

Dr. Sabrina Appel, Accelerator Physics Department, GSI, Darmstadt

Outline



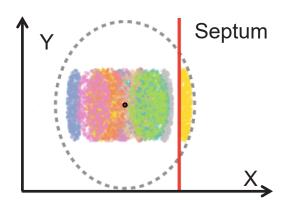
- Nature-inspired optimization
- Evolutionary algorithm
- Particle swarm optimization



- Machine Learning
 - Linear Regression
 - Artificial Neural Networks

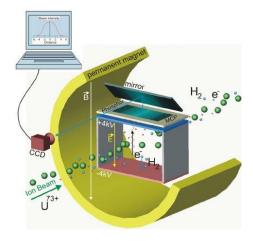


- Example optimization problem:
 - Multi-Turn Injection



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- Example Machine Learning
 - Beam profile reconstruction



Outline



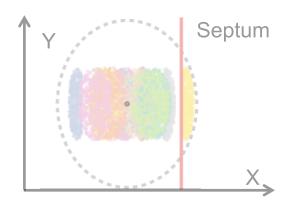
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- **Evolutionary** algorithm
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- **Machine Learning**
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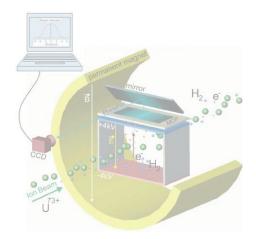


- **Example optimization problem:**
 - Multi-Turn Injection



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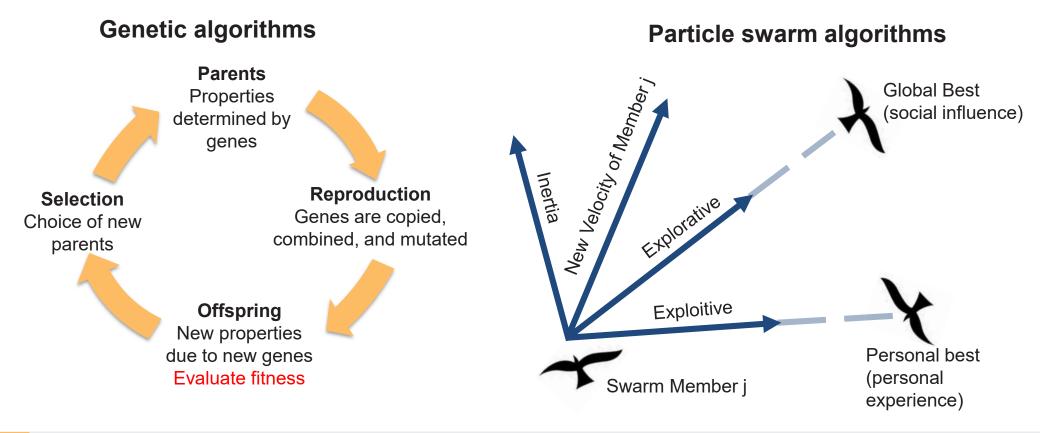
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Nature-inspired optimization



- Search for solutions using techniques such as mutation, selection and crossover
- Nature-inspired algorithms are smart parameter scans
- The fitness measures how good an individual is adapted



Outline



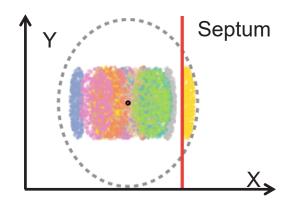
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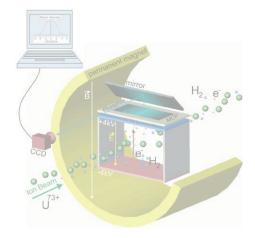
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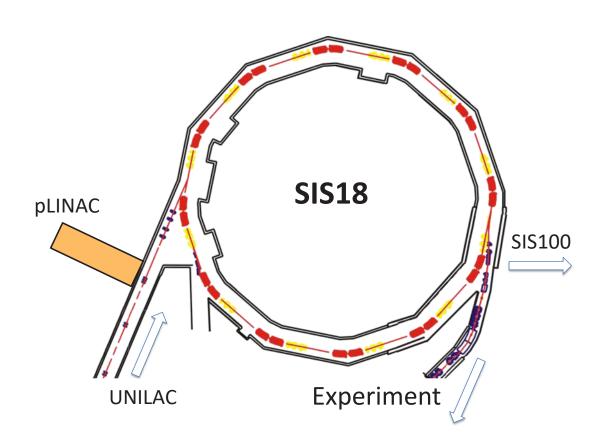


