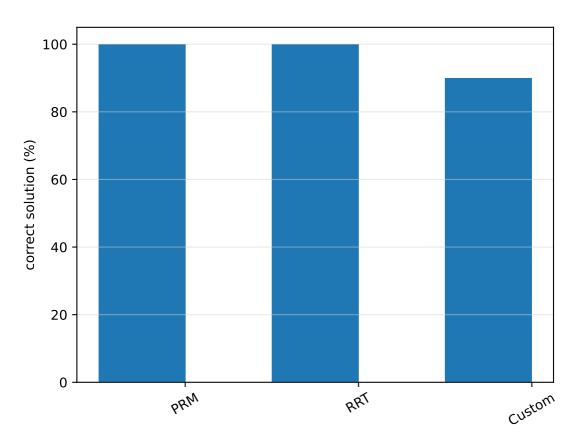
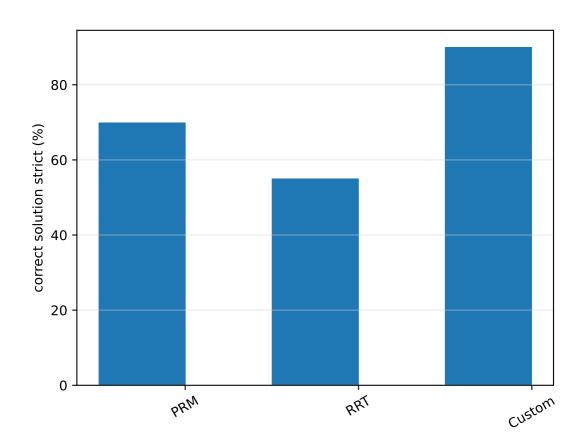
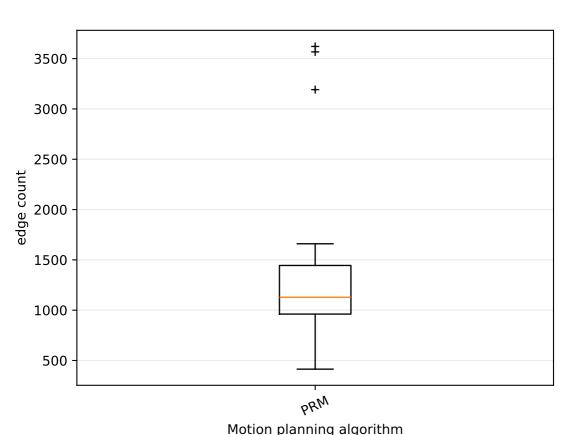
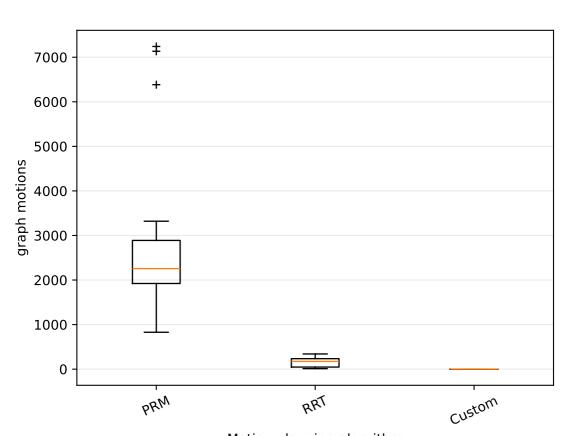


