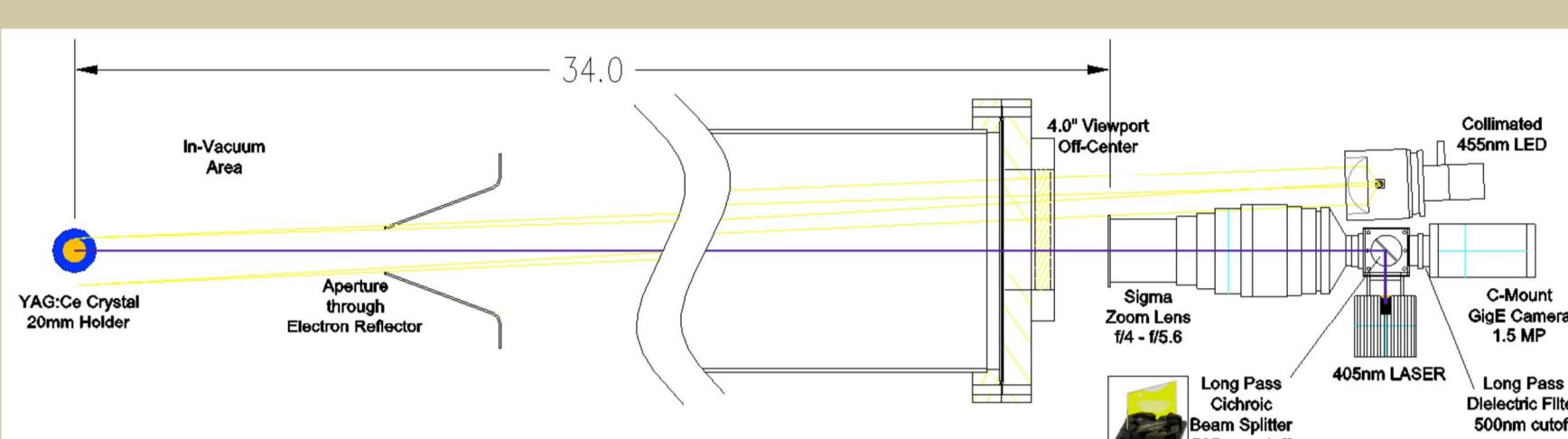
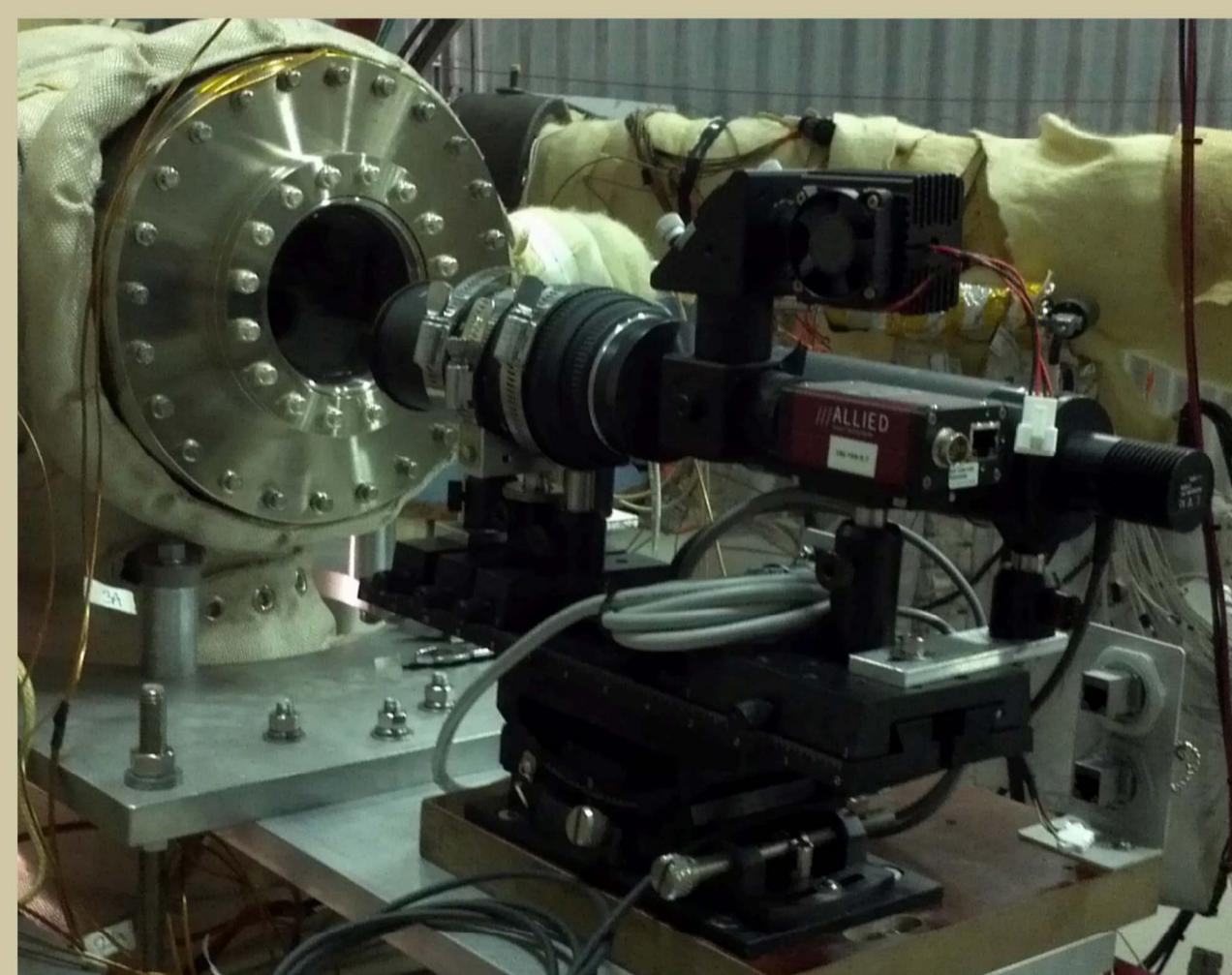


