

Name: \_\_\_\_\_

SR No: \_\_\_\_\_

Question:	1	Total
Points:	5	5
Score:		

1. Let  $(X_k : k \in \mathbb{N})$  be a sequence of independent and identically distributed random variables with  $P(X_k = 1) = P(X_k = -1) = 0.5$  for all  $k$ . For each  $n \in \mathbb{N}$ , define  $P_n = \prod_{k=1}^n X_k$ .

(a) Evaluate the mean and autocorrelation of the process  $(P_n : n \in \mathbb{N})$ . (3)

(b) Is the process  $(P_n : n \in \mathbb{N})$  wide-sense stationary? Justify your answer. (2)

### Summary for E2-202 Course

1.  $(\Omega, \mathcal{F})$  measurable space;  $\Omega$  - non-empty but otherwise arbitrary  
 $\mathcal{F}$  -  $\sigma$ -algebra of subsets of  $\Omega$

$P : \mathcal{F} \rightarrow [0, 1]$  prob. measure

(i)  $\Omega \in \mathcal{F}$

(ii)  $P(\Omega) = 1$  (pairwise)

(ii)  $A \in \mathcal{F} \Leftrightarrow A^c \in \mathcal{F}$

(iii)  $A_1, A_2, \dots \in \mathcal{F}$  disjoint  $\Rightarrow \bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$

$$P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P(A_i)$$

$(\Omega, \mathcal{F}, P)$  - probability space.

Note: If  $A \in \mathcal{F}$  and  $B \subseteq A$ , then it need not be the case that  $B \in \mathcal{F}$ . That is, not every subset of a set should belong to  $\mathcal{F}$ .

2. Some corollaries from above axioms:

•  $A \subseteq B \Rightarrow P(A) \leq P(B)$ , equality iff  $P(B|A) = 0$ .

Converse not true, i.e.;  $P(A) \leq P(B) \not\Rightarrow A \subseteq B$ .

•  $P(\emptyset) = 0$

•  $P(A \cup B) = P(A) + P(B) - P(A \cap B)$

• Finite additivity:  $A_1, \dots, A_n$  pairwise disjoint. Then,  $P\left(\bigcup_{i=1}^n A_i\right) = \sum_{i=1}^n P(A_i)$ .

3. Continuity of prob. measure  $P$ :

(i) If  $A_1 \subseteq A_2 \subseteq \dots$ ,  $A_i \in \mathcal{F}$ , then

$$P\left(\bigcup_{i=1}^{\infty} A_i\right) = \lim_{i \rightarrow \infty} P(A_i)$$

(ii) If  $A_1 \supseteq A_2 \supseteq \dots$ ,  $A_i \in \mathcal{F}$ , then

$$P\left(\bigcap_{i=1}^{\infty} A_i\right) = \lim_{i \rightarrow \infty} P(A_i).$$

3. Conditional probability : Two events A and B given.

$$\underline{P(A \cap B) = P(A)}$$

Suppose  $P(B) > 0$ .

$P(A|B) := \frac{P(A \cap B)}{P(B)}$ . This def<sup>n</sup> makes sense only if  $P(B) > 0$ . Otherwise, if  $P(B) = 0$ , all we can say is  $P(A \cap B) \leq P(B) = 0 \Leftrightarrow P(A \cap B) = 0$ .

Note:  $A|B$  is not an event. The above B s.t.

def<sup>n</sup> means that for fixed  $P(B) > 0$ ,

$Q(\cdot) = P(\cdot|B) : \mathcal{F} \rightarrow [0,1]$  is a probability measure

Law of total probability ;

Partition  $\Omega$  into  $B_1, B_2, \dots$ , i.e.,

$$\Omega = \bigcup_{i=1}^{\infty} B_i, \quad B_i \cap B_j = \emptyset \quad \forall i \neq j.$$

Then, for any event  $A \in \mathcal{F}$ ,

$$P(A) = \sum_{i=1}^{\infty} P(A|B_i) \cdot P(B_i)$$

$$P(A) = P(A \cap \Omega)$$

$$= P(A \cap \bigcup_{i=1}^{\infty} B_i)$$

$$= P\left(\bigcup_{i=1}^{\infty} A \cap B_i\right)$$

$$= \sum_{i=1}^{\infty} P(A \cap B_i)$$

Further, if  $P(B_i) > 0 \quad \forall i$ , then

$$P(A) = \sum_{i=1}^{\infty} P(A|B_i) P(B_i)$$

Bayes rule :

$$P(B_i|A) = \frac{P(A|B_i) P(B_i)}{P(A)}. \quad \begin{array}{l} \text{(This is just a restatement of} \\ \text{saying} \\ P(A) \cdot P(B_i|A) = P(A \cap B_i) \\ = P(B_i) P(A|B_i). \end{array}$$

when  $P(B_i) > 0 \quad \forall i$  and  $P(A) > 0$ .

