

Constructing the Bounds for Neural network training using Grammatical Evolution

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Abstract: Artificial neural networks are widely established models of computational intelligence that have been tested for effectiveness in a variety of real-world applications. These models require fitting a set of parameters through the use of some optimization technique. However, an issue that researchers often face is finding an efficient range of values for the parameters of the artificial neural network. This paper proposes an innovative technique of generating a promising range of values for the parameters of the artificial neural network. Finding the value field is done by a series of rules for partitioning the original set of values or expanding it, which rules are generated using Grammatical Evolution. After finding a promising interval of values, any optimization technique such as a genetic algorithm can be used to train the artificial neural network on that interval of values. The new technique was tested on a wide range of problems from the relevant literature and the results were extremely promising.

Keywords: Neural networks; Genetic algorithms; Grammatical Evolution

1. Introduction

Artificial neural networks (ANNs) are widespread machine learning models, which base their dynamics on a series of parameters which are also called computational units or weights in the relevant literature [1,2]. Neural networks are widely used in a variety of scientific applications, such as problems from physics [3–5], solutions of differential equations [6,7], agriculture problems [8,9], chemistry problems [10–12], problems that appear in the area of economic sciences [13–15], problems related to medicine [16,17] etc. Commonly, the neural networks are expressed as a function $N(\vec{x}, \vec{w})$, with the assumption that the vector \vec{x} stands for the input vector to the neural network and the vector \vec{w} is the parameter vector that should be estimated. The first vector is called pattern in the bibliography and the second one weight vector. Techniques that adjust the parameter vector \vec{w} minimize the so-called training error, defined as:

$$E(N(\vec{x}, \vec{w})) = \sum_{i=1}^M (N(\vec{x}_i, \vec{w}) - y_i)^2 \quad (1)$$

In equation 1 the set (\vec{x}_i, y_i) , $i = 1, \dots, M$ is denoted as the train set of the neural network. The y_i are considered the target outputs for the \vec{x}_i points. As proposed in [18], neural networks can be expressed as the following summation:

$$N(\vec{x}, \vec{w}) = \sum_{i=1}^H w_{(d+2)i-(d+1)} \sigma \left(\sum_{j=1}^d x_j w_{(d+2)i-(d+1)+j} + w_{(d+2)i} \right) \quad (2)$$

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The number of processing units is denoted by H and the value d stands for the dimension of input vector \vec{x} . The function $\sigma(x)$ denotes the well - known sigmoid function expressed as:

$$\sigma(x) = \frac{1}{1 + \exp(-x)} \quad (3)$$

From the above equations one can calculated the total number of parameters in the neural network as:

$$n = (d + 2)H \quad (4)$$

The training of neural networks has been performed by a variety of numerical methods in recent bibliography, such as: the Back Propagation method [19], the RPROP method [20], the Adam optimizer [21] etc. Furthermore, more advanced optimization methods have been incorporated to optimize the parameter vector of neural networks by minimizing equation 1 such as Quasi Newton methods [22], the Tabu Search method [23], Simulated Annealing [24], genetic Algorithms [25], Particle Swarm Optimization (PSO) [26], Differential Evolution [27], Ant Colony Optimization [28] etc.

Also, recently a series of hybrid optimization methods have been proposed to tackle the minimization of the training error, such as a method that combines PSO and genetic algorithms [29,30], incorporation of a particle swarm optimization algorithm and gravitational search algorithm [31], a combination of a genetic algorithm and controlled gradient method [32] etc.

In addition, an important topic for artificial neural networks such as parameter initialization has been studied by several researchers in recent years. In this area appeared papers such as initialization with decision trees [33], incorporation of the Cauchy's inequality [34], discriminant learning [35] etc. Also, another interesting topic in the area of neural networks is weight decaying, where some regularization is applied to the parameters of the neural network to avoid the overfitting problem. For this topic, several research papers have been suggested, such as a method that incorporates positive correlation [36], the SarProp algorithm [37], usage of pruning techniques [38] etc.

This paper proposes a two-stage method for efficient training of the parameters of artificial neural networks. In the first stage, a value interval is constructed for the parameters of the neural network through Grammatical Evolution [39]. In the first stage of this work, after an initial estimate of the interval for the parameters of the neural network is made, a series of rules for partitioning and expanding the initial value interval are applied with the usage of Grammatical Evolution, until a promising value interval is found. In the second stage of the method, a genetic algorithm is applied to train the parameters of the artificial neural network. Training is performed within the optimal interval of values found in the first stage of the method. The proposed method utilizes a genetic algorithm in the second stage to train the neural network, but any other optimization method can be used instead of genetic algorithms. However, genetic algorithms are used because they are easily adaptable to many optimization problems, they are fault tolerant and because they can be easily parallelized using modern computing techniques.

The proposed method seeks in its first stage to find, using an evolutionary rule technique, a range of values for the parameters of the artificial neural networks. This interval should on the one hand be small enough to speed up the method of the second stage that will be used to train the model and on the other hand the artificial neural network should have satisfactory generalization abilities within the interval of values of the first stage.

