



HSE
Occupational Health & Safety
and Environmental Protection unit



ROMULUSlib

An autonomous, TCP/IP-based, multi-architecture C networking library for DAQ and Control applications

Amitabh Yadav, Hamza Boukabache, Nicola Gerber, Katharina Ceesay-Seitz, Daniel Perrin
CROME Team

Track: Device Control and Integrating Diverse Systems I

18/10/2021 - ICALEPCS 2021, Beijing, China.

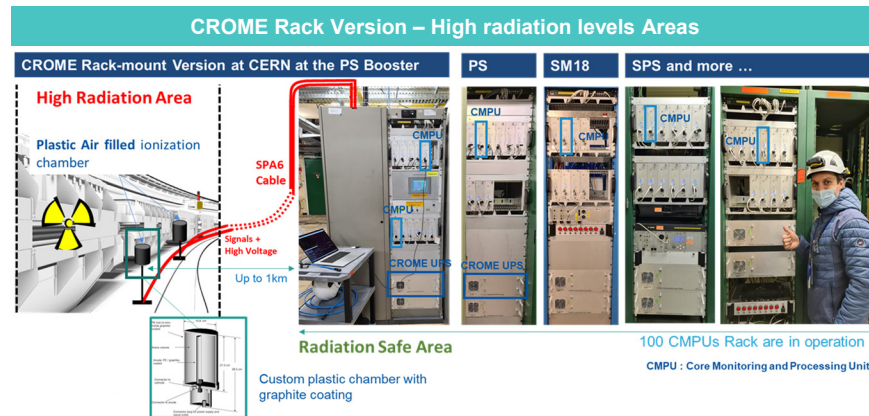
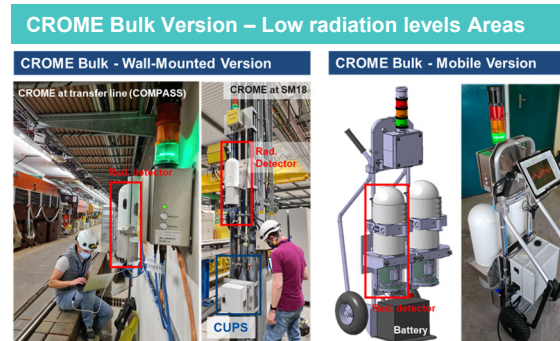
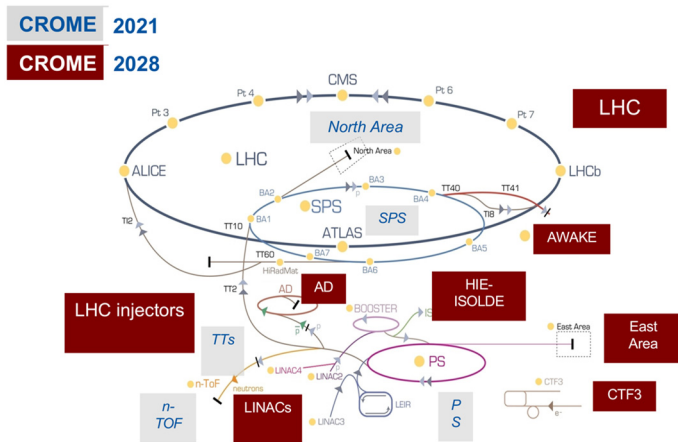
Agenda

- Overview of CROME Radiation Monitors
- Integration of CROME with SCADA supervision
- Motivation for ROMULUSlib
- ROMULUS Protocol
- Architecture and Library Functions
- Applications

CERN RadiatiOn Monitoring Electronics (CROME)

CROME: The new generation of Radiation Monitoring and Alarm and Interlock generation system.

