Numerical Analysis for Partial Differential Equations

Andrea Bonifacio

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1 Boundary Value Problems

1.1 Weak Formulation

Let's consider a problem

$$\begin{cases} \mathcal{L}u = f & \text{in } \Omega \\ +\text{B.C.} & \text{on } \partial\Omega \end{cases} \tag{1.1}$$

- Ω: open bounded domain in $\mathbb{R}^d$, with $d = 2, 3$
- $\partial\Omega$: boundary of Ω
- f: given
- B.C. accordingly to $\mathcal{L}$
- $\mathcal{L}$: 2^{nd} order operator, like:

  (1) $\mathcal{L}u = -\text{div}(\mu\nabla u) + \mathbf{b} \cdot \nabla u + \sigma u$ (non-conservative form)

  (2) $\mathcal{L}u = -\text{div}(\mu\nabla u) + \text{div}(\mathbf{b}u) + \sigma u$ (conservative form)

  - $\mu \in L^\infty(\Omega), \quad \mu(\mathbf{x}) \geq \mu_0 > 0$ uniformly bounded from below
  - $\mathbf{b} \in (L^\infty(\Omega))^d$ transport term
  - $\sigma \in L^2(\Omega)$ reaction term
  - $f \in L^2(\Omega)$ can be less regular

General elliptic problems

Consider

$$\begin{cases} -\text{div}(\mu\nabla u) + \mathbf{b} \cdot \nabla u + \sigma u = f & \text{in } \Omega \\ u = 0 & \text{on } \Gamma_D \\ \mu\nabla u \cdot \mathbf{n} = g & \text{on } \Gamma_N \end{cases} \qquad \begin{array}{l} g \in L^2(\Gamma_N) \\ \partial\Omega = \Gamma_D \cup \Gamma_N \\ {\Gamma_D}^{\circ} \cap {\Gamma_N}^{\circ} = \varnothing \end{array} \tag{1.2}$$

Suppose that $f \in L^2(\Omega)$ and $\mu, \sigma \in L^\infty(\Omega)$. Also suppose that $\exists\ \mu_0 > 0$ s.t. $\mu(\mathbf{x}) \geq \mu_0$, and $\sigma(\mathbf{x}) \geq 0$ a.e. on Ω. Then, given a test function v, we multiply the equation by v, and integrate on the domain Ω

$$\int_\Omega [-\text{div}(\mu\nabla u) + \mathbf{b} \cdot \nabla u + \sigma u]\, v = \int_\Omega fv$$

By applying Green's formula

$$\underbrace{\int_\Omega \mu\nabla u \cdot \nabla v + \int_\Omega \mathbf{b} \cdot \nabla uv + \int_\Omega \sigma uv}_{=:a(u,v)} = \int_\Omega fv + \underbrace{\int_{\Gamma_D} \mu\nabla u \cdot \mathbf{n}v}_{=0 \text{ if } v|_{\Gamma_D}=0} + \int_{\Gamma_N} \underbrace{\mu\nabla u \cdot \mathbf{n}}_{=g}\, v$$

So the weak formulation of the problem is

$$\begin{cases} \text{Find } u \in V & V = \{v \in H^1(\Omega), v|_{\Gamma_D} = 0\} =: H^1_{\Gamma_D}(\Omega) \\ a(u,v) = \langle F, v\rangle & \forall\ v \in V \end{cases} \tag{1.3}$$

where $a : V \times V \to \mathbb{R}$ is a bilinear form and $F : V \to \mathbb{R}$ is a linear form s.t. $\langle F, v\rangle \equiv F(v) = \int_\Omega fv + \int_{\Gamma_N} gv$.

Theorem 1.1 (Lax-Milgram)
Assume that

- V Hilbert space with $\|\cdot\|$ and inner product $(\cdot,\cdot)$
- $F \in V^* : |F(v)| \leq \|F\|_{V^*}\|v\| \ \forall\, v \in V$
- a continuous: $\exists\, M > 0 : |a(u,v)| \leq M\|u\|\,\|v\| \ \forall\, u, v \in V$
- a coercive: $\exists\, \alpha > 0 : a(v,v) \geq \alpha\|v\|^2 \,\forall\, v \in V$

Then, there exists a unique solution u of 1.3

Moreover

$$\alpha\|u\|^2 \leq a(u,u) = F(u) \leq \|F\|_{V^*}\|u\|$$

where α is the coercivity costant. Hence

$$\|u\| \leq \frac{\|F\|_{V^*}}{\alpha} \to \text{stability/continuous dependence on data}$$

But what if some of the assumptions of Lax-Milgram (in particular coercivity) are not satisfied?
We need a slightly more general problem to formulate Nečas theorem:

$$\begin{cases} \text{find } u \in V \\ a(u,w) = \langle F, w\rangle \quad \forall w \in W \end{cases} \tag{1.4}$$

They belong to different spaces: W for the test function, V the solutions
Theorem 1.2 (Nečas)
Assume that $F \in W^*$. Consider the following conditions:

- a continuous: $\exists\, M > 0 : |a(u,w)| \leq M\|u\|_V\|w\|_W \,\forall\, u \in V, w \in W$
- $\inf - \sup$ condition: $\exists\, \alpha > 0 : \forall\, v \in V \quad \sup_{w\in W\setminus\{0\}} \frac{a(v,m)}{\|w\|_W} \geq \alpha\|v\|_V$
- $\forall\, w \in W, w \neq 0, \exists\, v \in V : a(v,w) \neq 0$