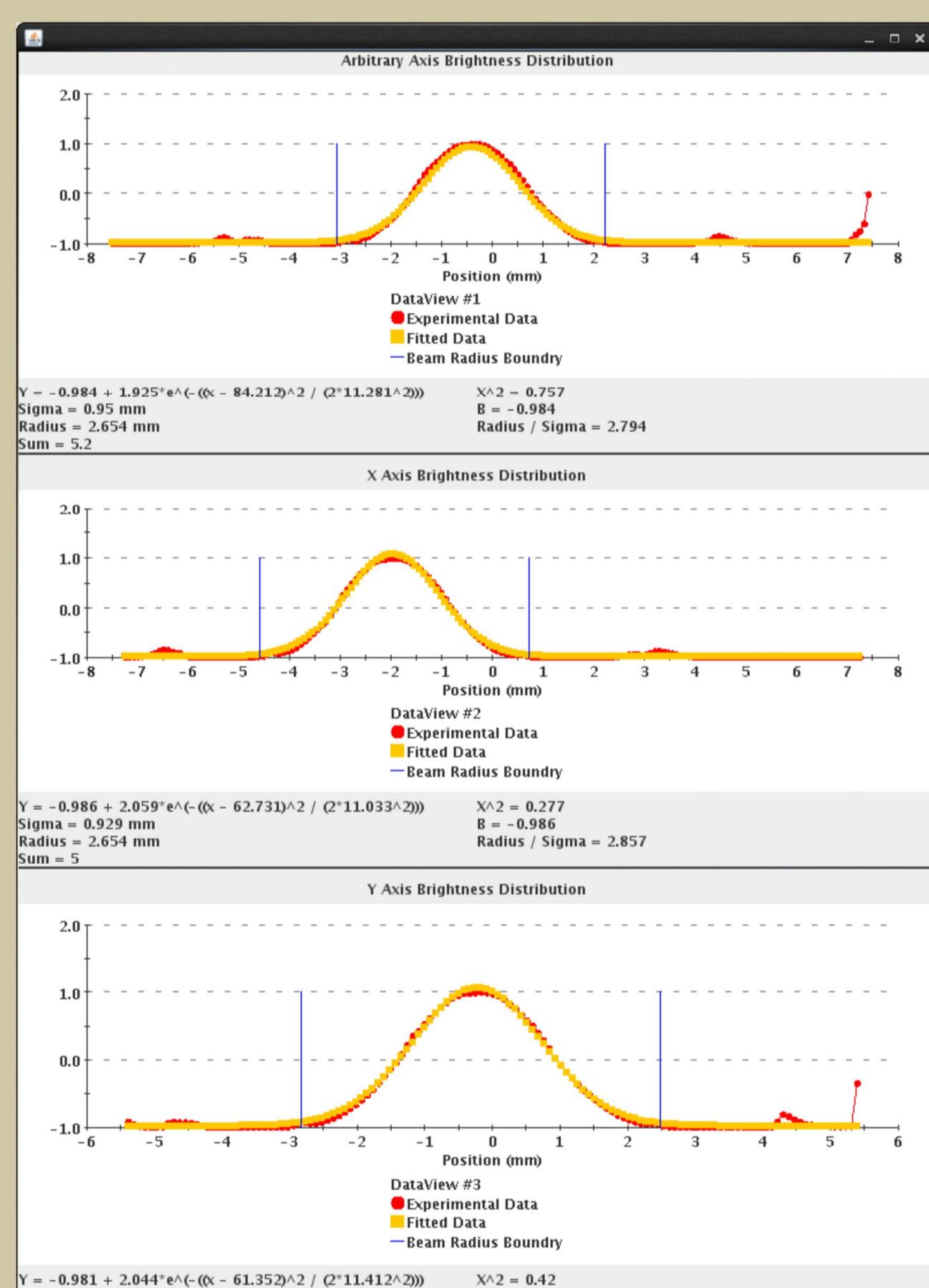
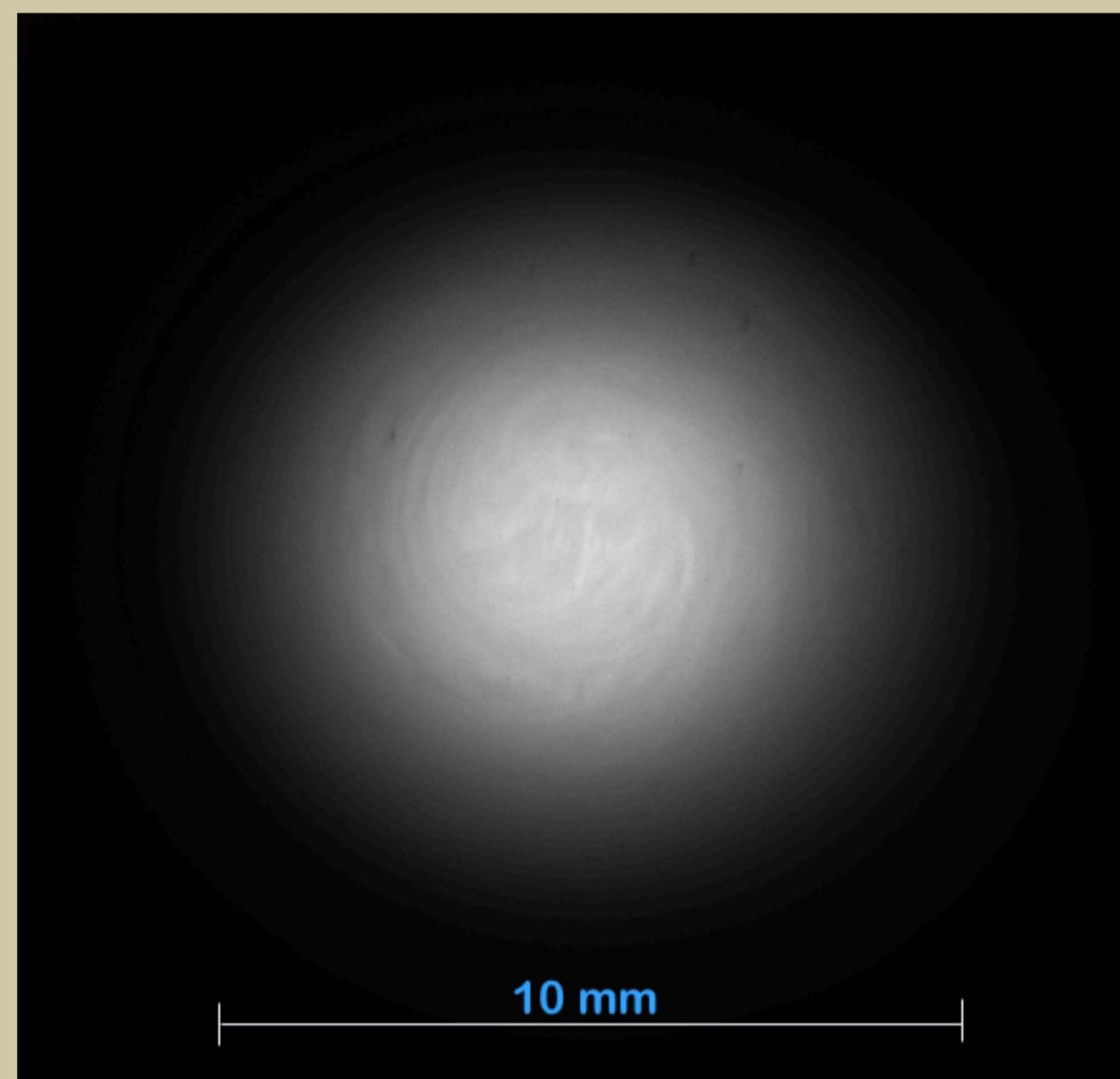
Optics Assembly