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(a) Evaluate the mean and autocorrelation of the process  $(P_n : n \in \mathbb{N})$ . (3)

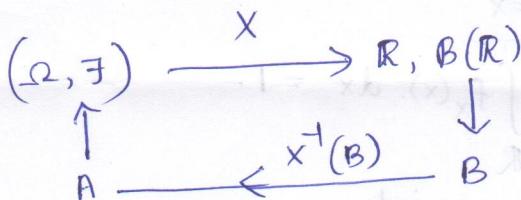
(b) Is the process  $(P_n : n \in \mathbb{N})$  wide-sense stationary? Justify your answer. (2)

#### 4. Random variables:

$(\Omega, \mathcal{F})$  given.

$x : \Omega \rightarrow \mathbb{R}$  is called a rv (or a measurable function) iff :

$\forall B \in \mathcal{B}(\mathbb{R})$ ,  $A = x^{-1}(B) \in \mathcal{F}$ .



- The def<sup>n</sup> of rv depends on what  $\mathcal{F}$  is. A func<sup>n</sup> which is a rv wrt a  $\sigma$ -algebra need not be a rv wrt another, perhaps different,  $\sigma$ -algebra.

When we consider  $\mathbb{R}$ , associated  $\sigma$ -algebra is the Borel  $\sigma$ -algebra of subsets of  $\mathbb{R}$ , denoted  $\mathcal{B}(\mathbb{R})$ . How we construct  $\mathcal{B}(\mathbb{R})$  is : collect all open subsets of  $\mathbb{R}$ , & build the smallest  $\sigma$ -algebra starting from it.

#### 5. CDF:

$$(\Omega, \mathcal{F}, P) \xrightarrow{x} (\mathbb{R}, \mathcal{B}(\mathbb{R}), P_x)$$

$P$  induces a prob. measure  $P_x$  on  $\mathbb{R}$  through  $x$ .

$P$  and  $P_x$  are nicely related as :

$$P_x((-\infty, x]) = P(\omega : x(\omega) \leq x).$$

This is called the cdf of  $x$ , denoted  $F_x(x)$ .

Thus,

$F_x(x) = P(x \leq x) \quad \forall x \in \mathbb{R}$   
 is a func<sup>n</sup> on  $\mathbb{R}$ , taking values in  $[0, 1]$   
 $(F_x : \mathbb{R} \rightarrow [0, 1]).$

### Properties of cdf:

- Right continuous ( $F(x+h) \rightarrow F(x)$  as  $h \downarrow 0$ )
- Non-decreasing ( $F(x) \leq F(y)$  if  $x \leq y$ )
- $\lim_{x \rightarrow \infty} F(x) = 1$ ,  $\lim_{x \rightarrow -\infty} F(x) = 0$ .

CDF always exists!

### 6. Pmf and pdf

Discrete svs:  $x: \Omega \rightarrow \mathbb{R}$  is discrete if it takes at most countably many values. We define pmf for  $X$  as

$$p_x(x) = P(X=x).$$

pmf sums up to 1, i.e.,  $\sum_x p_x(x) = 1$ .

Continuous svs:  $x: \Omega \rightarrow \mathbb{R}$  is continuous if its cdf is continuous.

We define pdf for  $X$  as

$$f_x(x) = \left. \frac{d}{dt} F_x(t) \right|_{t=x}$$

pdf integrates to 1, i.e.,  $\int_{\mathbb{R}} f_x(x) dx = 1$ .

Note: pdf need not always exist.

Similar notions extend to random vectors. There we have joint cdf and joint pmf/pdf.

### 7. Independence:

(i) of events:  $A, B \in \mathcal{F}$  are indep. iff  $P(A \cap B) = P(A) P(B)$

indep & condn'l indep. (ii) of svs: Two svs  $x: \Omega \rightarrow \mathbb{R}$  and  $y: \Omega \rightarrow \mathbb{R}$  are indep. iff

$\forall$  Borel sets  $C$  and  $D$ , we have  $P(x \in C, y \in D) = P(x \in C, y \in D)$ .

Instead of checking  $\forall C, D \in \mathcal{B}(\mathbb{R})$ , it suffices to check for

$(-\infty, x]$  and  $(-\infty, y]$   $\forall x, y \in \mathbb{R}$ ;

$x \perp\!\!\!\perp y \Leftrightarrow P(x \leq x, y \leq y) = P(x \leq x) P(y \leq y), \forall x, y \in \mathbb{R}$ .