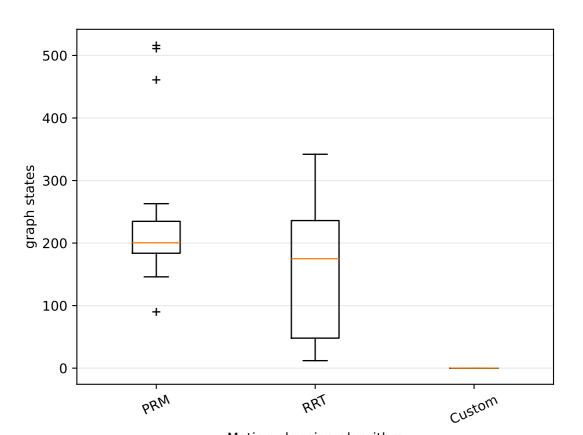
Motion planning algorithm

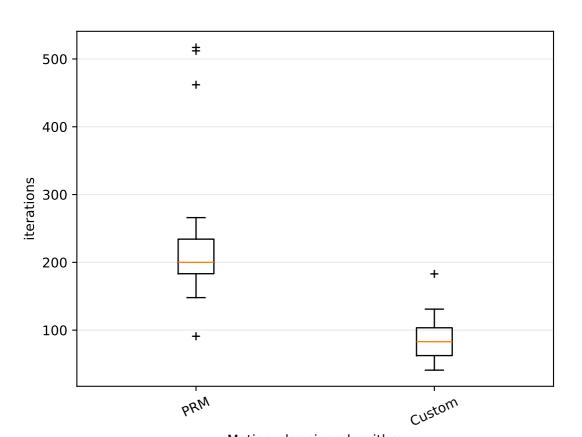


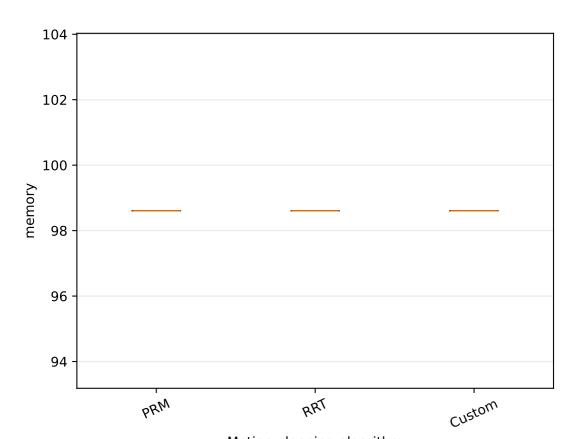


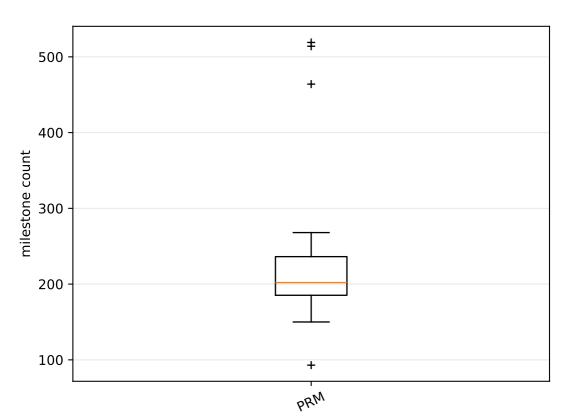




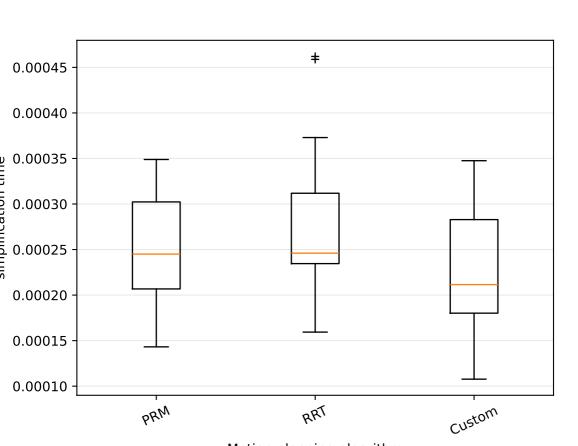


