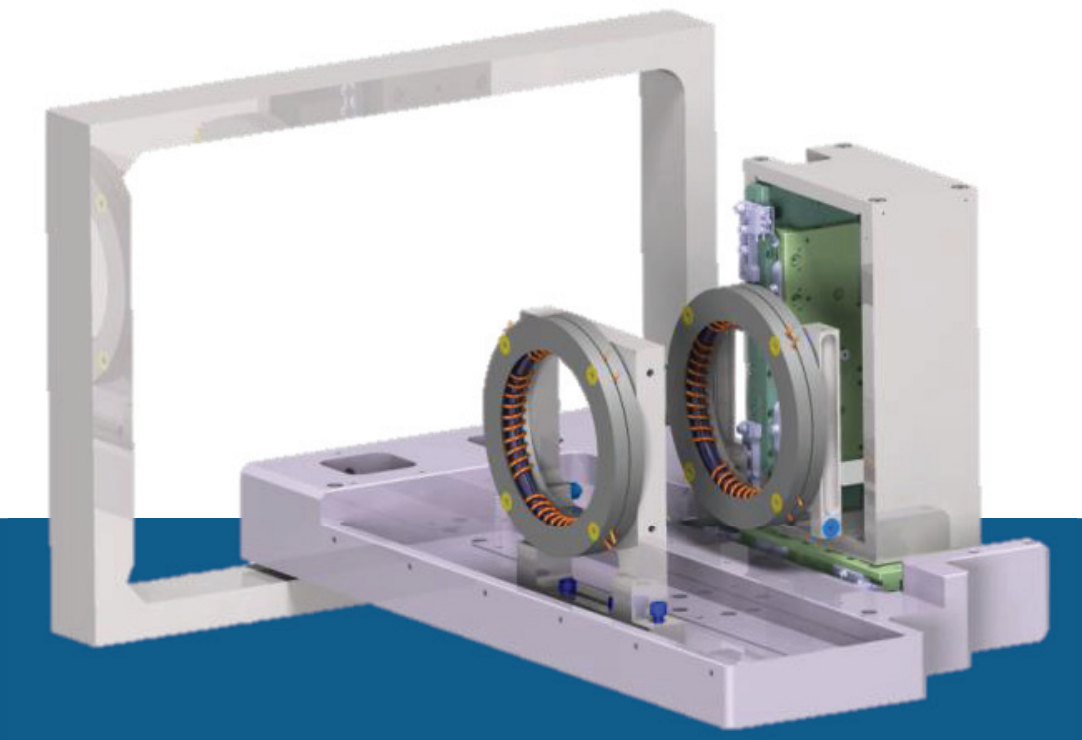


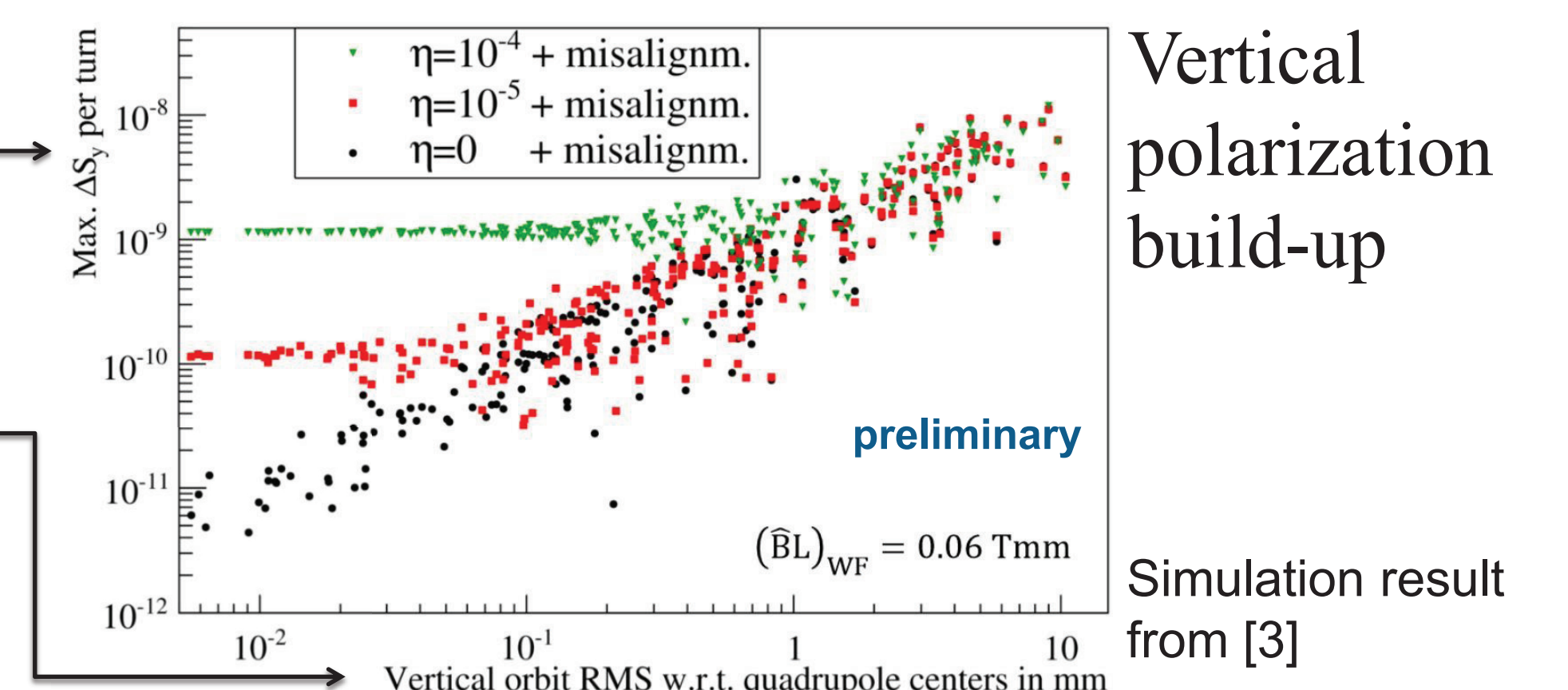
