# BEAM POSITION MONITOR SYSTEM FOR HIGH VOLTAGE ELECTRON COOLER FOR NICA COLLIDER

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The high collider is (BPM).

The high voltage (2.5 MV) electron cooler for NICA collider is now designing in BINP. Beam position monitor (BPM) system for orbit measurements has been developed at BINP. The system contains 16 BPMs inside the cooling sections, 4 BPMs inside the high voltage vessels and 22 BPMs in transport channels. Continuous electron beam is modulated with 10 MHz sinusoidal signal for capability to get signals from pickup electrodes. The beam current modulation can be varied in the range of 0.3-5 mA. The modulation signal may be supplied to each sector of the control electrode. So, the position of one quadrant sector of the electron beam can be measured by BPM system. Comparing the positions of each sectors from BPM to BPM it is possible to analyse the shape of the electron beam in the transport channel and cooling section. The BPMs inside the cooling section can measure both electron and ion beams. It is achieved by means of switching the reference signals inside the BPM electronics. The prototypes of new BPM electronics have highly precise beam position measurements. Position measurement error doesn't area to 2 been fabricated and tested. The BPM electronics provides measurement error doesn't exceed a few micron. Design features of the BPM system, its parameters and testing results are presented in this paper.

#### INTRODUCTION

The high voltage (2.5 MV) electron cooler for NICA collider is now designing in BINP [1]. Beam position monitor (BPM) system consists of 42 BPMs and electronics. 16 BPMs are located inside the cooling sections, 4 BPMs are installed inside the high voltage vessels and 22 BPMs are installed in transport channels. Continuous electron beam current is modulated with a ~10 MHz signal for capability to get signals from BPM electrodes. Some parameters of cooler and main BPM system requirements are presented in Table 1.

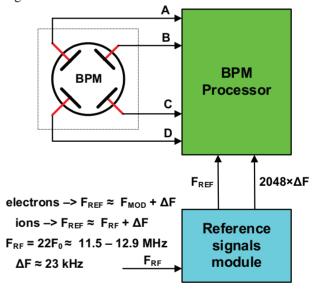
Table 1: Main Requirements to BPM System

Electron current	0.1-1 A
Modulation amplitude of electron	0.3-1.5 mA
current	
NICA collider revolution	523-586 kHz
frequency $F_0$	
Number of ion bunches $N_b$	22
Position measurement error	< 100 μm
Measurement rate	0.1-1 sec

To achieve the best cooling effectiveness electron and proton beams must be aligned inside the cooling section with accuracy better than 100  $\mu m$ . This condition requires simultaneous measurements of electron and proton beams position by 16 BPMs located inside the cooling sections. 22 BPMs in the transport channels and 4 BPMs inside the high voltage vessels measure only electron beam position. A feature of the gun four-sector control electrode using before in the COSY cooler allows measuring not only electron beam position but the beam shape and rotation [2].

### **SYSTEM STUCTURE**

The structure chart of the BPM system is presented in Fig. 1.



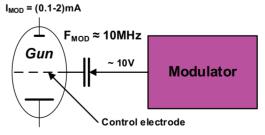


Figure 1: The structure of the BPM system.

The system consists of 42 BPMs, Signal Processing Electronics, including 21 BPM Processors and 38

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Preamplifiers, 2 Modulators, 1 Reference signals generator and 1 Reference signals distributor.

Modulator provides electron beam current modulation with frequency  $F_{MOD} \approx 10 \, \mathrm{MHz}$ . Signal Processing Electronics measures the beam signals amplitude at each of four BPM electrodes. The measurement is based on synchronous detecting of the BPM signal with frequency  $F_{SIGN}$ . For BPMs inside the cooling sections  $F_{SIGN}$  equals  $F_{MOD}$  for electron beam and  $F_{RF}$  for ion beam, where  $F_{RF} = 22F_{\theta}$ . Revolution frequency  $F_{\theta}$  is changed from 523 kHz to 586 kHz during acceleration in the NICA collider. For BPMs in the transport channels and guns  $F_{SIGN}$  equals  $F_{MOD}$ . The sinusoidal signal with frequency  $F_{REF} \approx F_{SIGN} + \Delta F$  generated by Reference signals module is used as reference signal.

The simultaneous measurements of electron and ion beams position inside the cooling sections is achieved by means of switching the reference signal between  $F_{MOD}$  +  $\Delta F$  and  $F_{RF}$  +  $\Delta F$ .

#### **ELECTRONICS**

## Modulator

The system contains 2 Modulators – one modulator for each Gun. A functional diagram of the Modulator is presented in Fig. 2.