The rest of this article is organized as follows: in section 2 the steps of the proposed method are outlined in detail, in section 3 the datasets used in the conducted experiments as well the experimental results are presented and finally in section 4 some conclusions are presented.

2. Method description

In this section a detailed description of the Grammatical Evolution technique is provided, accompanied by the proposed language that creates intervals for the parameters of the neural networks. Subsequently, the first phase of the proposed technique is described and finally, the second phase with the application of a genetic algorithm to the outcome of the first phase, is thoroughly analyzed.

2.1. Grammatical evolution

Grammatical evolution is an evolutionary process, where the chromosomes represent production rules of some provided BNF (Backus–Naur form) grammar [40] and this evolutionary process can evolve programs in the underlying language. Grammatical Evolution has been used successfully in many real world problems, such as function approximation [41,42], solution of trigonometric equations [43], automatic music composition [44], neural network construction [45,46], creating numeric constraints [47], video games [48,49], estimation of energy demand [50], combinatorial optimization [51], cryptography [52], evolution of decision trees [53], automatic design of analog electronic circuits [54] etc. Any BNF grammar can be described as the set $G = (N, T, S, P)$ where

- N is the set of the non-terminal symbols. Every symbol in N has a series of production rules, used to produce terminal symbols.
- T is the set of terminal symbols.
- S denotes the start symbol of the grammar, with $S \in N$.
- P is the set of production rules, to create terminal symbols non - terminal symbols. These rules are in the form $A \rightarrow a$ or $A \rightarrow aB$, $A, B \in N$, $a \in T$.

The algorithm initiates from the symbol S and iteratively produces terminal symbols by replacing non-terminal symbols with the right hand of the selected production rule. Every production rule is selected using the following steps:

- Get the next element V from the current chromosome.
- Select the next production rule according to: $\text{Rule} = V \bmod N_R$, where N_R is the total number of production rules for the current non – terminal symbol.

The grammar used in the current work is shown in Figure 1.

```

S ::= <expr>      (0)
<expr> ::= (<xlist> , <lcommand>, <rcommand>) (0)
          | <expr>, <expr>                    (1)
<xlist> ::= x1    (0)
          | x2    (1)
          | .....
          | xn    (n)
<left_command> ::= NOTHING (0)
          | EXPAND (1)
          | DIVIDE (2)
<right_command> ::= NOTHING (0)
          | EXPAND (1)
          | DIVIDE (2)

```

Figure 1. BNF grammar used in the current work. The value n stands for the number of total parameters in the neural network.

The symbols in $\langle \rangle$ represent the non-terminal symbols of the grammar. The numbers in parentheses in the right part of each rule, indicate production rule sequence numbers. In the proposed language described by the grammar of the scheme, three distinct operations can be applied to parameters of the artificial neural network either on the left end of the parameter's value range (described by $\langle \text{lcommand} \rangle$) or on the right end of the value range (described by the $\langle \text{rcommand} \rangle$ symbol). These commands are

1. NOTHING. This command means that no action takes place. 111
2. EXPAND. With this command, the corresponding end of the value field is extended by 50% of the width of the field. 112
3. DIVIDE. With this command, the corresponding end of the value field is shrunk by 50% of the width of the field. 113

As a complete example consider a neural network with $H = 2$ hidden nodes and the dimension of the objective problem is set to $d = 2$. Hence, the total number of parameters in the neural network is $n = (d + 2)H = 8$. Also, for reasons of simplicity, we consider that the initial range of values for all parameters of the artificial neural network is the interval $[-2, 2]$ and is denoted as a the set of intervals 114

$$I_N = \{[-2, 2], [-2, 2], [-2, 2], [-2, 2], [-2, 2], [-2, 2], [-2, 2], [-2, 2]\} \quad (5) \quad 115$$

and consider also the chromosome 121

$$x = [9, 8, 6, 4, 15, 9, 16, 23, 7]$$

The steps to produce the final program 122

$$p_{\text{test}} = (x7, \text{EXPAND}, \text{NOTHING}), (x1, \text{DIVIDE}, \text{EXPAND})$$

are shown in Table 1. 123

Table 1. Steps to produce a valid expression from the BNF grammar.

