

# Water Turbidity Measurement- Algorithm

NITAY OZER

ITAY MAL

SUPERVISOR ADI VAINIGER

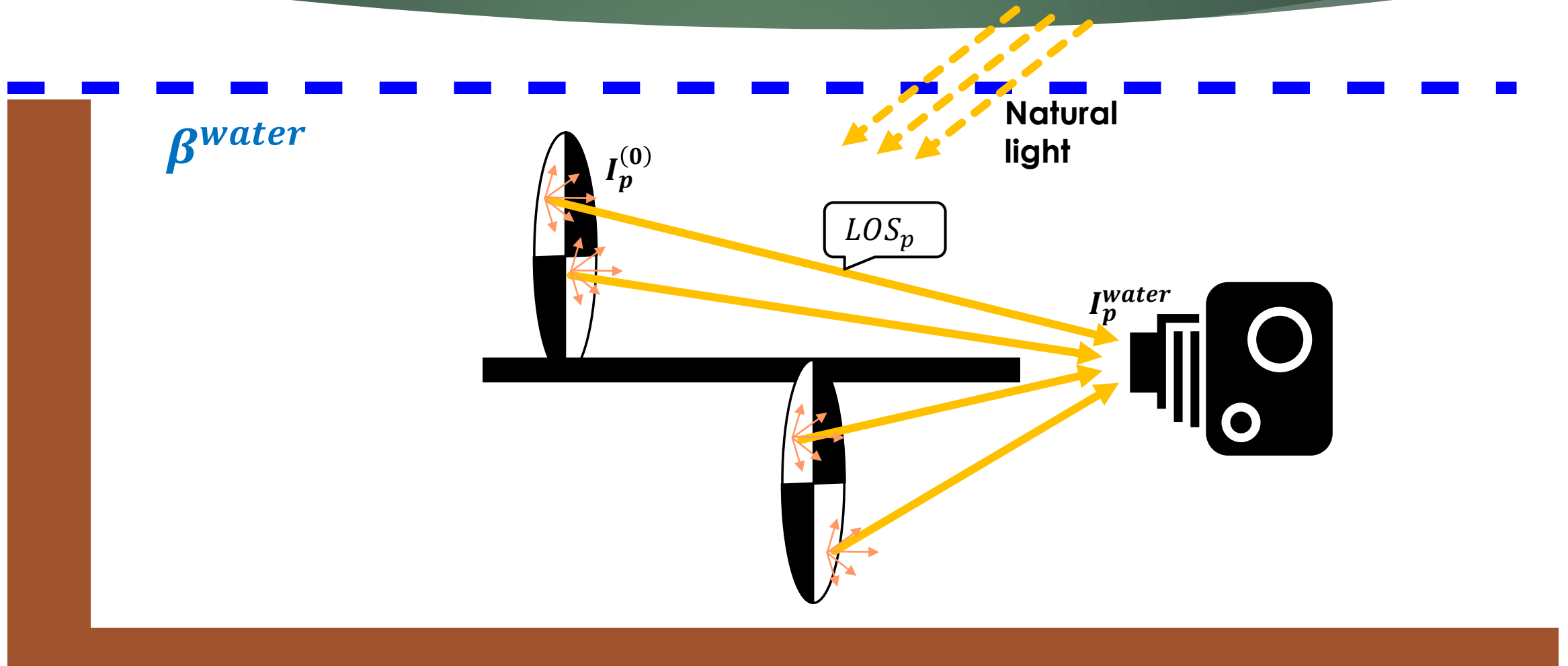
$$I_p^{water} \triangleq I_p^{(0)} e^{-\int_{X \in LOS_p} \beta^{water} dX} + I_p^{Ambient}$$

Where:

$$\beta^{water} \triangleq \underbrace{\beta_A^{water}}_{Absorption} + \underbrace{\beta_s^{water}}_{Scatter}$$

