





#### Memory Organization for Energy-Efficient Learning and Inference in Digital Neuromorphic Accelerators

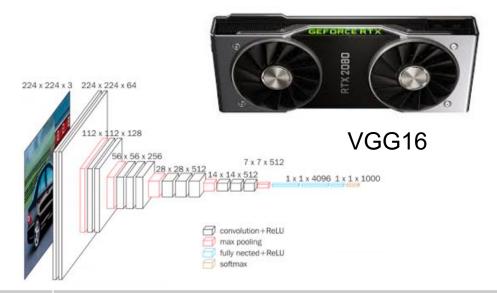


Clemens JS Schaefer<sup>1</sup>, Patrick Faley<sup>1</sup>, Emre O Neftci<sup>2</sup> and Siddharth Joshi<sup>1</sup>

<sup>1</sup> University of Notre Dame du Lac - Intelligent Microsystems Lab <sup>2</sup>UC Irvine - Neuromorphic Machine Intelligence Lab

#### Potential of Biological Neural Networks

 Biological systems: continuously learning, unreliable stimuli, noisy environment and still energy efficient

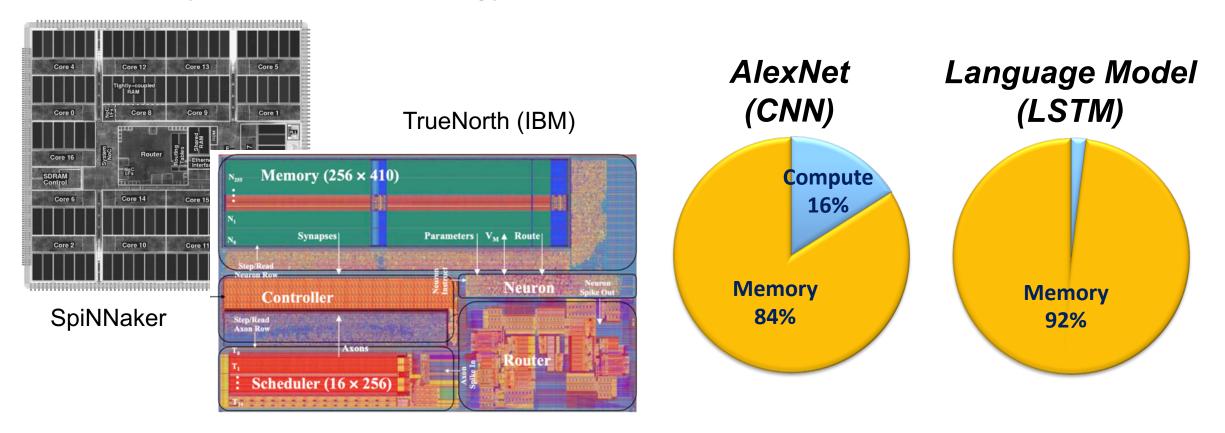




| Power                                       | 180-360W                | ~0.000036344W     |
|---|-------------------------|-------------------|
| Volume/Space                                | 267 mm x 116 mm x 35 mm | > 1mm x 1mm x 1mm |
| Computational Resources (number of neurons) | 14,719,656 neurons      | ~135,000 neurons  |

#### **Neuromorphic Systems**

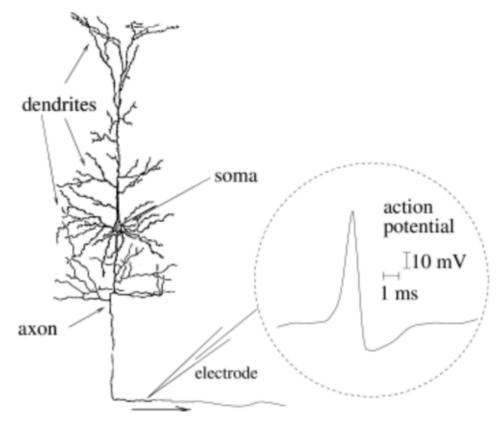
- Co-development of hardware and software to mimic biological systems
- Neurosynaptic core: neuron and synapse subsystem
- Memory access major energy driver



### **Spiking Neural Networks**

- Hodgkin and Huxley [7] analyzing biological nervous systems
- Communication and compute through action potential (spikes)
- Various formulations, e.g. Hodgkin-Huxley, Izhikevich, Integrate-and-Fire