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(a) Evaluate the mean and autocorrelation of the process  $(P_n : n \in \mathbb{N})$ . (3)(b) Is the process  $(P_n : n \in \mathbb{N})$  wide-sense stationary? Justify your answer. (2)

### 8. Expectations as Lebesgue integrals

- (i) For simple rws:  $x : \Omega \rightarrow \mathbb{R}$  is simple if it takes only finitely many values, say  $a_1, \dots, a_n \in \mathbb{R}$ ,  $n < \infty$ . For such a rw, expectation is defined as

$$E[x] = \sum_{i=1}^n a_i P(X=a_i).$$

- (ii) For non-negative rws:

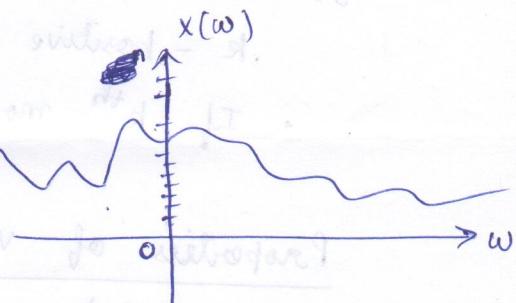
Given  $X \geq 0$ , perform a quantization into  $n \cdot 2^n$  levels. Call this quantized

rw as  $X_n$ , i.e.,

$$X_n(\omega) = \sum_{i=1}^{n \cdot 2^n} \frac{i-1}{2^n} \cdot \mathbf{1}_{\left[\frac{i-1}{2^n}, \frac{i}{2^n}\right)}(x_n(\omega)) + n \mathbf{1}_{(x_n(\omega) \geq n)}.$$

Then,  $X_n(\omega) \uparrow X(\omega) \quad \forall \omega \in \Omega$ . Define

$$E[X] = \lim_{n \rightarrow \infty} E[X_n].$$



- (iii) For arbitrary rws:

Suppose  $x : \Omega \rightarrow \mathbb{R}$  is a rw. Define

$$x_+ = \max\{0, x\}, \quad x_- = -\min\{0, x\}.$$

Then,  $Ex$  is defined as

$$Ex = Ex_+ - Ex_- \text{ provided the RHS is not } -\infty.$$

If RHS is  $-\infty$ , then  $Ex$  is undefined (or  $Ex$  doesn't exist).

Note:  $Ex$  exists iff ~~exists~~

$$\min\{Ex_+, Ex_-\} < \infty$$

$Ex$  is finite iff  $E|x| < \infty$ .

## Properties of expectation

1.  $E[aX + bY] = aE[X] + bE[Y]$  (linearity) (only for sums of finite # rvs, not infinite, i.e.,  $E\left[\sum_{k=1}^{\infty} a_k X_k\right] = \sum_{k=1}^{\infty} a_k E[X_k]$  in general)
2. If  $X \leq Y$ ,  $E[X] \leq E[Y]$ .
3. Suppose  $X \geq 0$  is a non-negative rv. Then
  - $E[X] = 0 \Rightarrow P(X=0) = 1$ .
  - $E[X] < \infty \Rightarrow P(X < \infty) = 1$ . this is sometimes useful in the context of stopping times, to show that a stopping time is finite with prob. 1.
4.  $E[XY] = E[X]E[Y]$   $\Leftarrow$   
 $x$  and  $y$  are uncorrelated if
4. If  $x$  and  $y$  are independent, then  $x$  &  $y$  are uncorrelated.  
 $X \perp\!\!\!\perp Y \Rightarrow X \text{ & } Y \text{ uncorrelated}$   
 $\Leftarrow$ ? not always.
5.  $X$  rv,  
 $k$ -positive integer  
 • If  $k^{\text{th}}$  moment is finite, all lower order moments are finite.

## Properties of variance

- $$\text{Var}(X) = E[(X - E[X])^2] \stackrel{\text{if } E[X] < \infty}{=} E[X^2] - (E[X])^2$$
- For any 2 rvs  $X$  and  $Y$ ,  
 $\text{Var}(X+Y) = \text{Var}(X) + \text{Var}(Y) + 2\text{cov}(X, Y)$
  - If  $x$  and  $y$  are uncorrelated,  
 $\text{Var}(x+y) = \text{Var}(x) + \text{Var}(y)$
  - $\text{Var}(aX) = a^2 \text{Var}(X)$

### Cauchy-Schwarz

$$|\text{cov}(X, Y)| \leq \sqrt{\text{Var}(X)\text{Var}(Y)}$$

Define  $\rho(X, Y) = \frac{\text{cov}(X, Y)}{\sqrt{\text{Var}(X)\text{Var}(Y)}}$  — correlation coefficient.

