

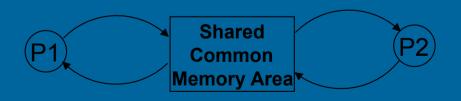
FIT3142 Distributed Computing

Topic 1 – Reading Materials: Inter Process Communications & Remote Procedure Call Mechanisms

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Inter-process Communication (IPC)

- IPC basically requires information sharing among two or more processes.
 Two basic methods-
 - Original sharing (Shared data approach)
 - Copy Sharing (Message passing approach)





Shared data approach

Message passing approach



Message Passing System

- A message-passing system is a sub-system of a distributed system that provides a set of message-based IPC protocols and does so by shielding the details of complex network protocols and multiple heterogeneous platforms from programmers.
- It enables processes to communicate by exchanging messages
- Allows programs to be written by using simple communication primitives, such as *send* and *receive*.
- Serves as a suitable infrastructure for building other higher level IPC systems, such as RPC (Remote Procedure Call) and DSM (Distributed Shared Memory).



Desirable features of a good message passing system

- Simplicity
- Uniform semantics
 - Same primitives for local and remote communication
- Efficiency
 - Reduce the number of message as far as possible
 - Some optimization normally adopted for efficiency include-
 - > Avoiding the cost of establishing and terminating connections between the same pair of processes for each and every message exchange between them
 - > Minimizing cost of maintaining connections
 - > Piggybacking of acknowledgment of previous message with the next message.



Desirable features of a good message passing system

Reliability

Lost and duplicate message handling

Correctness

- Atomicity
- Ordered delivery
- Survivability

Flexibility

Can drop one or more correctness properties



Desirable features of a good message passing system

Security

- Authentication of sender and receiver
- Encryption of messages

Portability

- Message passing system should itself be portable
- The application written by using primitives of the IPC protocol should be portable.



Issues in IPC by message passing

- A typical message structure
 - Header
 - Addresses
 - ✓ Sender address
 - ✓ Receiver address
 - Sequence number
 - Structural information
 - ✓ Type
 - ✓ Number of bytes
 - Message

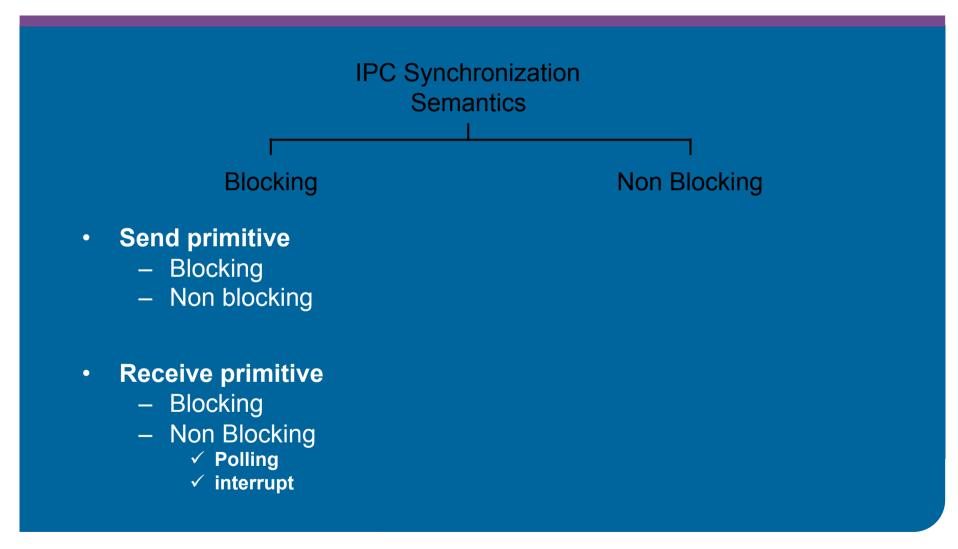


In the Design an IPC protocol

- Some of the main issues will be:
- Identity related
 - Who is the sender?
 - Who is the receiver?
- Network Topology related
 - 1 receiver or many?
- Flow control related
 - Guaranteed by the receiver?
 - Sender should wait for reply?
- Error control and channel management
 - Node crash.....what to do?
 - Receiver not ready…what to do?



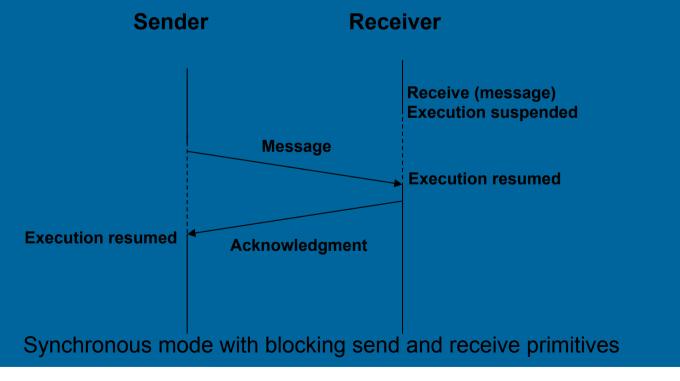
Synchronization in IPC





Synchronous & Asynchronous Communication

 When both the send and receive primitives of a communication between two processes use blocking semantics, the communication is said to be Synchronous; otherwise it is asynchronous.





