

## 4 Lecture 4

### 4.1 Operations on linear transformations

**Definition 4.1** (Composition of linear transformations). Let  $T : V \rightarrow W$  and  $S : W \rightarrow U$  be linear transformations. The **composition**  $ST$  (or  $S \circ T$ ) of  $T$  and  $S$  is defined as

$$(ST)(x) = S(T(x)).$$

One can also check that  $ST : V \rightarrow U$  is a linear transformation.

**Proposition 4.2.** Let  $R, S, T$  be linear transformations. Whenever the composition in each item is defined, we have

- (i)  $R(ST) = (RS)T$
- (ii)  $R(S + T) = RS + RT$
- (iii)  $(R + S)T = RT + ST$
- (iv) For  $a \in F$ ,  $a(ST) = (aS)T = S(aT)$
- (iv)  $T \circ \text{id}_V = T$ ,  $\text{id}_W \circ T = T$

*Proof.* One can directly verify these properties following the definition.  $\square$

*Remark 4.3.* We note that in general  $ST \neq TS$  since as maps  $T : V \rightarrow W$  and  $S : W \rightarrow U$  one can only be composed in the order  $ST$  but not in the order of  $TS$ . Even when

$V = W = U$ , we do have examples of  $T, S : V \rightarrow V$  such that  $ST \neq TS$ .  $T = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$  and  $S = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ . Then  $ST = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$  and  $TS = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ .

### 4.2 Invertibility and rank-nullity theorem

**Definition 4.4.** Let  $T : V \rightarrow W$  be a linear transformation.

$T$  is **injective (one-to-one)** if  $T(x) = T(y)$  implies  $x = y$ .

$T$  is **surjective (onto)** if for any  $y \in W$  there is  $x \in V$  such that  $T(x) = y$ .

$T$  is **invertible (nonsingular)** if it is both injective and surjective. An invertible  $T$  is called an **isomorphism** between  $V$  and  $W$ .

$V$  and  $W$  are **isomorphic** if there exists an isomorphism between them. We denote  $V$  and  $W$  are isomorphic by  $V \cong W$ .

**Definition 4.5.** The **kernel (null space)** of  $T$  is

$$\ker T = \{x \in V : T(x) = 0\}.$$

The **nullity** of  $T$  is  $\text{null } T = \dim \ker T$ .

The **image (range)** of  $T$  is

$$\text{im } T = \{T(x) : x \in V\}.$$

The **rank** of  $T$  is  $\text{rank } T = \dim \text{im } T$ .

**Lemma 4.6.** *Let  $T : V \rightarrow W$  be a linear transformation. Then  $\ker T$  is a subspace of  $V$  and  $\operatorname{im} T$  is a subspace of  $W$ .*

*Proof.* Since  $T(0_V) = 0_W$ ,  $0_V \in \ker T$ . Let  $x, y \in \ker T$ ,  $c \in F$ . Then  $T(x + y) = T(x) + T(y) = 0 + 0 = 0$  and  $T(cx) = cT(x) = 0$ . Thus  $x + y \in \ker T$ ,  $cx \in \ker T$ .

Since  $T(0_V) = 0_W$ ,  $0_W \in \operatorname{im} T$ . Let  $u, v \in \operatorname{im} T$ . Then there exist  $x, y \in V$  such that  $T(x) = u$  and  $T(y) = v$ . We have  $u + v = T(x) + T(y) = T(x + y) \in \operatorname{im} T$  and  $cu = cT(x) = T(cx) \in \operatorname{im} T$ .  $\square$

**Proposition 4.7.** *We have the following characterization of injectivity and surjectivity of a linear transformation  $T$ .*

- (i)  *$T$  is injective if and only if  $\ker T = \{0\}$ .*
- (ii)  *$T$  is surjective if and only if  $\operatorname{im} T = W$ .*

*Proof.* (i) Since  $T$  is injective and  $T(0) = 0$ , we have  $\ker T = \{0\}$ .

Suppose  $T(x) = T(y)$ . Then by linearity of  $T$ ,  $T(x - y) = T(x) - T(y) = 0$ . Thus  $x - y \in \ker T = \{0\}$ . Hence  $x = y$ .