Then, Cauchy-Schwarz says

$$|\rho(X, Y)| \leq 1$$

Equality implies  $\exists a, b \in \mathbb{R}$  s.t.  $X = aY + b$ .

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### 9. Some inequalities:

• Markov (only for non-neg rws) Suppose  $x \geq 0$ . Then,

$$P(X > t) \leq \frac{Ex}{t} \quad \forall t > 0.$$

• Chebyshev (for any rws)

$$P(|X - Ex| > t) \leq \frac{\text{Var}(X)}{t^2}.$$

• Chernoff bound (for any rws)

$$\begin{aligned} P(X > a) &= P(tx > ta) \\ &= P(e^{tx} > e^{ta}) \end{aligned} \quad \forall t > 0$$

$$\leq \frac{E[e^{tx}]}{e^{ta}} \quad (\text{by Markov}), \quad \forall t > 0$$

$$\Rightarrow P(X > a) \leq \inf_{t > 0} \frac{E[e^{tx}]}{e^{ta}}.$$

### 10. MGF and characteristic func<sup>n</sup>

$$M_X(t) = E[e^{tx}] \quad (\text{expect. always exists since } e^{tx} > 0), \quad t \in \mathbb{R}.$$

If  $M_X(t) < \infty \quad \forall t \in (-\delta, \delta)$  for some  $\delta > 0$ , then all moments of  $X$  exist.

Properties: (i)  $M_X(0) = 1$ .

(ii) If all moments exist, then

$$E[X^n] = d^n |M_X(t)|.$$

- If  $m_x(t) = m_y(t) \forall t \in \mathbb{R}$ , then  $F_x(x) = F_y(x) \forall x \in \mathbb{R}$ ,  
i.e., mgf uniquely characterizes the distn.

- Two rvs  $x$  and  $y$  are independent. Then,

$$M_{x+y}(t) = M_x(t) M_y(t) \forall t \in \mathbb{R}.$$

Characteristic func<sup>n</sup>

$$\phi_x(\omega) = E[e^{j\omega X}], \quad \omega \in \mathbb{R}.$$

Properties:

$$(i) \phi_x(0) = 1$$

$$(ii) |\phi_x(\omega)| \leq 1 \quad \forall \omega \in \mathbb{R}.$$

(iii) If  $EX^n$  exists, then it can be obtained by

$$EX^n = (-j)^n \cdot \frac{d^n}{dw^n} (\phi_x(w))|_{w=0}.$$

(iv)

$$X \perp\!\!\!\perp Y \Rightarrow \phi_{x+y}(\omega) = \phi_x(\omega) \phi_y(\omega).$$

Note:

$$X \perp\!\!\!\perp Y \Leftrightarrow \forall t_1, t_2 \in \mathbb{R},$$

$$m_x(t) = m_{x_1}(t_1) m_{x_2}(t_2), \text{ where}$$

$$\underline{x} = \begin{bmatrix} x \\ y \end{bmatrix}, \quad \underline{t} = \begin{bmatrix} t_1 \\ t_2 \end{bmatrix} \in \mathbb{R}.$$

$$X \perp\!\!\!\perp Y \Leftrightarrow \forall w_1, w_2 \in \mathbb{R},$$

$$\phi_x(\underline{\omega}) = \phi_{x_1}(\omega_1) \phi_{x_2}(\omega_2), \text{ where}$$

$$\underline{x} = \begin{bmatrix} x \\ y \end{bmatrix}, \quad \underline{\omega} = \begin{bmatrix} \omega_1 \\ \omega_2 \end{bmatrix}.$$

- If  $X \perp\!\!\!\perp Y$ , then density of  $X+Y$  ~~=~~ convolution of  $f_x$  and  $f_y$   
Converse not true. (HW4, Q1)

Joint mgf and char. func<sup>n</sup>:

$$\boxed{\begin{aligned} & \underline{x} = (x_1, \dots, x_n), \quad \underline{t} = (t_1, \dots, t_n) \in \mathbb{R}^n, \quad \underline{\omega} = (\omega_1, \dots, \omega_n) \in \mathbb{R}^n \\ & m_x(\underline{t}) = E[e^{\underline{t}^T \underline{x}}] \end{aligned}}$$

$$m_x(\underline{t}) = E[e^{\underline{t}^T \underline{x}}]$$

$$\phi_x(\underline{\omega}) = E[e^{j\underline{\omega}^T \underline{x}}].$$

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$$P(S_1 > s | N(t) = n).$$

Characteristic function & joint characteristic func<sup>n</sup> always exist

10. Jointly Gaussian rns :

$$x_1, \dots, x_n \text{ jointly Gaussian iff } \Phi_X(\omega) = e^{j\omega^T \mu - \frac{\omega^T K \omega}{2}}, \text{ where } \mu = E\underline{x}.$$

Alternatively,  $x_1, \dots, x_n$  jointly Gaussian

iff every linear combination of  $x_1, \dots, x_n$  is Gaussian, i.e.,  
 $a_1 x_1 + \dots + a_n x_n$  Gaussian  $\forall a_1, \dots, a_n \in \mathbb{R}$ .

