# **Specification**

We shall define a class named DirectedGraph representing a directed graph.

The library contains external function related to the creation and display of a DirectedGraph object, using a list-of-edges representation:

# def generate\_random\_graph(n, m, file\_path):

generates a random graph with a given number of vertices and edges. The cost will be an integer from the interval [0, 1.000.000]. If the number of edges is invalid an error will be raised. The graph will be written in the text file having the path file\_path.

### def read\_graph(file\_path):

reads a graph from a text file with the path *file\_path*.

# def print\_graph(G, option):

prints a <code>DirectedGraph</code> object depending on the option of the user. If <code>option == False</code>, the graph will be displayed on the console. Otherwise, the graph will be written in the <code>graph\_modif.txt</code> file. The graph is represented as a list of edges (associated to their costs).

Some classes of exceptions that are used in order to raise logical and input errors are:

#### Class VertexError(Exception):

thrown when a vertex that should be added in the list of vertices of a DirectedGraph object  $g.\_vertices$  already exists in it.

### Class NonexistentVertexError(Exception):

thrown when applying an operation on a vertex that does not exist in the list of vertices of a *DirectedGraph* object *g.\_\_vertices*.

# Class EdgeError(Exception):

thrown when an edge that should be added in the list of edges of a *DirectedGraph* object *g.\_\_edges* already exists in it.

# Class NonexistentError(Exception):

thrown when applying an operation on an edge that does not exist in the list of edges of a *DirectedGraph* object *g.\_\_edges*.

### Class InvalidEdges(Exception):

thrown when the number of edges inputted is greater than the provided number of vertices (Condition for a directed graph that admits loops:  $E \leftarrow V^2$ )

The class DirectedGraph will provide the following methods:

#### def add\_vertex(self, x):

adds a vertex to the graph. If the vertex already exists in the graph, *VertexError* will be raised.

#### def remove\_vertex(self, x):

removes a vertex from the graph. All edges containing x as the origin or target vertex, The outbound and inbound lists of x will be deleted (using  $self.remove\_edge()$ ). If x is not a vertex, NonexistentVertexError will be raised.

#### def add\_edge(self, x, y, c):

adds an edge to the graph. If **x** or **y** are not vertices **NonexistentVertexError** will be raised. If the edge already exists in the graph, **EdgeError** will be raised.

### def remove\_edge(self, x, y):

removes a given edge from the graph. Its cost, y as the outbound of x and x as the inbound of y will be deleted. If x or y are not vertices, NonexistentVertexError will be raised. If (x, y) is not an edge, NonexistentEdgeError will be raised.

# def update\_edge(self, x, y, new\_cost):

updates the cost of an edge. If there is no x or y vertex, NonexistentVertexError will be raised. If (x, y) is not an edge, NonexistentEdgeError will be raised.

### def is\_edge(self, x, y):

checks if there is an edge in the graph that has the origin x and the target y (returns *True* if it finds the given edge, *False* otherwise). If x or y are not vertices, *NonexistentVertexError* will be raised.

### def in\_degree(self, x):

returns the in degree of a vertex x. If x is not a vertex, NonexistentVertexError will be raised.

# def out\_degree(self, x):

returns the out degree of a vertex x. If x is not a vertex, NonexistentVertexError will be raised.

## def copy(self):

returns a deepcopy of the graph.

# **Implementation**

Class *DirectedGraph* will have the following data members:

## self.\_\_vertices = []

represents the list of the vertices.

### self.\_\_edges = []

represents the list of the edges.

```
self.__costs = {}
```

represents a dictionary associated to the costs of each edge. **self.\_\_costs[e]** represents the cost of the edge **e**.

```
self.__outbound = {}
```

represents a dictionary associated to the outbound neighbours of each vertex.

self.\_\_outbound[v] represents the list of outbound neighbors of the vertex v.

```
self.__inbound = {}
```

represents a dictionary associated to the inbound neighbours of each vertex.

self. \_inbound[v] represents the list of inbound neighbors of the vertex v.

The data members are initialized using  $self.add\_vertex(x)$  and  $self.add\_edge(x, y, c)$ :

```
constructor
def __init__(self, vertices, edges):
    self.__vertices = []
    self.__edges = []
    self.__costs = {}
    self.__outbound = {}
    self.__inbound = {}

    for vertex in vertices:
        self.add_vertex(vertex)

    for edge in edges:
        self.add_edge(edge[0], edge[1], edge[2])
```

The parsing of a *DirectedGraph* object is done using ite

```
ITERATORS
"""

def parse_vertices(self):
    return [vertex for vertex in self.__vertices]

def parse_edges(self):
    return [edge for edge in self.__edges]

def parse_inbound(self, x):
    return [y for y in self.__inbound[x]]

def parse_outbound(self, x):
    return [y for y in self.__outbound[x]]
```