

COMP3670 2021 Theory Assignment 3

Yuxuan Lin – u6828533@anu.edu.au

October 10, 2021

Introduction to Machine Learning

By turning in this assignment, I agree by the ANU honor code and declare that all of this is my own work.

Exercise 1

a) **Proof:** We will prove by induction that, for all $n \in \mathbb{Z}_+$,

$$p(\theta|x_{1:n} = 1^n) = \frac{\theta^n p(\theta)}{\int_{\theta} \theta^n p(\theta) d\theta} \quad (1)$$

Base case: When $n = 1$,

$$\begin{aligned} p(\theta|x_1 = 1) &= \frac{p(x_1 = 1|\theta)p(\theta)}{p(x_1 = 1)} \dots\dots\dots \text{Bayes' theorem} \\ &= \frac{p(x_1 = 1|\theta)p(\theta)}{\int_{\theta} p(x_1 = 1, \theta) d\theta} \dots\dots\dots \text{sum rule of probability} \\ &= \frac{p(x_1 = 1|\theta)p(\theta)}{\int_{\theta} p(x_1 = 1|\theta)p(\theta) d\theta} \dots\dots\dots \text{product rule of probability} \\ &= \frac{\theta p(\theta)}{\int_{\theta} \theta p(\theta) d\theta} \dots\dots\dots \text{conditional probability} \end{aligned}$$

Induction step: To start with, I will prove **Bayes' theorem with 3 events**

$$p(x|y, z) = \frac{p(z|x, y)p(x|y)}{p(z|y)}$$

$$\begin{aligned}
p(x|y, z) &= \frac{p(x, y, z)}{p(z, y)} \\
&= \frac{p(z|x, y)p(x, y)}{p(z, y)} \\
&= \frac{p(z|x, y)p(x|y)p(y)}{p(z|y)p(y)} \\
&= \frac{p(z|x, y)p(x|y)}{p(z|y)}.
\end{aligned}$$

Let $k \in \mathbb{Z}_+$, $k \geq 2$ be given and suppose (1) is true for $n = k$. Then

$$\begin{aligned}
p(\theta|x_{1:k+1} = 1^{k+1}) &= p(\theta|x_{1:k} = 1^k, x_{k+1} = 1) \\
&= \frac{p(x_{k+1} = 1|\theta, x_{1:k} = 1^k)p(\theta|x_{1:k} = 1^k)}{p(x_{k+1} = 1|x_{1:k} = 1^k)} \dots\dots\dots \text{Bayes' theorem with 3 events} \\
&= \frac{p(x_{k+1} = 1|\theta, x_{1:k} = 1^k)p(\theta|x_{1:k} = 1^k)}{\int_{\theta} p(x_{k+1} = 1, \theta|x_{1:k} = 1^k)d\theta} \dots\dots\dots \text{sum rule of probability} \\
&= \frac{p(x_{k+1} = 1|\theta, x_{1:k} = 1^k)p(\theta|x_{1:k} = 1^k)}{\int_{\theta} p(x_{k+1} = 1|\theta, x_{1:k} = 1^k)p(\theta|x_{1:k} = 1^k)d\theta} \dots\dots\dots \text{product rule of probability} \\
&= \frac{p(x_{k+1} = 1|\theta)p(\theta|x_{1:k} = 1^k)}{\int_{\theta} p(x_{k+1} = 1|\theta)p(\theta|x_{1:k} = 1^k)d\theta} \dots\dots\dots \text{independent and identically distributed} \\
&= \frac{\theta p(\theta|x_{1:k} = 1^k)}{\int_{\theta} \theta p(\theta|x_{1:k} = 1^k)d\theta} \\
&= \frac{\theta \frac{\theta^k p(\theta)}{\int_{\theta} \theta^k p(\theta)d\theta}}{\int_{\theta} \theta \frac{\theta^k p(\theta)}{\int_{\theta} \theta^k p(\theta)d\theta} d\theta} \dots\dots\dots \text{induction proof assumption} \\
&= \frac{\theta^{k+1} p(\theta)}{\int_{\theta} \theta^{k+1} p(\theta)d\theta} \dots\dots\dots \text{expected value is a constant}
\end{aligned}$$

Thus, (1) holds for $n = k + 1$, and the proof of the induction step is complete.