Properties of  $K$ :

(i)  $K$  is symmetric. Thus, all its eigenvalues are real.

Also,  $K$  is diagonalizable, i.e.,  $\exists$  an orthogonal matrix

$Q$  s.t.

$$Q K Q^T = \text{diag}(\lambda_1, \dots, \lambda_n); \quad \lambda_1, \dots, \lambda_n - \text{eigenvalues}$$

(ii)  $K$  is tve semidefinite, i.e.,

$$\underline{a}^T K \underline{a} \geq 0 \quad \forall \underline{a} \in \mathbb{R}^n.$$

diag - matrix with only diagonal entries

If  $K$  is tve definite, then it is invertible, and a joint pdf for  $x_1, \dots, x_n$  jointly Gaussian can be written as

$$f_{\underline{x}}(\underline{x}) = \frac{1}{(2\pi)^n \sqrt{\det(K)}} e^{-\frac{1}{2} (\underline{x} - \mu)^T K^{-1} (\underline{x} - \mu)}$$

$\forall \underline{x} \in \mathbb{R}^n$

~~Given~~

- $x_1, \dots, x_n$  jointly Gaussian. Then

$x_1, \dots, x_n$  indep  $\Leftrightarrow$  cov. matrix is diagonal.

Corollary : If  $X$  and  $Y$  are jointly Gaussian, then

$X \perp\!\!\!\perp Y \Leftrightarrow X$  and  $Y$  uncorrelated.

## II. Transformations:

$$T: (x_1, \dots, x_n) \rightarrow (y_1, \dots, y_n)$$

$$f_{y_1, \dots, y_n}(y_1, \dots, y_n) = \left| \begin{array}{cccc} \frac{\partial x_1}{\partial y_1} & \frac{\partial x_1}{\partial y_2} & \dots & \frac{\partial x_1}{\partial y_n} \\ \vdots & & & \\ \frac{\partial x_n}{\partial y_1} & \frac{\partial x_n}{\partial y_2} & \dots & \frac{\partial x_n}{\partial y_n} \end{array} \right| \cdot f_{x_1, \dots, x_n}(x_1, \dots, x_n)$$

$\underbrace{|\det(\text{Jacobian})|}$

## 12. Conditional expectations

$(\Omega, \mathcal{F}, P)$  given,  $X: \Omega \rightarrow \mathbb{R}$  r.v. given.

Suppose  $\mathcal{G} \subseteq \mathcal{F}$  is a sub  $\sigma$ -algebra of  $\mathcal{F}$ . Then,

$E[X|\mathcal{G}]$  is any r.v.  $Y$  which satisfies :

(i)  $Y \in \mathcal{G}$ , i.e.,  $Y$  is  $\mathcal{G}$ -measurable

(ii)  $\forall A \in \mathcal{G}$ ,

$$\int_A x dP = \int_A y dP$$

$$\text{or } E[X \mathbf{1}_A] = E[Y \mathbf{1}_A].$$

E.g.: • If  $X \perp\!\!\!\perp \mathcal{G}$ , then  $E[X|\mathcal{G}] = E[X]$

• If  $X \in \mathcal{G}$ , then  $E[X|\mathcal{G}] = X$ .

•  $E[X|Y] = E[X|\sigma(Y)]$ , where  $\sigma(Y)$  is the smallest  $\sigma$ -algebra w.r.t. which  $Y$  is measurable, i.e.,

$$\sigma(Y) = \{A \in \mathcal{F} : \exists B \in \mathcal{B}(\mathbb{R}) \text{ s.t. } A = Y^{-1}(B)\}$$

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$$P(S_1 > s | N(t) = n).$$

## 12. Convergence

Four forms: Almost sure:  $P(x_n \rightarrow x) = 1$ .

