CNN on CIFR Assignment:

- Please visit this link to access the state-of-art DenseNet code for reference DenseNet cifar10 notebook link
- 2. You need to create a copy of this and "retrain" this model to achieve 90+ test accuracy.
- 3. You cannot use DropOut layers.
- 4. You MUST use Image Augmentation Techniques.
- 5. You cannot use an already trained model as a beginning points, you have to initilize as your own
- 6. You cannot run the program for more than 300 Epochs, and it should be clear from your log, that you have only used 300 Epochs
- 7. You cannot use test images for training the model.
- 8. You cannot change the general architecture of DenseNet (which means you must use Dense Block, Transition and Output blocks as mentioned in the code)
- 9. You are free to change Convolution types (e.g. from 3x3 normal convolution to Depthwise Separable, etc)
- 10. You cannot have more than 1 Million parameters in total
- 11. You are free to move the code from Keras to Tensorflow, Pytorch, MXNET etc.
- 12. You can use any optimization algorithm you need.
- 13. You can checkpoint your model and retrain the model from that checkpoint so that no need of training the model from first if you lost at any epoch while training. You can directly load that model and Train from that epoch.

```
from google.colab import drive
drive.mount('/content/gdrive')

Mounted at /content/gdrive

from tensorflow.python.client import device_lib
device_lib.list_local_devices()

[name: "/device:CPU:0"
    device_type: "CPU"
    memory_limit: 268435456
    locality {
    }
    incarnation: 6447702113979293328, name: "/device:GPU:0"
    device_type: "GPU"
    memory_limit: 11345264640
    locality {
        bus_id: 1
```

```
links {
        }
      }
      incarnation: 16374535067227115615
      physical device desc: "device: 0, name: Tesla K80, pci bus id: 0000:00:04.0, compute ca
import os
root path = '/content/gdrive/MyDrive/cifar-10'
import warnings
warnings.filterwarnings("ignore")
# import keras
# from keras.datasets import cifar10
# from keras.models import Model, Sequential
# from keras.layers import Dense, Dropout, Flatten, Input, AveragePooling2D, merge, Activatio
# from keras.layers import Conv2D, MaxPooling2D, BatchNormalization
# from keras.layers import Concatenate
# from keras.optimizers import Adam
from tensorflow.keras import models, layers
from tensorflow.keras.models import Model
from tensorflow.keras.layers import BatchNormalization, Activation, Flatten
from tensorflow.keras.optimizers import Adam
# this part will prevent tensorflow to allocate all the avaliable GPU Memory
# backend
import tensorflow as tf
# Hyperparameters
batch size = 128
num classes = 10
epochs = 30
1 = 6
num filter = 64
compression = 0.5
dropout_rate = 0
# Load CIFAR10 Data
(X_train, y_train), (X_test, y_test) = tf.keras.datasets.cifar10.load_data()
img height, img width, channel = X train.shape[1],X train.shape[2],X train.shape[3]
# convert to one hot encoing
y_train = tf.keras.utils.to_categorical(y_train, num_classes)
y_test = tf.keras.utils.to_categorical(y_test, num_classes)
     Downloading data from <a href="https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz">https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz</a>
     170500096/170498071 [==============] - 2s Ous/step
```

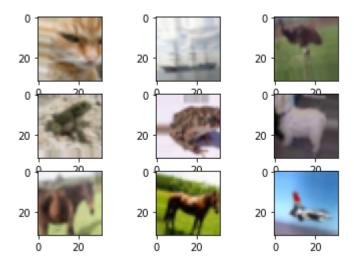
```
170508288/170498071 [============= ] - 2s Ous/step
X train.shape
    (50000, 32, 32, 3)
y_train.shape
    (50000, 10)
X_test.shape
    (10000, 32, 32, 3)
y test.shape
    (10000, 10)
```

Data Augmentation:

- Data augmentation involves making copies of the examples in the training dataset with small random modifications.
- This has a regularizing effect as it both expands the training dataset and allows the model to learn the same general features, although in a more generalized manner.

```
#https://machinelearningmastery.com/how-to-develop-a-cnn-from-scratch-for-cifar-10-photo-clas
   from keras.preprocessing.image import ImageDataGenerator
   # define data preparation
   # Using image augmentation techniques
   datagen = ImageDataGenerator(
           featurewise_center=False, # set input mean to 0 over the dataset
           samplewise center=False, # set each sample mean to 0
           zca whitening=False, # apply ZCA whitening
           rotation_range=12, # randomly rotate images in the range (degrees, 0 to 180)
           zoom range = 0.15, # Randomly zoom image
           width shift range=0.15, # randomly shift images horizontally (fraction of total widt
           height shift range=0.15, # randomly shift images vertically (fraction of total heigh
           horizontal_flip=True, # randomly flip images
           vertical flip=False) # randomly flip images
   datagen.fit(X train)
   import matplotlib.pyplot as plt
   import numpy as np
   # configure batch size and retrieve one batch of images
   for X_batch, y_batch in datagen.flow(X_train, y_train, batch_size=9):
     # create a grid of 3x3 images
https://colab.research.google.com/drive/1nyrRY1EI95tMCrIJ6GHaGwUYdkZU2bnb#scrollTo=d6a39P839TIO&printMode=true
                                                                                                 3/20
```

```
for i in range(0, 9):
   plt.subplot(330 + 1 + i)
   plt.imshow(X_batch[i].astype(np.uint8))
# show the plot
plt.show()
break
```



Define: Dense Block , Transition Block , Output Block.

```
# Dense Block
def denseblock(input, num filter = 12, dropout rate = 0.2):
   global compression
   temp = input
   for in range(1):
        BatchNorm = layers.BatchNormalization()(temp)
       relu = layers.Activation('relu')(BatchNorm)
        Conv2D_3_3 = layers.Conv2D(int(num_filter*compression), (3,3), use_bias=False ,paddin
        if dropout rate>0:
            Conv2D_3_3 = layers.Dropout(dropout_rate)(Conv2D_3_3)
        concat = layers.Concatenate(axis=-1)([temp,Conv2D_3_3])
        temp = concat
   return temp
## transition Blosck
def transition(input, num_filter = 12, dropout_rate = 0.2):
   global compression
   BatchNorm = layers.BatchNormalization()(input)
   relu = layers.Activation('relu')(BatchNorm)
   Conv2D BottleNeck = layers.Conv2D(int(num filter*compression), (1,1), use bias=False ,pad
   if dropout rate>0:
        Conv2D BottleNeck = layers.Dropout(dropout rate)(Conv2D BottleNeck)
```

```
Cnn On cifar Dataset.ipynb - Colaboratory
   avg = layers.AveragePooling2D(pool size=(2,2))(Conv2D BottleNeck)
   return avg
#output layer
def output_layer(input):
   global compression
   BatchNorm = layers.BatchNormalization()(input)
   relu = layers.Activation('relu')(BatchNorm)
   cv = layers.Conv2D(14, (1,1), use bias=False ,padding='same')(relu)
   AvgPooling = layers.AveragePooling2D(pool size=(2,2))(cv)
   flat = layers.Flatten()(AvgPooling)
   output = layers.Dense(num classes, activation='softmax')(flat)
   return output
 Define Model with some paramter.
```

```
- num filter = 64
```

$$-1 = 6$$

- Dropout rate = 0

- Batch size = 128

```
num filter = 64
dropout rate = 0
1 = 6
input = layers.Input(shape=(img height, img width, channel,))
First Conv2D = layers.Conv2D(num filter, (3,3), use bias=False ,padding='same')(input)
First Block = denseblock(First Conv2D, num filter, dropout rate)
First Transition = transition(First Block, num filter, dropout rate)
Second Block = denseblock(First Transition, num filter, dropout rate)
Second Transition = transition(Second Block, num filter, dropout rate)
Third Block = denseblock(Second Transition, num filter, dropout rate)
Third Transition = transition(Third Block, num filter, dropout rate)
Last Block = denseblock(Third Transition, num filter, dropout rate)
output = output layer(Last Block)
#https://arxiv.org/pdf/1608.06993.pdf
from IPython.display import IFrame, YouTubeVideo
YouTubeVideo(id='-W6y8xnd--U', width=600)
```

Densely Connected Convolutional Networks



▼ Here's the complete architecture of your model:

model = Model(inputs=[input], outputs=[output])
model.summary()