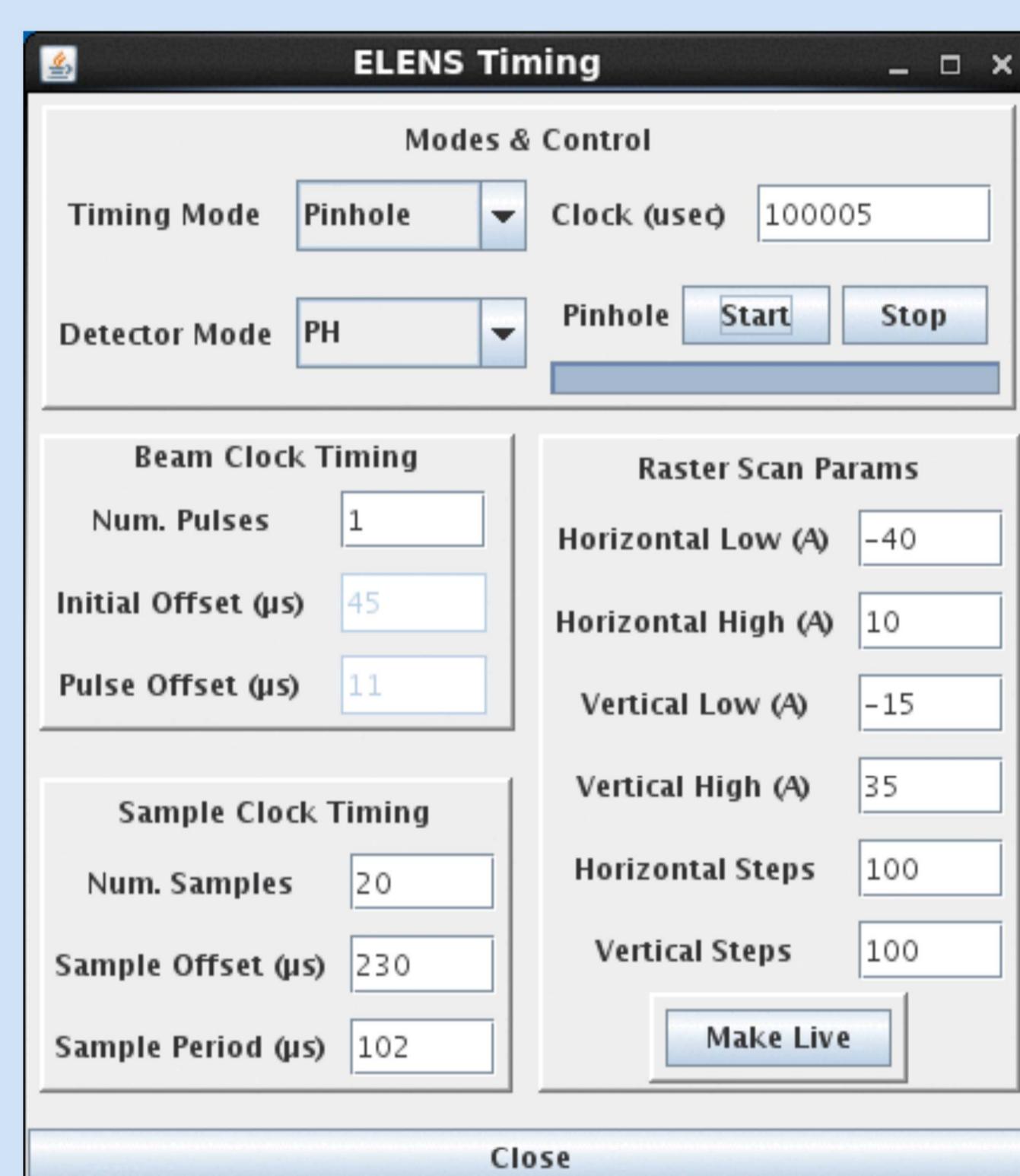
Camera: Manta G145B, GigE, 2/3" CCD 1.5MP 12-bit
 Zoom Lens: manual
 Target: YAG:Ce crystal (0.1mm) d=1.3m
 Illumination:
 • Adjacent mounted White projection LED
 • Adjacent mounted 455nm (blue) projection LED
 • On Axis 405nm (violet) Laser via dichroic beam splitter



Optics assembly mounted downstream of collector window.