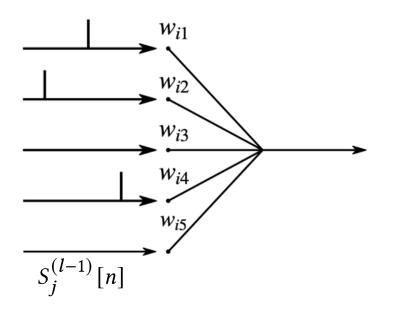


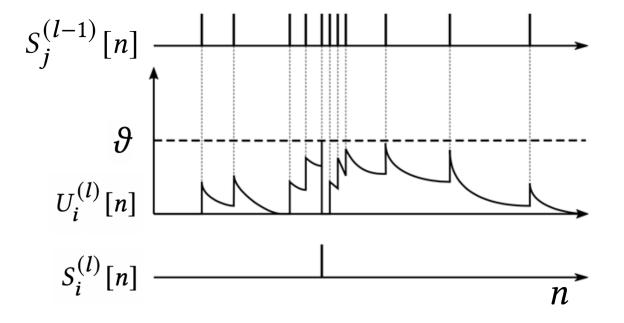
### **Spiking Neural Networks**

- Neuron state is governed by incoming spikes, corresponding weights and reset dynamics [8]
- Spikes are generated by step-function

$$U_i^{(l)}[n] = \sum_j W_{ij}^{(l)} P_j[n] - \delta R_i[n],$$

$$S_i^{(l)}[n] = \Theta(U_i^{(l)}[n] - \vartheta),$$





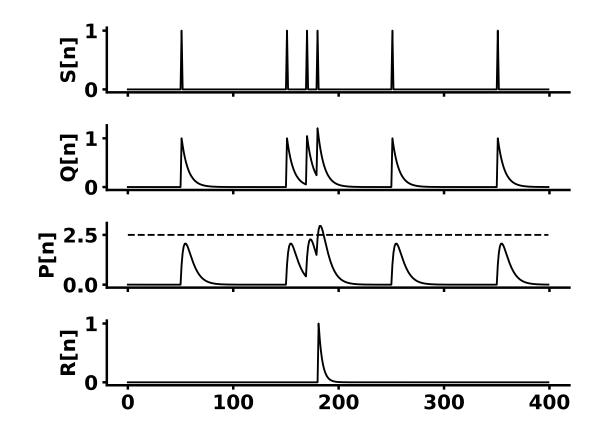
### **Spiking Neural Networks**

- Neural dynamics defined by synapse state (Q), membrane trace (P) and refractory state (R)
- Behavior of neurons defined through time constants (alpha, beta, gamma)

$$Q_{j}[n+1] = \alpha Q_{j}[n] + S_{j}^{(l-1)}[n],$$
  

$$P_{j}[n+1] = \beta P_{j}[n] + Q_{j}[n],$$
  

$$R_{i}[n+1] = \gamma R_{i}[n] + S_{i}^{(l)}[n].$$



# **Training Spiking Neural Networks**

- Evolutionary learning, e.g. genetic algorithms
- Biologically inspired training algorithm, e.g. hebbian learning (spike-timing-dependent plasticity)
- Traditional machine learning, e.g. backpropagation
- Surrogate Gradient Learning, e.g. SuperSpike [13, 8]

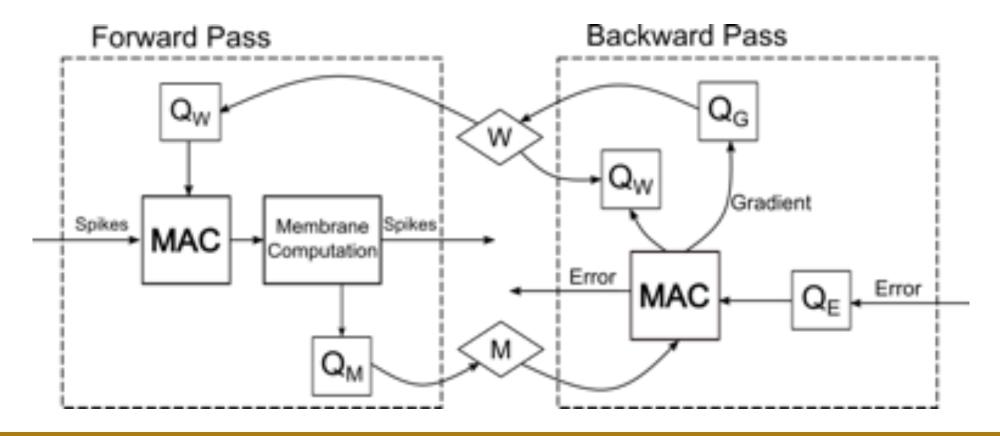
$$\frac{\partial}{\partial W_{ij}} \mathcal{L} = \frac{\partial}{\partial W_{ij}} U_i \frac{\partial}{\partial U_i} S_i \frac{\partial}{\partial S_i} \mathcal{L}$$

