



Direct digitization and ADC parameter trade-off for bunch-by-bunch signal processing

Irene Degl'Innocenti
Università di Pisa, CERN

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Outline

- Introduction

- Direct digitization of bunch signals in beam instrumentation
- ADC parameter trade-off



Outline

- Introduction
- Analysis of the error in the energy measurement of a direct digitally acquired pulse signal
 - The effect of a limited sampling rate
 - The effect of a limited sampling resolution
 - A combined SNR expression



Outline

- Introduction
- Analysis of the error in the energy measurement of a direct digitally acquired pulse
- Application example
 - A proposed architecture for the LHC BPM read-out electronics
 - Expected position resolution with commercial ADCs



Outline

- Introduction
- Analysis of the error in the energy measurement of a direct digitally acquired pulse
- Application example
- Summary



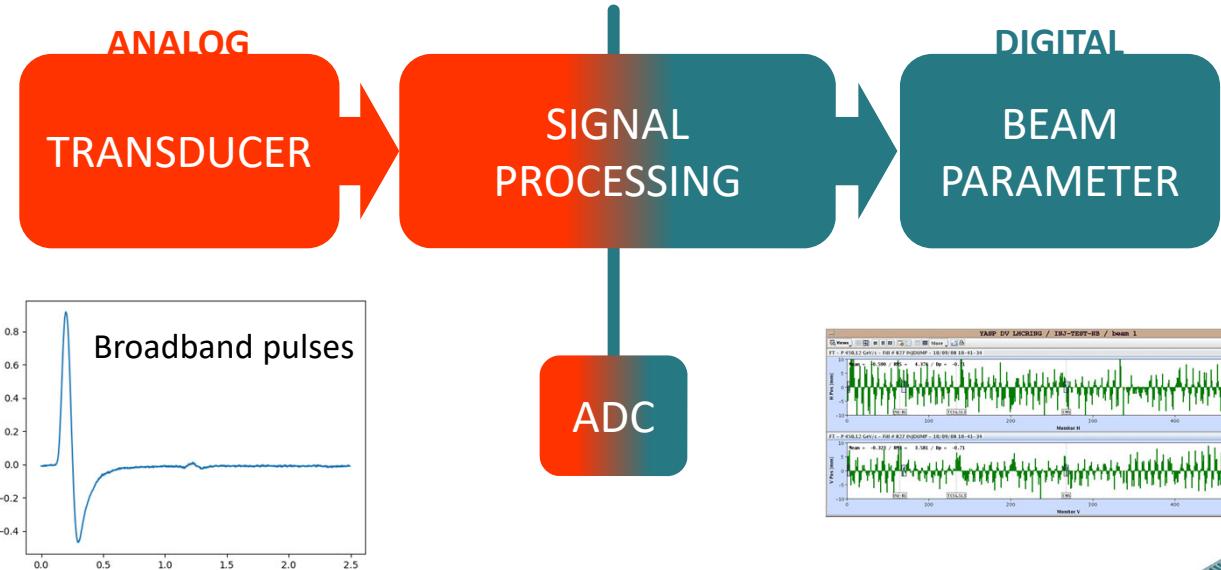


Introduction



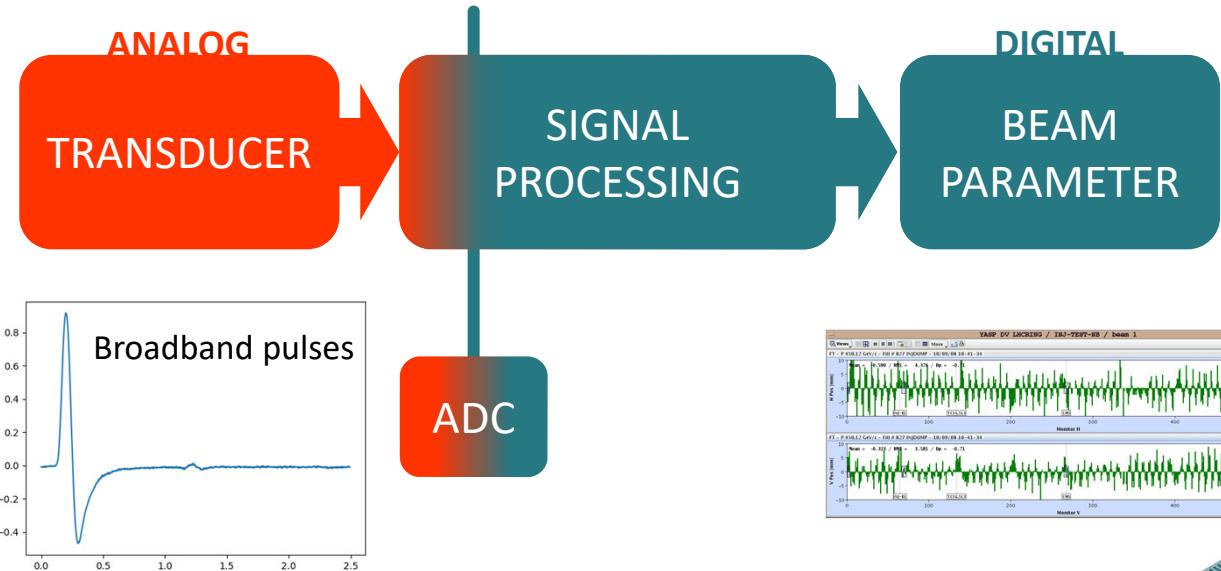
Introduction

Direct digitization in Beam Instrumentation



Introduction

Direct digitization in Beam Instrumentation



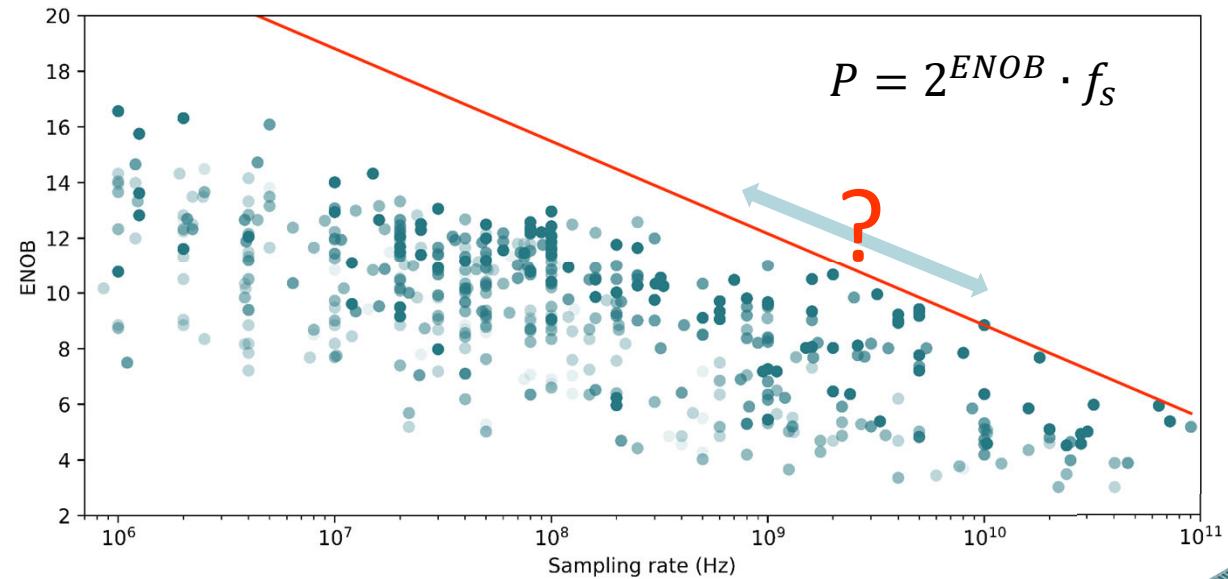
Direct digitization in Beam Instrumentation

- Less analogue components
 - Less parameter spread
 - Less parameter drifts effects
- Reprogrammable algorithms
- BUT demanding requirements in terms of resolution and sampling rate on the digitization stage



Introduction

Analog to Digital Converter trade-off



Data source: B. Murmann, "ADC Performance Survey 1997-2020," [Online].
Available: <http://web.stanford.edu/~murmann/adcsurvey.html>



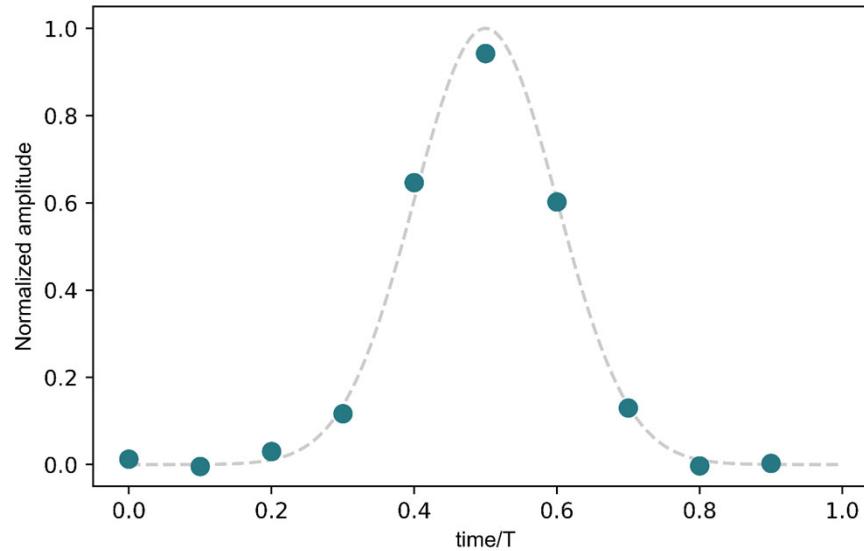


Analysis of the error in the power measurement of a direct digitally acquired pulse signal



Problem Definition

Power measurement of a pulsed signal



$$P_T = \frac{1}{T} \int_0^T |x(t)|^2 dt$$

$$\bar{P}_T = \frac{1}{N} \sum_{n=0}^{N-1} (\hat{x}_{n,\tau} + v_n)^2$$



Problem Definition

Power measurement of a pulsed signal

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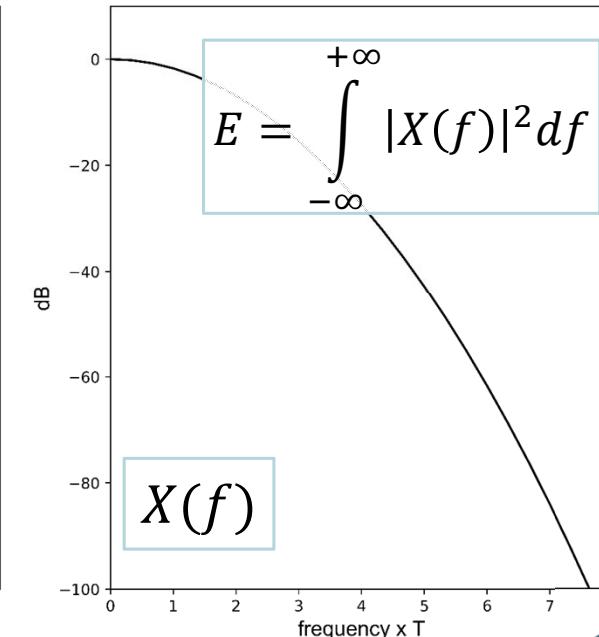
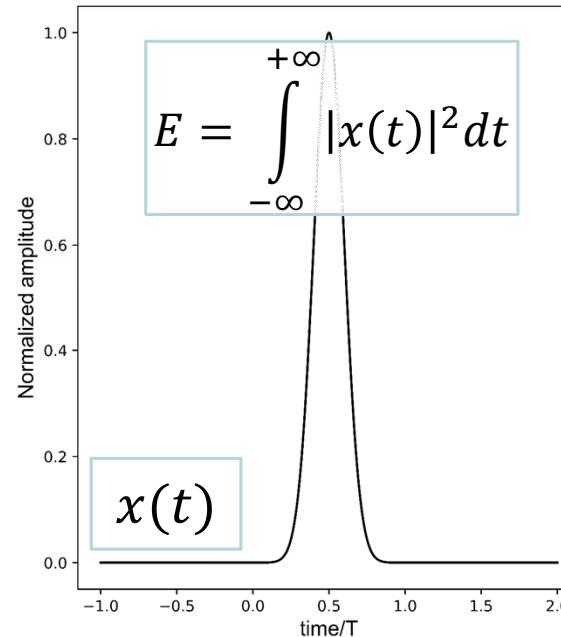
$$\overline{P}_T = \frac{1}{N} \sum_{n=0}^{N-1} (\hat{x}_{n,\tau} + v_n)^2$$

- Is \overline{P}_T a good estimation of P_T ?
 - What is the effect of a limited unsynchronised sampling rate?
 - What is the effect of the finite resolution of the converter?



