

Introducing an evolutionary method to create the bounds of artificial neural networks

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Abstract: Artificial neural networks are widely used in applications from various scientific fields and in a multitude of practical applications. In recent years, a multitude of scientific publications have been presented on the effective training of their parameters, but in many cases overfitting problems appear, where the artificial neural network shows poor results when used on data that was not present during training. This text proposes the incorporation of a three - stage evolutionary technique, which has its roots in the differential evolution technique, for the effective training of the parameters of artificial neural networks and the avoidance of the problem of overfitting. The new method effectively constructs the parameter value range of the artificial neural network, achieving both a reduction in training error and preventing the network from experiencing overfitting phenomena. This new technique was successfully applied to a wide range of problems from the relevant literature and the results were extremely promising.

Keywords: Neural networks; Evolutionary algorithms; Stochastic methods; Differential Evolution

1. Introduction

One of the most widespread machine learning models with many applications is artificial neural networks [1,2]. Artificial neural networks are parametric models defined as $N(\vec{x}, \vec{w})$, where the vector \vec{x} represents the input pattern for the neural network and the vector \vec{w} denotes the associated set of parameters that should be estimated by some optimization procedure. These optimization procedures usually minimize the so - called training error, defined as:

$$E(N(\vec{x}, \vec{w})) = \sum_{i=1}^M (N(\vec{x}_i, \vec{w}) - y_i)^2 \quad (1)$$

The set (\vec{x}_i, y_i) , $i = 1, \dots, M$ stands for the training set of the dataset and the values y_i are the expected outputs for each pattern \vec{x}_i . These models have been applied on wide series of applications from the related literature, such as image processing [3], time series forecasting [4], credit card analysis [5], physics problems [6,7], solar radiation prediction [8], agriculture problems [9] etc.

The equation 1 has been tackled by a variety of optimization and metaheuristic methods, such as the Back Propagation algorithm [10,11], the RPROP method [12,13], the Adam Optimizer [14], the Levenberg Marquardt method [15] etc. Furthermore, global optimization techniques have been also applied to neural network training. Among them one can detect the Simulated Annealing approach [16], the Genetic Algorithm approach [17], the Particle Swarm Optimization (PSO) method [18], the Ant Colony Optimization procedure [19], the Gray Wolf Optimizer [20], the Whale optimization technique [21] etc. Also, Sexton et al proposed the incorporation of tabu search algorithm for neural network

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training [22], Zhang et al suggested a hybrid algorithm that combines the PSO method and the Back Propagation algorithm for efficient neural networks training [23]. Recently, Zhao et al suggested the usage of a new Cascaded Forward Algorithm to train artificial neural networks [24]. Also, since in recent years there has been an explosive development and use of parallel computing architectures, several researchers have proposed their use for the efficient and rapid training of artificial neural networks [25,26].

However, although the above techniques are extremely effective in reducing the training error of artificial neural networks, they often cause the problem of overfitting, where the artificial neural network exhibits poor results when applied to data that was not present during its training. An overview of the overfitting problem can be found in the work of Ying [27]. A series of methods has been proposed in the recent literature to tackle the overfitting problem, such as the weight sharing method [28,29], pruning techniques [30,31], the incorporation of early stopping [32,33], weight decaying [34,35] etc. Furthermore, it has been suggested by various researchers the usage of dynamic architectures to handle the overfitting problem [36–38].

This work proposes the adoption of a three-stage technique that will have two goals: the effective training of artificial neural networks and the avoidance of the phenomenon of overfitting. In the first phase, a genetic algorithm [39] is used to detect an initial range of values for the parameters of the artificial neural network. This genetic algorithm uses a modified version of the artificial neural network's training error as a fitness function, in order to avoid the problem of overfitting. During the second phase of the proposed algorithm, a bounding technique which is based on the Differential Evolution algorithm [40] is used in order to efficiently identify promising ranges for the parameters of the neural networks. The Differential Evolution method was used at this stage of the proposed procedure as it has only a small number of parameters that the user must initialize, but also because it has been used with excellent success in a wide range of practical optimization applications [41–44]. During the third phase, a genetic algorithm is applied to train efficiently the neural network using the bounds that have been produced in the second phase for the parameters of the model. The proposed method have been applied on a wide series of classification and regression datasets and comparison was performed against traditional techniques for the training of neural networks.

The remaining of this article is organized as follows: in section 2 the proposed method is discussed in detail, in section 3 the used datasets as well as the conducted experiments are discussed and finally, in section 4 some conclusions are presented.

2. The proposed method

In this section, a detailed presentation and analysis of the three stages of the proposed technique for the effective training of artificial neural networks is provided.

2.1. The genetic algorithm of the first phase

The neural network used in the current work is a network with one processing level and it can be defined using the following equation:

$$N(\vec{x}, \vec{w}) = \sum_{i=1}^H w_{(d+2)i-(d+1)} \sigma \left(\sum_{j=1}^d x_j w_{(d+2)i-(d+1)+j} + w_{(d+2)i} \right) \quad (2)$$

that have been proposed in [45]. In this equation the constant H represents the number of processing units of the network and the constant d stands for the dimension of the input pattern \vec{x} . Following the equation, one can derive that the total number of parameters of the network is calculated as $n = (d + 2)H$. The current work adopts neural networks of one processing layer (hidden layer). According to the the Hornik's theorem [46] these networks can approximate any function with a sufficient number of computing units in the hidden layer. The function $\sigma(x)$ denotes the sigmoid function with the following formula:

$$\sigma(x) = \frac{1}{1 + \exp(-x)} \quad (3)$$

An example plot for this function is shown in Figure 1.

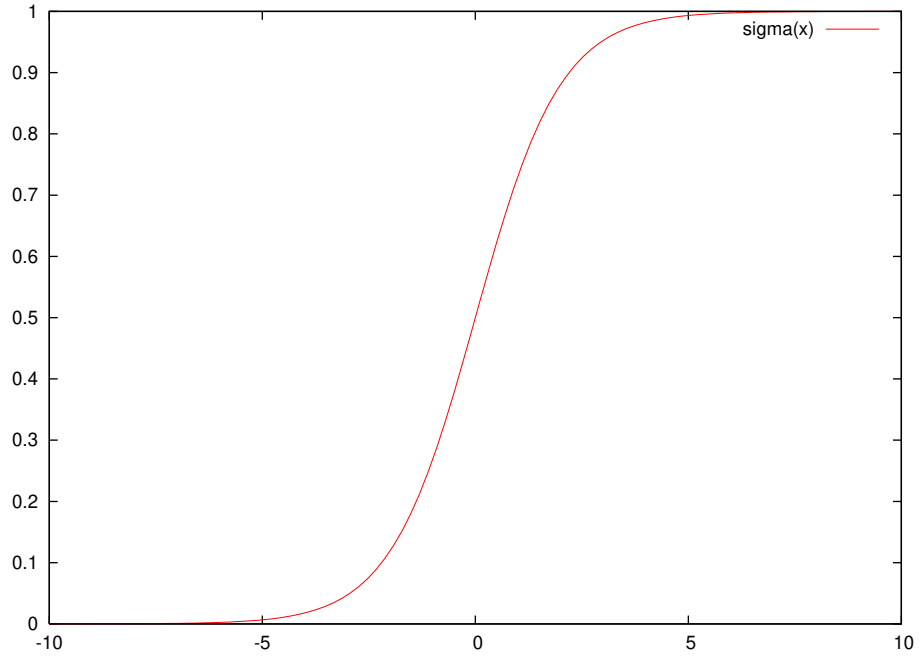


Figure 1. An example plot of the sigmoid function.