$$-\Delta W_{ij}^l \propto \frac{\partial}{\partial W_{ij}} \mathcal{L} = P_j[n] \sigma'(U_i^l[n]) E_i[n]$$

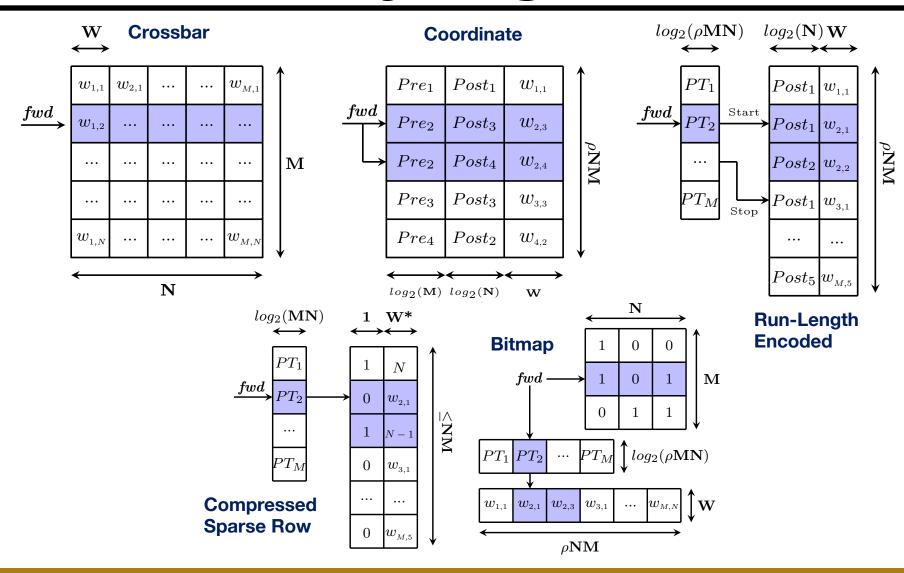
$$U[n]$$

# **Quantizing SNNs**

- Quantization to integers: clipping and rounding of values
- Forward pass: weights and copy of membrane potential
- Backward pass: errors and gradients (with stochastic rounding)



