```
Experiment No: 01
Experiment Name: UNIT
IMPULSE SIGNAL
t1=-1:0.001:1;
plot(t1,impluse);
xlabel('time-->');
ylabel('amplitude-->');
title('UNIT IMPULSE
SIGNAL');
axis([-1 1 0 1.5]);
SIGNAL');
%UNIT STEP SIGNAL
t2=-5:0.01:5;
step=[zeros(1,500),ones(1,5 t=-5:0.0; width=2;
width=2;
y=tripuls(t,width);
plot(t2,step); subplot(2,2,2);
xlabel('time-->'); plot(t,y);
ylabel('amplitude-->'); xlabel('time-->');
title('UNIT STEP SIGNAL'); ylabel('amplitude-->');
axis([-5 5 0 1.5]); title('CONTITUOUS TIME triangular c')
t3=0:0.01:6;
t3=0:0.01:6;
ramp=t3;
subplot(2,2,3);
plot(t3,ramp);
t3=0:0.01:6;
parabola=0.5*(t3.^2);
subplot(2,2,4);
plot(t3,parabola);
xlabel('time-->');
ylabel('amplitude-->');
title('UNIT PARABOIC
SIGNAL');
```

```
Experiment Name: Generation of elementary signals in
        continuous time
y=rectpuls(t,widtn);
subplot(2,2,1);
plot(t,y);
xlabel('time-->');
ylabel('amplitude-->');
title('CONTITUOUS TIME
RANTANGULAR SOGNAL');
axis(I-5 5 0 1.5));
       axis([-5 5 0 1.5]);
       %triangular signal t=-5:0.01:5;
      axis([-5 5 0 1.5]);
       %sinc signal
t=-5:0.01:5;
      width=2;
       ylabel('amplitude-->');
title('CONTITUOUS sinc
 titie(
signal');
       axis([-5 5 -0.5 1.5]);
        %signum signal
       t=-10:0.01:10;
        width=2;
         y=sign(t);
         subplot(2,2,4);
         plot(t,y);
         xlabel('time-->');
ylabel('amplitude-->');
         title('CONTITUOUS sinc
          signal');
```

axis([-5 5 -1.5 1.5]);

Experiment No: 02

```
Experiment No: 03
      Experiment Name: generation
      of continuous time
      sinusoidal & Gaussian
      signal
     t=-0.05:0.001:0.05;
    f=100;
r=100;
a=2;
yt=a*sin(2*pi*f*t);
subplot(2,1,1);
plot(t,yt);
xlabel('time-->');
ylabel('amplitude-->');
title('sinusoidal signal
');
    a=3;
  yt=exp(-a*t.^2);
subplot(2,1,2);
    plot(t,yt);
xlabel('time-->');
    ylabel('amplitude-->');
     title('gaussian signal ');
      Experiment No: 04
      Experiment Name:generation
     of continuous time
    sinusoidal signal of
      frequency 100Hz in time
      duration of 100 msec
      %with time shifting 5 sec
      t=-0.05:0.001:0.05;
       f=100;
       a=4;
       y1=a*cos(2*pi*f*t);
       y2=a*cos(2*pi*f*(t-0.005));
       subplot(2,1,1);
       plot(t,y1);
       xlabel('time-->');
      ylabel('amplitude-->');
```

title('sinusoidal signal

subplot(2,1,2);plot(t,y2);xlabel('time-->'); ylabel('amplitude-->'); title('time shifted sinusoidal signal ');

');

