



BITS Pilani
Pilani Campus

Applied Machine Learning

Dr. Harikrishnan N B
Computer Science and Information Systems



SE ZG568 / SS ZG568, Applied Machine Learning Lecture No. 3 [04- Feb-2025]

Recap

‘Learning’ in Machine Learning

Supervised Learning Setup

k-NN

Training, Crossvalidation, Testing

Performance Metric

Curse of Dimensionality

Basics of Linear Algebra, Linear Regression, PCA

Why should I learn Linear Algebra?



Barnsley Fern Leaf

Fractals using Iterated Function Systems

Why should I learn Linear Algebra?



Barnsley Fern Leaf

Are you curious to **write a computer program** to generate this fern leaf?

w	a	b	c	d	e	f	p	Portion generated
f_1	0	0	0	0.16	0	0	0.01	Stem
f_2	0.85	0.04	-0.04	0.85	0	1.60	0.85	Successively smaller leaflets
f_3	0.20	-0.26	0.23	0.22	0	1.60	0.07	Largest left-hand leaflet
f_4	-0.15	0.28	0.26	0.24	0	0.44	0.07	Largest right-hand leaflet

These correspond to the following transformations:

$$f_1(x, y) = \begin{bmatrix} 0.00 & 0.00 \\ 0.00 & 0.16 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$f_2(x, y) = \begin{bmatrix} 0.85 & 0.04 \\ -0.04 & 0.85 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 0.00 \\ 1.60 \end{bmatrix}$$

$$f_3(x, y) = \begin{bmatrix} 0.20 & -0.26 \\ 0.23 & 0.22 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 0.00 \\ 1.60 \end{bmatrix}$$

$$f_4(x, y) = \begin{bmatrix} -0.15 & 0.28 \\ 0.26 & 0.24 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 0.00 \\ 0.44 \end{bmatrix}$$

Linear Transform

Affine Transform

Why should I learn Linear Algebra?

Google search results for "fourier":

Joseph Fourier
French mathematician and physicist

Joseph Fourier
Jean-Baptiste Joseph Fourier was a French mathematician and physicist born in Auxerre and best known for initiating the investigation of Fourier series, ...

Fourier transform
In physics, engineering and mathematics, the Fourier transform (FT) is an integral transform that takes a function as input and outputs another function ...

People also ask

What is Fourier used for?

Joseph Fourier | Biography & Facts
Joseph Fourier, French mathematician, known also as an Egyptologist and administrator, who exerted strong influence on mathematical physics.

Joseph Fourier (1768 - 1830) - Biography
Joseph Fourier studied the mathematical theory of heat conduction. He established the partial differential equation governing heat diffusion and solved it by ...

But what is the Fourier Transform? A visual introduction.

Why should I learn Linear Algebra?

A screenshot of a Google search results page for the query "fourier". The results include:

- Joseph Fourier**: French mathematician and physicist. Wikipedia link.
- Joseph Fourier**: Jean-Baptiste Joseph Fourier was a French mathematician and physicist born in Auxerre and best known for initiating the investigation of Fourier series, ...
- Fourier transform**: In physics, engineering and mathematics, the Fourier transform (FT) is an integral transform that takes a function as input and outputs another function ...
- People also ask**: What is Fourier used for?
- Britannica**: Joseph Fourier | Biography & Facts. Britannica link.
- Joseph Fourier (1768 - 1830) - Biography**: MacTutor History of Mathematics link.
- But what is the Fourier Transform? A visual introduction.**: YouTube link.

PageRank

O ↗

How does Google Search Engine works? The secret lies in linear algebra



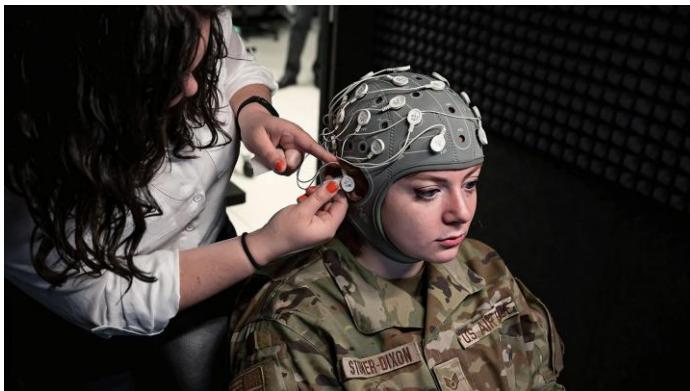
Page Rank
Algorithm

Larry Page and Sergey Brin

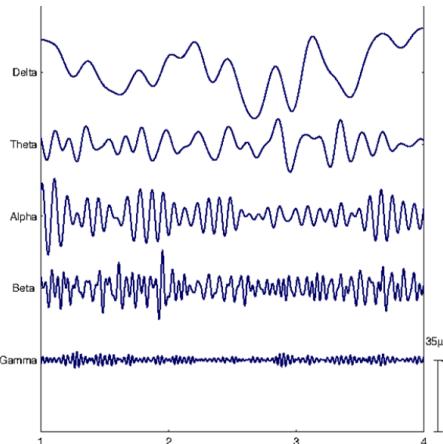
Image Source: <https://www.theverge.com/2019/12/4/20994361/google-alphabet-larry-page-sergey-brin-sundar-pichai-co-founders-ceo-timeline>

Why should I learn Linear Algebra?

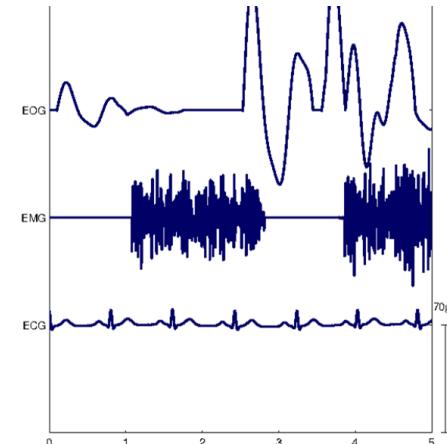
Ever measured the electrical activity of your brain?



Independent Component Analysis (ICA),
Principal Component Analysis (PCA) to
remove EEG artifacts



(a) Brain Rhythms



(b) Artifacts

Figure 1. (a) Five normal brain rhythms, from low to high frequencies. Delta, Theta, Alpha, Beta and Gamma rhythms comprise the background EEG spectrum. (b) Three different types of artifacts. Ocular, muscular and cardiac artifacts are the most frequent physiological contaminants in the literature on EEG artifact removal.

1. Reference: Urigüen, J. A., & Garcia-Zapirain, B. (2015). EEG artifact removal—state-of-the-art and guidelines. *Journal of neural engineering*, 12(3), 031001.

Goal of Linear Algebra

- The central problem of Linear Algebra is to **understand** a system of linear equations.

Goal of Linear Algebra

- The central problem of Linear Algebra is to **understand** a system of linear equations.

$$\begin{array}{l} -x + y = 0 \\ 2x + y = 3 \end{array}$$

System of Linear Equations

Goal of Linear Algebra

- The central problem of Linear Algebra is to **understand** a system of linear equations.

$$\begin{array}{l} -x + y = 0 \\ 2x + y = 3 \end{array} \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{System of Linear Equations}$$

Does this system of linear equations has a solution?



What is the value of the **unknown variables x and y** that satisfies this system of linear equations?

Goal of Linear Algebra

- The central problem of Linear Algebra is to **understand** a system of linear equations.

$$\begin{aligned} -x + y &= 0 \\ 2x + y &= 3 \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{System of Linear Equations}$$

Does this system of linear equations has a solution?



What is the value of the **unknown variables x and y** that satisfies this system of linear equations?

- Understanding involves**

- Insights about row picture and column picture.
- Explore the existence of solution to the system of linear equations.
- Insights about column space, row space, right null space, left null space.
- What new can we say about the system?**



Matrix- vector multiplication as dot product

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} a_{11} \times x + a_{12} \times y \\ a_{21} \times x + a_{22} \times y \end{bmatrix}$$

$$-x + y = 0$$

$$2x + y = 3$$

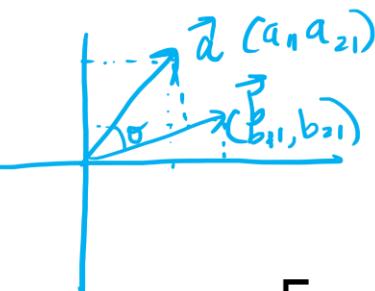
$$\begin{array}{c} \text{Row 1} \\ -1 \\ 1 \end{array} \quad \begin{array}{c} \text{Row 2} \\ 2 \\ 1 \end{array} \quad \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$$

$\begin{matrix} 2 \times 2 \\ \text{No of Rows} \end{matrix}$ $\begin{matrix} 2 \times 1 \\ \text{No of cols} \end{matrix}$

$$A_{m \times n} \vec{z}_{n \times k} = \vec{j}_{m \times k}$$

$$a^T_{1 \times n} b_{n \times 1}$$

Dot Product



$$a = \begin{bmatrix} a_{11} \\ a_{21} \end{bmatrix}$$

$$b = \begin{bmatrix} b_{11} \\ b_{21} \end{bmatrix}$$

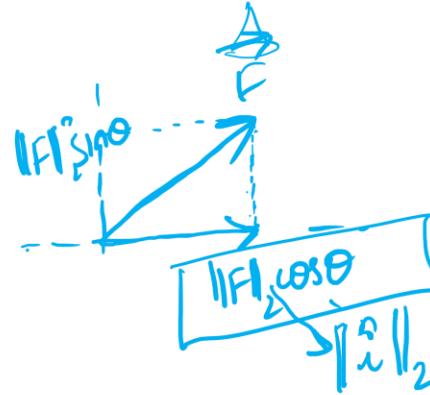
$$a = \begin{bmatrix} a_{11} \\ a_{21} \end{bmatrix} \quad b = \begin{bmatrix} b_{11} \\ b_{21} \end{bmatrix}$$