activation_2 (Activation)	(None,	32,	32,	128)	0	batch_normalization_ /
conv2d_3 (Conv2D)	(None,	32,	32,	32)	36864	activation_2[0][0]
concatenate_2 (Concatenate)	(None,	32,	32,	160)	0	concatenate_1[0][0] conv2d_3[0][0]
batch_normalization_3 (BatchNor	(None,	32,	32,	160)	640	concatenate_2[0][0]
activation_3 (Activation)	(None,	32,	32,	160)	0	batch_normalization_
conv2d_4 (Conv2D)	(None,	32,	32,	32)	46080	activation_3[0][0]
concatenate_3 (Concatenate)	(None,	32,	32,	192)	0	concatenate_2[0][0] conv2d_4[0][0]
batch_normalization_4 (BatchNor	(None,	32,	32,	192)	768	concatenate_3[0][0]
activation_4 (Activation)	(None,	32,	32,	192)	0	batch_normalization_4
conv2d_5 (Conv2D)	(None,	32,	32,	32)	55296	activation_4[0][0]
concatenate_4 (Concatenate)	(None,	32,	32,	224)	0	concatenate_3[0][0] conv2d_5[0][0]
batch_normalization_5 (BatchNor	(None,	32,	32,	224)	896	concatenate_4[0][0]
activation_5 (Activation)	(None,	32,	32,	224)	0	batch_normalization_
conv2d_6 (Conv2D)	(None,	32,	32,	32)	64512	activation_5[0][0]
concatenate_5 (Concatenate)	(None,	32,	32,	256)	0	concatenate_4[0][0] conv2d 6[0][0]

						~~~_~[~][~]
batch_normalization_6 (BatchNor	(None,	32,	32,	256)	1024	concatenate_5[0][0]
activation_6 (Activation)	(None,	32,	32,	256)	0	batch_normalization_
conv2d_7 (Conv2D)	(None,	32,	32,	32)	8192	activation_6[0][0]
average_pooling2d (AveragePooli	(None,	16,	16,	32)	0	conv2d_7[0][0]
batch_normalization_7 (BatchNor	(None,	16,	16,	32)	128	average_pooling2d[0]
activation_7 (Activation)	(None,	16,	16,	32)	0	batch_normalization_
conv2d_8 (Conv2D)	(None,	16,	16,	32)	9216	activation_7[0][0]
concatenate_6 (Concatenate)	(None,	16,	16,	64)	0	average_pooling2d[0] conv2d_8[0][0]
batch_normalization_8 (BatchNor	(None,	16,	16,	64)	256	concatenate_6[0][0]
activation_8 (Activation)	(None,	16,	16,	64)	0	batch_normalization_
conv2d_9 (Conv2D)	(None,	16,	16,	32)	18432	activation_8[0][0]
concatenate_7 (Concatenate)	(None,	16,	16,	96)	0	concatenate_6[0][0]
4						<b>•</b>

As we seen Total parameter is less than 1 millon which satisfy our assignment condition, So we can processed next operation.

```
print(f"Number of layers in model: {len(model.layers)}")
    Number of layers in model: 116

import warnings
warnings.filterwarnings("ignore")

import os
checkpoint_path = "/content/gdrive/MyDrive/cifar-10/cp1-{epoch:04d}.ckpt"
checkpoint_dir = os.path.dirname(checkpoint_path)

cp_callback = tf.keras.callbacks.ModelCheckpoint(
    checkpoint_path, verbose=1, save_weights_only=True)
```

### Compile the model

from tensorflow.keras.optimizers import SGD

```
# compile model
opt = SGD(lr=0.001, momentum=0.9)
model.compile(optimizer=opt, loss='categorical_crossentropy', metrics=['accuracy'])

steps_per_epoch = X_train.shape[0]//batch_size
steps_per_epoch
390
```

### Prepare Pixel Data

We know that the pixel values for each image in the dataset are unsigned integers in the range between no color and full color, or 0 and 255.

The prep_pixels() function below implement these behaviors and is provided with the pixel values for both the train and test datasets that will need to be scaled.

```
#https://machinelearningmastery.com/how-to-develop-a-cnn-from-scratch-for-cifar-10-photo-clas
# scale pixels

def prep_pixels(train, test):
    # convert from integers to floats
    train_norm = train.astype('float32')
    test_norm = test.astype('float32')
    # normalize to range 0-1
    train_norm = train_norm / 255.0
    test_norm = test_norm / 255.0
    # return normalized images
    return train_norm, test_norm

# prepare pixel data
X_train,X_test=prep_pixels(X_train,X_test)
```