Synchronous VS Asynchronous Communication

Synchronous

- Simple and easy to implement
- Contributes to reliability
- No backward error recovery needed

Asynchronous

- High concurrency
- More flexible than synchronous
- Lower deadlock risk than in synchronous communication (but beware)



Buffering

Synchronous systems

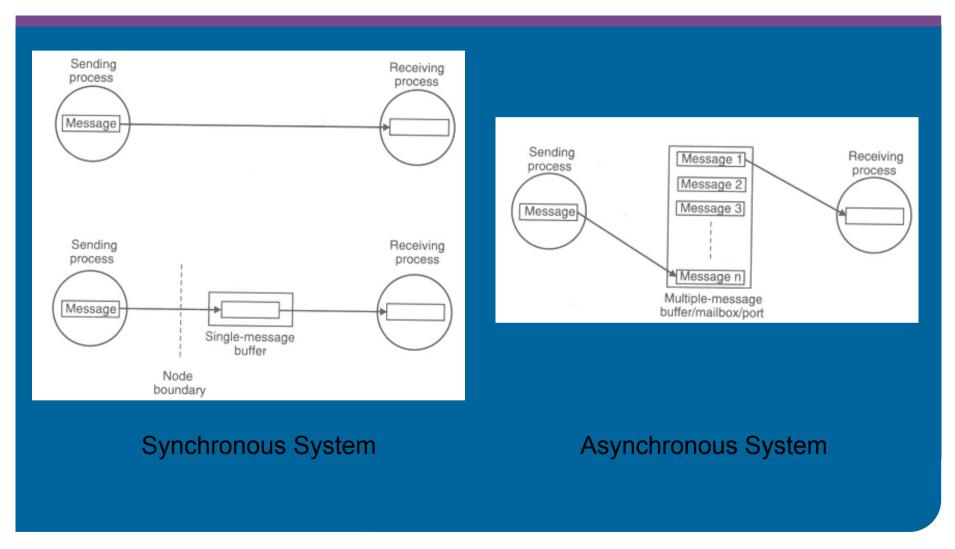
- Null buffer
- Single message buffer

Asynchronous systems

- Unbounded capacity buffer
- Finite message (multiple message buffer)



Buffering



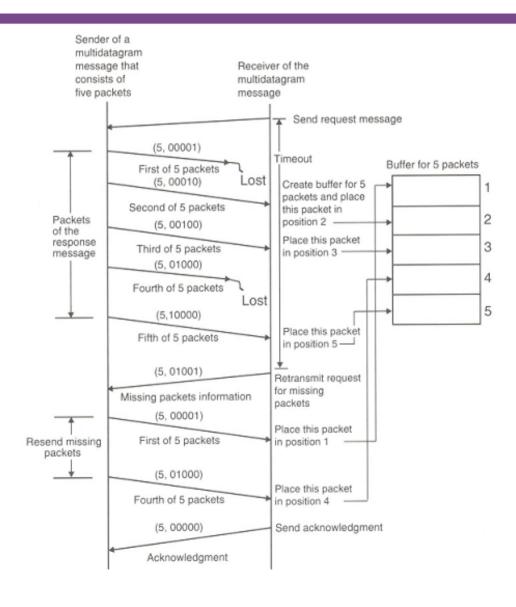


Multi-datagram Messages

- Almost all networks have an upper bound on the size of data that can be transmitted at a time. This is known as MTU (maximum transfer unit).
- Thus a message whose size is greater than MTU has to be fragmented - each fragment is sent in a packet. These packets are known as datagram.
- Thus messages may be single-datagram messages or multi-datagram messages
- Assembling and dissembling is the responsibility of message passing system.



Using Bitmap for Multidatagrams



Encoding Decoding

Encoding/Decoding is needed if

Sender and receiver have different architecture

Even for Homogeneous Encoding/Decoding is needed for

- ✓ Using an absolute pointer
- ✓ To know which object is stored in where and how much storage it requires



Process Addressing

Explicit Addressing

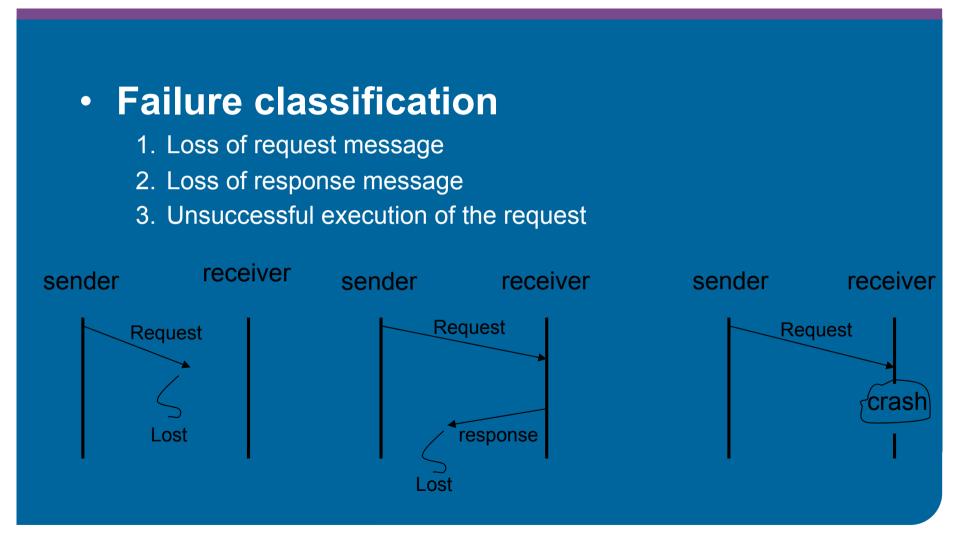
- Send(process_ID, message)
- Receive(process_ID, message)