$a \cdot b = a^T b$

dot product

$$a \cdot b = a^T b$$

$$[a_{11} \ a_{21}] \begin{bmatrix} b_{11} \\ b_{21} \end{bmatrix}_{1+2} = [a_{11}b_{11} + a_{21}b_{21}]$$



$\|u\|_2 = \sqrt{1^2 + 0^2} = 1$

$$F = m \cdot a \quad a \in \mathbb{R}^3$$

A diagram shows a force vector F acting on a mass m. The angle between F and a unit vector i-hat is theta. The component of F in the direction of i-hat is labeled ||F||_2 ||i||_2 cos theta.

$$a \cdot b = \|a\|_2 \|b\|_2 \cos \theta$$

$$\|F\|_2 \|i\|_2 \cos \theta$$

Matrix- vector multiplication as dot product

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} a_{11} \times x + a_{12} \times y \\ a_{21} \times x + a_{22} \times y \end{bmatrix}$$

Geometric Interpretation of Matrix Vector Multiplication

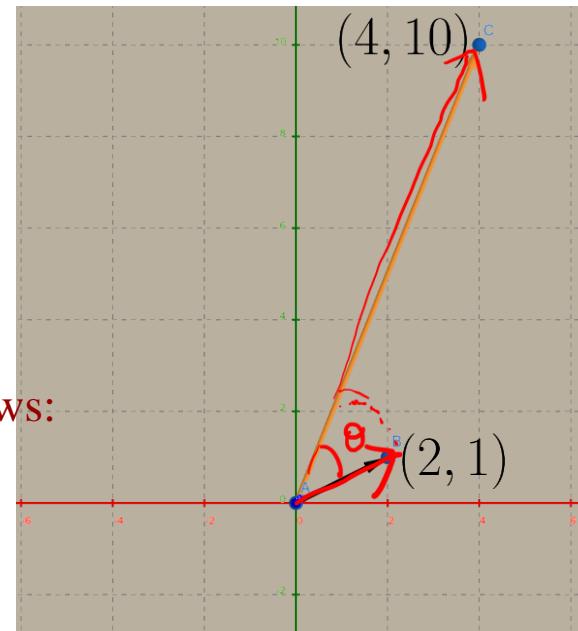
Intuition for Matrix vector multiplication for Square Matrices

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 10 \end{bmatrix}$$

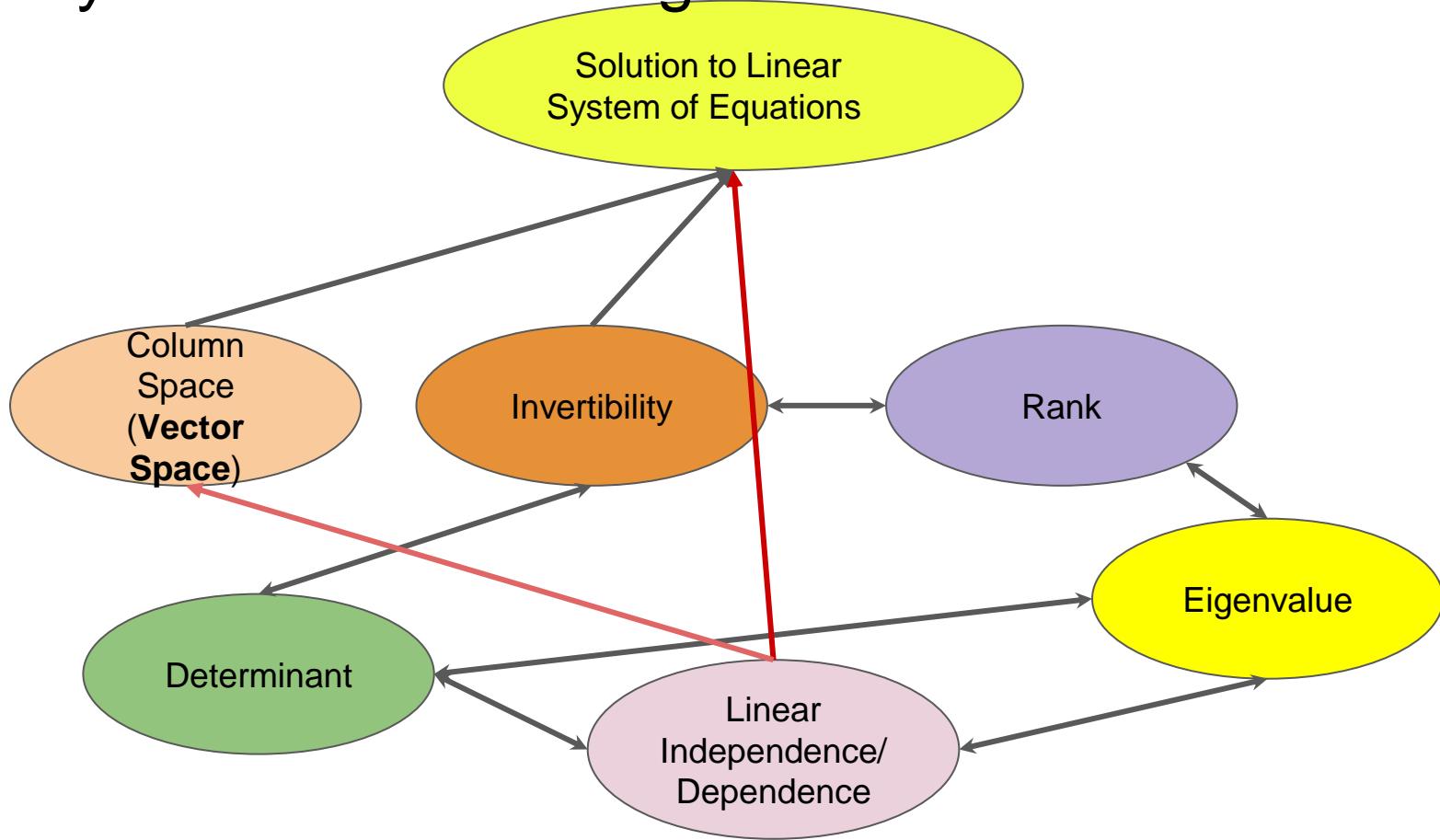
$$1 \times 2 + 2 \times 1 = 4$$
$$3 \times 2 + 4 \times 1 = 10$$

Matrix(Square Matrix) vector multiplication can be seen as follows:

- Rotation
- Stretching or Shrinking



Beauty Lies in Connecting Ideas

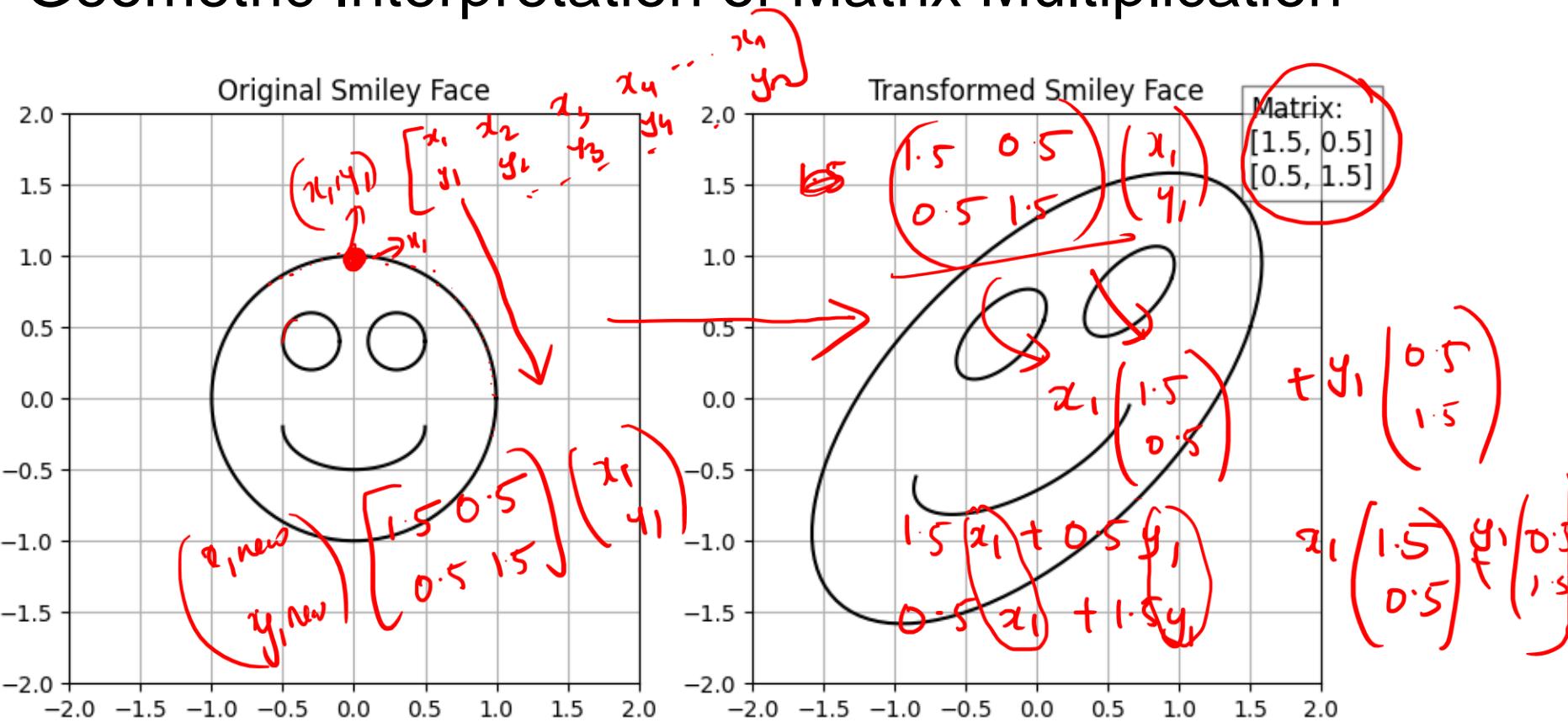


Matrix- vector multiplication

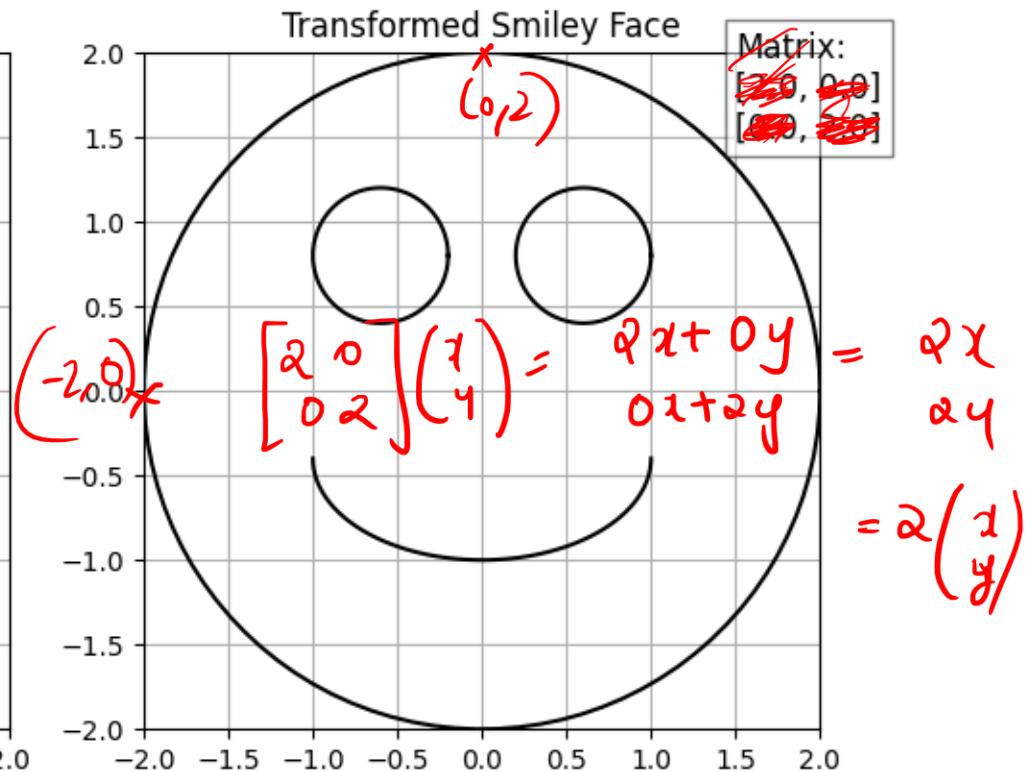
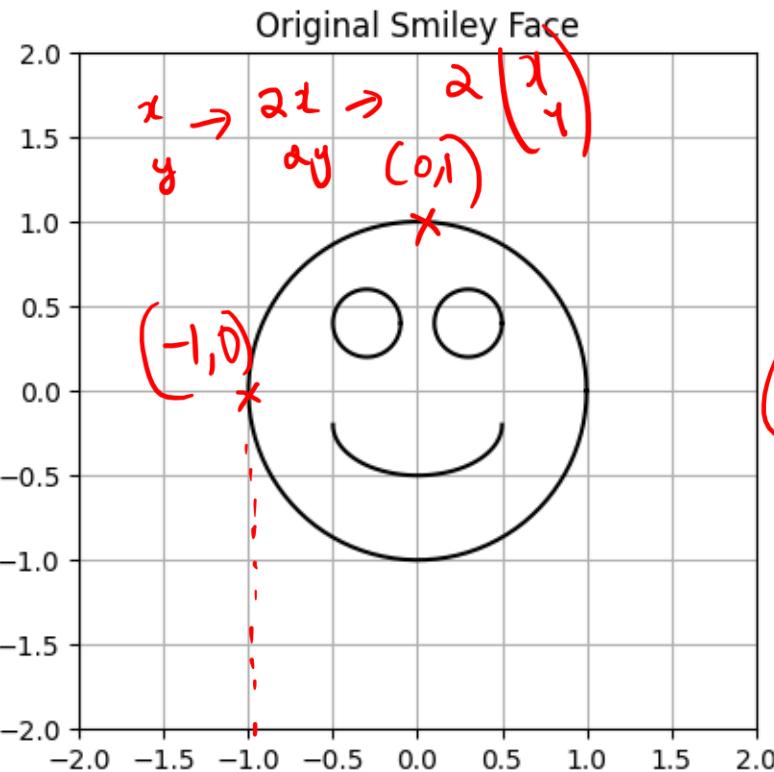
$$\begin{aligned}-x + y &= 0 \\ 2x + y &= 3\end{aligned}$$

Dot Product

Geometric Interpretation of Matrix Multiplication



Geometric Interpretation of Matrix Multiplication



What should I do if I want to rotate the smiley by 90 degree?



$$a \cdot b \quad a^T b = 0$$

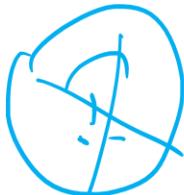
$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} =$$

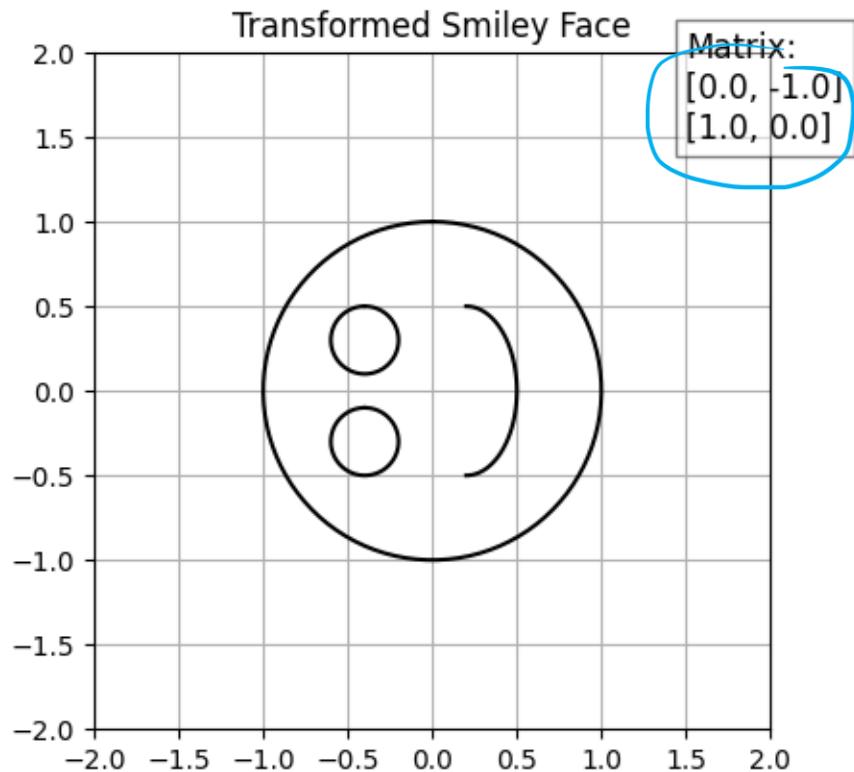
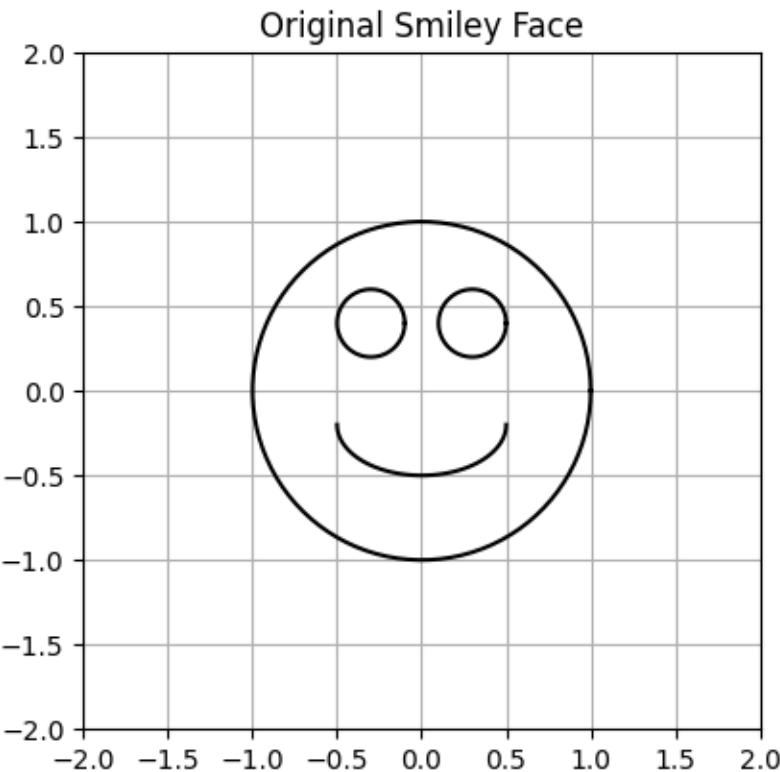
$$\begin{aligned} 0 \times x - 1 \times y &= -y \\ -1 \times x + 0 \times y &= -x \end{aligned}$$