As is evident from this particular form, this function tends very quickly to 1 as x goes to infinity and very quickly to 0 as the parameter x gets negative values. This phenomenon has the effect of the artificial neuronal network to lose its general abilities, as large changes in the values of the parameters cause no substantial change in the response of the sigmoid function. The function $B(a)$ is used here to measure this effect and it is calculated using the algorithm 1.

Algorithm 1 Calculating the quantity $B(N(\vec{x}, \vec{w}), a)$ with $a > 0$ for a provided neural network $N(x, w)$.

1. **Function** $B(N(\vec{x}, \vec{w}), a)$
 2. **Define** $c = 0$
 3. **For** $i = 1..H$ **Do**
 - (a) **For** $j = 1..M$ **Do**
 - i. **Set** $v = \sum_{k=1}^d (w_{(d+2)i-(d+i)+k} x_{jk}) + w_{(d+2)i}$
 - ii. **If** $|v| > a$ **then** $c = c + 1$
 - (b) **EndFor**
 4. **EndFor**
 5. **Return** $\frac{c}{H \star M}$
 6. **End Function**
-

The function $B(N(\vec{x}, \vec{w}), a)$ is used to calculate the fitness value for the used genetic algorithm described subsequently:

1. **Initialization step.**

- (a) **Set** the number of chromosomes denoted as N_c and the maximum number of allowed generations N_g .
- (b) **Set** as p_s the selection rate and as p_m the mutation rate.
- (c) **Initialize** randomly the N_c chromosomes. Each chromosome g_i , $i = 1, \dots, N_c$ represents a neural network $N(\vec{x}, \vec{g}_i)$.
- (d) **Set** $k = 0$, the generation counter.
2. **Fitness calculation step.**
 - (a) **For** each chromosome g_i , $i = 1, \dots, N_c$ **do**
 - i. **Set** $E(N(\vec{x}, \vec{g}_i)) = \sum_{j=1}^M (N(\vec{x}_j, \vec{g}_i) - y_j)^2$
 - ii. **Set** $b_i = B(N(\vec{x}, \vec{g}_i), a)$
 - iii. **Set** $f_i = E(N(\vec{x}, \vec{g}_i)) \times (1 + \lambda b_i^2)$ as the fitness value of chromosome g_i . The value λ has the property $\lambda > 1$.
 - (b) **End For**
3. **Genetic operations step.**
 - (a) **Copy** the best $(1 - p_s) \times N_c$ chromosomes to the next generation. The remaining will be substituted by individuals produced by crossover and mutation.
 - (b) **Perform** the crossover procedure. For every pair of constructed chromosomes (\tilde{z}, \tilde{w}) two chromosomes are selected from the current population using tournament selection. The new chromosomes are created through the process suggested by Kaelo et al [47].
 - (c) **Perform** the mutation procedure. For every element of each chromosome alter this element randomly with probability p_m .
4. **Termination check step.**
 - (a) **Set** $k = k + 1$
 - (b) **If** $k < N_g$ **goto** fitness calculation step.
5. **Bound creation step.**
 - (a) **Obtain** the best chromosome g^*
 - (b) **Create** the vectors L^* and R^* as:

$$\begin{aligned} L_i^* &= -f|g_i^*|, i = 1, \dots, n \\ R_i^* &= f|g_i^*|, i = 1, \dots, n \end{aligned}$$

where $f > 1$

2.2. The bounding technique of the second phase

During the second phase of the proposed algorithm, a systematic attempt is made to identify the optimal value interval within the vectors L^* and R^* identified in the previous phase. For this reason, an evolutionary technique that has its bases in the differential evolution technique is applied here. In this phase, the agents that constitute the candidate solutions generated by the differential evolution technique constitute ranges of values defined as: $[\vec{L}_k, \vec{R}_k]$. Also, the fitness value for each agent is defined as an interval $f = [f_1, f_2]$. In order to compare two intervals $a = [a_1, a_2]$ and $b = [b_1, b_2]$ the comparison operator $D(a, b)$ is used with the following definition:

$$D(a, b) = \begin{cases} \text{TRUE}, & a_1 < b_1, \text{OR } (a_1 = b_1 \text{ AND } a_2 < b_2) \\ \text{FALSE}, & \text{OTHERWISE} \end{cases} \quad (4)$$

The steps of the procedure used in the second phase have as follows:

1. **Initialization step.**
 - (a) **Set** the number of agents NP.
 - (b) **Set** the crossover probability CR.

- (c) **Set** the maximum number of iterations N_k . 133
- (d) **Set** the number of samples N_s . 134
- (e) **Initialize** each agent $a_i = [\vec{L}_i, \vec{R}_i]$, $i = 1, \dots, NP$ randomly inside the vectors L^* and R^* of the previous phase. 135
- (f) **Set** $k = 0$ as the iteration counter. 137
2. **Fitness calculation step.** 138
 - (a) **For** $i = 1, \dots, NP$ **do** 139
 - i. **Calculate** the fitness f_i of agent a_i using the algorithm 2. 140
 - (b) **End For** 141
3. **Main step.** 142
 - (a) **For** $i = 1, \dots, NP$ **do** 143
 - i. **Select** randomly three distinct agents a_{r1}, a_{r2}, a_{r3} . 144
 - ii. **Select** randomly an integer value $R \in [0, n]$. 145
 - iii. **Set** $t = a_i$ as the trial point. 146
 - iv. **For** $j = 1, \dots, n$ **do** 147
 - A. **If** $j = R$ OR $r \leq CR$ **set** $t_j = a_{r1,j} + F_r \times (a_{r2,j} - a_{r3,j})$ where r and F_r are random values in $[0,1]$. 148
 - v. **End For** 150
 - vi. **Set** t_f as the fitness of the trial set of intervals t . This fitness value is calculated using the algorithm 2. 151
 - vii. **If** $d(t_f, f_i) = \text{TRUE}$ **then** $a_i = t$. 153
 - (b) **End For** 154
4. **Termination check step.** 155
 - (a) **Set** $k = k + 1$ 156
 - (b) **If** $k \leq N_k$ **goto** Main Step. 157
5. **Final step.** 158
 - (a) **Obtain** the best agent $a^* = [\vec{L}_a^*, \vec{R}_a^*]$ 159
 - (b) **Return** a^* as the best located interval. 160

Algorithm 2 Fitness calculation for any agent $a = [\vec{L}_a, \vec{R}_a]$.

1. **Take** N_s random samples in a and form the set $S_a = \{\vec{s}_1, \vec{s}_2, \dots, \vec{s}_{N_s}\}$.
 2. **Set** $f_{\min} = \infty$
 3. **Set** $f_{\max} = -\infty$
 4. **For** $i = 1, \dots, N_s$ **do**
 - (a) **Calculate** $E_i = \sum_{j=1}^M (N(\vec{x}_j^i, \vec{s}_i^i) - y_j)^2$
 - (b) **If** $E_i < f_{\min}$ **set** $f_{\min} = E_i$
 - (c) **If** $E_i > f_{\max}$ **set** $f_{\max} = E_i$
 5. **End For**
 6. **Return** as fitness value the quantity $f_a = [f_{\min}, f_{\max}]$
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2.3. The final training method 161

In the last phase of the proposed procedure, a genetic algorithm is applied to train the artificial neural network. The network is trained within the interval a^* identified in the second phase of the procedure. The main steps of this genetic algorithm have as follows: 162

