GoPiGo3 DI Sensors

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Dexter Sensors Documentation

DI sensor documentation: https://di-sensors.readthedocs.io/en/master/

Dexter Temperature, Humidity, and Pressure Sensor Tutorial

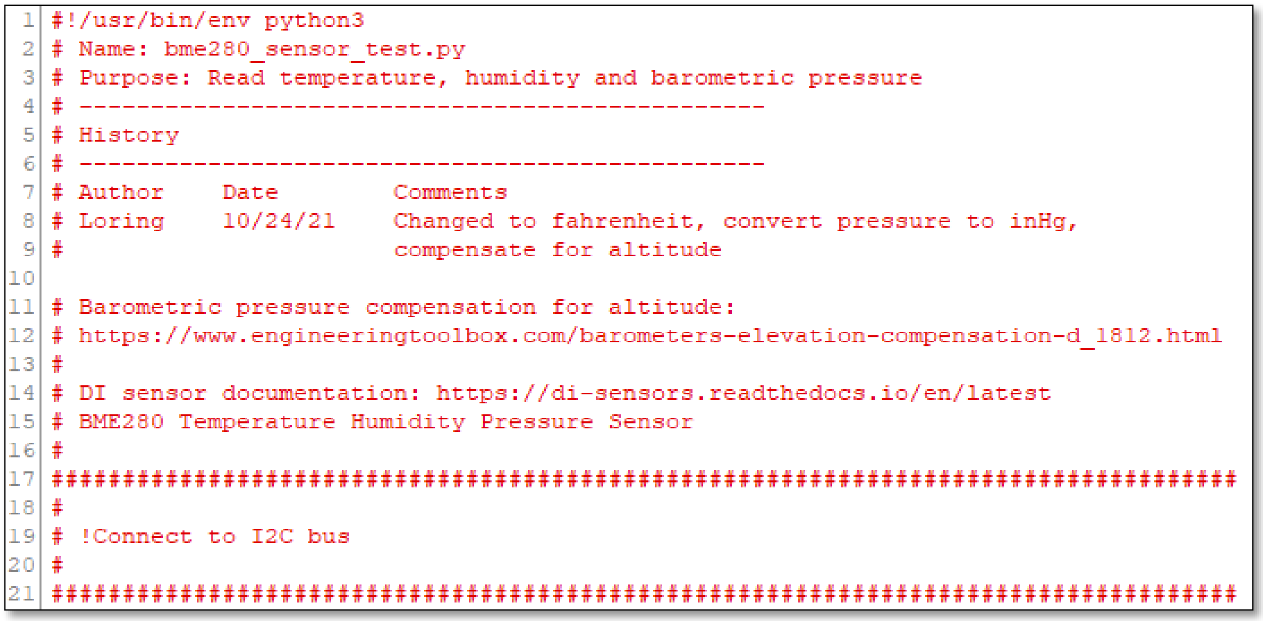
A tutorial for how to use the Dexter Temperature, Humidity Sensor (BME280).

Barometric pressure compensation for altitude:
https://www.engineeringtoolbox.com/barometers-elevation-compensation-d_1812.html

1. Shutdown the GoPiGo3. (Do not connect sensors when the GoPiGo3 has power.)
2. Plug the BME280 sensor into an I2C port.
3. Mount the sensor on a sensor mount.

bme280_sensor.py

This program will read the Dexter Temperature, Humidity Sensor (BME280) every 5 seconds and display to the console.



```
#!/usr/bin/env python3
# Name: bme280_sensor_test.py
# Purpose: Read temperature, humidity and barometric pressure
# ------------------------------------------------
# History
# ------------------------------------------------
# Author    Date        Comments
# Loring    10/24/21    Changed to fahrenheit, convert pressure to inHg,
#                       compensate for altitude

# Barometric pressure compensation for altitude:
# https://www.engineeringtoolbox.com/barometers-elevation-compensation-d_1812.html
#
# DI sensor documentation: https://di-sensors.readthedocs.io/en/latest
# BME280 Temperature Humidity Pressure Sensor
#
###################################################################################
#
# !Connect to I2C bus
#
###################################################################################
```

```python
from time import sleep
# EasyTHPSensor rounds data to 0 decimal for temp and humidty
from di_sensors.easy_temp_hum_press import EasyTHPSensor
from easygopigo3 import EasyGoPiGo3  # Import GoPiGo3 library

# Create an instance of the GoPiGo3 class
gpg = EasyGoPiGo3()

print("Example program for reading Dexter Industries")
print("Temperature Humidity Pressure Sensor on an I2C port.")

# Initialize an EasyTHPSensor object
my_thp = EasyTHPSensor()

try:
    while True:
        # Read temperature
        # temp = my_thp.safe_celsius()
        temp = my_thp.safe_fahrenheit()

        # Read relative humidity
        hum = my_thp.safe_humidity()

        # Read pressure in pascals
        press = my_thp.safe_pressure()

        # Convert pascals to inHg, compensate for 4000' altitude
        press = (press / 3386.38867) + 4.08

        # Print values to the console
        print("Temp: {:5.1f} °F  Humidity: {:5.1f}%  Pressure: {:5.2f}".format(
            temp, hum, press))

        # Pause between readings
        sleep(5)

# Except the program gets interrupted by Ctrl+C on the keyboard.
except KeyboardInterrupt:
    # Unconfigure the sensors, disable the motors,
    # and restore the LED to the control of the GoPiGo3 firmware
    gpg.reset_all()
```