Expression	Chromosome	Operation
	9,8,6,4,15,9,16,23,8	$9 \bmod 2 = 1$
$\langle \text{expr} \rangle, \langle \text{expr} \rangle$	8,6,4,15,9,16,23,8	$8 \bmod 2 = 0$
$(\langle \text{xlist} \rangle, \langle \text{lcommand} \rangle, \langle \text{rcommand} \rangle), \langle \text{expr} \rangle$	6,4,15,9,16,23,8	$6 \bmod 8 = 6$
$(x7, \langle \text{lcommand} \rangle, \langle \text{rcommand} \rangle), \langle \text{expr} \rangle$	4,15,9,16,23,8	$4 \bmod 3 = 1$
$(x7, \text{EXPAND}, \langle \text{rcommand} \rangle), \langle \text{expr} \rangle$	15,9,16,23,8	$15 \bmod 3 = 0$
$(x7, \text{EXPAND}, \text{NOTHING}), \langle \text{expr} \rangle$	9,16,23,8	$9 \bmod 2 = 1$
$(x7, \text{EXPAND}, \text{NOTHING}), (\langle \text{xlist} \rangle, \langle \text{lcommand} \rangle, \langle \text{rcommand} \rangle)$	16,23,8	$16 \bmod 8 = 0$
$(x7, \text{EXPAND}, \text{NOTHING}), (x1, \langle \text{lcommand} \rangle, \langle \text{rcommand} \rangle)$	23,8	$23 \bmod 3 = 2$
$(x7, \text{EXPAND}, \text{NOTHING}), (x1, \text{DIVIDE}, \langle \text{rcommand} \rangle)$	8	$8 \bmod 3 = 2$
$(x7, \text{EXPAND}, \text{NOTHING}), (x1, \text{DIVIDE}, \text{EXPAND})$		

After the application of the program p_{test} to the original interval I_N of equation 5, the new set has as follows: 124

$$I_N = \{[-4, 2], [-2, 2], [-2, 2], [-2, 2], [-2, 2], [-2, 2], [0, 4], [-2, 2]\} \quad (6) \quad 125$$

2.2. The first phase of the proposed method 126

Before starting the process of creating partitioning rules and expanding the value interval of the neural network weights, an initial estimate of this interval should be made. In the present work, only a few steps of a genetic algorithm are applied to make an initial estimate of the value interval. At the end of the genetic algorithm, the chromosome with the best value is the 127

$$IX = (IX_1, IX_2, \dots, IX_n) \quad (7) \quad 128$$

So, the initial interval set for the parameters of the neural network is calculated as 129

$$I_N = \{[-IX_1, IX_1], [-IX_2, IX_2], \dots, [-IX_n, IX_n]\} \quad (8) \quad 130$$

The first phase of the proposed technique will accept the set I_N as input and seek to compute a new set by reducing the training error of the artificial neural network. The first step is mainly a genetic algorithm and the corresponding steps are as follows: 131

1. **Set** N_c as the number of chromosomes for the Grammatical Evolution. 136
2. **Set** as H the number of weights for the neural network. 137
3. **Set** N_g the maximum number of allowed generations. 138
4. **Set** as p_s the selection rate, with $p_s \leq 1$. 139
5. **Set** as p_m the mutation rate, with $p_m \leq 1$. 140
6. **Set** N_s as the number of randomly created neural networks, that will be used in the fitness calculation. 141
7. **Initialize** randomly the N_c chromosomes. Every chromosome is a set of integer numbers used to produce valid programs through Grammatical Evolution and the associated grammar of Figure 1. 142
8. **Set** $f^* = [\infty, \infty]$, the best discovered fitness. For this algorithm, we consider the fitness function f_g of any given chromosome g as an interval $f_g = [f_{g,\text{low}}, f_{g,\text{upper}}]$ 143
9. **Set** iter=0. 144
10. **For** $i = 1, \dots, N_c$ **do** 145
 - (a) **Create** for the chromosome c_i the corresponding program p_i using the grammar of Figure 1. 146
 - (b) **Apply** the program p_i to I_N in order to produce the bounds $[L_{p_i}, R_{p_i}]$. 147
 - (c) **Set** $E_{\min} = \infty$, $E_{\max} = -\infty$ 148
 - (d) **For** $j = 1, \dots, N_s$ **do** 149
 - i. **Create** randomly $g_j \in [L_{p_i}, R_{p_i}]$ as a set for the parameters of neural network. 150
 - ii. **Calculate** the associated training error $E_{g_j} = \sum_{k=1}^M (N(\vec{x}_k, \vec{g}_j) - y_k)^2$ 151
 - iii. **If** $E_{g_j} \leq E_{\min}$ **then** $E_{\min} = E_{g_j}$ 152
 - iv. **If** $E_{g_j} \geq E_{\max}$ **then** $E_{\max} = E_{g_j}$ 153
 - (e) **EndFor** 154
 - (f) **Set** $f_i = [E_{\min}, E_{\max}]$ as the fitness value for the chromosome c_i . 155
11. **EndFor** 156
12. **Apply** the selection procedure. Firstly, the chromosomes are sorted with correspondence to their fitness values. Since fitness is considered an interval, a fitness comparison function is required. For this reason the operator $L^*(f_a, f_b)$ to compare two fitness values $f_a = [a_1, a_2]$ and $f_b = [b_1, b_2]$ as follows: 157

$$L^*(f_a, f_b) = \begin{cases} \text{TRUE}, & a_1 < b_1, \text{ OR } (a_1 = b_1 \text{ AND } a_2 < b_2) \\ \text{FALSE}, & \text{OTHERWISE} \end{cases} \quad (9)$$