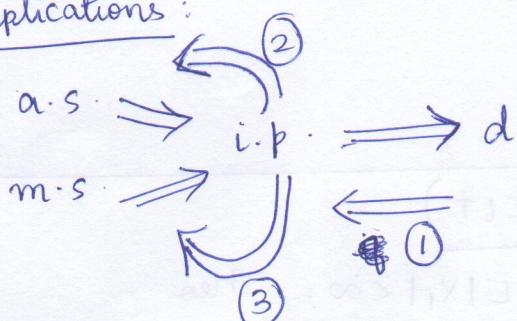
In prob:  $P(|x_n - x| > \varepsilon) \xrightarrow{n \rightarrow \infty} 0 \quad \forall \varepsilon > 0$

mean-squared:  $E[(x_n - x)^2] \xrightarrow{n \rightarrow \infty} 0$ .

In distribution:  $F_{x_n}(x) \xrightarrow{n \rightarrow \infty} F_x(x) \quad \forall x \in C_{F_x}$

↓  
set of  
continuity  
points of  
 $F_x$ .

### Implications:



① This is true only when  $x_n \xrightarrow{d} c$ ,  $c \in \mathbb{R}$ .

② Borel-Cantelli Lemma helps us go from i.p. to a.s.

③ If  $P(|x_n| \leq L) = 1 \quad \forall n \geq 1$ , then

$$x_n \xrightarrow{\text{i.p.}} x \Rightarrow x_n \xrightarrow{\text{m.s.}} x$$

### Borel-Cantelli Lemma:

• Infinitely often set: Let  $A_1, A_2, \dots \in \mathcal{F}_t$ . Then

$A = \bigcap_{n=1}^{\infty} \bigcup_{k=n}^{\infty} A_k$  is called "An i.o." set.  
or "w i.o." set.

- All but finitely many set :  $B = \bigcup_{k=1}^{\infty} \bigcap_{n=k}^{\infty} A_k$ .

Fact :  $B \subseteq A$ , i.e.,

NOTE : BCL is stated at the end of this doc.

$$\bigcup_{n=1}^{\infty} \bigcap_{k=n}^{\infty} A_k \subseteq \bigcap_{n=1}^{\infty} \bigcup_{k=n}^{\infty} A_k$$

13. Exchanging limits and expectations

$$\left( \lim_{n \rightarrow \infty} E[x_n] = E\left[\underbrace{\lim_{n \rightarrow \infty} x_n}_{=X}\right]. \right)$$

(i) MCT

(a) Suppose  $x_n \geq y$ ,  $Ey > -\infty$  and  $x_n \uparrow x$ . Then  $Ex_n \uparrow Ex$ .

(b) Suppose  $x_n \leq y$ ,  $Ey < \infty$ , and  $x_n \downarrow x$ . Then,  $Ex_n \downarrow Ex$ .

Corollary : If  $x_n \geq 0 \ \forall n \geq 1$ ,

frequently

$$E\left[\sum_{n=1}^{\infty} x_n\right] = \sum_{n=1}^{\infty} E[x_n] \quad (\text{used for } x_n = \mathbb{1}_{A_n}).$$

(ii) DCT :

Suppose  $|x_n| \leq y$ ,  $Ey < \infty$  and  $x_n \xrightarrow{a.s.} x$ . Then,

(i)  $E|x| < \infty$ .

(ii)  $Ex_n \rightarrow Ex$ .

14. Limit Theorems (WLLN, SLLN, CLT)

(i) WLLN :  $x_1, \dots, x_n \stackrel{iid}{\sim}$ ,  $E|x_1| < \infty$ . Then

$$\frac{x_1 + \dots + x_n}{n} \xrightarrow[n \rightarrow \infty]{i.p.} E[x_1].$$

(ii) SLLN :  $x_1, \dots, x_n \stackrel{iid}{\sim}$ ,  $E|x_1| < \infty$ . Then

$$\frac{x_1 + \dots + x_n}{n} \xrightarrow[n \rightarrow \infty]{a.s.} E[x_1].$$

(iii) CLT :  $x_1, \dots, x_n \stackrel{iid}{\sim}$ ,  $\text{Var}(x_1) < \infty$ . Then

$$\frac{x_1 + \dots + x_n}{\sqrt{n}} \xrightarrow[n \rightarrow \infty]{d} N(0, 1)$$

(Here,  $x_i$ 's are assumed to have zero mean & unit variance wlog)

Name: \_\_\_\_\_ SR No: \_\_\_\_\_

Question:	1	Total
Points:	5	5
Score:		

1. Let  $(N(t) : t \geq 0)$  be a homogeneous Poisson process with uniform rate  $\lambda$ . Let  $S_1$  denote the first jump time. Given  $t > 0$ , find the following conditional distribution for all  $s > 0$  and  $n \in \mathbb{N}$ ,

$$P(S_1 > s | N(t) = n).$$

### 15. Random processes

- It is a collection of rns  $\{x_t : t \in T\}$ . Here,  $T$  is an arbitrary index set.
  - Mean func<sup>n</sup>  $\mu_x(t) = E[x_t]$ .
  - Correlation func<sup>n</sup>  $R_x(t, \tau) = E[x_t x_\tau]$ .