(ii) This is just the definition of surjective.  $\square$

**Example 4.8.**  $T : F^n \rightarrow F^m$ ,  $T(x_1, \dots, x_n)^t = (x_1, \dots, x_r, 0, \dots, 0)^t$  for some  $0 \leq r \leq \min(m, n)$ . We have  $\ker T = \{(0, \dots, 0, x_{r+1}, \dots, x_n)^t : x_i \in F, r + 1 \leq i \leq n\}$  and  $\operatorname{im} T = \{(x_1, \dots, x_r, 0, \dots, 0)^t : x_i \in F, 1 \leq i \leq r\}$ . We have  $\operatorname{null} T = n - r$  and  $\operatorname{rank} T = r$ .  $T$  is injective if  $r = n$ .  $T$  is surjective if  $r = m$ .

**Proposition 4.9.** *The following are equivalent:*

- (i)  *$T : V \rightarrow W$  is invertible.*
- (ii) *There is  $S : W \rightarrow V$  linear such that  $ST = \operatorname{id}_V$  and  $TS = \operatorname{id}_W$ .*
- (iii)  *$T$  maps a basis into a basis.*

*If any of the above items is satisfied, then the linear transformation  $S$  in (ii) is unique.*

*Proof.* (i)  $\implies$  (ii) Since  $T$  is both injective and surjective, we can define  $S(y)$  to be the unique  $x$  such that  $T(x) = y$ . It follows from definition that  $ST = \operatorname{id}_V$  and  $TS = \operatorname{id}_W$ .

We now show that  $S$  is linear. In  $T(x + y) = T(x) + T(y)$ , we take  $x = S(u)$  and  $y = S(v)$ . Then we have  $T(S(u) + S(v)) = TS(u) + T(S(v)) = u + v$ . Composing  $S$  on both sides from the left, we get  $S(u) + S(v) = S(u + v)$ . Similarly we have  $T(cS(u)) = cTS(u) = cu$  and composing  $S$  on both sides, we have  $S(cu) = cS(u)$ .

(ii)  $\implies$  (iii) Let  $v_1, \dots, v_n$  be a basis of  $V$ . We show that  $T(v_1), \dots, T(v_n)$  is a basis of  $W$ . To show that  $T(v_1), \dots, T(v_n)$  is linearly independent, let  $a_1T(v_1) + \dots + a_nT(v_n) = 0$ . We compose  $S$  on both sides and use the linearity of  $S$  and  $ST = \operatorname{id}_V$ , we have  $S(a_1T(v_1) + \dots + a_nT(v_n)) = a_1v_1 + \dots + a_nv_n = 0 = 0$ . Since  $v_1, \dots, v_n$  is a basis, we have  $a_1 = \dots = a_n = 0$ .

Let  $y \in W$ . Since  $S(y) \in V$ , there exist  $a_1, \dots, a_n \in F$  such that  $S(y) = a_1v_1 + \dots + a_nv_n$ . Then  $y = TS(y) = T(a_1v_1 + \dots + a_nv_n) = a_1T(v_1) + \dots + a_nT(v_n)$ . Thus  $W = \operatorname{span}(T(v_1), \dots, T(v_n))$ .

(iii)  $\implies$  (i) To show that  $T$  is injective suppose  $T(x) = 0$ . We write  $x = a_1v_1 + \cdots + a_nv_n$ . Then by linearity,  $a_1T(v_1) + \cdots + a_nT(v_n) = T(x) = 0$ . Since  $T(v_1), \dots, T(v_n)$  is a basis,  $a_1 = \cdots = a_n = 0$ . To show that  $T$  is surjective, let  $y \in W$ . Since  $T(v_1), \dots, T(v_n)$  is a basis of  $W$ ,  $y = a_1T(v_1) + \cdots + a_nT(v_n) = T(a_1v_1 + \cdots + a_nv_n) \in \text{im } T$ .

To show uniqueness of  $S$ , we assume  $S_1, S_2$  are two maps satisfying (ii). We consider the composition  $S_1TS_2$ . On one hand,  $(S_1T)S_2 = \text{id}_V S_2 = S_2$ . On the other hand  $S_1(TS_2) = S_1\text{id}_W = S_1$ . Thus  $S_1 = S_2$ .  $\square$

**Definition 4.10.** The linear transformation  $S$  in (ii) is called the **inverse** of  $T$  and is denoted by  $T^{-1}$ .

