

# Olin College of Engineering

## ENGR2410 – Signals and Systems

### Reference 8

The properties of the discrete time Fourier transform are similar to the continuous time.

#### Continuous time

$$\begin{array}{ccccc}
 x(t) & \longrightarrow & \boxed{h(t)} & \longrightarrow & y(t) = x(t) * h(t) = \int_{\tau=-\infty}^{\tau=\infty} x(\tau)h(t-\tau)d\tau \\
 \mathcal{F} \downarrow & & & & \uparrow \mathcal{F}^{-1} \\
 X(j\omega) & \longrightarrow & \boxed{H(j\omega)} & \longrightarrow & Y(j\omega) = X(j\omega)H(j\omega)
 \end{array}$$

#### Discrete time<sup>1</sup> ( $n \in \mathbb{Z}$ )

$$\begin{array}{ccccc}
 x[n] & \longrightarrow & \boxed{h[n]} & \longrightarrow & y[n] = x[n] * h[n] = \sum_{k=-\infty}^{k=\infty} x[k]h[n-k] \\
 \mathcal{F} \downarrow & & & & \uparrow \mathcal{F}^{-1} \\
 X(\Omega) & \longrightarrow & \boxed{H(\Omega)} & \longrightarrow & Y(\Omega) = X(\Omega)H(\Omega)
 \end{array}$$

#### Frequency content of a discrete signal

$$x[n] \longrightarrow \boxed{D/C} \longrightarrow x_S(t)$$

The discrete-to-continuous (D/C) transformation above defines  $x_S(t)$  as a function of time sampled at an arbitrary  $f_S$  that corresponds to the discrete function  $x[n]$  such that

$$x_S(t) = \sum_n x[n]\delta(t - n/f_S)$$

We can use the continuous time Fourier transform to find  $X_S(j\omega)$ :

$$X_S(j\omega) = \int_t \sum_n x[n]\delta(t - n/f_S)e^{-j\omega t} dt$$

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<sup>1</sup>In the same way  $H(j\omega)$  is written to explicitly include the  $j$  in order to relate it to the Laplace transform,  $H(\Omega)$  is sometimes written as  $H(e^{j\Omega})$  to relate it to the Z transform.

Since we introduced  $f_S$  arbitrarily to define  $x_S(t)$ , we have to normalize the frequency such that  $\Omega = \omega/f_S$ . This is the *discrete time Fourier transform*.

$$X_S(\Omega) = \sum_n x[n]e^{-j\Omega n}$$

As in continuous time,  $X_S(\Omega)$  is a complex function which has magnitude and phase. However, note that since  $X_S(\Omega)$  is a linear combination of  $e^{j\Omega n}$  basis functions, *it always has a period of  $2\pi$* .

We can use orthogonality to find the inverse discrete time transform, noting that since  $n$  is an integer, we only need to integrate  $e^{j\Omega n}$  over any  $2\pi$  period;

$$\int_{\omega_0}^{\omega_0+2\pi} e^{j\Omega n} d\Omega = \begin{cases} 2\pi & n = 0 \\ 0 & n \neq 0 \end{cases}, \quad n \in \mathbb{Z}, \quad \omega_0 \in \mathbb{R}$$

Expanding  $X_S(\Omega)$ ,

$$X_S(\Omega) = \dots + x[-1]e^{j\Omega} + x[0] + x[1]e^{-j\Omega} + \dots + x[n]e^{-j\Omega n} + \dots$$

$$X_S(\Omega)e^{j\Omega n} = \dots + x[1]e^{j\Omega(n-1)} + \dots + x[n] + \dots$$

$$\int_{2\pi} X_S(\Omega)e^{j\Omega n} d\Omega = \dots + \int_{2\pi} x[1]e^{j\Omega(n-1)} d\Omega + \dots + \int_{2\pi} x[n] d\Omega + \dots$$

$$\int_{2\pi} X_S(\Omega)e^{j\Omega n} d\Omega = 2\pi x[n]$$

$$x[n] = \int_{2\pi} X_S(\Omega)e^{j\Omega n} \frac{d\Omega}{2\pi}$$

## A few properties and transforms

Discrete time impulse

$$\delta[n] = \begin{cases} 1 & n = 0 \\ 0 & \text{otherwise} \end{cases} \quad \xleftrightarrow{\mathcal{F}} \quad \sum_n \delta[n]e^{-j\Omega n} = 1$$