- **Example Machine Learning**
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Heavy-ion synchrotron SIS18



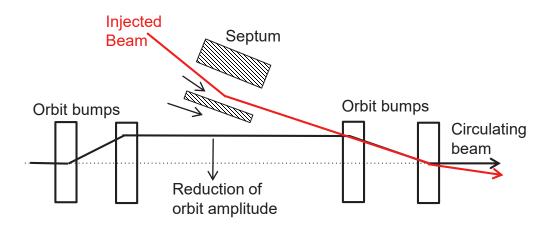


- SIS18 will serve as a booster for SIS100.
- MTI bottleneck to reach intense beams for FAIR.
- Loss-induced vacuum degradation is key intensitylimiting factor.
- Injector upgrade
 - pLINAC: New injector for protons.
 - UNILAC: Replacing of post-stripper section.
- GA optimization has been performed to define interface parameters.



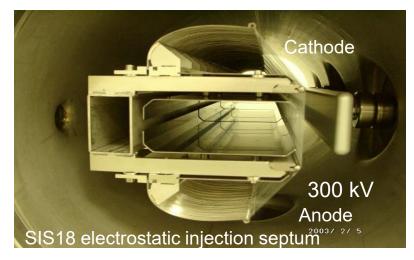


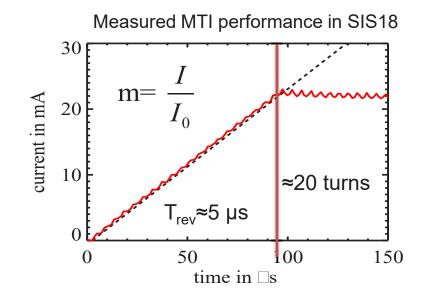
MTI has to respect Liouville's theorem: Injected beams only in free space



Gain factor should be high as possible \$m=\$ Injection loss should be low as possible $$_{\square=}$$

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 nI_0

MTI into SIS18: Model



Multi-objectives:

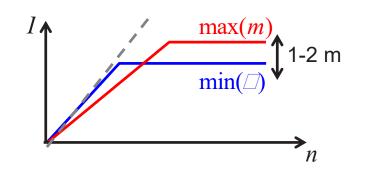
- Gain factor (maximize) $I = mI_0$
- Beam loss (minimize) $\Box = \frac{I_{loss}}{nI_0}$
- Emittance ε_x

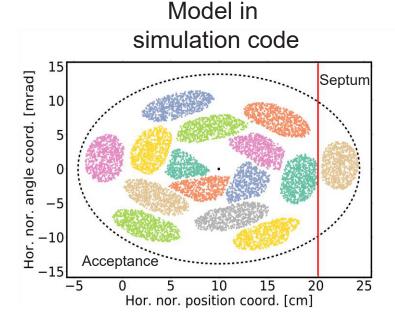


- Position of septum, machine acceptance

Parameters:

- Position of incoming beam at septum
- Initial bump amplitude and its decreasing
- Injected turns
- Horizontal tune and emittance





pyorbit



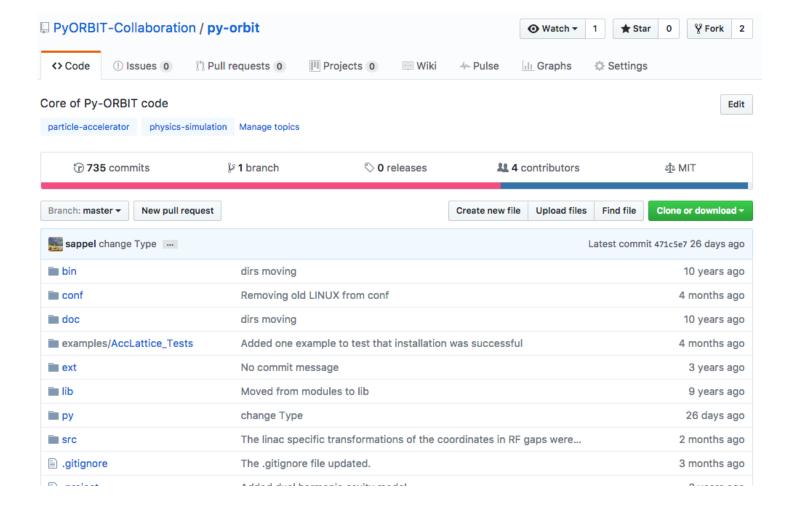
https://github.com/PyORBIT-Collaboration