# Our Approach

3



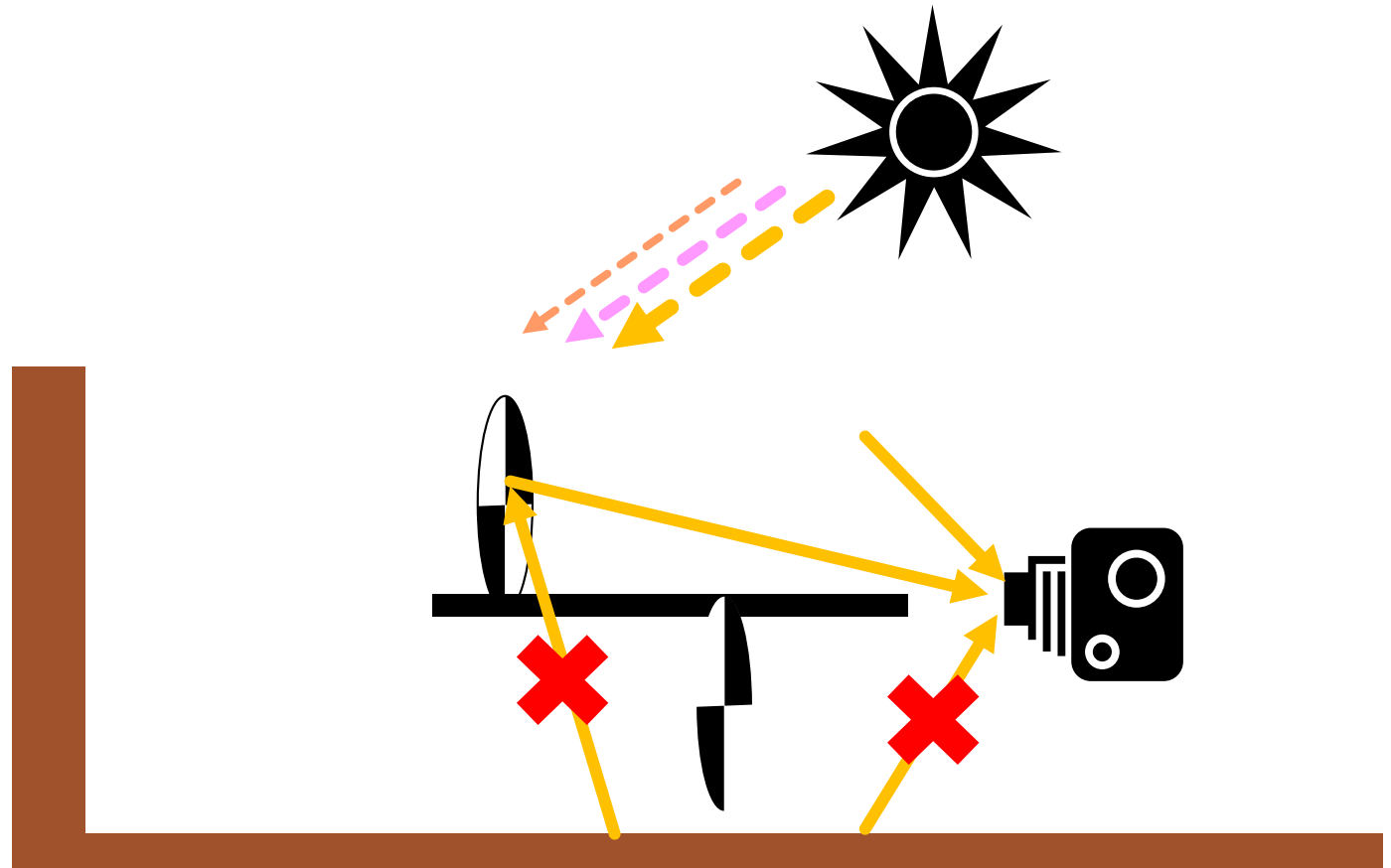
# Basic Assumptions

4

- ▶ Consistency of water turbidity in water body  $\Rightarrow \beta^{water} = \text{const.}$
- ▶ Invariant to light source.
- ▶ Water body is big enough  $\Rightarrow$  No reflectance from surroundings.