Experiment No: 05 Experiment No: 07 Experiment Name: generation Experiment Name: of unit step function using Multiplication of two signum(sign) function continuous-time signals clc; %u(t) = 0.5 sqn(t) + .5clear all; t=-10:0.01:10; clear all; step=0.5\*sign(t)+0.5;t=-5:0.001:5; subplot(3,1,1);f1=5; plot(t,step); x1=sinc(t).\*sin(2\*pi\*f1\*t);xlabel('time-->'); f2=1; ylabel('amplitude-->'); x2=3\*cos(2\*pi\*f2\*t).\*sin(2\*title('unit step signal pi\*f2\*(t+0.5)); u(t)'); subplot(2,1,1);axis([-10 10 0 1.2]); plot(t,x1); %y(t) = u(t-3)title('multiplication of y=0.5\*sign(t-3)+0.5;sinc and sine signals'); subplot(3,1,2); subplot(2,1,2);plot(t,y); plot(t,x2); xlabel('time-->'); xlabel('time'); ylabel('amplitude-->'); ylabel('amplitude'); title('shiftes unit step title('multiplication of cosine and phase shifted signal,u(t-3)'); axis([-10 10 0 1.2]); sine signals'); y(t) = u(t) - u(t-6)y=(0.5\*sign(t)+0.5)-Experiment No: 08 (0.5\*sign(t-6)+0.5);Experiment Name: shifting subplot(3,1,3);and scaling operation plot(t,y); xlabel('time-->'); %y1=sinc(t); ylabel('amplitude-->'); t=-10:0.001:10; title('shiftes unit step y1=sinc(t); signal, u(t)-u(t-6)'); subplot(2,2,1); axis([-10 10 0 1.2]); plot(t,y1); xlabel('time-->'); ylabel('amplitude-->'); Experiment No: 06 title('sinc signal'); Experiment Name: axis([-10 10 -0.5 1.5]); multiplication of two %y2=sinc(4\*t); continuous time signal. y2=sinc(4\*t);subplot(2,2,2);plot(t,y2);xlabel('time-->'); %x1(t) = 5exp(-at);ylabel('amplitude-->'); clc; t=0:0.001:5; title('compressed sinc a=1.2;signal'); axis([-10 10 -0.5 1.5]); x1=5\*exp(-a\*t);subplot(3,1,1); %y3=sinc(2t-5); y3=sinc(2\*[t-5]);plot(t,x1);title('First signal subplot(2,2,3);x1(t)'); plot(t,y3);%x2(t)=2sin(wt);xlabel('time-->'); ylabel('amplitude-->'); f=1;title('shifting sinc x2=2\*sin(2\*pi\*f\*t);signal'); subplot(3,1,2);axis([-10 10 -0.5 1.5]); plot(t, x2);title('Second signal %y4=sinc(0.5\*t); x2(t)'); y4 = sinc(0.5\*t);subplot(2,2,4);%Multiplication of x1(t) plot(t,y4);and x2(t)xlabel('time-->'); y=x1.\*x2;

ylabel('amplitude-->');
title('expanded sinc

axis([-10 10 -0.5 1.5]);

signal');

subplot(3,1,3);

signals y(t)');

xlabel('time--T');

ylabel('amplitude');

title ('Multiplication of

plot(t,y);

```
Experiment Name: Generation
 of elementary sequence in
 discrete time
 %unit impulse sequencen=-
 10:1:10;
 impulse=[zeros(1,10),ones(1
 ,1),zeros(1,10)];
 ubplot(2,2,1);
 stem(n,impulse);
 xlabel('Discrete time-->');
 ylabel('amplitude-->');
 title('unit impulse
 sequence');
 axis([-10 10 0 1.2]);
 %unit STEP sequence
 n=-10:1:10;
 step=[zeros(1,10),ones(1,11
 ) ];
 subplot(2,2,2);
stem(n, step);
 xlabel('Discrete time-->');
 ylabel('amplitude-->');
 title('unit STEP
 sequence');
 axis([-10 10 0 1.2]);
 %unit Ramp sequence
 n=0:1:10;
 ramp=n;
 subplot(2,2,3);
stem(n,ramp);
xlabel('Discrete time-->');
ylabel('amplitude-->');
 title('unit Ramp
 sequence');
 %unit parabolic sequence
 n=0:1:10;
 parabola=.5*(n.^2);
 subplot(2,2,4);
stem(n,parabola);
xlabel('Discrete time-->');
ylabel('amplitude-->');
 title('unit parabolic
 sequence');
```