1. **Initialization step.** 165

- (a) **Set** as N_c the number of chromosomes and as N_g the maximum number of allowed generations. 166
- (b) **Set** as p_s the selection rate and as p_m the mutation rate. 167
- (c) **Initialize** each chromosome g_i , $i = 1, \dots, N_c$ inside the bounds $a^* = [\vec{L}_a^*, \vec{R}_a^*]$ of the second phase. 168
- (d) **Set** $k = 0$ as the generation number. 169
2. **Fitness calculation step.** 170
- (a) **For** $i = 1, \dots, N_c$ **do** 171
- i. **Obtain** the neural network $N_i = N(\vec{x}, \vec{g}_i)$ for each chromosome \vec{g}_i . 172
- ii. **Set** $f_i = \sum_{j=1}^M (N(\vec{x}_j, \vec{g}_i) - y_j)^2$ as the associated fitness value. 173
- (b) **End For** 174
3. **Genetic operations step.** 175
- (a) **Perform** selection, crossover and mutation using the same operations as in the first phase of the proposed method. 176
4. **Termination check step.** 177
- (a) **Set** $k = k + 1$ 178
- (b) **If** $k \leq N_g$ **goto** Fitness Calculation Step. 179
5. **Testing step.** 180
- (a) **Obtain** the best chromosome \vec{g}^* . 181
- (b) **Create** the corresponding neural network $N(\vec{x}, \vec{g}^*)$ 182
- (c) **Apply** this neural network to the associated test set and report the results. 183

3. Results 184

The proposed method was tested for its efficiency on a series of classification and regression problems, that were obtained from the following online databases: 185

1. The UCI database located in <https://archive.ics.uci.edu/> (accessed on 17 February 2025) [48] 186
2. The Keel website, <https://sci2s.ugr.es/keel/datasets.php> (accessed on 17 February 2025) [49]. 187
3. The Statlib URL <ftp://lib.stat.cmu.edu/datasets/index.html> (accessed on 17 February 2025). 188

3.1. Datasets 189

The following series of classification datasets was used in the conducted experiments: 190

1. **Appendicitis**, which is medical dataset proposed in [50]. 191
2. **Alcohol**, which is related to experiments regarding alcohol consumption [51]. 192
3. **Australian**, which is related to various bank transactions [52]. 193
4. **Balance** dataset [53], which is used in various psychological experiments. 194
5. **Cleveland**, which is a medical dataset [54,55]. 195
6. **Circular** dataset, which is a dataset created artificially. 196
7. **Dermatology**, a medical dataset with 6 classes which is related to dermatology problems [56]. 197
8. **Ecoli**, which is used to problems regarding proteins [57]. 198
9. **Glass** dataset, which is related to glass component analysis. 199
10. **Haberman**, a medical dataset for the detection of breast cancer. 200
11. **Hayes-roth** dataset [58], a dataset with 3 classes. 201
12. **Heart**, a medical dataset about heart diseases [59] with two classes. 202
13. **HeartAttack**, a medical dataset used for the detection of heart diseases. 203
14. **Housevotes**, that contains data about the Congressional voting in USA [60]. 204
15. **Ionosphere**, that contains measurements about the ionosphere [61,62]. 205

16. **Liverdisorder**, which is a medical dataset [63,64]. 214
17. **Lymography** dataset [65]. 215
18. **Mammographic**, a medical dataset related to breast cancer [66]. 216
19. **Parkinsons**, a medical dataset related to Parkinson's disease [67,68]. 217
20. **Pima**, a medical dataset related to the presence of diabetes[69]. 218
21. **Phoneme**, used in sound experiments. 219
22. **Popfailures**, a dataset that contains climate measurements [70]. 220
23. **Regions2**, a medical dataset related to some liver biopsy images [71]. 221
24. **Saheart**, which is a medical dataset related to some heart diseases.[72]. 222
25. **Segment** dataset [73], used in various image processing cases. 223
26. **Statheart**, which is a medical dataset related to heart diseases. 224
27. **Spiral**, which is a dataset created artificially. 225
28. **Student**, a dataset that contains measurements from experiments conducted in schools [74]. 226
29. **Transfusion**, which is a medical dataset [75]. 228
30. **Wdbc**, a medical dataset used to predict the presence of breast cancer [76,77]. 229
31. **Wine**, a dataset used to predict the quality of wines [78,79]. 230
32. **EEG** dataset, which is a medical dataset related to EEG measurements[80,81] and the following cases were studied from this dataset: Z_F_S, ZO_NF_S and ZONF_S. 231
33. **Zoo**, a dataset used to predict the class of some animals [82] . 233

Furthermore, the following list of regression datasets was incorporated in the conducted experiments: 234

1. **Abalone**, a dataset related to the estimation of the age of abalones [83]. 236
2. **Airfoil**, a dataset provided by NASA [84]. 237
3. **Auto**, a dataset used for the estimation of fuel consumption in cars. 238
4. **BK**, which is used in basketball games. 239
5. **BL**, a dataset that contains measurements about electricity experiments. 240
6. **Baseball**, a dataset that contains data used in the estimation of the income of baseball players. 241
7. **Concrete**, a dataset used in civil engineering [85]. 243
8. **DEE**, a dataset that contains 6 features, which is used for the prediction of electricity prices. 244
9. **Friedman**, an artificial dataset[86]. 246
10. **FY**, this dataset used to estimate the longevity of fruit flies. 247
11. **HO**, a dataset provided by the STATLIB repository with 13 features. 248
12. **Housing**, which is used for the prediction of house prices [87]. 249
13. **Laser**, which is used in various laser experiments. 250
14. **LW**, which is a dataset with 9 features used to measure the weight of babes. 251
15. **Mortgage**, which is a dataset with 15 features related to the economy of USA. 252
16. **Plastic**, a dataset related to the pressure in plastics. 253
17. **PL**, a dataset provided by the STATLIB repository. 254
18. **Quake**, a dataset with 3 features that contains measurements from earthquakes. 255
19. **SN**, a dataset with 11 features, which is used in experiments related to trellising and pruning,. 256
20. **Stock**, a dataset with 9 features used to predict the prices of various stocks. 258
21. **Treasury**, which is a dataset with 15 features used in economic problems. 259

3.2. Experimental results 260

The software used in the conducted experiments was coded in C++, using the freely available Optimus programming tool, that can be downloaded from <https://github.com/itsoulos/GlobalOptimus/> (accessed on 17 February 2025). Each experiment was conducted 30 times using different seed for the random generator each time. For the validation of the experimental results the ten - fold cross validation method was used. The average classi- 261
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fication error as measured on the corresponding test set is reported for the classification datasets. This error is calculated using the following formula:

$$E_C(N(\vec{x}, \vec{w})) = 100 \times \frac{\sum_{i=1}^N (\text{class}(N(\vec{x}_i, \vec{w})) - y_i)}{N} \quad (5)$$

Also, the average regression error is reported for the regression datasets, that can be calculated as follows:

$$E_R(N(\vec{x}, \vec{w})) = \frac{\sum_{i=1}^N (N(\vec{x}_i, \vec{w}) - y_i)^2}{N} \quad (6)$$

All the experiments were performed on an AMD Ryzen 5950X with 128GB of RAM and the used operating system was Debian Linux. The values used for the parameters of the proposed method are shown in Table 1.

Table 1. The experimental settings used in the current algorithm.