Conclusion: By the principle of induction, (1) is true for all $n \in \mathbb{Z}_+$.

Since $\mathbb{E}[\theta^n] = \int_{\theta} \theta^n p(\theta) d\theta$, we can simplify the answer as

$$p(\theta|x_{1:n} = 1^n) = \frac{\theta^n p(\theta)}{\mathbb{E}[\theta^n]}.$$

b) **Proof:** We will prove by induction that, for all $n \in \mathbb{Z}_+$,

$$p(\theta|x_{1:n} = 0^n) = \frac{(1-\theta)^n p(\theta)}{\int_{\theta} (1-\theta)^n p(\theta) d\theta} \quad (2)$$

Base case: When $n = 1$,

$$\begin{aligned} p(\theta|x_1 = 0) &= \frac{p(x_1 = 0|\theta)p(\theta)}{p(x_1 = 0)} \dots\dots\dots \text{Bayes' theorem} \\ &= \frac{p(x_1 = 0|\theta)p(\theta)}{\int_{\theta} p(x_1 = 0, \theta) d\theta} \dots\dots\dots \text{sum rule of probability} \\ &= \frac{p(x_1 = 0|\theta)p(\theta)}{\int_{\theta} p(x_1 = 0|\theta)p(\theta) d\theta} \dots\dots\dots \text{product rule of probability} \\ &= \frac{(1-\theta)p(\theta)}{\int_{\theta} (1-\theta)p(\theta) d\theta} \dots\dots\dots \text{conditional probability} \end{aligned}$$

Induction step: Let $k \in \mathbb{Z}_+$, $k \geq 2$ be given and suppose (2) is true for $n = k$. Then

$$\begin{aligned}
p(\theta|x_{1:k+1} = 0^{k+1}) &= p(\theta|x_{1:k} = 0^k, x_{k+1} = 0) \\
&= \frac{p(x_{k+1} = 0|\theta, x_{1:k} = 0^k)p(\theta|x_{1:k} = 0^k)}{p(x_{k+1} = 0|x_{1:k} = 0^k)} \dots\dots\dots \text{Bayes' theorem with 3 events} \\
&= \frac{p(x_{k+1} = 0|\theta, x_{1:k} = 0^k)p(\theta|x_{1:k} = 0^k)}{\int_{\theta} p(x_{k+1} = 0, \theta|x_{1:k} = 0^k)d\theta} \dots\dots\dots \text{sum rule of probability} \\
&= \frac{p(x_{k+1} = 0|\theta, x_{1:k} = 0^k)p(\theta|x_{1:k} = 0^k)}{\int_{\theta} p(x_{k+1} = 0|\theta, x_{1:k} = 0^k)p(\theta|x_{1:k} = 0^k)d\theta} \dots\dots\dots \text{product rule of probability} \\
&= \frac{p(x_{k+1} = 0|\theta)p(\theta|x_{1:k} = 0^k)}{\int_{\theta} p(x_{k+1} = 0|\theta)p(\theta|x_{1:k} = 0^k)d\theta} \dots\dots\dots \text{independent and identically distributed} \\
&= \frac{(1 - \theta)p(\theta|x_{1:k} = 0^k)}{\int_{\theta} (1 - \theta)p(\theta|x_{1:k} = 0^k)d\theta} \\
&= \frac{(1 - \theta) \frac{(1 - \theta)^k p(\theta)}{\int_{\theta} (1 - \theta)^k p(\theta)d\theta}}{\int_{\theta} (1 - \theta) \frac{(1 - \theta)^k p(\theta)}{\int_{\theta} (1 - \theta)^k p(\theta)d\theta} d\theta} \dots\dots\dots \text{induction proof assumption} \\
&= \frac{(1 - \theta)^{k+1} p(\theta)}{\int_{\theta} (1 - \theta)^{k+1} p(\theta)d\theta} \dots\dots\dots \text{expected value is a constant}
\end{aligned}$$

Thus, (2) holds for $n = k + 1$, and the proof of the induction step is complete.

