

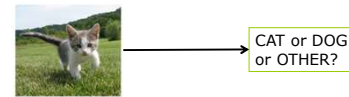
# METODE INTELIGENTE DE REZOLVARE A PROBLEMELOR REALE

Laura Dioşan  
Image segmentation

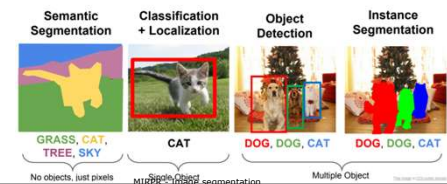
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## Automatic image processing

### Image classification



### Other tasks



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## Automatic image processing

### Image classification

- Does an image contain object X? [yes/no]

### Image detection and segmentation

- Does an image contain object X? [yes/no]
- Where is the object X? → Location of the object
  - Pixel-based granularity → semantic/instance segmentation
  - Object-based granularity → object detection
- Which object does this image contain? [where?]
- Aprox. localisation (Bounding box)
- Accurate localisation (contour) → Segmentation

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## Image segmentation

### Problem

- Aim
  - Classify each pixel
- Tasks
  - How many segments?
  - How many objects in an image?

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## Image segmentation

### Problem → Tasks

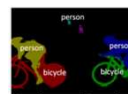
#### Semantic segmentation

- Labels for every pixel
- No differences across different instances of the same object



#### Instance segmentation

- Labels for every pixel
- unique label to every instance of a particular object in the image



- Special topic: Panoptic segmentation
  - Instance segmentation for background

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## Image segmentation

### Problem

- Challenges
  - Occlusion, Truncation, Scale, Illumination
  - Smooth boundaries

#### Evaluation

- TP - #pixels correctly classified as belonging to class X
- FP - #pixels classified as belonging to class X, but they belong to other classes
- FN - #pixels that belong to class X, but are not classified as belonging to class X
- $IOU_{class} = TP / (TP + FP + FN)$  - over all images

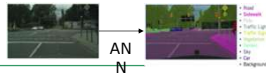
Ground Truth	Prediction	Class: Road	Class: Sidewalk
		$TP = 3$ $FP = 0$ $FN = 2$	$TP = 4$ $FP = 2$ $FN = 0$

$$IOU_{road} = \frac{3}{3+0+2} = \frac{3}{5}$$

$$IOU_{sidewalk} = \frac{4}{4+2+0} = \frac{4}{6}$$

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## Image segmentation



### Problem

#### Datasets

- 2001 Berkeley
  - <https://www2.eecs.berkeley.edu/Research/Projects/CS/vision/bsds/>
  - Good for edge detection problem (also)
- 2005 – Pascal VOC
  - 20 classes
- 2015 – COCO dataset (detection and segmentation)
  - <https://cocodataset.org/#detection-2015>
  - 91 classes
- 2015 – CityScapes
  - <https://www.cityscapes-dataset.com/>
  - 30 classes grouped in 8 categories
- CamVid
  - <http://mji.eng.cam.ac.uk/research/projects/VideoRec/CamVid/>

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## Image segmentation

### How?

#### Before Computer Vision

- Gestalt: whole or group
  - Whole is greater than sum of its parts
  - Relationships among parts can yield new properties/features
- Psychologists identified series of factors that predispose set of elements to be grouped (by human visual system)
  - "I stand at the window and see a house, trees, sky. Theoretically I might say there were 327 brightnesses and nuances of colour. Do I have '327'? No. I have sky, house, and trees." Max Wertheimer (1880-1943)

#### Computer Vision's era

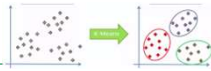
- Segmentation as clustering (K-means, GAMMs and EM, Mean Shift, ...)
- Segmentation as grouping by boundaries
- Graph-based segmentation
- Segmentation as energy minimization
- Region-based segmentation (-> Thresholding, Region growing)
- Edge detection segmentation
- Deep learning algorithms

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## Image segmentation



### How? -> Computer Vision's era

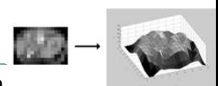
#### Segmentation as clustering

- Main idea
  - Group the "similar" pixels into clusters
- Algorithms:
  - K-means, GAMMs and EM, Mean Shift, ...
  - <https://scikit-learn.org/stable/modules/clustering.html>
- See
  - Comaniciu, D., & Meer, P. (2002). Mean shift: A robust approach toward feature space analysis. *IEEE Transactions on pattern analysis and machine intelligence*, 24(5), 603-619. <https://courses.csail.mit.edu/6.869/handouts/PAMI02meanshift.pdf>
  - <http://cs229.stanford.edu/notes2020spring/cs229-notes8.pdf>
  - <http://cs229.stanford.edu/notes2020spring/cs229-notes7b.pdf>
- + works well on a small dataset with convex clusters
- - large computational time, shape of clusters

