

- Q.29 Explain split range control system with the help of an example.
 - Q.30 Write any one application of feedforward control system
 - Q.31 Explain the concept of degree of freedom
 - Q.32 Write five differences between linear and nonlinear control system
 - Q.33 Explain any two nonlinearities in control system
 - Q.34 Explain the concept of jump resonance with the help of diagram
 - Q.35 Write five applications of robotics

SECTION-D

Note: Long answer type questions. Attempt any two questions out of three questions. (2x10=20)

- Q.36 Explain the computational softwares used in the field of instrumentation and control
 - Q.37 Describe the concept of ratio control system with the help of an example
 - Q.38 Write eight differences between open and closed loop control system

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4th Sem / Instrumentation & Control Engg.

Subject:- Advanced Control System

Time : 3 Hrs.

M.M. : 100

SECTION-A

Note: Multiple choice questions. All questions are compulsory (10x1=10)

- Q.1 Artificial Intelligence has its expansion in the following application.

 - a) Planning and Scheduling
 - b) Game playing
 - c) Robotics
 - d) All of the above

Q.2 MATLAB is used for

 - a) Analyze data
 - b) Develop algorithms
 - c) Matrix manipulations
 - d) All are correct

Q.3 Which part of robot provides motion to the manipulator and end-effector

 - a) Sensor
 - b) Controller
 - c) Actuator
 - d) All are correct

Q.4 Neural Networks are complex _____ with many parameters.

- a) Linear Functions b) Nonlinear Functions
 c) Discrete Functions d) Exponential Functions
- Q.5 MATLAB is known as
- a) Matrix Laboratory b) Mathematics
 c) Material Science d) None of these
- Q.6 In an open loop control system
- a) Feedback is present
 b) Feedback is absent
 c) Error detector is present
 d) None of these
- Q.7 Limit cycle is a behavior shown by
- a) Linear system b) Non linear system
 c) Signal flow graph d) Block diagram
- Q.8 Applications of robotics are
- a) Assembling b) dismantling
 c) Welding d) All of these
- Q.9 Following are robotic arm configuration
- a) Cartesian b) Cylindrical
 c) Spherical d) All of these
- Q.10 Accurate and reliable output is possible with which of the following system
- a) Open loop control system
 b) Closed loop control system
 c) Both 1 and 2
 d) None of these

SECTION-B

- Note:** Objective type questions. All questions are compulsory. (10x1=10)
- Q.11 Expand AI
 Q.12 Write two applications of Fuzzy Logic
 Q.13 Define feedback
 Q.14 Block diagram of cascade control has three loops.
 (True/False)
 Q.15 Expand ANN
 Q.16 Name two computational software
 Q.17 Define hysteresis
 Q.18 Neuro-fuzzy system is combination of _____
 Q.19 Write two applications of artificial intelligence
 Q.20 Write two examples of multi loop control system

SECTION-C

- Note:** Short answer type questions. Attempt any twelve questions out of fifteen questions. (12x5=60)
- Q.21 Explain the concept of Fuzzy Logic Control System
 Q.22 Write a short note on SCADA software
 Q.23 Explain classification of nonlinearities
 Q.24 Write five differences between feedback and feedforward control system
 Q.25 Tell five advantages of cascade control system
 Q.26 Write a short note on Multiloop control system
 Q.27 Explain the concept of Artificial intelligence
 Q.28 Write five applications of Artificial Neural Network