PARAMETER	MEANING	VALUE
H	Processing nodes	10
N_c	Chromosomes	500
N_g	Generations	200
p_s	Selection rate	0.9
p_m	Mutation rate	0.05
f	Bounding value	2.0
NP	Agents	200
F	Differential weight	0.8
CR	Crossover probability	0.9
N_s	Number of samples	50
N_k	Iterations	200

The following notation is used in the tables that contains the measurement from the conducted experiments:

1. The column DATASET contains the name of the used dataset.
2. The column ADAM represents the experimental results from the application of the ADAM optimization method [14] to a neural networks with $H = 10$ processing nodes.
3. The column BFGS denotes the incorporation of the BFGS optimization method [88] to train an artificial neural network with $H = 10$ processing nodes.
4. The column GENETIC represents the usage of a Genetic Algorithm with the experimental settings of Table 1, used to train a neural network with $H = 10$ processing nodes.
5. The column PROPOSED denotes the proposed method.
6. The row AVERAGE is used to measure the average classification or regression error for all dataset.

The table 2 is used to provide the experimental results for the classification datasets and the table 3 provides the corresponding results for the regression datasets.

Table 2. Experimental results for the used classification datasets. The numbers in cells represent average classification error as measured on the corresponding test set.

DATASET	ADAM	BFGS	GENETIC	RBF	PROPOSED
APPENDICITIS	16.50%	18.00%	24.40%	12.23%	15.00%
ALCOHOL	57.78%	41.50%	39.57%	49.32%	18.33%
AUSTRALIAN	35.65%	38.13%	32.21%	34.89%	21.49%
BALANCE	12.27%	8.64%	8.97%	33.53%	7.79%
CLEVELAND	67.55%	77.55%	51.60%	67.10%	42.38%
CIRCULAR	19.95%	6.08%	5.99%	5.98%	6.50%
DERMATOLOGY	26.14%	52.92%	30.58%	62.34%	4.97%
ECOLI	64.43%	69.52%	54.67%	59.48%	40.30%
GLASS	61.38%	54.67%	52.86%	50.46%	54.38%
HABERMAN	29.00%	29.34%	28.66%	25.10%	26.53%
HAYES-ROTH	59.70%	37.33%	56.18%	64.36%	34.31%
HEART	38.53%	39.44%	28.34%	31.20%	13.11%
HEARTATTACK	45.55%	46.67%	29.03%	29.00%	21.90%
HOUSEVOTES	7.48%	7.13%	6.62%	6.13%	6.09%
IONOSPHERE	16.64%	15.29%	15.14%	16.22%	10.37%
LIVERDISORDER	41.53%	42.59%	31.11%	30.84%	29.94%
LYMOGRAPHY	39.79%	35.43%	28.42%	25.50%	17.93%
MAMMOGRAPHIC	46.25%	17.24%	19.88%	21.38%	16.63%
PARKINSONS	24.06%	27.58%	18.05%	17.41%	12.79%
PHONEME	29.43%	15.58%	15.55%	23.32%	18.10%
PIMA	34.85%	35.59%	32.19%	25.78%	25.03%
POPFAILURES	5.18%	5.24%	5.94%	7.04%	4.45%
REGIONS2	29.85%	36.28%	29.39%	38.29%	25.19%
SAHEART	34.04%	37.48%	34.86%	32.19%	29.26%
SEGMENT	49.75%	68.97%	57.72%	59.68%	27.80%
SONAR	30.33%	25.85%	22.40%	27.90%	20.50%
SPIRAL	47.67%	47.99%	48.66%	44.87%	41.60%
STATHEART	44.04%	39.65%	27.25%	31.36%	19.74%
STUDENT	5.13%	7.14%	5.61%	5.49%	4.00%
TRANSFUSION	25.68%	25.84%	24.87%	26.41%	23.35%
WDBC	35.35%	29.91%	8.56%	7.27%	6.73%
WINE	29.40%	59.71%	19.20%	31.41%	6.29%
Z_F_S	47.81%	39.37%	10.73%	13.16%	8.38%
ZO_NF_S	47.43%	43.04%	21.54%	9.02%	4.32%
ZONF_S	11.99%	15.62%	4.36%	4.03%	1.76%
ZOO	14.13%	10.70%	9.50%	21.93%	7.00%
AVERAGE	34.23%	33.58%	26.13%	29.21%	18.73%

Table 3. Experimental results for the used regression datasets. Numbers in cells represent average regression error as calculated on the corresponding test set.

DATASET	ADAM	BFGS	GENETIC	RBF	PROPOSED
ABALONE	4.30	5.69	7.17	7.37	4.32
AIRFOIL	0.005	0.003	0.003	0.27	0.002
AUTO	70.84	60.97	12.18	17.87	12.78
BK	0.0252	0.28	0.027	0.02	0.02
BL	0.622	2.55	5.74	0.013	0.006
BASEBALL	77.90	119.63	103.60	93.02	60.74
CONCRETE	0.078	0.066	0.0099	0.011	0.006
DEE	0.63	2.36	1.013	0.17	0.19
FRIEDMAN	22.90	1.263	1.249	7.23	2.21
FY	0.038	0.19	0.65	0.041	0.067
HO	0.035	0.62	2.78	0.03	0.015
HOUSING	80.99	97.38	43.26	57.68	20.74
LASER	0.03	0.015	0.59	0.03	0.004
LW	0.028	2.98	1.90	0.03	0.011
MORTGAGE	9.24	8.23	2.41	1.45	0.32
PL	0.117	0.29	0.29	2.118	0.022
PLASTIC	11.71	20.32	2.791	8.62	2.16
QUAKE	0.07	0.42	0.04	0.07	0.036
SN	0.026	0.40	2.95	0.027	0.023
STOCK	180.89	302.43	3.88	12.23	5.57
TREASURY	11.16	9.91	2.93	2.02	0.68
AVERAGE	22.46	30.29	9.31	10.02	5.23

The statistical analysis derived from Table 2 presents the error rates for various classification datasets using five different machine learning models: ADAM, BFGS, GENETIC, RBF, and PROPOSED. The analysis focuses on comparing the models in terms of their effectiveness, with a lower error rate indicating better performance. Initially, it is observed that the PROPOSED model achieves the lowest average error rate (18.73%) compared to the other models, which have average error rates of 34.23% (ADAM), 33.58% (BFGS), 26.13% (GENETIC), and 29.21% (RBF). This highlights the overall superiority of the PROPOSED model. Examining individual datasets, the PROPOSED model exhibits the lowest error rate in many cases, such as "BALANCE" (7.79%), "DERMATOLOGY" (4.97%), "STUDENT" (4.00%), "ZO_NF_S" (4.32%), "ZONF_S" (1.76%), and "ZOO" (7.00%). Notably, its performance on "ZONF_S," with an error rate of only 1.76%, demonstrates exceptional accuracy. In other datasets, such as "CIRCULAR" and "HOUSEVOTES," the PROPOSED model performs very close to the best result but does not outperform the others. In some cases, such as "SEGMENT" and "WINE," it shows higher error rates, indicating room for improvement with specific types of data. In comparison, the ADAM model exhibits the highest overall deviation, making it the least effective. The RBF model also shows higher error rates compared to the PROPOSED model in several datasets, such as "BALANCE" and "ZOO." Similarly, the BFGS model fails to achieve low error rates in critical datasets such as "HEART" and "STATHEART." The GENETIC model demonstrates intermediate performance, achieving lower error rates than ADAM and BFGS but higher than the PROPOSED model. In conclusion, the analysis confirms that the PROPOSED model is the most reliable and consistent in most cases, achieving the lowest overall average error rate.