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## Image segmentation



### How? -> Computer Vision's era

#### Segmentation as grouping by boundaries

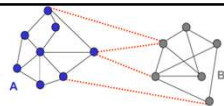
- Main idea
  - Edge-based methods
- Algorithms:
  - Watershed – good for hierarchical segmentation
    - the image is regarded as a topographic landscape with ridges and valleys
  - Level-sets
- See
  - <https://members.accu.org/index.php/journals/1469>
  - [https://hub.gke2.mybinder.org/user/scikit-image-lpeqj3jb/notebooks/notebooks/auto\\_examples/segmentation/plot\\_watershed.ipynb](https://hub.gke2.mybinder.org/user/scikit-image-lpeqj3jb/notebooks/notebooks/auto_examples/segmentation/plot_watershed.ipynb)
- + Fast (apply filters)
- - if there are too many edges or less contrast objects

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## Image segmentation



### How? -> Computer Vision's era

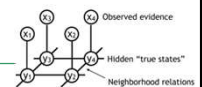
#### Graph-based segmentation

- Main idea
  - Images as graphs (nodes – pixels, weights (affinity matrix) – location/intensity/color/texture filters) and break graph in segments
- Algorithms
  - Graph-Cut – eigen values of affinity matrix
  - Min-cut
- See
  - <http://cs.brown.edu/people/pfelzens/segment/>
  - Shi, J., & Malik, J. (2000). Normalized cuts and image segmentation. *IEEE Transactions on pattern analysis and machine intelligence*, 22(8), 888-905. [https://ieeexplore.ieee.org/stamp/stamp.jsp?arnumber=868688&casa\\_tok=gn523BGFY2CwAAAAAwBuB6ZnAc3vHP11l6gl2Nyjpl0vAHGefdvKegPJLacEIB332Xn0EnlF94R1qKk4MUdXgcFALPA&tag=1](https://ieeexplore.ieee.org/stamp/stamp.jsp?arnumber=868688&casa_tok=gn523BGFY2CwAAAAAwBuB6ZnAc3vHP11l6gl2Nyjpl0vAHGefdvKegPJLacEIB332Xn0EnlF94R1qKk4MUdXgcFALPA&tag=1)
- + Flexible to choice of affinity matrix
- + Generally works better than other methods
- - Can be expensive, especially with many cuts.
- - Bias toward balanced partitions
- - Constrained by affinity matrix model

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## Image segmentation



### How? -> Computer Vision's era

#### Segmentation as energy minimization

- Main idea
  - Markov Random Fields (MRFs) and Conditional Random Fields (CRFs)
    - Rich probabilistic model for images
    - Built in local, modular way - Get global effects from only learning/modeling local ones
    - After conditioning, get a Markov Random Field (MRF)
- Algorithms
  - Grab-Cut (2004)
- See
  - Boykov, Y., Veksler, O., & Zabih, R. (2001). Fast approximate energy minimization via graph cuts. *IEEE Transactions on pattern analysis and machine intelligence*, 23(11), 1222-1239. <http://utluu.cs.uuic.edu/~daf/courses/Opt-2017/combinatorialpapers/00569314.pdf>
- + Very powerful, get global results by defining local interactions
- + Very general
- + Rather efficient
- - Only works for sub modular energy functions (binary)
- - Only approximate algorithms work for multi-label case

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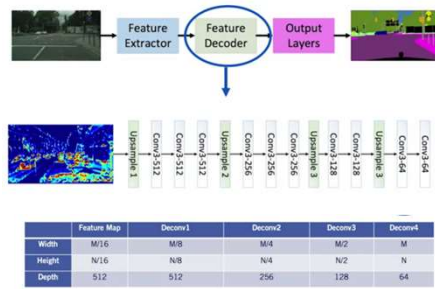
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## Image segmentation

### Learning same resolution feature maps

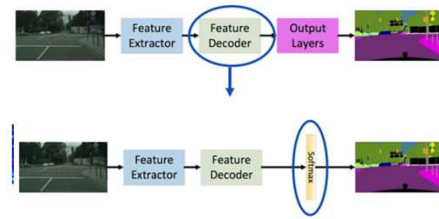


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## Image segmentation

### Output computation



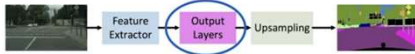
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## Image segmentation

### Fully convolutional networks

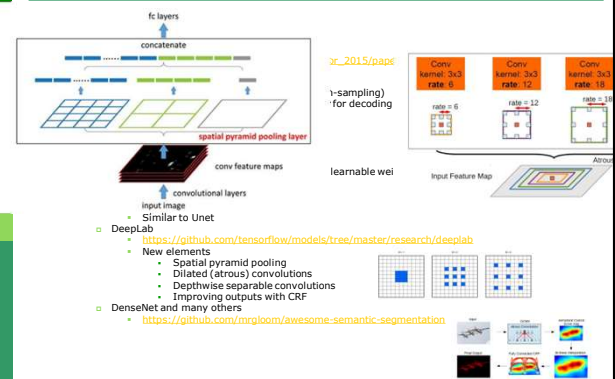
- Feature extraction by convolutions (down-sampling / encoder path)
  - Extract and interpret the context (what?)
- Segmentation map by recovering spatial information by convolutions (up-sampling / decoder part)
  - Enable precise location (where?)
  - Transform FC layers from a classification architecture into 1/more convolutions (deconvolutions or transposed convolutions) -> up-sampling
- Skip connections
  - Recover the fine-grained spatial information lost in pooling or down-sampling layers
  - Merge (concatenate or sum) more feature maps from the down-sampling path with feature maps from the up-sampling path
    - Helps combining context information with spatial information