Open-source hosting

20/10/18

PyORBIT-Collaboration

> SNS, CERN, GSI, J-PARC

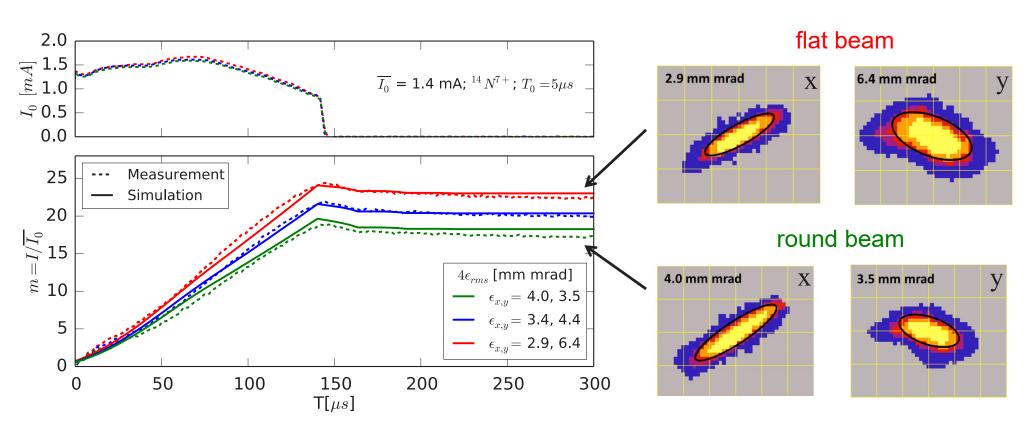




Implementation and validation

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MTI performance has been measured as a function of injector emittance. Round-to-flat transformation with EMTEX Beam line.



Excellent agreement between simulation and measurement!

L. Groening et al: Phys. Rev. Lett. 113 264802 (2014), S. Appel et al: Nucl. Instrum. Methods A 866 (2017), pp. 36-39

Optimization results



Optimization of loss

Genetic algorithms can improve MTI.

Especially for longer injection GA discovers a much better solution.

Optimization of loss and gain factor

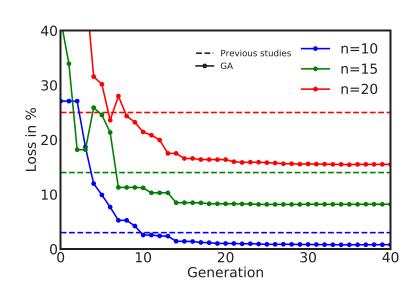
Dependence of gain factor on loss.

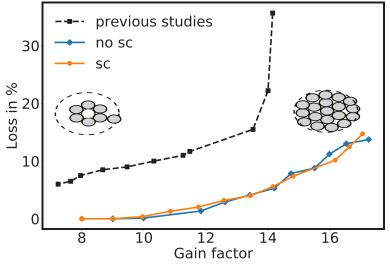
Loss-free injection could be found.

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Space charge results in a similar PA front, but with different injection settings.

MOPSA shown similar result with fast convergence.





Optimization results

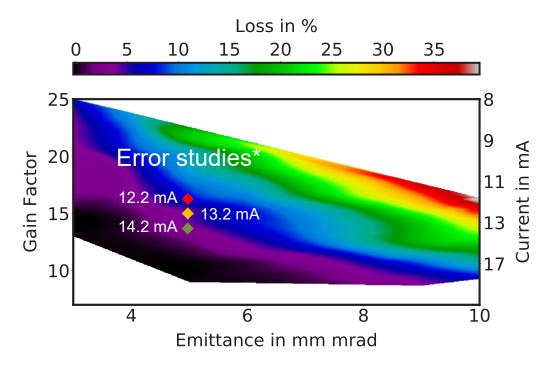


Optimization of loss, gain factor and beam emittance (injector)

Dependence of interface parameter

$$\mathbf{B} = \frac{I}{\square} \qquad \mathbf{m}(\square) = \frac{N}{I} q f_0$$

allows to define a frame, in which the required beam parameter can be matched at best.