In practice this means that the fitness value f_a is considered smaller than f_b if $L^*(f_a, f_b) = \text{TRUE}$. The first $(1 - p_s) \times N_c$ chromosomes with the lowest fitness values are copied to the next generation. The remaining chromosomes are substituted by chromosomes produced by the crossover procedure. During the selection process, for every new offspring, two chromosomes are selected as parents from the population using well - known procedure of tournament selection. 167

13. **Apply** the crossover procedure. For each pair (z, w) of parents, two new chromosomes \tilde{z} and \tilde{w} are created using the one - point crossover, graphically shown in Figure 2. 168
14. **Apply** the mutation procedure. For each element of every chromosome alter the corresponding element with probability p_m . 169
15. **Set** iter=iter+1 170
16. **If** iter $\leq N_g$ **goto** step 10. 171

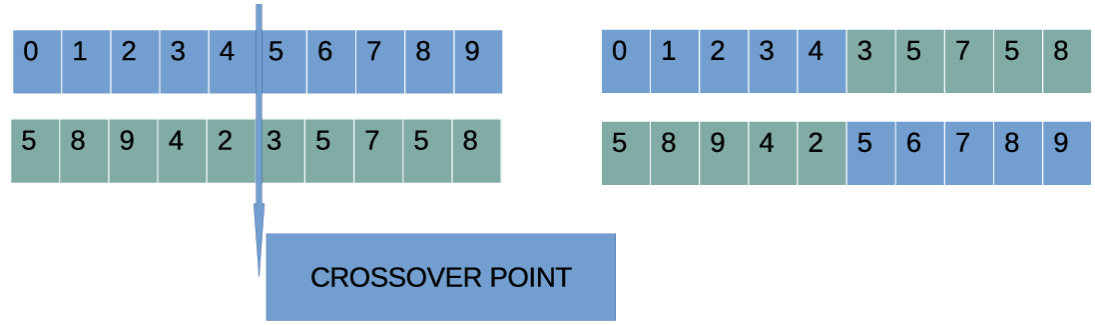


Figure 2. The one point crossover, used in the Grammatical Evolution.

2.3. The second phase of the proposed method

1. Initialization Step

- (a) Set N_c as the number of chromosomes that participate in the genetic algorithm.
- (b) Set N_g the maximum number of allowed iterations.
- (c) Set H the number of weights for the neural network.
- (d) Get the best interval S from the previous step of subsection 2.2.
- (e) Initialize using uniform distribution the N_c chromosomes in S .
- (f) Set as p_s the selection rate, with $p_s \leq 1$.
- (g) Set as p_m the mutation rate, with $p_m \leq 1$.
- (h) Set $iter=0$.

2. Fitness calculation Step

- (a) For $i = 1, \dots, N_g$ do
 - i. Calculate the fitness f_i of chromosome g_i as $f_i = \sum_{j=1}^M (N(\vec{x}_j, \vec{g}_i) - y_j)^2$

(b) EndFor

3. Genetic operations step

- (a) **Selection procedure.** Initially, the chromosomes are sorted according to their fitness values. The first $(1 - p_s) \times N_c$ chromosomes with the lowest fitness values are copied to the next generation. The remaining chromosomes are substituted by chromosomes produced by the crossover procedure. During the selection process, for every new offspring, two chromosomes are selected as parents from the population using well - known procedure of tournament selection.
- (b) **Crossover procedure:** For each pair (z, w) of selected parents, two chromosomes \tilde{z} and \tilde{w} are constructed using the following equations:

$$\begin{aligned}\tilde{z}_i &= a_i z_i + (1 - a_i) w_i \\ \tilde{w}_i &= a_i w_i + (1 - a_i) z_i\end{aligned}\quad (10)$$

Where a_i is random number with the property $a_i \in [-0.5, 1.5]$ [55].

- (c) **Mutation procedure:** For each element of every chromosome alter the corresponding element with probability p_m .

4. Termination Check Step

- (a) Set $iter = iter + 1$
- (b) If $iter \leq N_g$ goto step 2. else apply a local search procedure to the best chromosome of the population. In the current work the BFGS variant of Powell [56] was used.

3. Experiments

The effectiveness of the proposed method was evaluated on a series of classification and regression datasets, used in the relevant literature. These datasets can be downloaded from the following online databases:

1. UCI dataset repository, <https://archive.ics.uci.edu/ml/index.php>[57].
2. Keel repository, <https://sci2s.ugr.es/keel/datasets.php>[58].
3. The Statlib URL <ftp://lib.stat.cmu.edu/datasets/index.html>.

