

The top level of the plant is a variant subsystem which is used to switch between plant configurations. It is depicted in Figure ??.

The possible plant configurations are:

- Actual hardware drivers. [Hardware implementation only.]
- Hardware-equivalent model of nonlinear dynamics. [Simulation only.]
- Hardware-equivalent model of linear dynamics. [Simulation only.]

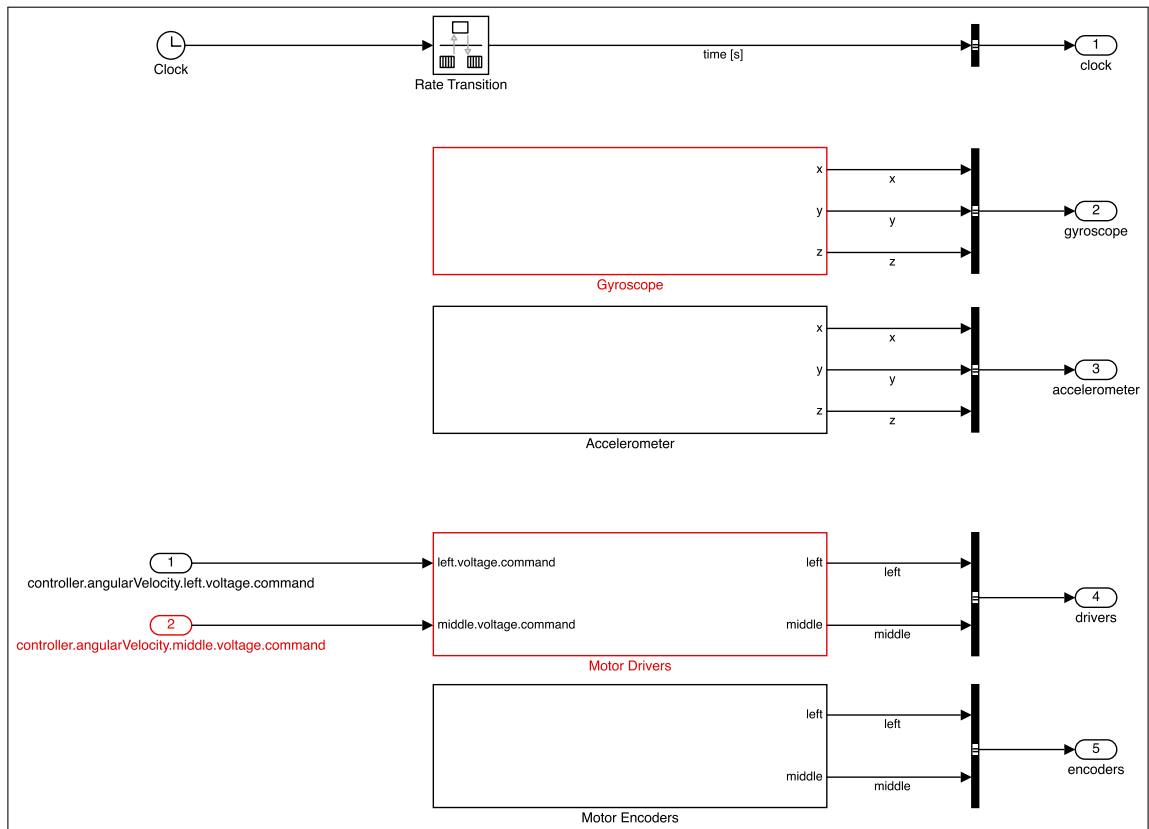


Figure 0.1: [minseg_M2V3_2017a]: Plant