Implicit Addressing

- Send_any(service_ID, message)
- Receive_any(process_ID, message)

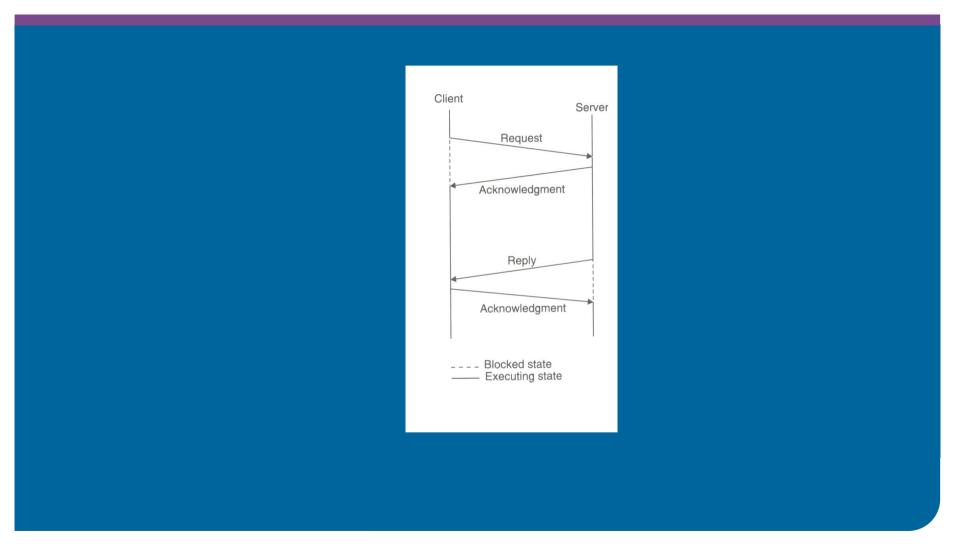


Failure Handling

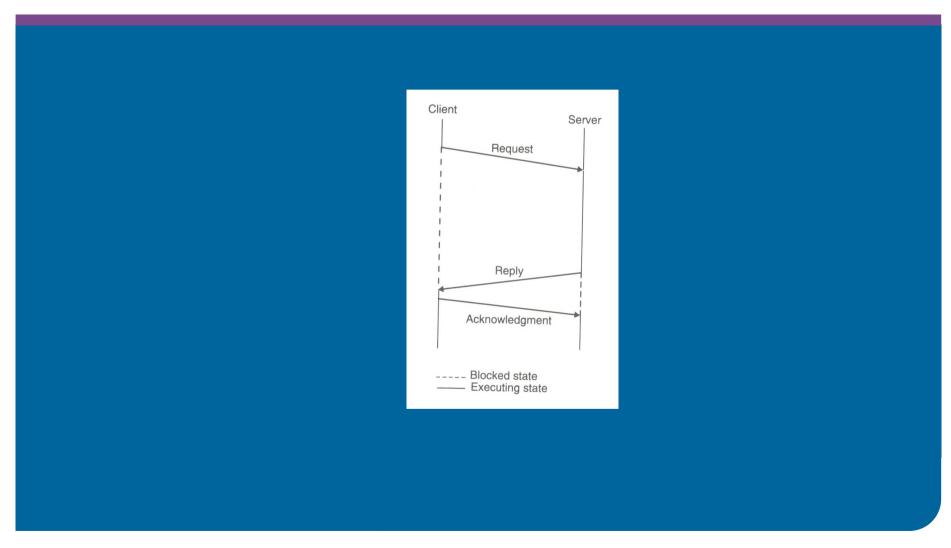




4-message reliable IPC protocol

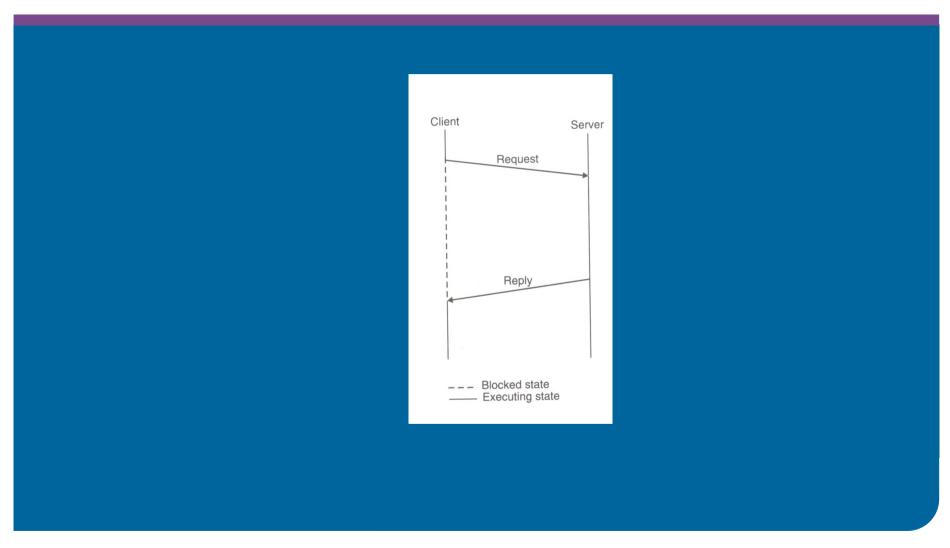


3-message Reliable IPC protocol



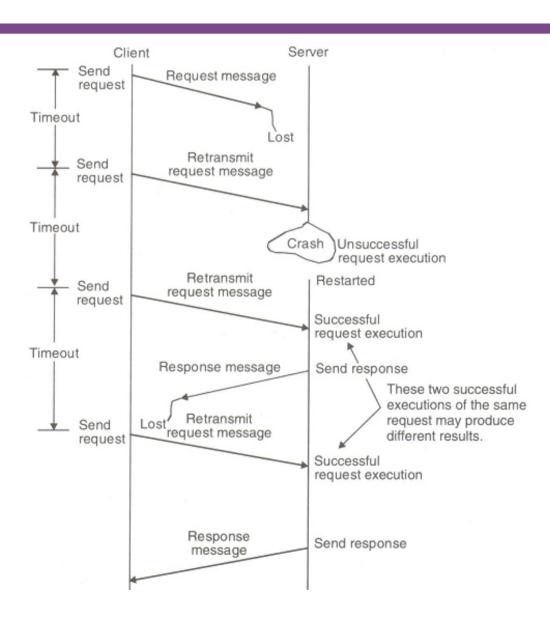


2-message Reliable IPC protocol





An Example of Fault Tolerant System



Idempotency

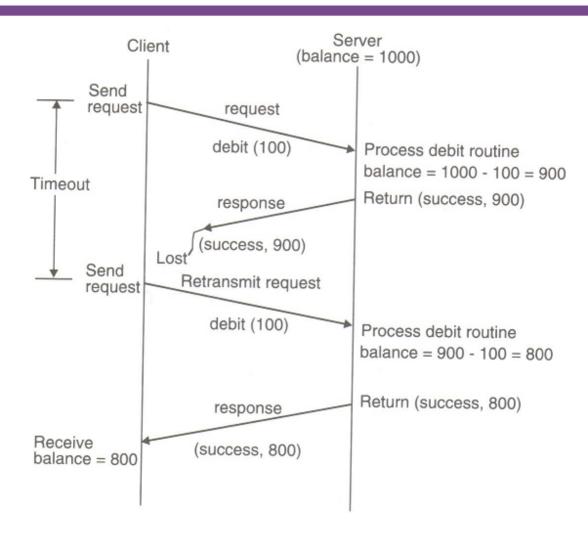
What is the difference between the following two functions?

```
getSqrt(n){ return sqrt(n)}
```

Debit (amount)

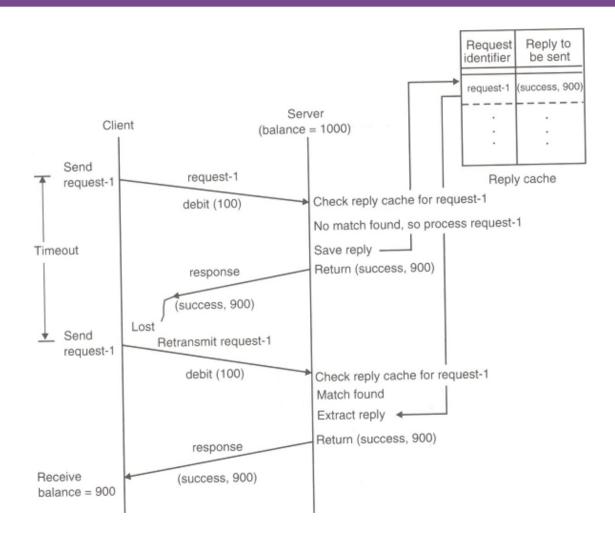


A Non-Idempotent Routine



Implementation of Idempotency

- How to implement Idempotency?
 - Adding sequence number with the request message
 - Introduction of 'Reply cache'



Group Communication

Group communication may be

- One to many
- Many to one
- Many to many

One to many

- Group management
- Group addressing
- Buffered and unbuffered multicast
- Send-to-all and Bulletin-Board semantics
- Flexible reliability in multicast communication
- Atomic multicast



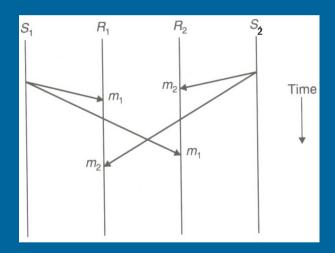
Many to Many communication

- The issues related to one-to-many and many-toone communications also applies here
- In addition, ordered message delivery is an important issue. This is trivial in one-to-many or many-to-one communications.
- For example, two server processes are maintaining a single salary database. Two client processes send updates for a salary record. What happen if they reach in different order? (will sequencing of messages help in this case?)