Delay

$$x[n - n_0] \quad \xleftrightarrow{\mathcal{F}} \quad \sum_n \underbrace{x[n - n_0]}_m e^{-j\Omega n} = \sum_m \underbrace{x[m]e^{-j\Omega m}}_{X(\Omega)} e^{-j\Omega n_0} = X(\Omega)e^{-j\Omega n_0}$$

In the case of a complex exponential  $e^{j\Omega_0 n}$ , we can verify that an impulse at  $\Omega_0$  works since

$$\int_{-\pi}^{\pi} 2\pi \delta(\Omega - \Omega_0) e^{j\Omega n} \frac{d\Omega}{2\pi} = e^{j\Omega_0 n}, \quad -\pi \leq \Omega_0 \leq \pi$$

However, this must work for any  $2\pi$  period, and we know that  $X(\Omega)$  must be  $2\pi$  periodic, so that the impulse can be shifted by an integer multiple of  $2\pi$ :

$$\int_{-\pi+2\pi k}^{\pi+2\pi k} 2\pi \delta(\Omega - \Omega_0 - 2\pi k) e^{j\Omega n} \frac{d\Omega}{2\pi} = e^{j\Omega_0 n} e^{j2\pi k n}, \quad -\pi \leq \Omega_0 \leq \pi, \quad k \in \mathbb{Z}$$

Since we are only integrating over one  $2\pi$  period, we can add all these impulses and guarantee that there will be a single impulse in any  $2\pi$  period:

$$e^{j\Omega_0 n} = \int_{2\pi} \underbrace{\sum_k 2\pi \delta(\Omega - \Omega_0 - 2\pi k) e^{j\Omega n} \frac{d\Omega}{2\pi}}_{X(\Omega)} \xleftrightarrow{\mathcal{F}} \sum_k 2\pi \delta(\Omega - \Omega_0 - 2\pi k), \quad k \in \mathbb{Z}$$

### First-order difference equation

$$y[n] - ay[n-1] = x[n]$$

If  $x[n] = \delta[n]$ , then  $y[n] = h[n]$ , the impulse response.

$$\delta[n] \longrightarrow \boxed{h[n]} \longrightarrow h[n]$$

Since  $\delta[n] = 0$  for all  $n < 0$ ,  $h[n] = 0$ , for all  $n < 0$ . Specifically,

$$h[-1] = 0$$

Then,

$$h[0] - a \overset{0}{\cancel{h[-1]}} = \overset{1}{\cancel{\delta[0]}} \Rightarrow h[0] = 1$$

$$h[1] - a \overset{1}{\cancel{h[0]}} = \overset{0}{\cancel{\delta[1]}} \Rightarrow h[1] = a$$

$$h[2] - a \overset{a}{\cancel{h[1]}} = \overset{0}{\cancel{\delta[2]}} \Rightarrow h[2] = a^2$$

and so forth. In general,

$$h[n] = a^n u[n]$$

where

$$u[n] = \begin{cases} 1 & n = 0, 1, 2, 3, \dots \\ 0 & \text{otherwise} \end{cases}$$

As in the continuous time case, complex exponentials are eigenfunctions of discrete time LTI systems such that

$$e^{j\Omega n} \longrightarrow \boxed{h[n]} \longrightarrow H(\Omega)e^{j\Omega n}$$

We can use this to find  $H(\Omega)$  for the first-order difference equation by letting  $x[n] = e^{j\Omega n}$  and  $y[n] = H(\Omega)e^{j\Omega n}$ .

$$\begin{aligned} y[n] - ay[n-1] &= x[n] \\ H(\Omega)e^{j\Omega n} - aH(\Omega)e^{j\Omega n}e^{-j\Omega} &= e^{j\Omega n} \\ H(\Omega) &= \frac{1}{1 - ae^{-j\Omega}} \end{aligned}$$

