

```

/**
 * @file autoTest.c
 * @brief autonomous mode for testing
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 *
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 */

#include "../include/auto.h"

void autonTest() {
    update();
    driveSet(35, 35);
    int angle;

    Mutex m = angleFromUpcomingLine(&angle, NULL, 5000);
    mutexTakeDelete(m, -1);
    #ifdef DEBUG_MODE
        printf("\n\n//\n\rA:%d\n\\\\\\n\n", angle);
    #endif

    gyro.zero = angle;
    gyro.child->zero = angle;
    driveSet(0, 0);
    // turnTo(0, 2500);
} /* autonLeftRed12 */

```