

# A Fast Iterative Shrinkage-Thresholding Algorithm for Linear Inverse Problems

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$$\mathbf{Ax} = \mathbf{b} + \mathbf{w}.$$

$$(\text{LS}): \quad \hat{\mathbf{x}}_{\text{LS}} = \underset{\mathbf{x}}{\operatorname{argmin}} \|\mathbf{Ax} - \mathbf{b}\|^2.$$

$$(\text{T}): \quad \hat{\mathbf{x}}_{\text{TIK}} = \underset{\mathbf{x}}{\operatorname{argmin}} \{ \|\mathbf{Ax} - \mathbf{b}\|^2 + \lambda \|\mathbf{Lx}\|^2 \}.$$

# ISTA

$$\min_{\mathbf{x}} \{F(\mathbf{x}) \equiv \|\mathbf{Ax} - \mathbf{b}\|^2 + \lambda \|\mathbf{x}\|_1\},$$

$$\mathbf{x}_{k+1} = \mathcal{T}_{\lambda t} \left( \mathbf{x}_k - 2t \mathbf{A}^T (\mathbf{Ax}_k - \mathbf{b}) \right),$$

$$\mathcal{T}_{\alpha}(\mathbf{x})_i = (|x_i| - \alpha)_+ \text{sgn}(x_i).$$

# CONTRIBUTION

$$\min_{\mathbf{x}} \{F(\mathbf{x}) \equiv f(\mathbf{x}) + g(\mathbf{x})\},$$

$$\mathbf{x}_{k+1} = \mathcal{T}_{\lambda t}(G(\mathbf{x}_k)),$$

$$\mathbf{x}_{k+1} = \mathcal{T}_{\lambda t}(G(\mathbf{y}_k)),$$

# ISTA ALGORITHM

**ISTA with constant stepsize**

**Input:**  $L := L(f)$  - A Lipschitz constant of  $\nabla f$ .

**Step 0.** Take  $\mathbf{x}_0 \in \mathbb{R}^n$ .

**Step k.** ( $k \geq 1$ ) Compute

$$(3.1) \quad \mathbf{x}_k = p_L(\mathbf{x}_{k-1}).$$

# ISTA ALGORITHM

## ISTA with backtracking

**Step 0.** Take  $L_0 > 0$ , some  $\eta > 1$ , and  $\mathbf{x}_0 \in \mathbb{R}^n$ .

**Step k.** ( $k \geq 1$ ) Find the smallest nonnegative integers  $i_k$  such that with  $\bar{L} = \eta^{i_k} L_{k-1}$

$$(3.2) \quad F(p_{\bar{L}}(\mathbf{x}_{k-1})) \leq Q_{\bar{L}}(p_{\bar{L}}(\mathbf{x}_{k-1}), \mathbf{x}_{k-1}).$$

Set  $L_k = \eta^{i_k} L_{k-1}$  and compute

$$(3.3) \quad \mathbf{x}_k = p_{L_k}(\mathbf{x}_{k-1}).$$

# FISTA ALGORITHM

**FISTA with constant stepsize**

**Input:**  $L = L(f)$  - A Lipschitz constant of  $\nabla f$ .

**Step 0.** Take  $\mathbf{y}_1 = \mathbf{x}_0 \in \mathbb{R}^n$ ,  $t_1 = 1$ .

**Step k.** ( $k \geq 1$ ) Compute

$$(4.1) \quad \mathbf{x}_k = p_L(\mathbf{y}_k),$$

$$(4.2) \quad t_{k+1} = \frac{1 + \sqrt{1 + 4t_k^2}}{2},$$

$$(4.3) \quad \mathbf{y}_{k+1} = \mathbf{x}_k + \left( \frac{t_k - 1}{t_{k+1}} \right) (\mathbf{x}_k - \mathbf{x}_{k-1}).$$



# NUMERICAL EXAMPLES

original



blurred and noisy



ISTA:  $F_{100} = 5.44\text{e-}1$

ISTA:  $F_{200} = 3.60\text{e-}1$

# PLES

FISTA:  $F_{100} = 2.40\text{e-}1$

FISTA:  $F_{200} = 2.28\text{e-}1$

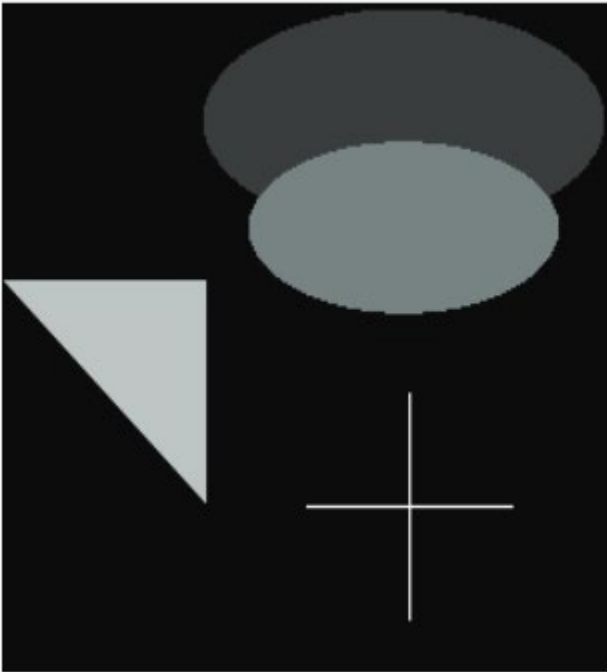
MTWIST:  $F_{100} = 3.09\text{e-}1$

MTWIST:  $F_{200} = 2.61\text{e-}1$



# NUMERICAL EXAMPLES

original



blurred and noisy



ISTA:  $F_{100} = 5.67\text{e-}1$

ISTA:  $F_{200} = 4.27\text{e-}1$

PLES

FISTA:  $F_{100} = 3.21\text{e-}1$

FISTA:  $F_{200} = 3.09\text{e-}1$

MTWIST:  $F_{100} = 3.83\text{e-}1$

MTWIST:  $F_{200} = 3.41\text{e-}1$