Semantics for ordered delivery in many-tomany communications

No-ordering



No ordering constraint



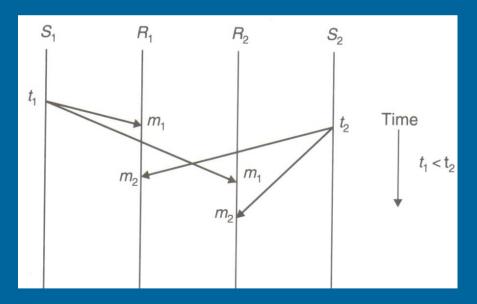
Semantics for ordered delivery in many-tomany communications

Absolute ordering

 All messages are delivered to all receiver processes in the exact order in which they were sent.

Using global timestamp as message identifiers with sliding window

protocol



Absolute ordering semantic



Semantics for ordered delivery in many-tomany communications

Consistent ordering

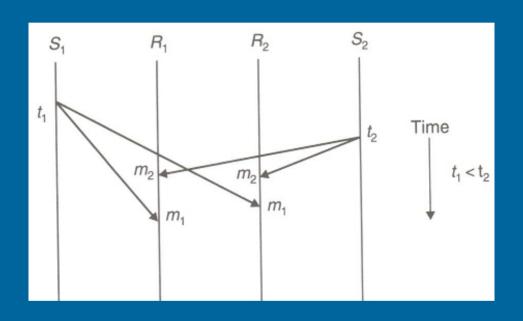
All messages are delivered to all receivers in the same order.
However, this order may be different from the order in which messages were sent.

Implementation

- Make the communication appear as a combination of many-toone and one-to-many communication [Chang and Maxemchuk]
- Kernels of sending machines send messages to a single receiver (known as sequencer) that assigns a sequence number to each message and then multicast it.
- Subject to single point of failure and hence has poor reliability.
- A distributed algorithm ABCAST in ISIS system [Birman and Renesse] (self study)



Semantics for ordered delivery in many-tomany comm.







Semantics for ordered delivery in many-tomany comm.

Causal ordering

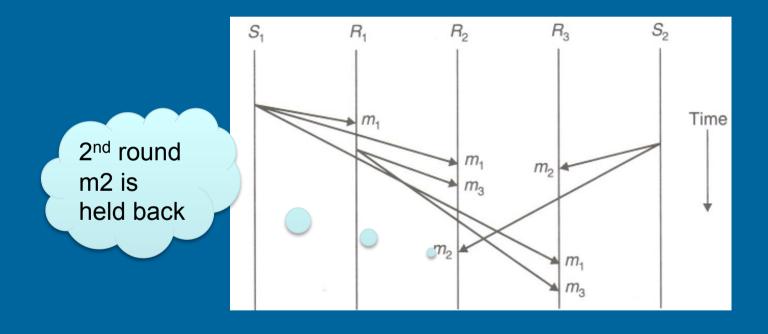
- If the event of sending one message is causally related to the event of sending another message, the two messages are delivered to all receivers in correct order.
- Two message sending events are said to be causally related if they are corelated by the *happened-before* relation.
- [The expression $a \rightarrow b$ is read "a happens before b" and means that all processes agree that first event a occurs, then afterward, event b occurs. The happens-before relation can be observed directly in two situations:
 - 1. If a and b are events in the same process, and a occurs before b, then $a \rightarrow b$ is true.
 - 2. If a is the event of a message being sent by one process, and b is the event of the message being received by another process, then $a \rightarrow b$ is also true.

Happens-before is a transitive relation, so if $a \rightarrow b$ and $b \rightarrow c$, then $a \rightarrow c$.



Semantics for ordered delivery in many-tomany comm.

• One example of implementing Causal consistency is *CBCAST* in *ISIS* system [Birman et al].



Causal ordering semantic



Remote Procedure Call (RPC)

- The IPC part of a distributed application can be adequately and efficiently handled by using an IPC protocol based on message passing system.
- However, an independently developed IPC protocol is tailored specifically to one application and does not provide a foundation on which to build a variety of distributed applications.
- Therefore, a need was felt for a general IPC protocol that can be used for designing several distributed applications.
- The RPC facility emerged out of this need.



Remote Procedure Call

- While the RPC is not the universal panacea for all types of distributed applications but for a fairly large number of distributed applications.
- The RPC has become a widely accepted IPC mechanism in DS. Its features –
 - Simple call syntax.
 - Familiar semantics.
 - Specification of a well defined interface.
 - Ease of use.
 - Generality. "In single-machine computations procedure calls are often the most important mechanism for communication between the parts of the algorithm" [Birrell and Nelson].
 - Its efficiency