# Beam based calibration of a Rogowski coil used as a horizontal and vertical Beam Position Monitor

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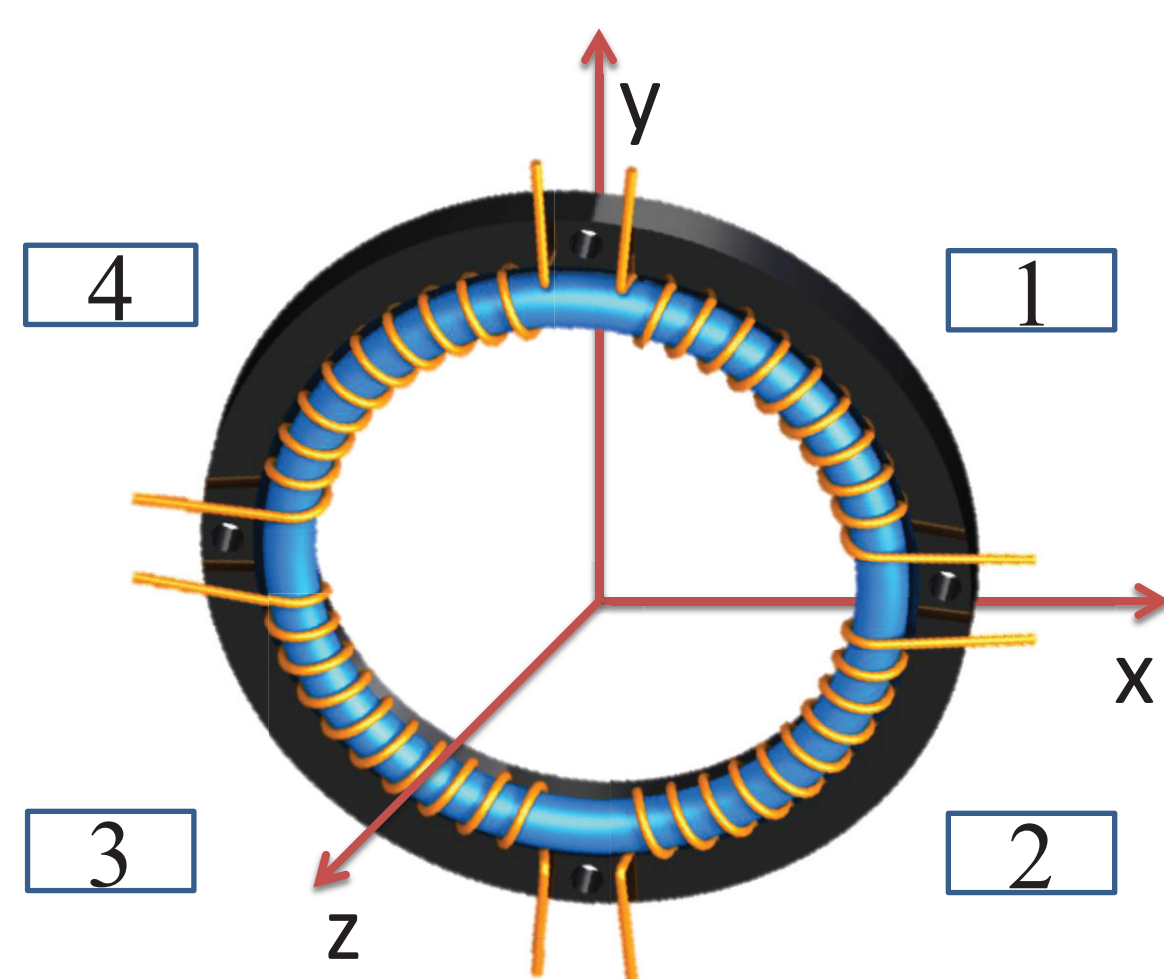
## Motivation