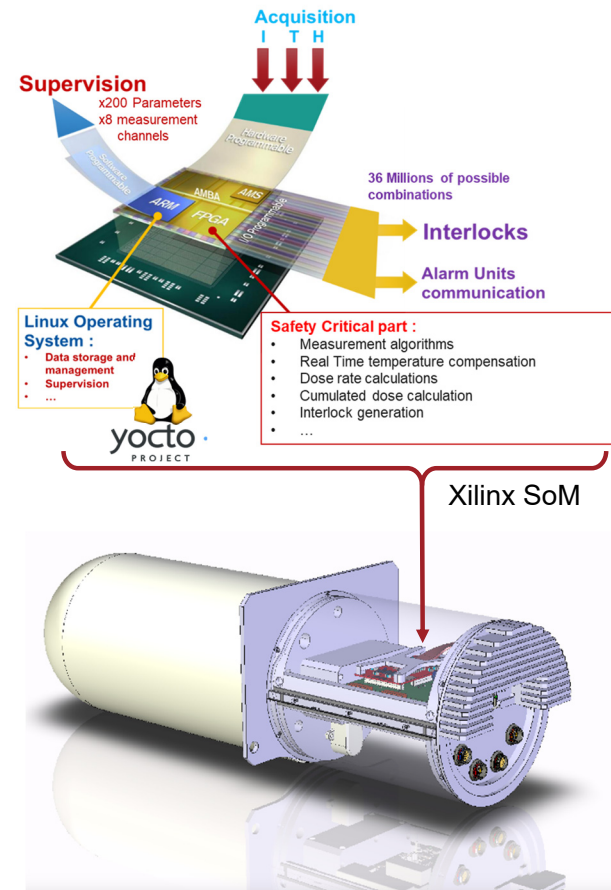
Bulk - Wall Mounted System - Low Radiation levels areas.
Rack System with SPA6 cable - High Radiation levels areas.



H. Boukabache et al., "Towards a novel modular architecture for cern radiation monitoring," Radiation protection dosimetry, vol. 173, no. 1-3, pp. 240–244, 2017.
C. Toner et al., "Fault resilient fpga design for 28 nm zynq system-on-chip based radiation monitoring system at cern," Microelectronics Reliability, vol. 100, p. 113 492, 2019.

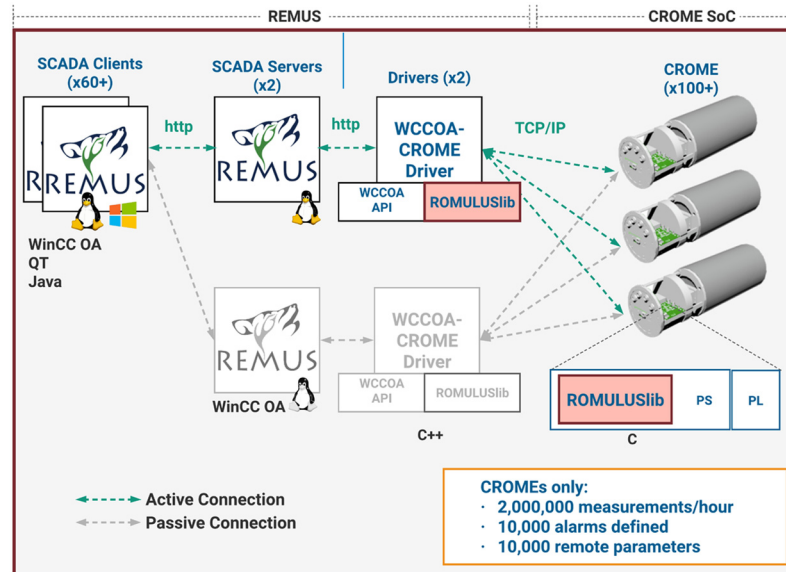
CERN RadiatiOn Monitoring Electronics (CROME)

- Employs Radiation Detector connected to the DAQ electronics based on Zynq-7000 Series SoC
- A custom-built embedded linux OS on 32-bit ARM PS core. PS-PL integration implemented on shared-BRAM memory.
- PS is responsible for communication of more than 200 parameters across 8 measurement channels with REMUS/SCADA supervision system via TCP/IP.
- Safety critical operations including Alarms and Interlocks implemented on PL FPGA fabric.



Integration of CROME with REMUS/SCADA Supervision

- REMUS is based on WinCC Open Architecture allows for display of near real-time measurements, alarms statuses and operational states of connected devices.
- CROME communicates with REMUS via TCP/IP protocol over the CERN Technical Network.
- The need for reliable connectivity and logging capabilities motivated the development of a dedicated TCP/IP-based C networking library, ROMULUSlib.
- REMUS currently handles 2 millions measurements/hour using ROMULUSlib from the CROME devices currently operational at CERN.
- ROMULUSlib rests on top of WinCC OA API and forms the interface between CROME devices and REMUS.



Courtesy of Adrien Ledoul

ROMULUSlib: A portable C networking library for SoC to SCADA communication

Motivation for ROMULUSlib:

- PLC-to-SCADA control systems for LHC Cryogenics control in accelerator and experimental control, Gas systems, Cooling systems, HVAC etc.
- SoC-to-SCADA systems employed in DAQ and Control systems in ATLAS, CMS, ALICE and other experiments.
- Some libraries for communication over Ethernet:
Profinet, Ethernet IP, Quasar (based on OPC UA), MODBUS TCP/IP etc.