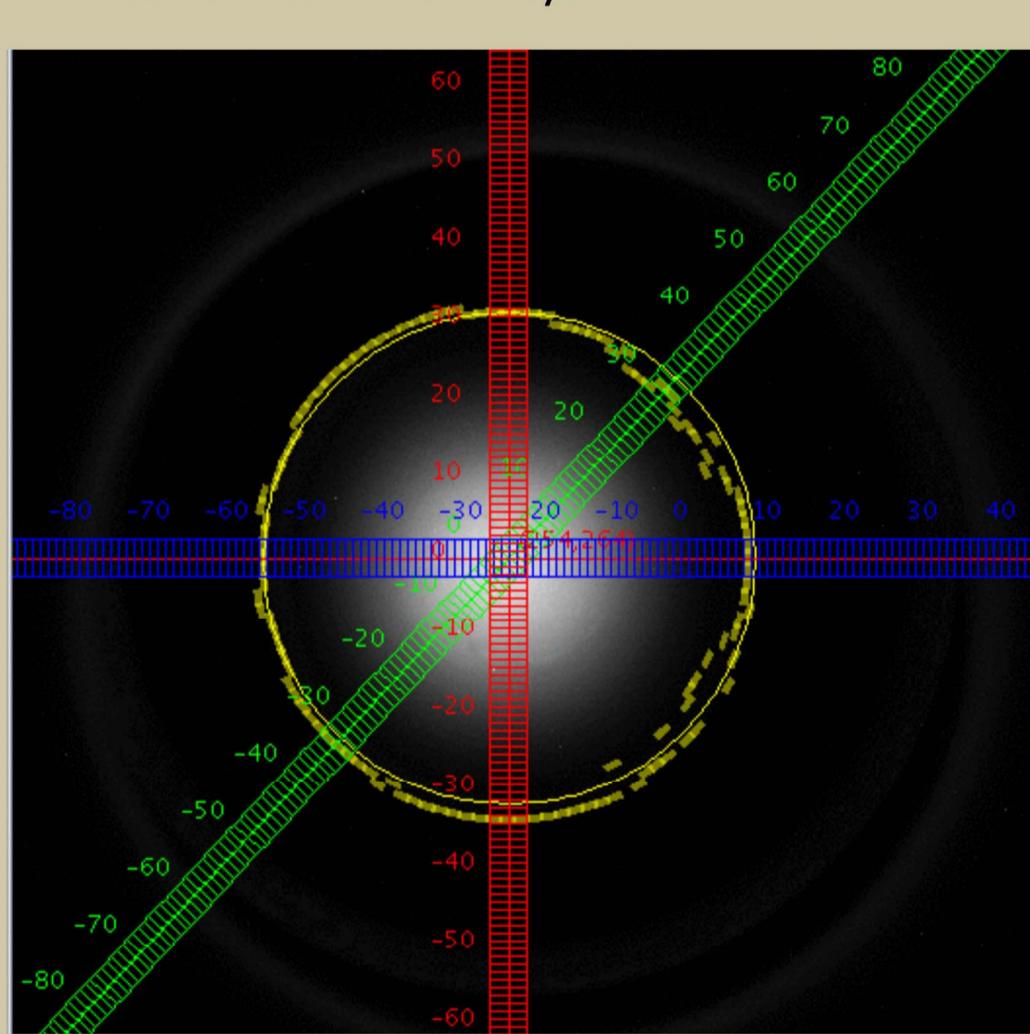
PinHole Scan Parameters



YAG Profile 70mA, 6keV

Axis Definition for Profile Plots

Controls are provided in the software to define an arbitrary axis, in addition to the X & Y axes, along which to compute average values within defined boxes, and plot the intensity profile for the three axes, as shown on the right. A boundary definition circle is automatically defined at 2.5% intensity.

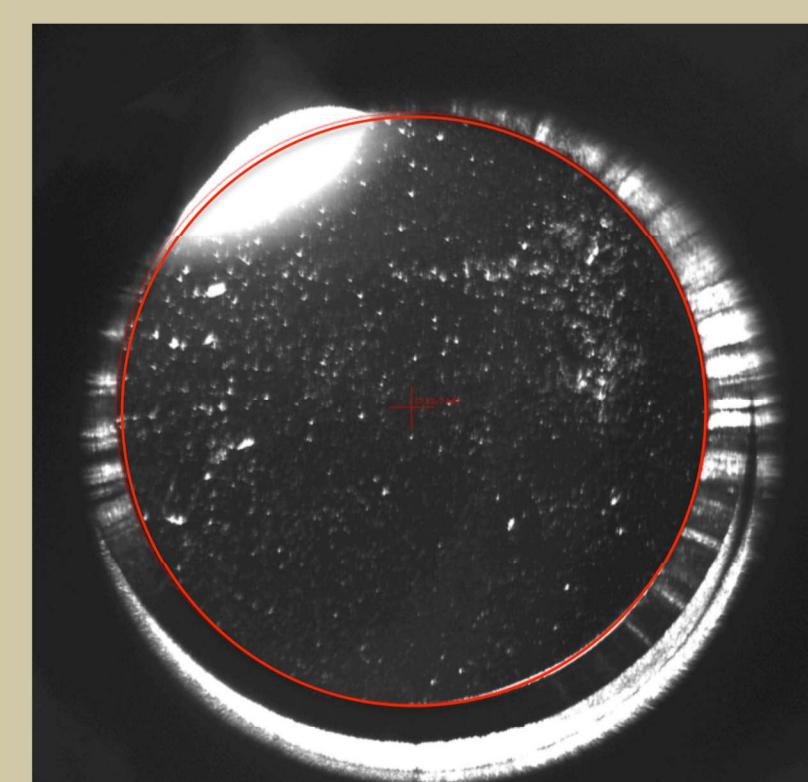


Profiles & Statistics

The plots generated include the averaged intensity points with a fitted curve overlaid. The blue lines show the beam radius boundary. Calculated data include the trend line formula, Sigma, radius and χ^2 .