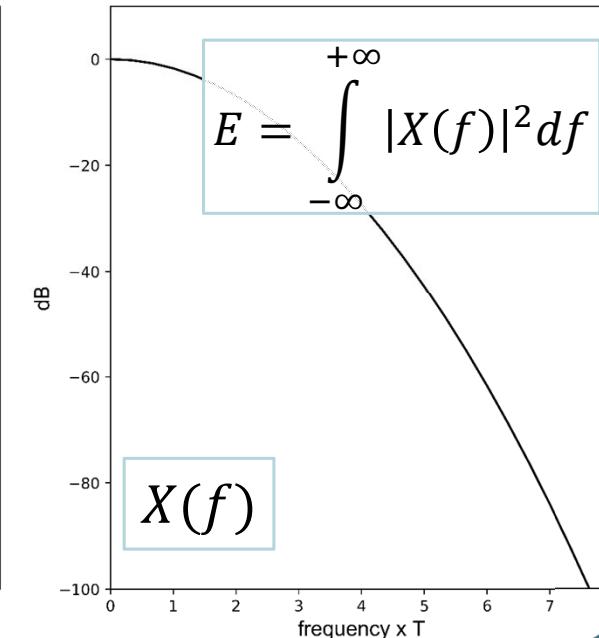
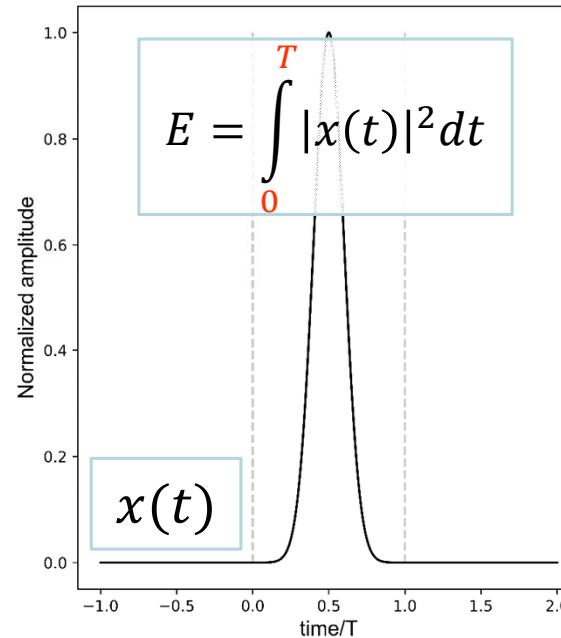
Limited Sampling Rate

Energy and power in time and frequency domain



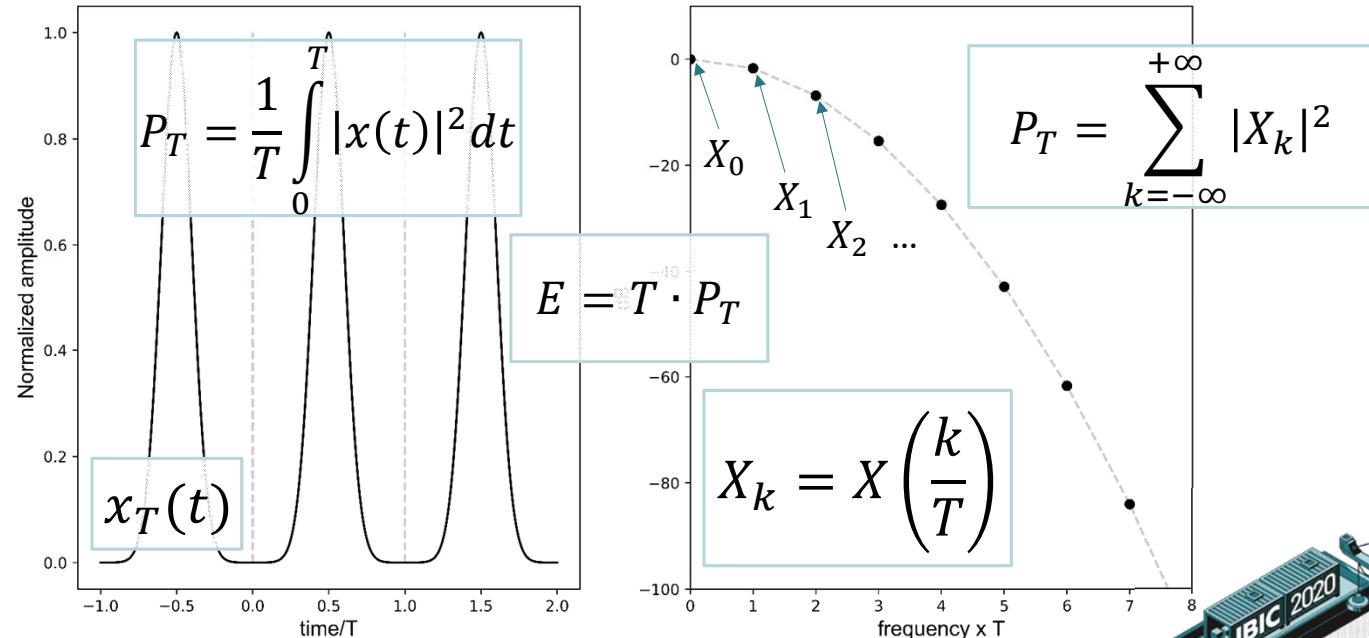
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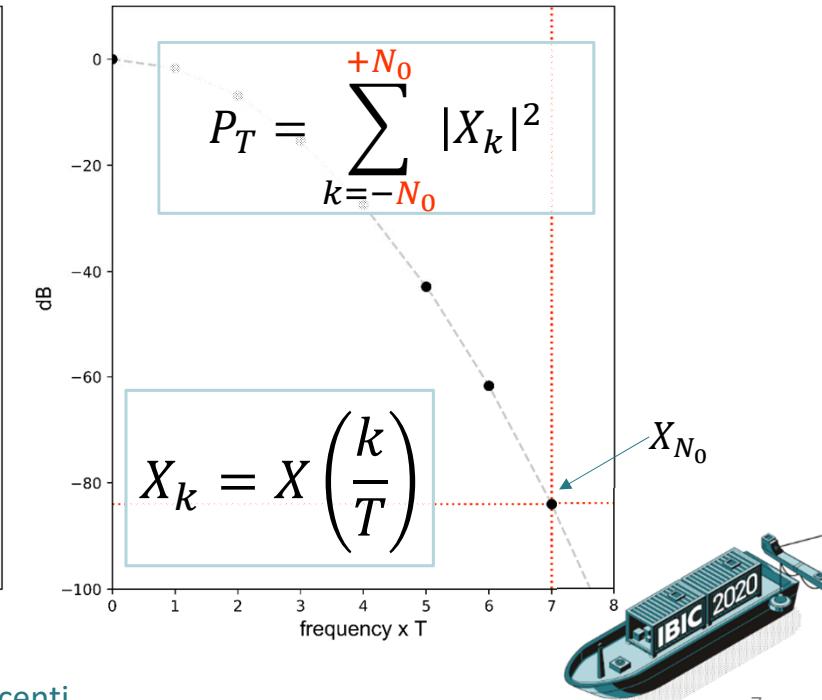
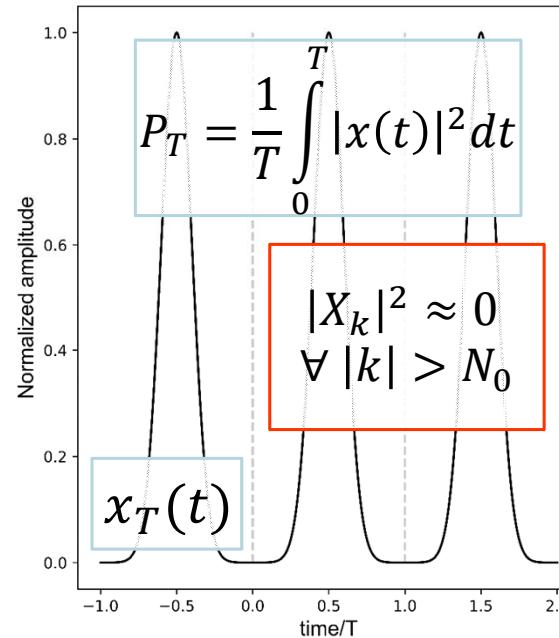
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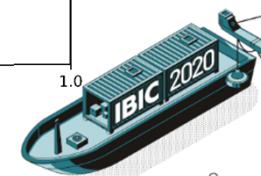
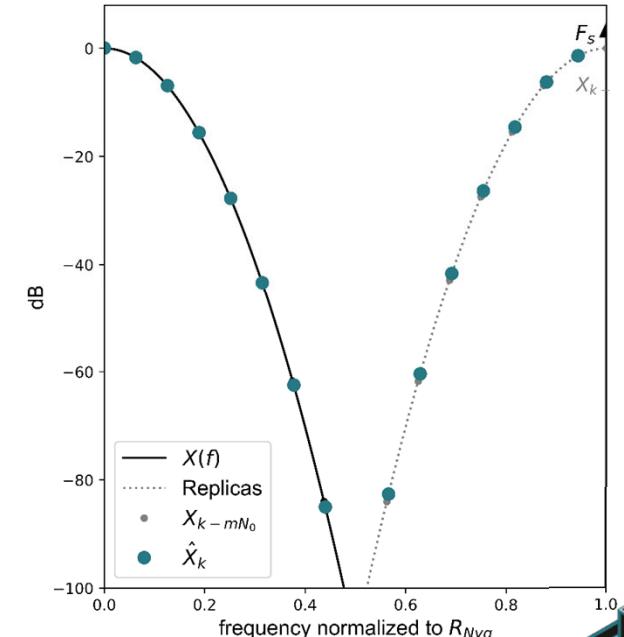
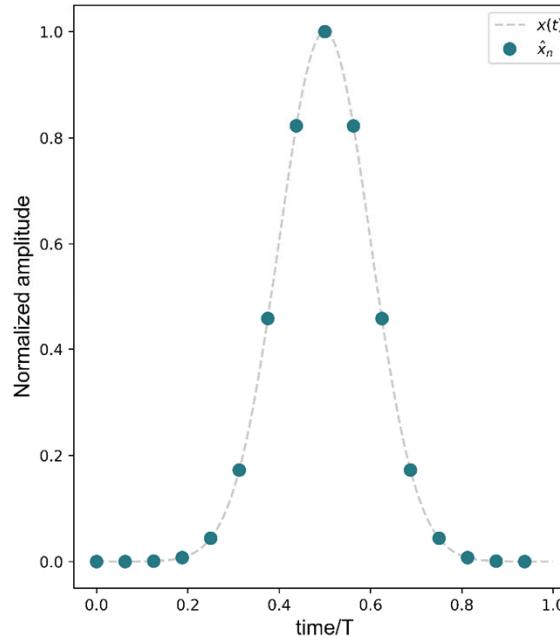
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Energy and power in time and frequency domain



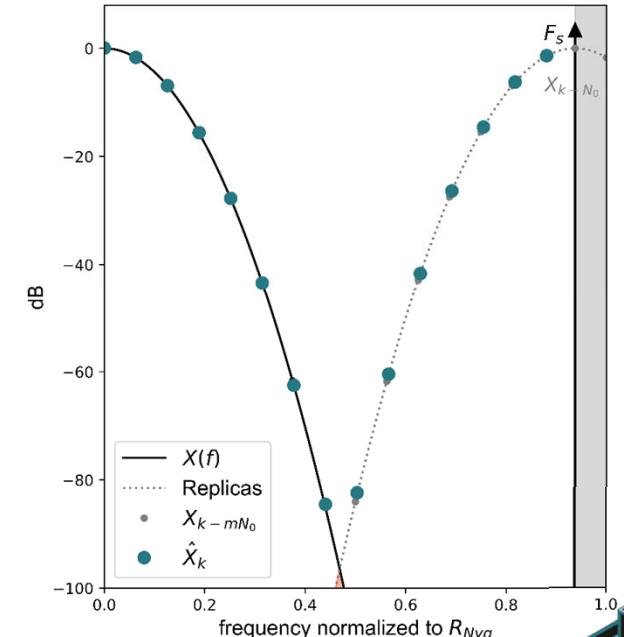
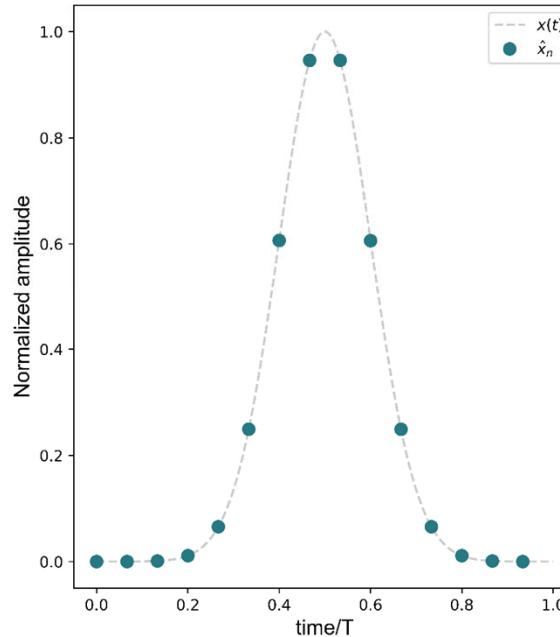
Limited Sampling Rate

