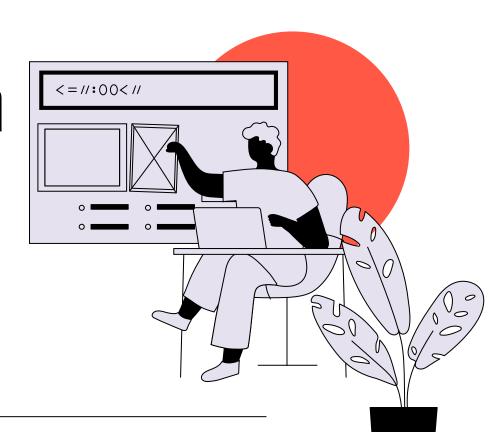
# Deep Semi-supervised learning (SSL)

On aerial datasets





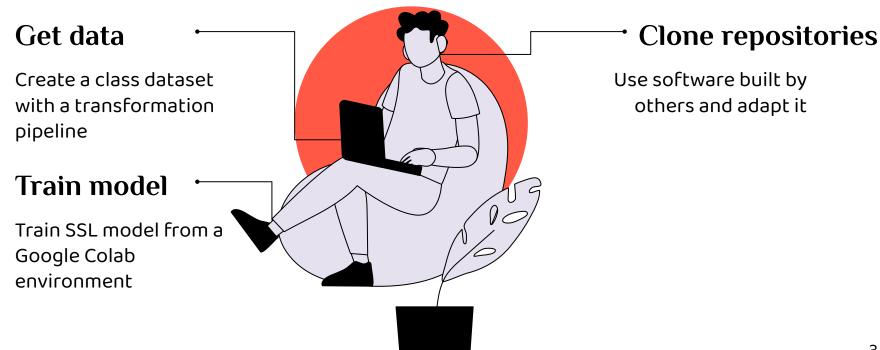
#### **About me**



- Itzá Hernández
- PhD. Computer Science Computer Vision
- University Jaume I, Castellón, Spain
- @itzahs 📊 💟 🗘



## Learning outcomes of this workshop



## Content of this workshop

Introduction to DSSL 14:00 - 14:20 (20 min)

Data & Code

Pause & Questions
14:50 - 15:00 (10 min)

**Training model** 15:00 - 15:30 (30 min)

Questions welcome anytime





# **U1**Introduction

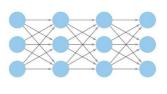
Deep Semi Supervised Learning 14:00 - 14:20



