

# Timur Ismagilov

[tile24@soton.ac.uk](mailto:tile24@soton.ac.uk)

## EDUCATION

---

### University of Southampton | Oct 2024 – June 2028

PhD Researcher, Computer Science | Agents, Interaction and Complexity Research Group

In connection with Responsible AI UK, my research area is in Visual Place Recognition, Computer Vision and Robotics. I look to develop effective place recognition algorithms capable of running on resource constrained devices.

### Imperial College London | Sept 2020 - June 2024

MEng + BEng in Electronic & Information Engineering | First Class Honours

• Machine Learning • Computer Vision & Pattern Recognition • Mathematics for ML • Self-Organising Multi-Agent Systems • Deep Learning • Machine Learning for Finance • High Level Programming •

### Ibstock Place School | - July 2020

A\*A\*A\* for Maths, Physics, Further Maths at A-level

12 A\* grades at GCSE with Free Standing Maths Qualification

## PUBLICATIONS

---

**T. Ismagilov**, B. Ferrarini, M. Milford, T. V. T. Nguyen, S. Ramchurn, and S. Ehsan, "On Motion Blur and Deblurring in Visual Place Recognition", 2024, IEEE Robotics and Automation Letters. DOI: 10.1109/LRA.2025.3554103

## SKILLS

---

C++, Python, Machine Learning (TensorFlow, Keras, PyTorch, Scikit-learn)

F#, Web Development (React, NodeJS, Javascript, HTML, CSS)

Compilers, Communication Networks

## PROFESSIONAL EXPERIENCE

---

### Thruvision | Machine Learning Engineer Placement

April-October 2023 | Abingdon, Oxford

- Researched and developed specialised deep learning programs for classification and detection of concealed objects in images, using Python TensorFlow and Keras API.
- Implemented feature engineering pipeline for optimal pre-processing of data prior to use in computer vision related tasks, including image construction using depth information.
- Designed and developed a client-server platform for efficient camera data collection, efficiently integrating it with existing codebase.
- Made use of knowledge in software systems, camera models (coordinate systems and scene planes) and signals, as well as opportunities to research frontiers in computer vision.

**Skills:** Python, C++, TensorFlow, Keras, Scikit-learn, Computer Vision, Software Systems, Camera model

### Procter & Gamble | I.T Internship

July-September 2022 | Weybridge, London

- Planned, designed and implemented a Data Collection Toolkit for efficient management and organizing of Metaverse projects by the Digital Experiences Team.
- Designed and Created Video-Audio Training videos for Ambassadors use prior to public events in the Metaverse hosted by P&G.
- Saved £1000's per year and hours of time using new centralized Workflow structure.

**Skills:** Workflow Structure & Automation with SharePoint, PowerApps & Power Automate, Project Management

## PROJECTS

---

Simultaneous 6DOF Pose Estimation for Multiple Small Objects | Masters Project

### October 2023 – June 2024 | London

- Conducted extensive literature review for research of 6DOF pose estimation methods.
- Self-proposed and implemented two modifications to a state-of-the-art model: attention-enhanced feature extraction and T-GCN pose refinement – a first for this task.
- Focused on improving performance in localising small, texture-less and occluded objects seen at training time. Required extensive tuning of proposed modifications.
- Achieved marginal improvement in unseen scenes and significant improvement in seen scenes.

**Skills:** Python, PyTorch, Machine Learning, Deep Learning, Computer Vision

### Deep Learning & Kaggle | [Group/Personal Projects](#)

#### May 2021 - | London

- Developed complex parameter tuning and decision tree ensemble training algorithms for protein function prediction, achieving silver (top 5%) in first Kaggle contest with 1500+ teams.
- From scratch, derived and implemented:
  - Conv2D, BatchNorm2D, Pooling2D and Linear layers.
  - U-Net like segmentation model to perform encoding and decoding of images in brain MRI dataset, achieving 95%+ accuracy.
  - Neural network and decision tree algorithms to predict house prices in California and Wi-Fi signal strength respectively.
- Performed in-depth cross-validated hyperparameter tuning on deep CNN models on ImageNet dataset. Supported with quantitative and qualitative analysis.
- Derived mathematical foundations of Variational Auto-Encoders (VAE), implementing one for analysis on MNIST dataset.
- Researched and implemented DCGAN's and WGAN's for creation of Monet-like paintings from photos as well as CIFAR-10 image generation.
- Derived and implemented PCA, LDA, Clustering and Bagging algorithms for pattern recognition tasks involving time-series tactile data.

**Skills:** Python, Machine Learning, Computer Vision, Data Science, PyTorch, TensorFlow, MATLAB

### C to MIPS Compiler | [Pair Project](#) | [GitHub: https://github.com/itmr1/CtoMips-Compiler](https://github.com/itmr1/CtoMips-Compiler)

#### March 2022 | London

- Fundamentally, without libraries, implemented a compiler for pre-processed C90 to MIPS Assembly, including a Lexer, Parser and test suite.
- In 2000 lines of code, the compiler successfully interprets global variables, functions, expressions that are logical, assignment, relational, arithmetic and conditional statements including switches, for and while loops and jump statements.

**Skills:** C, C++, OOP, MIPS Assembly Language, Compiler Design

### Mars Rover | [Group Project](#) | [GitHub: https://github.com/itmr1/Mars\\_Rover\\_Group23](https://github.com/itmr1/Mars_Rover_Group23)

#### May 2022 | London

- Worked in a team of 6 to deliver 7 critical sub-systems of a Mars Rover, with primary responsibility of the Command sub-system.
- Coordinated with team to create a system of web applications and database to receive and display raw data (Obstacles, Battery, Location), as well as send movement commands to Rover FPGA.
- Implemented A-star algorithm to find an optimal path around obstacles and enable autonomous movement.

**Skills:** JavaScript, C++, React JS, Node JS, SQL, CSS, Web Application Development, Project Management

### MIPS CPU | [Group Project](#) | [GitHub: https://github.com/itmr1/MIPS\\_CPU](https://github.com/itmr1/MIPS_CPU)

#### November 2021 | London

- Created a working Bus-based interface 32-bit CPU Using Icarus Verilog, executing over 150 Instructions.
- Used shell scripting to create a compiler and test-bench against other Verilog MIPS CPU's.
- Included filtering in test-bench script for optimised testing user interface.

**Skills:** Verilog, Shell Scripting, Computer Architecture, Project Management

### ISSIE | [Solo & Group Project](#) | [GitHub: https://github.com/tomcl/issie](https://github.com/tomcl/issie)

#### February 2023 | London

- Issie is a digital circuit design simulator written in F# and consisted of over 40,000 lines of code when I began work on it, requiring quick familiarisation of its implementation in this language.

- Successfully implemented a completely new interface to support my new scaling, flipping and rotation features, as well as a new distinctive style of logical components. My design was chosen to be integrated into production.
- Regularly coordinated with team to avoid redundant code and integrate our features together.

**Skills:** F#, Codebase proficiency, Teamwork