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1  #include <iostream>
2  #include "QSolver.h"
3  #include "SU2_CFD.hpp"
4
5  QCircuit amplitude_encode(qvec q, vector<double> data)
6  {
7      if (data.size() > (1 << q.size()))
8      {
9          throw exception("error");
10     }
11     while(data.size() < (1 << q.size()))
12     {
13         data.push_back(0);
14     }
15     QCircuit qcir;
16     double sum_0 = 0;
17     double sum_1 = 0;
18     size_t high_bit = (size_t)log2(data.size())-1;
19     if (high_bit == 0)
20     {
21         if ((data[0] + data[1]) > 1e-20)
22         {
23             qcir << RY(q[0], 2 * acos(data[0] / sqrt(data[0] * data[0] + data[1] *
24                 data[1])));
25         }
26     }
27     else
28     {
29         for (auto i = 0; i < (data.size() >> 1); i++)
30         {
31             sum_0 += data[i] * data[i];
32             sum_1 += data[i + (data.size() >> 1)] * data[i + (data.size() >> 1)];
33         }
34         if (sum_0+sum_1 > 1e-20)
35             qcir << RY(q[high_bit], 2 * acos(sqrt(sum_0 / (sum_0+sum_1))));
36         else
37         {
38             throw exception("error");
39         }
40         if (sum_0 > 1e-20)
41         {
42             qvec temp({ q[high_bit] });
43             vector<double> vtemp(data.begin(), data.begin() + (data.size() >> 1));
44             qcir <<X(q[high_bit])<< amplitude_encode(q - temp, vtemp).control({ q
45                 [high_bit] }) << X(q[high_bit]);
46         }
47         if (sum_1 > 1e-20)
48         {
49             qvec temp({ q[high_bit] });
50             vector<double> vtemp(data.begin() + (data.size() >> 1), data.end());
51             qcir << amplitude_encode(q - temp, vtemp).control({ q[high_bit] });

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52     }
53     return qcir;
54 }
55
56 QCircuit init_superposition_state(qvec q, size_t d)
57 {
58     QCircuit qcir;
59
60
61     size_t highest_bit = (size_t)log2(d-1);
62
63     if (d == (1 << (int)log2(d)))
64     {
65         for (auto i = 0; i < (int)log2(d); i++)
66         {
67             qcir << H(q[i]);
68         }
69     }
70     else if (d == 3)
71     {
72         qcir << RY(q[1], 2 * acos(sqrt(2.0 / 3))) << X(q[1]);
73         qcir << H(q[0]).control({ q[1] }) << X(q[1]);
74     }
75     else
76     {
77         qcir << RY(q[highest_bit], 2 * acos(sqrt((1 << highest_bit)*1.0 / d)));
78         QCircuit qcir1;
79         for (auto i = 0; i < highest_bit; i++)
80         {
81             qcir1 << H(q[i]);
82         }
83         qcir << X(q[highest_bit]) << qcir1.control({ q[highest_bit] }) << X(q
84             [highest_bit]);
85
86         size_t d1 = d - (1 << highest_bit);
87         if(d1 > 1)
88         {
89             QCircuit qcir2 = init_superposition_state(q, d1);
90             qcir2.setControl({ q[highest_bit] });
91             qcir << qcir2;
92         }
93     }
94     return qcir;
95 }
96
97 QSolver::QSolver(string cfg_file) :
98     m_cfg_file(cfg_file),
99     m_Cheby_times(64),
100     m_const_coef(100)
101 {
102     //coefficient of Chebyshev polynomial
103     m_alpha = { 1.949549963644177, -1.8488512882814025, 1.7487543978311608,
104         -1.6496525062919445,