From the above:

$$I_p^{water} = I_p^{(0)} e^{-\beta^{water} \cdot \Delta x} + I_p^{Ambient}$$



# Calculating $\beta^{water}$ with 2 Targets

5

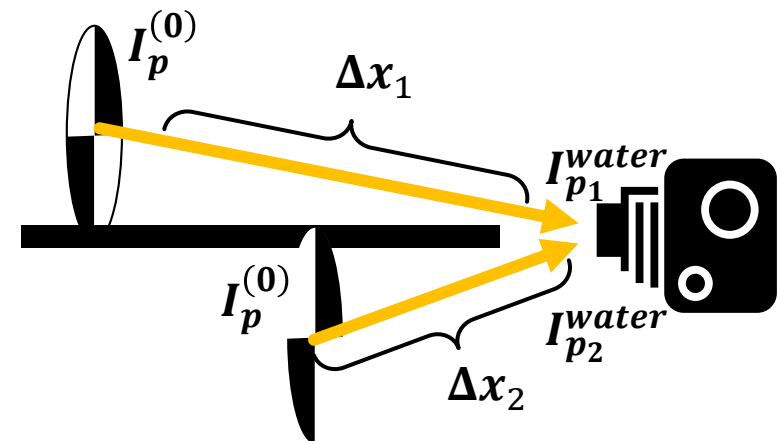
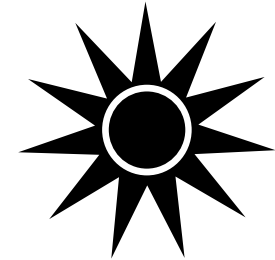
From 1st target:

$$I_{p1}^{water} = I_p^{(0)} e^{-\beta^{water} \cdot \Delta x_1} + I_{p1}^{Ambient}$$

From 2nd target:

