C$

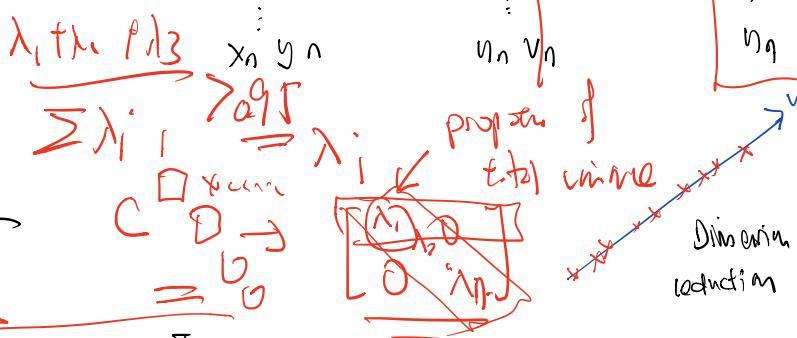
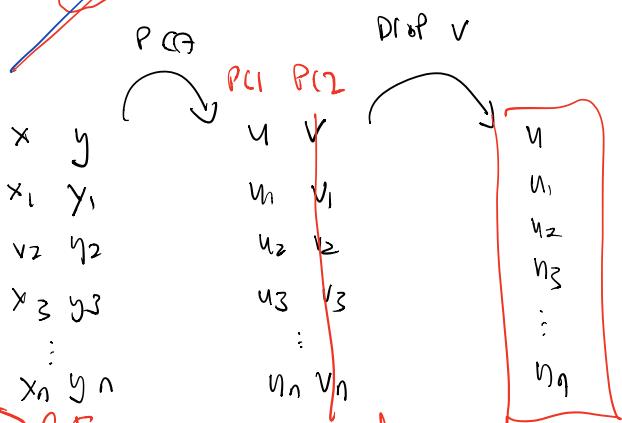
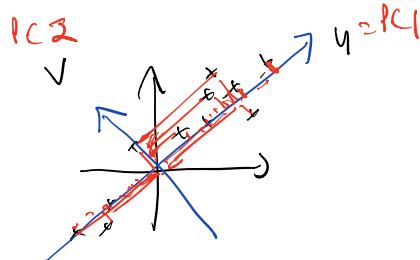
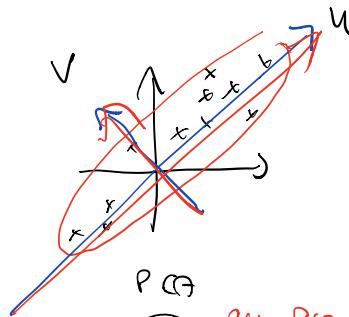
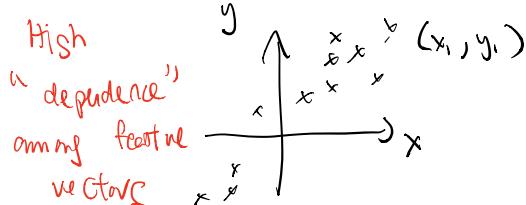


Symmetric positive definite

$C = Q \Lambda Q^T$

$C = Q \Lambda Q^T$

Note how SVD & PCA
are related
SVD stats $\in X$



$$\frac{1}{n-1} \underline{\underline{XX^T}} = \underbrace{U \Sigma V^T}_{= U \Sigma \Sigma^T V^T} V \Sigma^T U^T$$

Trace

Explained variance

$$= 95\%$$

$$\lambda_i = \frac{\sigma_i^2}{n-1}$$

Principal component eigenvalues are given by $\frac{\sum \lambda_i}{n-1}$

Principal component vectors are given by U

Summary (Highlights of underproduct linear algebra in 3 weeks)

① Vectors 3 vector spaces, norms

② Matrix * vector \rightarrow linear combination

③ Linear combinations

$$\begin{bmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

④ Linear independence

Fundamental subspaces

⑤ Rank, span, basis

$$\begin{array}{c} \xrightarrow{\quad} \\ \xrightarrow{\quad} \end{array} \begin{array}{c} \text{LU} \\ \text{LDU} \end{array}$$

⑥ Gaussian elimination

$$\begin{array}{c} \xrightarrow{\quad} \\ \xrightarrow{\quad} \end{array} \begin{array}{c} \text{LDLT} \\ \text{CC}^T \text{ (Cholesky)} \end{array}$$

⑦ Orthogonalization

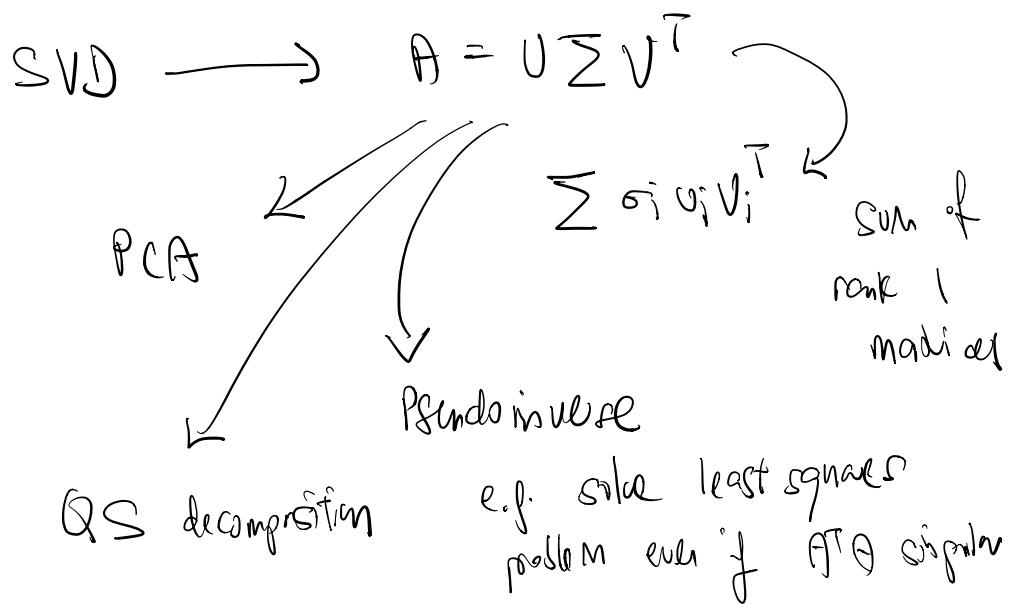
$$\begin{array}{c} \xrightarrow{\quad} \\ \xrightarrow{\quad} \end{array} \begin{array}{c} \text{QR} \\ \text{LD}^T \text{ D}^{\frac{1}{2}} \text{ L}^T \end{array}$$

$$\begin{array}{c} \xrightarrow{\quad} \\ \xrightarrow{\quad} \end{array} \begin{array}{c} \text{Gram Schmidt} \\ \{u_1, u_2, \dots, u_n\} \\ \{v_1, v_2, \dots, v_n\} \end{array}$$

⑧ Change of basis \longrightarrow $\underline{S = Q \Lambda Q^T}$

$$\begin{array}{c} \xrightarrow{\quad} \\ \xrightarrow{\quad} \end{array} \begin{array}{c} \text{eigenvectors} \\ \text{basis} \end{array} \quad \begin{array}{c} \xrightarrow{\quad} \\ \xrightarrow{\quad} \end{array} \begin{array}{c} \text{eigenvalues} \end{array}$$

⑨



⑩ Now for some Python examples.