

The selection of hardware consists of selecting:

- A specific device to serve as the plant with respect to the designated control problem.

*[MinSeg two-wheeled robot.]*

- A specific device to serve as the controller with respect to the designated control problem.

*[Arduino Mega2560 single-board microcontroller, included with MinSeg two-wheeled robot.]*

- A specific computer to be used to interface with the controller.

*[Available laptop installed with Mathworks Software Suite and supporting software.]*