

① We will show that 2-SAT can be solved in polynomial time.

→ construction: make a directed graph having nodes as $x_1, \bar{x}_1, x_2, \bar{x}_2, \dots, x_n, \bar{x}_n$ (variables and their negations) summing up to $2n$ total nodes.

NOTES

→ the clause $(x_i \vee x_j)$ can be rewritten as $(\bar{x}_i \Rightarrow x_j) \wedge (\bar{x}_j \Rightarrow x_i)$

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→ Now in this graph if for any i , there exists a path from x_i to \bar{x}_i and also from \bar{x}_i to x_i then both x_i and \bar{x}_i should be of same truth value in order to satisfy the constraint graph but it is a contradiction, hence the formula can't be satisfied by a valid ~~set~~ assignment of truth variables.

→ As finding the path/checking for path existence between 2 nodes is in polynomial time, $\forall i$ we will check the existence of path from x_i to \bar{x}_i and from \bar{x}_i to x_i .

→ Total checks = $2n$ (2 for each i)

Total time = $2n \cdot p(n)$ ($p(n)$ is time taken to check path existence b/w 2 nodes)
also $p(n)$ is polynomial time

\therefore 2-SAT is in P \because if 2-SAT is NP-complete every problem in NP can be reduced to 2-SAT in polynomial time $\therefore NP = P$.

②. We will show a reduction from 3-SAT to Max cut

let $3\text{-SAT} \xrightarrow{m} \text{Max-Cut}$

• first we will show reduction of 3-SAT to NAE 4-SAT

NOTES for an instance ϕ of 3-SAT, we replace each clause $x_1 \vee x_2 \vee x_3$ to NAE(x_1, x_2, x_3, \bar{x}) leading to an instance ϕ' .

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- Now let $x_1, x_2, x_3, \dots, x_n$ be a satisfying assignment to ϕ . \therefore for $\bar{z} = 0$, $x_1, x_2, \dots, x_n, 0$ is satisfying assignment ϕ' for NAE 4-SAT.
- Also, if x_1, x_2, \dots, x_n, z is satisfying assignment for NAE 4-SAT, $\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n, \bar{z}$ also satisfies.
- In one of these two solutions, $\bar{z} = 0$. This assignment corresponds to a satisfying assignment of ϕ .
- Now, we ~~show~~ show reduction of NAE 4-SAT to NAE-3SAT
 split each clause $C_i = \text{NAE}(x, y, z, w)$ to $C_i^1 = \text{NAE}(x, y, a_i)$
 and $C_i^2 = \text{NAE}(z, w, \bar{a}_i)$
 then we show reduction of NAE 3-SAT to Max-Cut
~~Max-Cut~~ $\phi_M \Rightarrow (G, c)$
- $\forall x_i$, add two nodes x_i and \bar{x}_i to G and then connect them by edge e_i of $10 \times$ total number of clauses $= 10 \cdot m$
- Now, for each clause $C_i = \text{NAE}(a, b, c)$ we add edges $a-b$ and $b-c$ and $a-c$ each of capacity 1.
~~So~~ $C = n(10m) + 2m = m(10n + 2)$
- Now if ϕ is satisfiable, \exists cut in G such that one side contains all vertices that have value 1 and other side contains all vertices with value 0 in ϕ .
- NOTES Since either x_i or \bar{x}_i is 1 in assignment, all variable edges contribute $(N \cdot 2m)$ capacity to the cut.

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- Also for each clause, exactly 2 edges go through cut as ϕ is satisfying assignment.
If G contains cut of size $n \cdot M + 2 \cdot m$
first each variable edge goes through cut as if any variable gets missed, max capacity possible is $(n-1)(10m) + 6m = 10nm - 7m < 10nm + 2m$
- Since no cut can get all 3 edges of a clause as it forms a triangle \therefore if any clause edge is missed capacity $< 10nm + 2m$
 \therefore all clauses are satisfiable \Rightarrow satisfying assignment exists.
 \therefore the reduction from 3-SAT to Max-Cut is valid.

⑤ (a) FALSE.

We will prove by contradiction.

Let $P = \text{SPACE}(n) \therefore \exists$ algorithm to simulate TM with space n in n^c ($c = \text{constant}$) time.

But, this means \exists algorithm to simulate a n^2 space TM in n^c time.

$\therefore P = \text{SPACE}(n) = \text{SPACE}(n^2)$

But by space hierarchy theorem,
 $\text{SPACE}(n) \neq \text{SPACE}(n^2)$

NOTES \therefore this is a contradiction
hence $P = \text{SPACE}(n)$ is false.

	M	T	W	T	F	S	S
O	1	2	3	4	5	6	7
C	8	9	10	11	12	13	14
T	15	16	17	18	19	20	21
	22	23	24	25	26	27	28
	29	30	31				

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(b) TRUE

$L = \{ s \mid s \text{ contains properly nested parenthesis} \}$

• L can be solved in polynomial time, let ϕ be an instance of L . Let '(' and ')' are opening and closing parenthesis.

10. Maintain $cnt = 0$ variable (having initial value $= 0$)

• Iterate ϕ from L to R starting from beginning.

12. Whenever we encounter '(' (opening parenthesis) increase cnt by 1 and when we encounter closing parenthesis decrement cnt by 1.

1. { If $cnt < 0$ at any time while iterating, reject ϕ .
2. elseif $cnt > 0$ after the iteration is complete, reject ϕ .
3. else accept ϕ . ——— ①

3. similarly, we ~~can~~ need to iterate from Right to Left
set $cnt = 0$, if we encounter ')' do $cnt++$,
4. else if we see '(' do $cnt--$.

5. apply the condition shown in ①,

6. so, L is in P and takes $O(n)$ space
and is also in $SPACE(n)$.

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③ (a) proof by contradiction

say $\exists L \in \text{NP-complete}$ and $L \in \text{coNP}$

as $L \in \text{NP-complete} \Rightarrow L \in \text{NP} \therefore L \in \text{NP} \neq \text{coNP}$

also any NP language (say L_2) can be reduced to L by using the definition of NP-complete.

\therefore All languages L_2 in NP ~~can~~ also belong to coNP as they can be reduced to L in polynomial time

$\therefore \text{NP} = \text{coNP}$

which is a contradiction hence, no NP can be in coNP.

(b) we know that for a language L in P, $\neg L$ is also in P [because P is closed under negation]

$\therefore L$ is both in NP and coNP

as $\text{NP} \neq \text{coNP}$, there exists some L which is not in P

$\Rightarrow L$ is coNP-complete $\Rightarrow L$ is in coNP

As $\text{NP} \neq \text{coNP}$,

$\exists L$ in NP but not in coNP.

④(a) Need of time-constructability is to clock the time when a machine runs for simulating the machine only for $f(n)$ steps on input of n length, using only $O(f(n))$ number of steps.

In order to do this we must be able to compute $f(n)$ value in $O(f(n))$ time.

Also, if $f(n)$ cannot be computed in $O(f(n))$ time then total runtime of machine will not be fixed and may take arbitrary values.

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