

Adapt the parameters of RBF networks using Grammatical Evolution

Ioannis G. Tsoulos^{1,†,‡,*}, Alexandros Tzallas², Evangelos Karvounis³

¹ Department of Informatics and Telecommunications, University of Ioannina, Greece; itsoulos@uoi.gr
² Department of Informatics and Telecommunications, University of Ioannina, Greece; tzallas@uoi.gr
³ Department of Informatics and Telecommunications, University of Ioannina, Greece; ekarvounis@uoi.gr
* Correspondence: itsoulos@uoi.gr;
[†] Current address: Department of Informatics and Telecommunications, University of Ioannina, Greece.
[‡] These authors contributed equally to this work.

Abstract: Radial basis function networks are widely used in a multitude of applications in various scientific areas in both classification and data fitting problems. These networks deal with the above problems by adjusting their parameters with various optimization techniques. However, an important issue to address is to locate a satisfactory interval for the parameters of the network before adjusting these parameters. This paper proposes a method of two stages, where in the first stage with the incorporation of Grammatical Evolution, rules are generated to create the optimal value interval of the network parameters. During the second stage of the technique, the mentioned parameters are fine-tuned with a genetic algorithm. The current work was tested on a number of datasets from the recent literature and found to reduce the classification or data fitting error by over 40% on most datasets. In addition, the proposed method appears in the experiments to be robust, as the fluctuation of the number of network parameters does not significantly affect its performance.

Keywords: Neural networks; Genetic algorithms; Genetic programming; Grammatical evolution

1. Introduction

Many practical problems of the modern world can be thought of either as data fitting problems, as for example, problems that appears in physics [1,2], problems related to chemistry [3,4], economic problems [5,6], medicine problems [7,8], etc. A commonly used machine learning tool to handle problems of this nature, is the Radial Basis Function (RBF) network [9,10]. Usually, an RBF network is expressed using the following equation:

$$y(\vec{x}) = \sum_{i=1}^k w_i \phi(\|\vec{x} - \vec{c}_i\|) \quad (1)$$

where the symbols in the equation are defined as follows:

1. The element \vec{x} represents the input pattern from the dataset describing the problem. For the rest of this paper, the notation d will be used to represent the number of elements in \vec{x} .
2. The parameter k denotes the number of weights used to train the RBF network and the associated vector of weights is denoted as \vec{w} .
3. The vectors \vec{c}_i , $i = 1, \dots, k$ stand for the centers of the model.
4. The value $y(\vec{x})$ represents the value of the network for the given pattern \vec{x} .

The $\phi(x)$ function, in most cases represent the Gaussian function given by:

$$\phi(x) = \exp\left(-\frac{(x - c)^2}{\sigma^2}\right) \quad (2)$$

Citation: Tsoulos, I.G.; Tzallas A; Karvounis E Adapt the parameters of RBF networks using Grammatical Evolution. *Journal Not Specified* **2023**, *1*, 0. <https://doi.org/>

Received:

Revised:

Accepted:

Published:

Copyright: © 2023 by the authors. Submitted to *Journal Not Specified* for possible open access publication under the terms and conditions of the Creative Commons Attribution (CC BY) license (<https://creativecommons.org/licenses/by/4.0/>).

The main advantages of RBF networks are:

1. They have a simpler structure than other models used in machine learning, such as multilayer perceptron neural networks (MLPs)[11], since they have only one processing layer and therefore have faster training techniques and they have faster response times.
2. They can be used to efficiently approximate any continuous function [12].

The RBF networks were applied in a variety of problems, such as problems from physics [13–16], solving differential equations [17–19], robotics [20,21], face recognition [22], digital communications [23,24], chemistry problems [25,26], economic problems [27–29], network security problems [30,31] etc. Also, recently a variety of papers have appeared proposing novel initialization techniques for the network parameters [32–34]. Also, Benoudjit et al [35] discuss the effect of kernel widths on RBF networks. Moreover, Neruda et al [36] presents a comparison of some learning methods for RBF networks. Additionally, a variety of pruning techniques [37–39] have been suggested in the literature for decreasing the number parameters. Due to the widespread usage of RBF networks but also because considerable computing time is often required for their effective training, in recent years a series of techniques have been published [40,41] for the exploitation of parallel computing units to adjust the parameters.

In the same direction of research, other machine learning models have been proposed, such as Support Vector Machines (SVM) [42,43], decision trees [44,45] etc. Also, Wang et al suggested an auto - encoder reduction method, applied on a series of large datasets[46]. Various methods have been proposed in the same direction, such as the work of Agarwal and Bhanot [47] proposed to adapt the RBF parameters, the usage of the ABC algorithm[48], the incorporation of the Firefly algorithm[49]. Furthermore, Gyamfi et al [50] recently proposed a differential RBF network that incorporates partial differential equations, aiming to make the network more robust in the presence of noise data. Also, Li et al [51] proposed a multivariate ensembles-based hierarchical linkage strategy (ME-HL) for system reliability evaluation of aeroengine cooling blades.

The parameters of the RBF network are modified in order to minimize the following loss - function, called training error of the network:

$$E(y(x, g)) = \sum_{i=1}^m (y(\vec{x}_i, \vec{g}) - t_i)^2 \quad (3)$$

Where the parameter m denotes the number of patterns, the t_i represent the expected output for pattern \vec{x}_i . The vector \vec{g} represents the parameter set of the network.

A common method of calculating the parameters in these neural networks uses a technique to calculate the centers of the functions $\phi(x)$ and then the vector of weights \vec{w} is calculated as a solution of a linear system of equations. Typically, the method used to calculate the centers is the well - known k-means method [52]. In many cases, this way of estimating the parameters leads to over-fitting of the model so that it cannot generalize satisfactorily to unknown data. Furthermore, since there is no range of values for the parameters, there is the possibility that they will take extremely large or extremely small values, with the result that any generalizability of the model is lost. This work suggests a two phase method to minimize the error of equation (3). During the first phase, an attempt is made to bound the parameter values to intervals at which the training error is likely to be significantly reduced. The identification of the most promising intervals for the parameters is performed using a technique that utilizes Grammatical Evolution[53], that collects information from the training data. During the second phase, the parameters can be trained inside the best located range of the first phase using some global optimization method [54,55]. In the proposed approach, the widely used method of genetic algorithm [56–58] was used for the second phase of the process. The main contributions of the suggested approach are:

1. The first phase procedure seeks to locate a range of values for the parameters, while also reducing the error of the network on the training data set.
2. The rules Grammatical Evolution uses in the first phase are simple and can be generalized to any data set for data classification or fitting.
3. The determination of the value interval is done in such a way that it is faster and more efficient to train the parameters with some optimization method during the second phase.
4. After identifying a promising value interval from the first phase, any global optimization method can be used on that value interval to effectively minimize the network training error.

The rest of this paper is divided in the following sections: in section 2 the proposed method is fully described, the section 3 presents the used datasets and the conducted experiments and finally in section 4 some a discussion on the conducted experiments is made.

2. Method description

This section starts with an extended presentation of the Grammatical Evolution technique and the grammar that will be used to generate partition rules for the parameter set of RBFs. Afterwards, the first phase of the proposed methodology will be extensively analyzed and then the second phase, where a Genetic Algorithm will be applied to the outcome of the first phase.

2.1. Grammatical Evolution

Grammatical evolution is a Genetic algorithm, where the chromosomes are integer numbers. Genetic Algorithms was initially proposed by John Holland [59] are biologically inspired algorithms. The algorithm starts by forming a population of potential solutions to an optimization problem. These solutions are called chromosomes and they are gradually altered using the genetic operators of selection, crossover and mutation[60]. The chromosomes in the Grammatical Evolution stand for series of production rules of any given BNF (Backus–Naur form) grammar[61]. Grammatical Evolution has been applied with success in a variety of cases, such as function approximation[62,63], solving equations related to trigonometry [64], automatic composition of music[65], construction of neural networks [66,67], producing numeric constraints[68], video games [69,70], estimation of energy demand[71], combinatorial optimization [72], cryptography [73] etc. The BNF grammar can be used to describe the syntax of programming languages and usually it is defined as $G = (N, T, S, P)$ where

- N is a set of the non - terminal symbols. A series of production rules is associated with every non - terminal symbol. The application of these production rules produces series of terminal symbols.
- T stands for the set of terminal symbols.
- S denotes the start symbol of the grammar and $S \in N$.
- P defines the set of production rules. These are rules are following the following notations: $A \rightarrow a$ or $A \rightarrow aB$, $A, B \in N$, $a \in T$.

The algorithm begins using the symbol S and gradually creates series of terminal symbols with the assistance of the production rules. The production rules are selected through the following procedure:

- Denote with V the next element from the current chromosome.
- The next production rule is calculated as: $\text{Rule} = V \bmod R$. The number R stands for the total number of production rules for non – terminal symbol which is currently under processing.