- Measure Electric Dipole Moment (EDM) of charged hadrons at COSY
- Use **RF Wien Filter** build up a EDM signal
- EDM  $\eta$  rotates spin out of horizontal plane  $\Rightarrow \frac{\Delta S_y}{\text{turn}}$
- Study **systematic effects**, like misalignments of magnets by controlling the **orbit** of the beam
  - Improve Beam Position Monitor (BPM) system, including new BPMs
  - Magnetostatic pick-ups based on Rogowski coil design



## Design of Rogowski Pick-Up Coil for a SQUID-BPM

- Torus with:
  - Major radius  $R = 40 \text{ mm}$
  - Minor radius  $a = 5 \text{ mm}$
  - Winding with cooper wire  $N = 350$



BPM in x- and y-direction  
(horizontal & vertical)

- Voltage induced by magnetic field  $\vec{B}$  of a bunched particle beam  $(x_0, y_0)$  in z-direction:

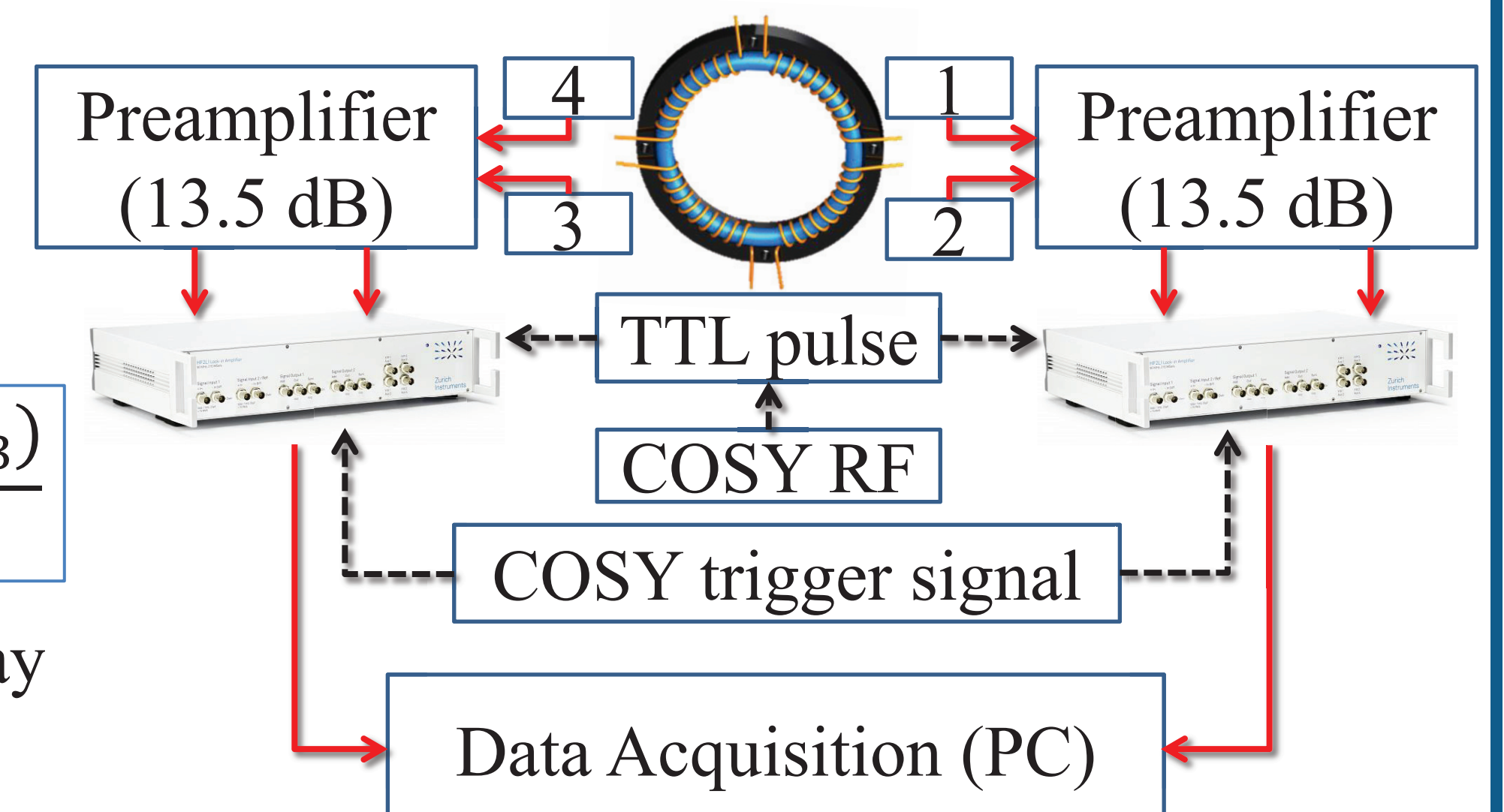
$$U_{ind} = -\frac{d}{dt} \int \vec{B} \cdot d\vec{A} = -\frac{d}{dt} \iiint B_\phi dr dz R d\phi$$

- Beam position determination in dependency of induced voltages:

$$x = m \cdot \frac{(U_1 + U_2) - (U_3 + U_4)}{U_1 + U_2 + U_3 + U_4} \quad y = m \cdot \frac{(U_1 + U_4) - (U_2 + U_3)}{U_1 + U_2 + U_3 + U_4}$$

- The arrangement of the segments is chosen in such a way that the BPM sensitivity is linear
- Theoretical prediction for sensitivity  $m = \frac{\pi\sqrt{R^2 - a^2}}{2}$  depends only on tube and torus parameters