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103      1.5519270299129846, -1.455943195687338, 1.3620459665535882,
      -1.2705563586796345,
104      1.1817682156051097, -1.095945491847383, 1.0133200852492674,
      -0.9340902433058914,
105      0.8584195544185835, -0.7864365209351393, 0.718234697381761,
      -0.653873364863425,
106      0.5933787015467717, -0.5367453997184383, 0.48393867233793647,
      -0.43489658640845813,
107      0.38953265692367894, -0.3477386335979911, 0.3093874129600493,
      -0.274336010541416,
108      0.2424285316221708, -0.21349908406872772, 0.18737458295107148,
      -0.1638774035777065,
109      0.14282784705571605, -0.12404639019677266, 0.10735569929006719,
      -0.09258239472103647,
110      0.07955856042991463, -0.06812299861332467, 0.05812223575125098,
      -0.049411290903158406,
111      0.04185422121218744, -0.03532446267101167, 0.02970498645435139,
      -0.024888292554356185,
112      0.020776263132320862, -0.01727989800452769, 0.014318954104793266,
      -0.01182150971054103,
113      0.009723472783751415, -0.007968051061520803, 0.00650519962632839,
      -0.005291059678290213,
114      0.004287400195696609, -0.003461072169953997, 0.0027834831888454113,
      -0.002230098358538782,
115      0.0017799719295396406, -0.0014153125440208496, 0.0011210837618425746,
      -0.0008846404522002947,
116      0.0006954007529361845, -0.0005445525905065386, 0.00042479320707228724,
      -0.00033009974110103914,
117      0.0002555286366486786, -0.00019704149590170955, 0.00015135492154600306,
      -0.00011581190277550591 };
118
119     for (auto i = 0; i < m_alpha.size(); i++)
120     {
121         m_alpha[i] = sqrt(abs(m_alpha[i]));
122     }
123 }
124
125 void QSolver::run()
126 {
127     init();
128
129     auto qm = initQuantumMachine(CPU_SINGLE_THREAD_WITH_ORACLE);
130     Configuration config = { 10000, 10000 };
131     qm->setConfig(config);
132     ModuleContext::setContext(qm);
133     size_t qnum = ceil(log2(m_solution.size()));
134     size_t qtum = ceil(log2(m_Cheby_times));
135     qvec qi(qnum);
136     qvec qi_anc(1);
137     qvec qj(qnum);
138     qvec qj_anc(1);
139     qvec qt(qtum);
140     qvec qlist = qi + qi_anc + qj + qj_anc + qt;

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141     QProg prog;
142
143     prog << one_iteration_qcir(qt, qi, qi_anc, qj, qj_anc);
144
145     string s = transformQProgToOriginIR(prog, qm);
146     cout << s << endl;
147     ofstream outfile;
148     outfile.open("QuantumLinearSolver.txt", ios_base::out | ios_base::trunc);
149     if (!outfile.fail())
150     {
151         outfile << s;
152         outfile.close();
153     }
154
155     qm->directlyRun(prog);
156     auto target_state = qm->getQState();
157
158     auto tmp_coef = getSquareRoot(m_solution);
159     for (auto i = 0; i < m_solution.size(); i++)
160     {
161         m_solution[i] += tmp_coef * target_state[i].real();
162     }
163 }
164
165 void QSolver::init()
166 {
167     char config_file_name[MAX_STRING_SIZE];
168     strcpy(config_file_name, m_cfg_file.c_str());
169
170     CFluidDriver* driver = new CFluidDriver(config_file_name, 1, 2, false, 0,
171                                             m_solution);
172
173     driver->GetSparseMatrixAndResidual(m_sparse_matrix, m_none_zero_block,
174                                     m_residual);
175
176     delete driver;
177     driver = nullptr;
178
179     m_all_index_map = mapAllIndex(m_none_zero_block);
180     m_sparse_coef = m_none_zero_block[0].size();
181     for (size_t i = 1; i < m_none_zero_block.size(); i++)
182     {
183         if (m_sparse_coef < m_none_zero_block[i].size())
184         {
185             m_sparse_coef = m_none_zero_block[i].size();
186         }
187     }
188     m_sparse_coef = m_sparse_coef * 4;
189 }
190
191 QCircuit QSolver::T_circuit_subspace(qvec qi, qvec qj, qvec qj_anc)
192 {
193     QCircuit qcir;
194     size_t qtemp = (size_t)log(m_sparse_coef) + 1;

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192     qcir << init_superposition_state(qj, m_sparse_coef);
193     string OLname = "OL_" + to_string(2 * qi.get().size());
194     auto OL_oracle = oracle((qi + qj).get(), OLname, m_all_index_map);
195     qcir << OL_oracle;
196     string OMname = "OM_" + to_string(2 * qi.get().size() + 1);
197     auto OM_oracle = oracle((qi + qj + qj_anc).get(), OMname, m_sparse_matrix,
198                             m_none_zero_block);
199     qcir << OM_oracle;
200     return qcir;
201 }
202 QCircuit QSolver::T_circuit(qvec qi, qvec qi_anc, qvec qj, qvec qj_anc)
203 {
204     QCircuit qcir;
205     qcir << X(qi_anc[0]);
206     QCircuit qcirl = T_circuit_subspace(qi, qj, qj_anc);
207     qcirl.setControl({ qi_anc[0] });
208     qcir << qcirl;
209     qcir << X(qi_anc[0]);
210     qcir << X(qj_anc[0]).control({ qi_anc[0] });
211     return qcir;
212 }
213
214 QCircuit QSolver::W_circuit(qvec qi, qvec qi_anc, qvec qj, qvec qj_anc)
215 {
216     QCircuit qcir;
217     qcir << T_circuit(qi, qi_anc, qj, qj_anc).dagger();
218     for (auto i = 0; i < qj.size(); i++)
219     {
220         qcir << X(qj[i]);
221     }
222     qcir << X(qj_anc[0]);
223     qcir << Z(qj_anc[0]).control(qj.get());
224     for (auto i = 0; i < qj.size(); i++)
225     {
226         qcir << X(qj[i]);
227     }
228     qcir << X(qj_anc[0]);
229     qcir << Z(qj_anc[0]) << X(qj_anc[0]) << Z(qj_anc[0]) << X(qj_anc[0]);
230
231     qcir << T_circuit(qi, qi_anc, qj, qj_anc);
232
233     qcir << CNOT(qi_anc[0], qj_anc[0]) << CNOT(qj_anc[0], qi_anc[0]) << CNOT(qi_anc
234         [0], qj_anc[0]);
235     for (auto i = 0; i < qi.size(); i++)
236     {
237         qcir << CNOT(qi[i], qj[i]) << CNOT(qj[i], qi[i]) << CNOT(qi[i], qj[i]);
238     }
239     return qcir;
240 }
241 QCircuit QSolver::Chebyshev(size_t n, qvec qi, qvec qi_anc, qvec qj, qvec qj_anc)
242 {