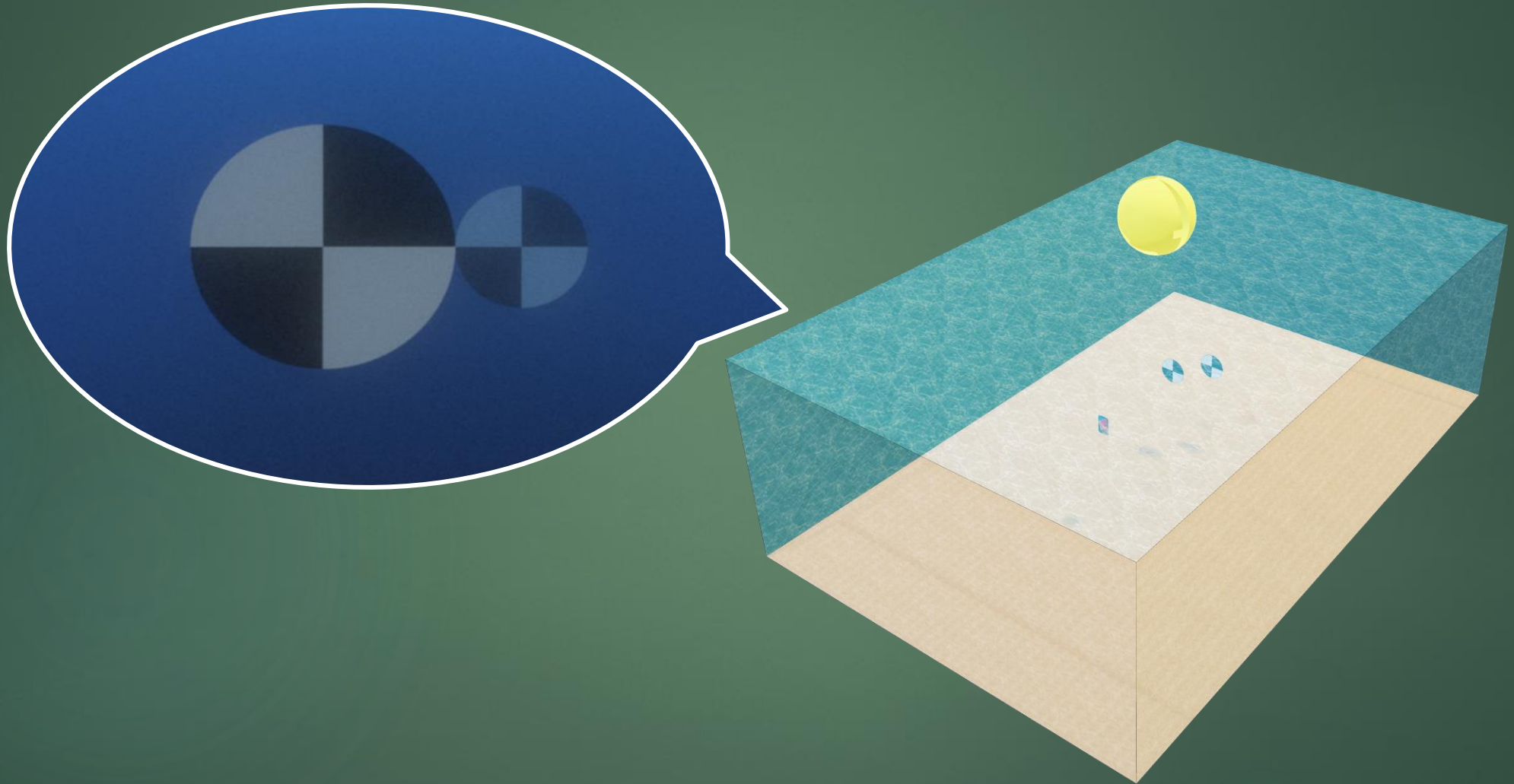
$$I_{p2}^{water} = I_p^{(0)} e^{-\beta^{water} \cdot \Delta x_2} + I_{p2}^{Ambient}$$

$$\beta^{water} = - \frac{\ln \left( \frac{I_{p1}^{water} - I_{p1}^{Ambient}}{I_{p2}^{water} - I_{p2}^{Ambient}} \right)}{\Delta x_1 - \Delta x_2}$$



