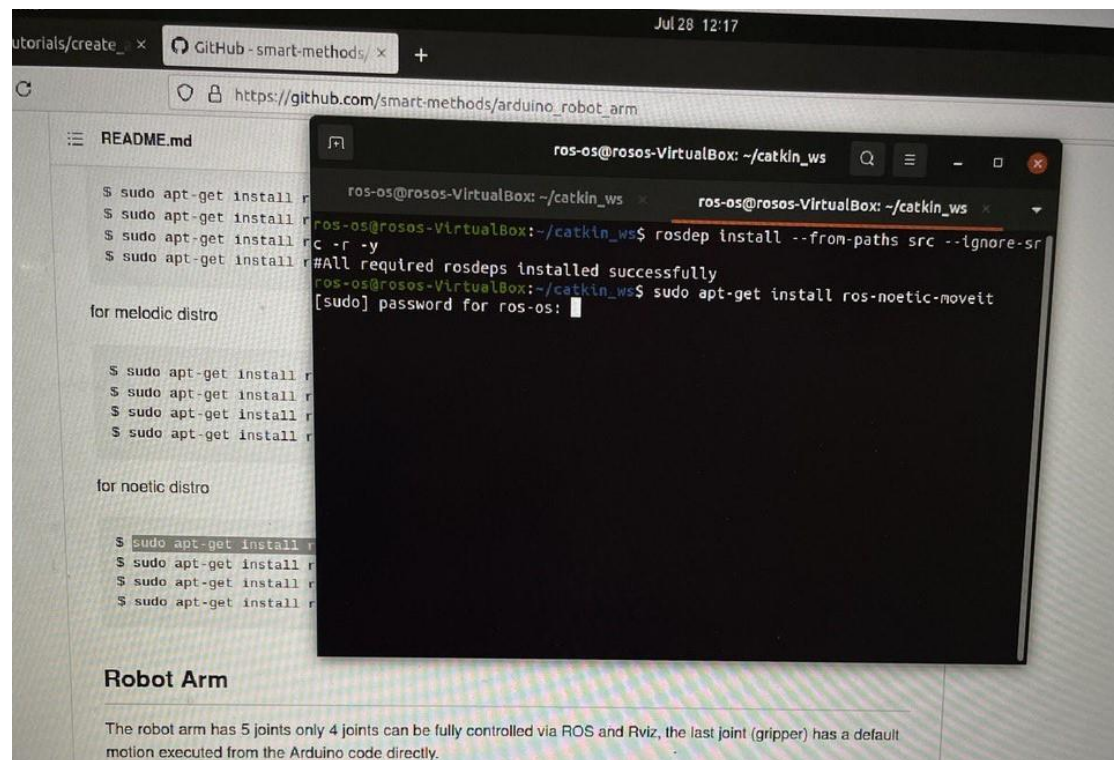
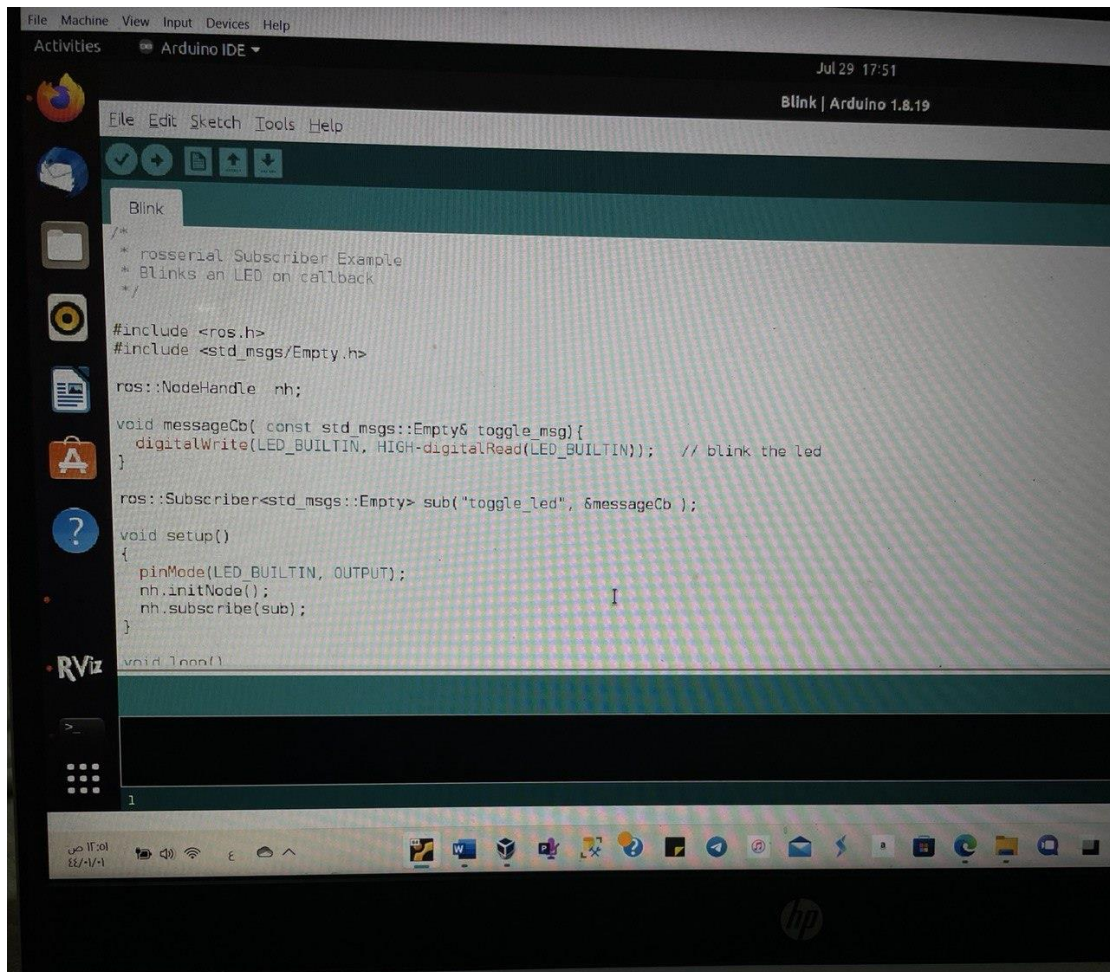