$$-xy - yx \Rightarrow -2xy$$

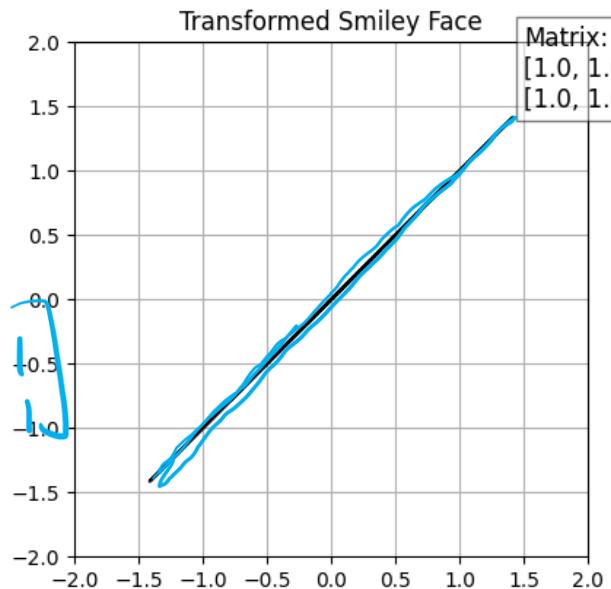
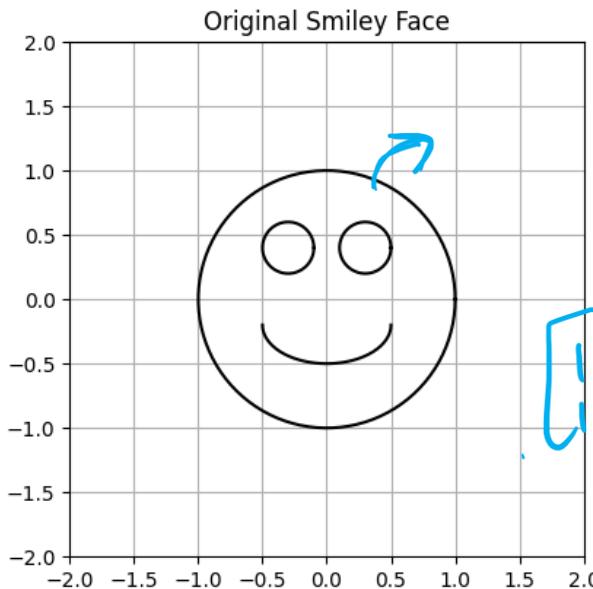
$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix} \begin{pmatrix} -y \\ x \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix} \begin{pmatrix} -y \\ x \end{pmatrix} = -xy + yx = 0$$



What should I do if I want to rotate the smiley by 90 degree?



What can you say about the following transformation?

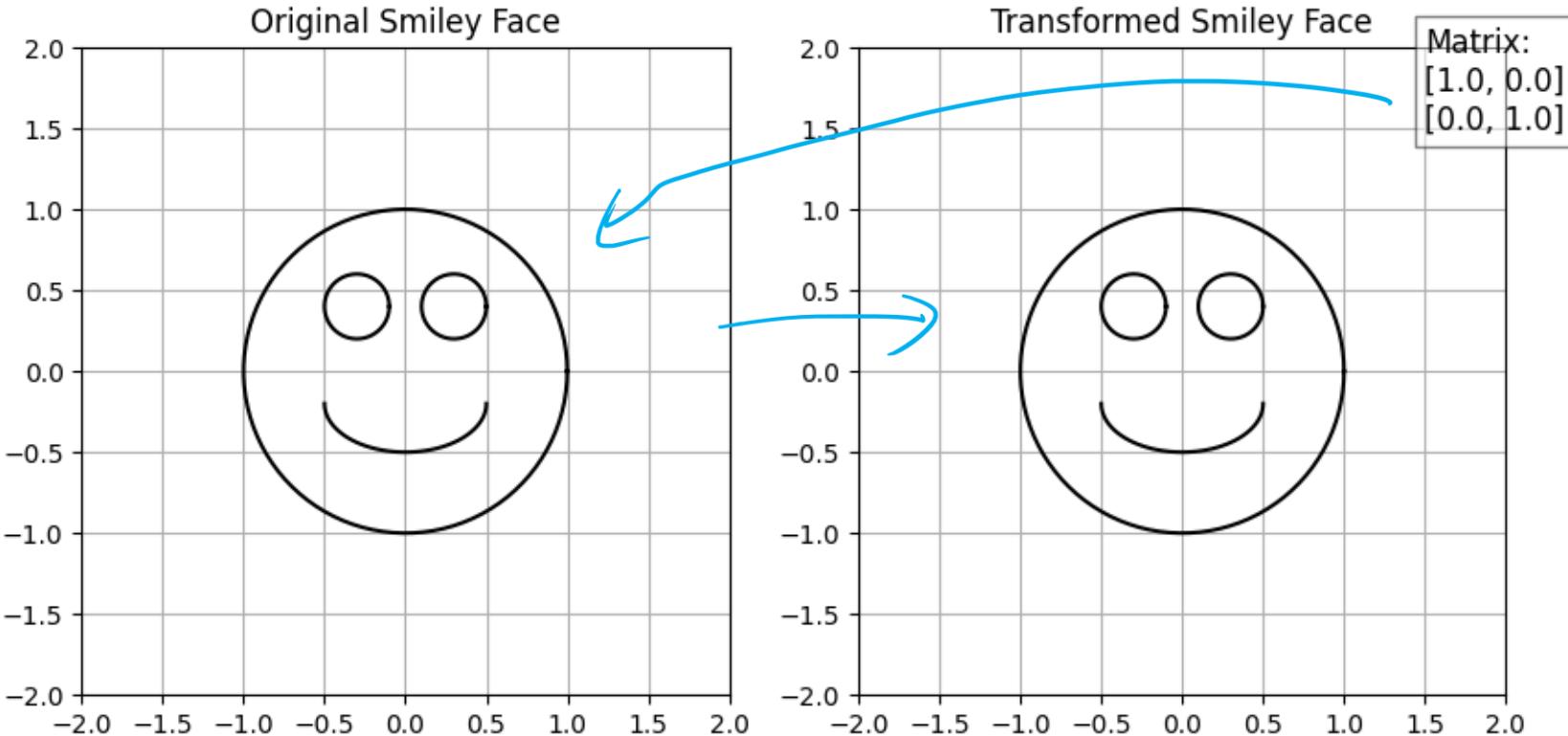


$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x+y \\ x+y \end{pmatrix}$$
$$x\begin{pmatrix} 1 \\ 1 \end{pmatrix} + y\begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Figure out the transformation (matrix) that will preserve the smiley as it is!

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Figure out the transformation (matrix) that will preserve the smiley as it is!



Identity Matrix

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} x+0y \\ 0x+y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}$$

Inverse of a Matrix

$$AA^{-1} = A^{-1}A = I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}_{2 \times 2}$$

If a matrix is invertible
 A^{-1}

$$\boxed{AA^{-1} = A^{-1}A = I_{n \times n}}$$

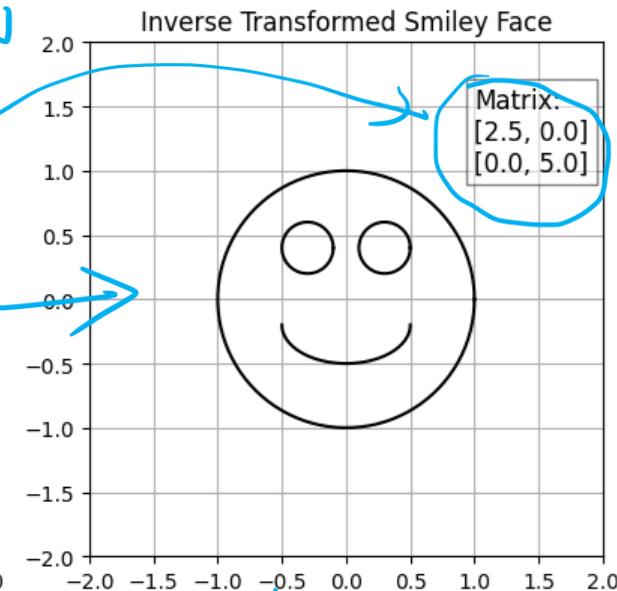
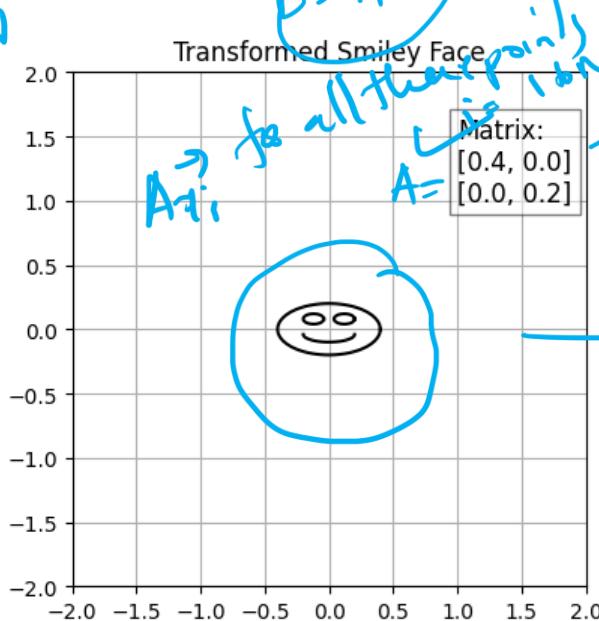
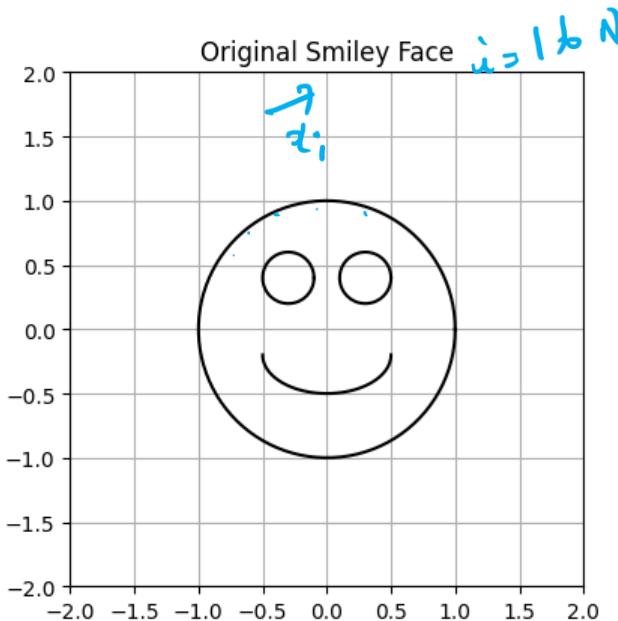
If $A_{n \times n}$ is invertible $A^{-1}_{n \times n}$