Note that we just found  $h[n]$  and  $H(\Omega)$  for the first-order difference equation. Since

$$\begin{array}{ccccc} \delta[n] & \longrightarrow & \boxed{h[n]} & \longrightarrow & h[n] \\ \mathcal{F} \downarrow & & & & \\ 1 & \longrightarrow & \boxed{H(\Omega)} & \longrightarrow & H(\Omega) \end{array}$$

we expect that

$$h[n] \xleftrightarrow{\mathcal{F}} H(\Omega)$$

Specifically,

$$\boxed{a^n u[n] \xleftrightarrow{\mathcal{F}} \frac{1}{1 - ae^{-j\Omega}}}$$

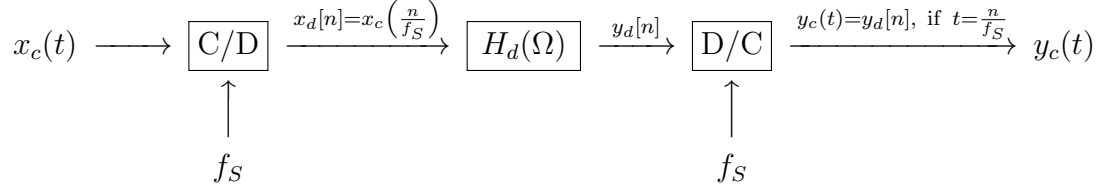
In order to verify this, compute  $H(\Omega)$  using the definition of the transform:

$$H(\Omega) = \sum_n h[n]e^{-j\Omega n} = \sum_n a^n u[n]e^{-j\Omega n} = \sum_{n=0}^{\infty} (ae^{-j\Omega})^n = \frac{1}{1 - ae^{-j\Omega}}$$

Note that  $|a| < 1$  for the sum to converge.

## DT processing of CT signals

Two subsystems that convert a continuous time signal  $x_c(t)$  into a discrete time signal  $x_d[n]$ , (C/D), and vice versa, (D/C), can be used to process  $x_c(t)$  using a discrete filter  $H_d(\Omega)$ .



Keeping in mind that sampling at  $f_s$  constrains  $\Omega$  such that

$$\frac{\omega}{f_s} = \Omega$$

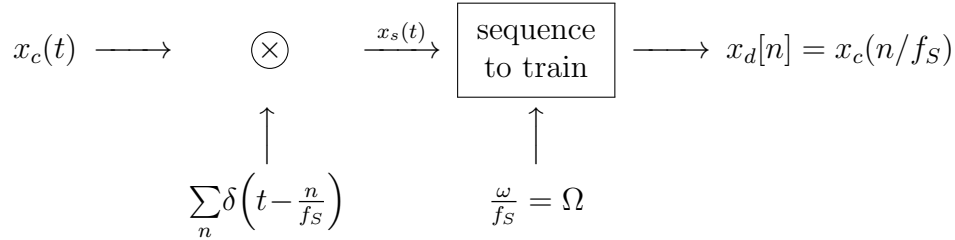
If  $x_c(t)$  is bandlimited by  $f_{max}$  such that the sampling frequency  $f_s > 2f_{max}$ , the system above is equivalent to an LTI system  $H_c(j\omega)$ , where

$$H_c(j\omega) = \begin{cases} H_d(\omega/f_s) & -2\pi\frac{f_s}{2} \leq \omega \leq 2\pi\frac{f_s}{2} \\ 0 & \text{otherwise} \end{cases}$$

Equivalently,

$$Y_c(j\omega) = H_d(\omega/f_s)X_c(j\omega)$$

In order to show this result, we need to define the C/D and D/C subsystems. The C/D subsystem samples  $x_c(t)$  using a pulse train, and the resulting sampled  $x_s(t)$  is redefined as a discrete sequence,



Similarly, a continuous signal  $y_c(t)$  can be reconstructed from a discrete signal  $y_d[n]$  using the D/C system below.