## Machine Learning & Deep Learning







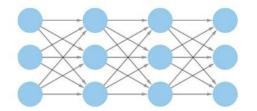


Feature extraction

Classification

Class probability







Feature extraction + Classification

Class probability

Supervised

Semi-supervised

Unsupervised

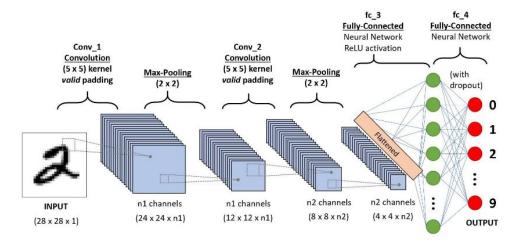


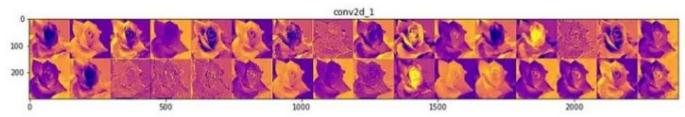


#### Convolutional Neural Network (CNN)



Original Image







### DL in Aerial Image Classification

**Pixel-level** 





**Object-level** 





Scene-level

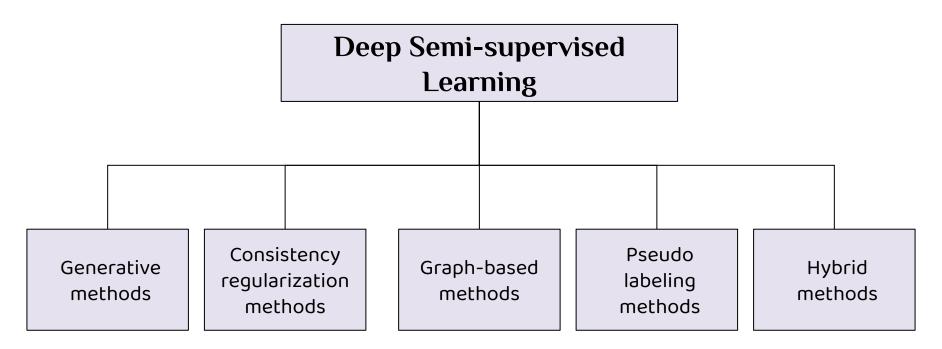








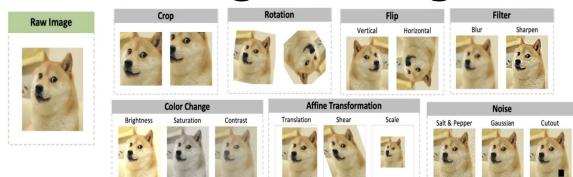
## **Taxonomy**







#### Image data augmentation for DL



 Data Warping: transforms existing images such as the label is preserved.



Synthetic data - CycleGANS - emotion classification

 Oversampling: creates synthetic instances and add them to the training set.

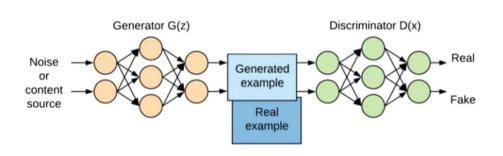
[4] Sharma, A. (2019, June 12). Complete Guide to Data Augmentation for Computer Vision. Towards Data Science. <a href="https://towardsdatascience.com/complete-guide-to-data-augmentation-for-computer-vision-1abe4063ad07">https://towardsdatascience.com/complete-guide-to-data-augmentation-for-computer-vision-1abe4063ad07</a>.

[5] Shorten, C., Khoshgoftaar, T.M. A survey on Image Data Augmentation for Deep Learning. J Big Data 6, 60 (2019). https://doi.org/10.1186/s40537-019-0197-0





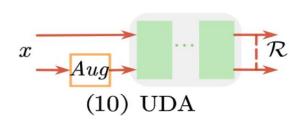
#### Generative methods



Generative modeling refers to the practice of **creating artificial instances** from a dataset such that they retain similar characteristics to the original dataset.

e.g. Generative Adversarial Networks (**GAN**) and Variational AutoEncoder (**VAE**).

#### Consistency regularization



= Basic Neural Network Layer Augmentation Operator.

RandAugment and Back-translation for UDA.

A consistency regularization term is applied to the **final loss function**. e.g. **Cross Entropy for example H(F(x), Tx).** 

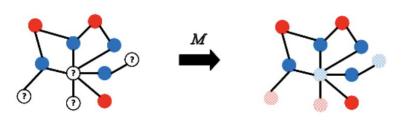
A realistic perturbation in the training data should not change the output of the model.

e.g. Unsupervised Data Augmentation (UDA).





#### **Graph-based**

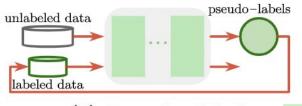


The nodes/vertices are **representations of the training samples** and the edges encode the relationships between the nodes.

The goal is to encode the nodes as small-scale vectors at first and then how each node belongs within the context in the graph.

Deep embedding methods are **AutoEncoders** and Graph Neural Networks (GNN).

# Pseudo-labelling



(3) Pseudo-label

= Basic Neural Network Layer

Pseudo-labeling methods rely on the **high-confidence of pseudo-labels**, which can be added to the training data set as labeled data.

Self-training: leverage model's own confident predictions to produce the pseudo-labels for **unlabeled data**.