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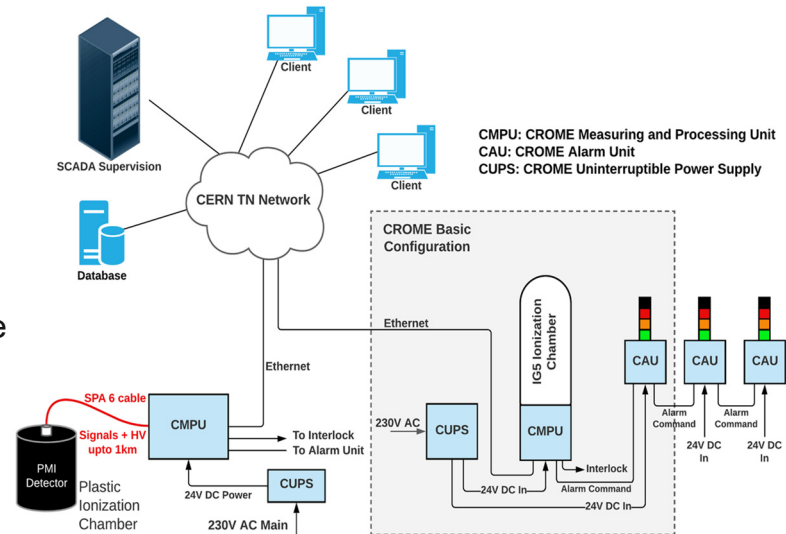
ROMULUSlib offers:

- A full-fledged reliable variable frame-length TCP/IP communication.
- Built completely in C and uses sockets, a part of POSIX standard for compliant OS for multi-architecture support.
- Allows for multi-user full-duplex communication with CROME devices through SCADA supervision and/or an 'expert application' connected to the devices through the network via Ethernet connection.
- ROMULUSlib is built and tested successfully with:
 - gcc 4.8.5 on x84_64,
 - arm32, and
 - with Apple clang version 11.0.3 on x86_64 Darwin MacOS Kernel 19.4.0.

ROMULUS TCP/IP Communication Protocol (1)

ROMULUSlib provides:

- Functions to perform full-fledged TCP/IP Networking.
- TCP/IP frame construction for different measurement channels.
- Multiple Communication Modes to transmit single, multiple and (possibly) infinite frames for streaming data over multiple channels.
- Multiple utilities:
 - Functions for log reporting of warnings and errors,
 - Print functions: ROMULUS frame, Measurement Struct etc.
 - Checksum functions etc.



ROMULUS TCP/IP Communication Protocol (2)

Modes of Communication:

- **Simple Request-Response Scheme**

Single request frame responded to with single response frame.

Simple Request-Response Scheme:

Supervision	Direction	Measurement Device
1 frame of ROMULUS_STATUS_REQUEST	→	
	←	1 frame of ROMULUS_STATUS_RESPONSE

ROMULUS TCP/IP Communication Protocol (2)

Modes of Communication:

- **Simple Request-Response Scheme**

Single request frame responded to with single response frame.

- **Complex Request-Response Scheme**

1. *Real Scheme:*

- Single request frame responded to with finite multiple response frames.
- The last response frame is always fixed to indicate the end of the communication.

2. *Streaming-like Scheme:*

- Single request frame responded to with possibly infinite response frames.
- Breaks to the connection or stop command by supervision terminates the stream.

Simple Request-Response Scheme:

Supervision	Direction	Measurement Device
1 frame of ROMULUS_STATUS_REQUEST	→	
	←	1 frame of ROMULUS_STATUS_RESPONSE

Real Request-Response Scheme:

Supervision	Direction	Measurement Device
1 frame of ROMULUS_DATA_REQUEST	→	
	←	0 to n frames of ROMULUS_DATA_RESPONSE
	←	1 frame of ROMULUS_DONE_RESPONSE

