Reminders for NAPDE

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June 13, 2023

Reminders on calculus

$$\int_{\Omega} -\Delta u v = \int_{\Omega} \nabla u \cdot \nabla v - \underbrace{\int_{\Gamma_D} \nabla u \cdot \mathbf{n} v}_{=0 \text{ if } v|_{\Gamma_D} = 0}$$

$$\int_{\Omega} \operatorname{div} u = \int_{\partial \Omega} u \cdot \mathbf{n}$$

$$-\int_{\Omega} \mathbf{v} \cdot \nabla p = \int_{\Omega} p \operatorname{div} \mathbf{v} + \int_{\partial \Omega} \mathbf{v} \cdot \mathbf{n} p$$

$$\int_{\Omega} \frac{\partial}{\partial x} u^2 = \frac{1}{2} \int_{\partial \Omega} u \cdot \mathbf{n}$$

Lifting Operators

If u on $\partial\Omega$ is non null, we need to solve this problem, otherwise we cannot use test functions that vanish at the boundary. To do so, given u=g on $\partial\Omega$ we use a lifting operator $Rg\in H^1(\Omega):Rg|_{\partial\Omega}=g$, and modify our solution such that $u=\overset{\circ}{u}+Rg$, so the function $\overset{\circ}{u}$ has the properties we need. We then look for bilinear formulation such as $a(\overset{\circ}{u},v)$ and add to the right hand side -a(Rg,v).

Weak Formulations

Elliptic equations

$$\begin{cases} -\operatorname{div}(\mu\nabla u) + \mathbf{b} \cdot \nabla u + \sigma u = f & \text{in } \Omega \quad g \in L^2(\Gamma_N) \\ u = 0 & \text{on } \Gamma_D \quad \partial \Omega = \Gamma_D \cup \Gamma_N \\ \mu\nabla u \cdot \mathbf{n} = g & \text{on } \Gamma_N \quad \Gamma_D{}^{\mathrm{o}} \cap \Gamma_N{}^{\mathrm{o}} = \varnothing \end{cases}$$

$$\downarrow \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad$$

Parabolic equations

$$\begin{cases} \frac{\partial u}{\partial t} - \nu \frac{\partial^2 u}{\partial x^2} = f & 0 < x < d, t > 0 \\ u(x,0) = u_0(x) & 0 < x < d \\ u(0,t) = u(d,t) = 0 & t > 0 \end{cases}$$

$$\downarrow \qquad \qquad \downarrow$$

$$\int_{\Omega} \frac{\partial u(t)}{\partial t} v \, d\Omega + a(u(t),v) = \int_{\Omega} f(t) v \, d\Omega \quad \forall \ v \in V$$

for each t > 0, we need to find $u_h(t) \in V_h$ s.t.

$$\int_{\Omega} \frac{\partial u_h(t)}{\partial t} v_h \, d\Omega + a(u_h(t), v_h) = \int_{\Omega} f(t) v_h \, d\Omega \quad \forall \ v_h \in V_h$$

Numerical formulation

Continuous Galerkin

space
$$V_h = \{v_h \in \mathcal{C}^0(\overline{\Omega}) : v_h|_{\mathcal{K}} \in \mathbb{P}^r(\mathcal{K}) \ \forall \ \mathcal{K} \in \mathcal{T}_h, v_h|_{\Gamma_D} = 0\}$$

find $u_h \in V_h : a(u_h, v_h) = F(v_h) \quad \forall \ v_h \in V_h$

Discontinuous Galerkin

SEM-NI

space
$$X_{\delta} = \left\{ v_{\delta} \in \mathcal{C}^{0}(\Omega) : v|_{\mathcal{K}} = \hat{v}_{\delta} \circ \mathbf{F}_{\mathcal{K}}^{-1}, \text{ with } \hat{v}_{\delta} \in \mathbb{Q}_{p}(\hat{\mathcal{K}}) \ \forall \ \mathcal{K} \in \mathcal{T}_{h} \right\}$$

$$\text{find } u_{\delta} \in X_{\delta} : a_{\delta}(u_{\delta}, v_{\delta}) = F_{\delta}(v_{\delta}) \quad \forall \ v_{\delta} \in X_{\delta}$$

Code implementation

CG-FEM

• Matrix A;

$$A_{ij} = \int_{\Omega} \nabla \varphi_j \nabla \varphi_i$$

Loop on all the elements and compute locally (elements with $\hat{\cdot}$ are computed on the reference element):

$$A_{loc_{ij}} = \det(\mathbf{B}_{\mathcal{K}}) \int_{\hat{\mathcal{K}}} \hat{\nabla} \hat{\varphi}_{j}^{T} \mathbf{B}_{\mathcal{K}}^{-1} \mathbf{B}_{\mathcal{K}}^{-1} \hat{\nabla} \hat{\varphi}_{i} = \frac{\det(\mathbf{B})}{2} \hat{\nabla} \hat{\varphi}_{j}^{T} \mathbf{B}_{\mathcal{K}}^{-1} \mathbf{B}_{\mathcal{K}}^{-T} \hat{\nabla} \hat{\varphi}_{i}$$

Can be implemented as

• Mass matrix M:

$$M_{ij} = \int_{\Omega} \varphi_j, \varphi_i$$

Loop on all the elements and calculate the local mass matrix

$$M_{loc_{ij}} = \det(\mathbf{B}_{\mathcal{K}}) \int_{\hat{\mathcal{K}}} \hat{\varphi}_{j}^{T} \hat{\varphi}_{i}$$

Can be implemented as

 \bullet Transport matrix T

Can be implemented as

• Right hand side **b**:

$$b_i = \int_{\Omega} f \varphi_i$$

which is computed

```
function [f]=C_loc_rhs2D(force,dphiq,BJ,w_2D,pphys_2D,nln,mu)
f = zeros(nln,1);
x = pphys_2D(:,1);
y = pphys_2D(:,2);
F = eval(force);
for s = 1:nln
    for k = 1:length(w_2D)
        Jdet = det(BJ(:,:,k)); % determinant
        f(s) = f(s) + w_2D(k)*Jdet*F(k)*dphiq(1,k,s);
    end
end
```

Convergence rates

Navier-Stokes

In case of inf-sup (LBB) condition satisfied by V and Q

$$\|\mathbf{u} - \mathbf{u}_h\|_V + \|p - p_h\|_Q \le C(\alpha_h, \beta_h, \gamma, \delta) \left\{ \inf_{\mathbf{v}_h \in V_h} \|\mathbf{u} - \mathbf{v}_h\|_V + \inf_{q_h \in Q_h} \|p - q_h\|_Q \right\}$$

where

- α_h is the coercivity constant on the subspace V_h of divergence free velocities
- β_h is the LBB constant
- γ is the continuity constant of $a(\cdot, \cdot)$
- δ is the continuity constant of $b(\cdot, \cdot)$

In case of Taylor-Hoods elements

$$\|\mathbf{u} - \mathbf{u}_h\|_V + \|p - p_h\|_Q \le Ch(\|\mathbf{u}\|_{H^{k+1}} + \|p\|_{H^k})$$