- A random process is fully specified by its FDDs, i.e.,

$$F_{x_{t_1}, x_{t_2}, \dots, x_{t_n}}(x_1, \dots, x_n) \quad \forall t_1, \dots, t_n \in T \\ \forall x_1, \dots, x_n \in \mathbb{R} \\ \forall n \geq 1.$$

- A rpn is said to be (strictly) stationary iff FDDs are time shift invariant, i.e.,

$$F_{x_{t_1}, x_{t_2}, \dots, x_{t_n}}(x_1, \dots, x_n) = F_{x_{t_1+\tau}, x_{t_2+\tau}, \dots, x_{t_n+\tau}}(x_1, \dots, x_n) \\ \forall x_1, \dots, x_n \in \mathbb{R} \\ \forall t_1, \dots, t_n \in T \\ \forall \tau, \dots, t_n + \tau \in T \\ \forall n \geq 1.$$

- A rpn is said to be wide-sense stationary (wss) iff
  - $\mu_x$  is not a func<sup>n</sup> of time
  - $R_x(t, t+\tau)$  is a func<sup>n</sup> only of  $\tau$   $\forall t \in T$ ,  $\forall \tau \in T$

- Any iid process is stationary.

## 16. DTMCs and Bernoulli processes

- $\{X_n : n \geq 1\}$  iid  $\text{Ber}(p)$  process.
- $N_n$  - # successes till time  $n$ .
- success instants  $T_k$ .  
time
- $\{T_k \leq n\} = \{N_{n+1} \geq k\}$ ;  $(T_k)$  and  $(N_n)$  are inverse processes.

stopping times:

$(\Omega, \mathcal{F}, P)$  given.

.  $(\mathcal{F}_t)_{t \in T}$  is a filtration - given

. A rv  $\tau : \Omega \rightarrow T$  is called a stopping time wrt  $(\mathcal{F}_t)$

if :  $\{\tau \leq t\} \in \mathcal{F}_t \quad \forall t \in T$ .

Properties of stopping times:

.  $\tau_1, \tau_2$  st  $\xrightarrow{\text{stop. time}}$   $\min\{\tau_1, \tau_2\}$  is a stopping time

.  $\tau_1, \tau_2$  st and  $T$  separable  $\Rightarrow \tau_1 + \tau_2$  stopping time

Stopping time  $\sigma$ -algebra

$$\mathcal{F}_\tau := \{A \in \mathcal{F} : A \cap \{\tau \leq t\} \in \mathcal{F}_t \quad \forall t \in T\}.$$

Wald's Lemma: iid

(i) Let  $(X_n)$  be a ~~process~~, and  $\mathcal{F}_n = \sigma(X_1, \dots, X_n)$ .

If  $P(N=n)=1$ , then

$$E\left[\sum_{i=1}^N X_i\right] = \sum_{i=1}^N E[X_i] = EN \cdot EX_1.$$

(ii) If  $N \parallel X_1, X_2, \dots$  ~~process~~ and  $X_i$  are iid, then

$$E\left[\sum_{i=1}^N X_i\right] = EN \cdot EX_1$$

Wald: (iii) If  $N$  is a stopping time with  $P(N < \infty) = 1$ , then

$$E\left[\sum_{i=1}^N X_i\right] = EN \cdot EX_1$$

Name: \_\_\_\_\_ SR No: \_\_\_\_\_

Question:	1	Total
Points:	5	5
Score:		

1. Let  $(N(t) : t \geq 0)$  be a homogeneous Poisson process with uniform rate  $\lambda$ . Let  $S_1$  denote the first jump time. Given  $t > 0$ , find the following conditional distribution for all  $s > 0$  and  $n \in \mathbb{N}$ ,

$$P(S_1 > s | N(t) = n).$$

Note: For Wald's lemma,  $N$  should be a stopping time wrt

$$\mathcal{F}_n = \sigma(x_1, \dots, x_n).$$

DTMCs:

- $(x_n)_{n \geq 1}$  is a DTMC on a countable state space  $S$  iff

$$P(x_{n+1} = j \mid x_0 = i_0, \dots, x_n = i_n) = P(x_{n+1} = j \mid x_n = i)$$

forall  $i_0, i_1, \dots, i_{n-1}, j, i \in S$  and  $\forall n \geq 1$ .