$$AA^{-1} = A^{-1}A = I_{n \times n}$$

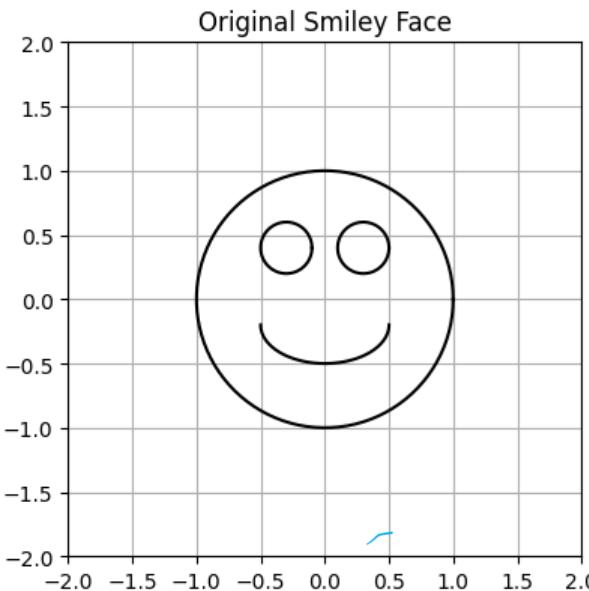
$$\begin{bmatrix} 1 & 0 & & \\ 0 & 1 & & \\ & & \ddots & \\ & & & n \times n \end{bmatrix}$$

$$\begin{bmatrix} A & B \\ 0.4 & 0 & 0.2 & 0 \\ 0 & 0 & 0 & 5 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} I$$

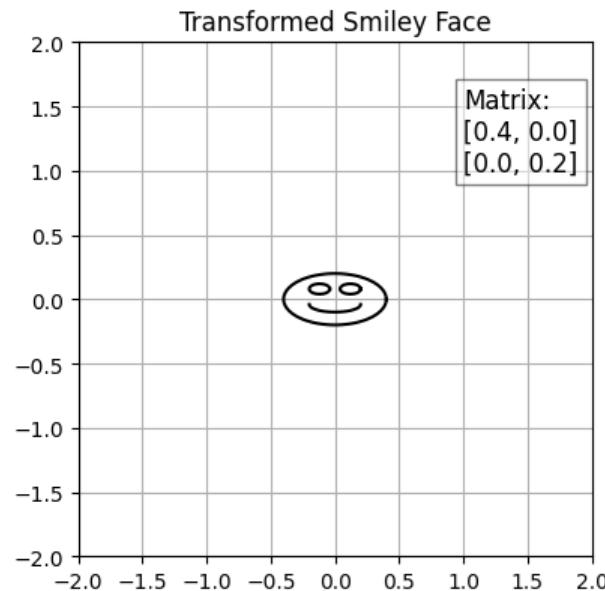
How do we understand matrix inverse geometrically?


 \vec{x}_i
 $A\vec{x}_i$
 $A^{-1}A\vec{x}_i$

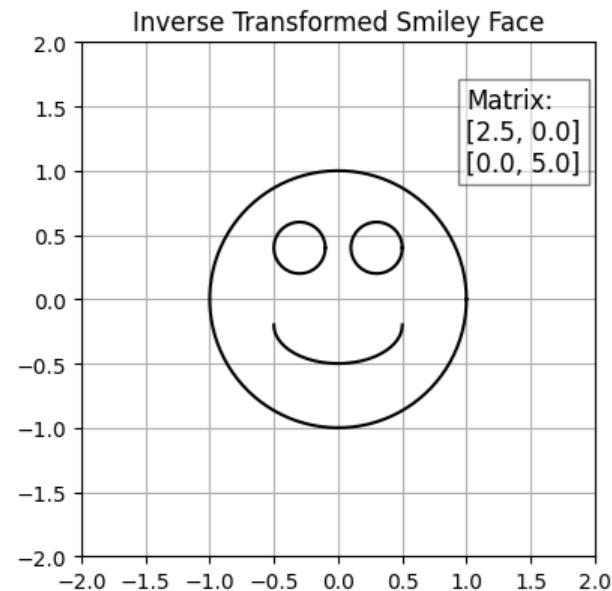
In a Nutshell



$$\vec{x}_i$$

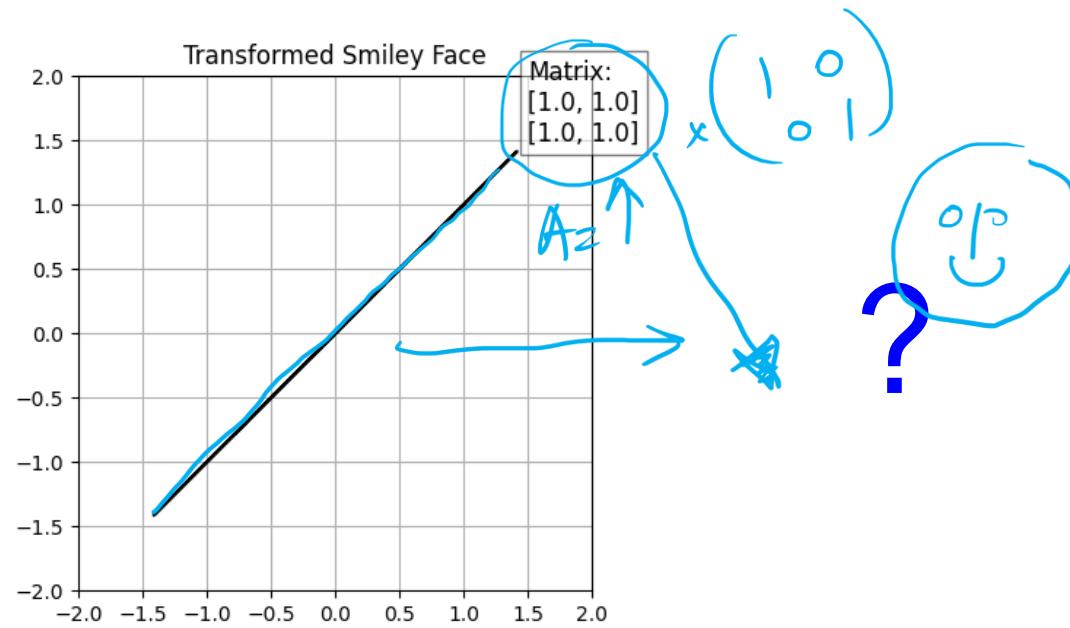
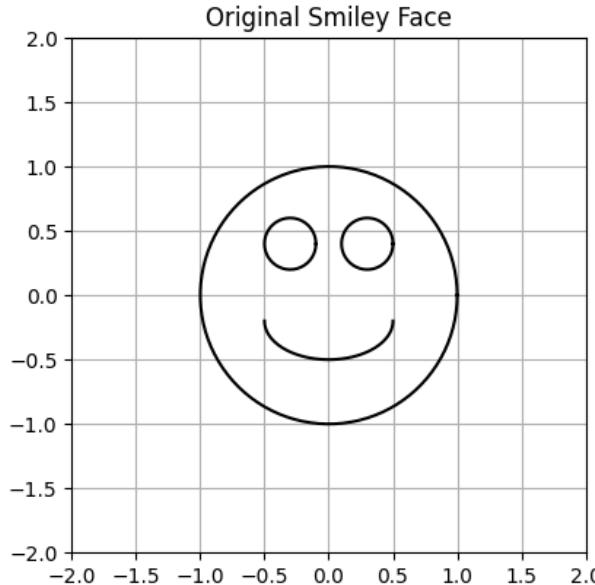


$$A\vec{x}_i$$



$$A^{-1}A\vec{x}_i$$

Can you get back the original smiley?