The Algorithm 1 shows the BNF grammar used by the proposed method. Each non - terminal symbol of the grammar is enclosed in $\langle \rangle$ symbol. The numbers that are enclosed in parentheses represent for the sequence numbers of production rules for every non -

terminal symbol. Every RBF network with k weights is constructed by the following series of parameters:

1. A series of vectors $\vec{c}_i, i = 1, \dots, k$ that stand for the centers of the model.
2. For every Gaussian unit an additional parameter σ_i is required.
3. The output weight vector \vec{w} .

The number n is the total number of parameters of the problem. In the case of this paper, it is the total number of parameters of the RBF network. For the current work, the number n can be computed using the following formula:

$$n = (d + 2) \times k \quad (4)$$

The number n in the corresponding grammar is computed as follows:

1. For each center $\vec{c}_i, i = 1, \dots, k$ there are d variables. As a consequence, every center required $d \times k$ parameters.
2. Every Gaussian unit requires an additional parameter: $\sigma_i, i = 1, \dots, k$, which means k more parameters.
3. The weight vector \vec{w} used in the output has k parameters.

As an example of production, the chromosome $x = [9, 8, 6, 4, 15, 9, 16, 23, 8]$ is considered where $d = 2, k = 2, n = 8$. The steps to produce the final program $p_{\text{test}} = (x_7, 0, 1), (x_1, 1, 0)$ are outlined in Table 1. Every partition program consists of a series of partition rules. Each partition rule contains three elements:

1. The variable for which its original interval will be partitioned, for example x_7 .
2. An integer number with values 0 and 1 at the left margin of the interval. If this value is 1, then the left margin of the corresponding variable's value field will be divided by two, otherwise no change will be made.
3. An integer number with values 0 and 1 at the right end of the range of values of the variable. If this value is 1, then the right end of the corresponding variable's value field will be divided by two, otherwise no change will be made.

Hence, for the example program p_{test} the two partition rules will divide the right end of the variable x_7 and the left end of the variable x_1 .

Algorithm 1 The BNF grammar used in the proposed method, to produce intervals for the RBF parameters. By using this grammar in the first phase of the current work, the optimal interval of values for the parameters will be identified.

```

S ::= <expr>      (0)
<expr> ::= (<xlist> , <digit>, <digit>) (0)
          | <expr>, <expr>              (1)
<xlist> ::= x1      (0)
          | x2 (1)
          | .....
          | xn (n)
<digit> ::= 0 (0)
          | 1 (1)

```

Table 1. The series of steps used to computer a valid expression from the BNF grammar for a given chromosome.

| Expression | Chromosome | Operation |
|------------------------------------|----------------------|------------|
| | 9,8,6,4,15,9,16,23,8 | 9 mod 2=1 |
| <expr>,<expr> | 8,6,4,15,9,16,23,8 | 8 mod 2=0 |
| (<xlist>,<digit>,<digit>),<expr> | 6,4,15,9,16,23,8 | 6 mod 8=6 |
| (x7,<digit>,<digit>),<expr> | 4,15,9,16,23,8 | 4 mod 2=0 |
| (x7,0,<digit>),<expr> | 15,9,16,23,8 | 15 mod 2=1 |
| (x7,0,1),<expr> | 9,16,23,8 | 9 mod 2 =1 |
| (x7,0,1),(<xlist>,<digit>,<digit>) | 16,23,8 | 16 mod 8=0 |
| (x7,0,1),(x1,<digit>,<digit>) | 23,8 | 23 mod 2=1 |
| (x7,0,1),(x1,1,<digit>) | 8 | 8 mod 2=0 |
| (x7,0,1),(x1,1,0) | | |

2.2. The first phase of the proposed algorithm

The purpose of this phase is to initialize the bounds of the RBF model and discover a promising interval for the corresponding values. For this initialization, the K-Means algorithm [52] technique is used, which is also used for the traditional RBF network training technique. A description of this algorithm in a series of steps is shown in Algorithm 2.

Algorithm 2 The K-Means algorithm.

1. Repeat

- (a) **Define** $S_j = \{\}, j = 1..k$
- (b) **For every** pattern $x_i, i = 1, ..., m$ **do**
 - i. **Compute** $j^* = \min_{i=1}^k \{D(x_i, c_j)\}$.
 - ii. **Compute** $S_{j^*} = S_{j^*} \cup \{x_i\}$.
- (c) **EndFor**
- (d) **For every** center $c_j, j = 1..k$ **do**
 - i. **Denote** as M_j the number of points in set S_j
 - ii. **Compute** c_j as

$$c_j = \frac{1}{M_j} \sum_{i=1}^{M_j} x_i$$

- (e) **EndFor**

2. **Compute** the quantities s_j as

$$\sigma_j^2 = \frac{\sum_{i=1}^{M_j} (x_i - c_j)^2}{M_j}$$

3. **Stop** the algorithm, if centers c_j do not change anymore.

Having calculated the centers c_i and the corresponding variances σ_i , the algorithm continues to compute the vectors \vec{L}, \vec{R} with dimension n , that will be used as the initial bounds of the parameters. The above vectors are calculated through the procedure of the algorithm 3.

Algorithm 3 The proposed algorithm used to locate the vectors \vec{L}, \vec{R}

1. **Set** $m=0$
 2. **Define** $F > 1$, the scaling factor.
 3. **Define** $B > 0$, the initial upper bound for the weight vector \vec{w} .
 4. **For** $i = 1..k$ **do**
 - (a) **For** $j = 1..d$ **do**
 - i. **Compute** $L_m = -F \times c_{ij}, R_m = F \times c_{ij}$
 - ii. **Compute** $m = m + 1$
 - (b) **EndFor**
 - (c) **Compute** $L_m = -F \times \sigma_i, R_m = F \times \sigma_i$
 - (d) **Compute** $m = m + 1$
 5. **EndFor**
 6. **For** $j = 1, \dots, k$ **do**
 - (a) **Compute** $L_m = -B, R_m = B$
 - (b) **Compute** $m = m + 1$
 7. **EndFor**
-

The range of values for the first $(d + 1) \times k$ parameters is estimated by multiplying the parameter F by the values already estimated by the K-Means algorithm. The bounds of the weight vector \vec{w} are initialized using the value B . Subsequently, genetic algorithm described here is performed to estimate the most promising range $[\vec{L}, \vec{R}]$ for the RBF parameters:

1. **Define** as N_c the number of chromosomes that will participate in the the Grammatical Evolution procedure.
2. **Define** as k the number of processing nodes of the used RBF model.
3. **Define** as N_g the number of allowed generations.
4. **Define** as p_s the used selection rate, with $p_s \leq 1$.
5. **Define** as p_m the used mutation rate, with $p_m \leq 1$.
6. **Define** as N_s as the total number of RBF networks that will be created randomly in every fitness calculation.
7. **Initialize** N_c chromosomes as sets of random numbers.
8. **Set** $f^* = [\infty, \infty]$, the fitness of the best chromosome. The fitness function f_g of any provided chromosome g is considered as an interval $f_g = [f_{g, \text{low}}, f_{g, \text{upper}}]$
9. **Set** $\text{iter}=0$.
10. **For** $i = 1, \dots, N_c$ **do**
 - (a) **Produce** the partition program p_i using the grammar of Figure 1 for the chromosome i .
 - (b) **Produce** the bounds $[\vec{L}_{p_i}, \vec{R}_{p_i}]$ for the partition program p_i .
 - (c) **Set** $E_{\min} = \infty, E_{\max} = -\infty$
 - (d) **For** $j = 1, \dots, N_s$ **do**
 - i. **Create** randomly a set of parameters $\vec{g}_j \in [\vec{L}_{p_i}, \vec{R}_{p_i}]$
 - ii. **Calculate** the error $E_{\vec{g}_j} = \sum_{k=1}^M (y(\vec{x}_k, \vec{g}_j) - t_k)^2$
 - iii. **If** $E_{\vec{g}_j} \leq E_{\min}$ **then** $E_{\min} = E_{\vec{g}_j}$
 - iv. **If** $E_{\vec{g}_j} \geq E_{\max}$ **then** $E_{\max} = E_{\vec{g}_j}$
 - (e) **EndFor**
 - (f) **Set** the fitness $f_i = [E_{\min}, E_{\max}]$
11. **EndFor**

12. **Perform** the procedure of selection: Initially, the chromosomes of the population are sorted according to their fitness values. Since the fitness values are intervals, the L^* operator is defined as:

$$L^*(f_a, f_b) = \begin{cases} \text{TRUE}, & a_1 < b_1, \text{OR } (a_1 = b_1 \text{ AND } a_2 < b_2) \\ \text{FALSE}, & \text{OTHERWISE} \end{cases} \quad (5)$$

As a consequence, the fitness value f_a is considered smaller than f_b if $L^*(f_a, f_b) = \text{TRUE}$. The first $(1 - p_s) \times N_c$ chromosomes with smaller fitness values are copied without changes to the next generation of the algorithm. The rest of chromosomes are replaced by chromosomes created in the crossover procedure.