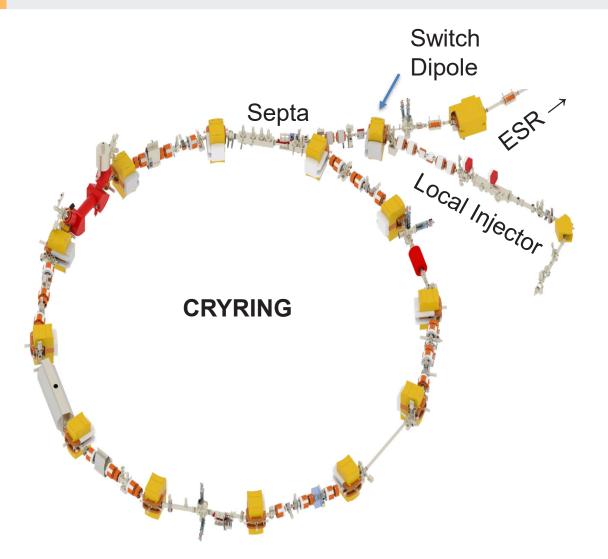
3D Pareto front for proton injector has generated also. pLINAC: Relaxed situation, generous beam parameter margin

S. Appel et al: Nucl. Instrum. Methods A 852 (2017), pp. 73-79 C. Kleffner, LINAC2018, THPO046 (2018)

^{*}A. Rubin, Beam dynamics design of the new FAIR post-stripper linac, GSI Accelerator Seminar, 14.05.17

CRYRING@ESR

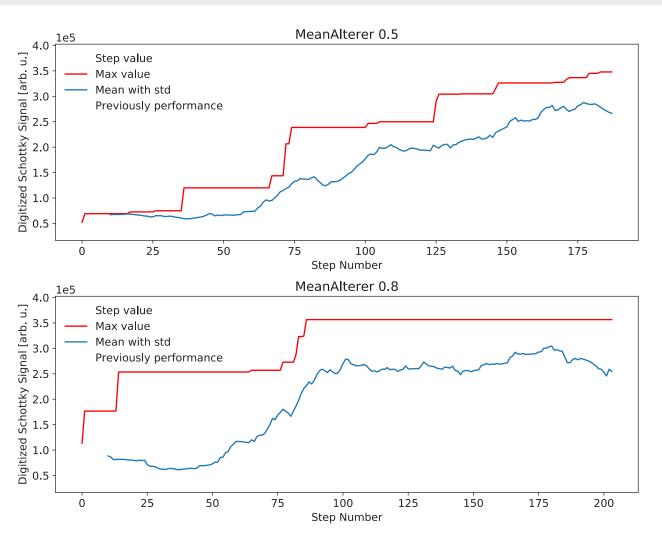




- Swedish in-kind contribution to FAIR
- CRYRING@ESR can be used stand-alone for testing novel technical developments.
- Control system is Java based.
- Jenetics end-user ready software library implementing an genetic algorithm in Java.
- Choice to use Jenetics was obvious although faster algorithm are known.

CRYRING@ESR: Online optimization





Large tournament size has chosen to reach fast convergence.

20/10/18

~ 90 minutes

Outline



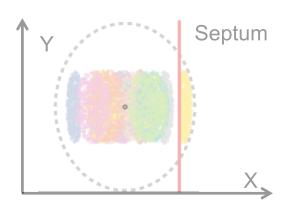
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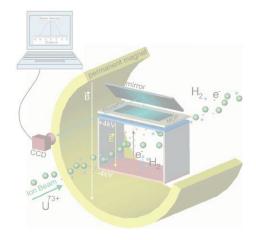