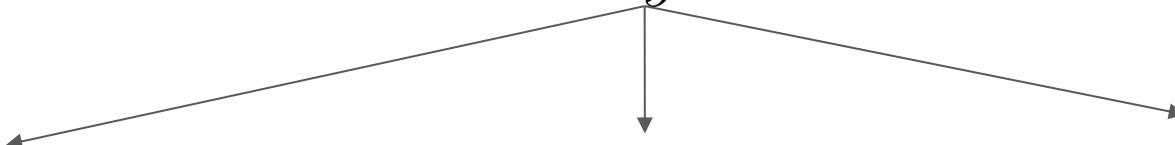
$$\vec{x}_i$$

$$A\vec{x}_i$$

$$A^{-1}A\vec{x}_i$$

Solutions to System of Linear Equations

$$\begin{aligned}-x + y &= 0 \\ 2x + y &= 3\end{aligned}$$



Algebraic Interpretation

Row Picture

Column Picture



Two Equations & Two Unknowns - Algebraic Interpretation

$$-x + y = 0 \quad \textcircled{1}$$

$$2x + y = 3 \quad \textcircled{2}$$

Gaussian Elimination

Two Equations and Two Unknowns- Algebraic Interpretation

$$\begin{aligned}-x + y &= 0 \\ 2x + y &= 3\end{aligned}$$

Elimination

$$\left[\begin{array}{cc|c} -1 & 1 & 0 \\ 2 & 1 & 3 \end{array} \right] R_1 \rightarrow 2R_1 \quad \text{Row}_1 \rightarrow 2\text{Row}_1$$

$$\begin{aligned}3y &= 3 \\ y &= 1\end{aligned}$$

Sub. $y = 1$ in
Equation 1, we
get: $x = 1$

What is the value of the **unknown variables x and y** that satisfies this system of linear equations?

$$\left[\begin{array}{ccc|c} x_1 & x_2 & x_3 & z_1 \\ x_2 & x_4 & x_5 & z_2 \\ x_3 & x_6 & x_7 & z_3 \\ \hline & & & 3/3 \end{array} \right]$$

$$\left[\begin{array}{ccc|c} z_1 & z_2 & z_3 & z_1 \\ 0 & z_4 & z_5 & z_2 \\ 0 & 0 & z_6 & z_3 \\ \hline & & & 3/3 \end{array} \right]$$

$$\left[\begin{array}{cc|c} -2 & 2 & 0 \\ 0 & 3 & 3 \end{array} \right] \left(\begin{array}{c} x \\ y \end{array} \right) = \left(\begin{array}{c} 0 \\ 3 \end{array} \right)$$

$$0x + 3y = 3$$

$$y = 1$$

$$\left[\begin{array}{cc|c} -2 & 2 & 0 \\ 2 & 1 & 3 \end{array} \right] \quad \begin{array}{l} R_2 \rightarrow R_1 + R_2 \\ R_2 \rightarrow R_1 + R_2 \end{array}$$

$$\left[\begin{array}{cc|c} -2 & 2 & 0 \\ 0 & 3 & 3 \end{array} \right]$$

Solution: $x = 1$, and $y = 1$

$$\begin{aligned}-2x + 2y &= 0 \\ -2x + a &= 0 \\ -2x &= -2 \\ x &= 1\end{aligned}$$

Two Equations and Two Unknowns-

Geometric Interpretation

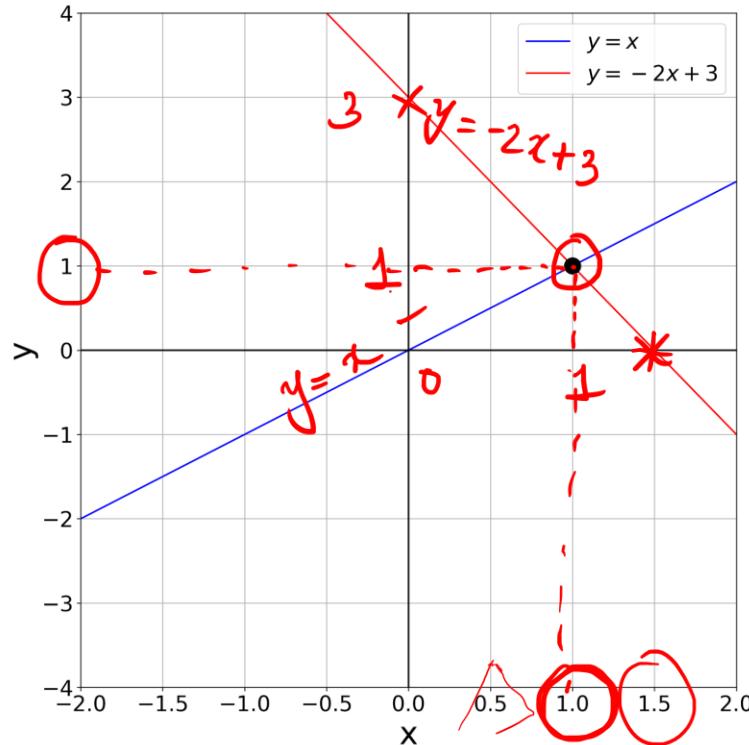
$$\begin{aligned} -x + y &= 0 \\ 2x + y &= 3 \end{aligned}$$

Row Picture

$$y = x$$

$$y = -2x + 3$$

$$0 = -2x + 3$$



$$y = x$$

$$y = -2x + 3$$

Two Equations and Two Unknowns-

Geometric Interpretation

$$\begin{aligned} -x + y &= 0 \\ 2x + y &= 3 \end{aligned}$$

Column Picture

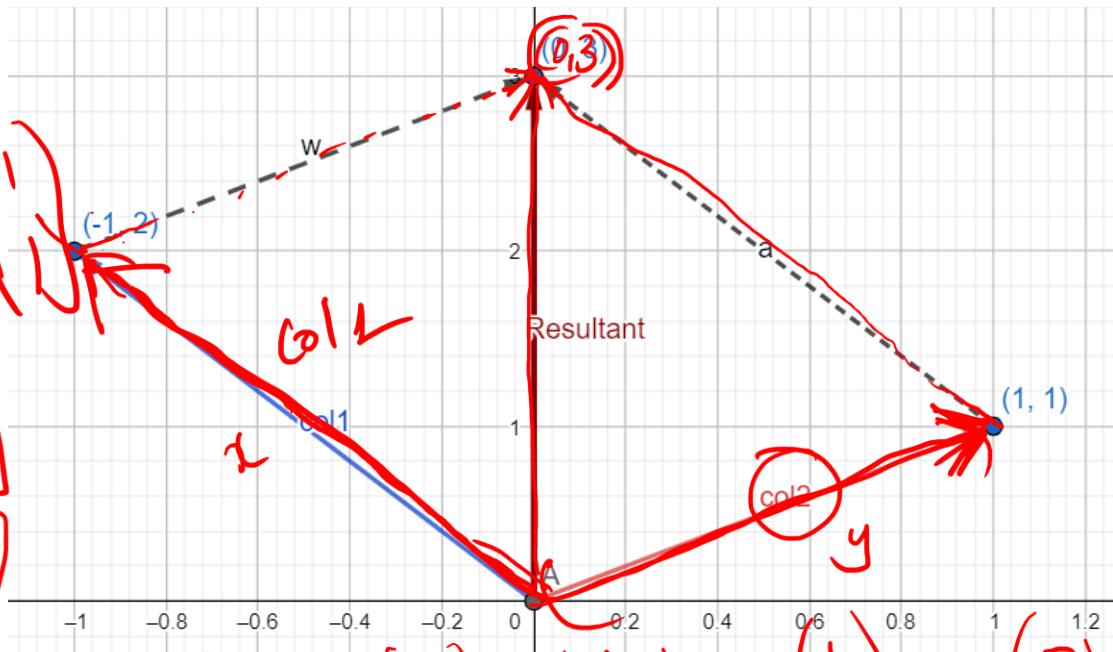
$$x \begin{bmatrix} -1 \\ 2 \end{bmatrix} + y \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$$

but

$$x \begin{bmatrix} -1 \\ 2 \end{bmatrix} + y \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$$

$$x \begin{bmatrix} -1 \\ 2 \end{bmatrix} + y \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$$

direction



$$1 \cdot \begin{bmatrix} -1 \\ 2 \end{bmatrix} + 1 \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$$

Two Equations and Two Unknowns-

$$\begin{aligned}-x + y &= 0 \\ 2x + y &= 3\end{aligned}$$

$$x \begin{pmatrix} -1 \\ 2 \end{pmatrix} + y \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 3 \end{pmatrix}$$

Some Observations

$$\begin{bmatrix} -1 & 1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix} \Leftrightarrow A\vec{x} = b$$

$$\vec{x} = \begin{pmatrix} x \\ y \end{pmatrix}$$

$$x \begin{bmatrix} -1 \\ 2 \end{bmatrix} + y \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$$