3.1. Experimental datasets

The classification datasets used in this paper are the following:

1. **Appendictis** a medical purpose dataset, suggested in [59].
2. **Australian** dataset [60], a dataset related to credit card transactions.
3. **Balance** dataset [61], related to psychological states.
4. **Cleveland** dataset, which is a medical dataset [62,63].
5. **Dermatology** dataset [64], a medical dataset related to erythemato-squamous diseases.
6. **Heart** dataset [65], a medical dataset related to heart diseases.
7. **Hayes roth** dataset [66].
8. **HouseVotes** dataset [67], related to votes in the U.S. House of Representatives Congressmen.
9. **Ionosphere** dataset, used for classification of radar returns from the ionosphere [68,69].
10. **Liverdisorder** dataset [70], a medical dataset related to liver disorders.
11. **Mammographic** dataset [71], used to identify breast tumors.
12. **Parkinsons** dataset, a medical dataset related to Parkinson's disease (PD)[72].
13. **Pima** dataset [73], used to detect the presence of diabetes.
14. **Popfailures** dataset [74], a dataset related to climate measurements.
15. **Regions2** dataset, medical dataset related to hepatitis C [75].
16. **Saheart** dataset [76], a medical dataset related to heart diseases.
17. **Segment** dataset [77], an image processing dataset.
18. **Wdbc** dataset [78], a medical dataset related to breast tumors.
19. **Wine** dataset, used to detect the origin of wines [79,80].
20. **Eeg** datasets, a medical dataset related to EEG measurements [81]. There are 3 different cases from this dataset used here denoted as Z_F_S, ZO_NF_S, ZONF_S.
21. **Zoo** dataset [82], used to classify animals.

The description of the used regression datasets has as follows:

1. **Abalone** dataset [84], used to to predict the age of abalone from physical measurements.
2. **Airfoil** dataset, derived from NASA [85].
3. **Baseball** dataset, used to estimate the salary of baseball players.
4. **BK** dataset [86], used to predict the points scored in a basketball game.
5. **BL** dataset, an electrical engineering dataset.
6. **Concrete** dataset [87].
7. **Dee** dataset, used to predict the price of electricity.
8. **Diabetes** dataset, a medical dataset.
9. **Housing** dataset, provided in [88].
10. **FA** dataset, used to predict the fit body fat.
11. **MB** dataset, available from from Smoothing Methods in Statistics [89].
12. **MORTGAGE** dataset, related to Economic data from USA.
13. **PY** dataset, (Pyrimidines problem) [90].
14. **Quake** dataset, used to predict the strength of a earthquakes.
15. **Treasure** dataset, related to Economic data from USA.
16. **Wankara** dataset, a dataset related to weather.

3.2. Experimental results

The proposed method was coded in ANSI C++ and the optimization methods were obtained from the freely available from the OPTIMUS computing environment, downloaded from <https://github.com/itsoulos/OPTIMUS/> (accessed on 9 September 2023). The results were validated using the 10 - fold validation technique in all datasets. The experiments were executed 30 times for each dataset using a different seed for the random generator each time. The average classification error is reported for the case of classification datasets and the average mean test error for the regression datasets. The machine used in the experiments was an AMD Ryzen 5950X with 128GB of RAM, running the Debian Linux operating system. The experimental settings are listed in the Table 2. The experimental results for the classification datasets are shown in Table 3, while for the regression datasets the results are shown in Table 4. The following applies to the results tables:

1. A genetic algorithm where the parameters have the values of Table 2 used to train a neural network with H hidden nodes. The results in the experimental tables are denoted by the label GENETIC.
2. The Adam optimization method is used to train a neural network with H hidden nodes. The column ADAM denotes the results for this method.
3. The RPROP method is used to train a neural network with H hidden nodes. The corresponding results are denoted by RPROP in the relevant tables.
4. The NEAT method (NeuroEvolution of Augmenting Topologies) [91], where the maximum number of allowed generations is the same as in the case of the genetic algorithm.
5. The proposed method (denoted as PROPOSED) was used with the experimental settings and are shown in Table 2.
6. An extra line was also added to the experimental tables under the title AVERAGE. This line represents the average classification or regression error for all datasets.

Table 2. Experimental parameters.

PARAMETER	VALUE
H	10
N_C	200
N_S	50
N_t	200
p_s	0.10
p_m	0.01

Table 3. Experimental results for classification datasets. The values in cells indicate average classification error as measured on test set.