#### train the model

```
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Epoch 17/30
390/390 [============= ] - 116s 298ms/step - loss: 0.6763 - accuracy:
Epoch 00017: saving model to /content/gdrive/MyDrive/cifar-10/cp1-0017.ckpt
Epoch 18/30
390/390 [================ ] - 116s 298ms/step - loss: 0.6629 - accuracy:
Epoch 00018: saving model to /content/gdrive/MyDrive/cifar-10/cp1-0018.ckpt
Epoch 19/30
390/390 [=============== ] - 116s 298ms/step - loss: 0.6492 - accuracy:
Epoch 00019: saving model to /content/gdrive/MyDrive/cifar-10/cp1-0019.ckpt
Epoch 20/30
390/390 [================ ] - 116s 298ms/step - loss: 0.6287 - accuracy:
Epoch 00020: saving model to /content/gdrive/MyDrive/cifar-10/cp1-0020.ckpt
Epoch 21/30
Epoch 00021: saving model to /content/gdrive/MyDrive/cifar-10/cp1-0021.ckpt
Epoch 22/30
390/390 [=============== ] - 117s 299ms/step - loss: 0.5999 - accuracy:
Epoch 00022: saving model to /content/gdrive/MyDrive/cifar-10/cp1-0022.ckpt
Epoch 23/30
390/390 [================= ] - 117s 298ms/step - loss: 0.5858 - accuracy:
Epoch 00023: saving model to /content/gdrive/MyDrive/cifar-10/cp1-0023.ckpt
Epoch 24/30
390/390 [================ ] - 116s 298ms/step - loss: 0.5761 - accuracy:
Epoch 00024: saving model to /content/gdrive/MyDrive/cifar-10/cp1-0024.ckpt
Epoch 25/30
Epoch 00025: saving model to /content/gdrive/MyDrive/cifar-10/cp1-0025.ckpt
Epoch 26/30
390/390 [================= ] - 116s 298ms/step - loss: 0.5527 - accuracy:
Epoch 00026: saving model to /content/gdrive/MyDrive/cifar-10/cp1-0026.ckpt
Epoch 27/30
390/390 [================= ] - 116s 298ms/step - loss: 0.5379 - accuracy:
Epoch 00027: saving model to /content/gdrive/MyDrive/cifar-10/cp1-0027.ckpt
Epoch 28/30
Epoch 00028: saving model to /content/gdrive/MyDrive/cifar-10/cp1-0028.ckpt
Epoch 29/30
Epoch 00029: saving model to /content/gdrive/MyDrive/cifar-10/cp1-0029.ckpt
Epoch 30/30
בחב / בחב
```

As we seen above we get that we don't Get Good accuracy with This Parameter. Now instead of using sgd we used Adam compiler with same parameter let's see what Adam compiler beacuse Adam is the best optimizers. If one wants to train the new

verbose = 1,validation_steps = X_test.shape[0]//batch_size, validation_data=(X_test, y_test),callbacks=[cp_callback])

```
Epoch 00006: saving model to /content/gdrive/My Drive/densenet training/cp1-30-0006.c
Epoch 7/20
Epoch 00007: saving model to /content/gdrive/My Drive/densenet training/cp1-30-0007.c
Epoch 8/20
390/390 [=============== ] - 116s 296ms/step - loss: 0.4645 - accuracy:
Epoch 00008: saving model to /content/gdrive/My Drive/densenet training/cp1-30-0008.c
Epoch 9/20
390/390 [================= ] - 115s 295ms/step - loss: 0.4395 - accuracy:
Epoch 00009: saving model to /content/gdrive/My Drive/densenet training/cp1-30-0009.c
Epoch 10/20
Epoch 00010: saving model to /content/gdrive/My Drive/densenet training/cp1-30-0010.c
Epoch 11/20
Epoch 00011: saving model to /content/gdrive/My Drive/densenet training/cp1-30-0011.c
Epoch 12/20
390/390 [================ ] - 115s 296ms/step - loss: 0.3844 - accuracy:
Epoch 00012: saving model to /content/gdrive/My Drive/densenet_training/cp1-30-0012.c
Epoch 13/20
390/390 [================= ] - 115s 296ms/step - loss: 0.3708 - accuracy:
Epoch 00013: saving model to /content/gdrive/My Drive/densenet training/cp1-30-0013.c
Epoch 14/20
Epoch 00014: saving model to /content/gdrive/My Drive/densenet training/cp1-30-0014.c
Epoch 15/20
Epoch 00015: saving model to /content/gdrive/My Drive/densenet training/cp1-30-0015.c
Epoch 16/20
390/390 [=================== ] - 115s 295ms/step - loss: 0.3395 - accuracy:
Epoch 00016: saving model to /content/gdrive/My Drive/densenet_training/cp1-30-0016.c
Epoch 17/20
390/390 [================= ] - 115s 295ms/step - loss: 0.3293 - accuracy:
Epoch 00017: saving model to /content/gdrive/My Drive/densenet training/cp1-30-0017.c
Epoch 18/20
Epoch 00018: saving model to /content/gdrive/My Drive/densenet training/cp1-30-0018.c
Epoch 19/20
```