CALIBRATION FUNCTIONS

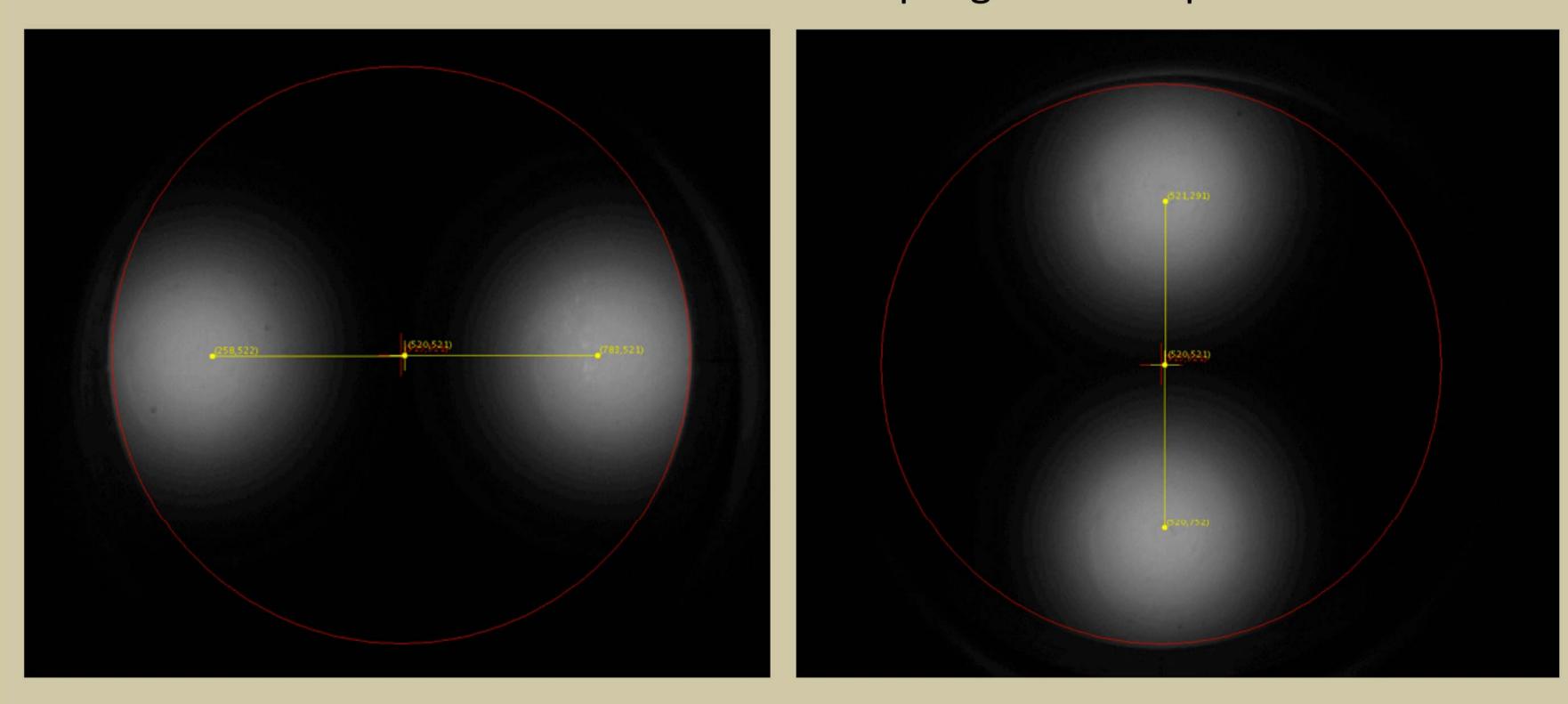
Procedures are provided in the software to calibrate the YAG image.



Reference Circle
 On illuminated YAG screen

Reference Circle - the red reference circle is drawn on the 20mm crystal holder bezel. This allows the software to compute the pixel/mm scaling coefficient.

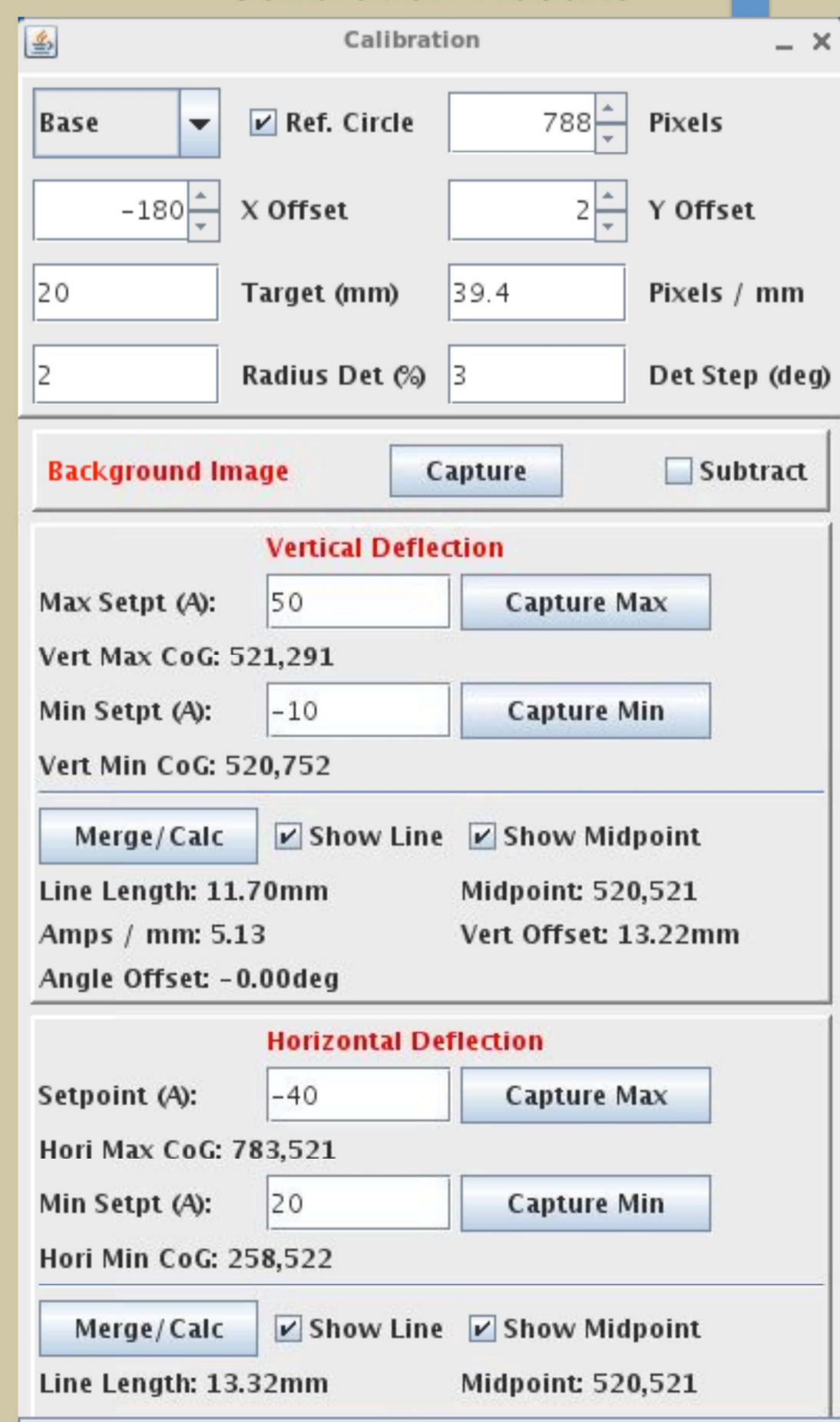
Deflection Coefficients - YAG screen images are taken at max horizontal & vertical steerer deflections. The software plots lines between the max deflected image pairs. The length and skew angle of the lines gives the steerer calibration coefficient (A/mm) and the skew angle error due to coupling between planes.