$A\vec{x} = b$ is the weighted linear combinations of columns of A

Two Equations and Two Unknowns-

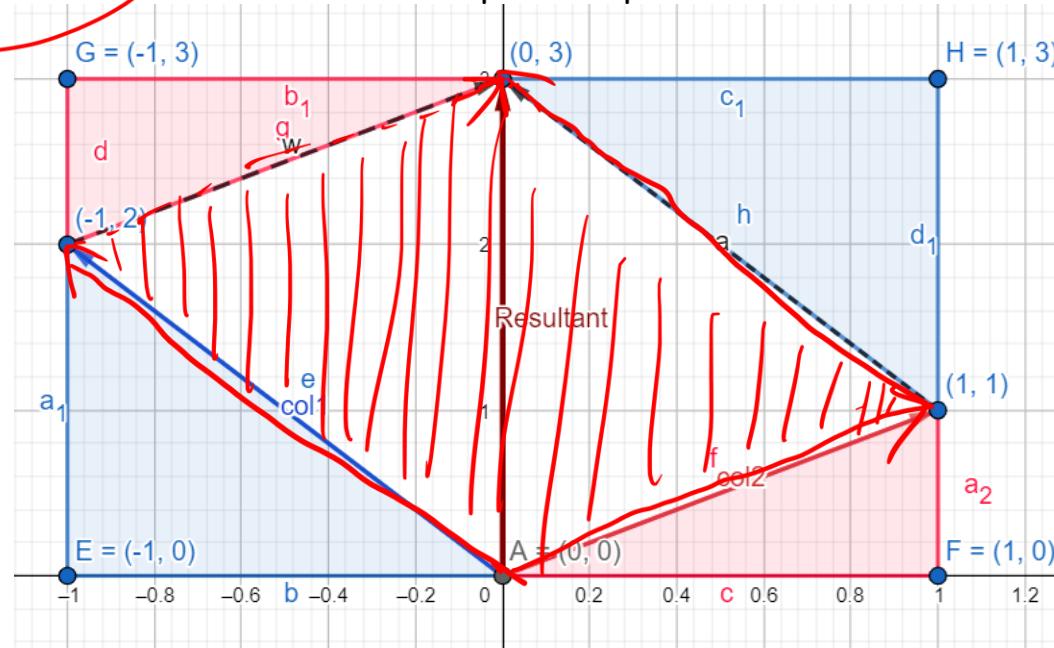
$$\begin{aligned} -x + y &= 0 \\ 2x + y &= 3 \end{aligned}$$

Determinant

$$|A| =$$

$$|A| = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = (ad - bc)$$

$$|A| = -3$$



$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$|A| = \boxed{ad - bc}$$

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$|A| = 0$$

Two Equations and Two Unknowns- Invertibility

$$A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$|A| = 0$$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$A^{-1} = \frac{1}{|A|} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$AA^{-1} = A^{-1}A = I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\begin{aligned} -x + y &= 0 \\ 2x + y &= 3 \end{aligned}$$

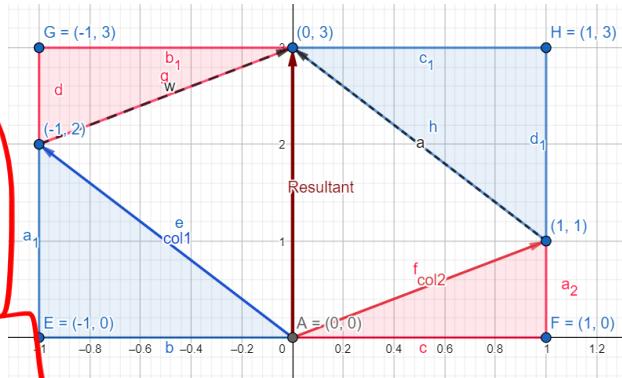
$$A = \begin{bmatrix} -1 & 1 \\ 2 & 1 \end{bmatrix}$$

$$|A| = -3$$

$$\frac{1}{|A|} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

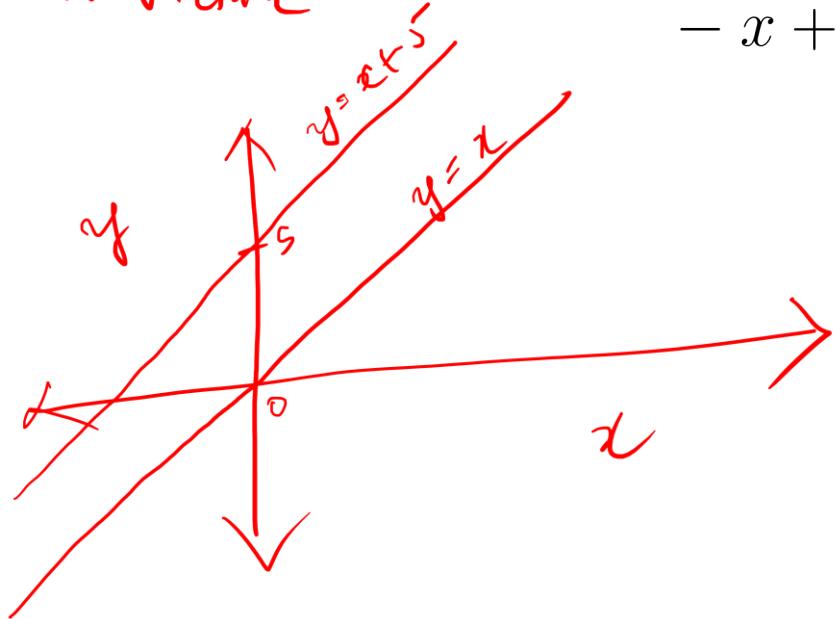
$$\begin{aligned} & \frac{1}{ad-bc} (ad-bc) \\ & \frac{1}{ad-bc} (-ac+ad) \\ & = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \end{aligned}$$

$$|A| = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = (ad - bc)$$



Two Equations and Two Unknowns- Contd..

Row Picture



$$\begin{aligned} -x + y &= 0 \\ -x + y &= 5 \end{aligned} \rightarrow \boxed{\quad}$$

Permanent Breakdown of Elimination

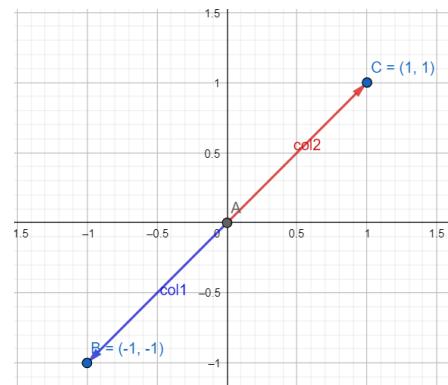
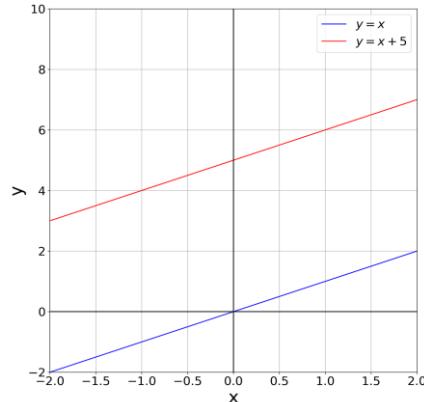
$$\begin{array}{l} -x + y = 0 \\ -x + y = 5 \end{array} \quad \left[\begin{array}{cc|c} -1 & 1 & 0 \\ -1 & 1 & 5 \end{array} \right] \quad \left[\begin{array}{c} x \\ y \end{array} \right] = \left[\begin{array}{c} 0 \\ 5 \end{array} \right]$$

$$\left[\begin{array}{cc|c} -1 & 1 & 0 \\ -1 & 1 & 5 \end{array} \right] \xrightarrow{R_2 \rightarrow R_2 - R_1} \left[\begin{array}{cc|c} -1 & 1 & 0 \\ 0 & 0 & 5 \end{array} \right]$$

$R_1 \rightarrow R_1 + R_2$

$$0y = 5$$

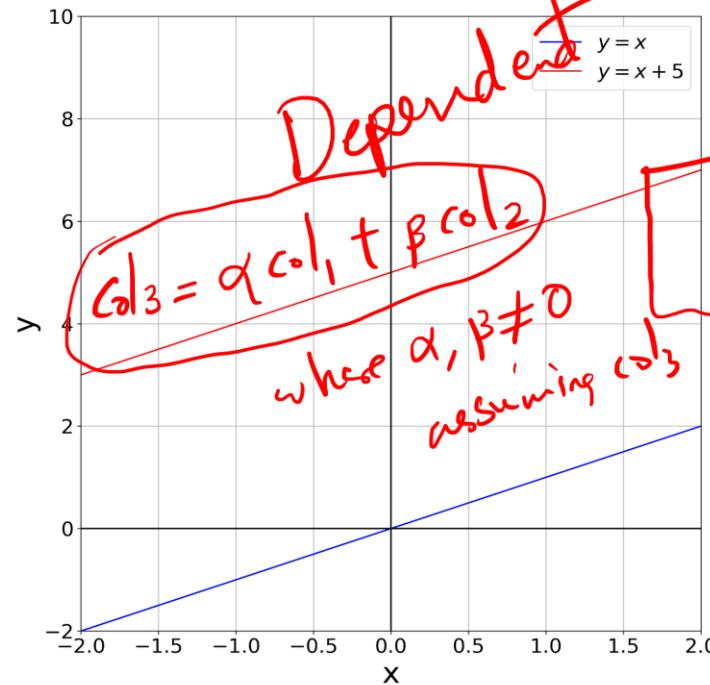
Permanent Breakdown
of elimination (NO
SOLUTION)



$\left[\begin{matrix} | & \text{Col}_1 & \downarrow \text{Col}_2 & \downarrow \text{Col}_3 | \end{matrix} \right]$

Two Equations and Two Unknowns- Contd..