Conclusion: By the principle of induction, (2) is true for all $n \in \mathbb{Z}_+$.

Since $\mathbb{E}[(1 - \theta)^n] = \int_{\theta} (1 - \theta)^n p(\theta)d\theta$, we can simplify the answer as

$$p(\theta|x_{1:n} = 1^n) = \frac{(1 - \theta)^n p(\theta)}{\mathbb{E}[(1 - \theta)^n]}.$$

c) Since $p(\theta) = 1$, $\boldsymbol{\theta} = \{\theta \in \mathbb{R} : 0 \leq \theta \leq 1\}$, from conclusion of a) we have

$$\begin{aligned} p(\theta|x_{1:n} = 1^n) &= \frac{\theta^n}{\int_0^1 \theta^n d\theta} \\ &= \frac{\theta^n}{\frac{\theta^{n+1}}{n+1} \Big|_0^1} \\ &= \frac{\theta^n}{\frac{1}{n+1}} \\ &= (n+1)\theta^n \end{aligned}$$

Hence, the answer is $p(\theta|x_{1:n} = 1^n) = (n+1)\theta^n$

d) Since expected value $\mu_n = \int_{\boldsymbol{\theta}} \theta p(\theta|x_{1:n} = 1^n) d\theta$, $\boldsymbol{\theta} = \{\theta \in \mathbb{R} : 0 \leq \theta \leq 1\}$, use conclusion of c) we have

$$\begin{aligned} \mu_n &= \int_0^1 (n+1)\theta^{n+1} d\theta \\ &= (n+1) \frac{\theta^{n+2}}{n+2} \Big|_0^1 \\ &= (n+1) \frac{1}{n+2} \\ &= \frac{n+1}{n+2} \end{aligned}$$

$$\begin{aligned} \lim_{n \rightarrow \infty} \mu_n &= \lim_{n \rightarrow \infty} \frac{n+1}{n+2} \\ &= \lim_{n \rightarrow \infty} \left(1 - \frac{1}{n+2}\right) \\ &= 1 - \frac{1}{\infty} \\ &= 1 - 0 \\ &= 1 \end{aligned}$$

Hence, the answers are $\mu_n = \frac{n+1}{n+2}$ and $\lim_{n \rightarrow \infty} \mu_n = 1$.

- e) Since variance $\sigma_n^2 = \int_{\theta} (\theta - \mu_n)^2 p(\theta|x_{1:n} = 1^n) d\theta$, $\theta = \{\theta \in \mathbb{R} : 0 \leq \theta \leq 1\}$, use conclusion of c) and d) we have

$$\begin{aligned}
\sigma_n^2 &= \int_0^1 \left(\theta - \frac{n+1}{n+2}\right)^2 (n+1) \theta^n d\theta \\
&= \int_0^1 \left[\frac{(n+1)^3}{(n+2)^2} \theta^n - \frac{2(n+1)^2}{n+2} \theta^{n+1} + (n+1) \theta^{n+2} \right] d\theta \\
&= \left[\frac{(n+1)^3}{(n+2)^2} \theta^{n+1} - \frac{2(n+1)^2}{(n+2)^2} \theta^{n+2} + \frac{n+1}{n+3} \theta^{n+3} \right] \Big|_0^1 \\
&= \frac{(n+1)^3}{(n+2)^2} - \frac{2(n+1)^2}{(n+2)^2} + \frac{n+1}{n+3} \dots \text{uniform prior is 1} \\
&= \frac{1+n}{3+n} - \frac{(1+n)^2}{(2+n)^2}
\end{aligned}$$

$$\lim_{n \rightarrow \infty} \sigma_n^2 = \lim_{n \rightarrow \infty} \left(\frac{1+n}{3+n} - \frac{(1+n)^2}{(2+n)^2} \right) = 0 \dots \text{calculated by Wolfram Alpha}$$

Hence, the answers are $\sigma_n^2 = \frac{1+n}{3+n} - \frac{(1+n)^2}{(2+n)^2}$ and $\lim_{n \rightarrow \infty} \sigma_n^2 = 0$.

