

- Q.29 Explain split range control system with the help of an example.
- Q.30 Write any one application of feedforward control system
- Q.31 Explain the concept of degree of freedom
- Q.32 Write five differences between linear and nonlinear control system
- Q.33 Explain any two nonlinearities in control system
- Q.34 Explain the concept of jump resonance with the help of diagram
- Q.35 Write five applications of robotics

SECTION-D

- Note:** Long answer type questions. Attempt any two questions out of three questions. (2x10=20)
- Q.36 Explain the computational softwares used in the field of instrumentation and control
- Q.37 Describe the concept of ratio control system with the help of an example
- Q.38 Write eight differences between open and closed loop control system

No. of Printed Pages : 4
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181544/121544/031544

4th Sem / Instrumentation & Control Engg. Subject:- Advanced Control System

Time : 3Hrs.

M.M. : 100

SECTION-A

Note: Multiple choice questions. All questions are compulsory (10x1=10)

- Q.1 Artificial Intelligence has its expansion in the following application.
- Planning and Scheduling
 - Game playing
 - Robotics
 - All of the above
- Q.2 MATLAB is used for
- Analyze data
 - Develop algorithms
 - Matrix manipulations
 - All are correct
- Q.3 Which part of robot provides motion to the manipulator and end-effector
- Sensor
 - Controller
 - Actuator
 - All are correct
- Q.4 Neural Networks are complex _____ with many parameters.

- a) Linear Functions b) Nonlinear Functions
 - c) Discrete Functions d) Exponential Functions
- Q.5 MATLAB is the known as
- a) Matrix Laboratory b) Mathematics
 - c) Material Science d) None of these
- Q.6 In an open loop control system
- a) Feedback is present
 - b) Feedback is absent
 - c) Error detector is present
 - d) None of these
- Q.7 Limit cycle is a behavior shown by
- a) Linear system b) Non linear system
 - c) Signal flow graph d) Block diagram
- Q.8 Applications of robotics are
- a) Assembling b) dismantling
 - c) Welding d) All of these
- Q.9 Following are robotic arm configuration
- a) Cartesian b) Cylindrical
 - c) Spherical d) All of these
- Q.10 Accurate and reliable output is possible with which of the following system
- a) Open loop control system
 - b) Closed loop control system
 - c) Both 1 and 2
 - d) None of these

SECTION-B

Note: Objective type questions. All questions are compulsory. (10x1=10)

- Q.11 Expand AI
- Q.12 Write two applications of Fuzzy Logic
- Q.13 Define feedback
- Q.14 Block diagram of cascade control has three loops. (True/False)
- Q.15 Expand ANN
- Q.16 Name two computational software
- Q.17 Define hysteresis
- Q.18 Neuro-fuzzy system is combination of _____
- Q.19 Write two applications of artificial intelligence
- Q.20 Write two examples of multi loop control system

SECTION-C

Note: Short answer type questions. Attempt any twelve questions out of fifteen questions. (12x5=60)

- Q.21 Explain the concept of Fuzzy Logic Control System
- Q.22 Write a short note on SCADA software
- Q.23 Explain classification of nonlinearities
- Q.24 Write five differences between feedback and feedforward control system
- Q.25 Tell five advantages of cascade control system
- Q.26 Write a short note on Multiloop control system
- Q.27 Explain the concept of Artificial intelligence
- Q.28 Write five applications of Artificial Neural Network