CNN-Based Image Classification on CIFAR-10 Dataset

Abdullah Farooq, Executive Member, ACM, Ammar Ahmad, Undergrad Junior, GIKI, and Bilal Malik, Undergrad Junior, GIKI

Abstract:

This report presents a comprehensive approach to implementing a Convolutional Neural Network (CNN) for image classification using Python's Keras library. It describes the process of loading, visualizing, and preprocessing the CIFAR-10 dataset, followed by the design and training of multiple variants of a CNN model. Each model is evaluated on various performance metrics, with comparisons based on performance scores.

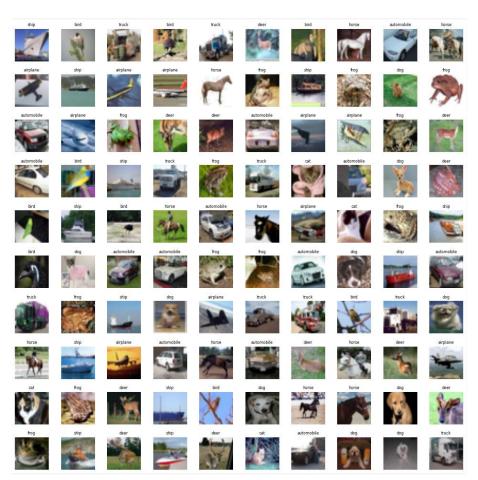
Introduction:

The CIFAR-10 dataset comprises 60,000 color images of size 32x32 pixels, evenly distributed across ten distinct classes. The main goal is to develop an accurate multiclassification model to classify these images effectively.

Methodology:

1. Data Loading & Visualization:

Initially, the CIFAR-10 dataset is loaded using the Keras library, followed by some preliminary visualization of sample images and class distribution.



2. Data Preprocessing:

The raw images are preprocessed by normalizing pixel values and implementing one-hot encoding on target labels.

3. Model Building & Training:

Five distinct models are built to compare the effects of different architectural decisions and techniques.

- 1. A simple Neural Network model.
- 2. A primary Convolutional Neural Network (CNN) model.
- 3. A CNN model with Dropout layers to prevent overfitting.
- 4. A CNN model with BatchNormalization layers to accelerate learning and further prevent overfitting.
- 5. An augmented CNN model with BatchNormalization and Dropout layers, trained using Adam optimizer and data augmentation techniques.

The models are trained for 15 epochs using a batch size of 32 and a training-validation split of 80-20.

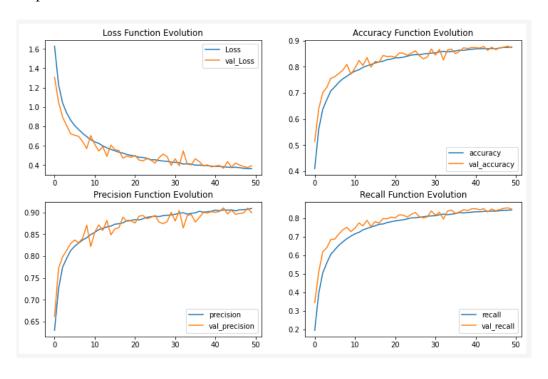
Model: "sequential"		
Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 32, 32, 32)	896
batch_normalization (BatchNo	(None, 32, 32, 32)	128
conv2d_1 (Conv2D)	(None, 32, 32, 32)	9248
batch_normalization_1 (Batch	(None, 32, 32, 32)	128
max_pooling2d (MaxPooling2D)	(None, 16, 16, 32)	0
dropout (Dropout)	(None, 16, 16, 32)	0
conv2d_2 (Conv2D)	(None, 16, 16, 64)	18496
batch_normalization_2 (Batch	(None, 16, 16, 64)	256
conv2d_3 (Conv2D)	(None, 16, 16, 64)	36928
batch_normalization_3 (Batch	(None, 16, 16, 64)	256
max_pooling2d_1 (MaxPooling2	(None, 8, 8, 64)	0
Total params: 552,362		
Trainable params: 551,466		
Non-trainable params: 896		

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1562/1562 [================= ] - 38s 20ms/step - loss: 1.6282 - accuracy: 0.4095 - precision: 0.6303
Epoch 2/50
Epoch 3/50
1562/1562 [================== ] - 30s 19ms/step - loss: 1.0423 - accuracy: 0.6369 - precision: 0.7746
Epoch 4/50
1562/1562 [============== ] - 31s 20ms/step - loss: 0.9402 - accuracy: 0.6734 - precision: 0.7946
Epoch 5/50
1562/1562 [=
     Epoch 6/50
1562/1562 [=
      =========================== ] - 30s 19ms/step - loss: 0.8097 - accuracy: 0.7230 - precision: 0.8225
Epoch 7/50
1562/1562 [=
      1562/1562 [=
     Epoch 9/50
Epoch 10/50
1562/1562 [===
      Fnoch 11/50
Epoch 12/50
1562/1562 [=
        Epoch 13/50
Epoch 49/50
        ========= ] - 30s 19ms/step - loss: 0.3646 - accuracy: 0.8738 - precision: 0.9070
1562/1562 [=
1562/1562 [================== ] - 30s 19ms/step - loss: 0.3649 - accuracy: 0.8755 - precision: 0.9091
```

Model Training

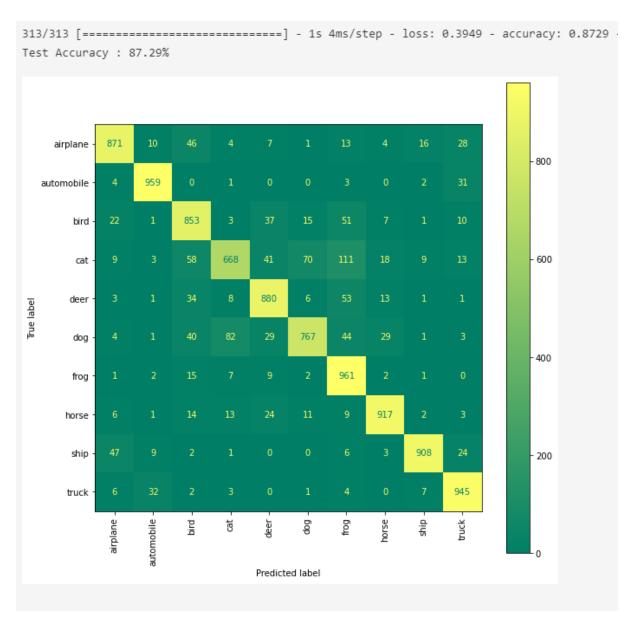
4. Model Evaluation:

After training, the models' performances are evaluated using accuracy as a metric on the test dataset. The training and validation loss curves are plotted to analyze the models' learning over the epochs.



Results:

The model evaluation results are tabulated, demonstrating how each model variant performed in terms of accuracy on the test dataset. Further, critical insights derived from the loss curves of each model are discussed.



Conclusion:

This report showcased the development of a CNN-based image classification model using the CIFAR-10 dataset. The model-building process underlined the significant roles of data preprocessing, careful architectural decisions, and regularization techniques in achieving a robust and accurate model. The comparison of different models' performance provided vital insights into the benefits of various CNN enhancements, ultimately leading to the selection of the optimal model configuration.

Reference(s):

- https://www.cs.toronto.edu/~kriz/cifar.html