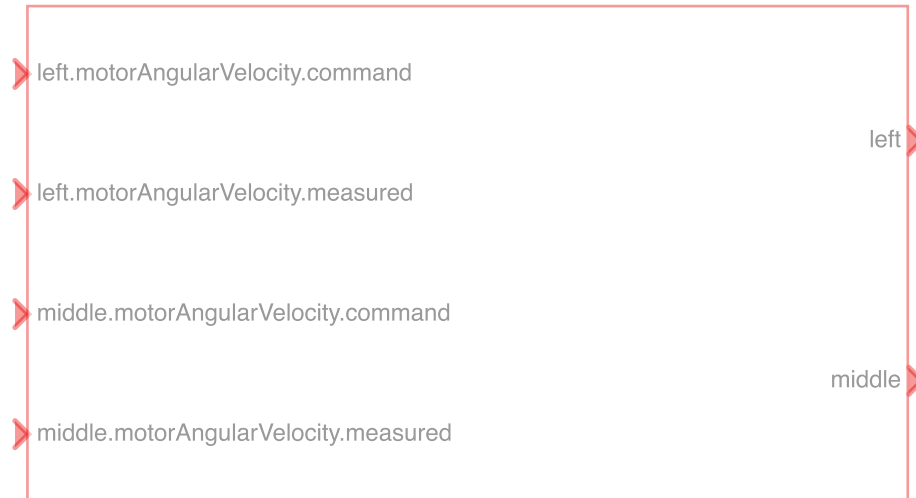
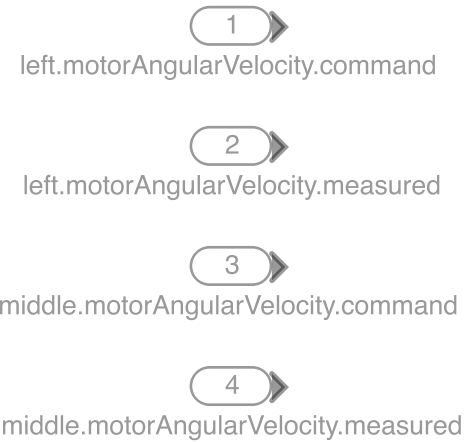


Feed-Forward
Input: Motor Voltage



PID
Input: Motor Angular Velocity