Experiment No: 09

Experiment Name: generation Experiment Name: Experiment Name: Fourier multiplication of two of discrete time transform and Inverse expotential sequence for discrete time siganl Fourier transform of a various values of a given sequence clc; clear all; clc; clear all; %x1(n) = 6\*a\*n;n=0:0.1:5; n=-10:1:10; clc; clear all; close all; %for 0<a<1 a=2: syms t; a=0.89;x1=6\*(a.\*n); $x1=exp(-t^2);$  $x1=a.^n;$ subplot(3,1,1);disp('The input equation subplot(2,2,1);stem(n,x1);is') stem(n,x1);title('x1(n)');disp(x1) xlabel('Discrete time-->'); %x2(n) = 6\*cos(wn);X1=fourier(x1);ylabel('amplitude-->'); f=1.2;disp('The fourier transform title('x1(n)--for 0<a<1'); x2=2\*cos(2\*pi\*f\*n);of the input equation is') %for a>1 subplot(3,1,2); disp(X1) a=1.22;stem(n, x2);x11=ifourier(X1); $x2=a.^n;$ title('x2(n)'); disp('The Inverse Fourier subplot(2,2,2);%multiplication of two transform is') stem(n,x2);sequences disp(x11) xlabel('Discrete time-->'); y=x1.\*x2;ylabel('amplitude-->'); subplot(3,1,3);title('x2(n)--for a>1'); stem(n,y);xlabel('Time');
ylabel('Amplitude'); %for -1<a<0 Experiment No: 14 a=-.89;Experiment Name: Fourier  $x3=a.^n;$ title('y(n)'); transform of a rectangular subplot(2,2,3);pulse stem(n,x3);Experiment No: 12 xlabel('Discrete time-->'); Experiment Name: generate ylabel('amplitude-->'); clc; clear all; close all; of the following discretetitle('x3(n)--for -1 < a < 0'); syms t w time sequence for a<-1% input signal x(t) a=-1.1; x=2\*(heaviside(t+2)heaviside(t-2));  $x4=a.^n;$ subplot(2,2,4);% x=5;subplot(3,1,1);stem(n.x4): ezplot(x,[-2 2]);xlabel('Discrete time-->');  $axis([-2.5 \ 2.5 \ 0 \ 2.5]);$ ylabel('amplitude-->'); %x(n) = u(n+3) + 5u(n-% fourier transform title('x4(n)--for a<-1'); 15)+4u(n+10) X=int(x\*exp(-1i\*w\*t),t,clc; clear all; 5.5): X=simplify(X);disp('The n=-20:1:20; fourier transform of x(t)u=[zeros(1,20),ones(1,21)];is') u1=[zeros(1,17),ones(1,24)] disp(X) subplot(3,1,2);u2=[zeros(1,35),ones(1,6)];ezplot(X); u2=5\*u2;%magnitude response u3=[zeros(1,10),ones(1,31)]  $Xm = sqrt((real(X).^2) + (imag($ ;u3=4\*u3;  $X).^2)$ x=u1+u2+u3;subplot(3,1,3);subplot(4,1,1);ezplot(Xm); stem(n,u1);title('u(n+3)'); subplot(4,1,2);stem(n,u2);title('5u(n-15)'); subplot(4,1,3);stem(n,u3);title('4u(n+10)'); subplot(4,1,4);stem(n,x);

title('x(n)');