What happens when we sample the pulse



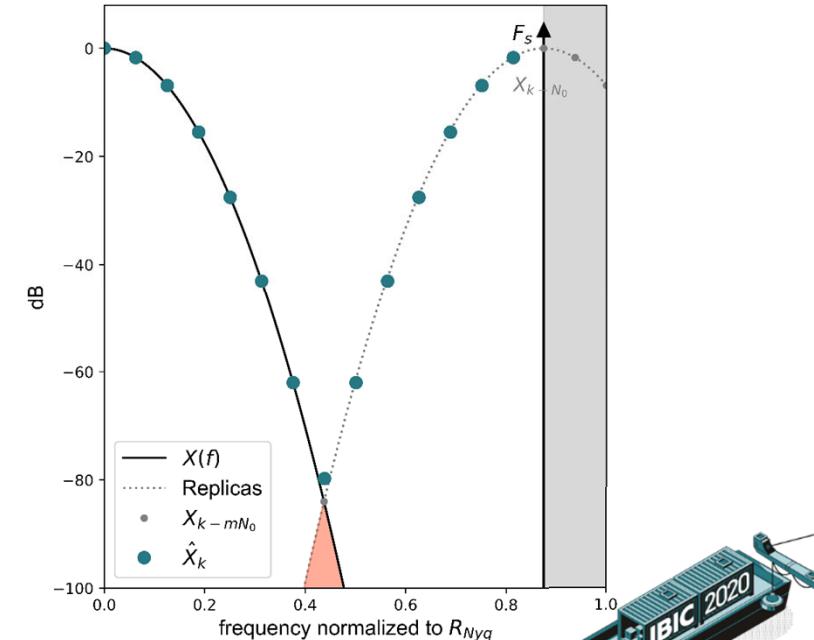
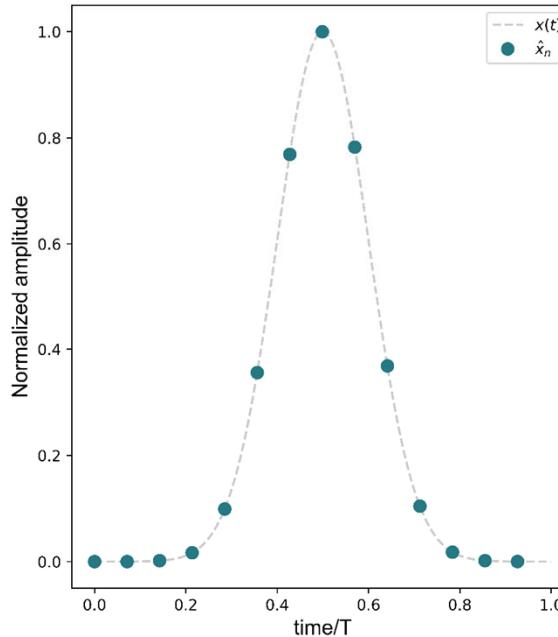
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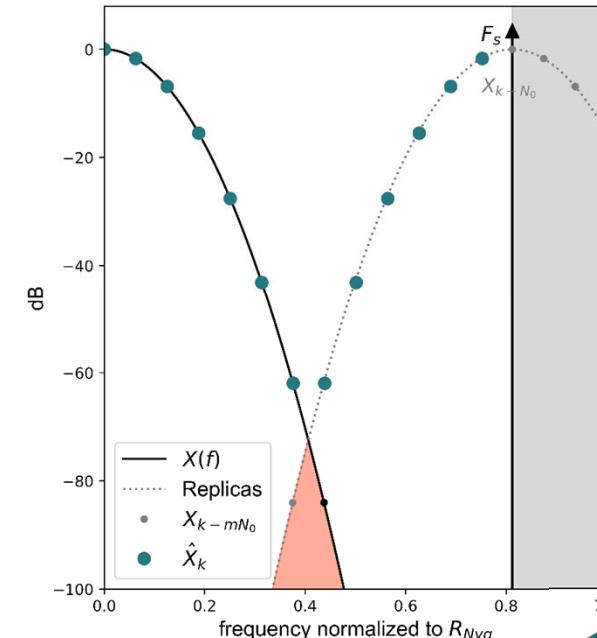
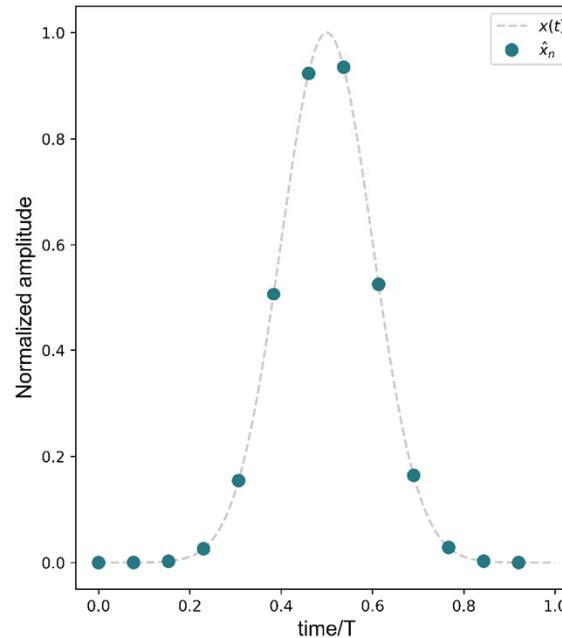
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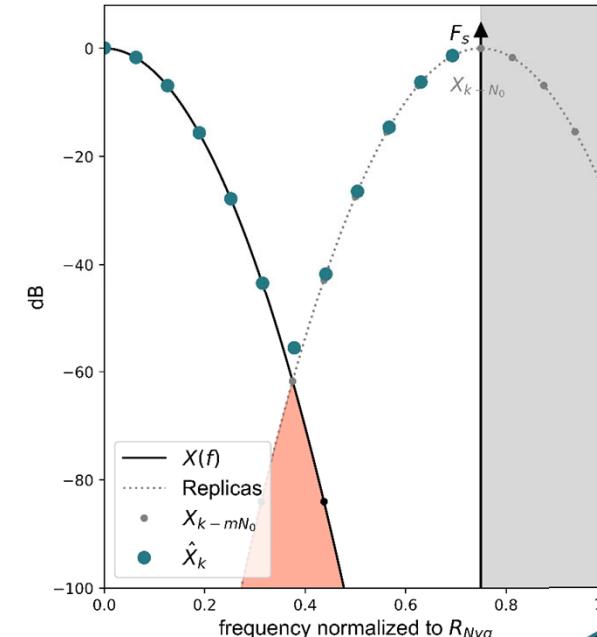
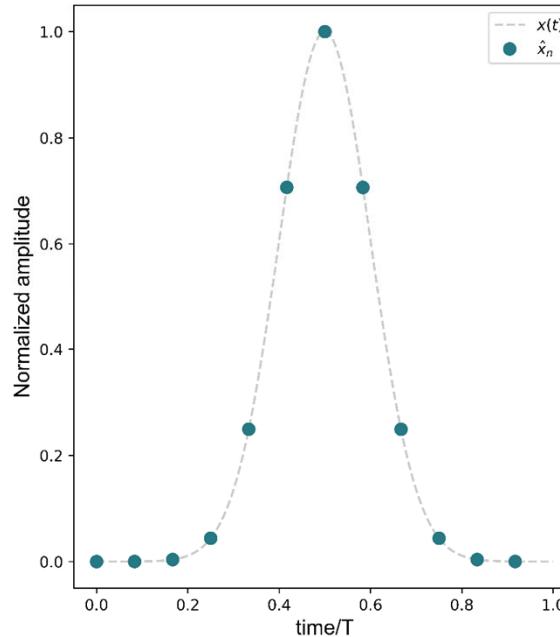
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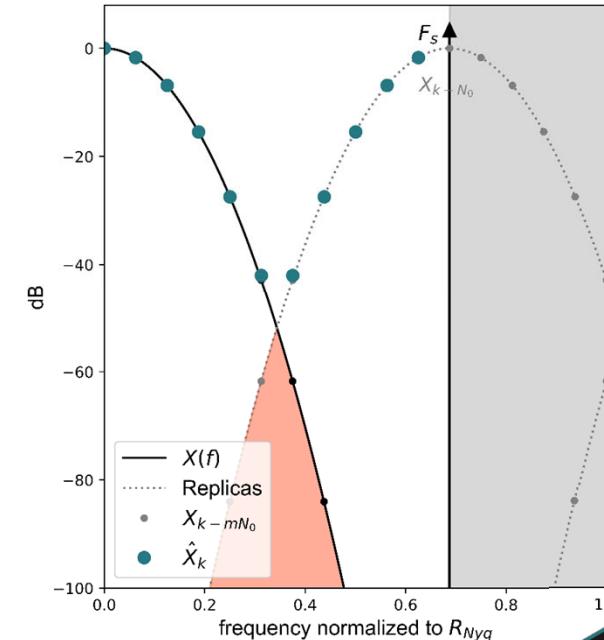
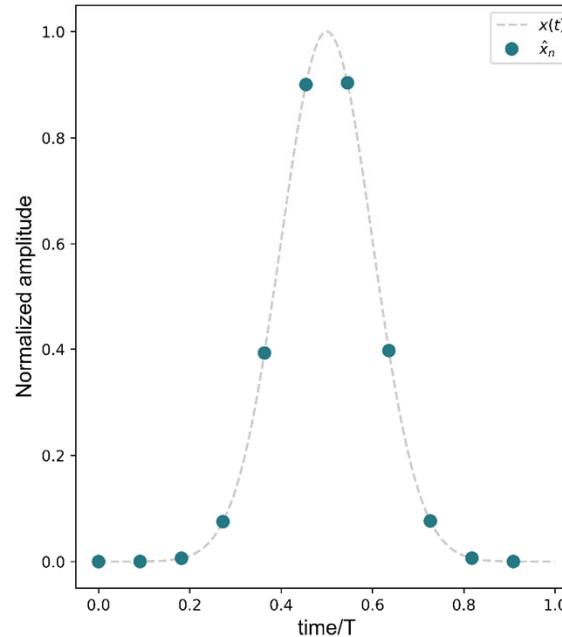
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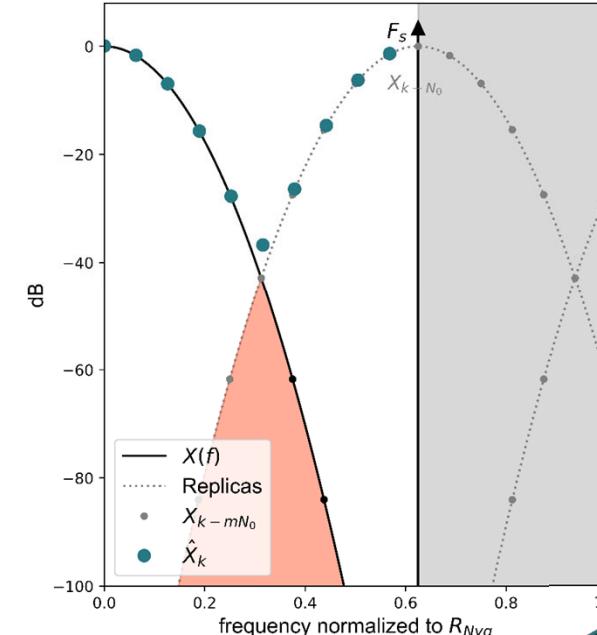
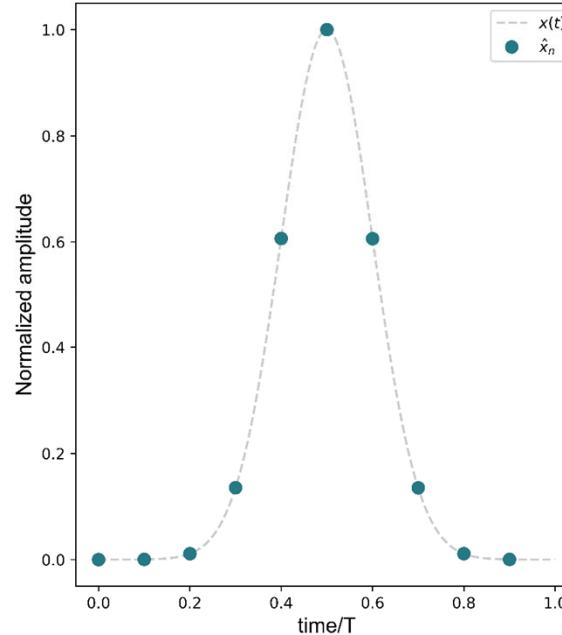
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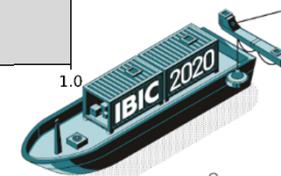