- f) If we take the derivative of the conclusion of c), we derive

$$p'(\theta|x_{1:n} = 1^n) = n(n+1)\theta^{n-1} \quad (3)$$

For $\theta \in \mathbb{R} : 0 \leq \theta \leq 1$, we always have (3) ≥ 0 , which means $p(\theta|x_{1:n} = 1^n)$ monotonically increases in the range of θ , then the maximum a posteriori will be always be reached when $\theta = 1$, as known as $\theta_{\text{MAP}n} = 1$.

$\theta_{\text{MAP}n}$ is a constant of 1 and it will not vary with n . Because the uniform prior $p(\theta) = 1$, the value selection of θ will not be biased in the range of θ . And what we observed are n consecutive ones. Consequently, we always have $\theta_{\text{MAP}n} = 1$ regardless of n .

- g) In my opinion, μ_n is a better choice for the best guess of the true value of θ . The reason I don't choose $\theta_{\text{MAP}n}$ is: Regardless of n , $\theta_{\text{MAP}n}$ is always 1. But when n is small, for instance, if we only flip the coin for once, and we will conclude that the true value of θ is 1 from $\theta_{\text{MAP}n}$. I think it is illogical. As for μ_n , it will get closer to 1 when n is large enough, which is a much more logical way for the best guess of the true value of θ .

h) From the conclusion of c), we have

$$p(\theta|x_{1:n} = 1^n) = \begin{cases} 1 & n = 0 \\ 2\theta & n = 1 \\ 3\theta^2 & n = 2 \\ 4\theta^3 & n = 3 \\ 5\theta^4 & n = 4 \end{cases}$$

Generated by *Desmos*, the plot is shown as below.

