

- Q.26 Explain the elements of process control with diagram. (CO-3)
- Q.27 Explain that the maximum power is contained in the carrier of amplitude modulated signal. (CO-5)
- Q.28 Define modulation. What is the need of modulation? (CO-2)
- Q.29 Compare analog and digital modulation. (CO-2)
- Q.30 Classify the AM transmitter on the basis of type of service involved. (CO-4)
- Q.31 Explain Vestigial Side Band system of modulation. (CO-4)
- Q.32 Explain ASK modulator with the help of its waveforms. (CO-5)
- Q.33 Draw block diagram of FHSS system and explain it. (CO-6)
- Q.34 Explain the frequency discrimination method of SSBSC generation. (CO-5)
- Q.35 Define the terms sensitivity and selectivity of receivers. (CO-4)

Section-D

- Note:** Long answer questions. Attempt any two questions out of three Questions. (2x10=20)
- Q.36 Explain the principle of operation and constructional details of solenoid valve. (CO-3)
- Q.37 Draw and explain the block diagram of FM super heterodyne radio receiver. (CO-5)
- Q.38 What are different digital modulation techniques? Also compare them. (CO-6)

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Sem- 5 Mechatronics Sub : Process Control & Data Communication

Time : 3 Hrs.

M.M. : 100

SECTION-A

- Note:** Multiple Choice Questions. All Questions are compulsory. (10x1=10)
- Q.1 Control system in which the output has no effect on the control action of the input signal is known as: (CO-1)
- Closed loop control system
 - Open loop control system
 - Automatic control system
 - Optimal control system
- Q.2 _____ are usually difficult to treat mathematically and there are no general methods available for solving a wide class of these systems: (CO-2)
- None linear control systems
 - Time invariant control systems
 - Time varying control systems
 - Linear control systems
- Q.3 The function of this element is to manipulate the signal presented to it preserving the original nature of the signal. (CO-1)
- Data presentation element
 - Variable conversion element
 - Primary sensing element
 - Variable manipulation element
- Q.4 Radar tracking systems, missile tracking systems

and machine tool position control are applications of _____. (CO-3)

- a) AC Closed loop control system
 - b) DC closed loop control system
 - c) A position control system
 - d) Automatic tank level control system
- Q.5 The controller required to handle fast process load changes is: (CO-4)
- a) PD controller
 - b) PI controller
 - c) PID controller
 - d) None of the above
- Q.6 The process of superimposing a single on the carrier wave is called: (CO-1)
- a) Transmission
 - b) Communication
 - c) Modulation
 - d) Demodulation
- Q.7 In a modulation system, if modulating frequency is doubled, the modulation index also becomes double, the system is (CO-2)
- a) FM
 - b) AM
 - c) PM
 - d) None of these
- Q.8 The useful power in amplitude modulation is carried by _____. (CO-2)
- a) Side bands
 - b) Carriers
 - c) Signals
 - d) Both A & C
- Q.9 In _____ shift keying the carrier frequency is shifted in steps corresponding to the levels of the digital modulating signal. (CO-3)
- a) Amplitude
 - b) Frequency
 - c) Phase
 - d) Carrier
- Q.10 In _____ spread spectrum the carrier hops randomly from one frequency to another frequency. (CO-4)

- a) Frequency hopping
- b) Direct sequence
- c) Both A & b
- d) None of these

Section-B

Note: Objective type questions. All questions are compulsory. (10x1=10)

- Q.11 Define control system. (CO-1)
- Q.12 Define LTI control system. (CO-1)
- Q.13 Write the example of open loop control system. (CO-2)
- Q.14 Write is an offset in control system? (CO-2)
- Q.15 what is a feed-forward control? (CO-4)
- Q.16 DSB-SC stands for? (CO-2)
- Q.17 Modulation index = ____ / _____. (CO-3)
- Q.18 Write one advantage of digital modulation. (CO-4)
- Q.19 QPSK stands for? (CO-2)
- Q.20 Which oscillator is used in transmitter? (CO-5)

Section-C

Note: Short answer type Question. Attempt any Twelve questions out of Fifteen Questions. (12x5=60)

- Q.21 Write comparison between time varying and time invariant system. (CO-2)
- Q.22 Write short note on continuous and discrete time control systems. (CO-1)
- Q.23 Explain proportional controller with suitable diagram. (CO-1)
- Q.24 Explain the response of proportional derivative to step test signal. (CO-3)
- Q.25 Explain the principle of operation and construction of piston operated valve. (CO-5)