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Machine Learning



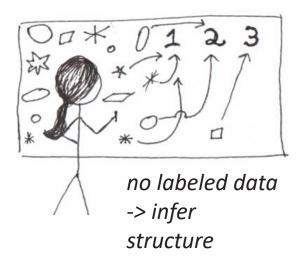
Supervised Learning



learn known input/output pairs

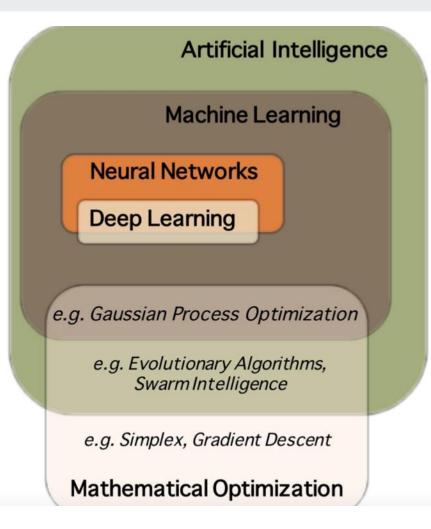


Unsupervised Learning



Reinforcement Learning

interact with the
environment -> adjust
behavior based on reaction



Source: Auralee Edelen, ICFA Workshop on ML for Particle Accelerators, SLAC, 27.02 - 02.03.2018

Machine Learning

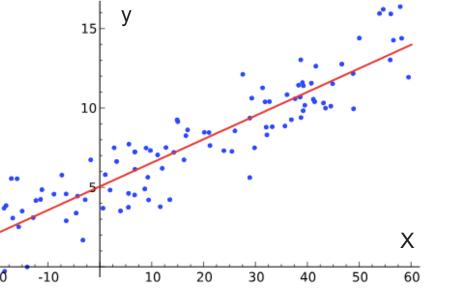


Machine Learning – algorithms which can learn and make predictions on data, without explicit programming.

ML covers many different algorithms with varying complexity from linear approximation to biologically inspired Artificial Neural Networks.

- Linear approach modelling.
- Relationship between scalar dependent variable and explanatory variables.

$$y = W^T x + b$$



Least squares approach is often used for fitting linear regression models.

Artificial Neural Network

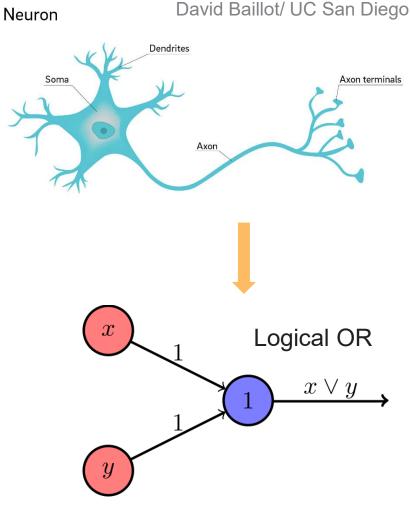


- Biologically inspired.
- The perceptron is a simplified model of a biological neuron.

Perceptron parameters:

- Weights from the inputs (X) and bias (b).
- g is the activation function, a step-like function with a threshold.

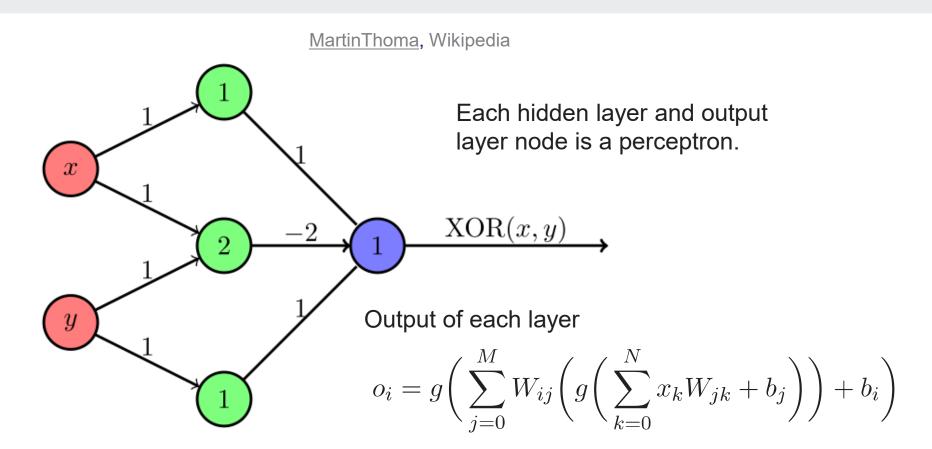
Output
$$o = g \left(\sum_{k=0}^{N} x_k W_k + b \right)$$



