

# The White Rabbit Project

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Hardware and Timing section

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## 1 Introduction

## 2 Technology

- Precision Time Protocol (IEEE 1588)
  - Layer 1 syntonization
  - Phase tracking

### 3 Hardware and applications

## 4 Conclusions

## Outline

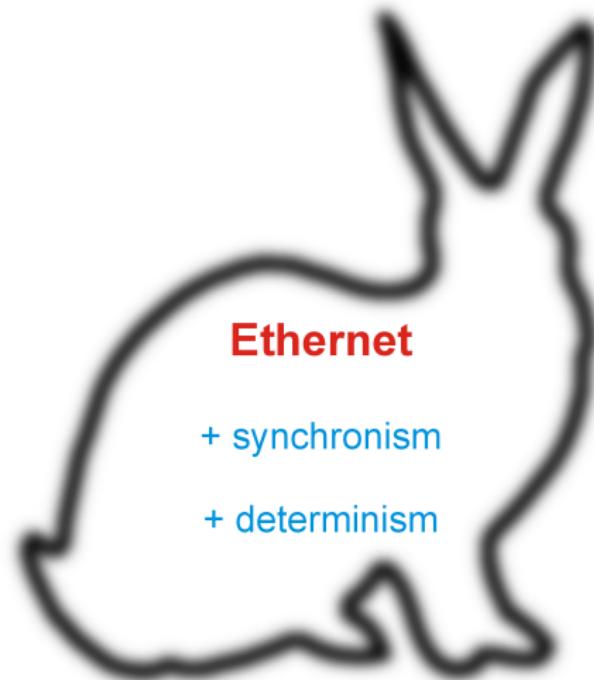
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# What is White Rabbit? 1/2



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    - Commercial support.
    - Many users: CERN, GSI, LHAASO, cosmic ray detectors, metrology labs...

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    - Commercial support.
    - Many users: CERN, GSI, LHAASO, cosmic ray detectors, metrology labs...
  - The most accurate solution for synchronisation in Ethernet networks.
  - A candidate to be standardised under IEEE 1588 (PTP).

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## Accuracy and precision

1 ns time synchronisation accuracy, 20 ps jitter.

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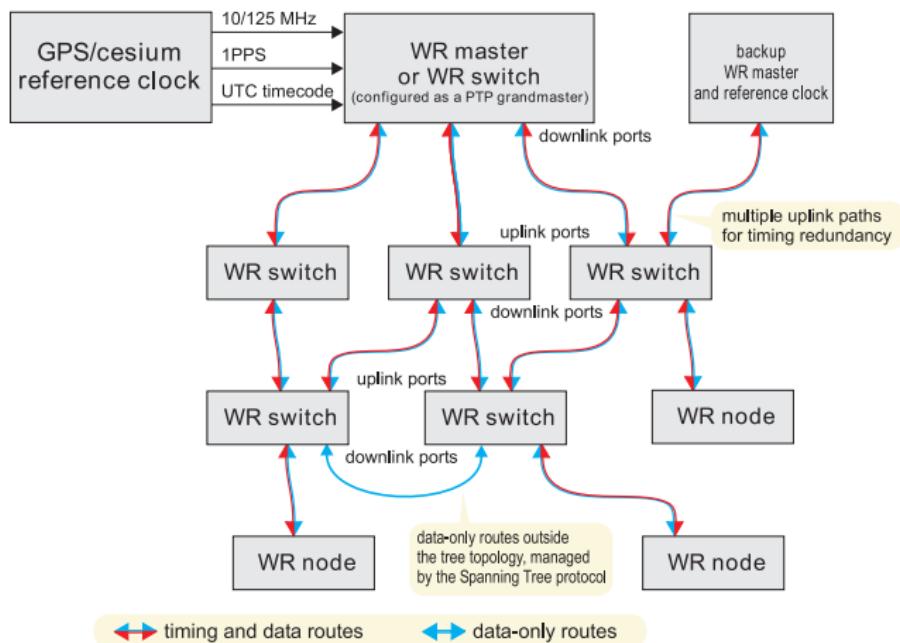
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# Technologies used in White Rabbit

Sub-nanosecond synchronisation in WR is achieved by using the following three technologies together:

- Precision Time Protocol (IEEE 1588).
  - Layer 1 syntonization.
  - DMTD phase tracking.

## Network topology



Links are 1Gb/s single fibre (TX and RX use different wavelengths).

# Precision Time Protocol (IEEE 1588)

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## PTP

Synchronises local clock with the master clock by measuring and compensating the delay introduced by the link.