The statistical analysis of Table 3 examines the absolute error values for various regression datasets using five different machine learning models: ADAM, BFGS, GENETIC, RBF, and PROPOSED. The analysis evaluates the models based on their performance, where lower error values indicate better accuracy. The PROPOSED model achieves the lowest average error (5.23) compared to the other models, which have average errors of 22.46 (ADAM), 30.29 (BFGS), 9.31 (GENETIC), and 10.02 (RBF). This result underscores the

superior performance of the PROPOSED model overall. Examining individual datasets, the PROPOSED model consistently achieves the smallest error in several cases. For instance, it outperforms other models in "AIRFOIL" (0.002), "BL" (0.006), "CONCRETE" (0.006), "HO" (0.015), "LASER" (0.004), "LW" (0.011), "MORTGAGE" (0.32), "PL" (0.022), and "PLASTIC" (2.16). These results highlight the model's robustness across diverse datasets. Notably, its performance on "AIRFOIL" with an error of 0.002 and "LASER" with 0.004 demonstrate exceptional precision. In some datasets, such as "SN" and "QUAKE," the PROPOSED model closely matches the best-performing results but does not necessarily achieve the lowest error. In certain cases, like "FRIEDMAN" and "STOCK," while still competitive, the model exhibits higher error values than some of its competitors. Specifically, in "STOCK," the PROPOSED model records an error of 5.57, which is higher than GENETIC's error of 3.88 but significantly lower than ADAM and BFGS. These cases indicate areas where further optimization of the PROPOSED model may be beneficial. Comparatively, the ADAM and BFGS models generally exhibit higher error rates, with BFGS particularly underperforming on datasets such as "BASEBALL" and "STOCK." The GENETIC model demonstrates strong performance, with its average error being the second lowest (9.31). However, its results are still consistently higher than the PROPOSED model on key datasets like "MORTGAGE" and "HOUSING." Similarly, the RBF model, while competitive in some cases, such as "TREASURY," has higher errors in others, such as "AUTO" and "BL." In conclusion, the analysis confirms that the PROPOSED model is the most effective and consistent across the majority of regression datasets, achieving the lowest overall average error.

In Figure 2, which pertains to classification datasets for various machine learning models, the proposed method demonstrates highly significant differences when compared to other methods. Specifically, the p-values are as follows: PROPOSED vs ADAM: $p=2.9e-11$, PROPOSED vs BFGS: $p=1.3e-09$, PROPOSED vs GENETIC: $p=1.6e-08$ and PROPOSED vs RBF: $p=8e-08$. These results highlight the statistical significance of the proposed method in classification tasks.

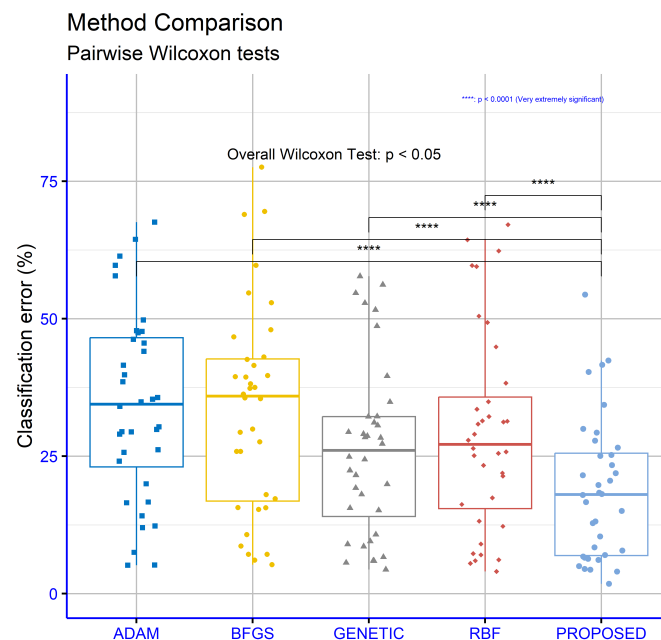


Figure 2. Statistical comparison of the used methods for the classification datasets.

In Figure 3, focusing on regression datasets for various machine learning models, the proposed method again shows statistically significant differences when compared to other methods. The corresponding p-values are: PROPOSED vs ADAM: $p=0.0001$, PROPOSED vs BFGS: $p=4.1e-05$, PROPOSED vs GENETIC: $p=0.0022$ and PROPOSED vs RBF: $p=0.00073$.

These results indicate the superiority of the proposed method across regression datasets with notable levels of significance.

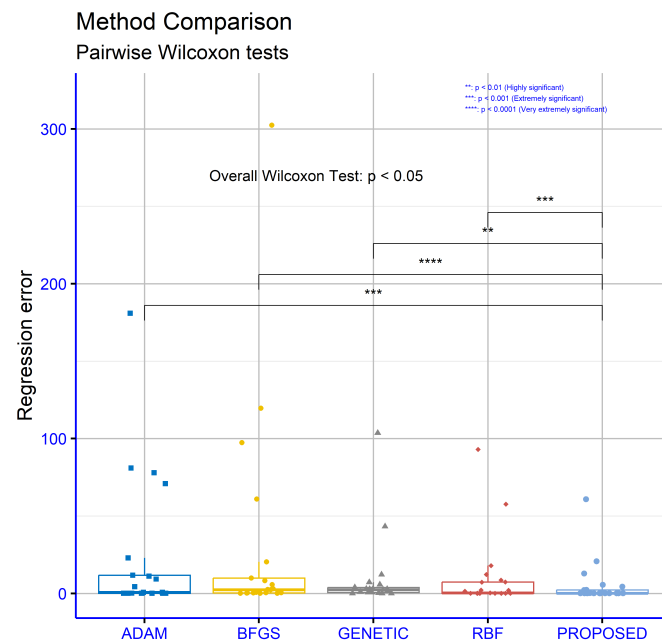


Figure 3. Statistical comparison between the used methods for the regression datasets.

3.2.1. Using different weight methods

An additional experiment was executed where the parameter F of the differential evolution was altered using some well - known approaches from the relevant literature. In the following tables the following methods, as denoted in the experimental tables, were obtained for the calculation of the parameter F :

1. RANDOM. This method is used for the current approach, where the differential weight is a random number in $[0, 1]$.
2. FIXED. This method is used when the value for F is used, as denoted in Table 1.
3. ADAPT. This method is used for the adaptive calculation of parameter F as proposed in [93].
4. MIGRANT. For this case the calculation for parameter F as proposed in [92] is adopted.

The experimental results using the current method and the previously mentioned method for differential weight are listed in Tables 4 and 5 for the classification datasets and the regression datasets respectively.

Table 4. Experimental results for the classification datasets and the proposed method using a series of differential weight mechanisms.