13. **Perform** the crossover procedure. The crossover procedure will create new $p_s \times N_c$ chromosomes. For every pair of created offsprings two parents (z, w) are selected from the current population using the tournament selection. These parent will produce the offsprings \tilde{z} and \tilde{w} using the one - point crossover, shown in Figure 1.
14. **Perform** the mutation procedure. In this process a random number $r \in [0, 1]$ is drawn for every element of each chromosome. The corresponding element is changed randomly if $r \leq p_m$.
15. **Set** iter=iter+1
16. **If** iter $\leq N_g$ goto step 10.

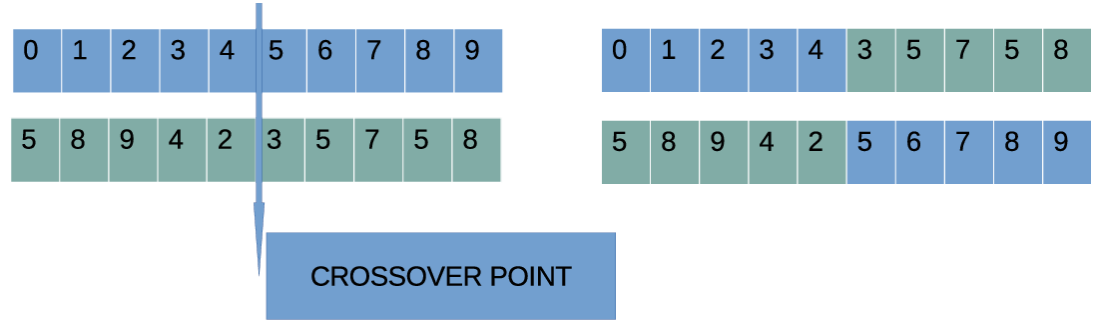


Figure 1. An example of the one point crossover procedure, as used in the Grammatical Evolution.

2.3. The second phase of the proposed algorithm

The second phase utilizes a genetic algorithm, to optimize the parameters of the RBF network. The optimization of the parameters uses as bounds the best interval produced in the first phase of the method. The layout of each chromosome is shown in Figure 2.

Figure 2. The layout of chromosomes in the second phase of the proposed algorithm.

| | | | | | | | | | | | | | | | | | | | |
|----------|----------|-----|----------|------------|----------|----------|-----|----------|------------|-----|----------|----------|-----|----------|------------|-------|-------|-----|-------|
| c_{11} | c_{12} | ... | c_{1d} | σ_1 | c_{21} | c_{22} | ... | c_{2d} | σ_2 | ... | c_{k1} | c_{k2} | ... | c_{kd} | σ_k | w_1 | w_2 | ... | w_k |
|----------|----------|-----|----------|------------|----------|----------|-----|----------|------------|-----|----------|----------|-----|----------|------------|-------|-------|-----|-------|

1. Initialization Step

- Define** as N_c as the number of chromosomes.
- Define** as N_g the total number of generations.
- Define** as k the number of processing nodes of the used RBF model.
- Define** as $S = [L_{\text{best}}, R_{\text{best}}]$ the best located interval of the first stage of the algorithm, of subsection 2.2.
- Produce** N_c random chromosomes in S .
- Define** as p_s the used selection rate, with $p_s \leq 1$.
- Define** as p_m the used mutation rate, with $p_m \leq 1$.
- Set** iter=0.

2. Fitness calculation Step

- (a) **For** $i = 1, \dots, N_g$ **do** 224
- i. **Compute** the fitness f_i of each chromosome g_i as $f_i = \sum_{j=1}^m (y(\vec{x}_j^i, \vec{g}_i) - t_j)_{225}^2$
- (b) **EndFor** 226
3. **Genetic operations step** 227
- (a) **Selection procedure.** Initially, the population is sorted according to the fitness 228
values. The first $(1 - p_s) \times N_c$ chromosomes with the lowest fitness values 229
remain intact. The rest of chromosomes are replaced by offsprings that will be 230
produced during the crossover procedure. 231
- (b) **Crossover procedure:** For every two new offsprings (\tilde{z}, \tilde{w}) , there are two 232
parents (z, w) that are selected from the current population with the selection 233
procedure of tournament selection. The offsprings are produced through the 234
following: 235
- $$\begin{aligned}\tilde{z}_i &= a_i z_i + (1 - a_i) w_i \\ \tilde{w}_i &= a_i w_i + (1 - a_i) z_i\end{aligned}\quad (6)$$
- The value a_i is a random number, where $a_i \in [-0.5, 1.5]$ [74]. 236
- (c) **Perform** the mutation procedure. In this process a random number $r \in [0, 1]$ is 237
drawn for every element of each chromosome. The corresponding element is 238
changed randomly if $r \leq p_m$. 239
4. **Termination Check Step** 240
- (a) **Set** $iter = iter + 1$ 241
- (b) **If** $iter \leq N_g$ **goto** step 2. 242

The steps of the current algorithm are also outlined graphically in Figure 3 using a flowchart. 243

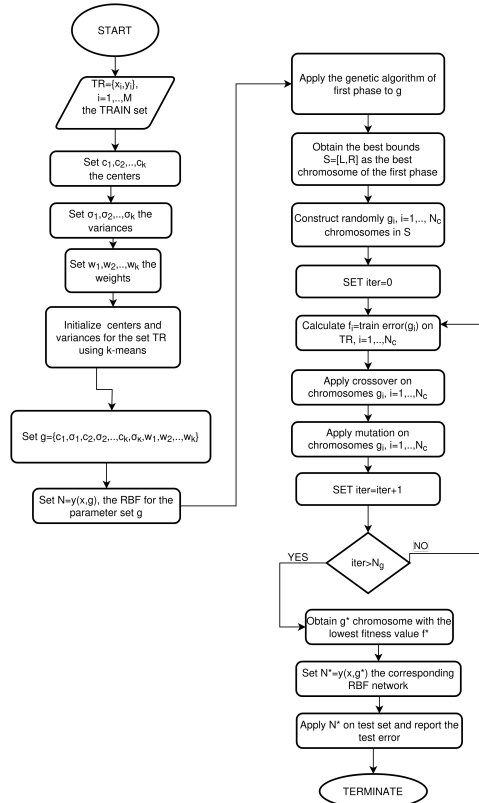


Figure 3. The flowchart of the proposed algorithm.

3. Experiments

3.1. Experimental datasets

The proposed method was tested on a wide set of classification and regression problems found in the relevant literature. The method was compared against some other well-known machine learning models. The following databases were used to obtain the datasets:

1. The UCI dataset repository, <https://archive.ics.uci.edu/ml/index.php> (accessed on 5 December 2023)
2. The Keel repository, <https://sci2s.ugr.es/keel/datasets.php> (accessed on 5 December 2023) [75].
3. The Statlib URL <http://lib.stat.cmu.edu/datasets/> (accessed on 5 December 2023).

The classification datasets are listed in Table 2 and the regression datasets are listed in Table 3.

Table 2. The classification datasets used in the experiments. The column DATASET denotes the number of the dataset, the column CLASSES stands for the number of classes in each dataset and the column REFERENCE points to the bibliography where the use of the particular data set is presented.

| DATASET | CLASSES | REFERENCE |
|---------------|---------|-----------|
| APPENDICITIS | 2 | [76] |
| AUSTRALIAN | 2 | [77] |
| BALANCE | 3 | [78] |
| CLEVELAND | 5 | [79,80] |
| DERMATOLOGY | 6 | [81] |
| HAYES ROTH | 3 | [82] |
| HEART | 2 | [83] |
| HOUSEVOTES | 2 | [84] |
| IONOSPHERE | 2 | [85,86] |
| LIVERDISORDER | 2 | [87] |
| MAMMOGRAPHIC | 2 | [88] |
| PARKINSONS | 2 | [89] |
| PIMA | 2 | [90] |
| POPFAILURES | 2 | [91] |
| SPIRAL | 2 | [92] |
| REGIONS2 | 5 | [93] |
| SAHEART | 2 | [94] |
| SEGMENT | 7 | [95] |
| WDBC | 2 | [96] |
| WINE | 3 | [97,98] |
| Z_F_S | 3 | [99] |
| ZO_NF_S | 3 | [99] |
| ZONF_S | 2 | [99] |
| ZOO | 7 | [100] |

Table 3. The regression datasets used in the experiments. The column DATASET denotes the number of the dataset and the column REFERENCE points to the bibliography or URL (KEEL or STATLIB) where the use of the particular data set is presented.

| DATASET | REFERENCE |
|----------|-----------|
| ABALONE | [101] |
| AIRFOIL | [102] |
| BASEBALL | STATLIB |
| BK | [103] |
| BL | STATLIB |
| CONCRETE | [104] |
| DEE | KEEL |
| DIABETES | KEEL |
| FA | STATLIB |
| HOUSING | [105] |
| MB | [106] |
| MORTGAGE | KEEL |
| NT | [107] |
| PY | [108] |
| QUAKE | [109] |
| TREASURY | KEEL |
| WANKARA | KEEL |