#### Hybrid: Fixmatch - Consistency Regularization and Pseudo Labeling

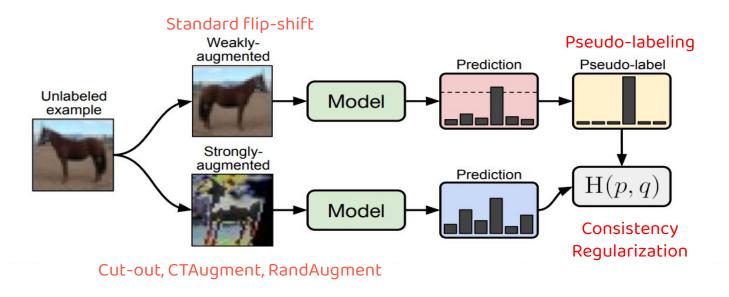


Figure 1: Diagram of FixMatch. A weakly-augmented image (top) is fed into the model to obtain predictions (red box). When the model assigns a probability to any class which is above a threshold (dotted line), the prediction is converted to a one-hot pseudo-label. Then, we compute the model's prediction for a strong augmentation of the same image (bottom). The model is trained to make its prediction on the strongly-augmented version match the pseudo-label via a cross-entropy loss.









# 02 Data & Code

Cloning the GitHub repositories and downloading the datasets 14:20 - 14:50





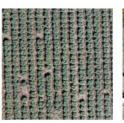
#### Dataset and sampling stategy

#### UCM Dataset [download]:

- 21 clases
- 100 images per class
- 256 x 256 pixels (0.3 m)

#### Sampling strategy:

- 50 % training and 50% testing (Cheng, G. et al, 2020) [2].
- When using supervised 1,050 samples
- When using semi-supervised 84 samples or 4 labels per class (Sohn, K. et al, 2020) [6].





airplane

















medium residential

mobile home park

overpass





## Semi-supervised learning toolbox

#### Class-Aware Contrastive Semi-Supervised Learning



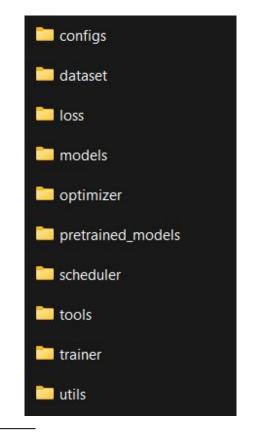




## Semi-supervised learning toolbox



https://github.com/TencentYoutuResearch/Classification-SemiCLS







#### Codes for this workshop







Colab 1: UCM download



Colab 2: Clone repository



#### Space requirements



Jupyter Notebook

https://github.com/itzahs/Geo PythonWorkshop2023 SSL

- Google Account with 5GB space on Drive available
- Optional: Google Drive Desktop and Visual Studio Code











# International Women's Day

# Pause & Questions

8th March - International Women's Day 14:50 - 15:00









# 04 Model training

Modify the configuration files and launch the training 15:00 - 15:30



```
train = dict(eval_step=1024,
             total steps=2**20, #1024*20,
             trainer=dict(type="FixMatch",
                          threshold=0.95,
                           T=1.,
                           lambda u=1.,
                           loss_x=dict(
                               type="cross_entropy",
                               reduction="mean"),
                           loss u=dict(
                               type="cross entropy",
                               reduction="none"),
num classes = 10 #21
```

- How often model performance is evaluated.
- 2. Overall duration of the training process.





```
model = dict(
     type="wideresnet",
     depth=28,
     widen factor=2,
     dropout=0,
     num classes=num classes,
cifar10_mean = (0.4914, 0.4822, 0.4465)
cifar10 std = (0.2471, 0.2435, 0.2616)
\#ucm\ mean = (0.485, 0.456, 0.406)
\#ucm std = (0.229, 0.224, 0.225)
```

WideResNet - Number of filters in the ResNet increased by a value of 2.