Horizontal Deflection

Vertical Deflection

Calibration Results

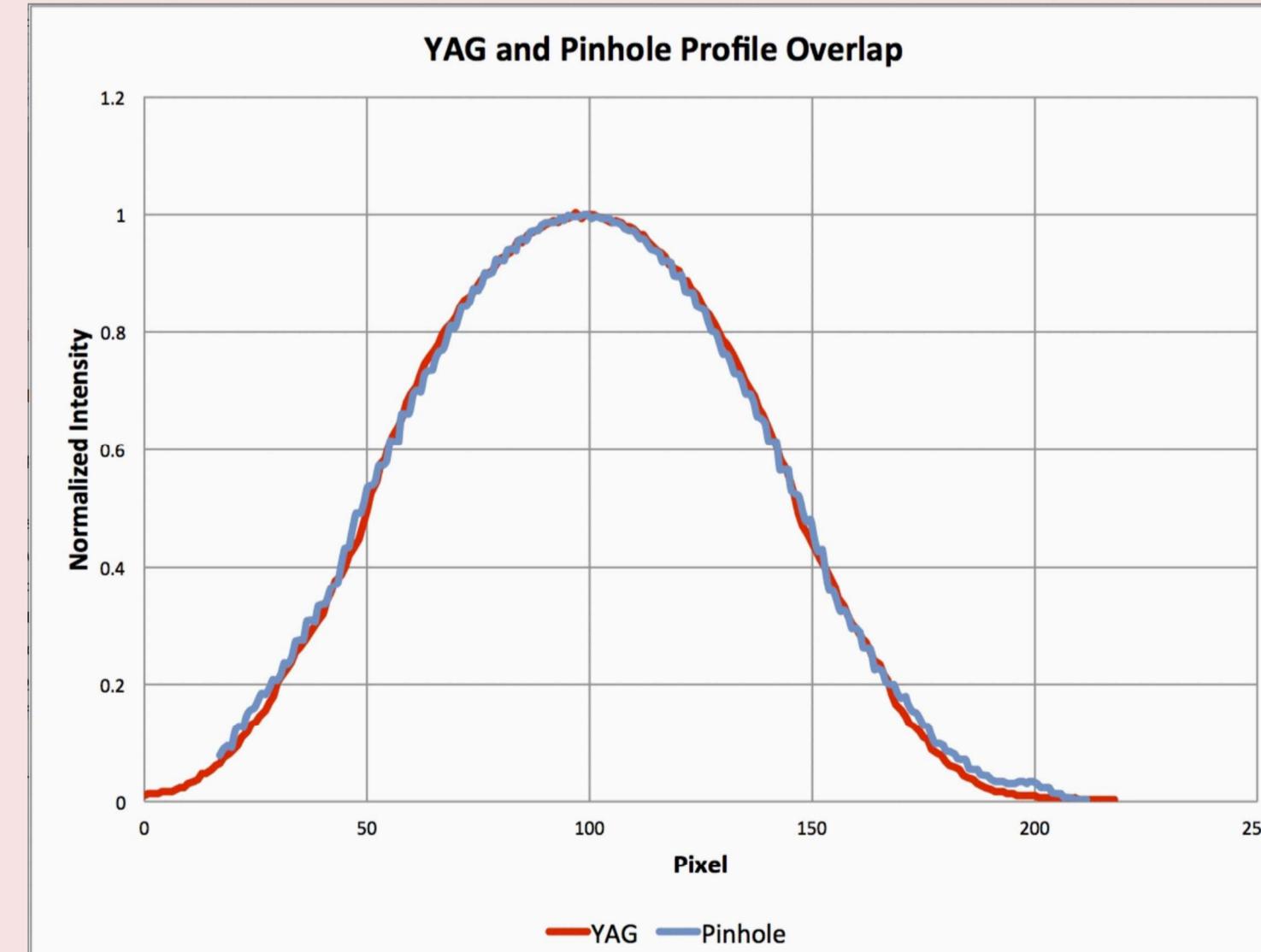


Machine Measurement Parameters

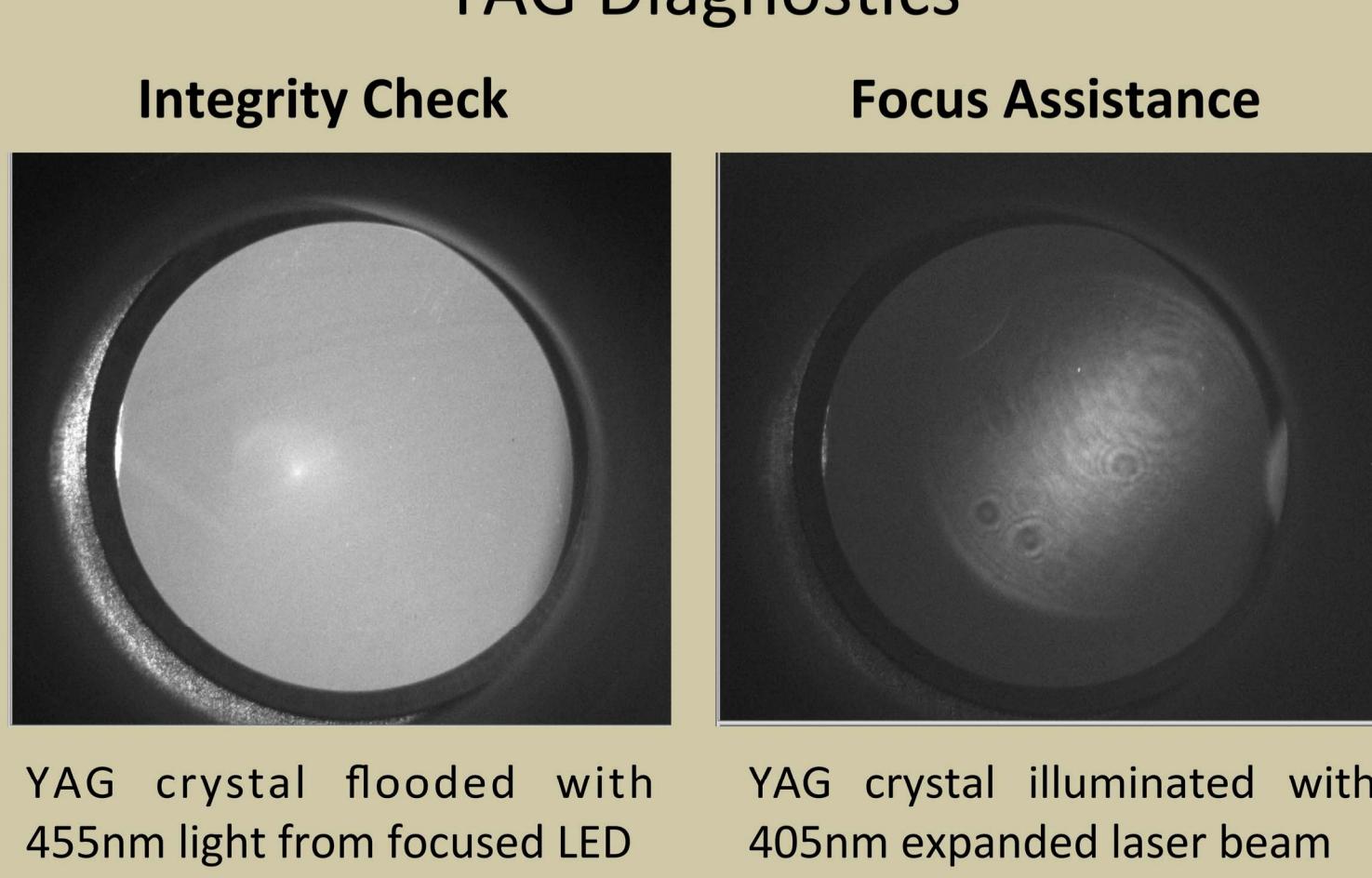
Parameter	YAG	PinHole
Beam Energy	6 KeV	6 keV
Beam Current	70 mA	210 mA
Pulse Width	1 μs	12.5 μs
Rep Rate	1 Hz	10 Hz
Resolution	\sim 40 pixels/mm	\sim 8.5pts/mm

Comparison of YAG vs PinHole Scan Beam Image Profiles

Excellent agreement of the two profiling methods. YAG screen shall be the preferred method with the PinHole scan retained as a back-up measuring system.