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243     QCircuit qcir;
244     for (auto i = 0; i < n; i++)
245     {
246         qcir << W_circuit(qi, qi_anc, qj, qj_anc);
247     }
248     return qcir;
249 }
250
251 QCircuit QSolver::Chebyshev_minus(size_t n, qvec qi, qvec qi_anc, qvec qj, qvec qj_anc)
252 {
253     QCircuit qcir;
254     qcir << Z(qi.get()[0]) << X(qi.get()[0]) << Z(qi.get()[0]) << X(qi.get()[0]);
255     for (auto i = 0; i < n; i++)
256     {
257         qcir << W_circuit(qi, qi_anc, qj, qj_anc);
258     }
259     return qcir;
260 }
261
262 QCircuit QSolver::one_iteration_qcir(qvec qt, qvec qi, qvec qi_anc, qvec qj, qvec qj_anc)
263 {
264     QCircuit qcir;
265     //init |b>
266     qcir << amplitude_encode(qi, m_residual);
267     //init alpha
268     qcir << amplitude_encode(qt, m_alpha);
269     qcir << T_circuit(qi, qi_anc, qj, qj_anc);
270     //controlled W^n
271     QCircuit temp= Chebyshev_minus((1 << 1), qi, qi_anc, qj, qj_anc);
272     temp.setControl({ qt[0] });
273     qcir << temp;
274     for (auto i = 1; i < qt.size(); i++)
275     {
276         QCircuit qcirtemp = Chebyshev((1 << (i+1)), qi, qi_anc, qj, qj_anc);
277         qcirtemp.setControl({ qt[i] });
278         qcir << qcirtemp;
279     }
280
281     string Trname = "truncation_" + to_string((qj + qi_anc + qj_anc+qt).get().size());
282     auto trun_oracle = oracle((qj + qi_anc + qj_anc+qt).get(), Trname);
283
284     QCircuit templ = Chebyshev(1, qi, qi_anc, qj, qj_anc);
285     qcir << templ;
286     qcir << T_circuit(qi, qi_anc, qj, qj_anc).dagger();
287     qcir << amplitude_encode(qt, m_alpha).dagger();
288     qcir << trun_oracle;
289     return qcir;
290 }
291
292 vector<vector<size_t>> QSolver::mapAllIndex(const vector<vector<size_t>>& data)

```

```
293 {
294     vector<vector<size_t>> post_data;
295     for (auto i = 0; i < 4*data.size(); i++)
296     {
297         auto row = i / 4;
298         vector<size_t> vtemp;
299         for (auto j = 0; j < 4*data[row].size(); j++)
300         {
301             vtemp.push_back(4 * data[row][j / 4] + j % 4);
302         }
303         post_data.push_back(vtemp);
304     }
305
306     vector<vector<size_t>> new_data = post_data;
307
308     for (size_t i = 0; i < post_data.size(); i++)
309     {
310         for (size_t j = 0; j < post_data.size(); j++)
311         {
312             if (find(post_data[i].begin(), post_data[i].end(), j) == post_data
313                 [i].end())
314             {
315                 new_data[i].push_back(j);
316             }
317         }
318     }
319     return new_data;
320 }
321
322 double QSolver::getSquareRoot(const vector<double>& data)
323 {
324     double sum = 0;
325
326     for (size_t i = 0; i < data.size(); i++)
327     {
328         sum += data[i] * data[i];
329     }
330
331     return sqrt(sum);
332 }
333
```