## Precision Time Protocol (IEEE 1588)

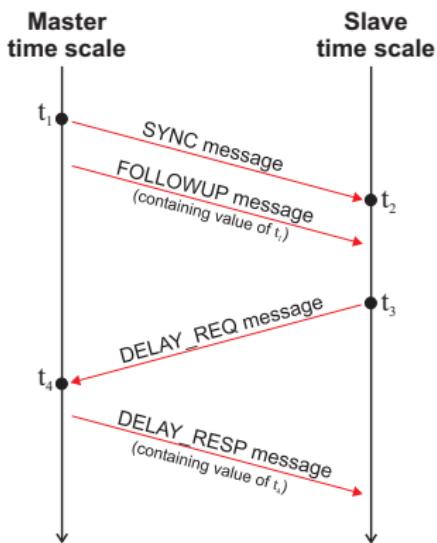
PTP

Synchronises local clock with the master clock by measuring and compensating the delay introduced by the link.

## Frame timestamping

Link delay is measured by exchanging frames with precise hardware transmit/receipt timestamps.

## Precision Time Protocol (IEEE 1588)



Having values of  $t_1 \dots t_4$ , slave can:

- calculate one-way link delay:  

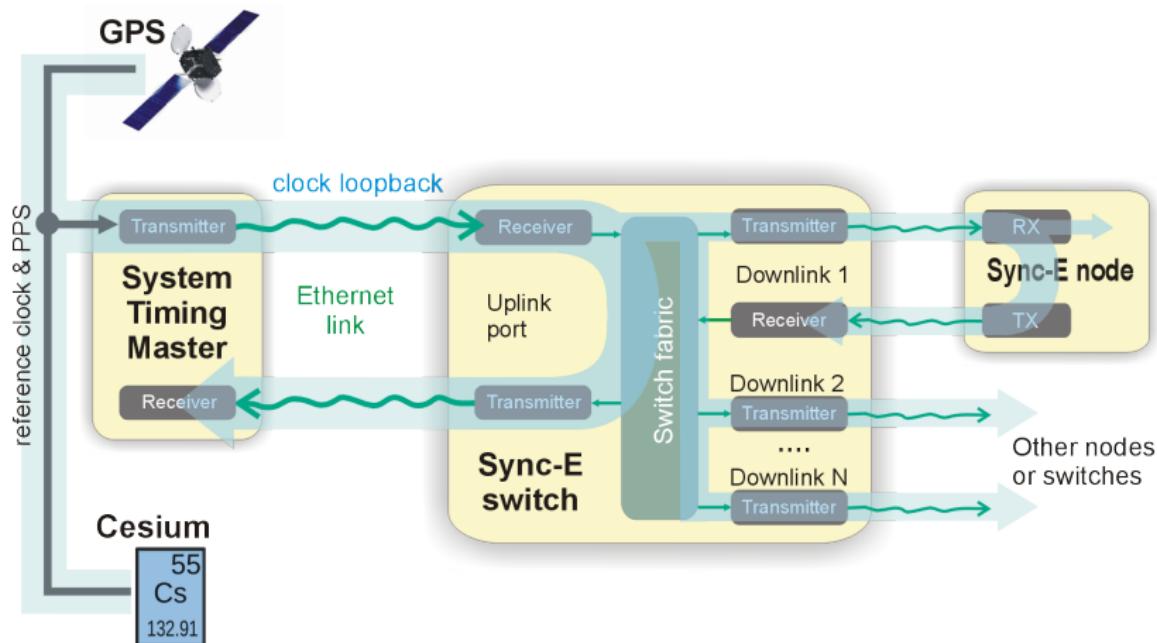
$$\delta_{ms} = \frac{(t_4 - t_1) - (t_3 - t_2)}{2}$$
  - synthesize its clock rate with the master by tracking the value of  
 $t_2 - t_1$
  - compute clock offset:  

$$offset = t_2 - (t_1 + \delta_{ms})$$

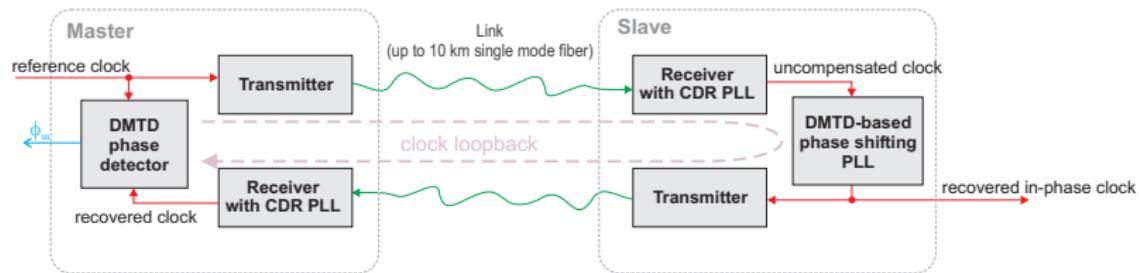
## Disadvantages of traditional PTP

- All nodes have free-running oscillators.
  - Frequency drift has to be continuously compensated, causing lots of network traffic.
  - That doesn't go well with determinism...