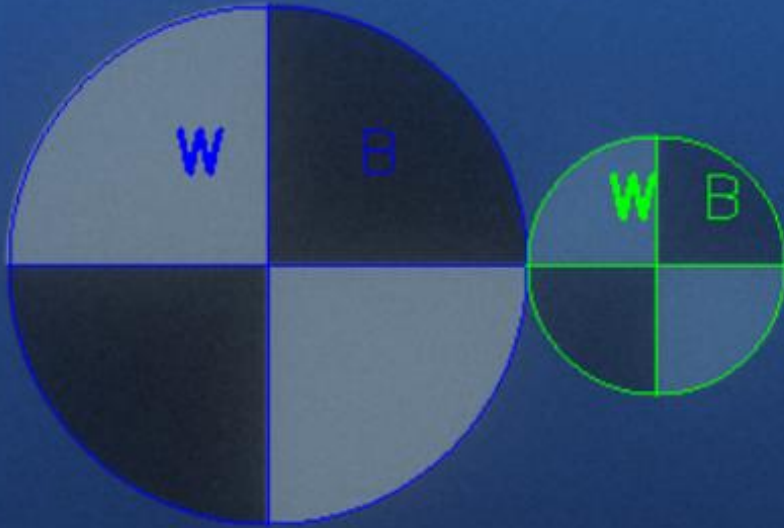
# Measurement Setup

6



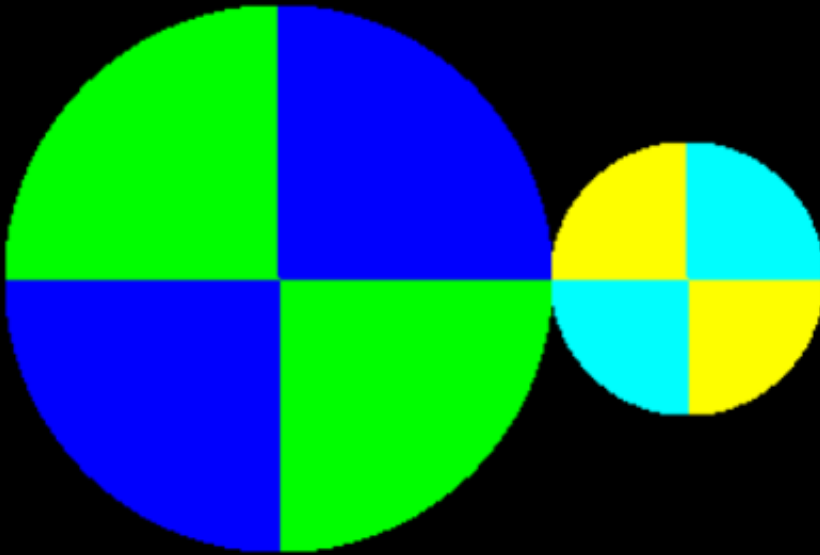
# Step I – Detecting the Targets

7



# Step II – Averaging the Quarters

8





# Step III – Calculating

9

```
target1 distance: 0.6009615384615384[m] | target2 distance: 1.2019230769230769[m]  
t1[B,G,R]: [0.23528907 0.16250007 0.10520586] t2[B,G,R]: [0.2170886 0.09373707 0.03434089]  
attenuation blue on white: 0.13396749591827392  
attenuation green on white: 0.9155072860717773  