Adam Give slightly Good output As compare to Sgd but we can't our expected outp

```
#checkpoints after 50th epoch
import os
checkpoint path = "/content/gdrive/My Drive/densenet training/cp1-50-{epoch:04d}.ckpt"
checkpoint dir = os.path.dirname(checkpoint path)
cp_callback = tf.keras.callbacks.ModelCheckpoint(
   checkpoint_path, verbose=1, save_weights_only=True)
# determine Loss function and Optimizer
model.compile(loss='categorical crossentropy',
             optimizer=Adam(),
             metrics=['accuracy'])
#https://machinelearningmastery.com/check-point-deep-learning-models-keras/
from keras.callbacks import ModelCheckpoint
history = model.fit_generator(datagen.flow(X_train, y_train, batch_size=batch_size),steps_per_
   epochs=20,
   verbose = 1, validation steps = X test.shape[0]//batch size,
   validation_data=(X_test, y_test), callbacks=[cp_callback])
    Epoch 1/20
    390/390 [============= ] - 153s 301ms/step - loss: 0.2897 - accuracy:
    Epoch 00001: saving model to /content/gdrive/My Drive/densenet_training/cp1-50-0001.c
    Epoch 2/20
    390/390 [================= ] - 113s 289ms/step - loss: 0.2866 - accuracy:
    Epoch 00002: saving model to /content/gdrive/My Drive/densenet_training/cp1-50-0002.c
    Epoch 3/20
    390/390 [=============== ] - 113s 289ms/step - loss: 0.2787 - accuracy:
    Epoch 00003: saving model to /content/gdrive/My Drive/densenet training/cp1-50-0003.c
```

```
Epoch 4/20
390/390 [============ ] - 113s 289ms/step - loss: 0.2761 - accuracy:
Epoch 00004: saving model to /content/gdrive/My Drive/densenet training/cp1-50-0004.c
Epoch 5/20
Epoch 00005: saving model to /content/gdrive/My Drive/densenet_training/cp1-50-0005.c
Epoch 6/20
390/390 [================= ] - 113s 289ms/step - loss: 0.2617 - accuracy:
Epoch 00006: saving model to /content/gdrive/My Drive/densenet_training/cp1-50-0006.c
Epoch 7/20
Epoch 00007: saving model to /content/gdrive/My Drive/densenet training/cp1-50-0007.c
Epoch 8/20
Epoch 00008: saving model to /content/gdrive/My Drive/densenet training/cp1-50-0008.c
Epoch 9/20
390/390 [================ ] - 113s 289ms/step - loss: 0.2387 - accuracy:
Epoch 00009: saving model to /content/gdrive/My Drive/densenet_training/cp1-50-0009.c
Epoch 10/20
390/390 [================ ] - 113s 289ms/step - loss: 0.2349 - accuracy:
Epoch 00010: saving model to /content/gdrive/My Drive/densenet_training/cp1-50-0010.c
Epoch 11/20
390/390 [=============== ] - 113s 290ms/step - loss: 0.2310 - accuracy:
Epoch 00011: saving model to /content/gdrive/My Drive/densenet training/cp1-50-0011.c
Epoch 12/20
390/390 [================ ] - 113s 290ms/step - loss: 0.2265 - accuracy:
Epoch 00012: saving model to /content/gdrive/My Drive/densenet_training/cp1-50-0012.c
Epoch 13/20
390/390 [================= ] - 114s 291ms/step - loss: 0.2185 - accuracy:
Epoch 00013: saving model to /content/gdrive/My Drive/densenet_training/cp1-50-0013.c
Epoch 14/20
390/390 [================ ] - 113s 291ms/step - loss: 0.2143 - accuracy:
Epoch 00014: saving model to /content/gdrive/My Drive/densenet training/cp1-50-0014.c
Epoch 15/20
```

```
model.load_weights('/content/gdrive/My Drive/densenet_training/cp1-50-0020.ckpt')
```

<tensorflow.python.training.tracking.util.CheckpointLoadStatus at 0x7f99bf2cf090>