3.2. Experimental results

The RBF model used in the experiments was implemented in ANSI C++ with the assistance of the open source Armadillo library [110]. The optimization methods used were also freely available from the OPTIMUS software, available from <https://github.com/itsoulos/OPTIMUS/> (accessed on 5 December 2023). For validation purposed, the 10 - fold validation technique was used for all datasets and for all methods that participate in the experiments. Also, all the experiments were conducted 30 times and the seed number of the random generator was different in each execution. The average classification error is reported for the classification datasets and the average mean test error for the regression datasets. The machine used in the experiments was an AMD Ryzen 5950X with 128GB of RAM and the operating system was Debian Linux. The values of the parameters used in the experiments are shown in Table 4. The experimental results for the classification datasets are outlined in Table 5 and for the regression datasets are listed in Table 6. For the tables with the experimental results, the following applies:

1. The column RPROP represents an artificial neural network [111,112]. This neural network has 10 processing nodes and was trained using the Rprop method [113].
2. The column denoted as ADAM stands the application of the Adam optimizer [114,115] to train an artificial neural network with 10 hidden nodes.
3. The column NEAT (NeuroEvolution of Augmenting Topologies) [116] denotes the application of the NEAT method for neural network training.
4. The RBF-KMEANS column denotes the original two - phase training method for RBF networks.
5. The column GENRBF stands for the RBF training method introduced in [117].
6. The column PROPOSED stands for the results obtained using the proposed method.
7. In the experimental tables an additional row was added with the title AVERAGE. This row contains the average classification or regression error for all datasets.

Table 4. The values used for the experimental parameters.

| PARAMETER | VALUE |
|-----------|-------|
| N_c | 200 |
| N_g | 100 |
| N_s | 50 |
| F | 10.0 |
| B | 100.0 |
| k | 10 |
| p_s | 0.90 |
| p_m | 0.05 |

Table 5. The first column denotes the name of the classification dataset and the the numbers in cells represent classification error for every method used in the experiments. The last row stands for the average classification error for all datasets.

| DATASET | RPROP | ADAM | NEAT | RBF-KMEANS | GENRBF | PROPOSED |
|----------------|---------------|---------------|---------------|---------------|---------------|---------------|
| Appendicitis | 16.30% | 16.50% | 17.20% | 12.23% | 16.83% | 15.77% |
| Australian | 36.12% | 35.65% | 31.98% | 34.89% | 41.79% | 22.40% |
| Balance | 8.81% | 7.87% | 23.14% | 33.42% | 38.02% | 15.62% |
| Cleveland | 61.41% | 67.55% | 53.44% | 67.10% | 67.47% | 50.37% |
| Dermatology | 15.12% | 26.14% | 32.43% | 62.34% | 61.46% | 35.73% |
| Hayes Roth | 37.46% | 59.70% | 50.15% | 64.36% | 63.46% | 35.33% |
| Heart | 30.51% | 38.53% | 39.27% | 31.20% | 28.44% | 15.91% |
| HouseVotes | 6.04% | 7.48% | 10.89% | 6.13% | 11.99% | 3.33% |
| Ionosphere | 13.65% | 16.64% | 19.67% | 16.22% | 19.83% | 9.30% |
| Liverdisorder | 40.26% | 41.53% | 30.67% | 30.84% | 36.97% | 28.44% |
| Mammographic | 18.46% | 46.25% | 22.85% | 21.38% | 30.41% | 17.72% |
| Parkinsons | 22.28% | 24.06% | 18.56% | 17.41% | 33.81% | 14.53% |
| Pima | 34.27% | 34.85% | 34.51% | 25.78% | 27.83% | 23.33% |
| Popfailures | 4.81% | 5.18% | 7.05% | 7.04% | 7.08% | 4.68% |
| Regions2 | 27.53% | 29.85% | 33.23% | 38.29% | 39.98% | 25.18% |
| Saheart | 34.90% | 34.04% | 34.51% | 32.19% | 33.90% | 29.46% |
| Segment | 52.14% | 49.75% | 66.72% | 59.68% | 54.25% | 49.22% |
| Spiral | 46.59% | 48.90% | 50.22% | 44.87% | 50.02% | 23.58% |
| Wdbc | 21.57% | 35.35% | 12.88% | 7.27% | 8.82% | 5.20% |
| Wine | 30.73% | 29.40% | 25.43% | 31.41% | 31.47% | 5.63% |
| Z_F_S | 29.28% | 47.81% | 38.41% | 13.16% | 23.37% | 3.90% |
| ZO_NF_S | 6.43% | 47.43% | 43.75% | 9.02% | 22.18% | 3.99% |
| ZONF_S | 27.27% | 11.99% | 5.44% | 4.03% | 17.41% | 1.67% |
| ZOO | 15.47% | 14.13% | 20.27% | 21.93% | 33.50% | 9.33% |
| AVERAGE | 26.56% | 32.36% | 30.11% | 28.84% | 33.35% | 18.73% |

Table 6. The first column denotes the name of the regression dataset and the the numbers in cells represent regression error for every method used in the experiments. The last row stands for the average regression error for all datasets.

| DATASET | RPROP | ADAM | NEAT | RBF-KMEANS | GENRBF | PROPOSED |
|----------------|--------------|--------------|--------------|--------------|--------------|-------------|
| ABALONE | 4.55 | 4.30 | 9.88 | 7.37 | 9.98 | 5.16 |
| AIRFOIL | 0.002 | 0.005 | 0.067 | 0.27 | 0.121 | 0.004 |
| BASEBALL | 92.05 | 77.90 | 100.39 | 93.02 | 98.91 | 81.26 |
| BK | 1.60 | 0.03 | 0.15 | 0.02 | 0.023 | 0.025 |
| BL | 4.38 | 0.28 | 0.05 | 0.013 | 0.005 | 0.0004 |
| CONCRETE | 0.009 | 0.078 | 0.081 | 0.011 | 0.015 | 0.006 |
| DEE | 0.608 | 0.630 | 1.512 | 0.17 | 0.25 | 0.16 |
| DIABETES | 1.11 | 3.03 | 4.25 | 0.49 | 2.92 | 1.74 |
| HOUSING | 74.38 | 80.20 | 56.49 | 57.68 | 95.69 | 21.11 |
| FA | 0.14 | 0.11 | 0.19 | 0.015 | 0.15 | 0.033 |
| MB | 0.55 | 0.06 | 0.061 | 2.16 | 0.41 | 0.19 |
| MORTGAGE | 9.19 | 9.24 | 14.11 | 1.45 | 1.92 | 0.014 |
| NT | 0.04 | 0.12 | 0.33 | 8.14 | 0.02 | 0.007 |
| PY | 0.039 | 0.09 | 0.075 | 0.012 | 0.029 | 0.019 |
| QUAKE | 0.041 | 0.06 | 0.298 | 0.07 | 0.79 | 0.034 |
| TREASURY | 10.88 | 11.16 | 15.52 | 2.02 | 1.89 | 0.098 |
| WANKARA | 0.0003 | 0.02 | 0.005 | 0.001 | 0.002 | 0.003 |
| AVERAGE | 11.71 | 11.02 | 11.97 | 10.17 | 12.54 | 6.46 |

On average, the current work appears to be 30-40% more accurate than the immediate best. In many cases, this percentage exceeds 70%. Moreover, in the vast majority of problems, the proposed technique significantly outperforms the next best available method in terms of test error. In order to validate the results, an additional experiment was executed on the classification datasets, where the number of nodes increases from 5 to 20 and the results are graphically outlined in Figure 4. From this experiment, one can draw two conclusions: firstly, the proposed technique has a significant advantage over the others to a large extent in terms of average classification error, and secondly, the proposed method is shown to be robust and not significantly dependent on the increase of processing nodes, since 5–10 processing nodes are enough to achieve low classification errors.



Figure 4. Average classification error for all classification datasets. The number of nodes increases from 5 to 20 and three models were used: the ADAM optimizer to optimize a neural network, the original RBF training method of two phases and the proposed method.

However, the proposed technique consists of two stages and in each of them a genetic algorithm should be executed. This means that it is significantly slower in computing time compared to the rest of the techniques and, of course, it needs more computing resources. This is graphically shown in Figure 5, where the average execution time for the method ADAM and the proposed method is shown for the classification datasets, when the number of processing nodes increases from 5 to 20. As expected, the current work requires significantly more time than a simple optimization technique such as ADAM, since it consists of two sequential genetic algorithms.