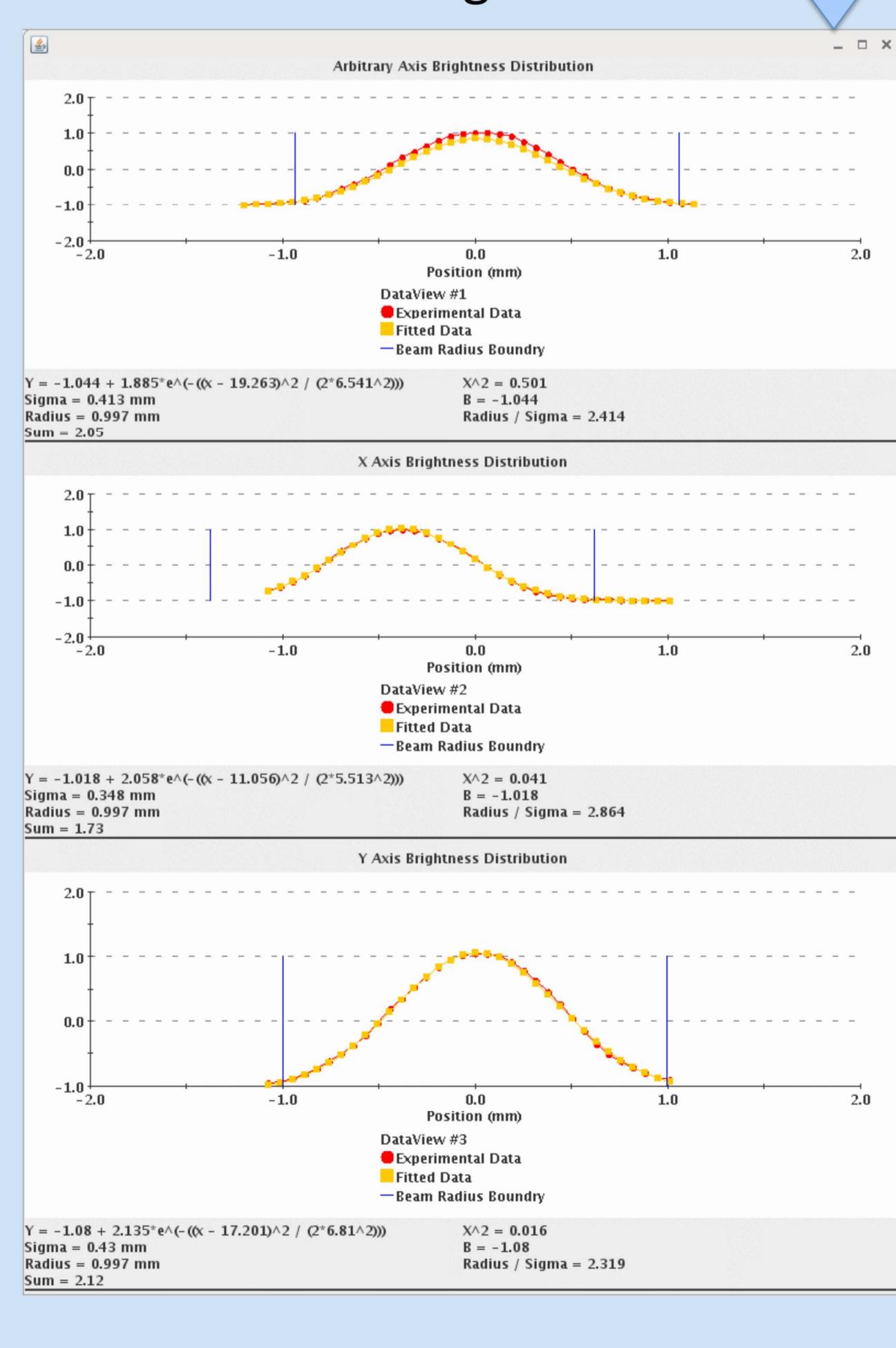
YAG Diagnostics



Integrity Check

Focus Assistance

PinHole Scan Image Profiles

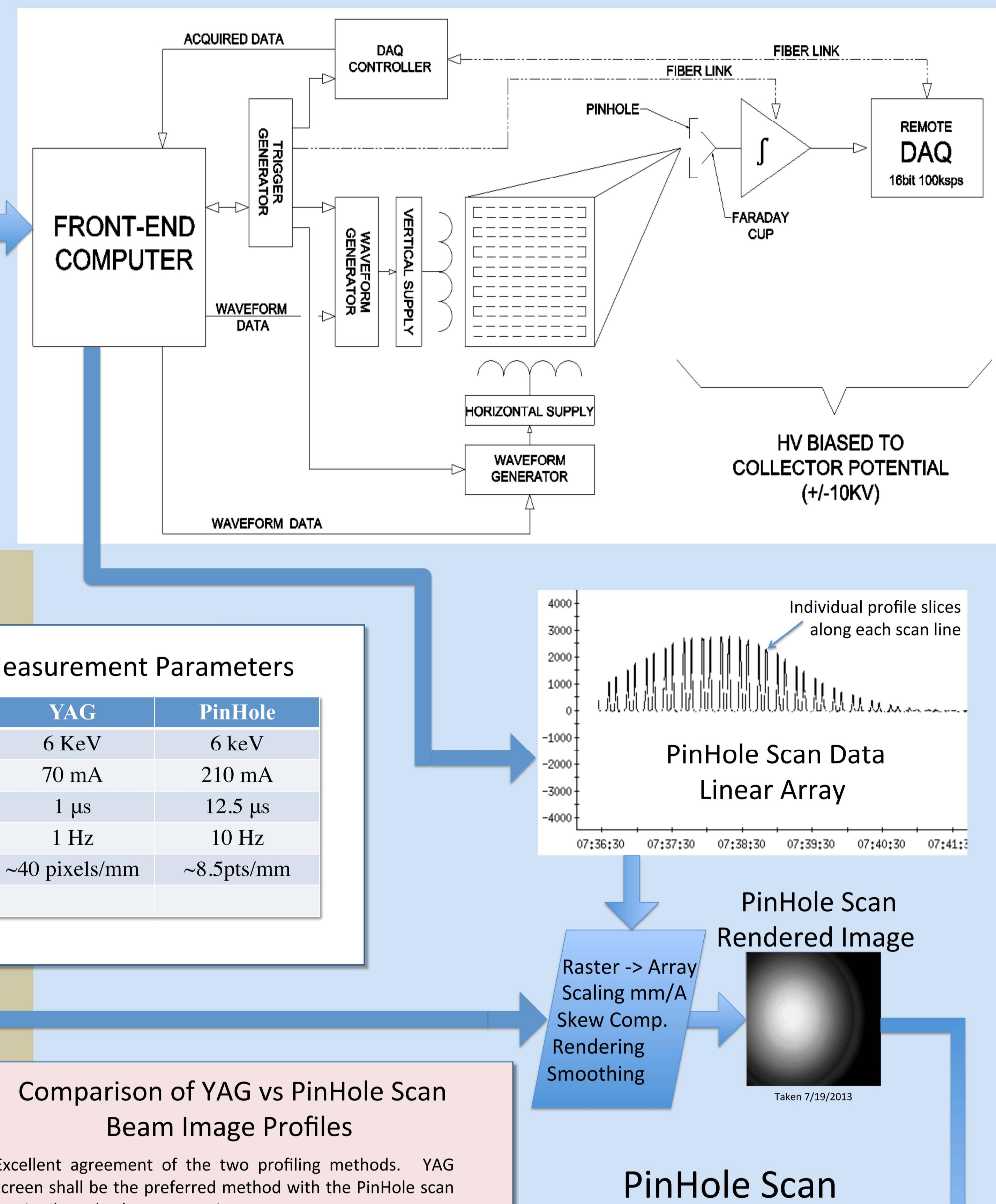


PinHole Scan Profile 210mA, 6keV

Pinhole scanning system is comprised of a scanned electron beam by controlled steering coils. Beam is raster scanned over a fixed faraday cup covered with a 0.1mm pinhole mask. The major hardware components are:

- Waveform Generators** - controller with waveform table coupled via fiber to a remote module with an analog output to generate arbitrary waveforms as well as 4 analog inputs for power supply readbacks.
- Timing inputs synchronize stepping through the waveform table.
- Data Acquisition Module** - module with 4 Analog inputs and is isolated from its controller by a bidirectional fiber optic link. The controller contains a readback buffer for the data as well as external timing sync inputs.
- Trigger Generator** - multi-channel module utilizing a widely-distributed master clock and event link to generate output pulses with programmable delays and widths with deterministic timing.
- Front End Computer** - (FEC) a VME-based controller running the VxWorks operating system used to control the other three components above and to bridge their parameters and data with the rest of the controls system infrastructure over an Ethernet network.

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PinHole Scan Rendered Image

Taken 7/19/2013

PinHole Scan 210mA, 6keV