MartinThoma, Wikipedia

Artificial Neural Network





Adding "hidden" layer(s) allow non-linear target functions to be represented

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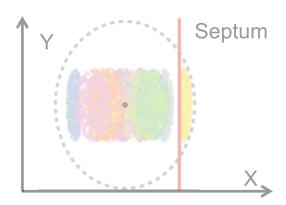
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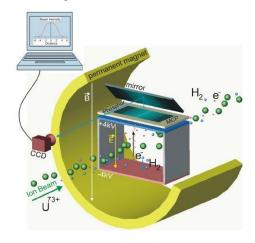
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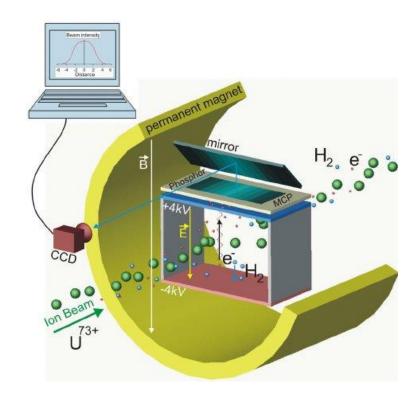


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IPM (Ionization Profile Monitors)

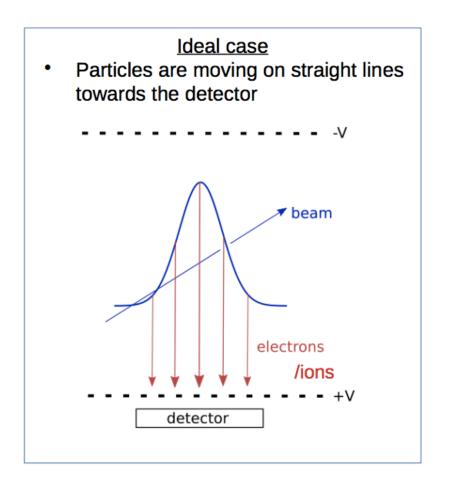


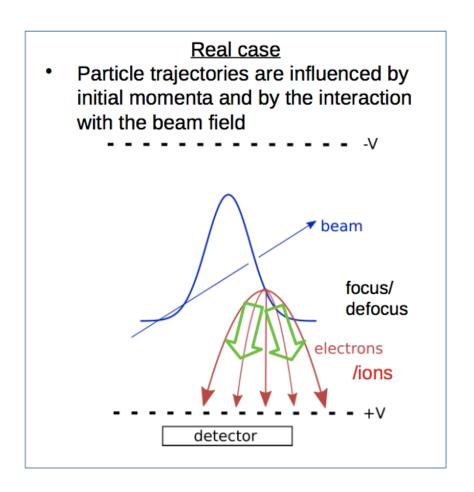
- For optimization and control knowledge of beam parameters is a key ingredient.
- IPM has been constructed first in Argonne National Laboratory in 1967.
- Measures transverse profile of a particle beam.
- Rest gas (pressure 10⁻⁸ mbar) is ionized by the beam.
- Electric field is used to transport electrons/ions to a detector.
- If electrons are used additional magnetic field is usually applied to confine their movement.



Profile Distorsion in IPM



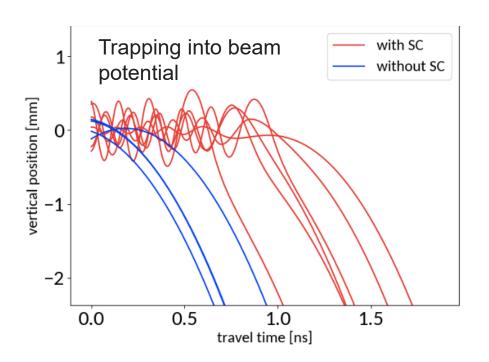


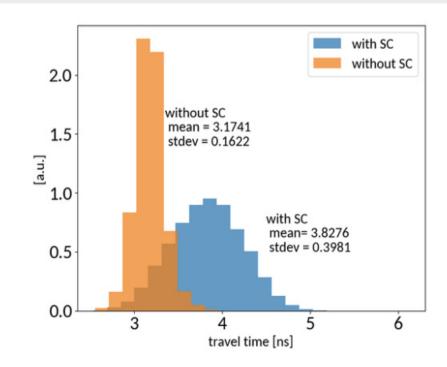


... instrumental effects come on top!