DATASET	GENETIC	ADAM	RPROP	NEAT	PROPOSED
Appendicitis	18.10%	16.50%	16.30%	17.20%	17.00%
Australian	32.21%	35.65%	36.12%	31.98%	24.55%
Balance	8.97%	7.87%	8.81%	23.14%	16.71%
Cleveland	51.60%	67.55%	61.41%	53.44%	47.91%
Dermatology	30.58%	26.14%	15.12%	32.43%	8.93%
Hayes Roth	56.18%	59.70%	37.46%	50.15%	32.21%
Heart	28.34%	38.53%	30.51%	39.27%	17.40%
HouseVotes	6.62%	7.48%	6.04%	10.89%	3.48%
Ionosphere	15.14%	16.64%	13.65%	19.67%	7.14%
Liverdisorder	31.11%	41.53%	40.26%	30.67%	28.90%
Lymography	23.26%	29.26%	24.67%	33.70%	17.86%
Mammographic	19.88%	46.25%	18.46%	22.85%	17.32%
Parkinsons	18.05%	24.06%	22.28%	18.56%	14.35%
Pima	32.19%	34.85%	34.27%	34.51%	25.58%
Popfailures	5.94%	5.18%	4.81%	7.05%	4.58%
Regions2	29.39%	29.85%	27.53%	33.23%	28.32%
Saheart	34.86%	34.04%	34.90%	34.51%	27.43%
Segment	57.72%	49.75%	52.14%	66.72%	20.68%
Wdbc	8.56%	35.35%	21.57%	12.88%	5.23%
Wine	19.20%	29.40%	30.73%	25.43%	5.35%
Z_F_S	10.73%	47.81%	29.28%	38.41%	6.56%
ZO_NF_S	8.41%	47.43%	6.43%	43.75%	3.60%
ZONF_S	2.60%	11.99%	27.27%	5.44%	2.21%
ZOO	16.67%	14.13%	15.47%	20.27%	6.10%
AVERAGE	23.60%	31.54%	25.65%	29.42%	16.23%

Table 4. Experimental results for regression datasets. The values indicate average regression error as measured on test set.

DATASET	GENETIC	ADAM	RPROP	NEAT	PROPOSED
ABALONE	7.17	4.30	4.55	9.88	4.48
AIRFOIL	0.003	0.005	0.002	0.067	0.002
BASEBALL	103.60	77.90	92.05	100.39	51.39
BK	0.027	0.03	1.599	0.15	0.02
BL	5.74	0.28	4.38	0.05	0.002
CONCRETE	0.0099	0.078	0.0086	0.081	0.004
DEE	1.013	0.63	0.608	1.512	0.23
DIABETES	19.86	3.03	1.11	4.25	0.41
HOUSING	43.26	80.20	74.38	56.49	24.55
FA	1.95	0.11	0.14	0.19	0.01
MB	3.39	0.06	0.055	0.061	0.048
MORTGAGE	2.41	9.24	9.19	14.11	0.65
PY	5.41	0.09	0.039	0.075	0.025
QUAKE	0.040	0.06	0.041	0.298	0.038
TREASURY	2.929	11.16	10.88	15.52	0.84
WANKARA	0.012	0.02	0.0003	0.005	0.0002
AVERAGE	12.30	11.70	12.44	12.70	5.17

In general, the proposed technique outperforms the rest of the techniques in the experiments. In fact, in many cases, the test error is reduced by more than 70%. Also, more experiments were conducted using the number of processing nodes (H) as well the number of generations (N_t), to determine the stability of the proposed technique. The average

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classification error for the classification datasets using different values for the H parameter is shown graphically in Figure 3. Furthermore, the average classification error of the proposed method for different number of maximum generations N_t is shown graphically in Figure 4. The proposed technique does not show significant changes in its behavior as the critical parameters change and therefore its stability to changes is evident. Also, the average execution time for different values of the N_t parameter is outlined in Figure 5. Judging from the above experiments, it can be said that the choice of values for the critical parameters H and N_t is a compromise between performance and speed for the proposed technique.

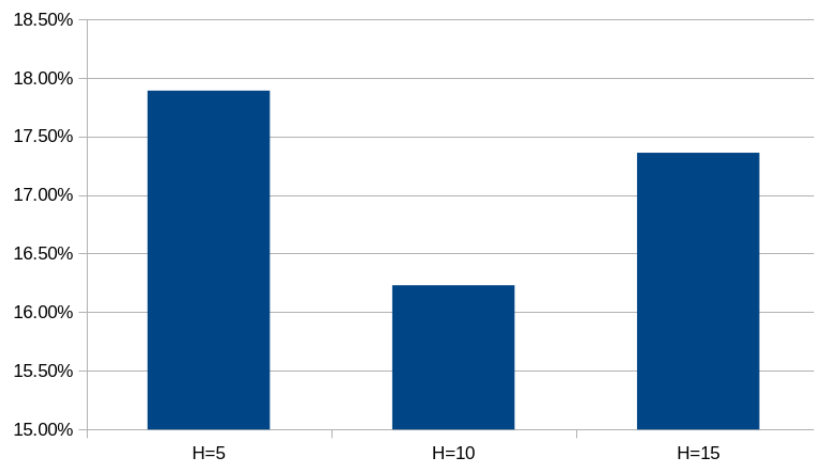


Figure 3. Average classification error using the proposed method and different values for the number of hidden nodes H .