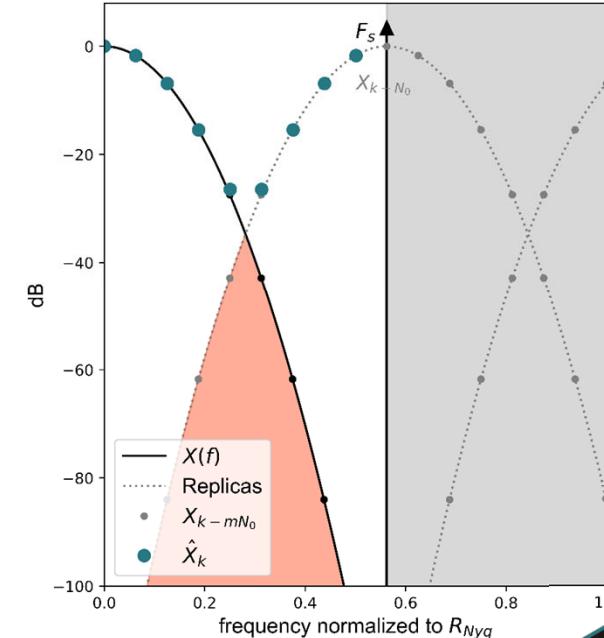
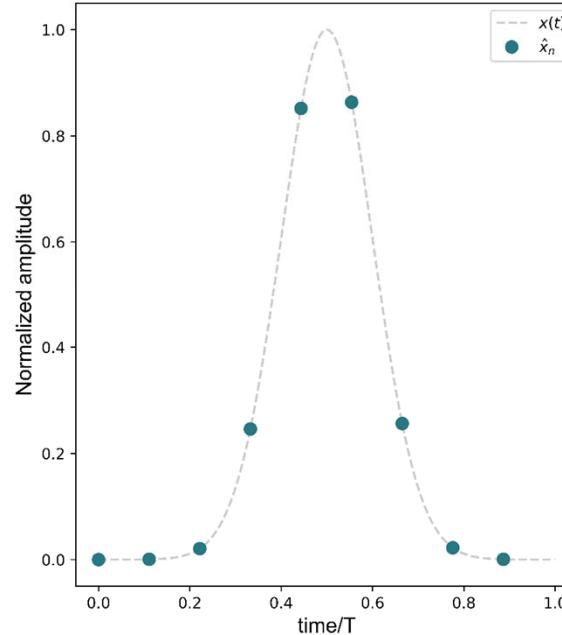
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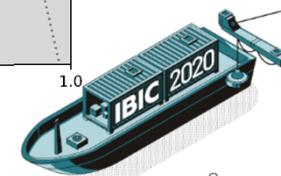
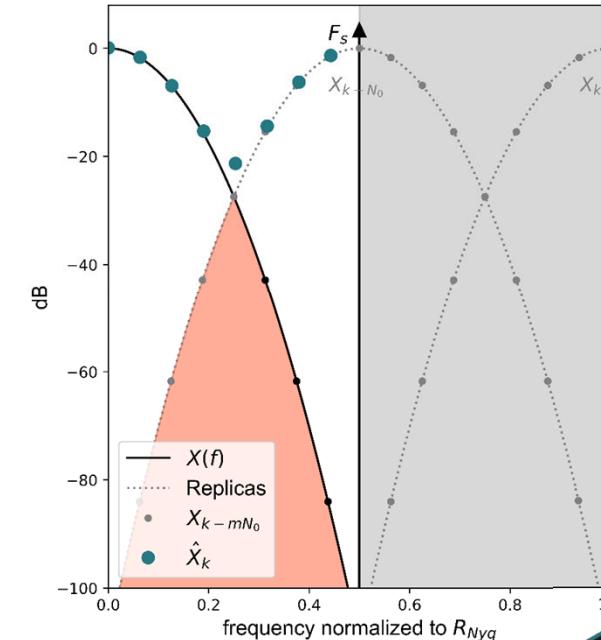
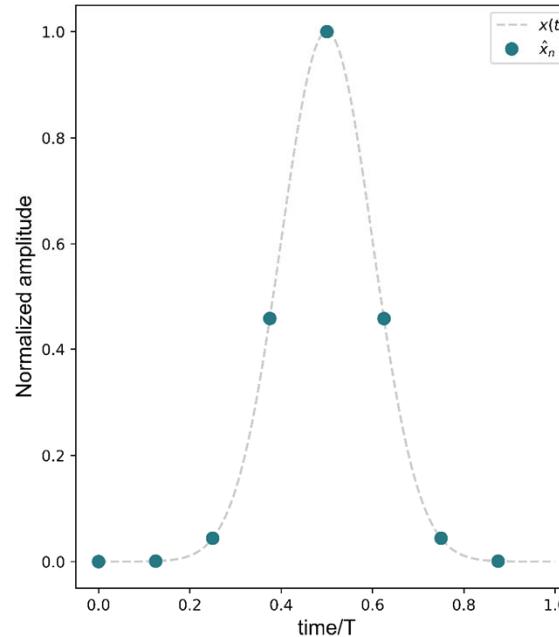
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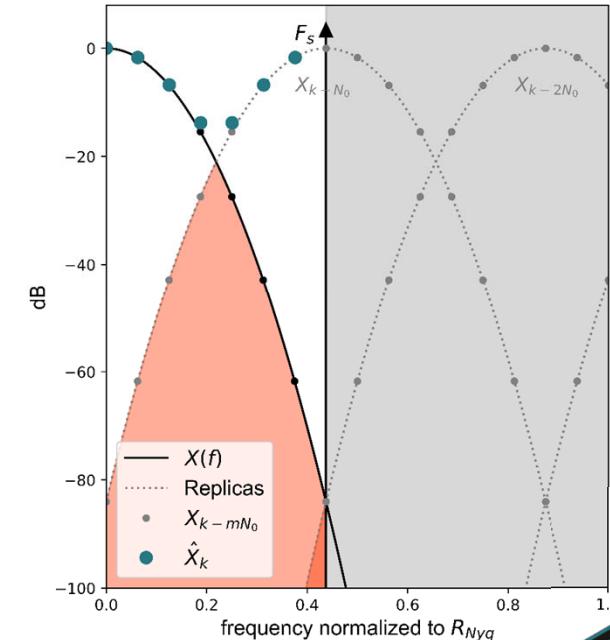
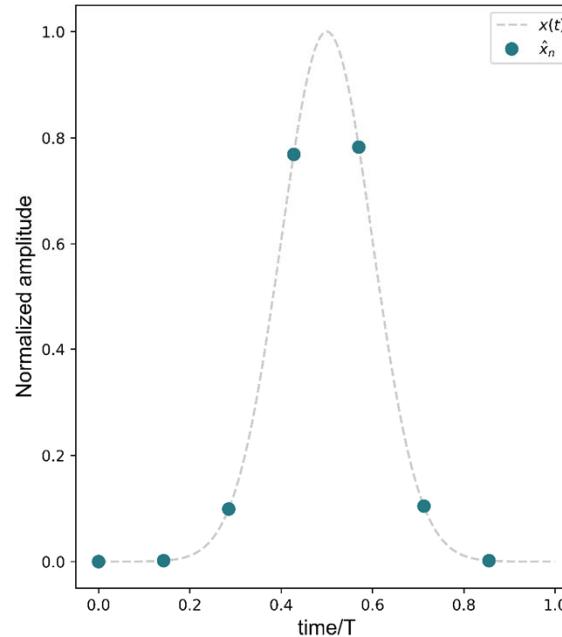
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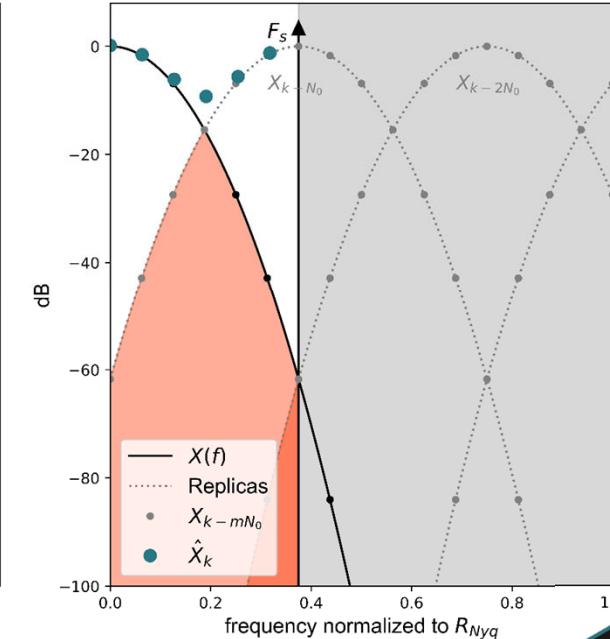
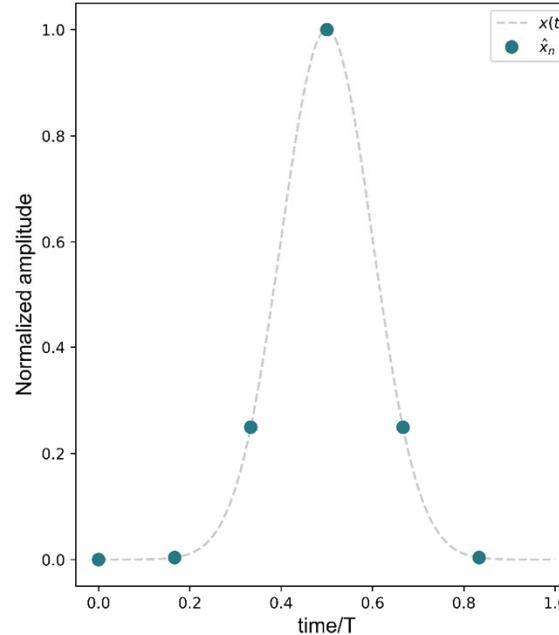
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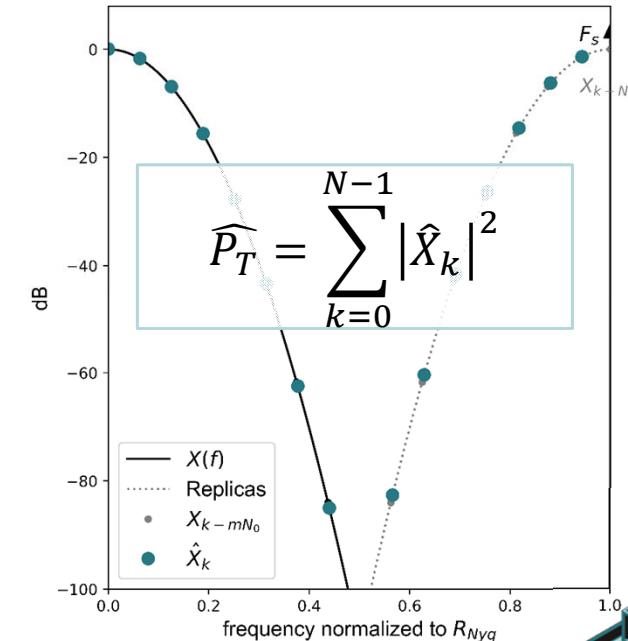
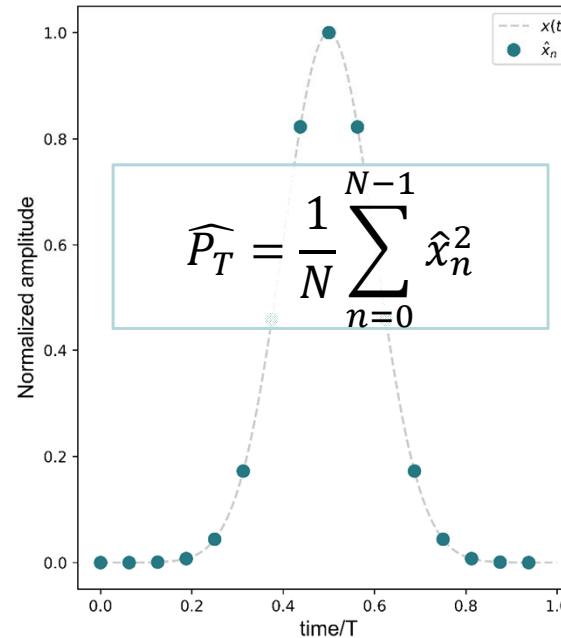
Limited Sampling Rate

What happens when we sample the pulse



Limited Sampling Rate

And the energy estimation?



