

```

/**
 * @file autoTest.c
 * @brief autonomous mode for testing
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 *
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 */

#include "../include/auto.h"

void autonTest() {
    driveSet(35, 35);
    int angle;

    Mutex m = angleFromUpcomingLine(&angle, NULL, 5000);
    mutexTakeDelete(m, -1);

    printf("\n\n//\n\rA:%d\n\\\\\\n\n", angle);

    delay(300);
    driveSet(0, 0);
} /* autonLeftRed12 */

```