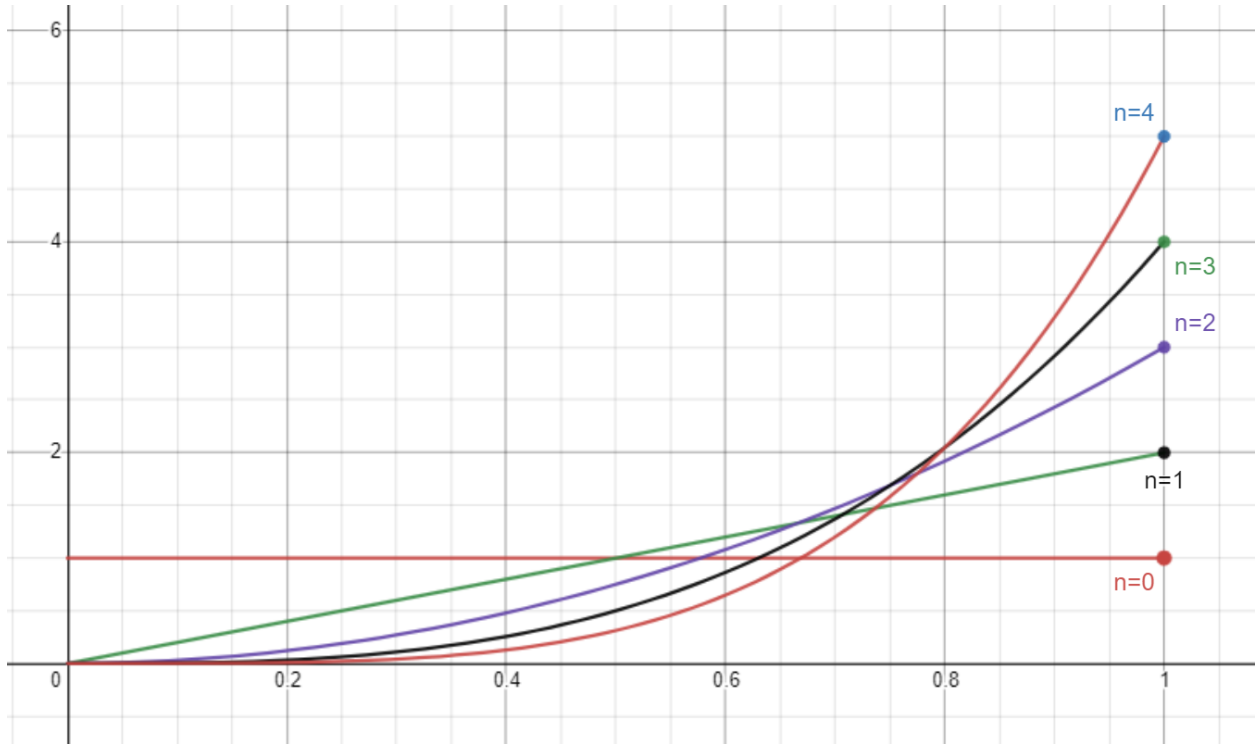


Figure 1: Probability Distributions

We observe from Figure 1 that, with the increase of n , the graphs of probability distributions $p(\theta|x_{1:n} = 1^n)$ are skewed towards $\theta = 1$.

Exercise 2

- a) For $\alpha = \beta = 1$, the camera is noisy-free, and it can perfectly report back the result value. Consequently, the agent updates it's prior to a posterior on θ based on general Bayesian inference.

For $\alpha = \beta = \frac{1}{2}$, the camera has half-n-half probabilities of reporting back a 0 or a 1, regardless of the true result of a coin flip. Consequently, the way that the agent updates it's prior to a posterior on θ will be: A posteriori on θ after updating will always be the same as the prior.

For $\alpha = \beta = 0$, the camera reports back an exactly wrong result value of the true result of a coin flip. Consequently, the way that the agent updates it's prior to a posterior on θ will be as the following:

- When the observation value is 0, as known as the true result of a coin flip is 1, then a posteriori will skew towards 1.
- When the observation value is 1, as known as the true result of a coin flip is 0, then a posteriori will skew towards 0.

- b) $\forall x \in \{0, 1\}$, we have

$$\begin{aligned}
 p(\hat{X} = x|\theta) &= \sum_{y=0}^1 p(\hat{X} = x, X = y|\theta) \\
 &= \sum_{y=0}^1 p(\hat{X} = x|X = y, \theta)p(X = y|\theta) \\
 &= p(\hat{X} = x|X = 1, \theta)p(X = 1|\theta) + p(\hat{X} = x|X = 0, \theta)p(X = 0|\theta) \\
 &= \theta p(\hat{X} = x|X = 1) + (1 - \theta)p(\hat{X} = x|X = 0)
 \end{aligned}$$

For $x = 0$:

$$p(\hat{X} = 0|\theta) = \theta p(\hat{X} = 0|X = 1) + (1 - \theta)p(\hat{X} = 0|X = 0) = \theta(1 - \beta) + (1 - \theta)\alpha$$

For $x = 1$:

$$p(\hat{X} = 1|\theta) = \theta p(\hat{X} = 1|X = 1) + (1 - \theta)p(\hat{X} = 1|X = 0) = \theta\beta + (1 - \theta)(1 - \alpha)$$

- c) Use the conclusion of b), and knowing that $\hat{X} = 1$, we have

$$\begin{aligned}
p(\theta|\hat{X} = 1) &= \frac{p(\hat{X} = 1|\theta)p(\theta)}{p(\hat{X} = 1)} \\
&= \frac{p(\hat{X} = 1|\theta)p(\theta)}{\int_0^1 p(\hat{X} = 1, \theta)d\theta} \\
&= \frac{[\theta\beta + (1 - \theta)(1 - \alpha)]p(\theta)}{\int_0^1 [\theta\beta + (1 - \theta)(1 - \alpha)]p(\theta)d\theta}
\end{aligned}$$

For $\alpha = \beta = 1$, we calculate

$$p(\theta|\hat{X} = 1) = \frac{\theta p(\theta)}{\int_0^1 \theta p(\theta)d\theta} = \frac{\theta p(\theta)}{\mathbb{E}[\theta]}$$

The camera is noisy-free, and it can perfectly report back the result value. Consequently, the agent updates it's prior to a posterior on θ based on general Bayesian inference.