## Example: Synchronous Ethernet

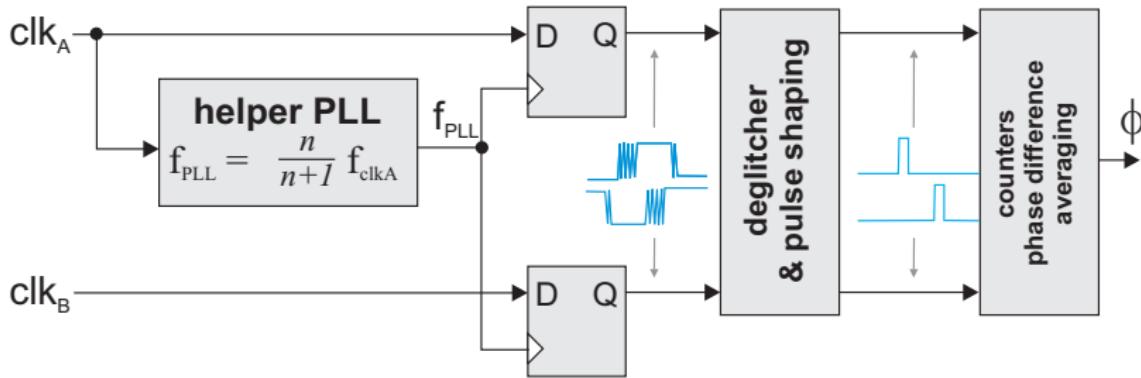


# Phase tracking



- Monitor phase of bounced-back clock continuously.
- Phase-locked loop in the slave follows the phase changes measured by the master.

## Digital DMTD (Dual Mixer Time Difference)



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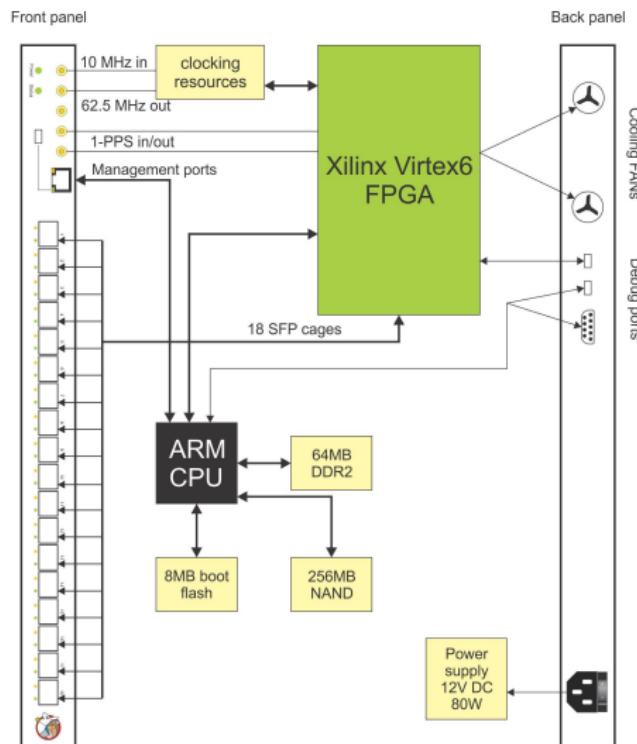
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# White Rabbit switch v3