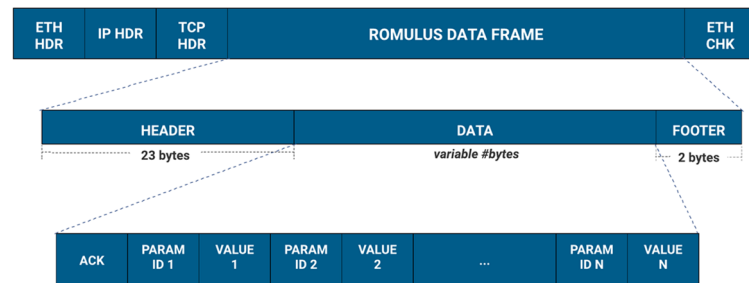
Streaming-Like Scheme:

Supervision	Direction	Measurement Device
1 frame of ROMULUS_RTSTREAM_REQUEST	→	
	←	0 to infinite frames of ROMULUS_RTSTREAM_RESPONSE
1 frame of ROMULUS_RTSTREAM_RESPONSE	←→	1 frame of ROMULUS_RTSTREAM_RESPONSE

ROMULUSlib Library Architecture (1)

ROMULUS TCP/IP data frame

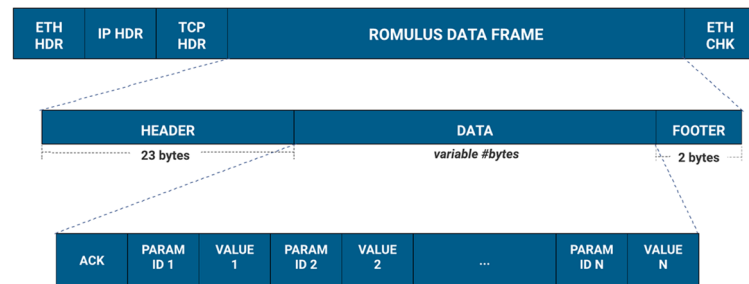
- 1500 bytes of TCP/IP frame.
- TCP and IP headers, ROMULUS data frame is set, and ETH checksum.
- ROMULUS data frame has 23 bytes header for information for device identity and the command ISA.
- The data packet within ROMULUS data frame stores contents that are individually defined for each command and command type.
- ACK acknowledge bits for most response commands.
- CheckSum footer.



ROMULUSlib Library Architecture (1)

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ROMULUS Measurement Channels

- C Structs to define a measurement channel.
- Supports multiple variables of nearly all C data types.
- Easy update of Struct table for different use cases in DAQ and control.
- 8 defined measurement channels in CROME.

ROMULUSlib Library Architecture (2)

romulus.h

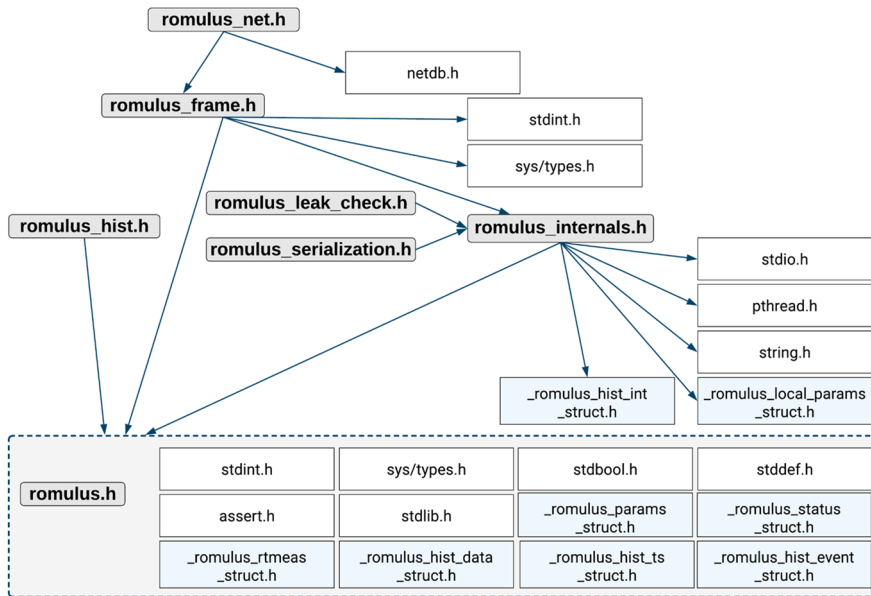
- initialization functions and timestamp
- all data types, structs and debug functions.

romulus_frame.h

- request-response frame construction functions
- frame validity check
- device ID generation

romulus_net.h

- networking
- send, receive functions for TCP/IP



romulus_internals.h

- internal data structures management.
- printing and I/O
- checksum

romulus_hist.h

- historics data/event management.

romulus_leak_check.h

- optional header file for memory leak check functions.

romulus_serialization.h

- data read functions.

