Welcome to Pair Interaction Detector Software by RGB cameras:

Tools:

- 1. Four cameras 'logitech c920'.
- 2. One computer.
- 3. Four Players.

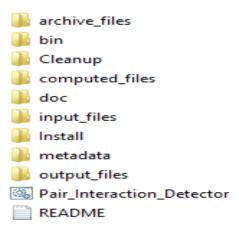
Preparation:

- 1. Each player choose distinct number from {1,2,3,4}
- 2. Connect all the cameras to the computer
- 3. Check the number of each camera by 'Start Calibration'
- 4. Player 'i' sitting against the camera 'i'
- 5. The players should sit as circle form

Important Issues:

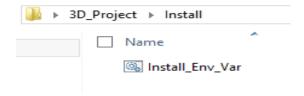
- 1. Don't change folders order!
- 2.Don't rename any file!

Files Structure:



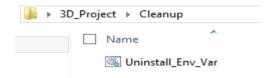
Installation:

Execute the script into "Install" folder named 'Install_Env_Var.bat' by double click.



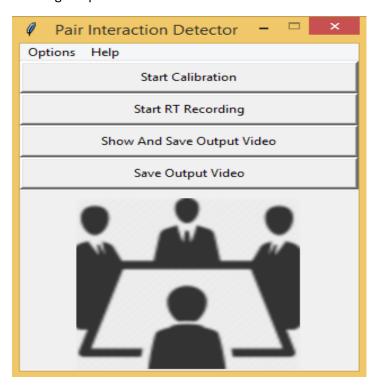
Uninstallation:

Execute the script into "Cleanup" folder named 'Uninstall_Env_Var.bat' by double click.



How To Use:

- Execute the script named 'Pair_Interaction_Detector.bat' by double click you'll see a
 graphic user interface for handling this application
- 2. You have a few buttons to use:
 - * 'Start Calibration': Open four cameras for making the calibration by sitting order.
 - * 'Start RT Recording': Open four cameras for scene real rime recording
- * 'Save Output Video': Save the output. it is including the files Matches.csv [participate sights, bi-directional sights between participates], Processed_Frames folder that contains processed video recorded frames for next matches analyzing, Video.avi file that contains processed video of last scene
- * 'Save And Show Output Video': Performing 'Save Output Video' method and than showing the processed video as a service



Explanation about the process:

1. Calibration:

- 1.0 Press on 'Start Calibration', a window with the camera view should open
 - 1.1 Ask the first player to look at the second player
 - 1.2 2 Press '2' on the keyboard
 - 1.3 If the image is blurred, then press again until you have a good image
 - 1.4 Press 'esc' button to finish with this participate
- 2.0 Ask the first player to look at the third player
 - 2.1 Press '3' on the keyboard
 - 2.2 If the image is blurred, then press again until you have a good image
 - 2.3 Press 'esc' button to finish with this participate
- 3.0 Ask the first player to look at the four players
 - 3.1 Press '4' on the keyboard
 - 3.2 If the image is blurred, then press again until you have a good image
 - 3.3 Press 'esc' button to finish with this participate
- 4.0 Ask the first player to look straight
 - 4.1 Press '5' on the keyboard
 - 4.2 If the image is blurred, then press again until you have a good image
 - 4.3 Press 'esc' button to finish with the first player
- After doing as the same concept for all participates move to step 2.

2. Real Time Recording:

- 1.0 Press on 'Start RT Recording', a window all cameras view should open
- 2.0 Make some group meeting with interactions and talking between the participates
- 3.0 Press 'esc' to finish the recording
- All frames will be saved in 'input_files' directory

3. Save Output Video:

- 1.0 Press on 'Save Output Video'
- 2.0 If there is no calibration frame and real time recording frames into 'input_files' and their computations into 'computed_files' it cannot continue and will raise a pop-up message as form of:



- 3.0 At this time all frames that were took at last process is computing and preparing an output
- 4.0 At the end of the processing you can except to see all frames in 'input_files' into '.zip' file and into 'output_files' a folder that is containing Processed_Frames of that process, Matches.csv that is containing matches of each frame from the video and the video recorded file itself.

Output folder example:

Processed_Frames



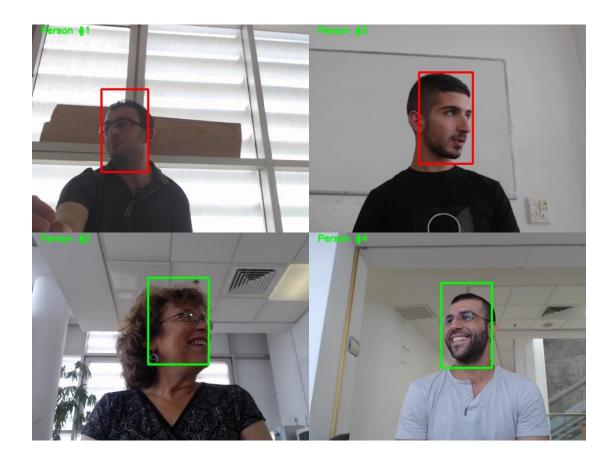
Matches



■ video

4. Show And Save Output Video:

- 1.0 Press on 'Show And Save Output Video'
- 2.0 The same functionality will apply
- 3.0 At the end computations and saving the video will be showing by the application
- 4.0 You can stop the showing using 'esc' button each time
- For more informations, Examples and documentations you can address our github repository or the web page in the university projects site:
 - o Github repository: https://github.com/itaycsguy/3D Cameras.git



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Thanks and have interesting execution!