DATASET	RANDOM	FIXED	ADAPT	MIGRANT
APPENDICITIS	15.00%	14.90%	15.30%	15.80%
ALCOHOL	18.33%	20.81%	22.08%	17.26%
AUSTRALIAN	21.49%	19.62%	23.91%	29.49%
BALANCE	7.79%	7.56%	8.39%	8.39%
CLEVELAND	42.38%	42.31%	41.79%	44.79%
CIRCULAR	6.50%	7.24%	7.40%	4.74%
DERMATOLOGY	4.97%	5.72%	5.71%	11.40%
ECOLI	40.30%	42.18%	45.51%	47.61%
GLASS	54.38%	54.33%	56.29%	49.00%
HABERMAN	26.53%	27.93%	30.00%	26.60%
HAYES-ROTH	34.31%	34.00%	28.62%	35.00%
HEART	13.11%	15.30%	14.56%	19.04%
HEARTATTACK	21.90%	19.57%	20.00%	20.70%
HOUSEVOTES	6.09%	6.00%	5.22%	5.48%
IONOSPHERE	10.37%	9.71%	8.86%	11.80%
LIVERDISORDER	29.94%	30.97%	29.56%	31.12%
LYMOGRAPHY	17.93%	18.93%	20.72%	20.93%
MAMMOGRAPHIC	16.63%	15.74%	16.12%	17.50%
PARKINSONS	12.79%	9.69%	11.58%	14.42%
PHONEME	18.10%	17.23%	18.15%	18.40%
PIMA	25.03%	27.66%	27.89%	27.70%
POPFAILURES	4.45%	5.19%	4.82%	4.39%
REGIONS2	25.19%	25.03%	23.24%	30.92%
SAHEART	29.26%	32.26%	30.76%	32.28%
SEGMENT	27.80%	36.29%	33.83%	42.80%
SONAR	20.50%	20.85%	21.00%	22.10%
SPIRAL	41.60%	43.93%	45.67%	44.04%
STATHEART	19.74%	18.52%	16.67%	17.41%
STUDENT	4.00%	4.38%	4.25%	4.63%
TRANSFUSION	23.35%	22.95%	24.58%	23.50%
WDBC	6.73%	6.48%	7.50%	4.18%
WINE	6.29%	5.82%	6.35%	11.59%
Z_F_S	8.38%	7.00%	9.27%	10.43%
ZO_NF_S	4.32%	5.52%	6.00%	8.36%
ZONF_S	1.76%	1.92%	2.20%	2.32%
ZOO	7.00%	4.90%	9.00%	6.10%
AVERAGE	18.73%	19.12%	19.52%	20.62%

Table 5. Experimental results for the regression datasets and the proposed method using a variety of techniques for the calculation of differential weight.

DATASET	RANDOM	FIXED	ADAPT	MIGRANT
ABALONE	4.32	4.47	4.35	4.41
AIRFOIL	0.002	0.003	0.003	0.003
AUTO	12.78	13.58	13.98	11.46
BK	0.02	0.057	0.021	0.021
BL	0.006	0.008	0.006	0.008
BASEBALL	60.74	65.12	67.71	60.10
CONCRETE	0.006	0.026	0.007	0.004
DEE	0.19	0.21	0.20	0.24
FRIEDMAN	2.21	2.79	3.18	1.88
FY	0.067	0.046	0.042	0.052
HO	0.015	0.017	0.052	0.013
HOUSING	20.74	24.63	24.83	24.71
LASER	0.004	0.004	0.004	0.003
LW	0.011	0.014	0.011	0.013
MORTGAGE	0.32	0.71	0.32	0.22
PL	0.022	0.022	0.022	0.023
PLASTIC	2.16	2.15	2.15	2.36
QUAKE	0.036	0.052	0.036	0.044
SN	0.023	0.036	0.025	0.024
STOCK	5.57	5.89	4.72	4.41
TREASURY	0.68	0.64	0.51	0.65
AVERAGE	5.23	5.74	5.82	5.27

The statistical analysis of Table 4 examines the percentage error rates across various classification datasets using four different computations of the critical weight differential parameter for the proposed machine learning model: RANDOM, FIXED, ADAPT, and MIGRANT. The RANDOM computation exhibits the lowest overall average error rate (18.73%), indicating superior performance compared to the other computations: FIXED (19.12%), ADAPT (19.52%), and MIGRANT (20.62%). This suggests that the RANDOM computation is the most reliable overall. Analyzing individual datasets, the RANDOM computation achieves the best error rates in several cases. For instance, it records the lowest error rates for datasets such as "ALCOHOL" (18.33%), "BALANCE" (7.79%), "CIRCULAR" (6.50%), "HOUSEVOTES" (6.09%), "PARKINSONS" (12.79%), "POPFAILURES" (4.45%), and "WDBC" (6.73%). These results highlight its effectiveness across a wide range of datasets. Specifically, the 4.45% error rate for "POPFAILURES" stands out as one of the lowest overall. In certain datasets, the FIXED computation outperforms others, such as in "Z_F_S" (7.00%) and "ZOO" (4.90%). However, the difference from RANDOM is minimal. The MIGRANT computation demonstrates the lowest error rates in only a few cases, such as "CIRCULAR" (4.74%) and "WDBC" (4.18%), suggesting it may be particularly effective for specific datasets. Meanwhile, the ADAPT computation achieves lower error rates in a few scenarios but generally remains less competitive. In other datasets, such as "GLASS," "SPIRAL," and "SEGMENT," all computations show high error rates, indicating these datasets are challenging to classify regardless of the computation. Nevertheless, the RANDOM computation remains consistently competitive even with these difficult datasets, as observed in "STATHEART" and "ZONE_S." In conclusion, the analysis reveals that the RANDOM computation is the most effective overall, achieving the lowest average error rate and demonstrating superior performance across a broad range of datasets. However, there are instances where other computations, such as FIXED and MIGRANT, show specialized advantages.

The statistical analysis of Table 5 pertains to regression datasets, using four different calculations of the critical parameter of differential weighting for the proposed machine

learning model: RANDOM, FIXED, ADAPT, and MIGRANT. The RANDOM calculation exhibits the lowest average error (5.23), making it the most efficient overall compared to FIXED (5.74), ADAPT (5.82), and MIGRANT (5.27). The small difference between RANDOM and MIGRANT suggests comparable performance between these two approaches, with RANDOM maintaining a slight edge. For individual datasets, the RANDOM calculation achieves the lowest error values in several cases, such as the "AUTO" (12.78), "FRIEDMAN" (2.21), "HO" (0.015), "MORTGAGE" (0.32), and "SN" (0.023) datasets. These results demonstrate the effectiveness of the RANDOM calculation across a wide range of datasets. In the "FRIEDMAN" dataset, the error value of 2.21 is significantly lower than the corresponding values of FIXED (2.79) and ADAPT (3.18), underscoring its performance in this specific dataset. The MIGRANT calculation demonstrates the best performance in certain datasets, such as "AUTO" (11.46) and "STOCK" (4.41), where it outperforms RANDOM. However, in other datasets, such as "PLASTIC" and "SN," it shows slightly higher error rates, indicating limitations with specific data. The FIXED calculation tends to have consistent but not top-performing results, while ADAPT generally shows higher error values, making it less effective overall. In summary, the analysis highlights that the RANDOM calculation is the most reliable and efficient, with the lowest average error and strong performance across various datasets. However, the MIGRANT calculation exhibits competitive performance in specific cases, while FIXED and ADAPT appear to require improvements to rival the other calculations.

Figure 4 evaluates classification datasets for different differential weight computations within the proposed machine learning model. The p-values are as follows: RANDOM vs FIXED: $p=0.43$, RANDOM vs ADAPT: $p=0.024$, RANDOM vs MIGRANT: $p=0.0021$, FIXED vs ADAPT $p=0.12$, FIXED vs MIGRANT: $p=0.0033$ and ADAPT vs MIGRANT: $p=0.043$. These results suggest that some comparisons, such as RANDOM vs MIGRANT and FIXED vs MIGRANT, show strong statistical significance, while others, such as RANDOM vs FIXED, do not demonstrate significant differences.