Limited Sampling Rate

And the energy estimation?

- If the *Nyquist-Shannon* criterion is met ($F_s > R_{Nyq}$)

$$\rightarrow \widehat{P}_T = P_T = E/T$$

- BUT what if $F_s < R_{Nyq}$?



Limited Sampling Rate

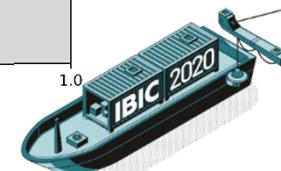
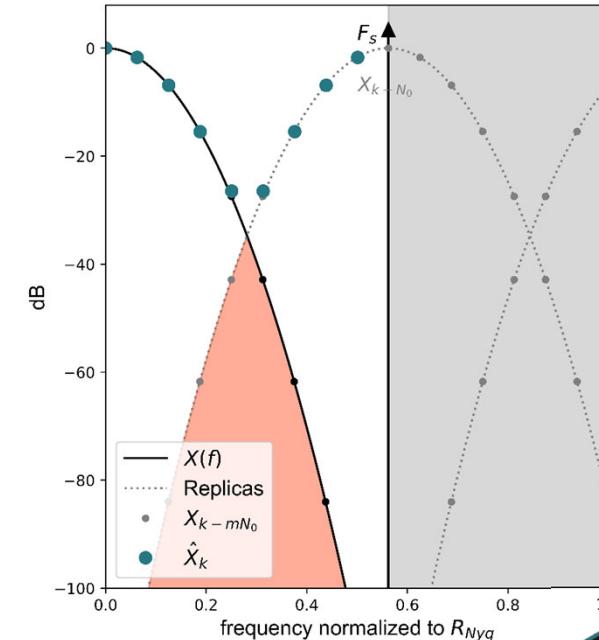
And the energy estimation?

$$\frac{R_{Nyq}}{2} < F_s < R_{Nyq}$$

$$\widehat{X}_k = X_{k-N} + X_k$$

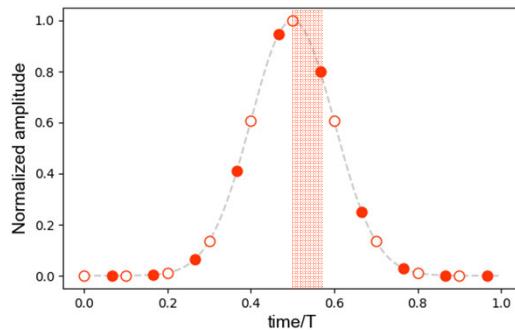


$$\widehat{P}_T = \sum_{k=0}^{N-1} |\widehat{X}_k|^2$$



Limited Sampling Rate

And the energy estimation?



Sampling rate

$$\text{Hyp: } \frac{R_{Nyq}}{2} < F_s < R_{Nyq} \leftrightarrow N_0 < N < 2N_0$$

Input signal spectrum

$$X_k = |X_k| e^{-i\phi_k}$$

Sampling delay

$$\tau$$

$$\widehat{P}_T = P_T + 2 \sum_{k=0}^{N-1} |X_k| |X_{k-N}| \cdot \cos(\phi_k - \phi_{k-N} - 2\pi F_s \tau)$$



Quantity to estimate



Error term



Limited Sampling Rate

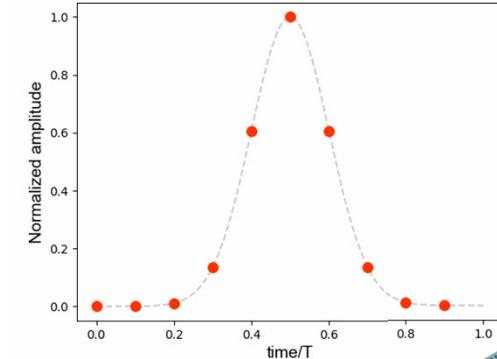
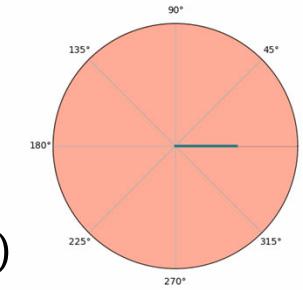
The estimation error

$$\epsilon(X_k, F_s, \tau) \triangleq \widehat{P}_T - P_T$$

$$\epsilon(X_k, F_s, \tau) = A_{X_k, N} \cdot 2 \cos(2\pi F_s \tau) + B_{X_k, N} \cdot 2 \sin(2\pi F_s \tau)$$

$$A_{X_k, N} \triangleq \sum_{k=0}^{N-1} |X_k| |X_{k-N}| \cdot \cos(\varphi_k - \varphi_{k-N})$$

$$B_{X_k, N} \triangleq \sum_{k=0}^{N-1} |X_k| |X_{k-N}| \cdot \sin(\varphi_k - \varphi_{k-N})$$



Limited Sampling Rate

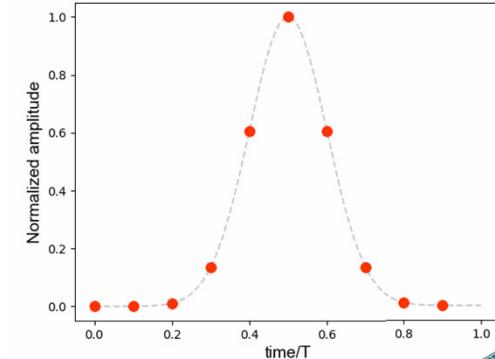
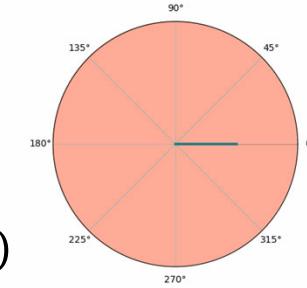
The estimation error

$$\epsilon(X_k, F_s, \tau) \triangleq \widehat{P}_T - P_T$$

$$\epsilon(X_k, F_s, \tau) = A_{X_k, N} \cdot 2 \cos(2\pi F_s \tau) + B_{X_k, N} \cdot 2 \sin(2\pi F_s \tau)$$

Hyp: $\tau = U \left[0, \frac{1}{F_s} \right]$

- $\mu_\epsilon = 0$;
- $\sigma_\epsilon^2 = 2 \left((A_{X_k, N})^2 + (B_{X_k, N})^2 \right)$



Limited Sampling Resolution

The introduction of the converter noise v

- We now take into account the limited resolution of the ADC
- How does it propagate in the estimator?

$$\widehat{P}_T = \frac{1}{N} \sum_{n=0}^{N-1} \hat{x}_n^2 \rightarrow \overline{P}_T = \frac{1}{N} \sum_{n=0}^{N-1} (\hat{x}_n + v_n)^2$$

- Zero-mean Gaussian variable, with σ_v^2 variance



Limited Sampling Resolution

The introduction of the converter noise ν

- We now take into account the limited resolution of the ADC
- How does it propagate in the estimator?

$$\overline{P_T} = \widehat{P}_T + \frac{1}{N} \sum_{n=0}^{N-1} \nu^2 + \frac{1}{N} \sum_{n=0}^{N-1} 2\widehat{x}_n \nu_n \rightarrow \eta \triangleq \overline{P_T} - \widehat{P}_T$$

- Zero-mean Gaussian variable, with σ_ν^2 variance



Limited Sampling Resolution

The introduction of the converter noise ν

$$\eta \triangleq \overline{P_T} - \widehat{P_T}$$

$$\mu_\eta = \sigma_\nu^2$$

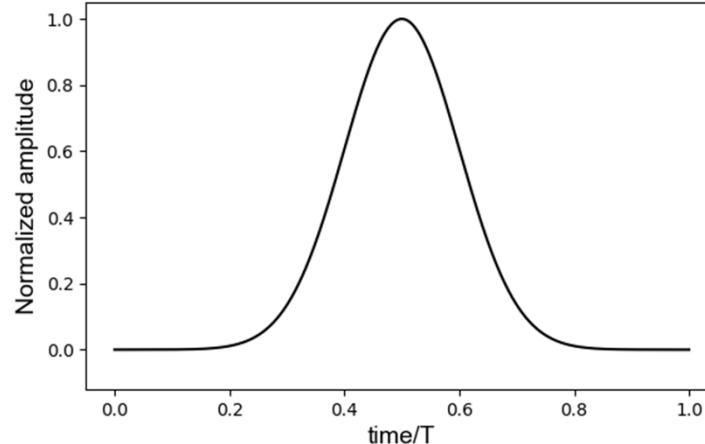
$$\sigma_\eta^2 = \frac{\sigma_\nu^4}{N} + 4P_T \frac{\sigma_\nu^2}{N}$$



A combined SNR expression

Total error

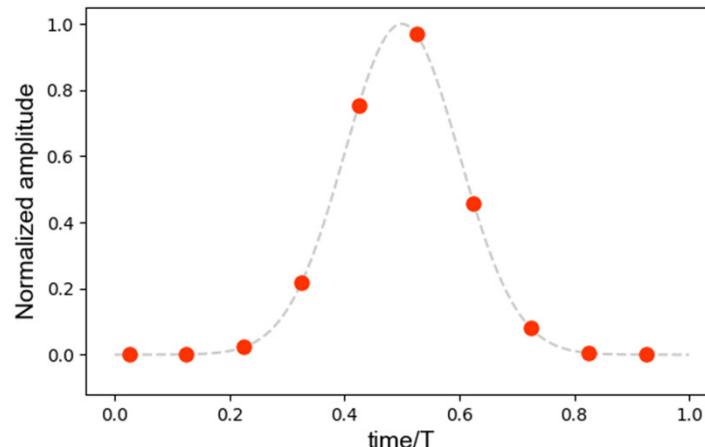
$$\overline{P_T} = \frac{1}{N} \sum_{n=0}^{N-1} (\hat{x}_n + v_n)^2 = P_T$$



A combined SNR expression

Total error

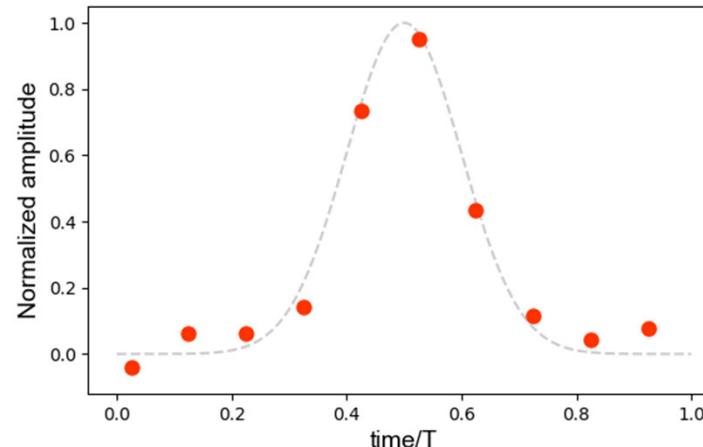
$$\overline{P_T} = \frac{1}{N} \sum_{n=0}^{N-1} (\hat{x}_n + v_n)^2 = P_T + \epsilon(X_k, F_s, \tau)$$



A combined SNR expression

Total error

$$\overline{P_T} = \frac{1}{N} \sum_{n=0}^{N-1} (\hat{x}_n + v_n)^2 = P_T + \epsilon(X_k, F_s, \tau) + \eta(P_T, \sigma_v^2, F_s)$$



A combined SNR expression

Total error

$$\overline{P_T} = \frac{1}{N} \sum_{n=0}^{N-1} (\hat{x}_n + v_n)^2 = P_T + \epsilon(X_k, F_s, \tau) + \eta(P_T, \sigma_v^2, F_s)$$

- Mean value:

$$\sigma_v^2$$

- Variance:

$$2 \left((A_{X_k, N})^2 + (B_{X_k, N})^2 \right) + \frac{\sigma_v^4}{N} + 4P_T \frac{\sigma_v^2}{N}$$