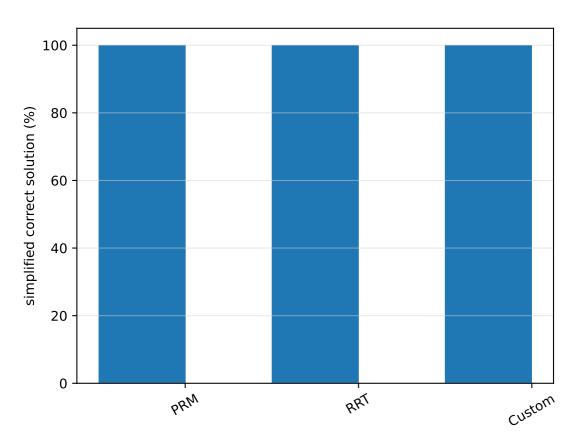


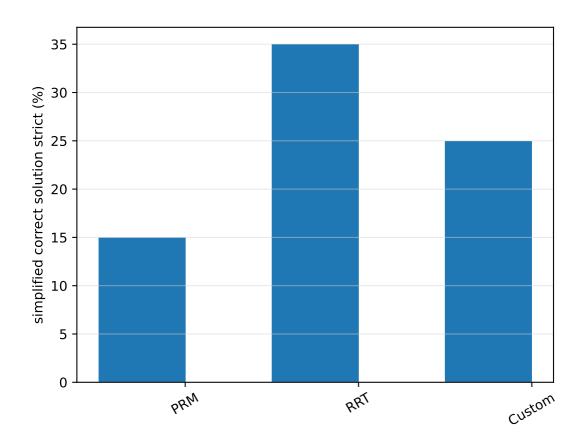


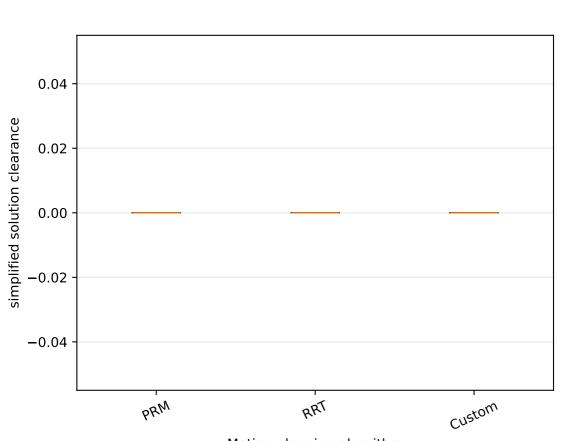


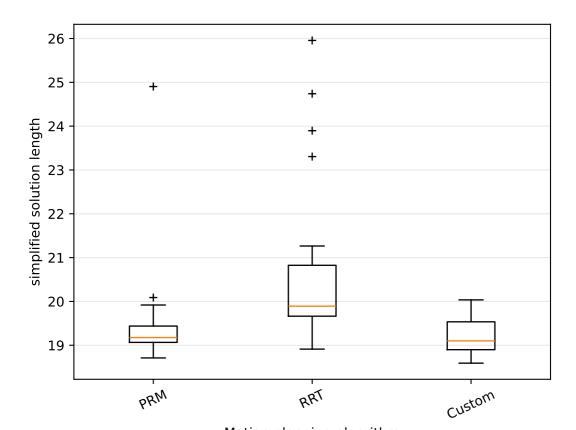
Motion planning algorithm

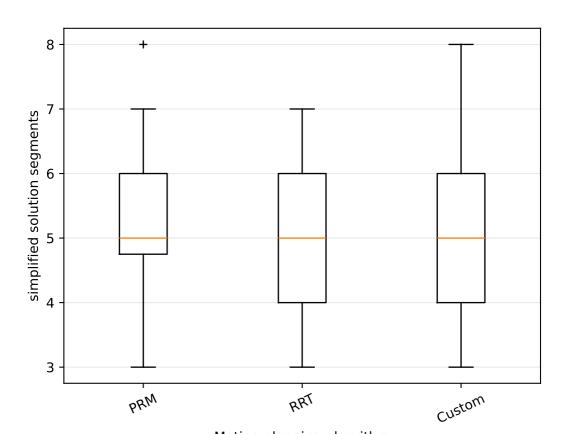