attenuation red on white: 1.8629847412109375
```

## Real Values:

$$\Delta x_1 = 0.6$$

$$\Delta x_2 = 1.2$$

$$\beta_s^{water}(r, g, b) = (0.64, 0.64, 0.64)$$

$$\beta_A^{water}(r, g, b) = (0.5, 0.2, 0)$$

$$\beta^{water}(r, g, b) = (1.14, 0.84, 0.64)$$

## Estimated Values:

$$\Delta x_1 = 0.6009$$

$$\Delta x_2 = 1.2019$$

$$\beta_s^{water}(r, g, b) = ???$$

$$\beta_A^{water}(r, g, b) = ???$$

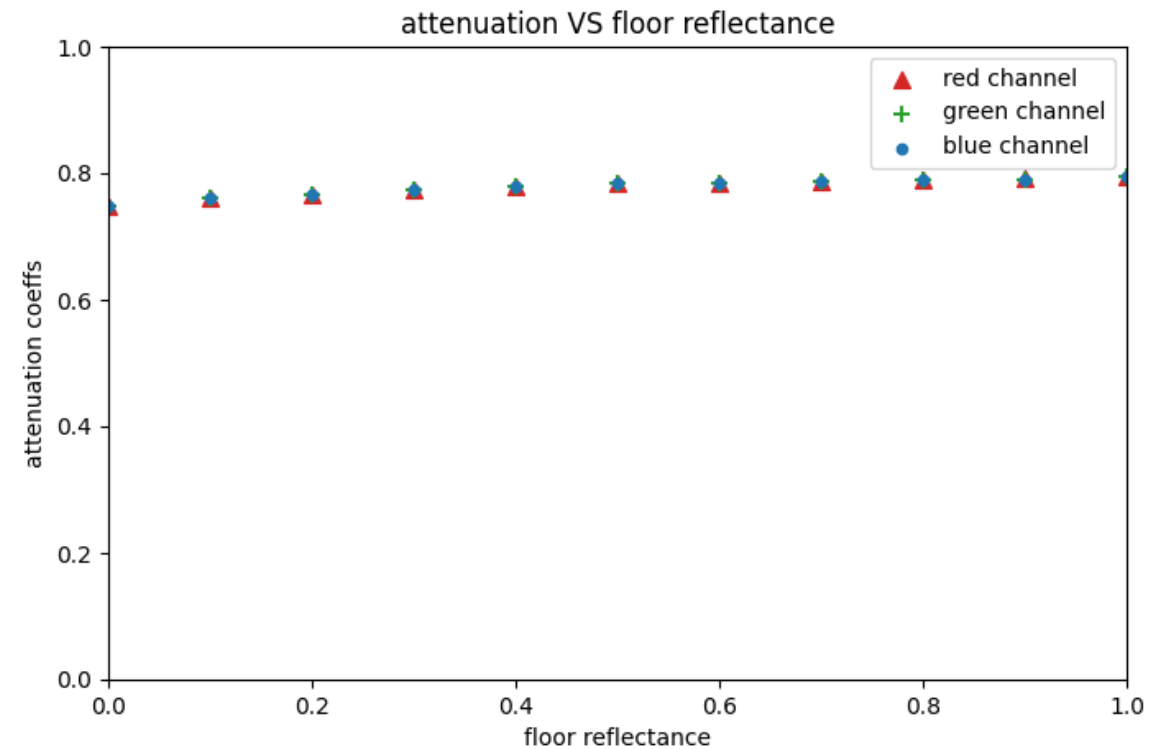
$$\beta^{water}(r, g, b) = (1.86, 0.91, 0.13)$$