### NOT GET OUR EXPECTED RESULT, WE HAVE TO GO AGAIN.

```
#checkpoints after 70th epoch
import os
checkpoint_path = "/content/gdrive/My Drive/densenet_training/cp1-70-{epoch:04d}.ckpt"
checkpoint dir = os.path.dirname(checkpoint path)
cp callback = tf.keras.callbacks.ModelCheckpoint(
   checkpoint path, verbose=1, save weights only=True)
# determine Loss function and Optimizer
model.compile(loss='categorical crossentropy',
            optimizer=Adam(),
            metrics=['accuracy'])
#https://machinelearningmastery.com/check-point-deep-learning-models-keras/
from keras.callbacks import ModelCheckpoint
history = model.fit generator(datagen.flow(X train, y train, batch size=batch size), steps per
   epochs=20,
   verbose = 1,validation_steps = X_test.shape[0]//batch_size,
   validation_data=(X_test, y_test), callbacks=[cp_callback])
    Epoch 00006: saving model to /content/gdrive/My Drive/densenet_training/cp1-70-0006.c
    Epoch 7/20
    390/390 [============== ] - 113s 290ms/step - loss: 0.1681 - accuracy:
    Epoch 00007: saving model to /content/gdrive/My Drive/densenet training/cp1-70-0007.c
    Epoch 8/20
    390/390 [============== ] - 113s 289ms/step - loss: 0.1637 - accuracy:
    Epoch 00008: saving model to /content/gdrive/My Drive/densenet_training/cp1-70-0008.c
    Epoch 9/20
    390/390 [================ ] - 113s 290ms/step - loss: 0.1643 - accuracy:
    Epoch 00009: saving model to /content/gdrive/My Drive/densenet_training/cp1-70-0009.c
    Epoch 10/20
    390/390 [================ ] - 113s 291ms/step - loss: 0.1637 - accuracy:
    Epoch 00010: saving model to /content/gdrive/My Drive/densenet training/cp1-70-0010.c
    Epoch 11/20
    390/390 [================ ] - 113s 290ms/step - loss: 0.1546 - accuracy:
    Epoch 00011: saving model to /content/gdrive/My Drive/densenet training/cp1-70-0011.c
    Epoch 12/20
    Epoch 00012: saving model to /content/gdrive/My Drive/densenet_training/cp1-70-0012.c
    Epoch 13/20
    390/390 [============ ] - 113s 290ms/step - loss: 0.1547 - accuracy:
```

```
Epoch 00013: saving model to /content/gdrive/My Drive/densenet training/cp1-70-0013.c
   Epoch 14/20
   Epoch 00014: saving model to /content/gdrive/My Drive/densenet training/cp1-70-0014.c
   Epoch 15/20
   Epoch 00015: saving model to /content/gdrive/My Drive/densenet_training/cp1-70-0015.c
   Epoch 16/20
   390/390 [================ ] - 113s 289ms/step - loss: 0.1461 - accuracy:
   Epoch 00016: saving model to /content/gdrive/My Drive/densenet training/cp1-70-0016.c
   Epoch 17/20
   390/390 [================ ] - 113s 289ms/step - loss: 0.1460 - accuracy:
   Epoch 00017: saving model to /content/gdrive/My Drive/densenet training/cp1-70-0017.c
   Epoch 18/20
   Epoch 00018: saving model to /content/gdrive/My Drive/densenet_training/cp1-70-0018.c
   Epoch 19/20
   390/390 [============== ] - 113s 289ms/step - loss: 0.1398 - accuracy:
   Epoch 00019: saving model to /content/gdrive/My Drive/densenet_training/cp1-70-0019.c
   Epoch 20/20
   390/390 [=============== ] - 113s 290ms/step - loss: 0.1358 - accuracy:
   Fnoch 00000 saving model to /content/gdrive/My Drive/densenet training/cn1-70-0000 c
model.load_weights('/content/gdrive/My Drive/densenet_training/cp1-70-0014.ckpt')
   <tensorflow.python.training.tracking.util.CheckpointLoadStatus at 0x7f99bfe676d0>
# Test the model
score = model.evaluate(X test, y test, verbose=1)
print('Test loss:', score[0])
print('Test accuracy:', score[1])
   Test loss: 0.3428269028663635
   Test accuracy: 0.8999999761581421
```

Here we get our output at 84 epoch. We Run it again and see it give even good result .

model.load weights('/content/gdrive/My Drive/densenet training/cp1-70-0020.ckpt')