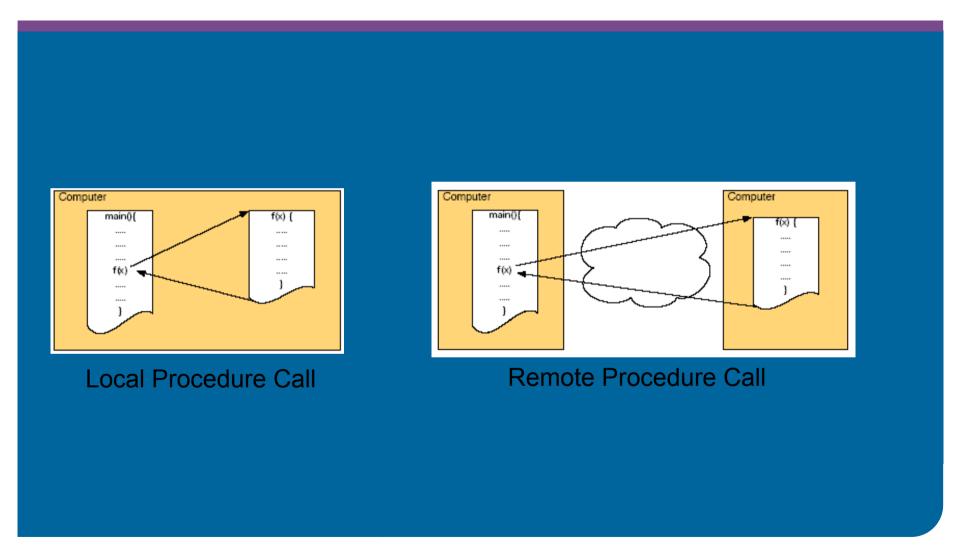


RPC model

- RPC model is similar to "Procedure call" model.
- Procedure call is same as function call or subroutine call
- Local Procedure Call The caller and the callee are within a single process on a given host.
- Remote Procedure Call (RPC) A process on the local system invokes a procedure on a remote system. The reason we call this a "procedure call" is because the intent is to make it appear to the programmer that a local procedure call is taking place.

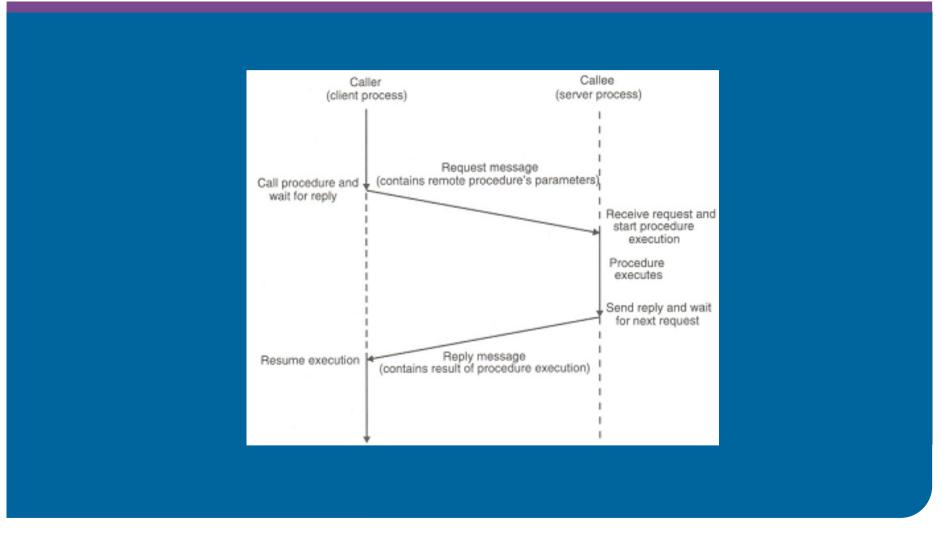


Local and Remote Procedure Call





A Typical Model of RPC

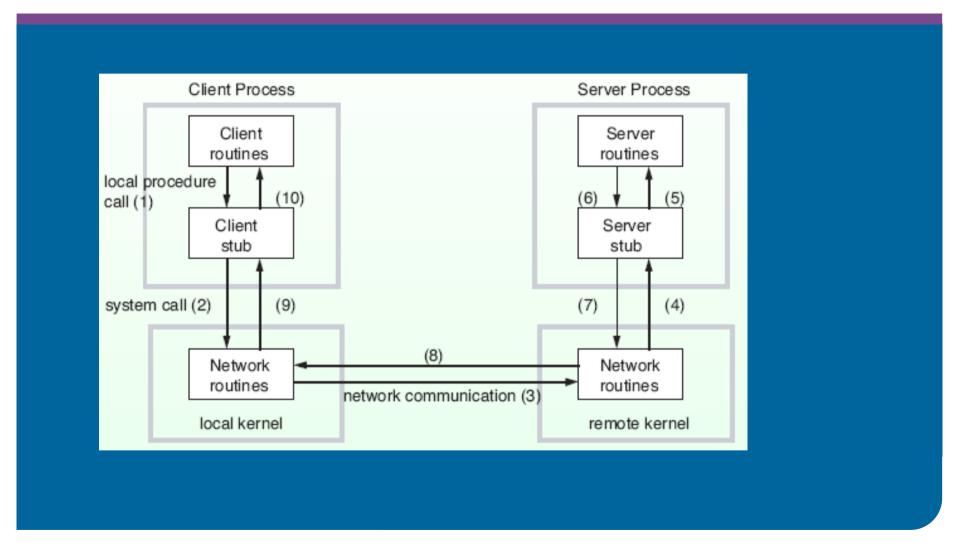


Implementing RPC mechanism

- To achieve the goal of semantic transparency, the implementation of an RPC mechanism is based on the concept of stubs
- Stubs provide a perfectly normal (local) procedure call abstraction
- To hide the distance and functional details of underlying network, an RPC communication package (known as RPCRuntime) is used.
- Thus RPC implementation involves five elements-
 - The client
 - The client stub
 - The RPCRuntime
 - The server stub
 - The server



RPC in Detail



Stubs

 Client and server stubs are generated from interface definition of server routines by development tools.

 Interface definition is similar to class definition in C++ and Java.