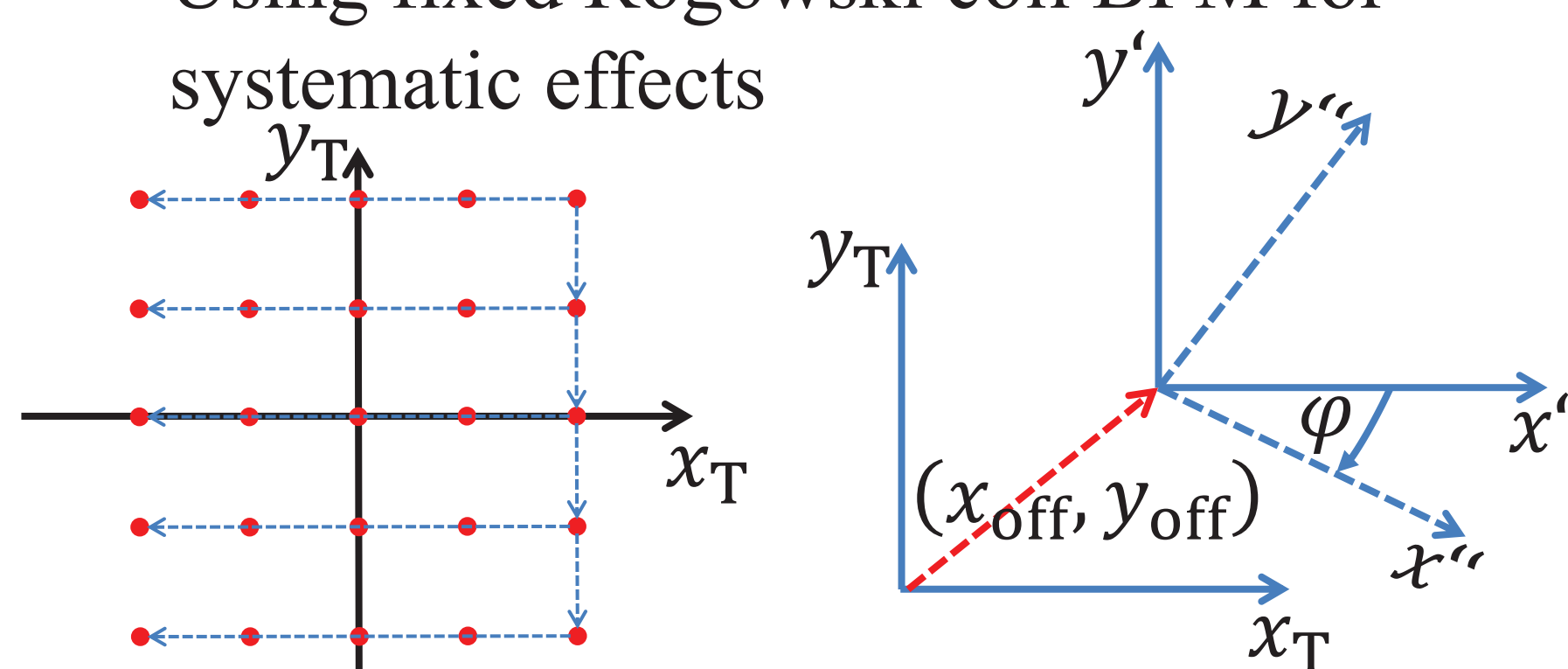
- Readout diagram for position determination of one Rogowski coil BPM:



- Cycle length of 210 s, sending each 5 s a trigger signal for position measurement

## Measurements at COSY

- Installation of two Rogowski coil BPMs:
  - Performing a grid measurement with the piezo table and measuring the beam position with the moved coil
  - Using fixed Rogowski coil BPM for systematic effects



$$x' = m_x \cdot m \cdot \frac{(U_1 + g_2 U_2) - (g_3 U_3 + g_4 U_4)}{U_1 + g_2 U_2 + g_3 U_3 + g_4 U_4}$$

$$y' = m_y \cdot m \cdot \frac{(U_1 + g_4 U_4) - (g_2 U_2 + g_3 U_3)}{U_1 + g_2 U_2 + g_3 U_3 + g_4 U_4}$$

- Weighting factors  $(g_2, g_3, g_4)$
- Offset  $(x_{off}, y_{off})$  and rotation  $(\varphi)$  to electrical centre
- Sensitivity scaling factors  $m_x$  and  $m_y$

- Applying calibration algorithm to the data of the moved Rogowski coil BPM
  - Minimize  $\chi^2$  in dependency calibration factors