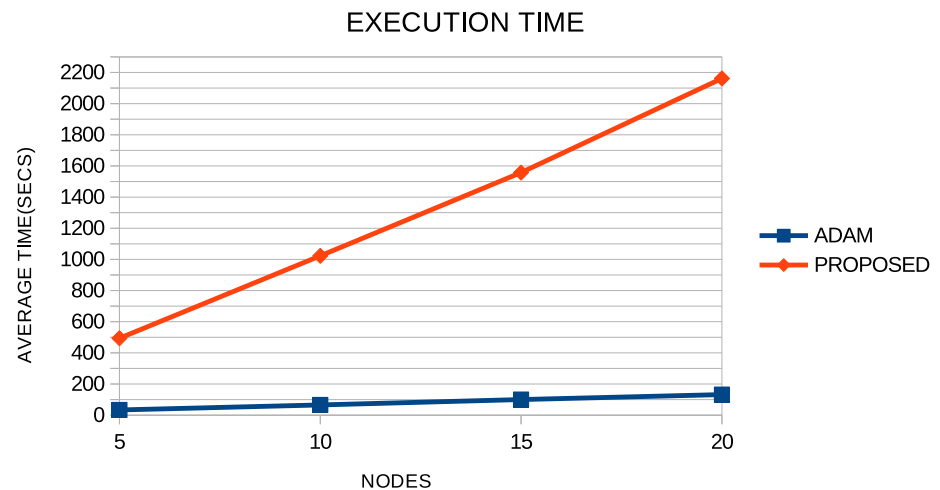


Figure 5. Average execution time for the ADAM optimizer used to train a neural network and the proposed technique.

Of course, since we are talking about Genetic Algorithms, the training time required could be significantly reduced by using parallel techniques that take advantage of modern parallel computing structures such as the MPI interface [118] or the OpenMP library [119]. The superiority of the proposed technique is also reinforced by the statistical tests carried out on the experimental results and outlined in figure 6.

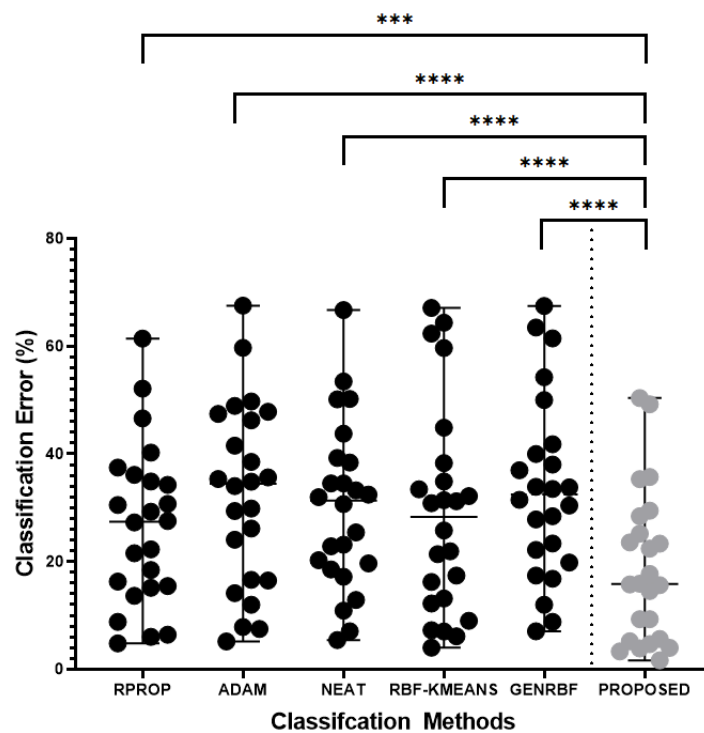


Figure 6. Scatter plot representation and the two-sample paired (Wilcoxon) signed-rank test results of the comparison for each of the five (5) classification methods (RPROP, ADAM, NEAT, RBF-KMEANS, and GENRBF) against the PROPOSED method regarding the error on the twenty-four (24) classification datasets. The stars only intend to flag significance levels for the two most used groups. A p-value of less than 0.001 is flagged with three stars (**). A p-value of less than 0.0001 is flagged with four stars (****).

In addition, an additional set of experiments was executed on the classification data. In this set of experiments the critical parameter F took the values 3, 5 and 10. The aim of this set of experiments was to establish the sensitivity of the proposed method to changes in its parameters. The experimental results are presented in the table 7 and a statistical test on the results is presented in figure 7. The results and the statistics test indicate that there is no significant difference in the efficiency of the method for different values of the critical parameter F .

Table 7. The following table presents experimental results from the use of the proposed technique in classification problems and for different values of the critical parameter F .

| DATASET | $F = 3$ | $F = 5$ | $F = 10$ |
|---------------|---------|---------|----------|
| Appendicitis | 15.57% | 16.60% | 15.77% |
| Australian | 24.29% | 23.94% | 22.40% |
| Balance | 17.22% | 15.39% | 15.62% |
| Cleveland | 52.09% | 51.65% | 50.37% |
| Dermatology | 37.23% | 36.81% | 35.73% |
| Hayes Roth | 35.72% | 32.31% | 35.33% |
| Heart | 16.32% | 15.54% | 15.91% |
| HouseVotes | 4.35% | 3.90% | 3.33% |
| Ionosphere | 12.50% | 11.44% | 9.30% |
| Liverdisorder | 28.08% | 28.19% | 28.44% |
| Mammographic | 17.49% | 17.15% | 17.72% |
| Parkinsons | 16.25% | 15.17% | 14.53% |
| Pima | 23.29% | 23.97% | 23.33% |
| Popfailures | 5.31% | 5.86% | 4.68% |
| Regions2 | 25.97% | 26.29% | 25.18% |
| Saheart | 28.52% | 28.59% | 29.46% |
| Segment | 44.95% | 48.77% | 49.22% |
| Spiral | 15.49% | 18.19% | 23.58% |
| Wdbc | 5.43% | 5.01% | 5.20% |
| Wine | 7.59% | 8.39% | 5.63% |
| Z_F_S | 4.37% | 4.26% | 3.90% |
| ZO_NF_S | 3.79% | 4.21% | 3.99% |
| ZONF_S | 2.34% | 2.26% | 1.67% |
| ZOO | 11.90% | 10.50% | 9.33% |
| AVERAGE | 19.03% | 18.93% | 18.73% |

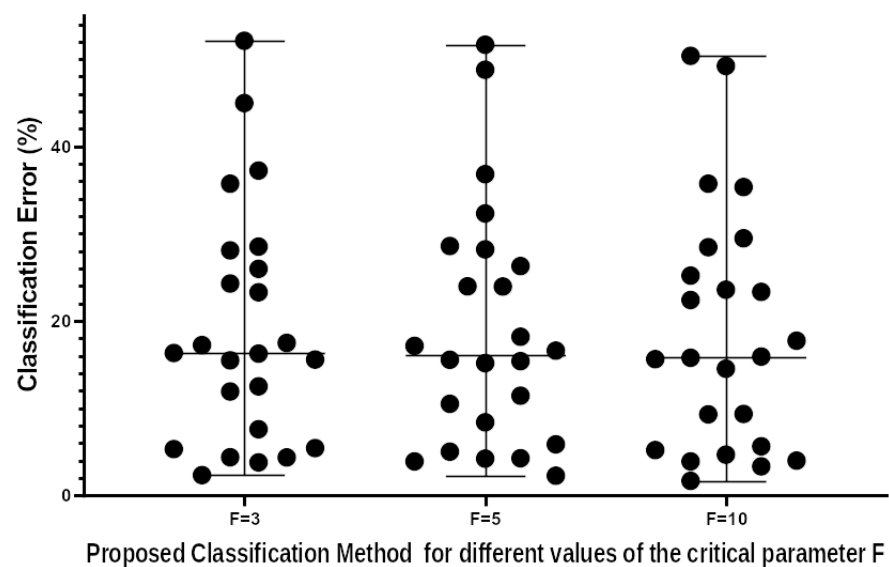


Figure 7. A Friedman test was conducted to find out whether different values of the critical parameter F had a difference or not in the classification error of the proposed method in twenty-four (24) other publicly available classification datasets. The analysis results for three different values of the critical parameter F ($F=3$, $F=5$, $F=10$) indicated no significant difference.

4. Conclusions

In the current work, an innovative two-stage technique was proposed for efficient training of RBF artificial neural networks. In the first stage of the application, using Grammatical Evolution, the interval of values of the neural network parameters is partitioned, so as to find a promising range that may contain low values of the training error. In the second stage, the neural network parameters are trained within the best range of values found in the first stage. The training of the parameters of the second phase is carried out using a Genetic Algorithm. The proposed method was applied on a wide series of well-known datasets from the relevant literature and was tested against a series of machine learning models. The new training technique was compared with the traditional method of training RBF networks but also with other machine learning models and from the experimental results its superiority is evident in percentages that exceed 40%. However, since the proposed technique include two genetic algorithms that are executed sequentially, the execution time required is longer compared to other techniques especially for datasets with many patterns. An immediate solution to increase the speed of the method would be the use of parallel computing techniques, since genetic algorithms can by nature be directly parallelized.

