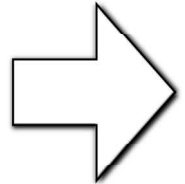
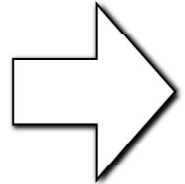


**Understanding the  
Platform - UAV IRIS+**



**Coupling A Robot Gripper**



**Creating a Set of  
Movement Functions  
To Control the UAV**