# **Memory Organization**

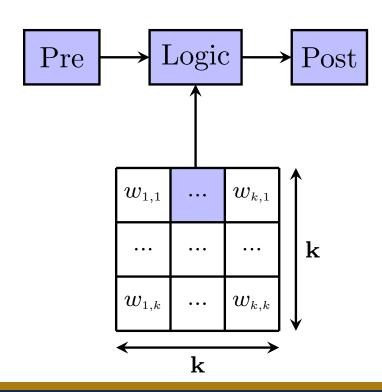


### **Memory Organization**

#### **Functional for 2D Convolution**

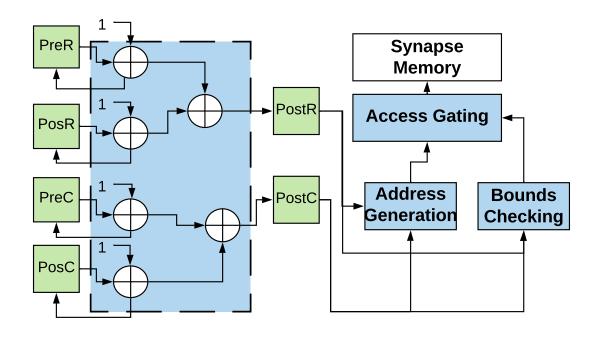
#### Froward pass

$$f(PreR, PosR) = PreR + PosR$$
  
 $f(PreC, PosC) = PreC + PosC$ 



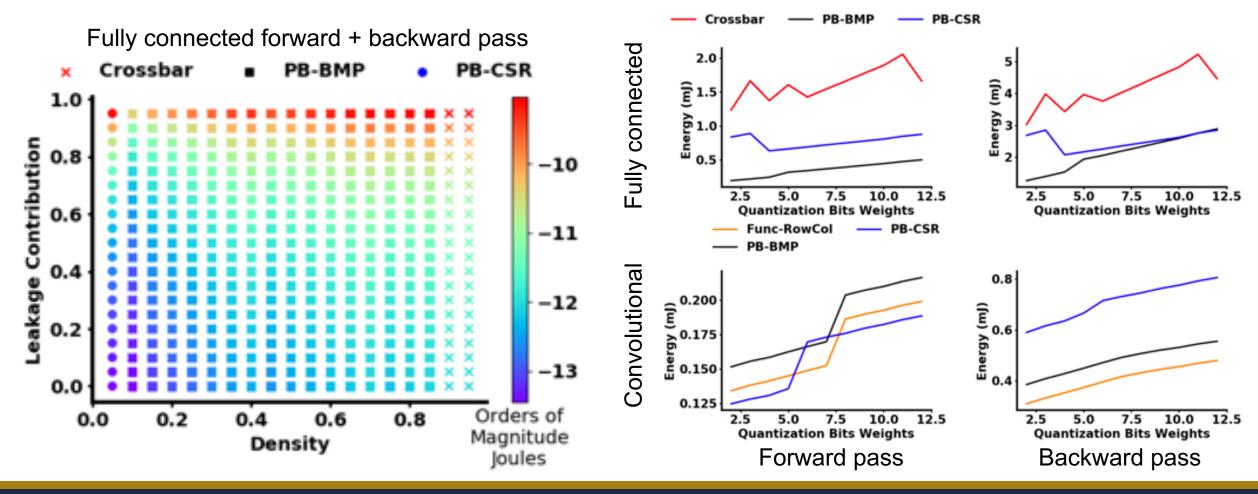
#### **Backward pass**

$$f^{-1}(PostR, PosR) = PostR - PosR$$
  
 $f^{-1}(PostC, PosC) = PostC - PosC.$ 



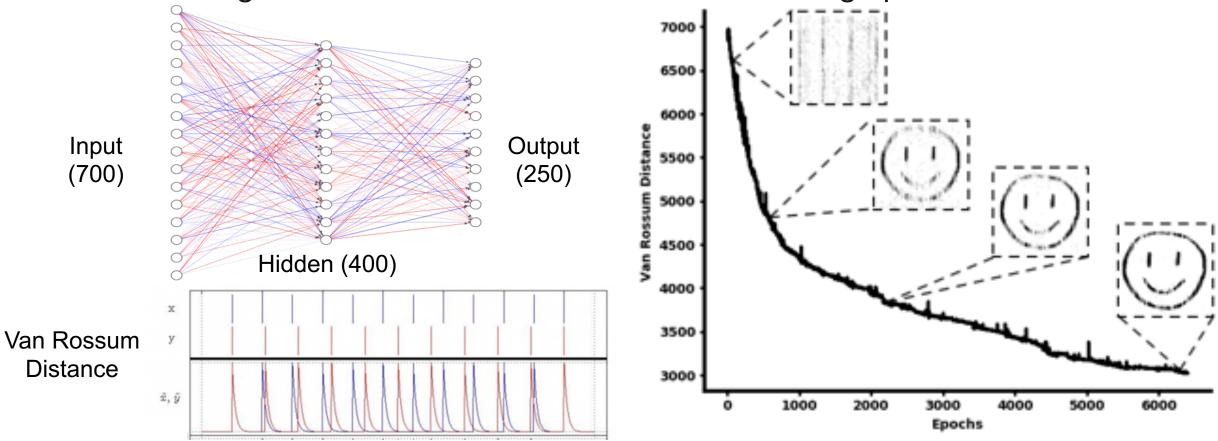
#### **Experiments and Results**

 Energy consumption of one fully connected layer (input 728, output 128) and convolutional layer (input 28x28, kernel 3x3, in channels 32, out channels 32)