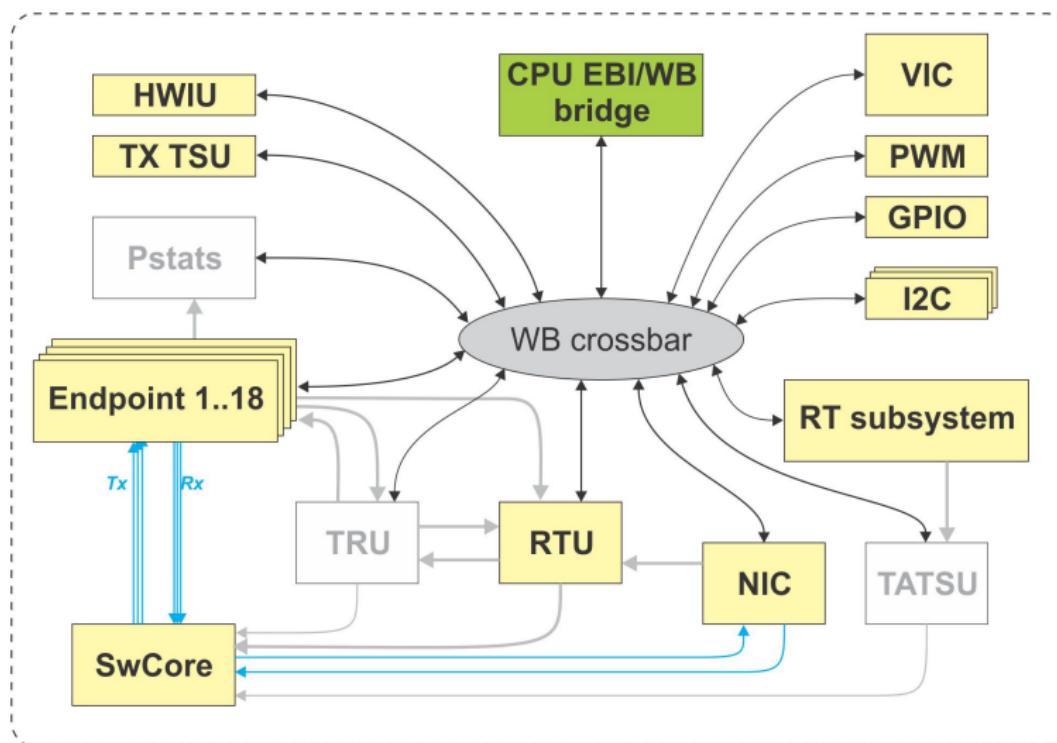


Image courtesy of Seven Solutions

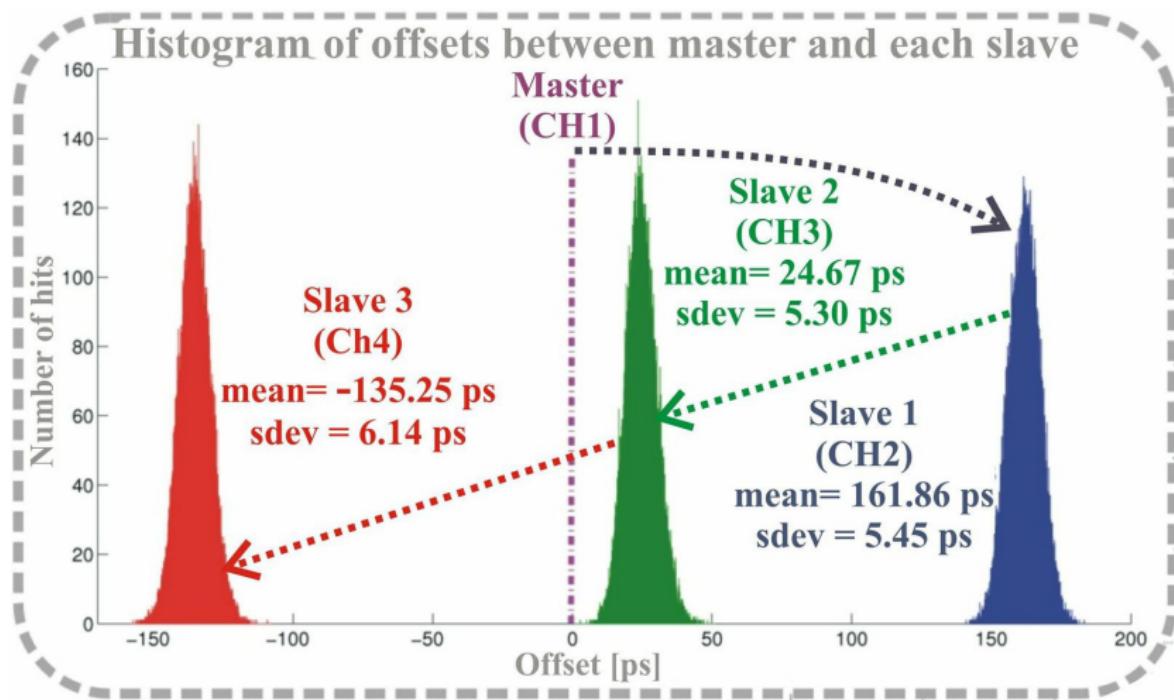
# Simplified block diagram of WR