**Corollary 4.11.** If  $V \cong W$ , then  $\dim V = \dim W$ .

*Proof.* If  $V \cong W$ , then there is an isomorphism  $T : V \rightarrow W$ . By Proposition 4.9 (iii),  $T$  maps a basis into a basis and hence  $\dim V = \dim W$ .  $\square$

**Lemma 4.12.** If  $T : V \rightarrow W$  and  $S : W \rightarrow U$  are both invertible, then  $ST$  is invertible and  $(ST)^{-1} = T^{-1}S^{-1}$ .

*Proof.* We have  $(ST)(T^{-1}S^{-1}) = S(TT^{-1})S^{-1} = SS^{-1} = \text{id}_U$  and  $(T^{-1}S^{-1})(ST) = T^{-1}(S^{-1}S)T = T^{-1}T = \text{id}_V$ . The conclusion follows from Proposition 4.9.  $\square$

**Theorem 4.13** (First isomorphism theorem). Let  $T : V \rightarrow W$  be a linear transformation. We define  $\bar{T} : V/\ker T \rightarrow \text{im } T$  to be  $\bar{T}(x + \ker T) = T(x)$ . Then  $\bar{T}$  is a well-defined linear transformation and is an isomorphism.

$$\begin{array}{ccc} V & \xrightarrow{T} & W \\ \pi \downarrow & & \uparrow i \\ V/\ker T & \xrightarrow{\bar{T}} & \text{im } T \end{array}$$

*Proof.* We first show that  $\bar{T}$  is well-defined. For any  $x' \in x + \ker T$ , we have  $x - x' \in \ker T$ . Then  $T(x) = T(x') + T(x - x') = T(x')$ .

$\bar{T}$  is linear follows from the linearity of  $T$ .

If  $\bar{T}(x + \ker T) = T(x) = 0$  then  $x \in \ker T$ . Thus  $x + \ker T = 0 + \ker T$ . This shows  $\bar{T}$  is injective.

For any  $y \in \text{im } T$ , there exists  $x \in V$  such that  $T(x) = y$ . Thus  $\bar{T}(x + \ker T) = y$ . This shows that  $\bar{T}$  is surjective. Hence  $\bar{T}$  is an isomorphism.  $\square$

**Corollary 4.14** (Rank-nullity theorem). Let  $T : V \rightarrow W$  be a linear transformation. Then

$$\dim V = \text{null } T + \text{rank } T.$$

*Proof.* By Theorem 4.13,  $\bar{T} : V/\ker T \rightarrow \text{im } T$  is an isomorphism. By we have  $\dim(V/\ker T) = \dim \text{im } T$ . By Theorem 3.16, we have  $\dim V - \dim \ker T = \dim(V/\ker T) = \dim \text{im } T$ .  $\square$

**Corollary 4.15** (Underdetermined system of linear equations). *Let  $T : V \rightarrow W$  be a linear transformation and  $\dim W < \dim V$ . Then there is  $0 \neq x \in V$  such that  $T(x) = 0$ .*

*Proof.*  $\text{null } T = \dim V - \text{rank } T \geq \dim V - \dim W > 0$ .  $\square$

**Corollary 4.16.** *Let  $V, W$  be finite dimensional vector spaces such that  $\dim V = \dim W$  and  $T : V \rightarrow W$  be a linear transformation. Then the following are equivalent:*

- (i)  $T$  is an isomorphism.
- (ii)  $T$  injective.
- (iii)  $T$  surjective.
- (iv) There is  $S : W \rightarrow V$  such that  $ST = \text{id}_V$ .
- (v) There is  $S : W \rightarrow V$  such that  $TS = \text{id}_W$ .

*Proof.* (i)  $\implies$  (ii): This follows directly from definition.

(ii)  $\implies$  (iii): By (ii) and Lemma 4.7, we have  $\text{null } T = 0$ . By Corollary 4.14, we have  $\text{rank } T = \dim V = \dim W$ . By Lemma 2.17,  $\text{im } T = W$ .

(iii)  $\implies$  (i): By (iii) we have  $\text{rank } T = \dim W = \dim V$ . By Corollary 4.14, we have  $\text{null } T = 0$  and hence  $\ker T = \{0\}$ . Thus  $T$  is an isomorphism.

(i)  $\implies$  (iv) and (i)  $\implies$  (v): This follows from Proposition 4.9.

(iv)  $\implies$  (ii): Let  $x \in \ker T$ . Then  $x = ST(x) = S(0) = 0$ . Thus  $\ker T = \{0\}$ .