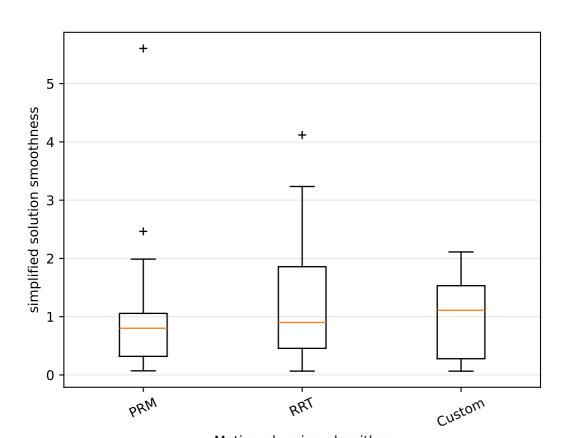


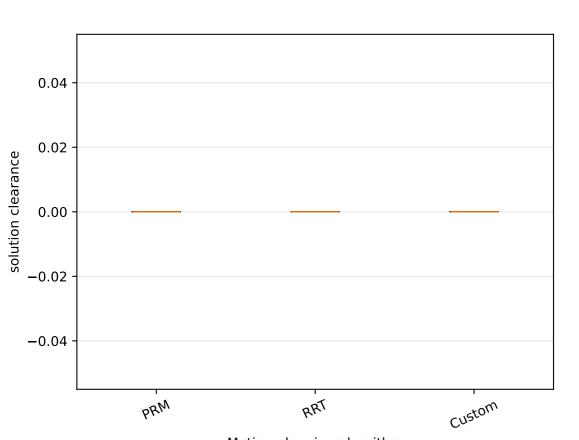


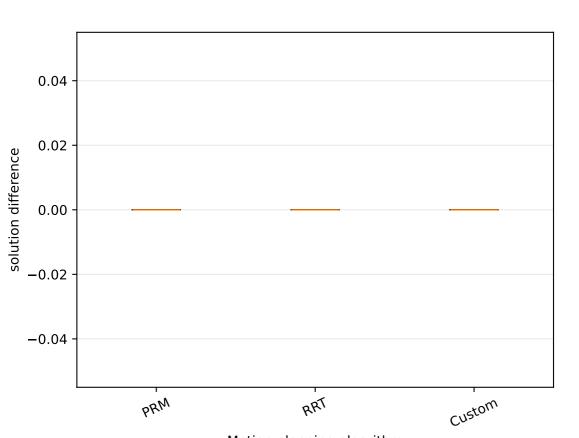


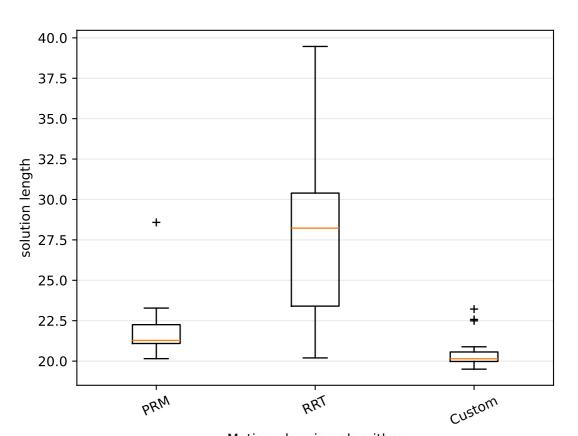


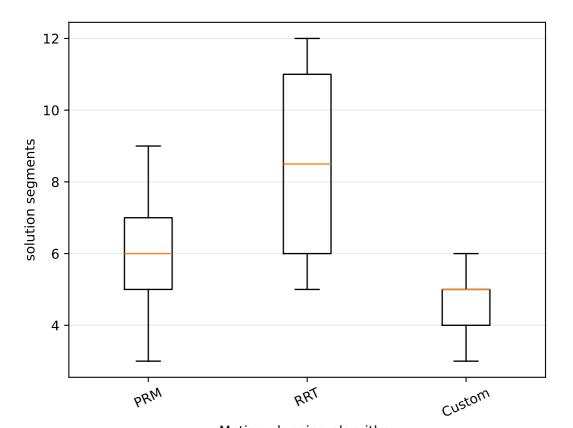


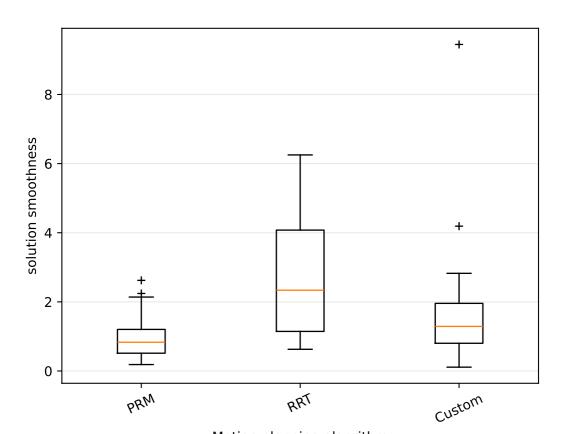