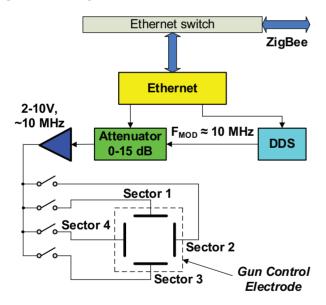


Figure 2: Functional diagram of the Modulator.

Gun Control electrode consists of four sectors. Modulation voltage can be applied both to all sectors and to one of them. In the last case only a part of electron beam in transverse cross-section will be modulated. By switching on different sectors in turn one can get information about the beam shape and beam precession due to longitudinal field in different BPM locations [2].

Modulator is located inside the High Voltage (HV) tank at potential of up to 2.5 MV. Modulation signal with

frequency  $F_{MOD} \approx 10$  MHz is generated by DDS. An amplitude of modulation voltage can be set in the range 2-10 V with help of programmable attenuator.

## Signal Processing Electronics

Functional diagram of the Signal Processing Electronics for BPMs inside the cooling sections and transport channels is presented in Fig. 3.

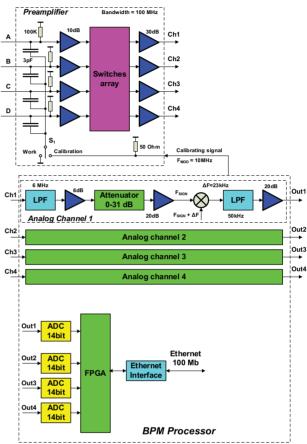


Figure 3: Functional diagram of the Signal Processing Electronics for BPMs inside the cooling sections and transport channels.

Signal Processing Electronics for each BPM inside the cooling sections and transport channels consists of Preamplifier with high input impedance located near BPM and BPM Processor. Preamplifier is connected with BPM via four 75 Ohm cables with length ~1 m. BPM Processors are placed in the rack located in the electronics room. Switches array used in Preamplifier provides 4 connection combinations between 4 BPM electrodes and 4 signal processing channels. Use of the Switches array allows to eliminate measurement error caused by inequality of the channels transmission coefficients.

After amplification the BPM signals with frequency  $F_{SIGN}$  are mixed with reference frequency  $F_{REF} \approx F_{SIGN} + \Delta F$ . Then the signals with frequency  $\Delta F \approx 23$  kHz after low pass filtering and amplification are sampled by 14 bit ADC. The signals in digital form come to FPGA where digital processing is performed. This digital signal

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processing includes synchronous detecting and accumulation. The frequencies  $F_{MOD}$  and  $F_{REF}$  are generated by different modules. So, for electrons  $F_{REF}$  value is not exactly equaled to  $F_{MOD} + \Delta F$ . A difference between the reference frequency  $F_{REF}$  and  $F_{MOD} + \Delta F$  for proper synchronous detecting must be less than 1 kHz. To achieve this a tracking of the reference frequency  $F_{REF}$  to  $F_{MOD} + \Delta F$  is implemented. The tracking procedure includes measurement of the difference between  $F_{REF}$  and  $F_{MOD} + \Delta F$  values on base of spectrum of ADC data.

In calibration mode special calibrating signal with frequency  $F_{CAL} \approx 10$  MHz comes through the switch S<sub>1</sub> and capacitances to each Preamplifier input (see Fig. 3).

BPM Processor occupies one 1U 19" chassis (Fig. 4). Each BPM Processor can serve two BPMs.



Figure 4: BPM processor prototype.

Signal Processing Electronics for BPMs inside the guns is fully located within one module BPM Processor (1U 19" chassis). It has not the Preamplifiers in separate bodies. Reference signal  $F_{REF}$  and calibrating signal  $F_{CAL}$  are generated inside the BPM Processor.

## **EXPERIMENTAL RESULTS**

Prototypes of all BPM electronics modules have been fabricated and tested. Main accuracy parameters have been measured with using of the signal generator. A sinusoidal test signal with frequency  $\sim 10$  MHz was applied via four-way splitter to four Preamplifier inputs. Signal amplitude was changed in the range 0.2-1 mV which corresponds to beam current modulation range 0.3-1.5 mA. Three measured main parameters of accuracy (for  $K_X \approx K_Y \approx 40$  mm) are presented in Table 2.

Table 2: Main Accuracy Parameters of the BPM System

Dependence of the result on beam	~4 µm
modulation current ( $I_{MOD} = 0.3-1.5 \text{ mA}$ )	-
Resolution ( $I_{MOD} = 0.3-1.5 \text{ mA}$ )	< 1 μm
Dependence of the result on the	~2 µm/°C
temperature	

An accuracy achieved with prototypes satisfies all cooler requirements.

#### **STATUS**

All BPMs and electronics are fabricating now in BINP. It is planned to complete fabrication and testing all the BPM electronics modules in 2020 year.

#### REFERENCES

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