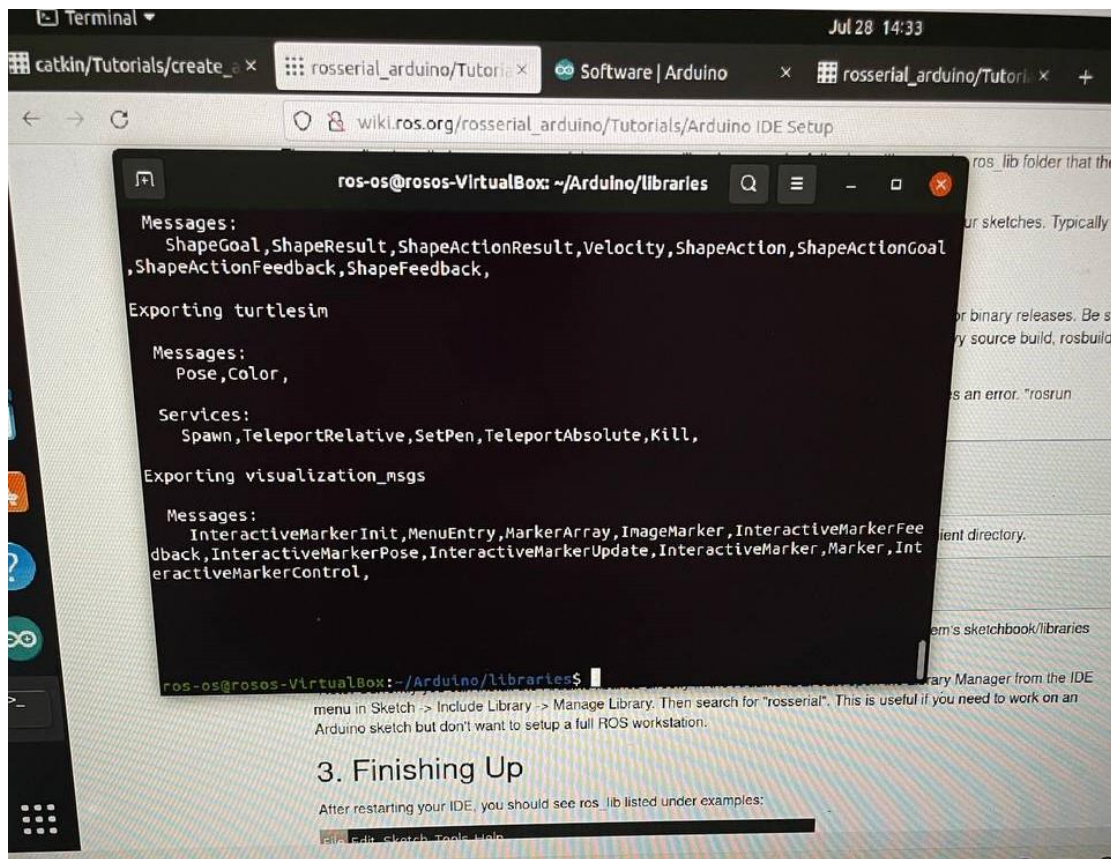
# Dependencies



# Configuring Arduino with ROS



Install the arduino package and ros library



Controlling the robot arm by joint\_state\_publisher