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## Image segmentation

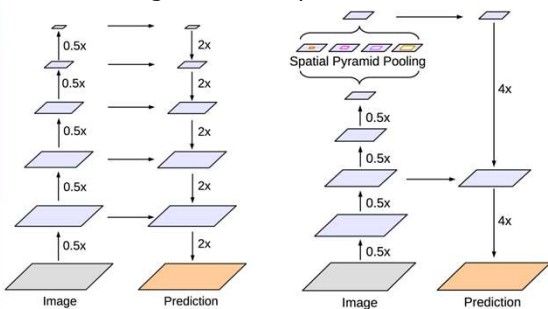


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## Image segmentation

### Unet / SegNet vs DeepLab



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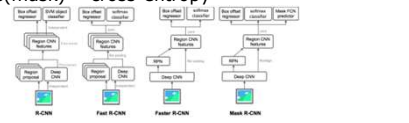
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## Image segmentation

### Mask R-CNN

- <https://arxiv.org/pdf/1703.06870.pdf>

- Similar to Faster R-CNN, but predict masks as well as BBs
  - a Fully CNN (on top of feature map) for determining a binary mask (object or not) for each RoI
  - RoI Alignment -> bilinear interpolation
- Loss = Loss(classific) + Loss(bb) + Loss(mask)
  - Loss(mask) = cross-entropy



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## Image segmentation

### □ Detectron

- Feature extraction
  - Feature pyramid network
  - Different backbones (ResNet)
- Proposal generator
  - Region proposal network
- Target tasks
  - BB prediction
  - BB classification
  - Pixel-level classification inside a BB (segmentation)
- Loss = Loss(classific) + Loss(bb) + Loss(mask)
  - Loss(mask) = cross-entropy
  - Focal loss
- Non-local NN <https://arxiv.org/pdf/1711.07971.pdf>
  - Long-range dependencies
    - Recurrent operations (repeated convolutions = local neighbourhood)
    - Non-local operations
      - Mean of all positions of an input => a very large receptive field
      - Self-attention (machine translation)
      - CRF (graphical models)



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## Image segmentation

### □ YOLACT (You Only Look At CoefficientTs)

- <https://github.com/dbolya/yolact>
- <https://arxiv.org/pdf/1904.02689.pdf>

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### □ Vision Transformers (ViT)

- reducing architecture complexity
- exploring scalability and training efficiency
- **An Image is Worth 16x16 Words**
  - <https://arxiv.org/pdf/2010.11929.pdf>
  - <https://ai.facebook.com/research/publications/end-to-end-object-detection-with-transformers>
  - NLP transformers <http://jalamar.github.io/illustrated-transformer/>
- [https://github.com/google-research/vision\\_transformer](https://github.com/google-research/vision_transformer)

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## Image segmentation

### □ More details

- <https://arxiv.org/pdf/2001.05566.pdf>
- <https://heartbeat.fritz.ai/a-2019-guide-to-semantic-segmentation-ca8242f5a7fc>
- <https://paperswithcode.com/sota/instance-segmentation-on-coco>
- <https://link.springer.com/article/10.1007/s13735-020-00195-x>

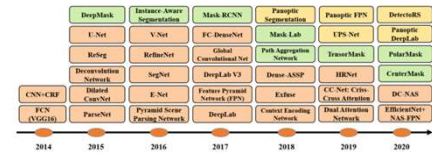


Fig. 30. The timeline of DL-based segmentation algorithms for 2D images, from 2014 to 2020. Orange, green, and yellow blocks refer to semantic, instance, and panoptic segmentation algorithms respectively.

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## Image segmentation

### □ Segmentation

- partitioning an image into meaningful segments, which share a common representation.
- Dense pixel prediction -> it classifies each pixel into one of a few classes

### □ Semantic segmentation

- Segment all interest objects (by different classes = semantic classes)

### □ Instance segmentation

- Segment all interest objects (by different classes = semantic classes)
- Predict an instance label for each object of interest

### □ Panoptic segmentation

- Instance segmentation of all interest objects (by classes) and the background

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## Image segmentation

### □ Semantic segmentation



Input



Output

Legend

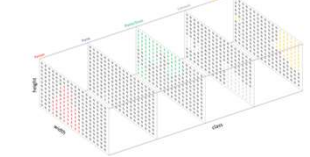
1: Person

2: Park

3: Background

4: Sky

5: Water



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