switch



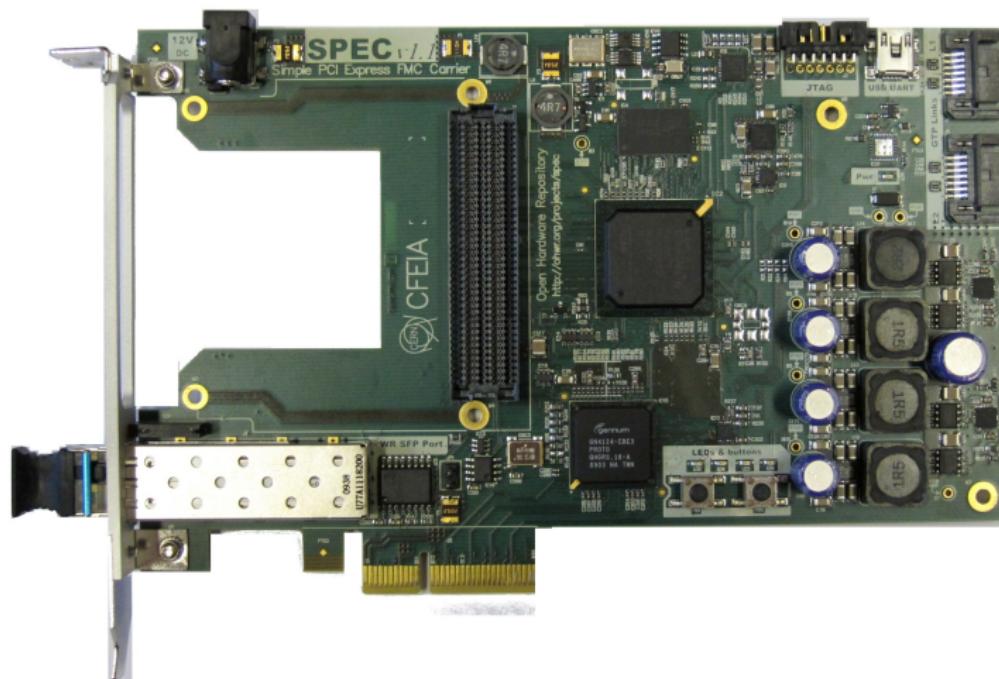
# WR switch FPGA block diagram



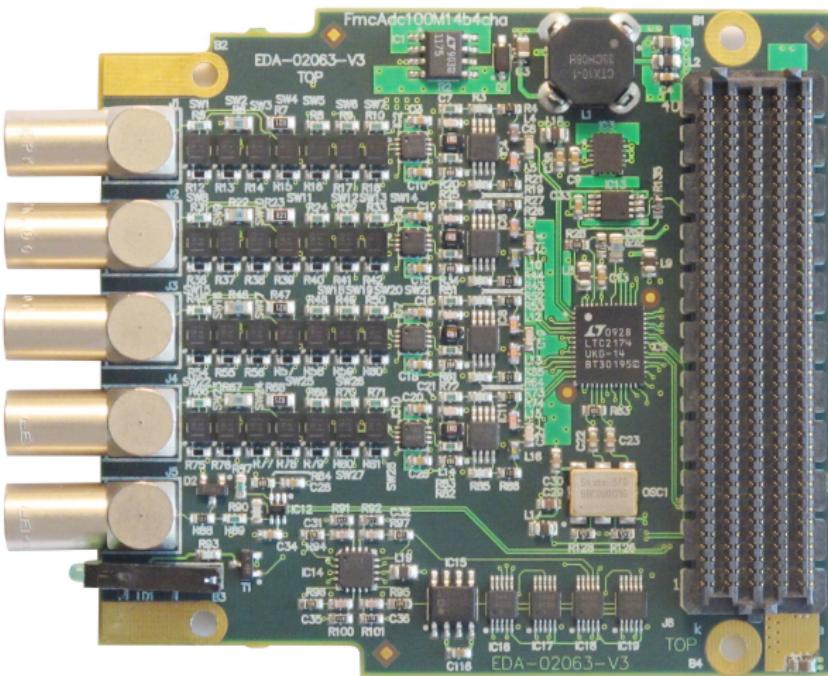
# Synchronisation performance