Future improvements to the proposed method may include:

1. The proposed method can be applied to other variants of artificial neural networks.
2. Use of intelligent learning techniques in place of the K-Means technique to initialize the neural network parameters.
3. Using techniques to dynamically determine the number of necessary parameters of the neural network. For the time being, the number of parameters is considered constant, but this has the consequence of observing over-training phenomena in various data sets.
4. Implementation of crossover and mutation techniques that focus more on the existing interval construction technique for the model parameters.
5. Use of efficient termination techniques for Genetic Algorithms, for the most efficient termination of techniques without wasting computing time on unnecessary iterations.
6. Usage of techniques that are based on parallel programming to increase the speed of the method.

Author Contributions: I.G.T., A.T. and E.K. conceived the idea and methodology and supervised the technical part regarding the software. I.G.T. executed the experiments, employing several datasets. A.T. performed the statistical analysis and all authors prepared the manuscript. All authors have read and agreed to the published version of the manuscript.

Funding: This research received no external funding.

Institutional Review Board Statement: Not applicable.

Informed Consent Statement: Not applicable.

Data Availability Statement: Not applicable.

Acknowledgments: This research has been financed by the European Union : Next Generation EU through the Program Greece 2.0 National Recovery and Resilience Plan , under the call RESEARCH – CREATE – INNOVATE, project name “iCREW: Intelligent small craft simulator for advanced crew training using Virtual Reality techniques” (project code:TAEDK-06195)

Conflicts of Interest: The authors declare no conflict of interest.

References

1. M. Mjahed, The use of clustering techniques for the classification of high energy physics data, *Nuclear Instruments and Methods in Physics Research Section A: Accelerators, Spectrometers, Detectors and Associated Equipment* **559**, pp. 199-202, 2006.
2. M Andrews, M Paulini, S Gleyzer, B Poczoz, End-to-End Event Classification of High-Energy Physics Data, *Journal of Physics: Conference Series* **1085**, 2018.

3. P. He, C.J. Xu, Y.Z. Liang, K.T. Fang, Improving the classification accuracy in chemistry via boosting technique, *Chemometrics and Intelligent Laboratory Systems* **70**, pp. 39-46, 2004. 362
4. J.A. Aguiar, M.L. Gong, T.Tasdzien, Crystallographic prediction from diffraction and chemistry data for higher throughput classification using machine learning, *Computational Materials Science* **173**, 109409, 2020. 363
5. I. Kaastra, M. Boyd, Designing a neural network for forecasting financial and economic time series, *Neurocomputing* **10**, pp. 215-236, 1996. 364
6. R. Hafezi, J. Shahrabi, E. Hadavandi, A bat-neural network multi-agent system (BNNMAS) for stock price prediction: Case study of DAX stock price, *Applied Soft Computing* **29**, pp. 196-210, 2015. 365
7. S.S. Yadav, S.M. Jadhav, Deep convolutional neural network based medical image classification for disease diagnosis. *J Big Data* **6**, 113, 2019. 366
8. L. Qing, W. Linhong, D. Xuehai, A Novel Neural Network-Based Method for Medical Text Classification, *Future Internet* **11**, 255, 2019. 367
9. J. Park and I. W. Sandberg, Universal Approximation Using Radial-Basis-Function Networks, *Neural Computation* **3**, pp. 246-257, 1991. 368
10. G.A. Montazer, D. Giveki, M. Karami, H. Rastegar, Radial basis function neural networks: A review. *Comput. Rev. J* **1**, pp. 52-74, 2018. 369
11. O.I. Abiodun, A. Jantan, A. E. Omolara, K.V. Dada, N. A. Mohamed, H. Arshad, State-of-the-art in artificial neural network applications: A survey, *Heliyon* **4**, e00938, 2018. 370
12. Y. Liao, S. C. Fang, and H. L. W. Nuttle, "Relaxed conditions for radial-basis function networks to be universal approximators," *Neural Networks*, vol. 16, no. 7, pp. 1019–1028, 2003. 371
13. P. Teng, Machine-learning quantum mechanics: Solving quantum mechanics problems using radial basis function networks, *Phys. Rev. E* **98**, 033305, 2018. 372
14. R. Jovanović, A. Sretenovic, Ensemble of radial basis neural networks with K-means clustering for heating energy consumption prediction, *FME Transactions* **45**, pp. 51-57, 2017. 373
15. V.I. Gorbachenko, M.V. Zhukov, Solving boundary value problems of mathematical physics using radial basis function networks. *Comput. Math. and Math. Phys.* **57**, pp. 145–155, 2017. 374
16. J. Määttä, V. Bazaliy, J. Kimari, F. Djurabekova, K. Nordlund, T. Roos, Gradient-based training and pruning of radial basis function networks with an application in materials physics, *Neural Networks* **133**, pp. 123-131, 2021. 375
17. Nam Mai-Duy, Thanh Tran-Cong, Numerical solution of differential equations using multiquadric radial basis function networks, *Neural Networks* **14**, pp. 185-199, 2001. 376
18. N. Mai-Duy, Solving high order ordinary differential equations with radial basis function networks. *Int. J. Numer. Meth. Engng.* **62**, pp. 824-852, 2005. 377
19. S.A. Sarra, Adaptive radial basis function methods for time dependent partial differential equations, *Applied Numerical Mathematics* **54**, pp. 79-94, 2005. 378
20. R. -J. Lian, Adaptive Self-Organizing Fuzzy Sliding-Mode Radial Basis-Function Neural-Network Controller for Robotic Systems, *IEEE Transactions on Industrial Electronics* **61**, pp. 1493-1503, 2014. 379
21. M. Vijay, D. Jena, Backstepping terminal sliding mode control of robot manipulator using radial basis functional neural networks. *Computers & Electrical Engineering* **67**, pp. 690-707, 2018. 380
22. M.J. Er, S. Wu, J. Lu, H.L. Toh, Face recognition with radial basis function (RBF) neural networks, *IEEE Transactions on Neural Networks* **13**, pp. 697-710, 2002. 381
23. C. Laoudias, P. Kemppi and C. G. Panayiotou, Localization Using Radial Basis Function Networks and Signal Strength Fingerprints in WLAN, *GLOBECOM 2009 - 2009 IEEE Global Telecommunications Conference*, Honolulu, HI, 2009, pp. 1-6, 2009. 382
24. M. Azarbad, S. Hakimi, A. Ebrahimzadeh, Automatic recognition of digital communication signal, *International journal of energy, information and communications* **3**, pp. 21-33, 2012. 383
25. D.L. Yu, J.B. Gomm, D. Williams, Sensor fault diagnosis in a chemical process via RBF neural networks, *Control Engineering Practice* **7**, pp. 49-55, 1999. 384
26. V. Shankar, G.B. Wright, A.L. Fogelson, R.M. Kirby, A radial basis function (RBF) finite difference method for the simulation of reaction–diffusion equations on stationary platelets within the augmented forcing method, *Int. J. Numer. Meth. Fluids* **75**, pp. 1-22, 2014. 385
27. W. Shen, X. Guo, C. Wu, D. Wu, Forecasting stock indices using radial basis function neural networks optimized by artificial fish swarm algorithm, *Knowledge-Based Systems* **24**, pp. 378-385, 2011. 386
28. J. A. Momoh, S. S. Reddy, Combined Economic and Emission Dispatch using Radial Basis Function, 2014 IEEE PES General Meeting | Conference & Exposition, National Harbor, MD, pp. 1-5, 2014. 387
29. P. Sohrabi, B. Jodeiri Shokri, H. Dehghani, Predicting coal price using time series methods and combination of radial basis function (RBF) neural network with time series. *Miner Econ* 2021. 388
30. U. Ravale, N. Marathe, P. Padiya, Feature Selection Based Hybrid Anomaly Intrusion Detection System Using K Means and RBF Kernel Function, *Procedia Computer Science* **45**, pp. 428-435, 2015. 389
31. M. Lopez-Martin, A. Sanchez-Esguevillas, J. I. Arribas, B. Carro, Network Intrusion Detection Based on Extended RBF Neural Network With Offline Reinforcement Learning, *IEEE Access* **9**, pp. 153153-153170, 2021. 390