Profile Distorsion in IPM





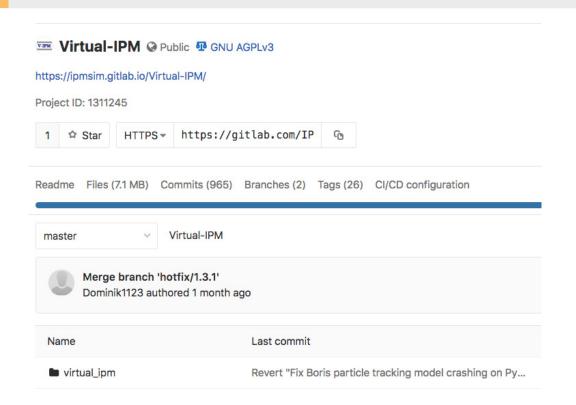


Electrons are trapped in bunch field for the time when bunch passes. They make several oscillations around bunch center. Complex movement!

Several attempts have been made to correct or describe such effects, but no sufficient analytic procedure was found yet.

Virtual-IPM program





Open-source hosting

Code on gitlab:

https://gitlab.com/IPMsim/Virtual-IPM

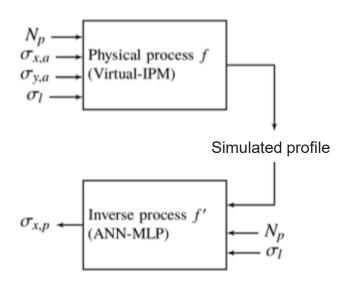
Available as python module:

https://pypi.org/project/virtual-ipm

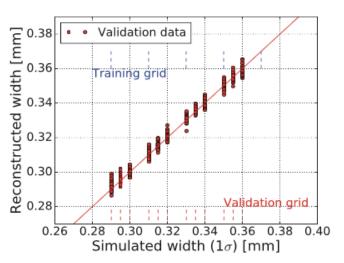
- After looking for a proper program: Decision to write Virtual-IPM.
- Written in Python with modern, modular architecture.
- Covers: IPM, BIF, gas jets.

Profile correction using ANN





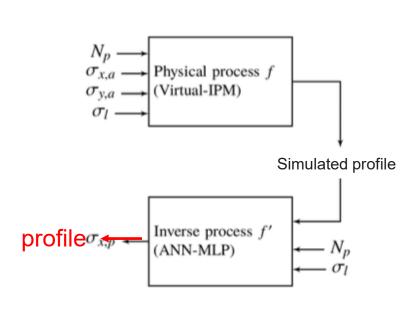
R. Singh, et al, Proc. of IBIC17 (WEPCC06)

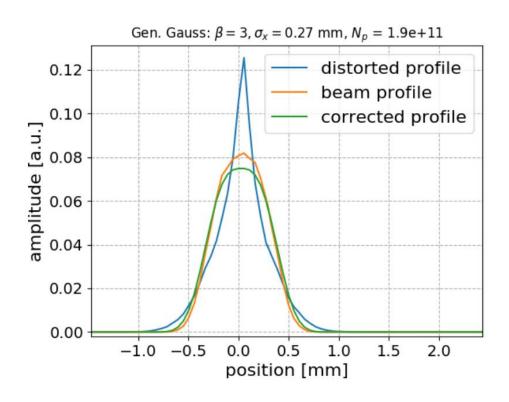


- Virtual-IPM was used for simulating the movement of electrons for a typical LHC case.
- Value of beam size restored with 1% accuracy!
- Good performance with noise.
- Even simple linear regression model showed very promising results for beam width reconstruction.

Profile correction using ANN







Results for Gaussian profiles: Very good profile shape reconstruction.

SIS100: Profile distortion for some beams a profile distortion is expected to be visible and will require a similar correction procedure."

M. Sapinski et al., in Proc. of HB2018, THA2WE02.

Summary

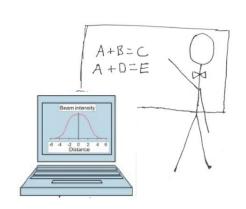


Nature-inspired optimization

- Multi-object optimization: Identification of injector brilliance range.
- Reach after ~1.5 hours of online optimization time previous transmission.
- Potential to reduce the manpower requirements.

Machine Learning

- First investigations, using simulated data, yield promising results.
- Method has a potential to extend usability and reduce cost of IPMs for high brightness beams.
- The application of machine learning to longitudinal Schottky signals is under investigation.



