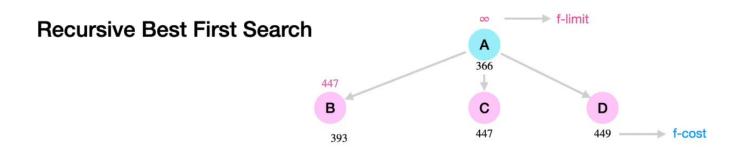
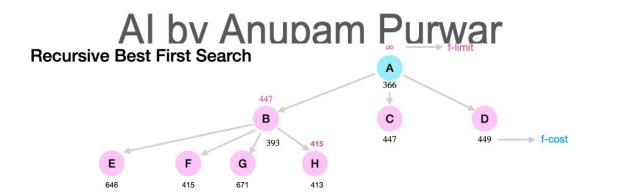
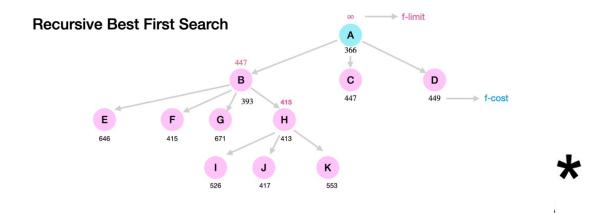
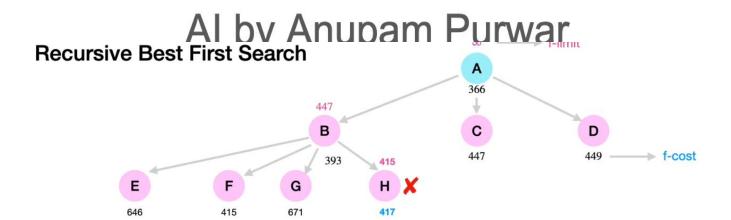
IDA* and RBS-A*

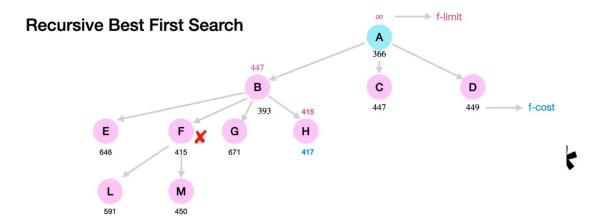
Al by Anupam Purwar



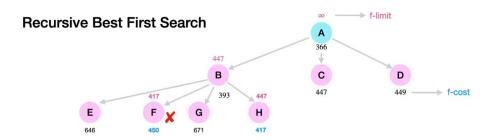


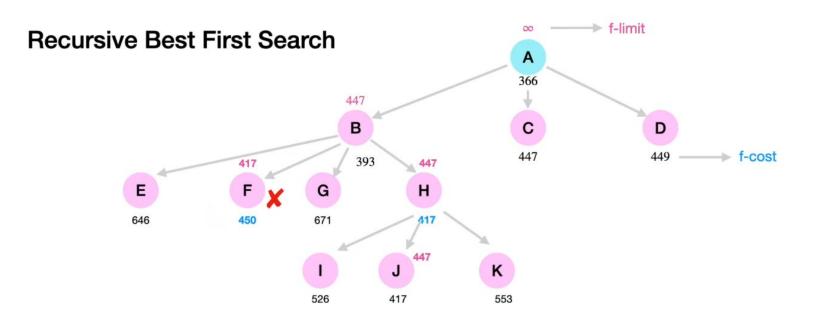


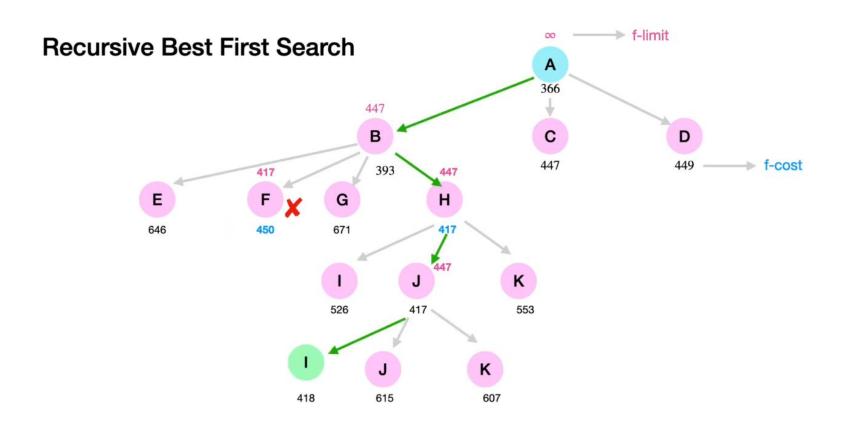




Al by Anupam Purwar







Time and space complexity of algorithms: IDA*, RBFS, BFS, DFS

 IDA* (Iterative Deepening A*) Recursive Best-First Search (RBFS) Breadth-First Search (BFS) Depth-First Search (DFS) 				
Algorithm	Time Complexity	Space Complexity	Complete	Optimal
IDA*	$O(b^d)$	O(d)	Yes	Yes (with admissible heuristic)
Recursive Best-First Search (RBFS)	$O(b^d)$ (can be more in practice)	O(bd)	Yes (with admissible heuristic)	Yes (with admissible heuristic)
Breadth-First Search (BFS)	$O(b^d)$	$O(b^d)$	Yes	Yes (if all step costs are equal)
Depth-First Search (DFS)	$O(b^m)$	O(m)	No	No

Notes"

b = branching factor

m = maximum depth of the shellowast spal node RBS-A*

IDA* and **RBFS** are informed search algorithms, using heuristics.

DFS and BFS are uninformed bling search algorithms. I war

DFS can get stuck in infinite paths in infinite-depth spaces (hence not complete).

BFS can consume a lot of memory, making it impractical for large search trees.

IDA* combines the space efficiency of DFS with the optimality of A*.