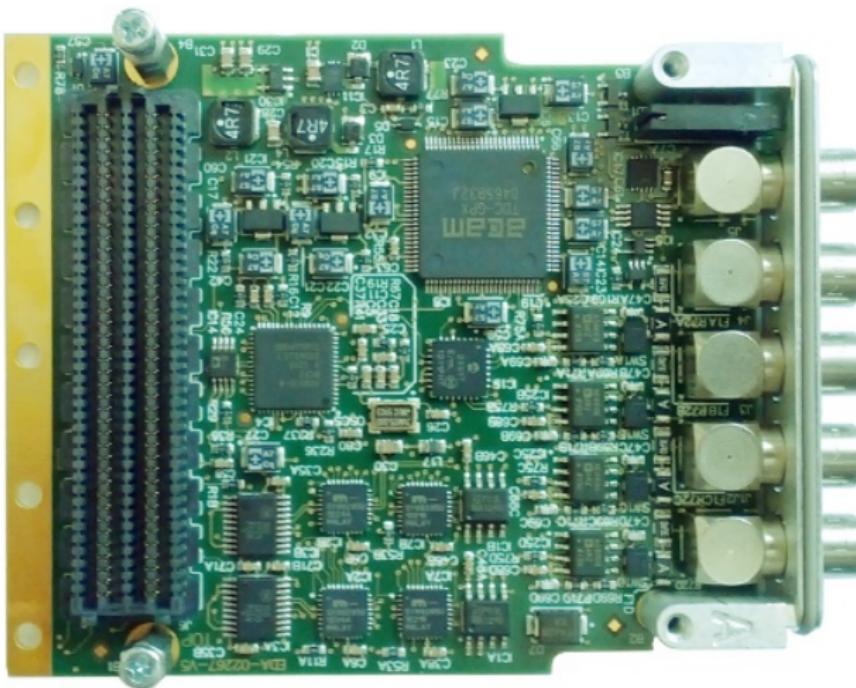
# PCIe FMC carrier



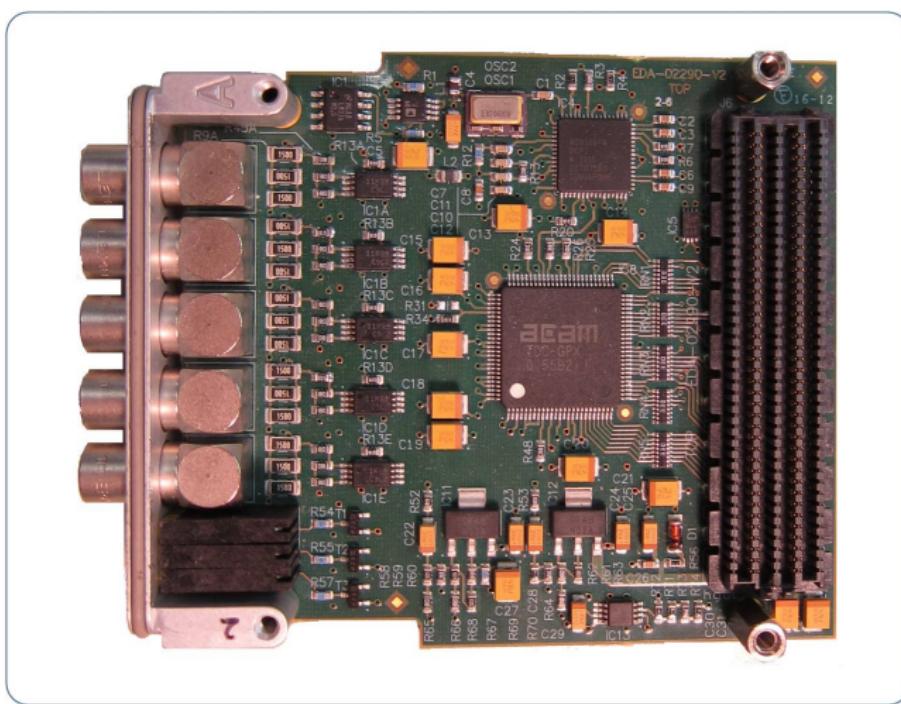
## FMC mezzanine: 100 MSPS 14-bit 4-channel ADC



