Olin College of Engineering
ENGR2410 – Signals and Systems

Lecture 2 Reference

Definitions

Linear system:

If

$$x_1 \rightarrow \boxed{L} \rightarrow y_1$$

and

$$x_2 \rightarrow \boxed{L} \rightarrow y_2$$

then

$$ax_1 + bx_2 \rightarrow \boxed{L} \rightarrow ay_1 + by_2.$$

Time-invariant system:

If

$$x_1(t) \rightarrow \boxed{TI} \rightarrow y_1(t)$$

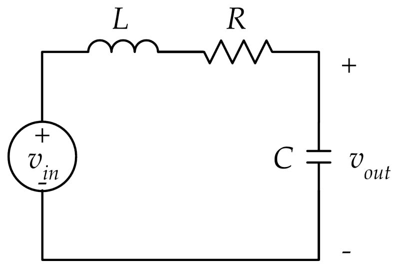
then

$$x_1(t-T) \rightarrow \boxed{TI} \rightarrow y_1(t-T).$$

Eigenfunctions

$$e^{st} \rightarrow \boxed{LTI} \rightarrow \underbrace{H(s)}_{\text{transfer function}} \underbrace{e^{st}}_{\text{eigenfunction}}$$

Example:



If $v_{in} = e^{st}$ in the circuit above, when know that $v_{out} = H(s)e^{st}$. Find $H(s)$ by substituting in the differential equation:

$$\begin{aligned}
&\ddot{v_o} + 2\alpha\dot{v_o} + \omega_0^2 v_o = \omega_0^2 v_i \\
&H(s)s^2\cancel{e^{st}} + 2\alpha H(s)s\cancel{e^{st}} + \omega_0^2 H(s)\cancel{e^{st}} = \omega_0^2\cancel{e^{st}} \\
&H(s)(s^2 + 2\alpha s + \omega_0^2) = \omega_0^2 \\
&H(s) = \frac{\omega_0^2}{s^2 + 2\alpha s + \omega_0^2}
\end{aligned}$$

Sinusoidal Steady State

A special (but important) case is when $s = j\omega$ such that the input is $e^{j\omega t}$, a complex exponential. By Euler's Equation,

$$e^{j\omega t} = \cos(\omega t) + j\sin(\omega t).$$

We can "construct" the cosine function using a linear combination of two complex exponentials:

$$\cos(\omega t) = \frac{1}{2}(e^{j\omega t} + e^{-j\omega t}).$$

By linearity,

$$\cos\omega t \rightarrow \boxed{LTI} \rightarrow \text{output}$$

is equivalent to

$$\begin{aligned}
&\frac{1}{2}e^{j\omega t} \rightarrow \boxed{LTI} \rightarrow \frac{1}{2}H(j\omega)e^{j\omega t} \\
&\quad + \qquad\qquad\qquad\qquad + \\
&\frac{1}{2}e^{-j\omega t} \rightarrow \boxed{LTI} \rightarrow \frac{1}{2}H(-j\omega)e^{-j\omega t}
\end{aligned}$$

Therefore, the output is

$$\frac{1}{2}H(j\omega)e^{j\omega t} + \frac{1}{2}H(-j\omega)e^{-j\omega t}.$$

If H is *holomorphic*, then $H(-j\omega) = H^*(j\omega)$, where the asterisk denotes the complex conjugate. Likely all the functions you will use will be holomorphic.

In polar form,

$$\begin{aligned} H(j\omega) &= |H(j\omega)|e^{j\angle H(j\omega)} \\ H(-j\omega) &= H^*(j\omega) = |H(j\omega)|e^{-j\angle H(j\omega)} \end{aligned}$$

So the output of the system is

$$\begin{aligned} &\frac{1}{2}|H(j\omega)|e^{j\angle H(j\omega)}e^{j\omega t} + \frac{1}{2}|H(j\omega)|e^{-j\angle H(j\omega)}e^{-j\omega t} \\ =&|H(j\omega)|\frac{e^{j(\omega t + \angle H(j\omega)} + e^{-j(\omega t + \angle H(j\omega)}}{2} \\ =&|H(j\omega)|\cos(\omega t + \angle H(j\omega)). \end{aligned}$$

The general solution for the sinusoidal steady state is

$$\boxed{\cos\omega t \rightarrow \boxed{LTI} \rightarrow |H(j\omega)|\cos(\omega t + \angle H(j\omega))}$$

Note:
(i) the output has the same frequency as the input
(ii) the output is scaled and shifted by $H(j\omega)$