A combined SNR expression

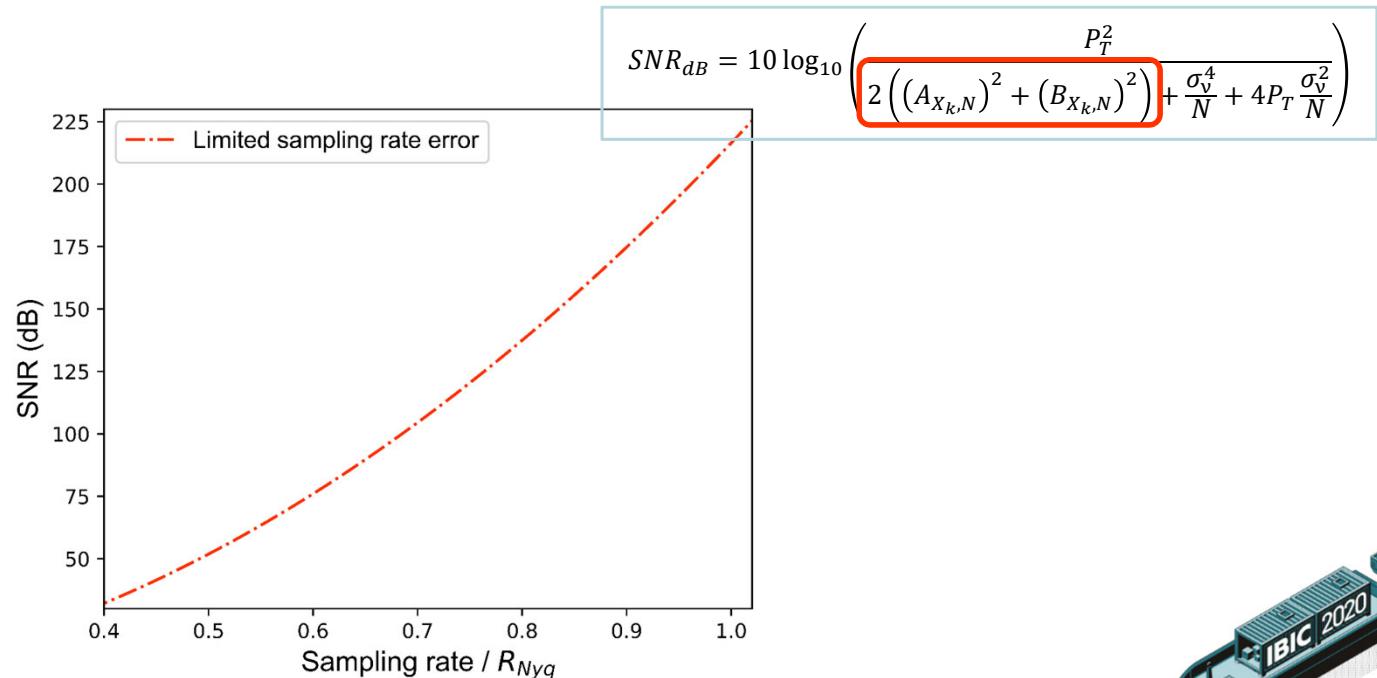
SNR expression of the averaged power measurement

$$SNR_{dB} = 10 \log_{10} \left(\frac{P_T^2}{2 \left((A_{X_k,N})^2 + (B_{X_k,N})^2 \right) + \frac{\sigma_v^4}{N} + 4P_T \frac{\sigma_v^2}{N}} \right)$$