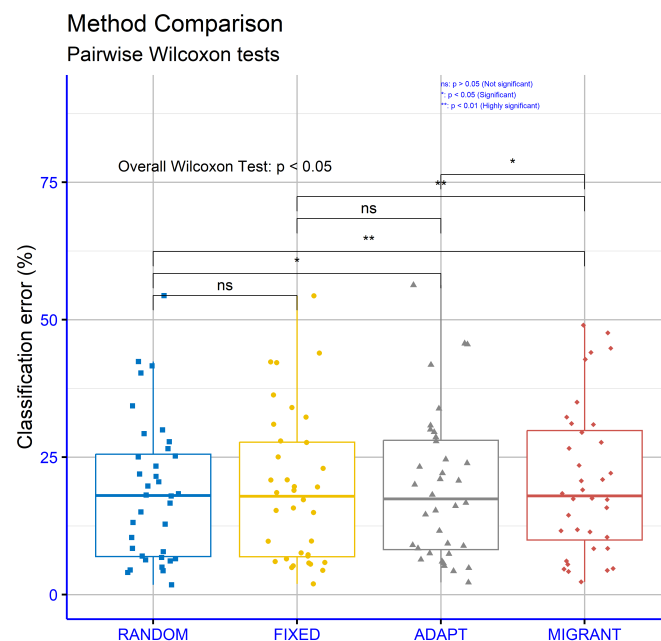


Figure 4. Statistical comparison between the proposed variations of the differential weight mechanisms. The experiments were conducted on the classification datasets.

Figure 5 presents results for regression datasets using different differential weight computations within the proposed model. The observed p-values are: RANDOM vs FIXED: $p=0.0066$, RANDOM vs ADAPT: $p=0.15$, RANDOM vs MIGRANT: $p=0.66$, FIXED vs

ADAPT: $p=0.64$, FIXED vs MIGRANT: $p=0.84$ and ADAPT vs MIGRANT: $p=0.47$. These findings indicate that most comparisons do not show significant differences, except for RANDOM vs FIXED, which demonstrates a notable level of significance.

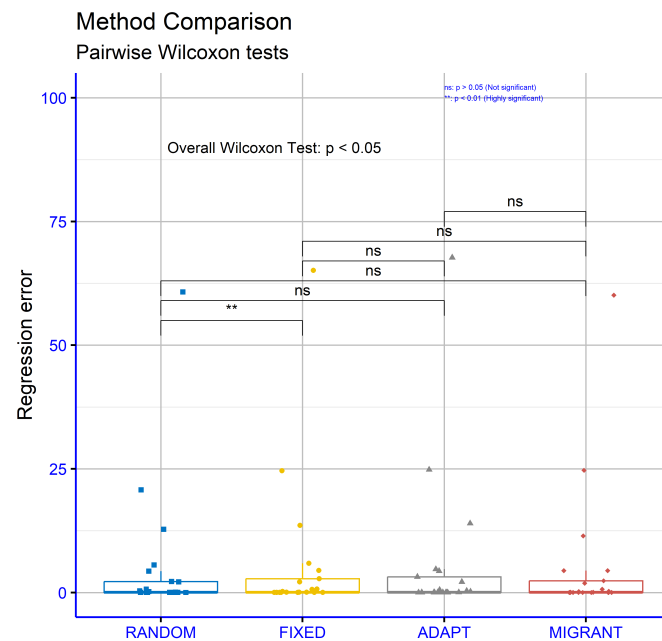


Figure 5. Statistical comparison for the different variations of the weight calculation mechanism. The experiments were conducted using the proposed method on the regression datasets.

3.2.2. Experiment with the number of agents

An additional experiment was conducted using different values for the parameter NP, which represents the number of agents. In this experiment the parameter NP took the values 50, 100 and 200. The experimental results for the classification datasets are shown in Table 6 and for the regression datasets in Table 7.

Table 6. Experimental results for the classification datasets and the proposed method using a variety of values for the parameter NP.

DATASET	NP=50	NP=100	NP=200
APPENDICITIS	14.00%	14.00%	15.00%
ALCOHOL	26.90%	25.36%	18.33%
AUSTRALIAN	30.67%	25.83%	21.49%
BALANCE	7.42%	8.13%	7.79%
CLEVELAND	39.55%	42.10%	42.38%
CIRCULAR	8.50%	6.79%	6.50%
DERMATOLOGY	9.89%	11.34%	4.97%
ECOLI	44.58%	41.48%	40.30%
GLASS	53.24%	55.00%	54.38%
HABERMAN	27.67%	27.70%	26.53%
HAYES-ROTH	36.08%	34.69%	34.31%
HEART	14.89%	14.85%	13.11%
HEARTATTACK	20.73%	17.93%	21.90%
HOUSEVOTES	3.91%	5.22%	6.09%
IONOSPHERE	8.03%	10.43%	10.37%
LIVERDISORDER	32.21%	30.18%	29.94%
LYMOGRAPHY	19.93%	18.86%	17.93%
MAMMOGRAPHIC	15.76%	16.53%	16.63%
PARKINSONS	12.05%	11.63%	12.79%
PHONEME	19.06%	19.08%	18.10%
PIMA	25.75%	28.51%	25.03%
POPFAILURES	5.74%	4.07%	4.45%
REGIONS2	24.71%	24.60%	25.19%
SAHEART	32.33%	31.72%	29.26%
SEGMENT	46.73%	44.27%	27.80%
SONAR	21.95%	22.75%	20.50%
SPIRAL	43.55%	44.08%	41.60%
STATHEART	18.70%	17.67%	19.74%
STUDENT	3.50%	3.70%	4.00%
TRANSFUSION	23.83%	23.87%	23.35%
WDBC	8.82%	7.00%	6.73%
WINE	8.82%	7.12%	6.29%
Z_F_S	8.30%	6.73%	8.38%
ZO_NF_S	7.04%	6.30%	4.32%
ZONF_S	2.08%	2.18%	1.76%
ZOO	6.00%	6.00%	7.00%
AVERAGE	20.36%	19.94%	18.73%

Table 7. Experimental results for the regression datasets using the proposed method and a variety of values for parameter NP.

DATASET	NP=50	NP=100	NP=200
ABALONE	4.41	4.35	4.32
AIRFOIL	0.003	0.003	0.002
AUTO	14.73	13.63	12.78
BK	0.019	0.018	0.02
BL	0.011	0.009	0.006
BASEBALL	63.75	57.75	60.74
CONCRETE	0.007	0.006	0.006
DEE	0.21	0.20	0.19
FRIEDMAN	3.43	2.83	2.21
FY	0.047	0.041	0.067
HO	0.016	0.014	0.015
HOUSING	28.28	25.95	20.74
LASER	0.005	0.005	0.004
LW	0.01	0.012	0.011
MORTGAGE	0.34	0.48	0.32
PL	0.022	0.022	0.022
PLASTIC	2.16	2.16	2.16
QUAKE	0.037	0.054	0.036
SN	0.026	0.025	0.023
STOCK	5.30	6.34	5.57
TREASURY	1.50	1.16	0.68
AVERAGE	5.92	5.48	5.23

The statistical analysis of Table 6 pertains to classification datasets, utilizing three different values for the critical parameter "NP" in the proposed machine learning model: NP=50, NP=100, and NP=200. The computation with NP=200 demonstrates the lowest average error rate (18.73%), indicating the highest efficiency compared to NP=100 (19.94%) and NP=50 (20.36%). This suggests that a higher value of the NP parameter is generally associated with better performance. In individual datasets, the computation with NP=200 achieves the lowest error rate in many cases, such as in "ALCOHOL" (18.33%), "AUSTRALIAN" (21.49%), "BALANCE" (7.79%), "DERMATOLOGY" (4.97%), "ECOLI" (40.30%), and "HEART" (13.11%). In some of these datasets, the difference between NP=200 and the other two values is notable. For instance, in the "DERMATOLOGY" dataset, the error rate with NP=200 (4.97%) is significantly lower than the corresponding values for NP=50 (9.89%) and NP=100 (11.34%), highlighting the clear superiority of NP=200 for this dataset. However, there are also datasets where the differences are less pronounced. For example, in "PHONEME," the error rates are relatively close across all parameter values, with NP=200 showing the smallest error (18.10%). In some other datasets, such as "HOUSEVOTES," NP=50 has a lower error rate (3.91%) than the other two parameter values. This indicates that in certain datasets, increasing the NP parameter does not necessarily lead to improved performance. Similarly, in the "Z_F_S" dataset, NP=100 achieves the lowest error rate (6.73%), while NP=200 exhibits a higher rate (8.38%), suggesting that performance may also depend on the characteristics of the data. Despite these exceptions, NP=200 generally exhibits the best overall performance, achieving the lowest average error rate and delivering strong results across a wide range of datasets.