<tensorflow.python.training.tracking.util.CheckpointLoadStatus at 0x7f99bfe0c750>

```
#checkpoints after 90 epoch
import os
checkpoint path = "/content/gdrive/My Drive/densenet training/cp1-90-{epoch:04d}.ckpt"
checkpoint dir = os.path.dirname(checkpoint path)
cp callback = tf.keras.callbacks.ModelCheckpoint(
   checkpoint path, verbose=1, save weights only=True)
# determine Loss function and Optimizer
model.compile(loss='categorical_crossentropy',
            optimizer=Adam(),
            metrics=['accuracy'])
#https://machinelearningmastery.com/check-point-deep-learning-models-keras/
from keras.callbacks import ModelCheckpoint
history = model.fit generator(datagen.flow(X train, y train, batch size=batch size), steps per
   epochs=20,
   verbose = 1,validation_steps = X_test.shape[0]//batch_size,
   validation_data=(X_test, y_test), callbacks=[cp_callback])
    Epoch 00006: saving model to /content/gdrive/My Drive/densenet_training/cp1-90-0006.c
    Epoch 7/20
    390/390 [=============== ] - 116s 297ms/step - loss: 0.1239 - accuracy:
    Epoch 00007: saving model to /content/gdrive/My Drive/densenet_training/cp1-90-0007.c
    Epoch 8/20
    390/390 [=============== ] - 112s 287ms/step - loss: 0.1227 - accuracy:
    Epoch 00008: saving model to /content/gdrive/My Drive/densenet training/cp1-90-0008.c
    Epoch 9/20
    390/390 [============= ] - 113s 288ms/step - loss: 0.1242 - accuracy:
    Epoch 00009: saving model to /content/gdrive/My Drive/densenet_training/cp1-90-0009.c
    Epoch 10/20
    390/390 [============ ] - 113s 288ms/step - loss: 0.1185 - accuracy:
    Epoch 00010: saving model to /content/gdrive/My Drive/densenet_training/cp1-90-0010.c
    Epoch 11/20
    390/390 [================ ] - 113s 289ms/step - loss: 0.1182 - accuracy:
    Epoch 00011: saving model to /content/gdrive/My Drive/densenet training/cp1-90-0011.c
    Epoch 12/20
    390/390 [================ ] - 113s 288ms/step - loss: 0.1167 - accuracy:
    Epoch 00012: saving model to /content/gdrive/My Drive/densenet_training/cp1-90-0012.c
```

```
Epoch 13/20
    390/390 [================ ] - 113s 289ms/step - loss: 0.1132 - accuracy:
    Epoch 00013: saving model to /content/gdrive/My Drive/densenet_training/cp1-90-0013.c
    Epoch 14/20
    390/390 [================ ] - 113s 289ms/step - loss: 0.1140 - accuracy:
    Epoch 00014: saving model to /content/gdrive/My Drive/densenet training/cp1-90-0014.c
    Epoch 15/20
    Epoch 00015: saving model to /content/gdrive/My Drive/densenet training/cp1-90-0015.c
    Epoch 16/20
    390/390 [============= ] - 113s 289ms/step - loss: 0.1138 - accuracy:
    Epoch 00016: saving model to /content/gdrive/My Drive/densenet_training/cp1-90-0016.c
    Epoch 17/20
    390/390 [================ ] - 113s 289ms/step - loss: 0.1103 - accuracy:
    Epoch 00017: saving model to /content/gdrive/My Drive/densenet_training/cp1-90-0017.c
    Epoch 18/20
    Epoch 00018: saving model to /content/gdrive/My Drive/densenet training/cp1-90-0018.c
    Epoch 19/20
    Epoch 00019: saving model to /content/gdrive/My Drive/densenet training/cp1-90-0019.c
    Epoch 20/20
    390/390 [=============== ] - 113s 289ms/step - loss: 0.1081 - accuracy:
model.load_weights('/content/gdrive/My Drive/densenet_training/cp1-90-0011.ckpt')
    <tensorflow.python.training.tracking.util.CheckpointLoadStatus at 0x7f99c1400bd0>
# Test the model
score = model.evaluate(X_test, y_test, verbose=1)
print('Test loss:', score[0])
print('Test accuracy:', score[1])
   Test loss: 0.36804988980293274
   Test accuracy: 0.9017000198364258
   4
model.load weights('/content/gdrive/My Drive/densenet training/cp1-90-0020.ckpt')
```

Now instead of Adam we used Sgd and see how it give result.