For example, the transfer function of 2nd order system in the previous section is

$$H(j\omega) = \frac{\omega_0^2}{-\omega^2 + j2\alpha\omega + \omega_0^2}$$

Its magnitude and phase are

$$|H(j\omega)| = \frac{\omega_0^2}{\sqrt{(\omega_0^2 - \omega^2)^2 + (2\alpha\omega)^2}}, \quad \angle H(j\omega) = -\tan^{-1}\left(\frac{2\alpha\omega}{\omega_0^2 - \omega^2}\right).$$

Therefore, if

$$v_i = V\cos(\omega t),$$

then

$$v_o = V\frac{\omega_0^2}{\sqrt{(\omega_0^2 - \omega^2)^2 + (2\alpha\omega)^2}}\cos\left[\omega t - \tan^{-1}\left(\frac{2\alpha\omega}{\omega_0^2 - \omega^2}\right)\right].$$

Bode Plot

The plot of $|H(j\omega)|$ and $\angle H(j\omega)$ as a function of ω completely describes $H(j\omega)$. A Bode plot shows $\log|H(j\omega)|$ as a function of $\log\omega$ for the magnitude and $\angle H(j\omega)$ as a function of $\log\omega$ for the angle.

In order to sketch a Bode plot, we consider the asymptotes at both extremes. For example, the transfer function of the 2nd order system in the previous section is

$$H(j\omega) = \frac{\omega_0^2}{-\omega^2 + j2\alpha\omega + \omega_0^2}$$

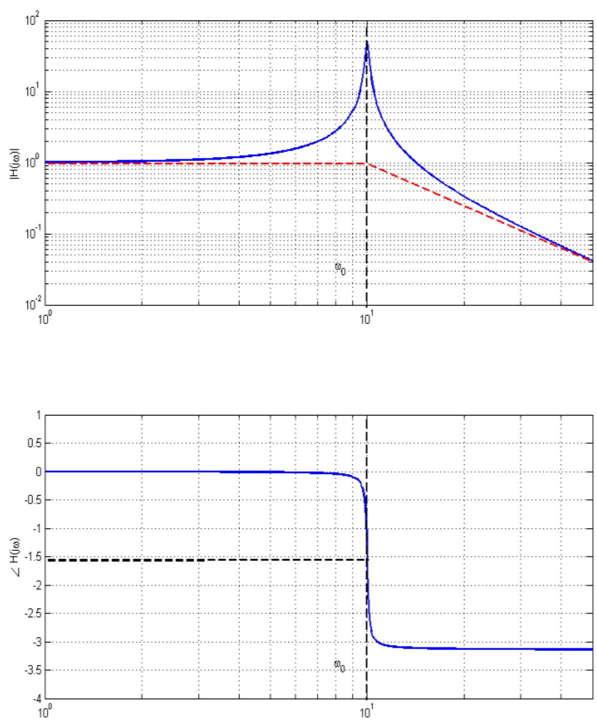
$$\text{If } \omega \to 0, \text{ then } H(j\omega) \approx \frac{\omega_0^2}{\omega_0^2} = 1 \qquad \text{and} \qquad |H(j\omega)| = 1, \quad \angle H(j\omega) = 0$$

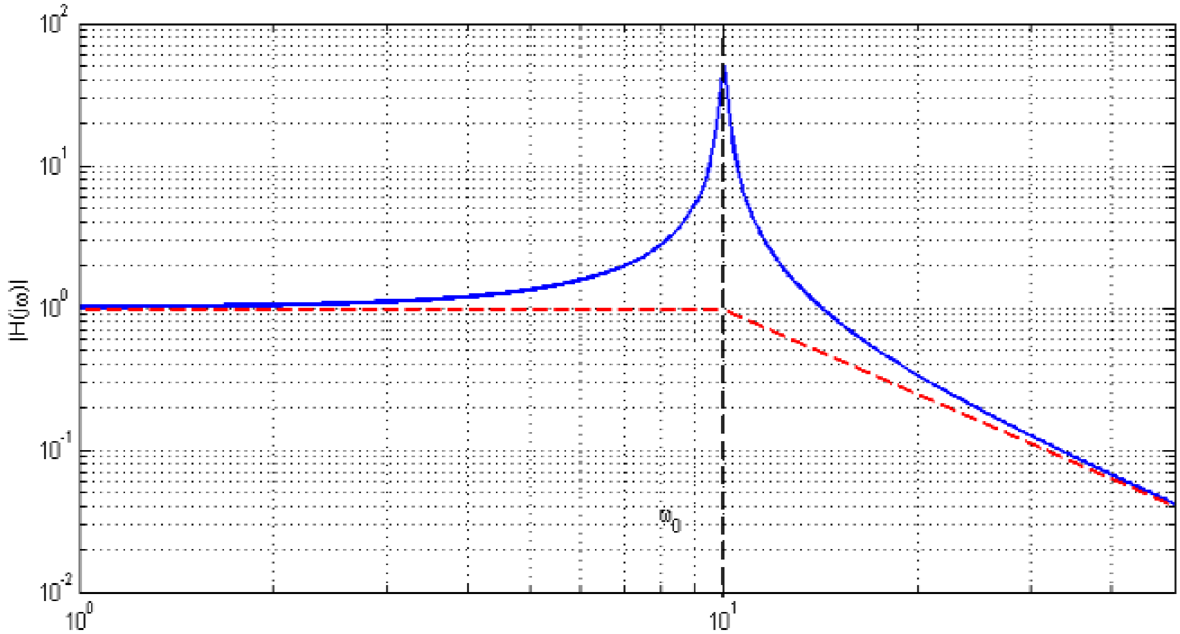
$$\text{If } \omega \to \infty, \text{ then } H(j\omega) \approx -\frac{\omega_0^2}{\omega^2} \qquad \text{and} \qquad |H(j\omega)| = \frac{\omega_0^2}{\omega^2}, \quad \angle H(j\omega) = \pm\pi$$