For $\alpha = \beta = \frac{1}{2}$, we calculate

$$p(\theta|\hat{X} = 1) = \frac{\frac{1}{2}p(\theta)}{\int_0^1 \frac{1}{2}p(\theta)d\theta} = \frac{\frac{1}{2}p(\theta)}{\frac{1}{2} \int_0^1 p(\theta)d\theta} = p(\theta) \dots \text{integral of a PDF is 1}$$

The camera has half-n-half probabilities of reporting back a 0 or a 1, regardless of the true result of a coin flip. Consequently, the way that the agent updates it's prior to a posterior on θ will be: A posteriori on θ after updating will always be the same as the prior.

For $\alpha = \beta = 0$, we calculate

$$p(\theta|\hat{X} = 1) = \frac{(1 - \theta)p(\theta)}{\int_0^1 (1 - \theta)p(\theta)d\theta} = \frac{(1 - \theta)p(\theta)}{\mathbb{E}[1 - \theta]}$$

The camera reports back an exactly wrong result value of the true result of a coin flip. Consequently, the way that the agent updates it's prior to a posterior on *theta* will be as the following:

- When the observation value is 0, as known as the true result of a coin flip is 1, then a posteriori will skew towards 1.

- When the observation value is 1, as known as the true result of a coin flip is 0, then a posteriori will skew towards 0.

d) Take $p(\theta) = 1$ into an equation we derive in c), then

$$\begin{aligned}
 p(\theta|\hat{X} = 1) &= \frac{[\theta\beta + (1-\theta)(1-\alpha)]p(\theta)}{\int_0^1 [\theta\beta + (1-\theta)(1-\alpha)]p(\theta)d\theta} \\
 &= \frac{\theta\beta + (1-\theta)(1-\alpha)}{\int_0^1 [\theta\beta + (1-\theta)(1-\alpha)]d\theta} \\
 &= \frac{\theta\beta + (1-\theta)(1-\alpha)}{\frac{1}{2}(1-\alpha+\beta)} \dots \text{calculated by Wolfram Alpha} \\
 &= 2\theta\alpha + 2(1-\theta)(1-\alpha) \dots \beta = \alpha \\
 &= 4\theta\alpha - 2\theta - 2\alpha + 2
 \end{aligned}$$

Hence, the answer is $p(\theta|\hat{X} = 1) = 4\theta\alpha - 2\theta - 2\alpha + 2$.

e) From the conclusion of d), we have

$$p(\theta|\hat{X} = 1) = \begin{cases} -2\theta + 2 & \alpha = 0 \\ -\theta + \frac{3}{2} & \alpha = 1/4 \\ 1 & \alpha = 2/4 \\ \theta + \frac{1}{2} & \alpha = 3/4 \\ 2\theta & \alpha = 1 \end{cases}$$

Generated by *Desmos*, the plot is shown as below.