32. L.I. Kuncheva, Initializing of an RBF network by a genetic algorithm, *Neurocomputing* **14**, pp. 273-288, 1997. 421
33. F. Ros, M. Pintore, A. Deman, J.R. Chr tien, Automatical initialization of RBF neural networks, *Chemometrics and Intelligent Laboratory Systems* **87**, pp. 26-32, 2007. 422
34. D. Wang, X.J. Zeng, J.A. Keane, A clustering algorithm for radial basis function neural network initialization, *Neurocomputing* **77**, pp. 144-155, 2012. 423
35. N. Benoudjit, M. Verleysen, On the Kernel Widths in Radial-Basis Function Networks, *Neural Processing Letters* **18**, pp. 139-154, 2003. 424
36. R. Neruda, P. Kudova, Learning methods for radial basis function networks, *Future Generation Computer Systems* **21**, pp. 1131-1142, 2005. 425
37. E. Ricci, R. Perfetti, Improved pruning strategy for radial basis function networks with dynamic decay adjustment, *Neurocomputing* **69**, pp. 1728-1732, 2006. 426
38. Guang-Bin Huang, P. Saratchandran and N. Sundararajan, A generalized growing and pruning RBF (GGAP-RBF) neural network for function approximation, *IEEE Transactions on Neural Networks* **16**, pp. 57-67, 2005. 427
39. M. Bortman and M. Aladjem, A Growing and Pruning Method for Radial Basis Function Networks, *IEEE Transactions on Neural Networks* **20**, pp. 1039-1045, 2009. 428
40. R. Yokota, L.A. Barba, M. G. Knepley, PetRBF — A parallel O(N) algorithm for radial basis function interpolation with Gaussians, *Computer Methods in Applied Mechanics and Engineering* **199**, pp. 1793-1804, 2010. 429
41. C. Lu, N. Ma, Z. Wang, Fault detection for hydraulic pump based on chaotic parallel RBF network, *EURASIP J. Adv. Signal Process.* **2011**, 49, 2011. 430
42. A. Iranmehr, H. Masnadi-Shirazi, N. Vasconcelos, Cost-sensitive support vector machines, *Neurocomputing* **343**, pp. 50-64, 2019. 431
43. J. Cervantes, F.G. Lamont, L.R. Mazahua, A. Lopez, A comprehensive survey on support vector machine classification: Applications, challenges and trends, *Neurocomputing* **408**, pp. 189-215, 2020. 432
44. S.B. Kotsiantis, Decision trees: a recent overview, *Artif Intell Rev* **39**, pp. 261-283, 2013. 433
45. D. Bertsimas, J. Dunn, Optimal classification trees, *Mach Learn* **106**, pp. 1039-1082, 2017. 434
46. Y. Wang, H. Yao, S. Zhao, Auto-encoder based dimensionality reduction, *Neurocomputing* **184**, pp. 232-242, 2016. 435
47. V. Agarwal, S. Bhanot, Radial basis function neural network-based face recognition using firefly algorithm, *Neural Comput & Applic* **30**, pp. 2643-2660, 2018. 436
48. S. Jiang et al., Prediction of Ecological Pressure on Resource-Based Cities Based on an RBF Neural Network Optimized by an Improved ABC Algorithm, *IEEE Access.* **7**, pp. 47423-47436, 2019. 437
49. I.U. Khan, N. Aslam, R. Alshehri, S. Alzahrani, M. Alghamdi, A. Almalki, M. Balabeed, Cervical Cancer Diagnosis Model Using Extreme Gradient Boosting and Bioinspired Firefly Optimization, *Scientific Programming* **2021**, Article ID 5540024, 2021. 438
50. K.S. Gyamfi, J. Brusey, E. Gaura, Differential radial basis function network for sequence modelling, *Expert Systems with Applications* **189**, 115982, 2022. 439
51. X.Q. Li, L.K. Song, Y.S. Choy, G.C. Bai, Multivariate ensembles-based hierarchical linkage strategy for system reliability evaluation of aeroengine cooling blades, *Aerospace Science and Technology* **138**, 108325, 2023. 440
52. J. MacQueen, Some methods for classification and analysis of multivariate observations, in: *Proceedings of the fifth Berkeley symposium on mathematical statistics and probability*, Vol. 1, No. 14, pp. 281-297, 1967. 441
53. M. O'Neill, C. Ryan, Grammatical evolution, *IEEE Trans. Evol. Comput.* **5**, pp. 349-358, 2001. 442
54. H.Q. Wang, D.S. Huang, B. Wang, Optimisation of radial basis function classifiers using simulated annealing algorithm for cancer classification. *electronics letters* **41**, pp. 630-632, 2005. 443
55. V. Fathi, G.A. Montazer, An improvement in RBF learning algorithm based on PSO for real time applications, *Neurocomputing* **111**, pp. 169-176, 2013. 444
56. D. Goldberg, *Genetic Algorithms in Search, Optimization and Machine Learning*, Addison-Wesley Publishing Company, Reading, Massachussets, 1989. 445
57. Z. Michalewicz, *Genetic Algorithms + Data Structures = Evolution Programs*. Springer - Verlag, Berlin, 1996. 446
58. S.A. Grady, M.Y. Hussaini, M.M. Abdullah, Placement of wind turbines using genetic algorithms, *Renewable Energy* **30**, pp. 259-270, 2005. 447
59. J.H. Holland, Genetic algorithms. *Scientific american* **267**, pp. 66-73, 1992. 448
60. J. Stender, *Parallel Genetic Algorithms: Theory & Applications*. Edition: IOS Press, 1993. 449
61. J. W. Backus. The Syntax and Semantics of the Proposed International Algebraic Language of the Zurich ACM-GAMM Conference. *Proceedings of the International Conference on Information Processing, UNESCO*, 1959, pp.125-132. 450
62. C. Ryan, J. Collins, M. O'Neill, Grammatical evolution: Evolving programs for an arbitrary language. In: Banzhaf, W., Poli, R., Schoenauer, M., Fogarty, T.C. (eds) *Genetic Programming. EuroGP 1998. Lecture Notes in Computer Science*, vol 1391. Springer, Berlin, Heidelberg, 1998. 451
63. M. O'Neill, M., C. Ryan, Evolving Multi-line Compilable C Programs. In: Poli, R., Nordin, P., Langdon, W.B., Fogarty, T.C. (eds) *Genetic Programming. EuroGP 1999. Lecture Notes in Computer Science*, vol 1598. Springer, Berlin, Heidelberg, 1999. 452
64. C. Ryan, M. O'Neill, J.J. Collins, Grammatical evolution: Solving trigonometric identities, *proceedings of Mendel*. Vol. 98. 1998. 453
65. A.O. Puente, R. S. Alfonso, M. A. Moreno, Automatic composition of music by means of grammatical evolution, In: *APL '02: Proceedings of the 2002 conference on APL: array processing languages: lore, problems, and applications July 2002 Pages 148-155*. 454