These conditions are necessary and sufficient for the existence and uniqueness of a solution of 1.4, for any $F \in W^*$. Moreover

$$\|u\|_V \leq \frac{1}{\alpha}\|F\|_{W^*}$$

When $W = V$ Lax-Milgram provides necessary and sufficient conditions for existence and uniqueness of solutions.
Going back to

$$\begin{cases} \mathcal{L}u = f & \text{in } \Omega \\ +\text{B.C.} & \text{on } \partial\Omega \end{cases}$$

What could be our choice of V? Given that

$$u \in V : a(u,v) = F(v) \quad \forall\, v \in V$$

and

$$a(u,v) = \int_\Omega \mu \underbrace{\nabla u \nabla v}_{\nabla u, \nabla v \in L^2} + \int_\Omega b\underbrace{\nabla u v}_{\in L^1} + \int_\Omega \sigma \underbrace{uv}_{\in L^1}$$

We want to choose v in order to have all of these integrable

$$\Rightarrow V = \left\{ v \in L^2(\Omega), \nabla u \in \left[L^2(\Omega)\right]^d, v|_{\Gamma_D} = 0 \right\} = V_{\Gamma_D}$$

.
Knowing that a Sobolev space

$$H^1 = \left\{ v \in L^2(\Omega), \nabla u \in \left[L^2(\Omega)\right]^d \right\}$$

we can say $V_{\Gamma_D} = \{v \in H^1(\Omega) : v|_{\Gamma_D} = 0\}$, and if $\Gamma_D = \partial\Omega$, then $V_{\Gamma_D} = H_0^1$

1.2 Approximation

Recall for a moment the weak formulation of a generic elliptic problem

$$\begin{cases} \text{Find } u \in V \\ a(u, v) = \langle F, v \rangle \quad \forall\, v \in V \end{cases} \tag{1.5}$$

with V being an appropriate Hilbert space, subset of $H^1()$, $a(\cdot, \cdot)$ being a continuous and coercive bilinear forrm from $V \times V \to \mathbb{R}$, $F(\cdot)$ being a continuous linear functional from $V \to \mathbb{R}$.
Let $V_h \subset V$ be a family of spaces that depends on a parameter $h > 0$, such that $\dim V_h = N_h < \infty$. We can rewrite the weak formulation

$$\begin{cases} \text{Find } u_h \in V_h \\ a(u_h, v_h) = \langle F, v_h \rangle \quad \forall\, v_h \in V_h \end{cases} \tag{1.6}$$

and is called a **Galerkin problem**. Denoting with $\{\varphi_j, j = 1, 2, \ldots, N_h\}$ a basis of V_h, it is sufficient that the (1.6) is verified for each function of the basis. Also we need that

$$a(u_h, \varphi_i) = F(\varphi_i) \quad i = 1, 2, \ldots, N_h$$

Since $u_h \in V_h$

$$u_h(\mathbf{x}) = \sum_{j=1}^{N_h} u_j \varphi_j(\mathbf{x})$$

where u_j are unknown coefficients. Then

$$\sum_{j=1}^{N_h} u_j a(\varphi_j, \varphi_i) = F(\varphi_i)$$

We denote by A the matrix made by $a_{ij} = a(\varphi_j, \varphi_i)$ and $\mathbf{f}$ the vector of $F(\varphi_i) = f_i$ components. If we denote the vector $\mathbf{u}$ made by the unknown coefficients u_h.

$$A\mathbf{u} = \mathbf{f} \tag{1.7}$$

Theorem 1.3
The stiffness matrix A associated to the Galerkin discretization of an elliptic problem, whose bilinear form is coercive is positive definite.

***Proof*.** Recall that a matrix $B \in \mathbb{R}^{n \times n}$ is said to be positive definite if

$$\mathbf{v}^T B \mathbf{v} \geq 0 \quad \forall\, \mathbf{v} \in \mathbb{R}^n$$

and

$$\mathbf{v}^T B \mathbf{v} = 0 \Leftrightarrow \mathbf{v} = \mathbf{0}$$

The correspondence

$$\mathbf{v} = (v_i) \in \mathbb{R}^{N_h} \longrightarrow v_h(x) = \sum_{j=1}^{N_h} v_j \varphi_j \in V_h$$

defines a bijection between V_h and $\mathbb{R}^{N_h}$. Given a generic vector $\mathbf{v} = (v_i)$ of $\mathbb{R}^{N_h}$, thanks to the bilinearity and coercivity of a we obtain

$$\begin{aligned}
\mathbf{v}^T A \mathbf{v} &= \sum_{j=1}^{N_h} \sum_{i=1}^{N_h} v_i a i_j v_j \\
&= \sum_{j=1}^{N_h} \sum_{i=1}^{N_h} v_i a(\varphi_j, \varphi_i) v_j \\
&= \sum_{j=1}^{N_h} \sum_{i=1}^{N_h} a(v_j \varphi_j, v_i \varphi_i) \\
&= a \left(\sum_{j=1}^{N_h} v_j \varphi_j \sum_{i=1}^{N_h} v_i \varphi_i \right) \\
&= a(v_h, v_h) \geq \alpha \|v_h\|_V^2 \geq 0
\end{aligned}$$

Moreover, if $\mathbf{v}^T A \mathbf{v} = 0$, then $\|v_h\|_V^2 = 0$. ★

Existence and uniqueness

Corollary 1.1
The solution of the Galerkin problem (1.6) exists and is unique.

To prove this we can prove that the solution to (1.7) exists and is unique.