

## Function Junction

Time required: 30 minutes

Please read all the directions carefully before beginning the assignment.

- Comment your code as shown in the tutorials and other code examples.
- Follow all directions carefully and accurately.
- Think of the directions as minimum requirements.

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### Understanding

Demonstrate understanding of:

**light sensor, serial monitor**

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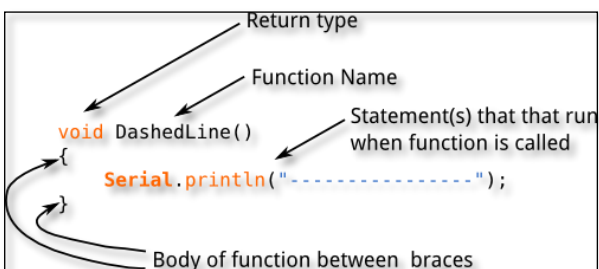
### Knowledge Points

As our code gets longer and more complex, it can get difficult to follow. Functions allow for reusable and modular code. A function is a code block. It wraps up everything needed to provide a service to the program. You can easily reuse the code in another sketch or the same sketch.

We have used pre written functions, such as **led.setColorAt();** and **delay(500);**. We will start writing our own.

Please go to the following web site to learn more about functions.

<https://startingelectronics.org/software/arduino/learn-to-program-course/15-functions/>



## Sample function

```
18 // Loop forever function
19 void loop() {
20     // Call function
21     simpleFunction();
22 }
23
24 void simpleFunction() {
25     // Put the code here
26 }
```

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## Requirements

Break our code into smaller chunks by dividing our code into functions.

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## Tutorial Assignment

1. Start the Arduino IDE. Save the sketch as **FunctionJunction**.
2. Complete and test the program as shown.

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## Challenge

- Create a new function that does something with LED's and/or sound.
- Call the new function.

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## Assignment Submission

1. All students: Zip up the sketch folder. Attach the zip file to the assignment in Blackboard.
2. The assignment is demonstrated in class.
3. Online students: A link to a YouTube video recording showing your robot going through its motions is placed in the submission area in BlackBoard.

```

1  /**
2   @file    FunctionJunction.ino
3   @author  William A Loring
4   @version V1.0.0
5   @date revised 02/20/2018  created: 12/16/16
6   @Description: Access the mBot onboard LED's with functions
7  */
8  #include <MeMCore.h>          // Include mBot library
9  // Initialize global variables
10 MeRGBLed led(0, 30);          // Create LED object
11 const int BLINK_DELAY = 500; // Initialize a constant for the delay time
12
13 // Initialization code, only runs once
14 void setup() {
15     // Set the physical pin to access the onboard LED's
16     led.setpin(13);
17 }
18
19 // Loop forever
20 void loop() {
21     // Call function
22     blinkLed();
23     // Call new function here
24 }
25
26 //-----
27 // Function to blink on board LED's
28 //-----
29 void blinkLed() {
30     led.setColorAt(0, 60, 0, 0); // Set LED0 (RightSide) to Red
31     led.setColorAt(1, 0, 0, 60); // Set LED1 (LeftSide) to Blue
32     led.show();                  // Show the specified color
33     delay(BLINK_DELAY);
34
35     led.setColorAt(0, 0, 0, 60); // Set LED0 (RightSide) to Blue
36     led.setColorAt(1, 60, 0, 0); // Set LED1 (LeftSide) to Red
37     led.show();                  // Show the specified color
38     delay(BLINK_DELAY);
39 }
40
41 // Create new function here

```