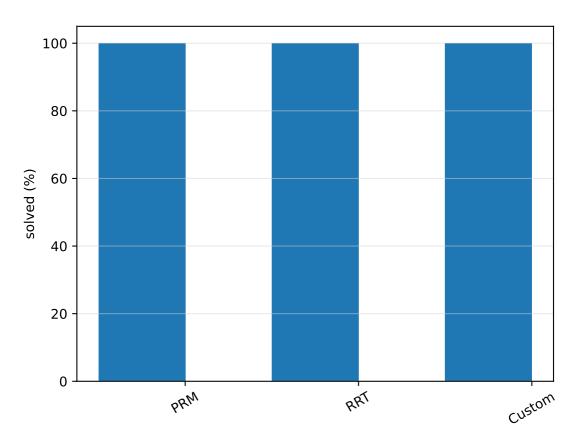


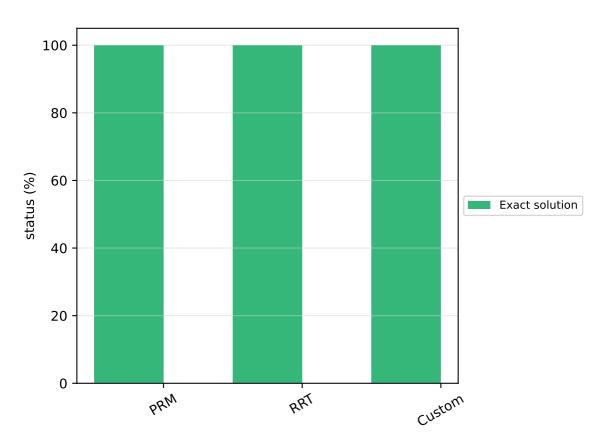


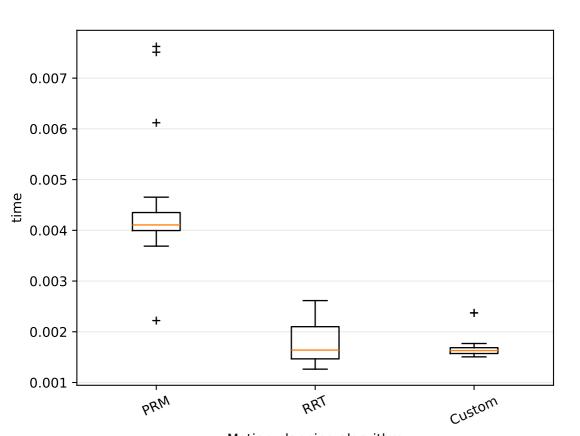


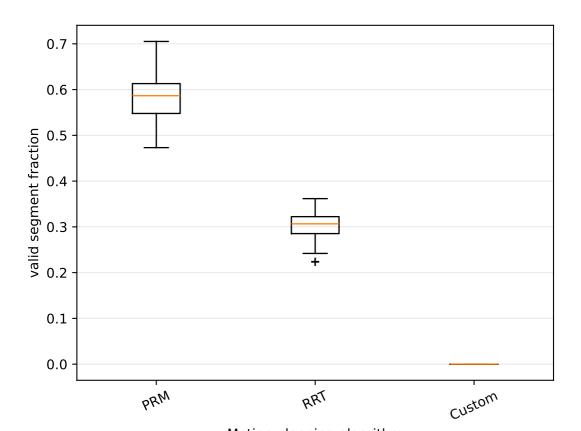


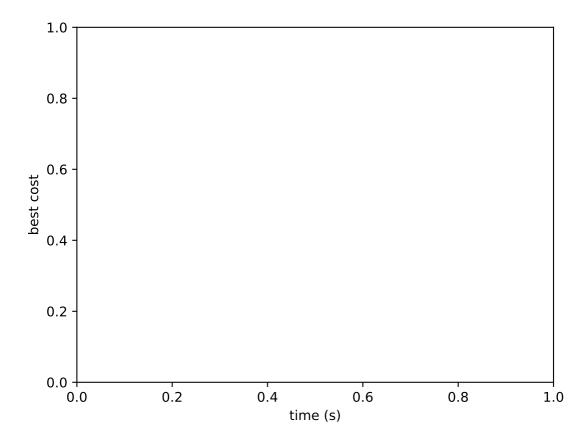