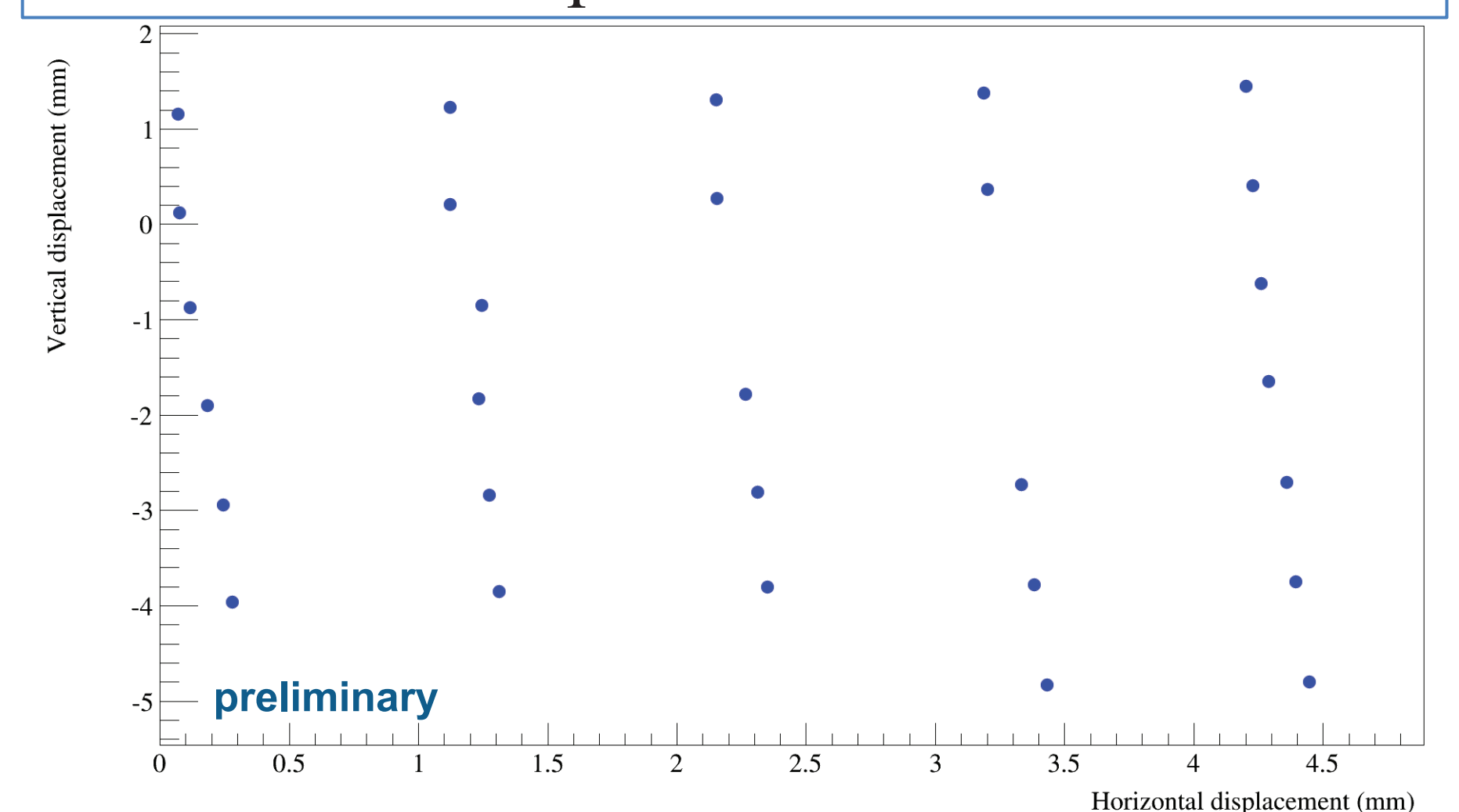
$$\chi^2 = \chi_x^2 + \chi_y^2$$

$$\chi_x^2 = \frac{(\chi' \cdot \cos(\varphi) - y' \cdot \sin(\varphi) - x_T - x_{off})^2}{(\sigma_{pos_x} \cdot \cos(\varphi))^2 + (\sigma_{pos_y} \cdot \sin(\varphi))^2 + (\sigma_{x,fluc})^2}$$