Row Picture



$$\begin{aligned}-x + y &= 0 \\ -x + y &= 5\end{aligned}$$

$\left[\begin{matrix} | & 1 & 1 | \end{matrix} \right]$

$\left[\begin{matrix} | & 1 & 2 \\ | & 2 & 4 | \end{matrix} \right]$

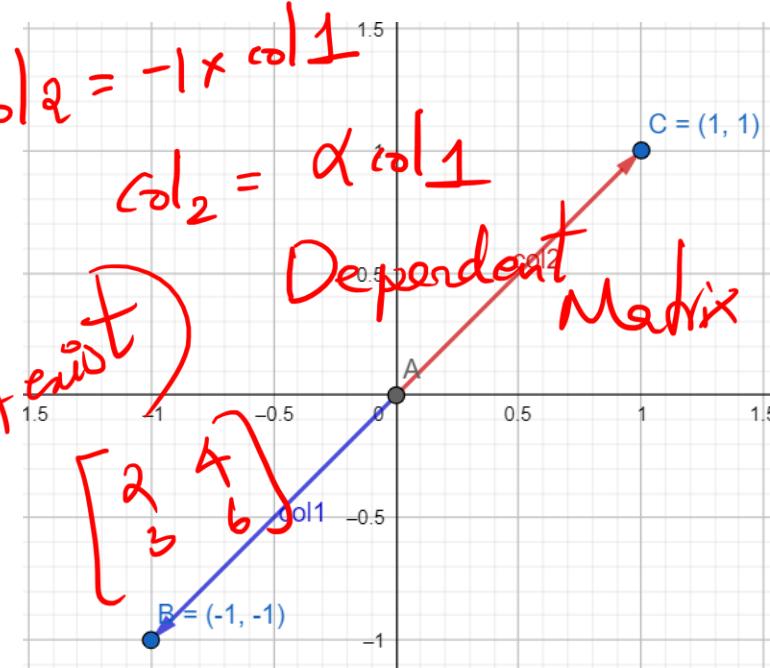
Column Picture

$$\left[\begin{matrix} | & -1 & 1 \\ | & -1 & 1 | \end{matrix} \right]$$

$\downarrow \text{Col}_2$

$$|\mathbf{A}| = 0$$

$(\bar{\mathbf{A}}^1)$ does not exist



Two Equations and Two Unknowns- Invertibility

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad A^{-1} = \frac{1}{|A|} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \quad AA^{-1} = A^{-1}A = I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

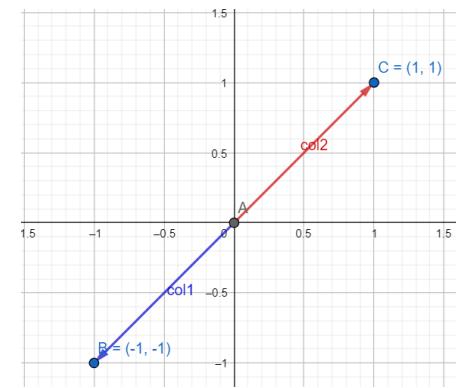
$$\begin{aligned} -x + y &= 0 \\ -x + y &= 5 \end{aligned}$$

$$|A| = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = (ad - bc)$$

$$A = \begin{bmatrix} -1 & 1 \\ -1 & 1 \end{bmatrix}$$

NOT INVERTIBLE

$$|A| = 0$$

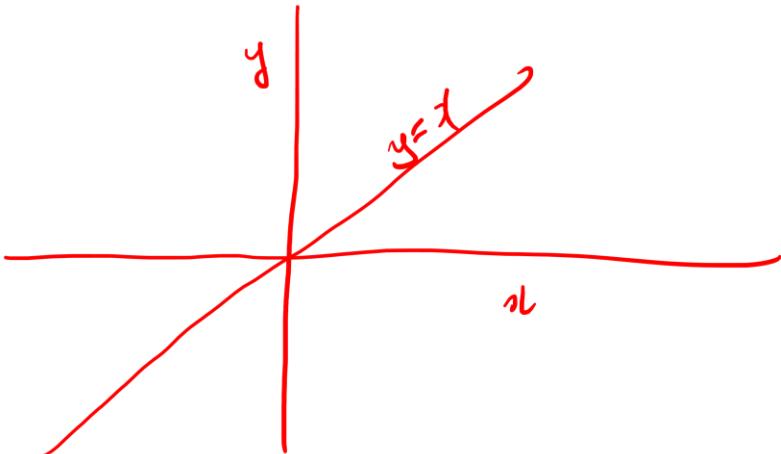


Two Equations and Two Unknowns- Contd..

$$-x + y = 0$$

$$-2x + 2y = 0$$

$$\begin{bmatrix} -1 & 1 \\ -2 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$



Infinitely many Solutions

$$\begin{bmatrix} -1 & 1 \\ -2 & 2 \end{bmatrix}$$

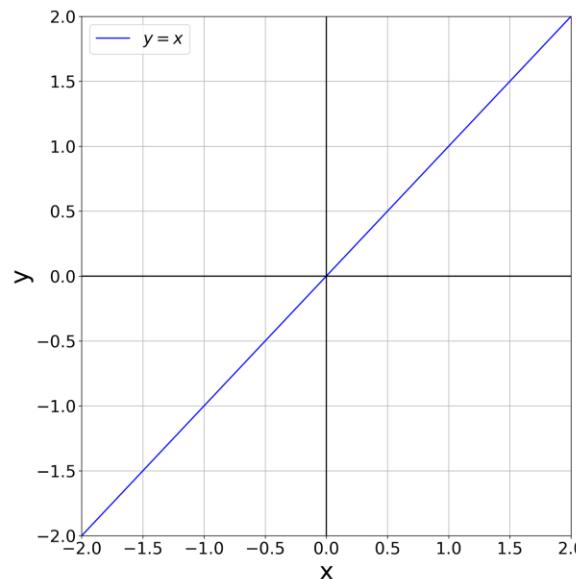
Two Equations and Two Unknowns-

Contd..

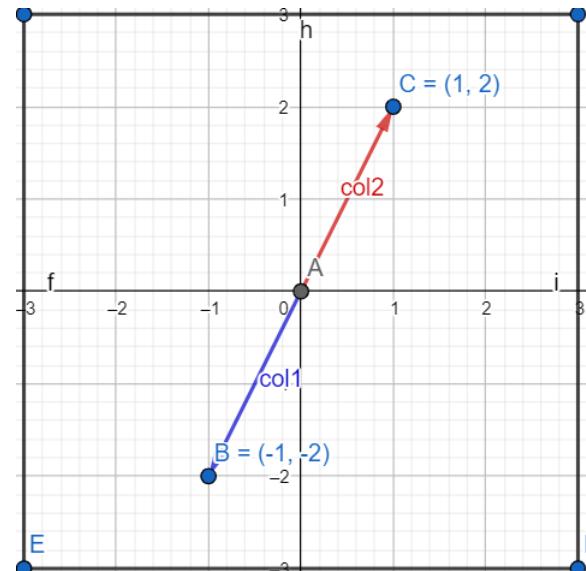
$$\begin{aligned}-x + y &= 0 \\ -2x + 2y &= 0\end{aligned}$$

$$\begin{bmatrix} -1 & 1 \\ -2 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Row Picture



Column Picture



Two Equations and Two Unknowns- Contd..

$$\begin{aligned}-x + y &= 0 \\ -2x + 2y &= 0\end{aligned}\quad \begin{bmatrix} -1 & 1 \\ -2 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$Ax = b$ has solution only when
 b lies in the "col space" of A

Temporary Breakdown of Elimination

$$\begin{aligned} -x + y &= 0 \\ -2x + 2y &= 0 \end{aligned} \quad \rightarrow \quad \begin{bmatrix} -1 & 1 \\ -2 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\left[\begin{array}{cc|c} -1 & 1 & 0 \\ -2 & 2 & 0 \end{array} \right] R_2 \rightarrow R_2 - 2R_1 \quad \left[\begin{array}{cc|c} -1 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

*nonzero number
0
Pemnove X*

y can take any value

0y = 0

0 / 0 X/X

*y can take any value
(Infinitely many solutions)*

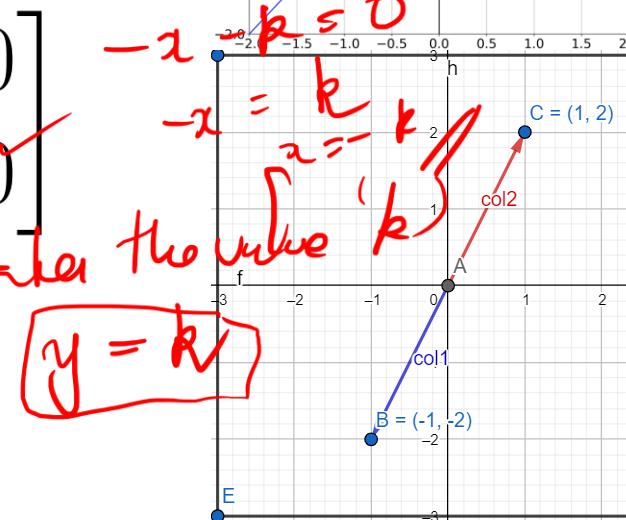
$$\begin{aligned} -x + y &= 0 \\ -x + k &= 0 \\ -x &= k \\ x &= -k \end{aligned}$$

-x + y = 0

-x + k = 0

y = k

x = -k



Two Equations and Two Unknowns- Invertibility

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad A^{-1} = \frac{1}{|A|} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \quad AA^{-1} = A^{-1}A = I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\begin{aligned} -x + y &= 0 \\ -2x + 2y &= 0 \end{aligned}$$

$$A = \begin{bmatrix} -1 & 1 \\ -2 & 2 \end{bmatrix}$$

NOT INVERTIBLE!!!

$$|A| = 0$$

$$|A| = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = (ad - bc)$$