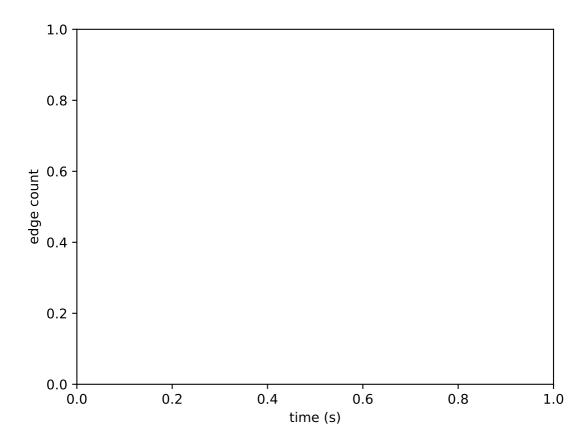


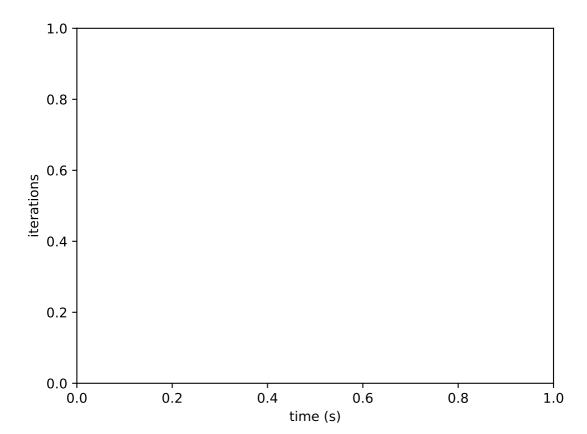


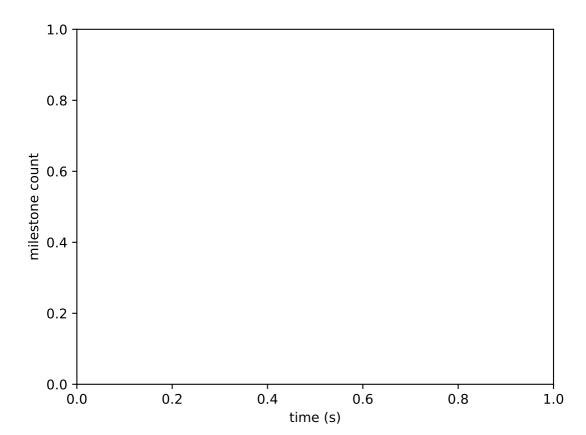












Experiment "Benchmark"

Number of averaged runs: 20

Time limit per run: 4 seconds

Memory limit per run: 100 MB