(v)  $\implies$  (iii): Let  $y \in W$ . Then  $y = TS(y) = T(S(y)) \in \text{im } T$ . Thus  $\text{im } T = W$ .  $\square$

*Remark 4.17.* The infinite dimensional version of (ii) and (iii) in this Corollary is called Fredholm alternative. It is useful in solving PDEs cf. [1, Chapter 8].

### 4.3 Basis, coordinates and matrix representation

In Lecture 2, we saw that a finite dimensional vector space is built up by a basis. In this section, we will see that given a basis on a vector space, a linear transformation reduces to a matrix.

**Lemma 4.18** (Basis and coordinates). *Let  $v_1, \dots, v_n$  be a basis of  $V$ . Then for every  $v \in V$ , there exists unique  $x_1, \dots, x_n \in F$  such that  $v = x_1v_1 + \dots + x_nv_n$ .*

*Proof.* Since  $v_1, \dots, v_n$  spans  $V$ , there exist  $x_1, \dots, x_n \in F$  such that  $x = x_1v_1 + \dots + x_nv_n$ . To show uniqueness we assume that  $x = y_1v_1 + \dots + y_nv_n$ . Then we have  $(x_1 - y_1)v_1 + \dots + (x_n - y_n)v_n = 0$ . Since  $v_1, \dots, v_n$  is linearly independent,  $x_1 - y_1 = \dots = x_n - y_n = 0$ . Thus  $x_i = y_i$  for all  $1 \leq i \leq n$ .  $\square$

**Definition 4.19.** Let  $\beta = (v_1, \dots, v_n)$  be a basis of  $V$ . We say that  $(x_1, \dots, x_n)^t$  is the **coordinates** of  $v$  under the basis and we write  $[v]_\beta$  for  $(x_1, \dots, x_n)^t$ .

**Theorem 4.20.** *Let  $V$  be a  $n$ -dimensional vector space over  $F$ . We define the map  $\phi_\beta : V \rightarrow F^n$  by  $\phi_\beta(v) = [v]_\beta$ . Then  $\phi_\beta$  is a linear isomorphism and  $\phi_\beta^{-1}(x_1, \dots, x_n)^t = x_1v_1 + \dots + x_nv_n$ .*

*Proof.* We first show that  $\phi_\beta$  is linear. Let  $\phi_\beta(v) = (x_1, \dots, x_n)^t$  and  $\phi_\beta(w) = (y_1, \dots, y_n)^t$ . Then  $v+w = (x_1+y_1)v_1 + \dots + (x_n+y_n)v_n$  and hence  $\phi_\beta(v+w) = (x_1+y_1, \dots, x_n+y_n)^t = \phi_\beta(v) + \phi_\beta(w)$ . Moreover,  $cv = cx_1v_1 + \dots + cx_nv_n$  then  $\phi_\beta(cv) = c\phi_\beta(v)$ .

Next we show that  $\phi_\beta$  is injective. If  $\phi_\beta(v) = \phi_\beta(w) = (x_1, \dots, x_n)^t$ , then  $v = x_1v_1 + \dots + x_nv_n = w$ . Hence  $\phi_\beta$  is injective.

Finally we show that  $\phi_\beta$  is surjective. For any  $(x_1, \dots, x_n)^t \in F^n$  we take  $v = x_1v_1 + \dots + x_nv_n$ . Then  $\phi_\beta(v) = (x_1, \dots, x_n)^t$ .

Thus  $\phi_\beta$  is an isomorphism and  $V \cong F^n$ .

Since  $\phi_\beta(v) = (x_1, \dots, x_n)^t$  implies that  $v = x_1v_1 + \dots + x_nv_n$ , we see that  $\phi_\beta^{-1}(x_1, \dots, x_n)^t = x_1v_1 + \dots + x_nv_n$ .  $\square$

**Lemma 4.21.** *Let  $T : V \rightarrow W$  be a linear transformations and  $v_1, \dots, v_n$  be a basis of  $V$ . Then  $T$  is uniquely determined by its values at  $T(v_1), \dots, T(v_n)$ .*

*Proof.* Let  $v \in V$ . Since  $v_1, \dots, v_n$  is a basis of  $V$ , we have  $v = x_1v_1 + \dots + x_nv_n$ . Then  $T(v) = T(x_1v_1 + \dots + x_nv_n) = x_1T(v_1) + \dots + x_nT(v_n)$ .  $\square$