Experiment No: 11

Experiment No: 13

Experiment No: 10

Experiment No: 17 Experiment No: 19 Experiment Name: Fourier Experiment Name: Time Experiment Name: Modulation scaling property of Fourier transform of a signal property of Fourier transform for rectangular transform signal clc; close all; clear all; svms t. w clc; clear all; close all; clc; clear all; close all; x1=exp(-abs(t));syms t w syms t w % input signal x(t) x2 = cos(10\*t);x1=heaviside(t+1)-heaviside(t-1); x=exp(-2\*t).\*heaviside(t);y=x1\*x2;subplot(2,1,1);subplot(3,1,1);x2=heaviside(t+5)ezplot(y); ezplot(x); heaviside(t-5); X1=fourier(x1) title('input signal') axis tight; Y=fourier(y) %fourier transform %fourier transform disp('The fourier transform subplot(2,1,1); of x(t) is') ezplot( $x_1$ , [-10 1] Yp=atan((imag(Y))/(real(Y))subplot(2,1,1,, ezplot(x1,[-10 10]); )
subplot(2,1,2);
ezplot(abs(Y),[-25 25]); X=fourier(x) title('rectangular X=simplify(X);signal'); title('FT Magnitude'); % Fourier response subplot(2,1,2); axis([-20 20 -0.2 1.2]); subplot(3,1,2); ezplot(x2,[-10 10]); ezplot(abs(X)); title('time scaled title('Magnitude response rectangular signal'); Experiment No: 20
Experiment Name: Generation of Fourier transform') figure; subplot(3,1,3); subplot(2,1,1); ezplot(atan((imag(X))/(real ezplot(X1,[-10 10]); of the Laplace transform of (X)))) signals title('fourier transform of title('phase response of the rectangular signal'); Fourier transform') axis tight; subplot(2,1,2); ezplot(X1,[-10 10]); ezplot(X1,[-10 10]); clc; clear all; close all; title('fourier transform of syms t a w the scaled rectangular Experiment No: 16 % laplace transform of signal'); Experiment Name: Time x1(t) = texp(-at)scaling property of Fourier axis tight; disp('the input signal transform for sinc signal OUTPUT x1(t) is') x1=t\*exp(-a\*t)disp('laplace transform of clc; clear all; close all; x1(t) is') syms t w X1=laplace(x1) Experiment No: 18 a=input('Input scaling % laplace transform of Experiment Name: Time factor') x2(t) = cos(wt)shifting property of the x=sinc(2\*pi\*0.1\*t); disp('the input signal Fourier transform X=fourier(x); x2(t) is') x2=cos(w\*t) X=simplify(X);x1=sinc(2\*pi\*a\*0.1\*t);disp('laplace transform of X1=fourier(x1); x2(t) is') X1=simplify(X1);X2=laplace(x2) % Calculation: No figure; % laplace transform of modification on Magnitude subplot(2,1,1);x3(t) = exp(-5t)ezplot(x,[-20,20]); spectra clc; clear all; close all; T=input('Enter time delay') syms t disp('the input signal title('without scaling'); x3(t) is') axis tight; x3=exp(-5\*t)ezplot(x1,[-20,20]); subplot(2,1,2);disp('laplace transform of y=sin(.2\*pi\*t)/(.2\*pi\*t);x3(t) is') X3=laplace(x3) [OUTPUT below] tight; subplot(2,1,1); figure; ezplot(y,[-100 100]); subplot(2,1,1); axis tight; ezplot(X,[-20,20]); subplot(2,1,2);title('Fourier transformed ezplot(y1,[-100 100]); without scaling'); axis axis tight; tight; Y=fourier(y); subplot(2,1,2);Y1=fourier(y1); ezplot(X1,[-20,20]); figure; title('Fourier transformed subplot(2,1,1);with scaling'); axis tight; ezplot(simplify(abs(Y)),[-OUTPUT 10 10]); axis tight;

title('FT of sinc signal')

ezplot(simplify(abs(Y1)),[-

title('FT of time shifted

subplot(2,1,2);

sinc signal')

10 10]);

Experiment No: 15

Experiment No: 21 Experiment Name: Finding the Laplace transform of signals

clc; clear all; close all; syms t % input signals x=exp(-t);y=x\*cos(10\*t);% ploting of signals subplot(2,1,1); ezplot(x,[0,5]);axis([0 5 0 1.1]); title('x(t)'); subplot(2,1,2);ezplot(y,[-1,5]); axis([0 5 -1.1 1.1]); title('y(t)'); % displaying the Laplace transform disp('laplace transformof x(t) is') X=laplace(x) y(t) is') Y=laplace(y) %frequency response Xm=abs(X);figure; subplot(2,1,1);ezplot(Xm); title('mag response of X(S)'); Ym=abs(Y);subplot(2,1,2);ezplot(Ym); title('mag response of Y(S)'); [OUTPUT FIGURE]

Experiment No: 22 Experiment Name: Generation of partial fraction expansion in Laplace transform

clc; clear all; close all; num=input('enter the numerator coefficients'); den=input('enter the denominator coefficients'); [r,p,k]=residue(num,den); disp('residue in the partial fraction are') disp(r) disp('poles of the system are') disp(p)

Experiment No: 23 Experiment Name: Time shifting property of Laplace transform

clc; clear all; close all; syms t real % laplace transform of the input disp('input signal');  $x1=(t^2).*heaviside(t)$ % laplace transform of the input signal X1=laplace(x1); disp('laplace transform of the input signal');
X1=simplify(X1) % delayed input signal disp('delayed input signal');  $x2=((t-2)^2).*heaviside(t-$ 2) % laplace transform of the delayed input signal disp('laplace transform of the delayed input signal'); X2=simplify(X2)

Experiment Name: Experiment No: 24 Convolution property of Laplace transform

clc; clear all; close all; syms t x1=exp(-2\*t);x2=heaviside(t);disp('laplace transform of x1(t) is') X1=laplace(x1);X1=simplify(X1) disp('laplace transform of
x2(t) is') X2=laplace(x2);X2=simplify(X2) % convolution using Laplace transform Y=X1.\*X2;disp('convolution of two signals is') y=ilaplace(Y) % plotting the convolution ezplot(y)