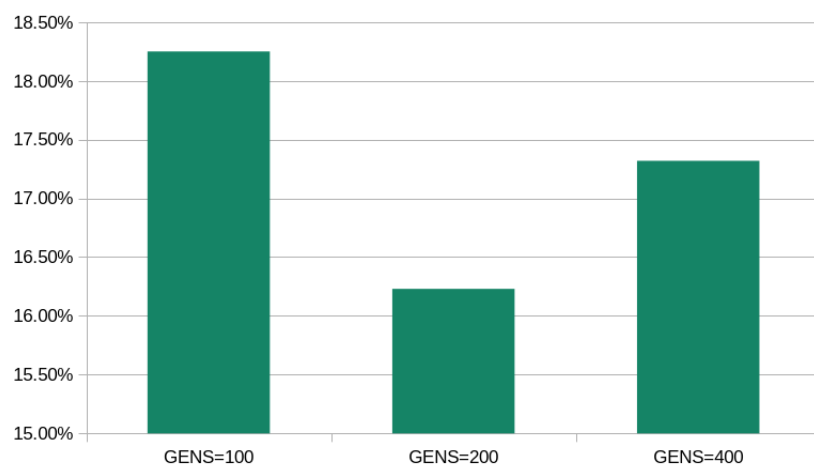


Figure 4. Average classification error of the proposed method using different values for the maximum number of allowed generations N_t .

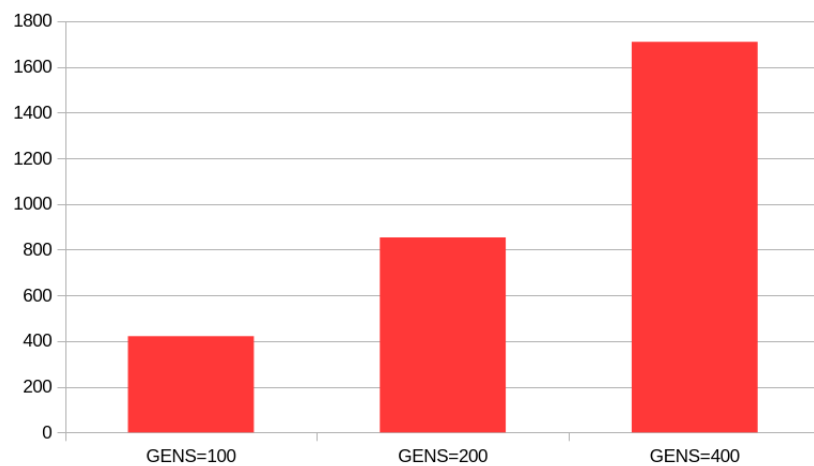


Figure 5. Average execution time of the proposed method, using different values of the N_t parameter.

The numerical superiority of the proposed technique over the others in the performed experiments is presented graphically and in the figures 6 and 7, where Wilcoxon signed-rank tests were performed on the executed experiments. However, since the proposed technique consists exclusively of a series of genetic algorithms, it can be significantly accelerated by the use of parallel computing techniques, since one of the main characteristics of genetic algorithms is their ease of parallelization [92,93]. Programming techniques that can be used to parallelize the method could be the MPI programming interface [94] or the OpenMP programming library [95].

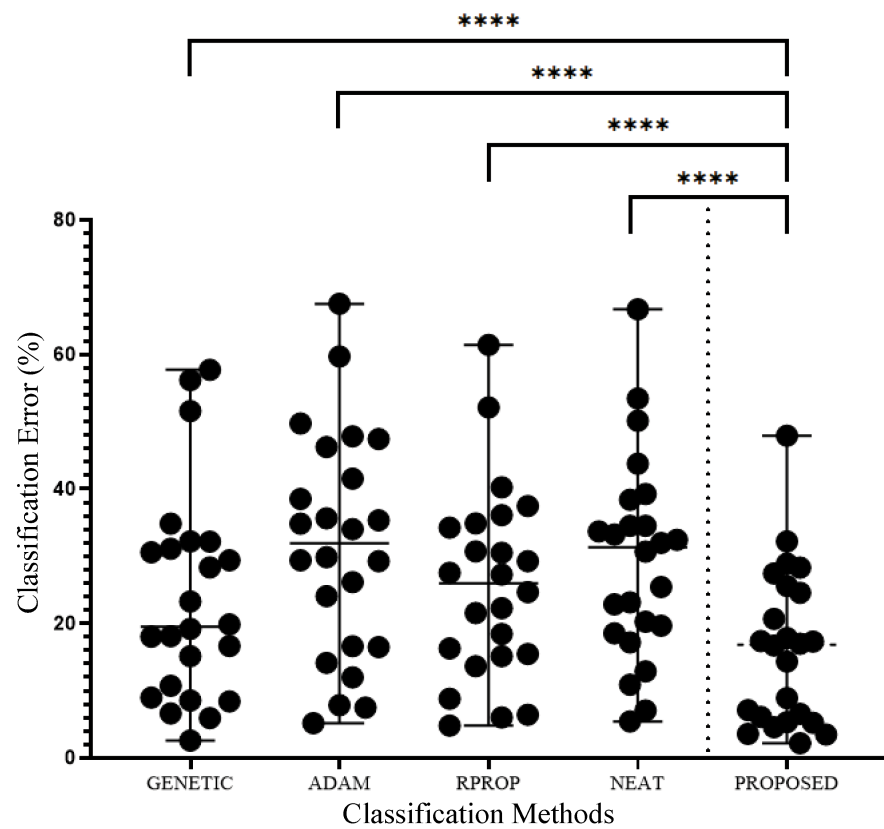


Figure 6. Scatter plot representation and the two-sample paired (Wilcoxon) signed-rank test results of the comparison for each of the four (4) classification methods (GENETIC, ADAM, RPROP, and NEAT) with the PROPOSED method regarding the classification error in twenty-four (24) different public available classification datasets. The stars only intend to flag significance levels for the two most used groups. A p-value of less than 0.0001 is flagged with four stars (****).