**Theorem 4.22.** *Let  $T : V \rightarrow W$  be a linear transformation. Let  $\beta = (v_1, \dots, v_n)$  be a basis of  $V$  and  $\gamma = (w_1, \dots, w_m)$  be a basis of  $W$ . Then there exists a unique matrix  $A \in M_{m \times n}(F)$  such that for any  $x \in F^n$ ,*

$$\phi_\gamma T \phi_\beta^{-1}(x) = Ax,$$

where  $\phi_\beta : V \rightarrow F^n$  and  $\phi_\gamma : W \rightarrow F^m$  are the coordinates isomorphisms.

The  $j$ -th column of  $A$  is given by the coordinates of  $T(v_j)$  under the basis  $\gamma$ . That is  $A = ([T(v_1)]_\gamma, \dots, [T(v_n)]_\gamma)$ .

*Proof.* Since  $(w_1, \dots, w_m)$  is a basis, for each  $j$  there exist scalars  $a_{1j}, \dots, a_{mj}$  such that

$$T(v_j) = \sum_{i=1}^m a_{ij}w_i. \quad (1)$$

Now for any  $x = (x_1, \dots, x_n)^t \in F^n$ ,

$$\begin{aligned} T \phi_\beta^{-1}(x) &= T(x_1v_1 + \dots + x_nv_n) = \sum_{j=1}^n x_j T(v_j) \\ &= \sum_{j=1}^n x_j \sum_{i=1}^m a_{ij}w_i = \sum_{i=1}^m \left( \sum_{j=1}^n a_{ij}x_j \right) w_i. \end{aligned}$$

Thus

$$\phi_\gamma T \phi_\beta^{-1}(x) = \begin{pmatrix} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n \end{pmatrix} = Ax.$$

We note that by (1), the  $j$ -th column of  $A$  is given by the coordinates of  $T(v_j)$  under the basis  $\gamma$ . This finishes the proof.  $\square$

**Definition 4.23.** The matrix  $A$  is called the **matrix representation** of  $T$  under the bases  $\beta$  of  $V$  and  $\gamma$  of  $W$  and is denoted by  $[T]_{\beta}^{\gamma}$ .

**Corollary 4.24.**  $\mathcal{L}(V, W) \cong M_{m \times n}(F)$ . In particular,  $\dim \mathcal{L}(V, W) = (\dim V)(\dim W)$

**Example 4.25** (The zero matrix). For the zero map  $0 : V \rightarrow W$ , its matrix representation is the **zero matrix** under any basis  $\beta$   $\gamma$  is  $[0]_{\beta}^{\gamma} = 0_{m \times n}$ .

**Example 4.26** (The identity matrix). For the identity map  $\text{id} : V \rightarrow V$ , its matrix

under a basis  $\beta$  is the **identity matrix**  $[\text{id}]_{\beta}^{\beta} = I_n = \begin{pmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{pmatrix} = (\delta_{ij})$  where

$n = \dim V$  and we used the **Kronecker delta** symbol  $\delta_{ij} = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$ .

**Example 4.27** (Diagonal matrix). If  $T(v_i) = \lambda_i v_i$  for all  $i$ , then

$$[T]_{\beta}^{\beta} = \text{diag}(\lambda_1, \dots, \lambda_n) = \begin{pmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{pmatrix}.$$

**Example 4.28.** Let  $T : \mathcal{P}_n(\mathbb{R}) \rightarrow \mathcal{P}_n(\mathbb{R})$   $Tf = f'$  and  $\beta = (1, x, \dots, x^n)$  be the standard basis. To compute  $[T]_{\beta}^{\beta}$ , we find  $T(x^k) = kx^{k-1}$ . Thus  $[T(x^k)]_{\beta} = (0, \dots, 0, k, 0, \dots, 0)^t$  where the  $k$  is at the  $(k-1)$ -th position. Then

$$[T]_{\beta}^{\beta} = \begin{pmatrix} 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 2 & \cdots & 0 \\ 0 & 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & & \vdots \\ 0 & 0 & 0 & \cdots & n \\ 0 & 0 & 0 & \cdots & 0 \end{pmatrix}.$$

## References

- [1] Gilbarg D, Trudinger NS. Elliptic partial differential equations of second order. Berlin: springer; 1977.