In the magnitude plot, the two lines intersect when $1 = \frac{\omega_0^2}{\omega^2}$, or $\omega = \omega_0$, the resonant frequency. If we substitute the resonant frequency into the transfer function, we find

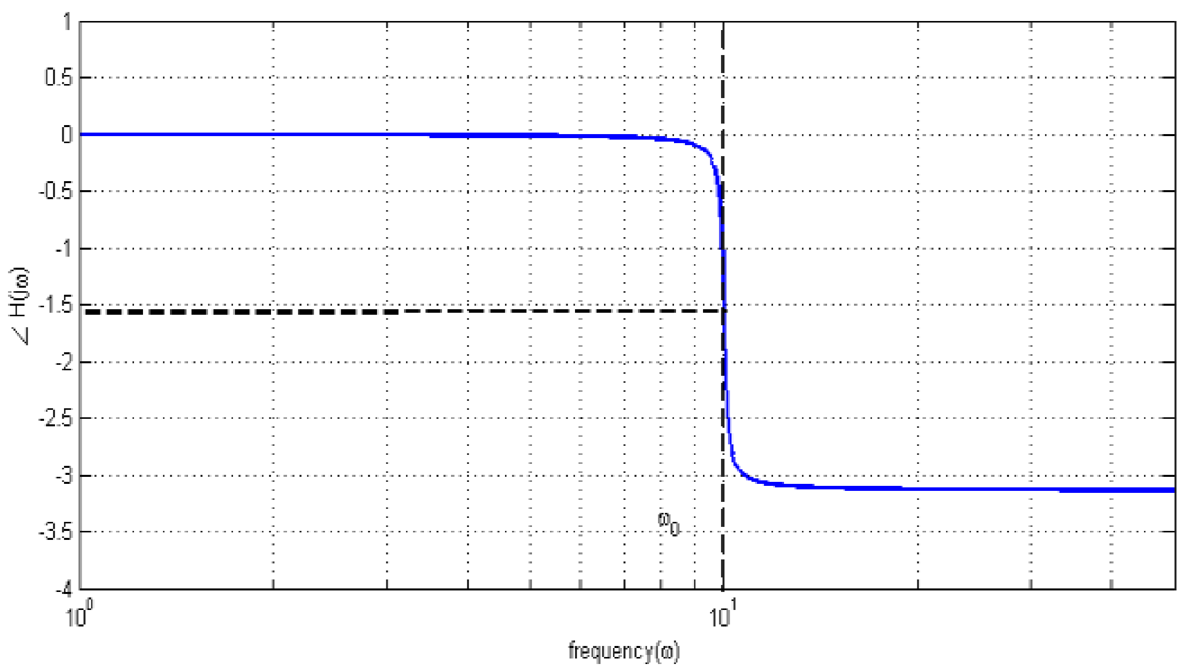
$$H(j\omega_0) = \frac{\omega_0^2}{j2\alpha\omega_0} = -j\frac{\omega_0}{2\alpha} \qquad \text{and} \qquad |H(j\omega)| = \frac{\omega_0}{2\alpha} \triangleq Q, \quad \angle H(j\omega) = -\frac{\pi}{2}.$$

The variable Q is called the quality factor and is widely used to characterize 2nd order systems. The Bode plot is shown below and larger on the next page.





|H(jω)|
ω0
10^2
10^1
10^0
10^-1
10^-2
10^0
10^1



∠ H(jω)
ω0
1
0.5
0
-0.5
-1
-1.5
-2
-2.5
-3
-3.5
-4
10^0
10^1
frequency(ω)