ROMULUSlib build instructions and Utility functions

To use ROMULUSlib for your DAQ and Control applications, follow the following 3 simple steps:

1. Update measurement channels in .gen files.
1. Run the Make script for after specifying target architecture for cross-compile.
This automatically generates necessary C Struct files for your use case and generates executables and symbolic link files to be installed in /usr/lib.
1. Import ROMULUSlib into your Embedded User Space application to make use of ROMULUSlib's TCP/IP networking functions, starting with `romulus_init()`.

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```
1| ROMULUS_LEAD_IN(** @brief to be done @ingroup romulus_structs *)  
2|  
3| STATUS_DEF(Timestamp, int64_t, /**< Timestamp of the specific sample measured in miliseconds since POSIX epoch. */)   
4|  
5| STATUS_DEF(Temperature, float, /**< Same as romulus_rtmeas_t#Temperature. */)   
6| STATUS_DEF(Humidity, float, /**< Same as romulus_rtmeas_t#Humidity. */)   
7|  
8| STATIC_DEF(CALLSTATUS, int32_t, /**< Status of the CALL. The CALL status is decoded as follows: bit 1 denotes 0 from the
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5 STATUS_DEF(Temperature, float, /**< Same as romulus_rtimeas_t#Temperature. */)
6 STATUS_DEF(Humidity, float, /**< Same as romulus_rtimeas_t#Humidity. */)
7
8 STATIC_DEF(CALIBRATION, int32_t, /**< Status of the CAL. The CAL status is decoded as follows: bit 1 denotes 0 from the
```