Time-homogeneity:

$$P(x_{n+1} = j \mid x_n = i) = P(x_1 = j \mid x_0 = i) = p_{ij}$$

- TPM: An  $|S| \times |S|$  matrix  $P$  whose  $(i, j)^{\text{th}}$  entry is  $(P)_{ij} = p_{ij}$ .

Row sums of  $P$  are 1.

Chapman-Kolmogorov equation:

$$p_{ij}^{(n)} = (P^n)_{ij}.$$

Strong Markov property:

$$P(x_{n+k} = j \mid x_0 = i_0, \dots, x_n = i_n) = p_{ij}^{(k)}.$$

## Hitting times & Recurrence times

$H_j = \inf \{ n \geq 1 : X_n = j \} \rightarrow$  first hitting time for state  $j$ .

$$f_{ij}^{(n)} = P(H_j = n | X_0 = i)$$

$$f_{ij} = \sum_{n=1}^{\infty} f_{ij}^{(n)}$$

- If  $f_{jj} < 1$ , then  $j$  is called transient.

$f_{jj} = 1$ ,  $j$  is called recurrent.

$$\mu_{jj} = \sum_{n=1}^{\infty} n \cdot f_{jj}^{(n)}$$

$\mu_{jj} < \infty$   
transient

$\mu_{jj} = +\infty$   
Null recurrent

-  $j$  transient  $\Leftrightarrow \sum_{n=1}^{\infty} p_{jj} < \infty$  (BCL; see mid term Q1)

$j$  recurrent  $\Leftrightarrow \sum_{n=1}^{\infty} p_{jj} = +\infty$  (cannot use BCL since  $(X_n)$  is not indep seq, it is Markov!)

## Communicating classes & class properties

-  $i \rightsquigarrow j$  if  $p_{ij}^{(n)} > 0$  for some  $n > 0$ .

-  $i \leftrightarrow j$  iff  $i \rightsquigarrow j$  and  $j \rightsquigarrow i$ .

ans partitions  $S$  into equivalence classes called Comm. classes.

- DTMC is said to be irreducible if only one comm class exists.

- Period of a state:

$$d(j) = \gcd \left( \{ n \geq 1 : f_{jj}^{(n)} > 0 \} \right).$$

$$= \gcd \left( \{ n \geq 1 : p_{jj}^{(n)} > 0 \} \right).$$

Name: \_\_\_\_\_ SR No: \_\_\_\_\_

Question:	1	Total
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Score:		

1. Let  $(N(t) : t \geq 0)$  be a homogeneous Poisson process with uniform rate  $\lambda$ . Let  $S_1$  denote the first jump time. Given  $t > 0$ , find the following conditional distribution for all  $s > 0$  and  $n \in \mathbb{N}$ ,

$$P(S_1 > s | N(t) = n).$$

- If ~~d(j)=1~~, j is called aperiodic state.
- Transience, recurrence & periodicity are class properties.
- A comm. class  $C$  is called open if there are no edges leaving  $C$ . A class which is not closed is said to be open.
- Open comm classes are transient
- Finite closed comm classes are the recurrent.

### Invariant distributions

A prob distb<sup>n</sup>  $\underline{\pi}$  is said to be a stationary distb<sup>n</sup> iff it satisfies  $\underline{\pi} = \underline{\pi} P$ .

- $(x_n)_{n \geq 1}$  DMC irreducible. Then  $\underline{\pi}$  prob vector
- $(x_n)_{n \geq 1}$  the recurrent  $\Leftrightarrow \exists$  unique  $\underline{\pi}_n$  s.t.  $\underline{\pi} = \underline{\pi} P$ .

- If  $(x_n)_{n \geq 1}$  is aperiodic, irreducible & the recurrent, then  $P_{ij}^{(n)} \rightarrow \pi_j$  as  $n \rightarrow \infty$   $\forall j \in S$ .

Consequently,

$$\text{little } n \text{ of } \pi_j^{(n)} \rightarrow \pi_j \quad \forall j \in S.$$

- one could use

### Borel - Cantelli Lemma

$A_1, A_2, \dots \in \mathcal{F}$

(i) If  $\sum_{n=1}^{\infty} P(A_n) < \infty$ , then  $P(A_n \text{ i.o.}) = 0$ .

(ii) If  $A_n$ 's are ~~independent~~ <sup>mutually</sup> independent (~~ie,  $A_i \cap A_j = \emptyset \forall i \neq j$~~ )  
and  $\sum_{n=1}^{\infty} P(A_n) = +\infty$ , then  $P(A_n \text{ i.o.}) = 1$

Note: we don't require independence above. Actually, only pairwise independence suffices.