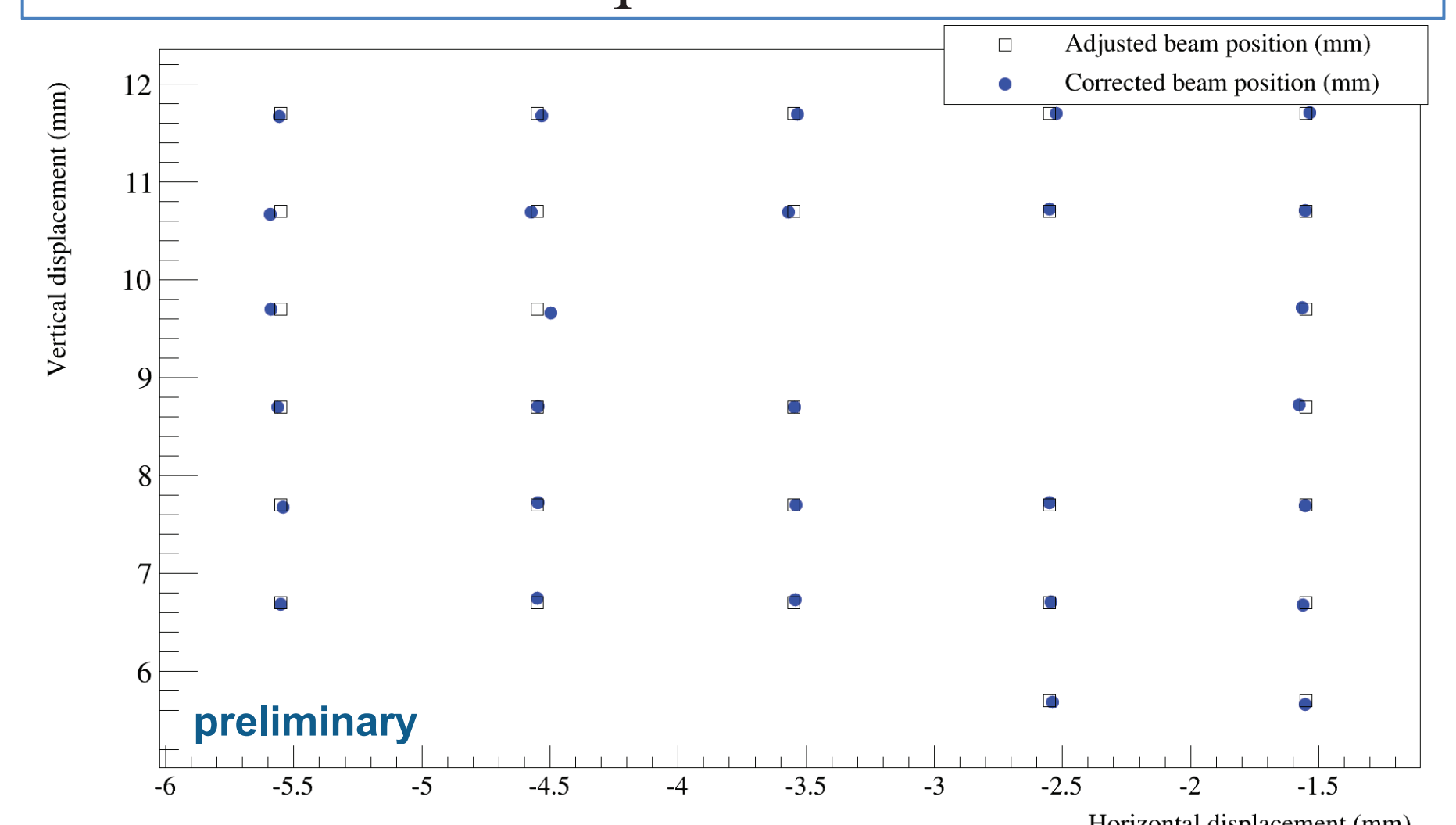
$$\chi_y^2 = \frac{(\chi' \cdot \sin(\varphi) + y' \cdot \cos(\varphi) - y_T - y_{off})^2}{(\sigma_{pos_x} \cdot \sin(\varphi))^2 + (\sigma_{pos_y} \cdot \cos(\varphi))^2 + (\sigma_{y,fluc})^2}$$

- Calibrating out systematic effects of the BPM itself like different numbers of windings for each segment, rotation of the torus or deviations of the radii
- $\sigma_{x,y,fluc}$  respects cycle fluctuation of the horizontal and vertical beam position ( $\sigma_{x,fluc} = 22 \mu\text{m}$ ,  $\sigma_{y,fluc} = 32 \mu\text{m}$ )

Measured beam position without calibration



Measured beam position with calibration



## Summary & Outlook

- The presented Rogowski coil BPM **measures the beam position in horizontal and vertical direction** in accelerator environment
- Successful installation of a moveable and fixed Rogowski Coil BPM in an accelerator environment
- The used minimization algorithm results in calibration factors
- The adjusted and measured beam position are in excellent agreement after calibration with the applied table positions
- Starting with cooling a Rogowski Coil BPM towards a SQUID-BPM

## References

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