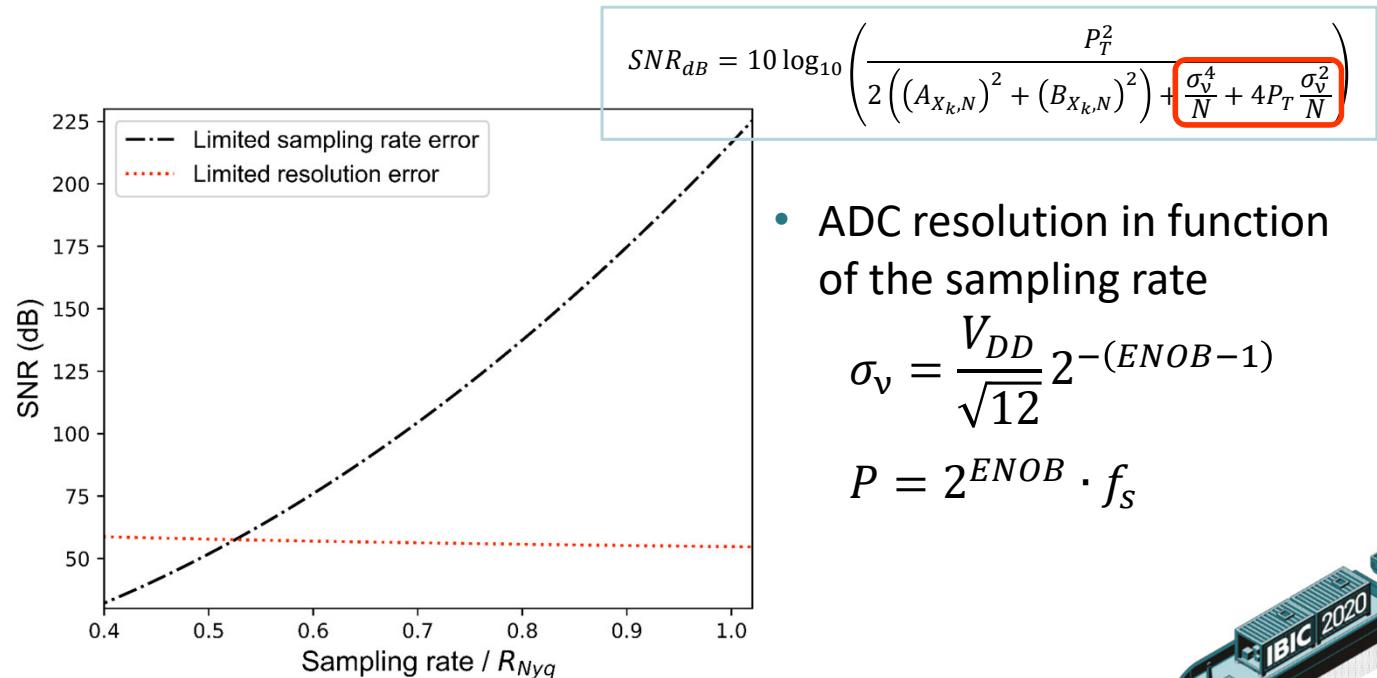
A combined SNR expression

SNR expression of the averaged power measurement



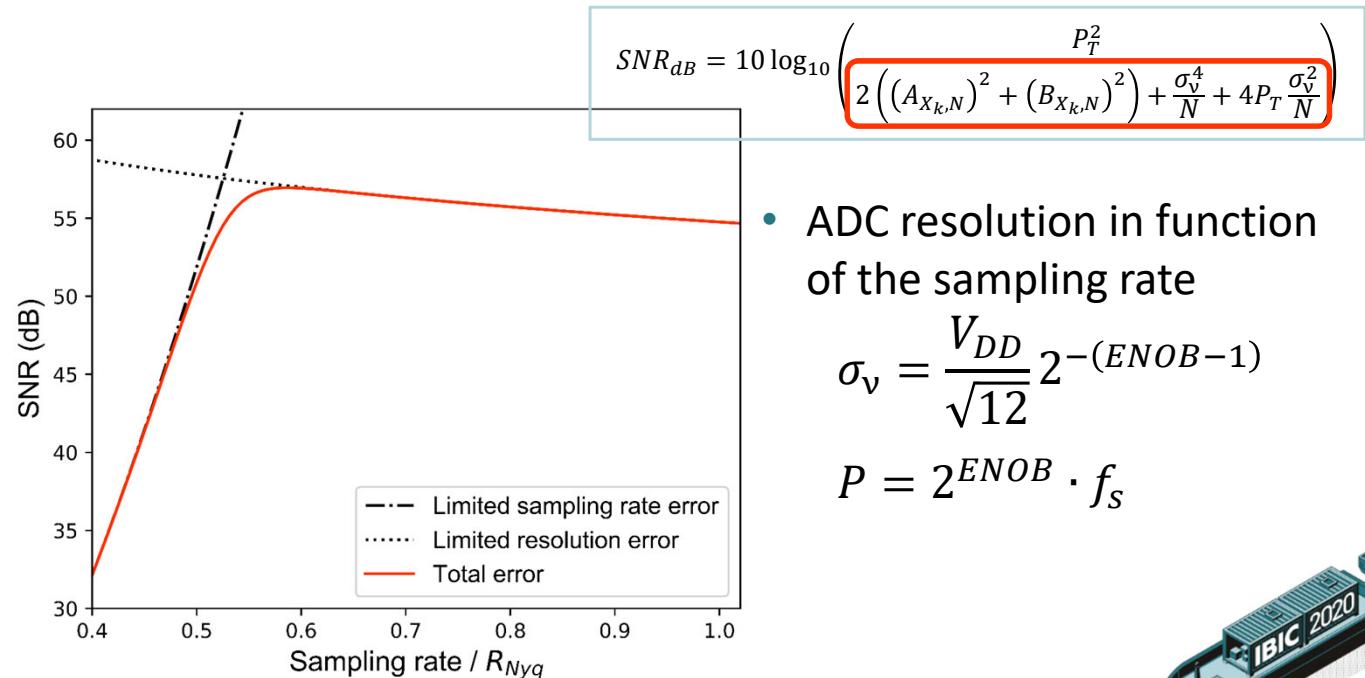
A combined SNR expression

SNR expression of the averaged power measurement



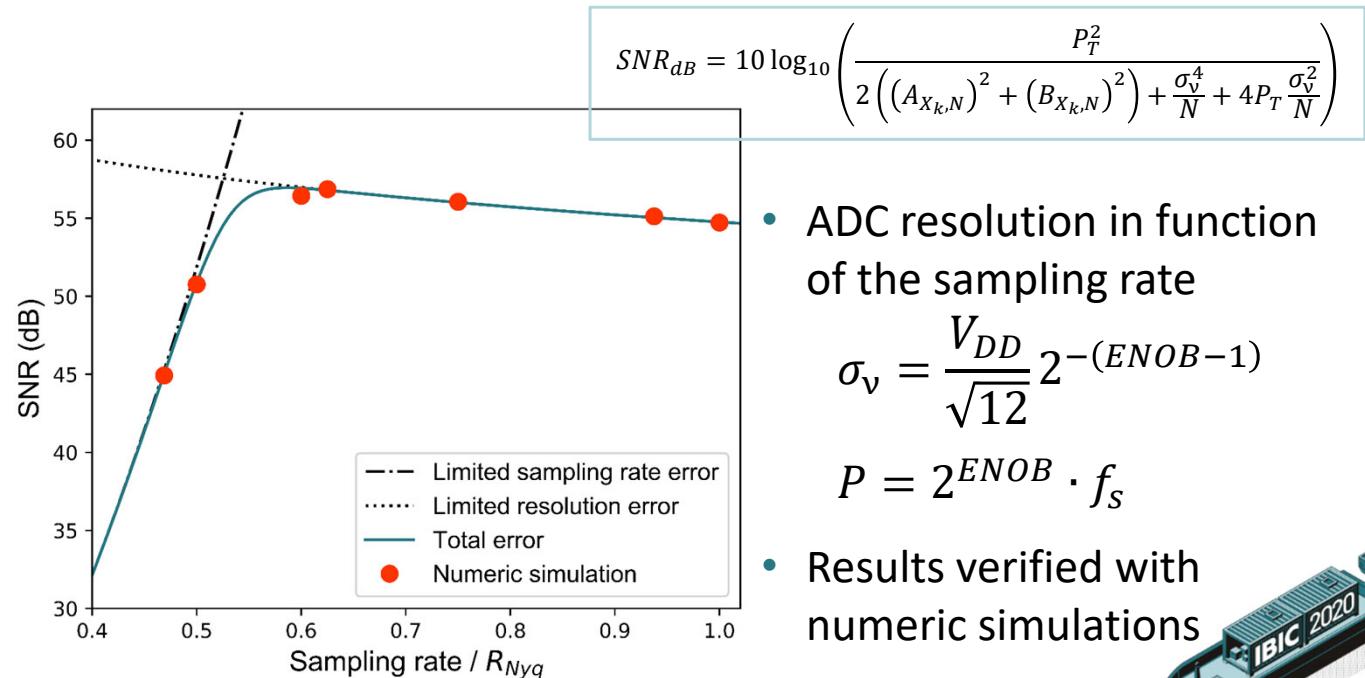
A combined SNR expression

SNR expression of the averaged power measurement



A combined SNR expression

SNR expression of the averaged power measurement



- ADC resolution in function of the sampling rate

$$\sigma_v = \frac{V_{DD}}{\sqrt{12}} 2^{-(ENOB-1)}$$

$$P = 2^{ENOB} \cdot f_s$$

- Results verified with numeric simulations





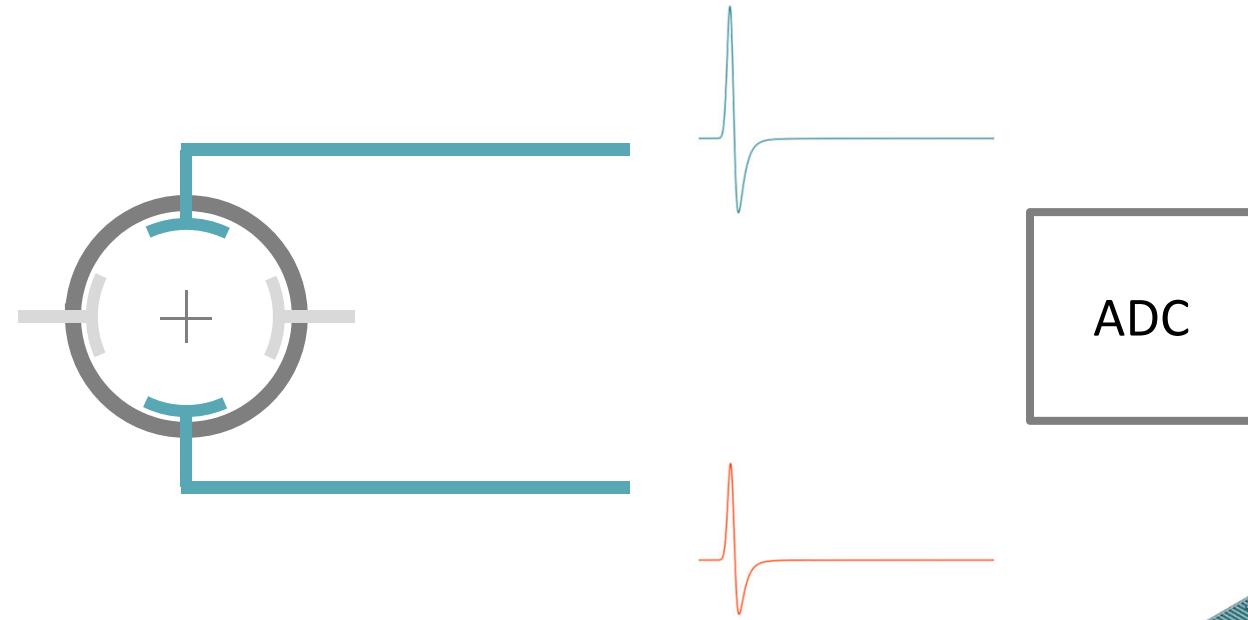
Application example

*A proposed new bunch-by-bunch
read-out system for the LHC BPM*



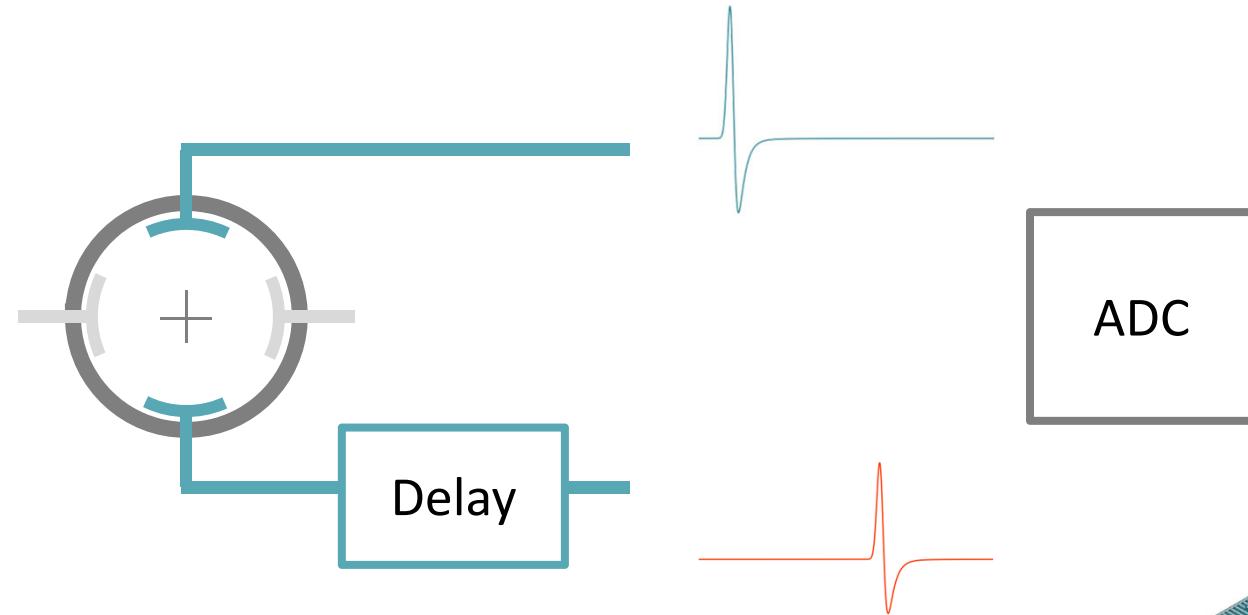
A possible architecture

Before the ADC: electrodes combination



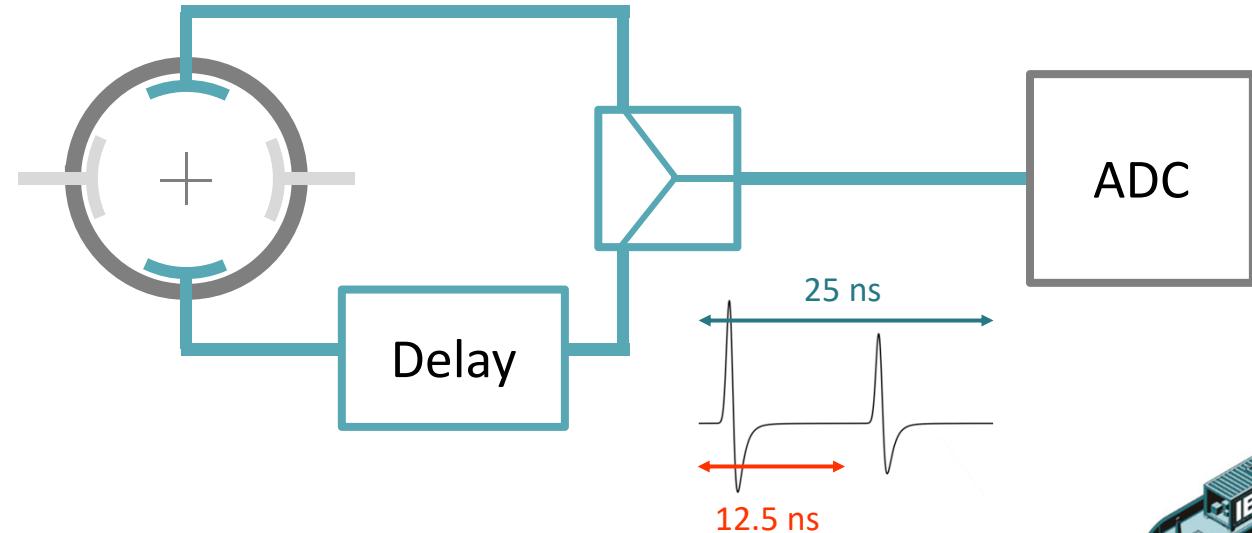
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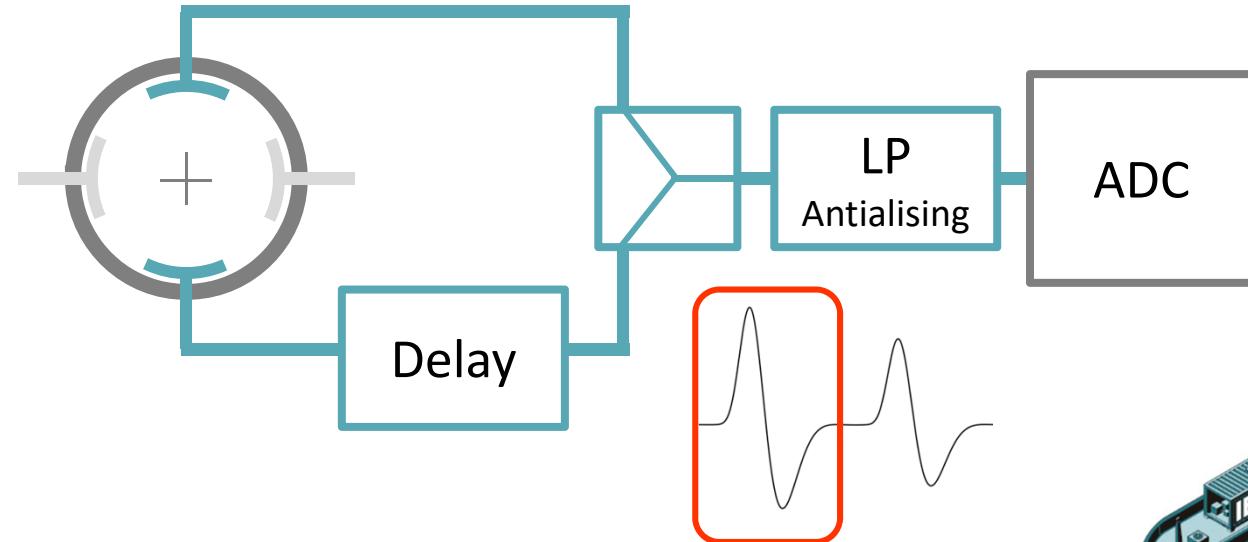
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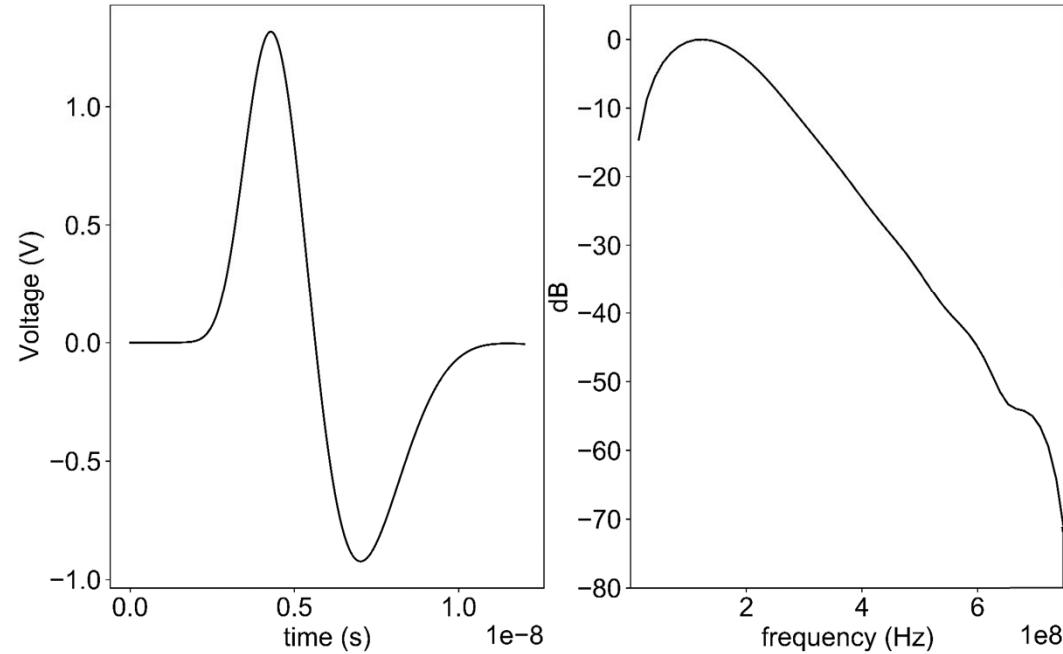
A possible architecture