ImageNet mean and std of the pixel intensities for each color channel (RGB).





```
data = dict(
    # CIFAR10SSL, CIFAR100SSL
    type="CIFAR10SSL", #"MyDataset",
    num workers=4, #0,
    num_labeled=250, #84,
    num classes=num classes,
    batch size=64, #8,
    expand_labels=False,
    mu=7,
    root="./data/CIFAR",
    #root="./UCMerced LandUse/Images",
    #labeled names file="./UCMerced LandUse/Images/UCM train.txt",
    #test names file="./UCMerced LandUse/Images/UCM test.txt",
```

4 labeled examples per class.

Path to images





```
lpipelines=[[
    # 50% chances that the image is horizontally flipped
    dict(type="RandomHorizontalFlip"),
    # RandomCrop crops a fixed size whereas RandomResizedCrop crops and then resizes.
    dict(type="RandomCrop",
         size=32.
         padding=int(32 * 0.125),
         padding mode='reflect'),
    #dict(type="RandomResizedCrop", size=224, scale=(0.2, 1.0)),
    dict(type="ToTensor"),
    dict(type="Normalize", mean=cifar10_mean, std=cifar10_std)
    #dict(type="Normalize", mean=ucm mean, std=ucm std)
]],
```



```
upipelinse=[[
    dict(type="RandomHorizontalFlip"),
    dict(type="RandomCrop",
         size=32,
         padding=int(32 * 0.125),
         padding mode='reflect'),
    #dict(type="Resize", size=256),
    #dict(type="CenterCrop", size=224),
    dict(type="ToTensor"),
    dict(type="Normalize", mean=cifar10_mean, std=cifar10_std)
    ],
    dict(type="RandomHorizontalFlip"),
    dict(type="RandomCrop",
         size=32.
         padding=int(32 * 0.125),
         padding mode='reflect'),
    #dict(type="RandomResizedCrop", size=224, scale=(0.2, 1.0)),
    dict(type="RandAugmentMC", n=2, m=10),
    dict(type="ToTensor"),
    dict(type="Normalize", mean=cifar10_mean, std=cifar10_std)
    #dict(type="Normalize", mean=ucm mean, std=ucm std)
```

#### Augmentation strategy

- Weak:
  - Flip
  - **Crop**
- Strong1:
  - RandomAugment
  - CutOut
- Strong2:
  - Random Color Jittering
  - Grayscale Conversion

```
vpipeline=[
    #dict(type="Resize", size=256),
    dict(type="ToTensor"),
    dict(type="Normalize", mean=cifar10_mean, std=cifar10_std)
    #dict(type="Normalize", mean=ucm_mean, std=ucm_std)
])
```

Some UCM samples are have inconsistent spatial sizes, whiles most have a shape of 256\*256\*3 some are 253\*256\*3.



#### Modifications: dataset builder file

```
81     else:
82
83     # check if .ipynb_checkpoints is in root, and exclude it
84     root = os.path.join(cfg.root, '')
85     if os.path.isdir(os.path.join(root, ".ipynb_checkpoints")):
86         exclude_dir = os.path.join(root, ".ipynb_checkpoints")
87     else:
88         exclude_dir = None
```

Google colab creates temporary ipynb inside the image folders and the dataset class gives error when other than if extensions are found.



#### Modifications: training file

```
444
                       data_x = labeled_iter.next()
                       #data x = next(labeled iter)
446
                   except Exception:
                       if args.world size > 1:
448
                           labeled epoch += 1
449
                           labeled trainloader.sampler.set epoch(labeled epoch)
                       labeled iter = iter(labeled trainloader)
                       data_x = labeled_iter.next()
                       #data x = next(labeled iter)
453
                   try:
                       data u = unlabeled iter.next()
                       #data u = next(unlabeled iter)
457
                   except Exception:
                       if args.world size > 1:
                           unlabeled epoch += 1
460
                           unlabeled trainloader.sampler.set epoch(unlabeled epoch)
                       unlabeled iter = iter(unlabeled trainloader)
461
462
                       data u = unlabeled iter.next()
463
                       #data u = next(unlabeled iter)
```









# Thanks!

Do you have any questions?

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@itzahs





#### References

#### Bibliography:

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