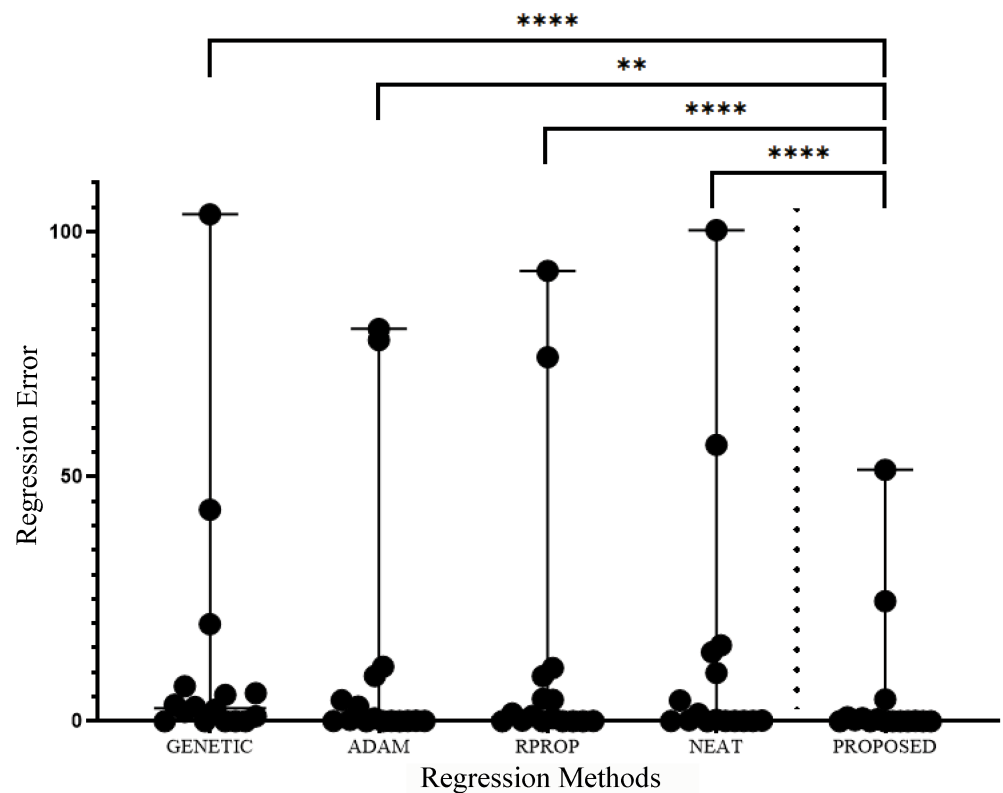


Figure 7. Scatter plot representation and the Wilcoxon signed-rank test results of the comparison for each of the four (4) regression methods (GENETIC, ADAM, RPROP, and NEAT) with the PROPOSED method regarding the regression error in sixteen (16) different publicly available regression datasets. Star links join significantly different values; one star (*) stands for $p < 0.001$, and four stars (****) stand for $p < 0.0001$.

4. Conclusions

This paper proposed a two-step technique to efficiently find a reliable interval of values for the parameters of artificial neural networks. In the first stage with partitioning techniques and using Grammatical Evolution, a range of parameter values was searched and, in the second stage, a genetic algorithm trained the artificial neural network within the optimal range of values of the first stage. The proposed technique is highly general and has been successfully applied to both data fitting and classification problems. In both cases, the experimental results demonstrate its superiority over other techniques appearing in the relevant literature on the training of artificial neural networks. In fact, in many cases in the performed experiments, the proposed method outperforms others that were tested in percentages that exceed 70%. In the future, a series of actions can be carried out to improve the results and speed up the proposed method, such as:

1. There is a need for more efficient techniques for initializing the value space for artificial neural network parameters. In the present work, the optimal result from the execution of a limited number of steps by a genetic algorithm was used as an initial estimate of the value interval.
2. In the present work, the same techniques as in any whole-chromosome genetic algorithm were used to perform the crossover and mutation operations. Research could be done at this point to find more focused crossover and mutation techniques for this particular problem.
3. The present technique consists of two phases, in each of which a problem-adapted genetic algorithm is executed. This means that significant computational time is

required to complete the algorithm. However, since genetic algorithms are inherently parallelizable, modern parallel programming techniques could be used here.

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