Before the ADC: signal “stretching” with LP filter



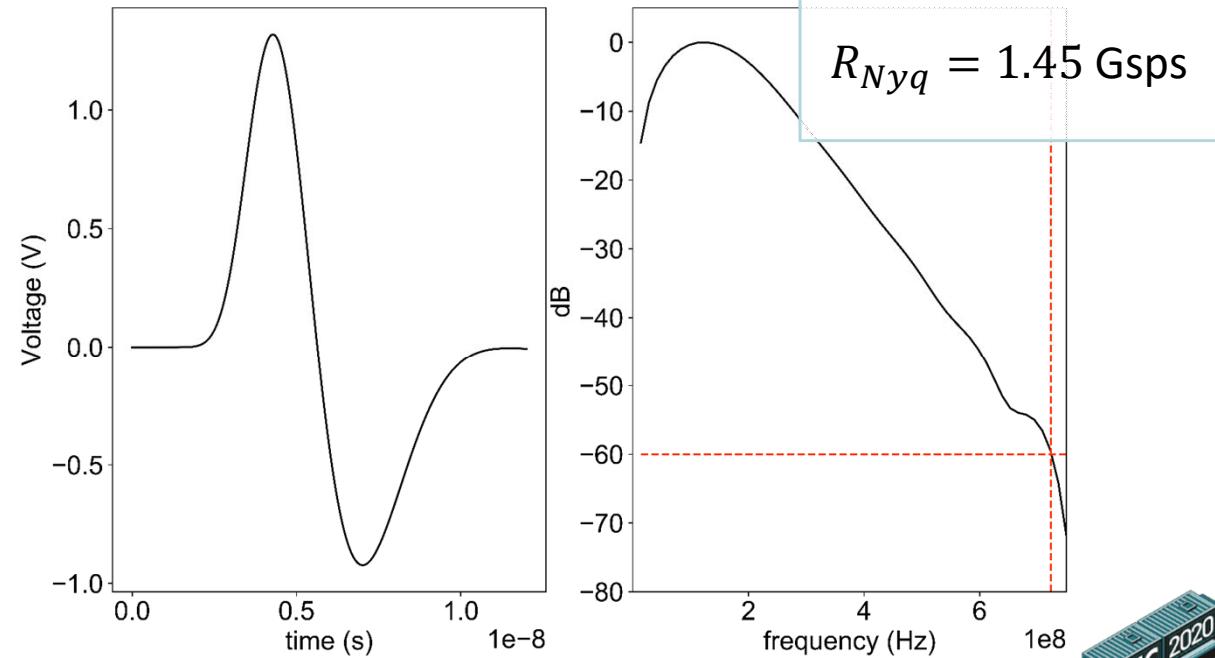
Single bunch pulse signal

- LP Filter
 - 200 MHz
 - N=4
- Antialiasing
 - 600 MHz
 - N=8



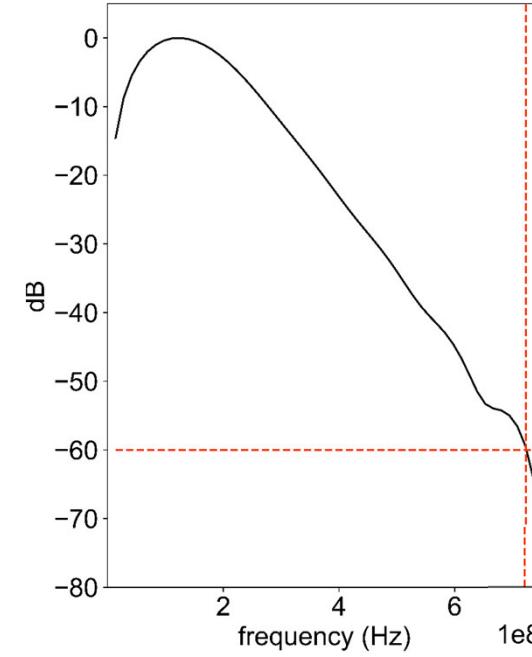
Single bunch pulse signal

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Power measurement SNR Analysis

$$SNR_{dB} = 10 \log_{10} \left(\frac{P_T^2}{2 \left((A_{X_k,N})^2 + (B_{X_k,N})^2 \right) + \frac{\sigma_v^4}{N} + 4P_T \frac{\sigma_v^2}{N}} \right)$$

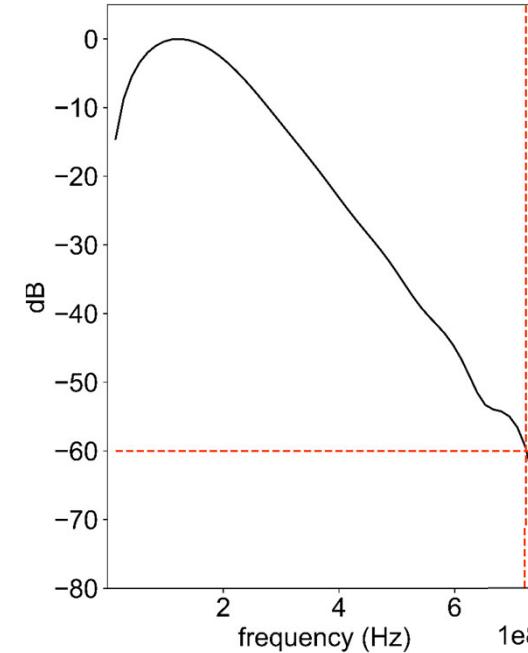


Power measurement SNR Analysis

$$SNR_{dB} = 10 \log_{10} \left(\frac{P_T^2}{2 \left((A_{X_{k,N}})^2 + (B_{X_{k,N}})^2 \right) + \frac{\sigma_v^4}{N} + 4P_T \frac{\sigma_v^2}{N}} \right)$$

$$\sigma_v = \frac{V_{DD}}{\sqrt{12}} 2^{-(ENOB-1)}$$

$$P = 2^{ENOB} \cdot f_s$$

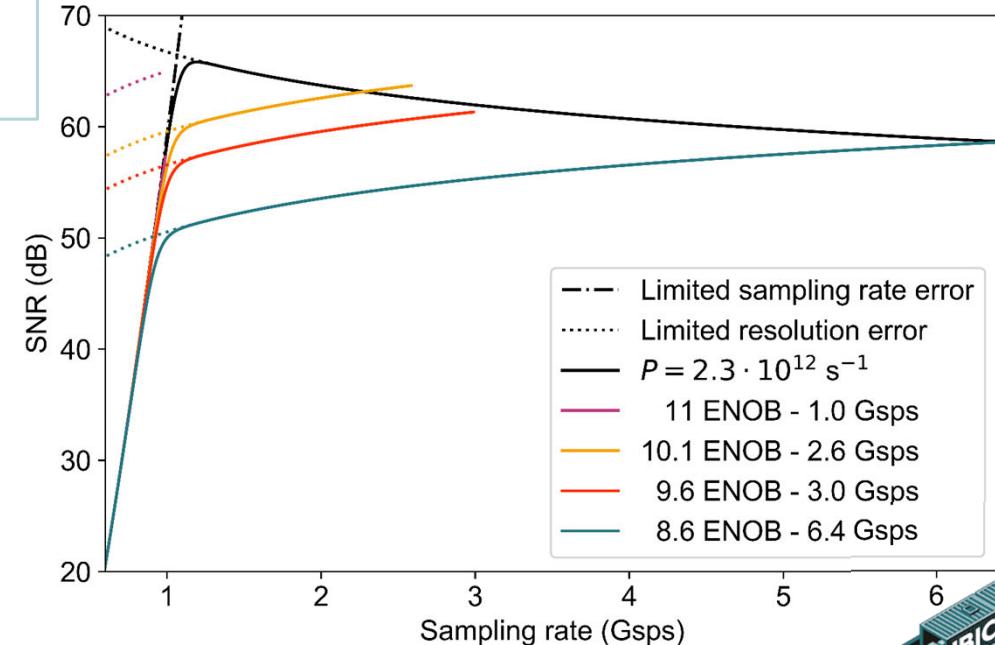


Power measurement SNR Analysis

$$SNR_{dB} = 10 \log_{10} \left(\frac{P_T^2}{2 \left((A_{X_k,N})^2 + (B_{X_k,N})^2 \right) + \frac{\sigma_v^4}{N} + 4P_T \frac{\sigma_v^2}{N}} \right)$$

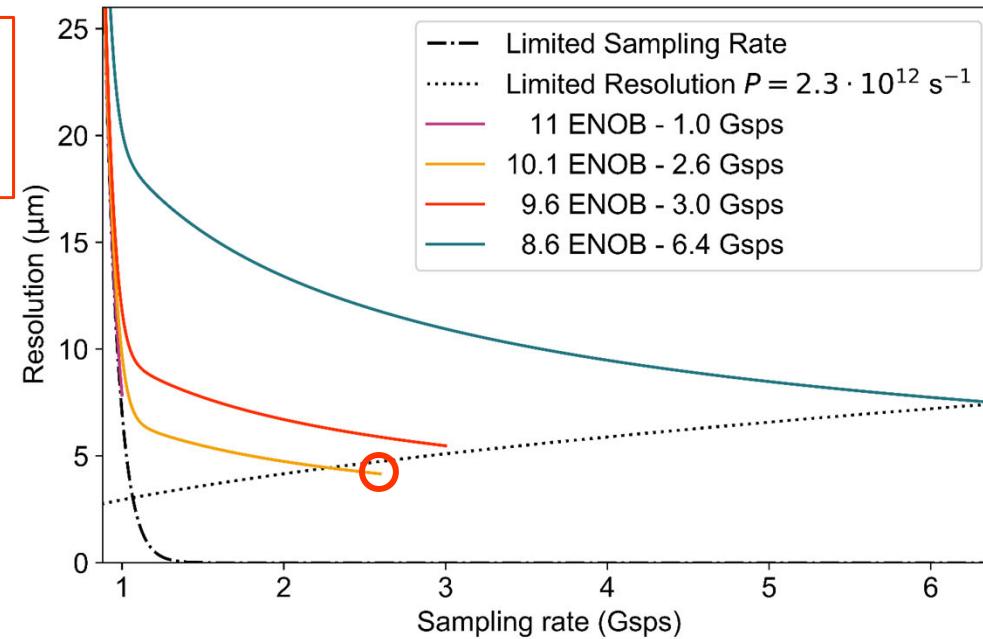
$$\sigma_v = \frac{V_{DD}}{\sqrt{12}} 2^{-(ENOB-1)}$$

$$P = 2^{ENOB} \cdot f_s$$



Position Resolution Analysis

$$\delta y \approx k_{\frac{\text{mm}}{\text{dB}}} \cdot 20 \log_{10} \left(\sqrt{1 + \frac{\sigma_e^2 + \sigma_\eta^2}{P_T}} \right)$$

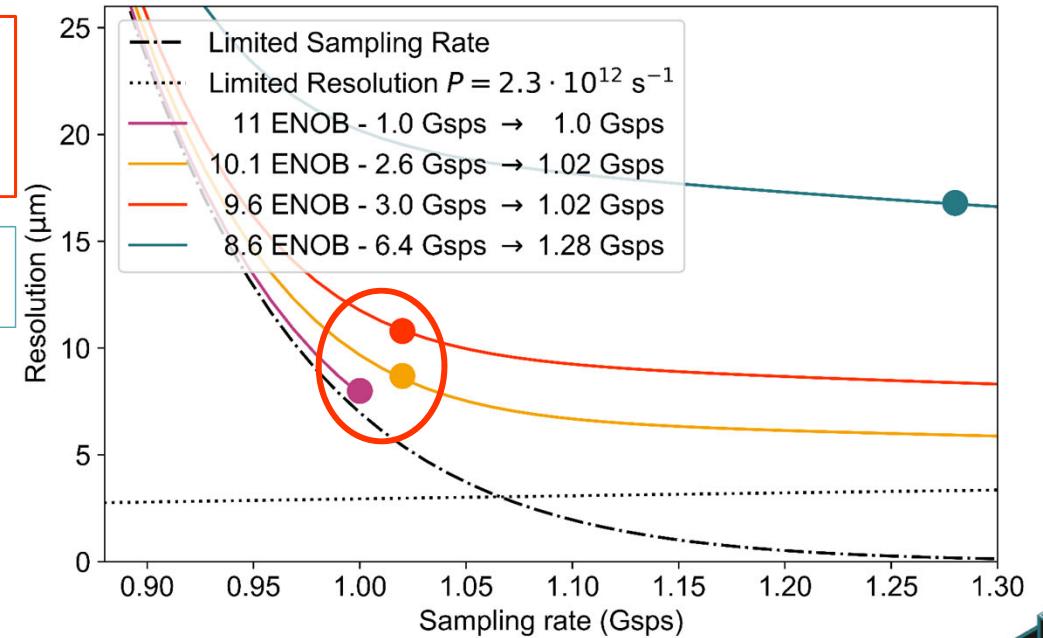


Position Resolution Analysis

With transmission bandwidth limit

$$\delta y \approx k_{\text{mm}} \cdot \frac{\text{dB}}{\text{dB}} \cdot 20 \log_{10} \left(\sqrt{1 + \frac{\sigma_e^2 + \sigma_\eta^2}{P_T}} \right)$$

2 serial links x 10.24 Gbps





Summary



Summary

- **Direct digitization** based systems are of growing interest for Beam Instrumentation applications.
- ADC state-of-the-art imposes a **trade-off** between sampling rate and resolution.
- It is possible to **estimate the error** introduced in the energy estimation of a digitized pulse as a function of the sampling rate and resolution.
- This analytic tool can facilitate the **analysis** of the performance of a system, but also assist in the **design** of a new system, especially in the selection of the ADC.