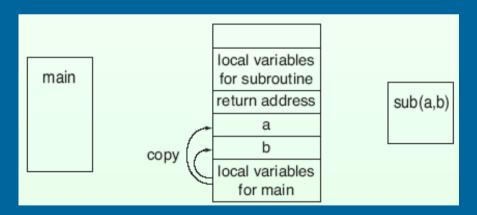
Parameter Passing Mechanisms

- When a procedure is called, parameters are passed to the procedure as the arguments. There are three methods to pass the parameters.
 - ocall-by-value
 - •call-by-reference
 - ocall-by-copy/restore



Call by value

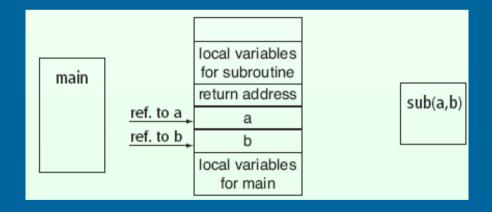
- The values of the arguments are copied to the stack and passed to the procedure.
- The called procedure may modify these, but the modifications do not affect the original value at the calling side.





Call-by-Reference

- The memory addresses of the variables corresponding to the arguments are put into the stack and passed to the procedure.
- Since these are memory addresses, the original values at the calling side are changed if modified by the called procedure.



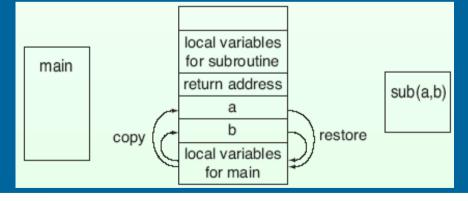


Call-by-Copy/Restore

- The values of the arguments are copied to the stack and passed to the procedure.
- When the processing of the procedure completes, the values are copied back to the original values at the calling side.

 If parameter values are changed in the subprogram, the values in the calling program are

also affected.



Parameter Passing in RPC

Which parameter passing mechanisms are possible?

olt is possible to implement all of the three mechanisms if you wish. Usually call-by-value and call-by-copy/restore are used.

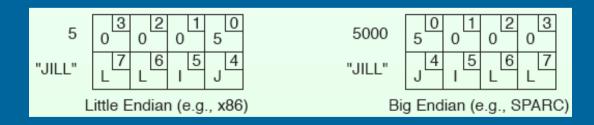
•Call-by-reference is difficult to implement. All data which may be referenced must be copied to the remote host and the reference to the copied data is used.

 Do we need to convert the values of the arguments into a standard format to transmit over the network?



Parameter Passing in RPC

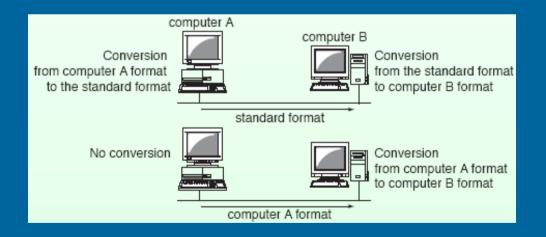
- Reasons to convert the values of the arguments into a standard format to transmit over the network
 - •Different machines use different character codes. E.g., IBM main frames use EBCDIC, while PCs use ASCII.
 - •Representation of numbers may differ from machine to machine.
 - ∘Big endian and little endian





Parameter Passing in RPC

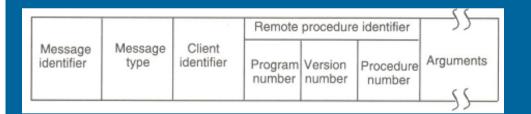
- If a standard format is not used, two message conversions are necessary.
 - If format information is attached to the message, only one conversion at the receiver will suffice.
 - •However, the receiver must be able to handle many different formats.

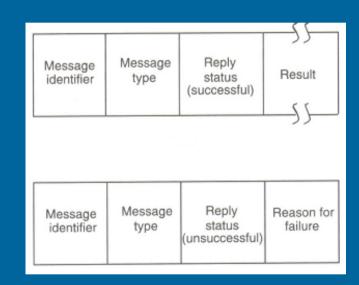




RPC Messages

- Generally two types of messages
 - Call messages
 - Reply messages





A typical RPC Call message format

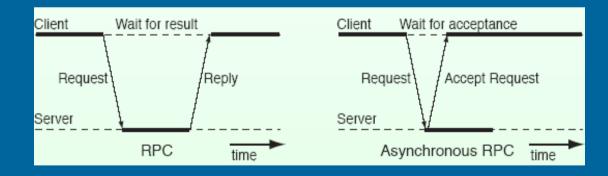
A typical RPC Reply message format (successful and unsuccessful)



Variations of RPC

Asynchronous RPC

- RPC (When a client requests a remote procedure, the client wait until a reply comes back in RPC.
- If no result is to be returned, unnecessary wait time overhead.
- In asynchronous RPC, the server immediately sends accept message when it receives a request.



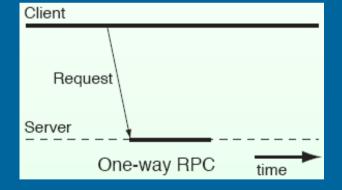


Call-Back RPC

One-way RPC

 In one-way RPC, the client immediately continues after sending the request to

the server.