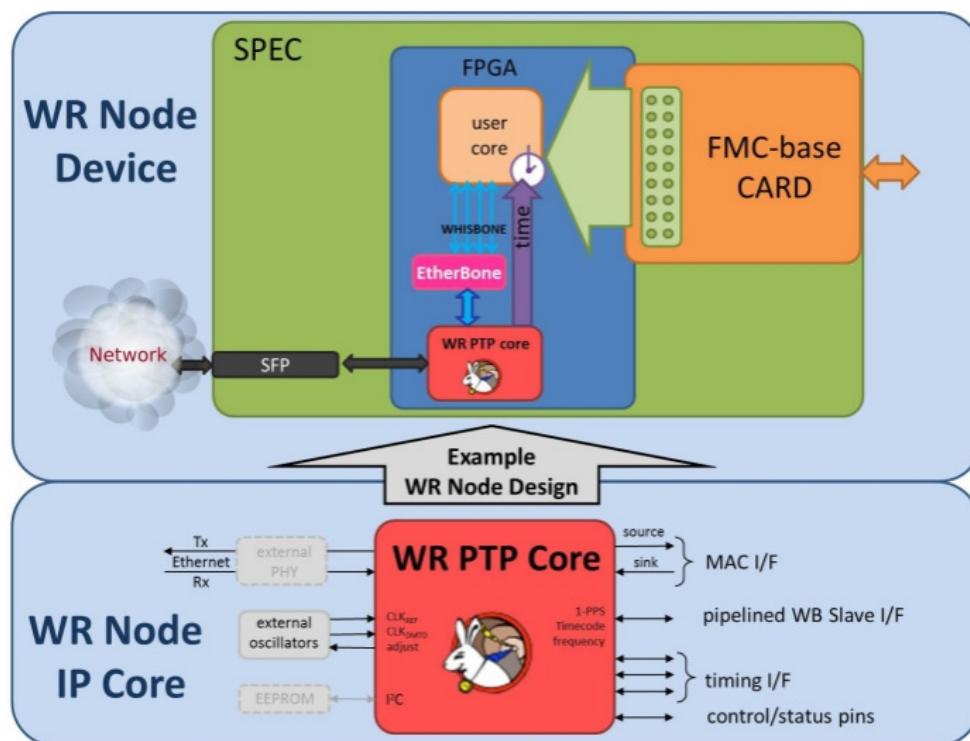
# Fine delay generator FMC



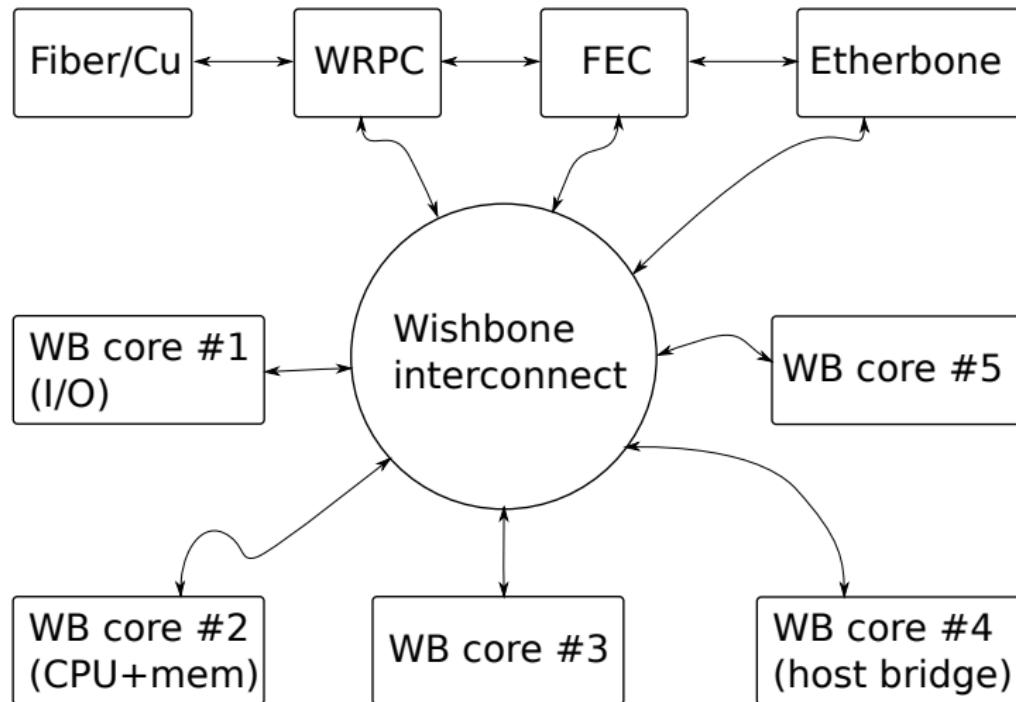
TDC FMC



# Simplified block diagram of a WR node



# Inside the FPGA of a WR node



# Etherbone

## Main goals

- Push the customisation layer up by introducing another generic layer on top of WR.
- Very elegant: the whole network is one huge memory map. All messages are reads and writes into some node address space.
- Sits on top of UDP/IP. UDP multi-cast behaves as expected, triggering multiple WB accesses at the same time in many nodes.

