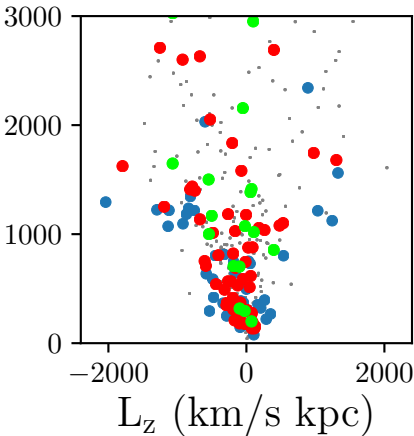


L_{\perp} (km/s kpc)



L_z (km/s kpc)