```
amitabh@amitabh-EliteBook-x360: ~/ROMULUSlib
amitabh@amitabh-EliteBook-x360:~$ cd ROMULUSlib/
amitabh@amitabh-EliteBook-x360:~/ROMULUSlib$ export CROSS_COMPILE=arm-linux-gnueabihf-
amitabh@amitabh-EliteBook-x360:~/ROMULUSlib$ make
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8 STATIC_DEF(FAILSTATUS, int32_t, /**< Status of the FAIL. The FAIL status is decoded as follows: bit 1 denotes 0 from the
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```
160 |
161 | logging(stdout, "Initialise network stack and ROMULUSlib...\n");
162 | romulus_init("CHROME Device");
163 | const romulus_param_protection_t* const romulusParametersProtectionMask = _createParameterProtectionMask();
164 | if(romulusParametersProtectionMask == NULL){
165 |     logging(stderr, "Failed to create parameter protection mask\n");
166 |     return EXIT_FAILURE;
167 | }
168 |
169 | romulus_socket_t listeningSocket = romulus_net_listen(localParams.RomulusPort);
170 | if(listeningSocket < 0){
171 |     logging(stderr, "Error while creating listening socket for ROMULUS parameterisation\n");
172 |     return EXIT_FAILURE;
173 | }
174 | else{
175 |     logging(stdout, "Created new socket %i to listen for incoming ROMULUS parameterisations\n", listeningSocket);
176 | }
177 | SocketCollection socketCollection = networkInitCollection();
```

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In order to facilitate debugging, ROMULUSlib provides additional utilities.

1. `remote_stream`: prints the TCP/IP frames for Real-Time Data.
2. `struct_info_printer`: prints all Struct Information as defined by the user.
3. `remote_dump`: prints status parameters, configuration parameters and hist data for specified time duration.

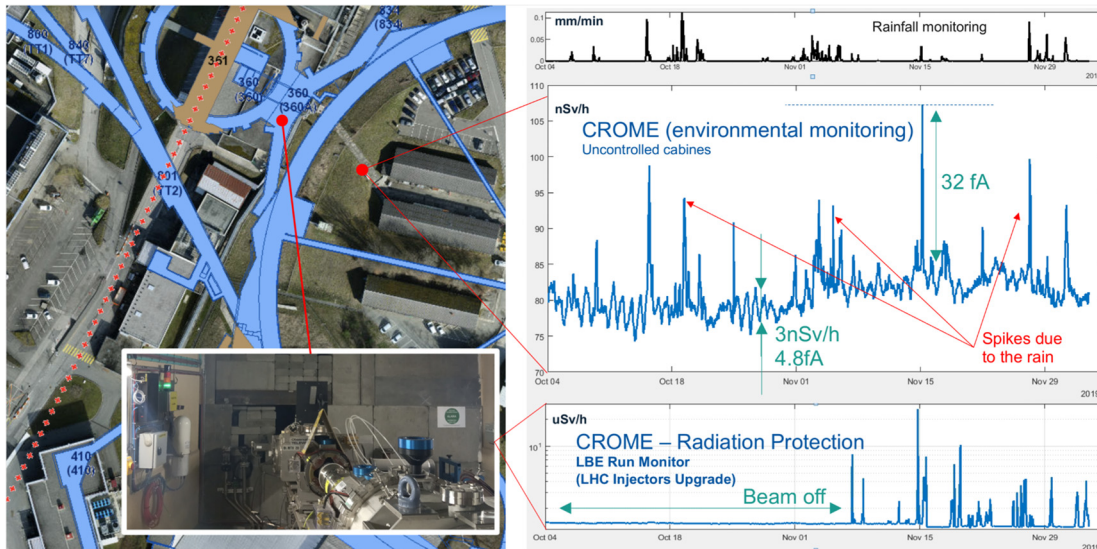
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Applications: CROME device at CERN

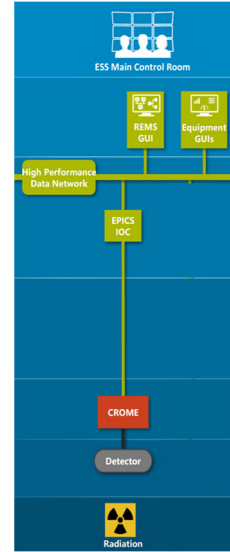
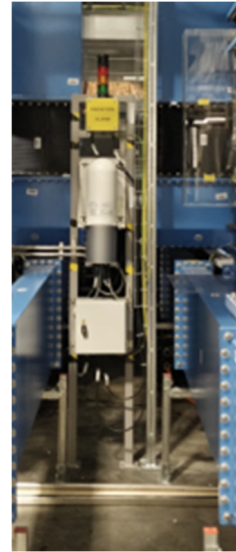
- Currently 150 CROME devices are installed at CERN at various locations.
- All commands/communications sent over CERN TN using ROMULUS protocol implemented in ROMULUSlib.
- Device communication access available to authorized MPs of CERN RP group via REMUS.
- ROMULUSlib_v6.2 in operation.
- **ROMULUSlib_v7** released (in operation from December 2021).
- ROMULUSlib_v1.0 developed and under testing for **CROME CJB**, the intelligent router for experiment interlocks.



H. Boukabache, "CROME remote management of SoC-based radiation monitors both at CERN and ESS,"
System-on-Chip 2nd Workshop - CERN, 2021, <https://indico.cern.ch/event/996093/>

Applications: ROMULUSlib integration with EPICS at ESS

- European Spallation Source (ESS) in Sweden deploys CROME radiation monitors communication using ROMULUS protocol with EPICS framework.
- The ESS' Radiological and Environmental Monitoring System (REMS) uses a two-fold approach:
 - a. InfluxDB and Grafana approach for quick online integration
 - b. EPICS integration for real time DAQ and control.



J. Hast, "ESS use case of the CROME monitor with EPICS," 2nd System-on-Chip Workshop - CERN, 2021, <https://indico.cern.ch/event/996093/>
EPICS: Experimental Physics and Industrial Control Systems

System Reliability through Regression Testing: RomLibEmu

- ROMULUS protocol works through request and response message passing.
- So that, malformed packets cannot create unexpected behaviour of CROME devices.
- An independent test framework, RomLibEmu, is developed in Python 3 for application robustness, reliability and safety.

WEBR01

RomLibEmu: Network interface stress tests for the CERN RadiatiOn Monitoring Electronics (CROME)

by Katharina Ceesay-Seitz

October 20, 2021 9:15 pm - 10:30 pm

K. Ceesay-Seitz, M. Leveneur, H. Boukabache, and D. Perrin, "Romlibemu: Network interface stress tests for the cern radiation monitoring electronics (crome)," in 18th International Conference on Accelerator and Large Experimental Physics Control Systems (ICALPCS 21), 2021.

Conclusion

- ROMULUSlib is a standalone TCP/IP networking library developed in C for POSIX compliant OS for multi-architecture support.
- ROMULUS provides complete functions for customization and data packet construction within the TCP/IP frame.
- Communication support via Single frame, multiple frames or streaming data frames.
- ROMULUSlib integrates seamlessly with SCADA supervision systems like REMUS and EPICS to reliably carrying out millions of data packet transactions every hour.

Thank you for your attention.