# Possible applications of White Rabbit

**Large-scale  
data acquisition  
systems**

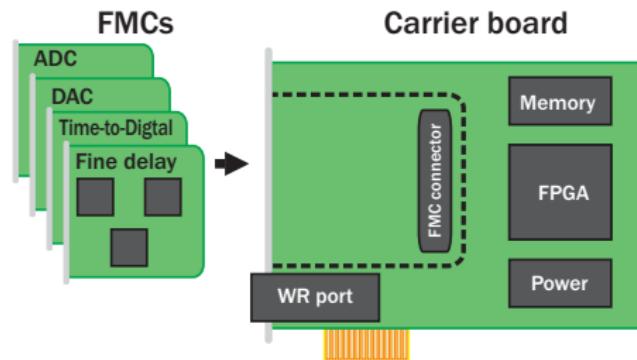
**Precise  
time tagging**

**Clock & trigger  
distribution**

**Robust  
event delivery**



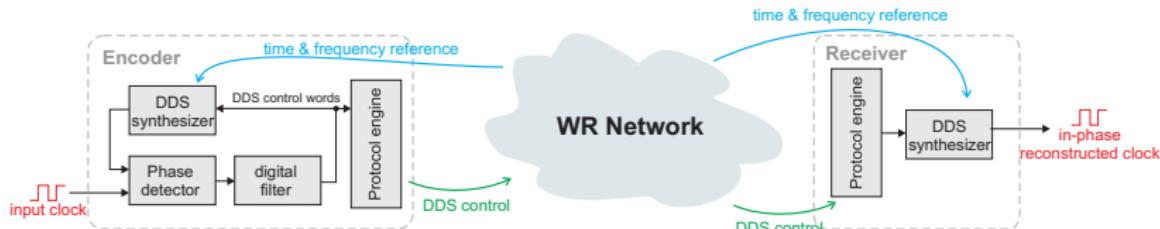
# WR in CERN's BE-CO-HT Hardware Kit



## CERN's BE-CO-HT FMC-based Hardware Kit:

- FMCs (FPGA Mezzanine Cards) with ADCs, DACs, TDCs, fine delays, digital I/O.
- Carrier boards in PCI-Express and VME64x formats (a μTCA carrier also exists in the OHR).
- All carriers are equipped with a White Rabbit port.

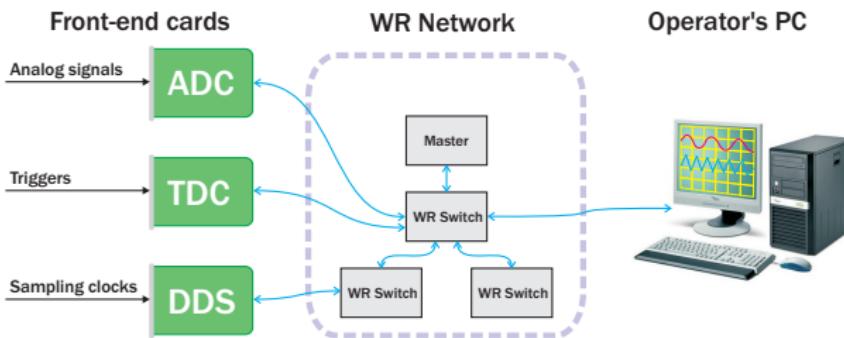
# Ethernet Clock distribution a.k.a. Distributed DDS



## Distributed Direct Digital Synthesis

- Replaces dozens of cables with a single fibre.
- Works over big distances without degrading signal quality.
- Can provide various clocks (RF of many rings and linacs) with a single, standard link.

# Distributed oscilloscope



- Common clock in the entire network: no skew between ADCs.
- Ability to sample with different clocks via Distributed DDS.
- External triggers can be time tagged with a TDC and used to reconstruct the original time base in the operator's PC.

# MIMO feedback systems

The highly deterministic nature of WR networks, coupled with the low latency of the WR switch, make WR an ideal platform for MIMO feedback systems, such as the Fast Orbit Feedback system needed in many synchrotrons.

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  - Now working on better diagnostics and remote management for the switch.
  - IEEE 1588 standardisation effort expected to converge in ~3 years.
  - First operational deployments expected at CERN and elsewhere in 2015.

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For more information see

<http://www.ohwr.org/projects/white-rabbit/wiki>