Some special types of RPC

- Callback RPC
- Broadcast RPC
- Batch-mode RPC
- Lightweight RPC



Optimizations for better Performance

In Six Different Ways

- Concurrent access to multiple servers
- Serving multiple requests simultaneously
- Reducing per-call workload of servers
- Reply caching of idempotent remote procedures
- Proper selection of timeout values
- Proper design of RPC protocol specification

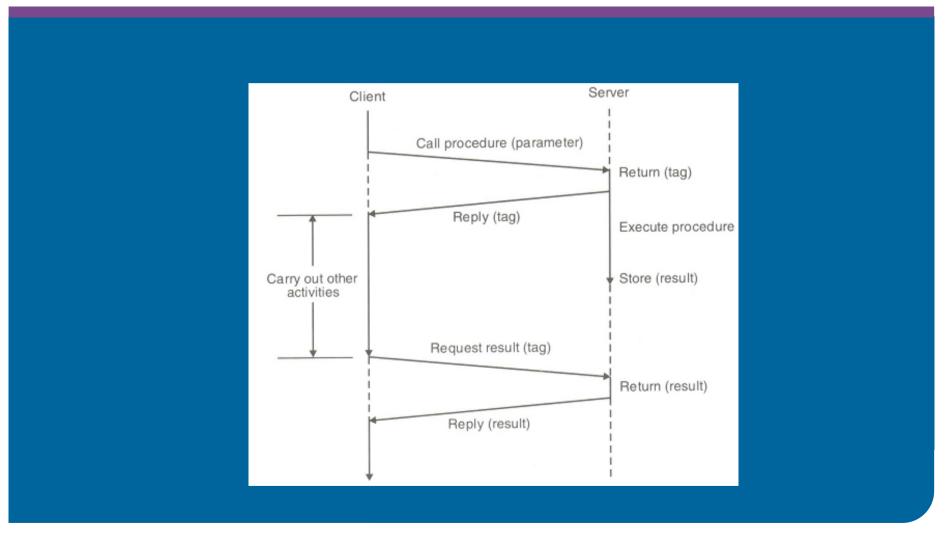


Concurrent Access to Multiple Server

- One of the following three may be adopted:
 - Threads
 - > Use of Threads in the implementation of a client process where each thread can independently make remote procedure calls to different servers.
 - > Addressing in underlying protocol should be rich enough to provide correct routing of responses.
 - Early reply approach [Wilbur and Bacarisse]
 - > A call is split into two separate RPC calls- one passing parameters and other requesting the result
 - > Server must hold the result causing congestion or unnecessary overhead.
 - Call buffering approach [Gimson]
 - > Clients and servers do not interact directly but via a call buffer server
 - A variant of this approach was implemented in MIT (Mercury Communication System)

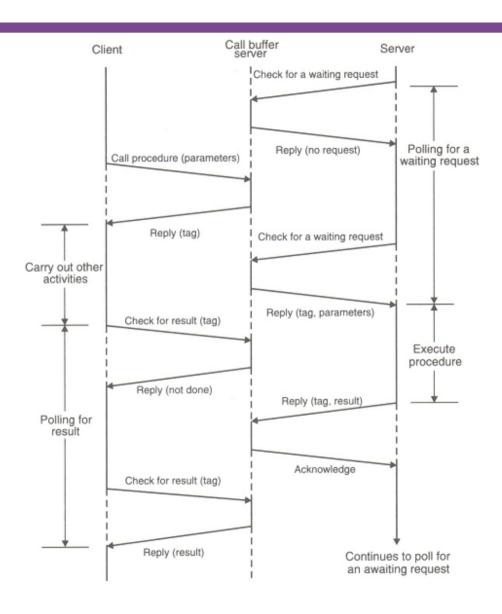


Early Reply Approach





Call Buffering Approach



Serving Multiple Requests Simultaneously

- Following types of delays are common-
 - A server, during the course of a call execution, may wait for a shared resource
 - A server calls a remote function that involves computation or transmission delays
- So the server may accept and process other requests while waiting to complete a request.
- Multiple-threaded server may be a solution.



Summation (1)

- What is the purpose of IPC?
 - information sharing among two or more processes
- Differences between Synchronous and Asynchronous Communications?
 - When both the send and receive primitives of a communication between two processes use blocking semantics, the communication is said to be Synchronous; otherwise it is asynchronous
- List the Types of Failure in IPC
 - Loss of request message, Loss of response message, Unsuccessful execution of the request



Summation (2)

- How to implement Idempotency?
 - Adding sequence number with the request message and Introduction of 'Reply cache'
- Three main types of Group Communications?
 - One to many, Many to one, Many to many
- One of the greatest challenges in Many to Many?
 - > Ordered Delivery
- Name an all propose IPC protocol?
 - Remote Procedure Call (RPC)



Summation (3)

- Name a few ways to optimise RPC?
 - Concurrent Access to Multiple Servers, Serving Muliple Requests Concurrently, Reducing Call Workload per Server
- Three different techniques for implementing Concurrent Access to Multiple Servers?
 - Threads, Early Reply, Call Buffering



References

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- 2. Birrell, A. D. and Nelson, B. J. *Implementing remote procedure calls*. ACM Trans. Comput. Syst. 2(1), 39-59, 1984.
- 3. Wilbur, S. and Bacarisse, B. *Building distributed systems with remote call*, Software Engineering Journal, 2(5), 148-159, 1987.
- 4. R. Gimson. Call buffering service. Technical Report 19, Programming Research Group, Oxford University, Oxford University, Oxford, England, 1985.