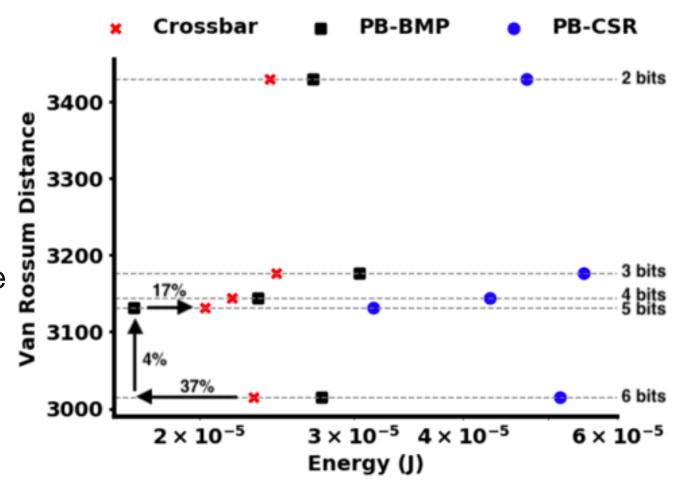
#### **Experiment Setup**

- Task: spatial-temporal pattern retention
- Leaky-integrate and fire neurons trained with BPTT and surrogate gradients
- Recording Van Rossum distance over 10000 training epochs



#### Conclusion

- Encoding schemes can exploit weight sparsity for energyefficiency
- Functional weight encoding for patterned connectivity
- Quantization induced sparsity and accuracy trade-offs translate to accuracy energy trade-offs
- Energy efficiency depends on access efficiency and memory size



#### References

- 1. S. Wu, G. Li, F. Chen, and L. Shi, "Training and inference with integers in deep neural networks," arXiv preprint arXiv:1802.04680, 2018.
- 2. S. Joshi, B. U. Pedroni, and G. Cauwenberghs, "Neuromorphic event- driven multi-scale synaptic connectivity and plasticity," in 2017 51st Asilomar Conference on Signals, Systems, and Computers. IEEE, 2017, pp. 1–5.
- 3. M. v. Rossum, "A novel spike distance," Neural computation, vol. 13, no. 4, pp. 751–763, 2001.
- 4. M. Davies, N. Srinivasa, T. H. Lin, G. Chinya, P. Joshi, A. Lines, A. Wild, and H. Wang, "Loihi: A neuromorphic manycore processor with on-chip learning," IEEE Micro, vol. PP, no. 99, pp. 1–1, 2018.
- 5. E. Neftci, H. Mostafa, and F. Zenke, "Surrogate gradient learning in spiking neural networks," Signal Processing Magazine, IEEE, Dec 2019, (accepted).
- 6. F.Zenke and S.Ganguli, "Superspike: Supervised learning in multi-layer spiking neural networks," arXiv preprint arXiv:1705.11146, 2017.
- 7. J. Kim, J. Koo, T. Kim, and J.-J. Kim, "Efficient synapse memory structure for reconfigurable digital neuromorphic hardware," Frontiers in neuroscience, vol. 12, p. 829, 2018.
- 8. S. Joshi, B. U. Pedroni, and G. Cauwenberghs, "Neuromorphic event- driven multi-scale synaptic connectivity and plasticity," in 2017 51st Asilomar Conference on Signals, Systems, and Computers. IEEE, 2017, pp. 1–5.
- 9. B. U. Pedroni, S. Sheik, S. Joshi, G. Detorakis, S. Paul, C. Augustine, E. Neftci, and G. Cauwenberghs, "Forward table-based presynaptic event-triggered spike-timing-dependent plasticity," Oct 2016.
- 10. P. Merolla, J. Arthur, F. Akopyan, N. Imam, R. Manohar, and D. Modha, "A digital neurosynaptic core using embedded crossbar memory with 45pj per spike in 45nm," in Custom Integrated Circuits Conference (CICC), 2011 IEEE, Sept. 2011, pp. 1–4.
- 11. B. U. Pedroni, S. Joshi, S. Deiss, S. Sheik, G. Detorakis, S. Paul, C. Augustine, E. O. Neftci, and G. Cauwenberghs, "Memory-efficient synaptic connectivity for spike-timing-dependent plasticity," Frontiers in neuroscience, vol. 13, p. 357, 2019.