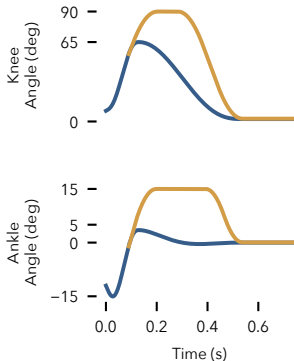


Large Obstacle



Small Obstacle



Normal Trajectory

Avoidance Trajectory