Dexter Grove Buzzer

AD1 or **AD2** port

```python
#!/usr/bin/env python3
# Name: buzzer.py
# Purpose: Play the Dexter buzzer
# ------------------------------------------------
# History
# ------------------------------------------------
# Author     Date          Comments
#
# EasyGoPiGo3 documentation: https://gopigo3.readthedocs.io/en/latest
# Copyright (c) 2017 Dexter Industries Released under the MIT license

import time  # Import time library sleep function
import easygopigo3 as easy  # Import the GoPiGo3 Library
gpg = easy.EasyGoPiGo3()    # Create an instance of the GoPiGo3 class

# Create an instance of the Buzzer on port AD1
my_buzzer = gpg.init_buzzer("AD1")

# List of first few notes for Twinkle, Twinkle little start
twinkle = ["C4", "C4", "G4", "G4", "A4", "A4", "G4"]

print("Expecting a buzzer on Port AD1")
print("A4")
my_buzzer.sound(440)    # Play 440 hz
time.sleep(1)
print("A5")
my_buzzer.sound(880)    # Play 880 hz
time.sleep(1)
print("A3")
my_buzzer.sound(220)    # Play 220 hz
time.sleep(1)

# Go through list one note at a time
for note in twinkle:
    print(note)
    my_buzzer.sound(my_buzzer.scale[note])
    time.sleep(0.5)
    my_buzzer.sound_off()
    time.sleep(0.25)

my_buzzer.sound_off()
```

Dexter Light and Color Sensor

I2C port

Example code: sensor_light_color.py

Dexter Inertial Measurement Unit (IMU)

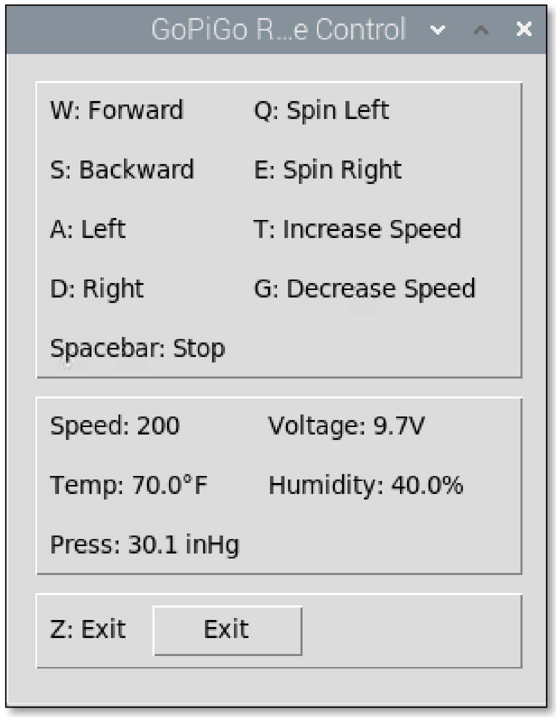
I2C port

Example code: sensor_imu.py

Sensors and Tkinter

The next step would be to send the data every 15 seconds or more to ThingSpeak. There is a tutorial to get started with that. All sensors can be setup to upload data to ThingSpeak.

The data can also be displayed in a GUI program. This is an example of a Tkinter remote control program that also displays real time data from a bme280 sensor.



W: Forward Q: Spin Left
S: Backward E: Spin Right
A: Left T: Increase Speed
D: Right G: Decrease Speed
Spacebar: Stop

Speed: 200 Voltage: 9.7V
Temp: 70.0°F Humidity: 40.0%
Press: 30.1 inHg

Z: Exit