66. Lídio Mauro Limade Campo, R. Célio Limã Oliveira, Mauro Roisenberg, Optimization of neural networks through grammatical evolution and a genetic algorithm, *Expert Systems with Applications* **56**, pp. 368-384, 2016. 480
67. K. Soltanian, A. Ebneenasir, M. Afsharchi, Modular Grammatical Evolution for the Generation of Artificial Neural Networks, *Evolutionary Computation* **30**, pp 291–327, 2022. 481
68. I. Dempsey, M.O' Neill, A. Brabazon, Constant creation in grammatical evolution, *International Journal of Innovative Computing and Applications* **1** , pp 23–38, 2007. 482
69. E. Galván-López, J.M. Swafford, M. O'Neill, A. Brabazon, Evolving a Ms. PacMan Controller Using Grammatical Evolution. In: , et al. *Applications of Evolutionary Computation. EvoApplications 2010. Lecture Notes in Computer Science*, vol 6024. Springer, Berlin, Heidelberg, 2010. 483
70. N. Shaker, M. Nicolau, G. N. Yannakakis, J. Togelius, M. O'Neill, Evolving levels for Super Mario Bros using grammatical evolution, *2012 IEEE Conference on Computational Intelligence and Games (CIG)*, 2012, pp. 304-31. 484
71. D. Martínez-Rodríguez, J. M. Colmenar, J. I. Hidalgo, R.J. Villanueva Micó, S. Salcedo-Sanz, Particle swarm grammatical evolution for energy demand estimation, *Energy Science and Engineering* **8**, pp. 1068-1079, 2020. 485
72. N. R. Sabar, M. Ayob, G. Kendall, R. Qu, Grammatical Evolution Hyper-Heuristic for Combinatorial Optimization Problems, *IEEE Transactions on Evolutionary Computation* **17**, pp. 840-861, 2013. 486
73. C. Ryan, M. Kshirsagar, G. Vaidya, G. et al. Design of a cryptographically secure pseudo random number generator with grammatical evolution. *Sci Rep* **12**, 8602, 2022. 487
74. P. Kaelo, M.M. Ali, Integrated crossover rules in real coded genetic algorithms, *European Journal of Operational Research* **176**, pp. 60-76, 2007. 488
75. J. Alcalá-Fdez, A. Fernandez, J. Luengo, J. Derrac, S. García, L. Sánchez, F. Herrera. KEEL Data-Mining Software Tool: Data Set Repository, Integration of Algorithms and Experimental Analysis Framework. *Journal of Multiple-Valued Logic and Soft Computing* **17**, pp. 255-287, 2011. 489
76. Weiss, Sholom M. and Kulikowski, Casimir A., *Computer Systems That Learn: Classification and Prediction Methods from Statistics, Neural Nets, Machine Learning, and Expert Systems*, Morgan Kaufmann Publishers Inc, 1991. 490
77. J.R. Quinlan, Simplifying Decision Trees. *International Journal of Man-Machine Studies* **27**, pp. 221-234, 1987. 491
78. T. Shultz, D. Mareschal, W. Schmidt, Modeling Cognitive Development on Balance Scale Phenomena, *Machine Learning* **16**, pp. 59-88, 1994. 492
79. Z.H. Zhou, Y. Jiang, NeC4.5: neural ensemble based C4.5," in *IEEE Transactions on Knowledge and Data Engineering* **16**, pp. 770-773, 2004. 493
80. R. Setiono , W.K. Leow, FERNN: An Algorithm for Fast Extraction of Rules from Neural Networks, *Applied Intelligence* **12**, pp. 15-25, 2000. 494
81. G. Demiroz, H.A. Govenir, N. Ilter, Learning Differential Diagnosis of Eryhemato-Squamous Diseases using Voting Feature Intervals, *Artificial Intelligence in Medicine*. **13**, pp. 147–165, 1998. 495
82. B. Hayes-Roth, B., F. Hayes-Roth. Concept learning and the recognition and classification of exemplars. *Journal of Verbal Learning and Verbal Behavior* **16**, pp. 321-338, 1977. 496
83. I. Kononenko, E. Šimec, M. Robnik-Šikonja, Overcoming the Myopia of Inductive Learning Algorithms with RELIEFF, *Applied Intelligence* **7**, pp. 39–55, 1997 497
84. R.M. French, N. Chater, Using noise to compute error surfaces in connectionist networks: a novel means of reducing catastrophic forgetting, *Neural Comput.* **14**, pp. 1755-1769, 2002. 498
85. J.G. Dy , C.E. Brodley, Feature Selection for Unsupervised Learning, *The Journal of Machine Learning Research* **5**, pp 845–889, 2004. 499
86. S. J. Perantonis, V. Virvilis, Input Feature Extraction for Multilayered Perceptrons Using Supervised Principal Component Analysis, *Neural Processing Letters* **10**, pp 243–252, 1999. 500
87. J. Garcke, M. Griebel, Classification with sparse grids using simplicial basis functions, *Intell. Data Anal.* **6**, pp. 483-502, 2002. 501
88. M. Elter, R. Schulz-Wendtland, T. Wittenberg, The prediction of breast cancer biopsy outcomes using two CAD approaches that both emphasize an intelligible decision process, *Med Phys.* **34**, pp. 4164-72, 2007. 502
89. Little MA, McSharry PE, Hunter EJ, Spielman J, Ramig LO. Suitability of dysphonia measurements for telemonitoring of Parkinson's disease. *IEEE Trans Biomed Eng.* 2009;56(4):1015. doi:10.1109/TBME.2008.2005954 503
90. J.W. Smith, J.E. Everhart, W.C. Dickson, W.C. Knowler, R.S. Johannes, Using the ADAP learning algorithm to forecast the onset of diabetes mellitus, In: *Proceedings of the Symposium on Computer Applications and Medical Care IEEE Computer Society Press*, pp.261-265, 1988. 504
91. D.D. Lucas, R. Klein, J. Tannahill, D. Ivanova, S. Brandon, D. Domyancic, Y. Zhang, Failure analysis of parameter-induced simulation crashes in climate models, *Geoscientific Model Development* **6**, pp. 1157-1171, 2013. 505
92. D. Gavrilis, I.G. Tsoulos, E. Dermatas, Selecting and constructing features using grammatical evolution, *Pattern Recognition Letters* **29**, pp. 1358-1365, 2008. 506
93. Giannakeas, N., Tsipouras, M.G., Tzallas, A.T., Kyriakidi, K., Tsianou, Z.E., Manousou, P., Hall, A., Karvounis, E.C., Tsianos, V., Tsianos, E. A clustering based method for collagen proportional area extraction in liver biopsy images (2015) *Proceedings of the Annual International Conference of the IEEE Engineering in Medicine and Biology Society, EMBS*, 2015-November, art. no. 7319047, pp. 3097-3100. 507

94. T. Hastie, R. Tibshirani, Non-parametric logistic and proportional odds regression, *JRSS-C (Applied Statistics)* **36**, pp. 260–276, 1987. 539
95. M. Dash, H. Liu, P. Scheuermann, K. L. Tan, Fast hierarchical clustering and its validation, *Data & Knowledge Engineering* **44**, pp. 109–138, 2003. 540
96. W.H. Wolberg, O.L. Mangasarian, Multisurface method of pattern separation for medical diagnosis applied to breast cytology, *Proc Natl Acad Sci U S A.* **87**, pp. 9193–9196, 1990. 543
97. M. Raymer, T.E. Doom, L.A. Kuhn, W.F. Punch, Knowledge discovery in medical and biological datasets using a hybrid Bayes classifier/evolutionary algorithm. *IEEE transactions on systems, man, and cybernetics. Part B, Cybernetics : a publication of the IEEE Systems, Man, and Cybernetics Society*, **33**, pp. 802-813, 2003. 544
98. P. Zhong, M. Fukushima, Regularized nonsmooth Newton method for multi-class support vector machines, *Optimization Methods and Software* **22**, pp. 225-236, 2007. 545
99. R.G. Andrzejak, K. Lehnertz, F. Mormann, C. Rieke, P. David, and C. E. Elger, Indications of nonlinear deterministic and finite-dimensional structures in time series of brain electrical activity: Dependence on recording region and brain state, *Phys. Rev. E* **64**, pp. 1-8, 2001. 546
100. M. Koivisto, K. Sood, Exact Bayesian Structure Discovery in Bayesian Networks, *The Journal of Machine Learning Research* **5**, pp. 549–573, 2004. 547
101. W. J Nash, T.L. Sellers, S.R. Talbot, A.J. Cawthor, W.B. Ford, The Population Biology of Abalone (*Haliotis* species) in Tasmania. I. Blacklip Abalone (*H. rubra*) from the North Coast and Islands of Bass Strait, Sea Fisheries Division, Technical Report No. 48 (ISSN 1034-3288), 1994. 548
102. T.F. Brooks, D.S. Pope, and A.M. Marcolini. Airfoil self-noise and prediction. Technical report, NASA RP-1218, July 1989. 549
103. J.S. Simonoff, *Smoothing Methods in Statistics*, Springer - Verlag, 1996. 550
104. I.Cheng Yeh, Modeling of strength of high performance concrete using artificial neural networks, *Cement and Concrete Research*. **28**, pp. 1797-1808, 1998. 551
105. D. Harrison and D.L. Rubinfeld, Hedonic prices and the demand for clean ai, *J. Environ. Economics & Management* **5**, pp. 81-102, 1978. 552
106. J.S. Simonoff, *Smoothing Methods in Statistics*, Springer - Verlag, 1996. 553
107. Mackowiak, P.A., Wasserman, S.S., Levine, M.M., 1992. A critical appraisal of 98.6 degrees f, the upper limit of the normal body temperature, and other legacies of Carl Reinhold August Wunderlich. *J. Amer. Med. Assoc.* **268**, 1578–1580 554
108. R.D. King, S. Muggleton, R. Lewis, M.J.E. Sternberg, *Proc. Nat. Acad. Sci. USA* **89**, pp. 11322–11326, 1992. 555
109. M. Sikora, L. Wrobel, Application of rule induction algorithms for analysis of data collected by seismic hazard monitoring systems in coal mines, *Archives of Mining Sciences* **55**, pp. 91-114, 2010. 556
110. C. Sanderson, R. Curtin, Armadillo: a template-based C++ library for linear algebra, *Journal of Open Source Software* **1**, pp. 26, 2016. 557
111. C. Bishop, *Neural Networks for Pattern Recognition*, Oxford University Press, 1995. 558
112. G. Cybenko, Approximation by superpositions of a sigmoidal function, *Mathematics of Control Signals and Systems* **2**, pp. 303-314, 1989. 559
113. M. Riedmiller and H. Braun, A Direct Adaptive Method for Faster Backpropagation Learning: The RPROP algorithm, *Proc. of the IEEE Intl. Conf. on Neural Networks*, San Francisco, CA, pp. 586–591, 1993. 560
114. D. P. Kingma, J. L. Ba, ADAM: a method for stochastic optimization, in: *Proceedings of the 3rd International Conference on Learning Representations (ICLR 2015)*, pp. 1–15, 2015. 561
115. Y. Xue, Y. Tong, F. Neri, An ensemble of differential evolution and Adam for training feed-forward neural networks. *Information Sciences* **608**, pp. 453-471, 2022. 562
116. K. O. Stanley, R. Miikkulainen, Evolving Neural Networks through Augmenting Topologies, *Evolutionary Computation* **10**, pp. 99-127, 2002. 563
117. S. Ding, L. Xu, C. Su et al, An optimizing method of RBF neural network based on genetic algorithm. *Neural Comput & Applic* **21**, pp. 333–336, 2012. 564
118. W. Gropp, E. Lusk, N. Doss, A. Skjellum, A high-performance, portable implementation of the MPI message passing interface standard, *Parallel Computing* **22**, pp. 789-828, 1996. 565
119. R. Chandra, L. Dagum, D. Kohr, D. Maydan, J. McDonald and R. Menon, *Parallel Programming in OpenMP*, Morgan Kaufmann Publishers Inc., 2001. 566