# Validating Assumptions

10

- ▶ Water body is big enough  $\Rightarrow$  No reflectance from surroundings.

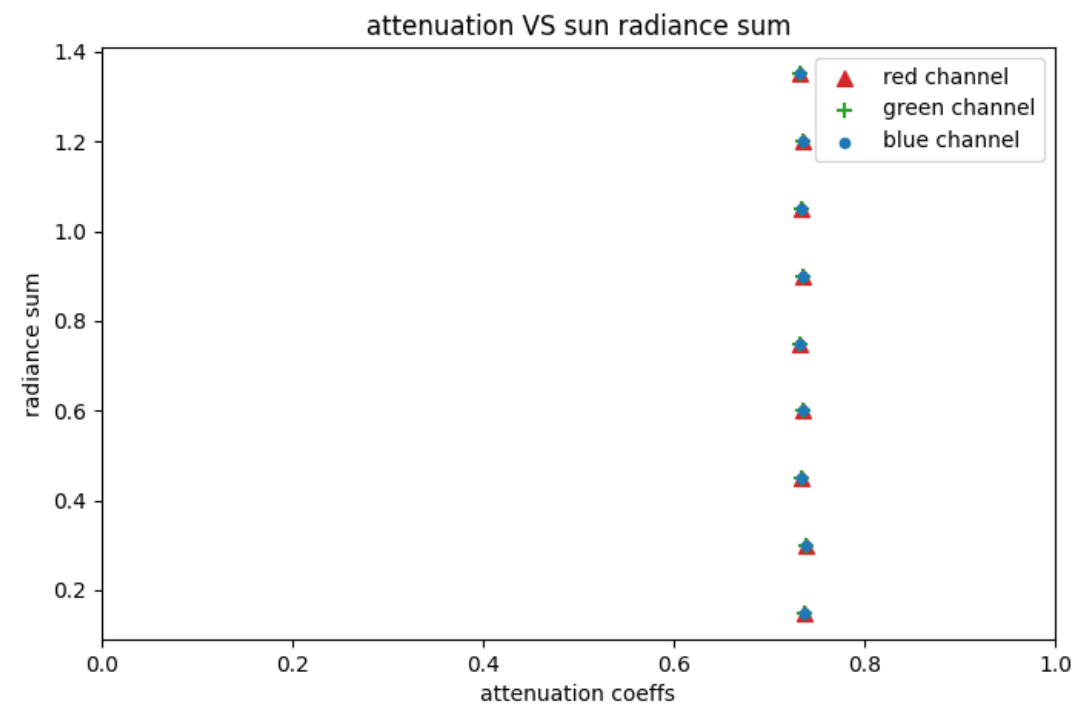
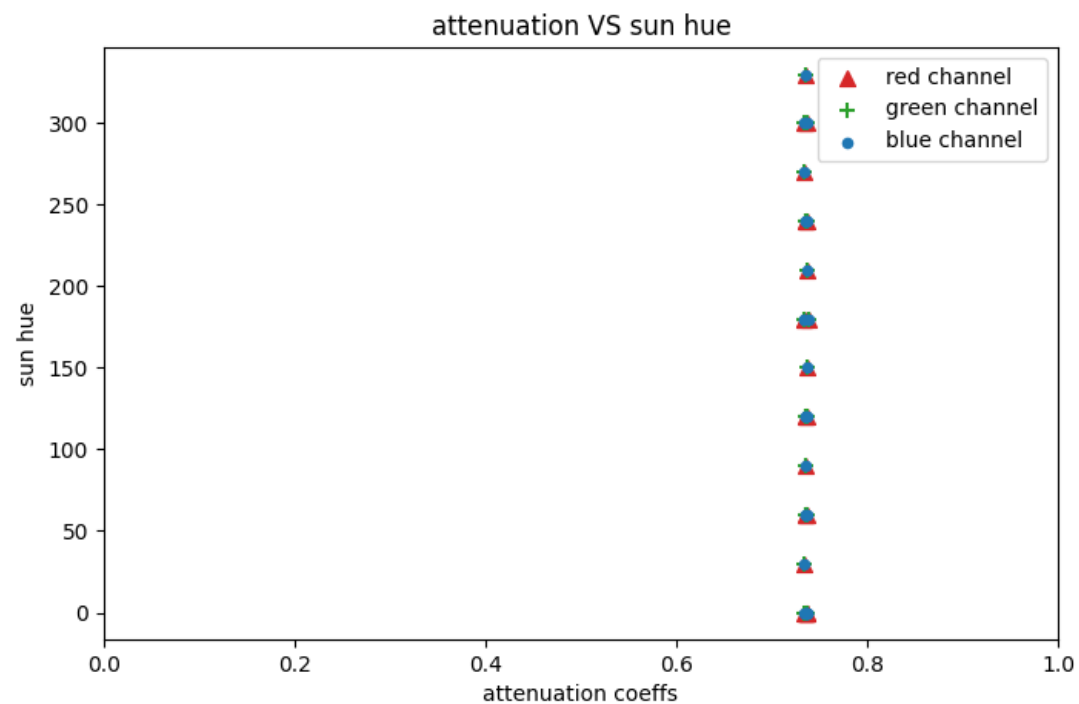
We chose to work with ***floor\_ref=0***



# Validating Assumptions

11

- Invariant to light source.