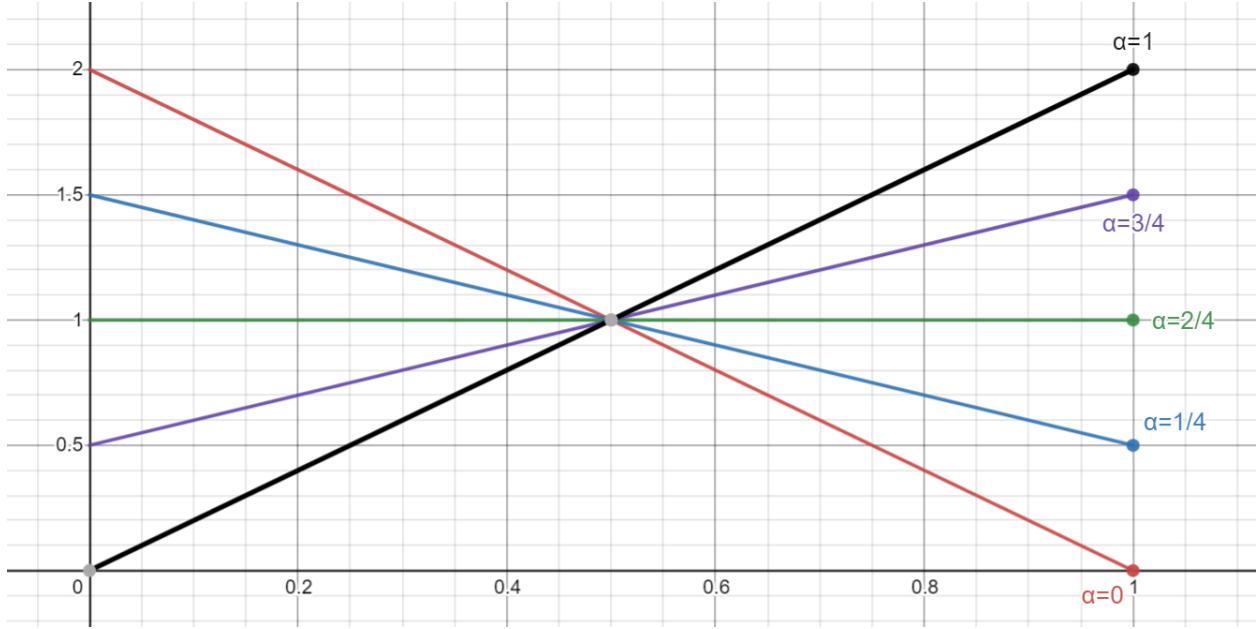


Figure 2: Posterior Distributions

We observe from Figure 2 that, with the increase of α , the graphs of posterior distributions $p(\theta|\hat{X} = 1)$ are skewed from 0 to 1.

- For $\alpha > \frac{1}{2}$, the camera reports back relatively true outcome of a coin flip. And the result value is perfectly correct when $\alpha = 1$.
- For $\alpha < \frac{1}{2}$, the camera reports back relatively false outcome of a coin flip. And the result value is exactly wrong when $\alpha = 0$.
- For $\alpha = \frac{1}{2}$, the camera cannot report back any useful information of a coin flip.

Question 3

a) The cdf for X can be derived as following:

$$\begin{aligned}F_X(x) &= P(X \leq x) \quad \dots \text{by definition} \\&= \int_{-\infty}^x p_X(z) dz \quad \dots \text{integral of pdf is cdf} \\&= \int_0^x p_X(z) dz \quad \dots 0 \leq x \leq 1\end{aligned}$$

The cdf for Y can be derived as following:

$$\begin{aligned}F_Y(y) &= P(Y \leq y) \quad \dots \text{by definition} \\&= P\left(\frac{1}{X} \leq y\right) \quad \dots Y = \frac{1}{X} \\&= P\left(\frac{1}{y} \leq X\right) \quad \dots X, y > 0 \\&= 1 - P\left(X < \frac{1}{y}\right) \quad \dots y \geq 1 \\&= 1 - P\left(X \leq \frac{1}{y}\right) \quad \dots X, y \text{ are continuous random variables,} \\&\quad \text{boundary value doesn't matter if being} \\&\quad \text{included or not} \\&= 1 - \int_0^{\frac{1}{y}} p_X(z) dz\end{aligned}$$

To get the pdf for Y , we derivate the cdf for Y :

$$\begin{aligned}p_Y(y) &= \frac{d}{dy} \left(1 - \int_0^{\frac{1}{y}} p_X(z) dz\right) \\&= - \frac{d}{dy} \left(\int_0^{\frac{1}{y}} p_X(z) dz\right)\end{aligned}$$