The analysis of Table 7 focuses on regression datasets, considering three distinct values for the critical parameter "NP" in the proposed machine learning model: NP=50, NP=100, and NP=200. The parameter NP=200 achieves the lowest average error (5.23), making it more effective than NP=100 (5.48) and NP=50 (5.92). This suggests that higher NP values are generally associated with improved performance. In specific datasets, NP=200 stands out for its superior performance. For instance, in "AIRFOIL" (0.002), "AUTO" (12.78), "BL"

(0.006), "CONCRETE" (0.006), "FRIEDMAN" (2.21), and "TREASURY" (0.68), the error values for NP=200 are the lowest. In the "FRIEDMAN" dataset, NP=200 (2.21) significantly outperforms NP=50 (3.43) and NP=100 (2.83), demonstrating its effectiveness. However, there are cases where other NP values show stronger performance. For example, in the "BK" dataset, NP=100 achieves the lowest error (0.018), while NP=200 (0.02) is slightly worse. Similarly, in the "FY" dataset, NP=100 exhibits the best performance (0.041), with NP=200 showing a higher error (0.067). Additionally, in the "BASEBALL" dataset, NP=100 outperforms NP=200, recording an error of 57.75 compared to 60.74. These variations indicate that the effectiveness of the NP parameter can depend on the characteristics of the dataset. Overall, NP=200 demonstrates the best average performance, highlighting its value in most cases. While other NP values achieve lower error rates in some datasets, NP=200 stands out for its general reliability and efficiency.

In Figure 6, focusing on classification datasets for different values of the critical parameter "NP" within the proposed model, the p-values are: NP=50 vs NP=100: $p=0.17$, NP=50 vs NP=200: $p=0.117$ and NP=100 vs NP=200: $p=0.032$. These results indicate that only the comparison between NP=100 and NP=200 demonstrates statistical significance.

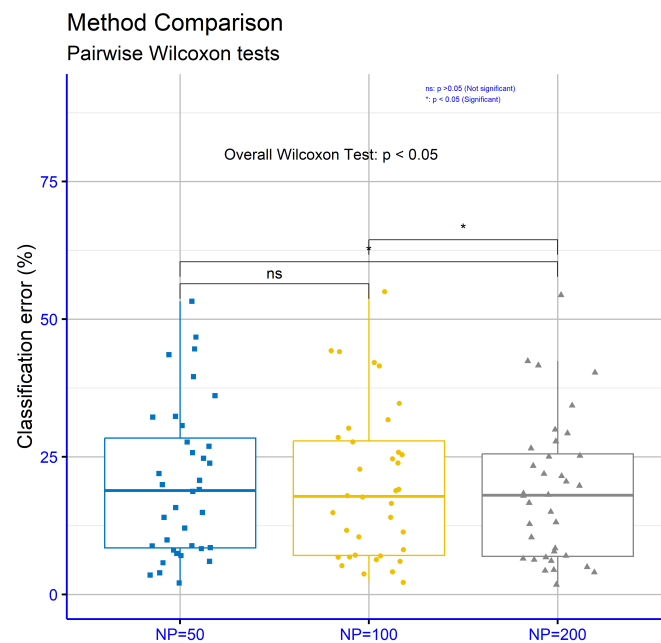


Figure 6. Statistical comparison for the experiments conducted on the classification datasets using the proposed method and different values for the parameter NP.

Finally, Figure 7 evaluates regression datasets for different values of the critical parameter "NP" within the proposed model. The respective p-values are: NP=50 vs NP=100: $p=0.08$, NP=50 vs NP=200: $p=0.012$ and NP=100 vs NP=200: $p=0.025$. These results show that the comparisons NP=50 vs NP=200 and NP=100 vs NP=200 exhibit statistically significant differences, while the comparison NP=50 vs NP=100 does not.

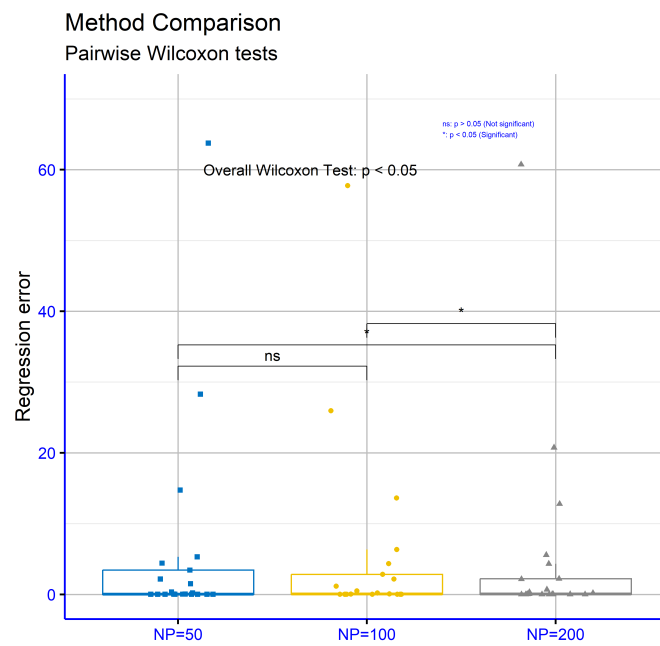


Figure 7. Statistical comparison for the conducted experiments on the regression datasets using the proposed method and different values of the parameter NP.

4. Conclusions

The proposed evolutionary method, based on differential evolution, proves to be highly effective in optimizing the weights of artificial neural networks, significantly reducing both training error and overfitting. Compared to other popular methods such as ADAM, BFGS, genetic algorithms, and RBF, the new approach demonstrates superior performance in classification tasks with an average error of 18.73% and regression tasks with an average error of 5.23%. Despite these positive results, certain datasets, such as "SEGMENT" and "STOCK," exhibit higher errors, likely due to data complexity or inherent noise that affects prediction accuracy. The random computation of parameter F and the use of a larger number of agents, such as NP=200, seem to enhance the system's performance. However, smaller NP values yield better results in some cases, indicating the necessity for adaptive parameter tuning mechanisms during the optimization process.

Future research could focus on applying the method to more complex or high-dimensional data, such as images, text, or time series, to evaluate its scalability and flexibility. Developing mechanisms for dynamic parameter tuning, such as F, CR, and NP, could eliminate the need for manual experimentation and enhance overall efficiency. Additionally, combining this evolutionary approach with other machine learning techniques, such as reinforcement learning or dynamic neural networks, may improve generalization and adaptability. Testing the method on different network architectures, such as recurrent neural networks (RNNs) or graph neural networks (GNNs), could provide valuable insights into its adaptability and flexibility across various contexts. Furthermore, a theoretical analysis of the algorithm's convergence and stability could offer a deeper understanding of its strengths and limitations. Finally, focused studies on datasets where the method underperforms could identify specific factors, such as noise, class imbalance, or feature complexity, and propose targeted optimizations to address these challenges effectively.

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