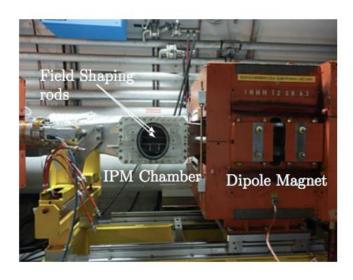


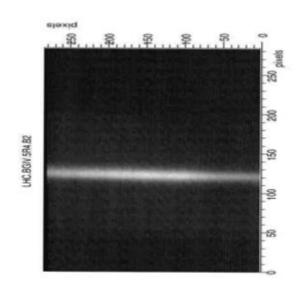
Thank you for your attention

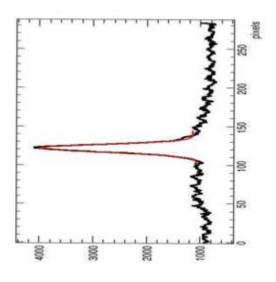
IPM (Ionization Profile Monitors)



IPM installation at LHC



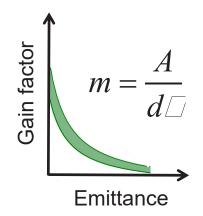




Injector brilliance depending



EMittance Transfer EXperiment (EMTEX)

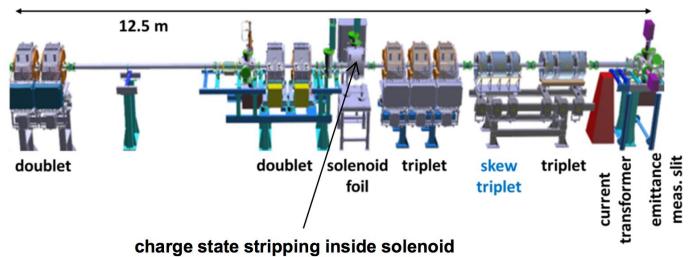


Re-partitioning of beam emittances increase efficiency

Beam flatness amount is controlled by solenoid field

Twiss-parameters are preserved

EMTEX Beam line



L. Groening: Phys. Rev. ST Accel. Beams 14 064201 (2011)C. Xiao et al: Phys. Rev. ST Accel. Beams 16 044201 (2013)

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L. Groening et al: Phys. Rev. Lett. 113 264802 (2014) S. Appel et al: Nucl. Instrum. Methods A 866 (2017), pp. 36-39

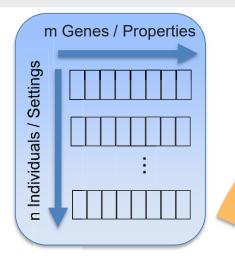
Genetic Algorithms

Selection

Choice of new

parents





Initialize population

Parents

Properties determined by genes

Fitness evaluation measures the individual adaptation

The survival of the fittest leads to an optimization of the properties.

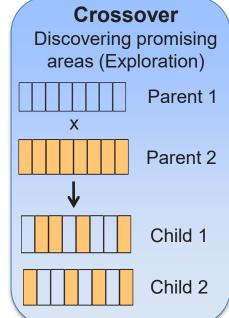
Offspring

New properties due to new genes

End condition

Reproduction

Genes are copied, combined, and mutated



Selection

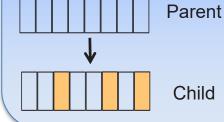
Tournament and ranking selection,





Mutation

Optimizing within promising areas (Exploitation)



Particle swarm algorithms



Inspiration from the "graceful but unpredictable choreography of a bird flock"

Position

$$x_i(t+1) = x_i(t) + v_i(t+1)$$

- Each individual particle position refers to a point in the variable space
- Inertia weight reflects effect of particle current motion
- Personal best; analogous to "nostalgia"
- Cognitive parameter is contribution of particle personal experience
- Global best is the best position ever for entire swarm
- Social parameter reflects publicized C_2 knowledge or social norms
- r₁, r₂ Stochastic elements of the algorithm

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Velocity update

$$x_i(t+1) = x_i(t) + v_i(t+1)$$
 $v_i(t+1) = wv_i(t) + r_1C_1(P_i^l - x_i) + r_2C_2(P^g - x_i)$

Local search Inertia

Global search