Apply the chain rule, we have $\frac{d}{dx} \int_a^{u(x)} f(t) dt = u'(x) f(u(x))$, then

$$\begin{aligned}
 P_Y(y) &= - \left(\frac{1}{y}\right)' P_X\left(\frac{1}{y}\right) \\
 &= - (y^{-1})' P_X\left(\frac{1}{y}\right) \\
 &= y^2 P_X\left(\frac{1}{y}\right) \\
 &= \frac{1}{y^2} P_X\left(\frac{1}{y}\right)
 \end{aligned}$$

Hence, we proved that $P_Y(y) = \frac{1}{y^2} P_X\left(\frac{1}{y}\right)$.

b) If player's guess m ~~was~~ ^{is} lower than c : ($m < c$, ~~$m \in$~~ ^{$m \in$} $[1, \infty)$)

player wins $m-1$, win probability $\int_m^\infty P_Y(y) dy$

If player's guess m ~~is~~ is higher than c : ($m > c$, $m \in [1, \infty)$)

player losses 1, loss probability ~~\int_1^m~~ $\int_1^m P_Y(y) dy$

We compute the expected profit as

$$\begin{aligned}
 E &= (m-1) \int_m^\infty P_Y(y) dy - \int_1^m P_Y(y) dy \\
 &= m \int_m^\infty P_Y(y) dy - \left(\int_1^m P_Y(y) dy + \int_m^\infty P_Y(y) dy \right) \\
 &= m \int_m^\infty P_Y(y) dy - \int_1^\infty P_Y(y) dy \\
 &= m \int_m^\infty P_Y(y) dy - 1 \quad \dots \text{pdf's integral is 1}
 \end{aligned}$$

Hence, the answer is $m \int_m^\infty P_Y(y) dy - 1$,

since we proved $P_Y(y) = \frac{1}{y^2} P_X\left(\frac{1}{y}\right)$ in a),

it can be expressed as $m \int_m^\infty \frac{1}{y^2} P_X\left(\frac{1}{y}\right) dy - 1$.

c) Take the equation of $P_X(x)$ into the conclusion of b), we derive

$$\text{expected profit } \mathbb{E} = m \int_m^{\infty} \frac{1}{y^2} dy - 1$$

$$= m \cdot \frac{1}{m} - 1 \quad \dots \int_m^{\infty} \frac{1}{y^2} dy = \frac{1}{m}, \quad \dots \text{calculated by WolframAlpha}$$

$$= 0$$

Hence, no matter what strategy the player uses, the expected profit is always 0.

d) Answer : $P_X(x) = -\ln(10) \cdot \log(x)$, $x \in (0, 1]$.

my idea of finding $P_X(x)$:

① $\int_0^1 P_X(x) dx = 1$ and $P_X(x) \geq 0$ (Basic)

② Since X is extremely biased towards small values, and $P_X(x) \geq 0$, I think $P_X(x)$ should be monotonically decreasing from ∞ to small values when $0 < x \leq 1$.

\Rightarrow I first thought of $-\log(x)$, but its integral over $(0, 1]$ is not 1, so I multiply it by $\ln(10)$.

\Rightarrow Finally, I derive $P_X(x) = -\ln(10) \cdot \log(x)$.

Proof of validity : $\int_0^1 P_X(x) dx = \int_0^1 [-\ln(10) \cdot \log_{10}(x)] dx = 1$ (WolframAlpha)

$$P_X(x) dx = -\ln(10) \log(x) \geq 0 \text{ for } 0 < x \leq 1.$$

$$\mathbb{E} = m \int_m^{\infty} \frac{1}{y^2} P_X\left(\frac{1}{y}\right) dy - 1 = m \int_m^{\infty} \frac{1}{y^2} (-\ln(10) \log\left(\frac{1}{y}\right)) dy - 1 = \ln(m) \quad (\text{WolframAlpha})$$

For any $B > 0$, $\exists m \geq e^B$, then $\mathbb{E} \geq \ln(e^B) = B$, expected profit is at least B .

$$(\text{eg: } m = 2 \cdot e^B) \Rightarrow \mathbb{E} = \ln(2e^B) = \ln(2) + B \geq B$$