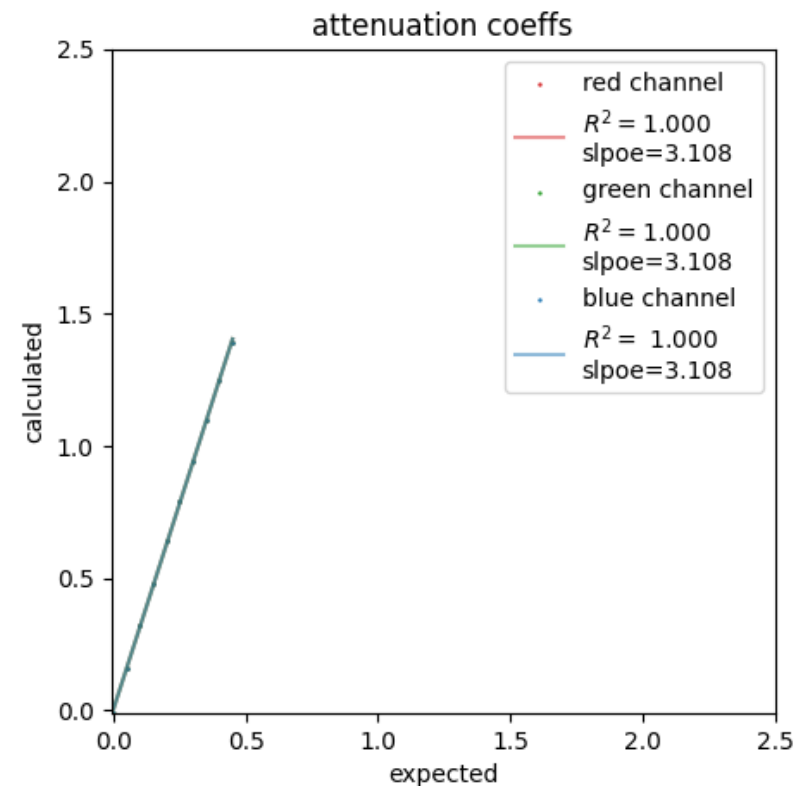


# Checking Absorption

12

- ▶ Sweeping only on  $\beta_A^{water} \in [0, 0.5]$ .
- ▶  $\beta_S^{water} = (0, 0, 0)$ .

We can see that the behavior is almost perfectly linear with error  $< 10^{-3}$ , and with slope = 3.108

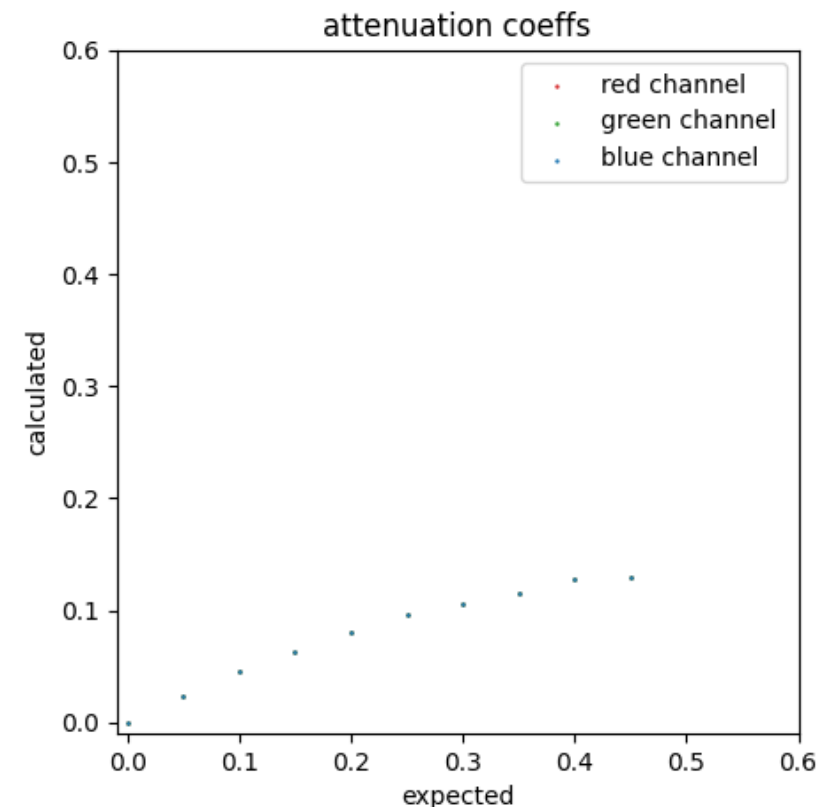


# Checking scatter

13

- ▶ Sweeping only on  $\beta_s^{water} \in [0,0.5]$ .
- ▶  $\beta_A^{water} = (0,0,0)$ .

We can see that the graph behavior is **not linear**.



# Checking scatter with absorption

14

- ▶ Sweeping only on  $\beta_S^{water} \in [0,1]$ .
- ▶  $\beta_A^{water} = (0.5, 0.2, 0)$ .

We can see that the graph behavior is still **not linear** and **different** for each channel.