<tensorflow.python.training.tracking.util.CheckpointLoadStatus at 0x7f59f3d5db10>

```
#checkpoints after 90 epoch
import os
checkpoint path = "/content/gdrive/My Drive/densenet training/cp1-110-{epoch:04d}.ckpt"
checkpoint dir = os.path.dirname(checkpoint path)
cp callback = tf.keras.callbacks.ModelCheckpoint(
   checkpoint path, verbose=1, save weights only=True)
# determine Loss function and Optimizer
from tensorflow.keras.optimizers import SGD
model.compile(loss='categorical_crossentropy',
            optimizer=SGD(lr=0.1, decay=1e-4, momentum=0.9, nesterov=True),
            metrics=['accuracy'])
#https://machinelearningmastery.com/check-point-deep-learning-models-keras/
from keras.callbacks import ModelCheckpoint
history = model.fit generator(datagen.flow(X train, y train, batch size=batch size), steps per
   epochs=20,
   verbose = 1,validation_steps = X_test.shape[0]//batch_size,
   validation_data=(X_test, y_test), callbacks=[cp_callback])
    390/390 [============= - - 113s 290ms/step - loss: 0.0814 - accuracy: •
    Epoch 00003: saving model to /content/gdrive/My Drive/densenet training/cp1-110-0003.
    Epoch 4/20
    390/390 [=============== ] - 113s 289ms/step - loss: 0.0757 - accuracy:
    Epoch 00004: saving model to /content/gdrive/My Drive/densenet_training/cp1-110-0004.
    Epoch 5/20
    Epoch 00005: saving model to /content/gdrive/My Drive/densenet training/cp1-110-0005.
    Epoch 6/20
    390/390 [================ ] - 113s 289ms/step - loss: 0.0684 - accuracy:
    Epoch 00006: saving model to /content/gdrive/My Drive/densenet_training/cp1-110-0006.
    Epoch 7/20
    390/390 [================ ] - 113s 289ms/step - loss: 0.0688 - accuracy:
    Epoch 00007: saving model to /content/gdrive/My Drive/densenet training/cp1-110-0007.
    Epoch 8/20
    Epoch 00008: saving model to /content/gdrive/My Drive/densenet training/cp1-110-0008.
    Epoch 9/20
    390/390 [================ ] - 113s 289ms/step - loss: 0.0681 - accuracy:
    Epoch 00009: saving model to /content/gdrive/My Drive/densenet_training/cp1-110-0009.
```

```
Epoch 00010: saving model to /content/gdrive/My Drive/densenet training/cp1-110-0010.
   Epoch 11/20
   Epoch 00011: saving model to /content/gdrive/My Drive/densenet_training/cp1-110-0011.
   Epoch 12/20
   390/390 [================ ] - 113s 291ms/step - loss: 0.0649 - accuracy:
   Epoch 00012: saving model to /content/gdrive/My Drive/densenet_training/cp1-110-0012.
   Epoch 13/20
   390/390 [================ ] - 113s 291ms/step - loss: 0.0643 - accuracy:
   Epoch 00013: saving model to /content/gdrive/My Drive/densenet training/cp1-110-0013.
   Epoch 14/20
   Epoch 00014: saving model to /content/gdrive/My Drive/densenet training/cp1-110-0014.
   Epoch 15/20
   390/390 [=============== ] - 114s 291ms/step - loss: 0.0632 - accuracy:
   Epoch 00015: saving model to /content/gdrive/My Drive/densenet_training/cp1-110-0015.
   Epoch 16/20
   390/390 [=============== ] - 113s 290ms/step - loss: 0.0631 - accuracy:
   Epoch 00016: saving model to /content/gdrive/My Drive/densenet_training/cp1-110-0016.
   Epoch 17/20
   390/390 [=============== ] - 113s 291ms/step - loss: 0.0628 - accuracy:
# Test the model
score = model.evaluate(X test, y test, verbose=1)
print('Test loss:', score[0])
print('Test accuracy:', score[1])
   Test loss: 0.28252753615379333
   Test accuracy: 0.9244999885559082
```

we get our Best output at 110 epoch , which 92.45 accuracy.

```
# Save the trained weights in to .h5 format
model.save_weights("model_dense.h5")
print("Saved model to disk")

Saved model to disk
```

# Conclusion:

After using some image augmentation techniques like rotation,horizontal flipping, height and width shifting, as well as changing some hyperparameters, we were able to get a model with 92.45% test accuracy. Our deep learning model has less than 1 Million parameters, and we have reached the desired accuracy in less than 300 epochs.

# Refernce:

- <a href="https://colab.research.google.com/drive/1NGQjke72AS93IOpNcnE9diQEg78-su3C#scrollTo=c5Wksy8z5-rw">https://colab.research.google.com/drive/1NGQjke72AS93IOpNcnE9diQEg78-su3C#scrollTo=c5Wksy8z5-rw</a>.
- <a href="https://machinelearningmastery.com/how-to-develop-a-cnn-from-scratch-for-cifar-10-photo-classification/">https://machinelearningmastery.com/how-to-develop-a-cnn-from-scratch-for-cifar-10-photo-classification/</a>
- https://www.tensorflow.org/tutorials/images/cnn

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