

# 5 - Regresion lineal regularizada, sesgo y varianza

January 28, 2019

Autores: Alberto Pastor Moreno e Iván Fernández Mena

## 1 Preprocesamiento de los datos

```
In [1]: import numpy as np
```

```
In [2]: from scipy.io import loadmat
```

```
In [3]: data = loadmat('datasets/ex5data1.mat')
```

```
X_train = data['X']
y_train = data['y']
X_val = data['Xval']
y_val = data['yval']
X_test = data['Xtest']
y_test = data['ytest']
```

```
print("X_train.shape:{}y_train.shape:{}\nX_val.shape:{}y_val.shape{}\nX_test.shape:{}y_
```

```
X_train.shape:(12, 1)y_train.shape:(12, 1)
```

```
X_val.shape:(21, 1)y_val.shape:(21, 1)
```

```
X_test.shape:(21, 1)y_test.shape:(21, 1)
```

```
In [4]: def cost(th, X, y, reg):
```

```
    m = len(X)
```

```
    Xs = np.insert(X, 0, values=np.ones(m), axis=1)
```

```
    J = (1/(2*m))*np.sum((np.dot(Xs, th.T) - y)**2) + np.sum(th[1:]**2)*(reg/(2*m))
```

```
    return J
```

```
def gradient(th, X, y, reg):
```

```
    m = len(X)
```

```
    Xs = np.insert(X, 0, values=np.ones(m), axis=1)
```

```
    gr = (1/m)*np.dot(Xs.T, (np.dot(Xs, th.T) - y))
```

```
    gr += np.insert(th[1:]*(reg/m), 0, values=0, axis=0)
```

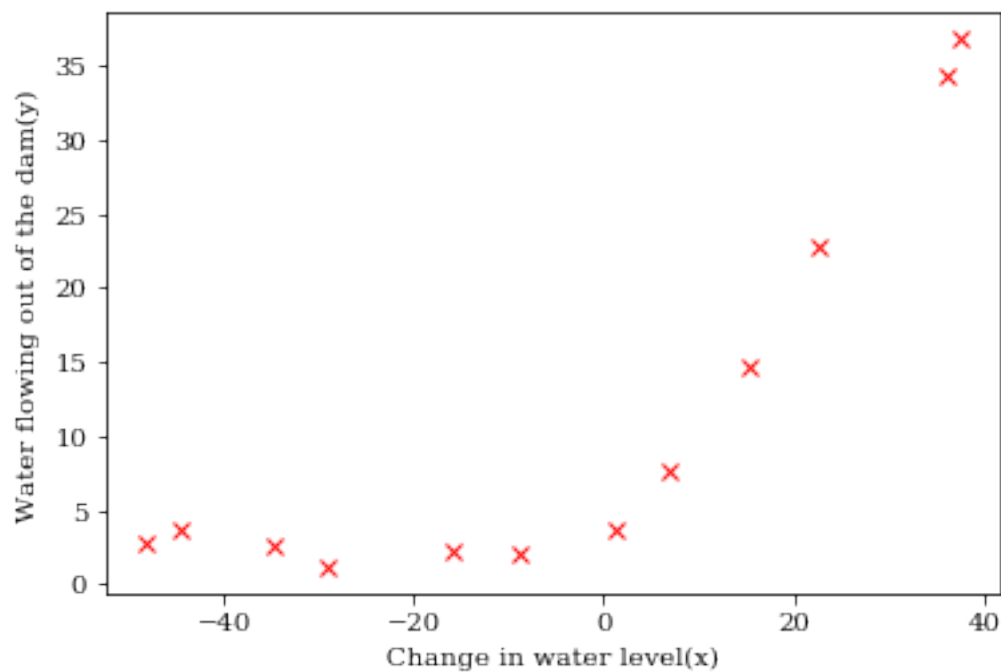
```
    return gr
```

```
def cg(th, X, y, reg):
    return (cost(th,X,y,reg), gradient(th,X,y,reg))
```

```
In [5]: import matplotlib.pyplot as plt
plt.rc('text', usetex=False)
plt.rc('font', family='serif')
```

```
In [6]: plt.figure()
plt.plot(X_train, y_train, 'rx')
plt.ylabel('Water flowing out of the dam(y)')
plt.xlabel('Change in water level(x)')
```

```
Out[6]: Text(0.5,0,'Change in water level(x)')
```



```
In [7]: m_train = len(X_train)
m_val = len(X_val)
m_test = len(X_test)
th_initial = np.ones(len(X_train[0]) + 1)
reg = 1.0
```

```
In [8]: cost(th_initial, X_train, np.ravel(y_train), reg)
```

```
Out[8]: 303.9931922202643
```

```
In [9]: gradient(th_initial, X_train, np.ravel(y_train), reg)
```

```
Out[9]: array([-15.30301567, 598.25074417])
```

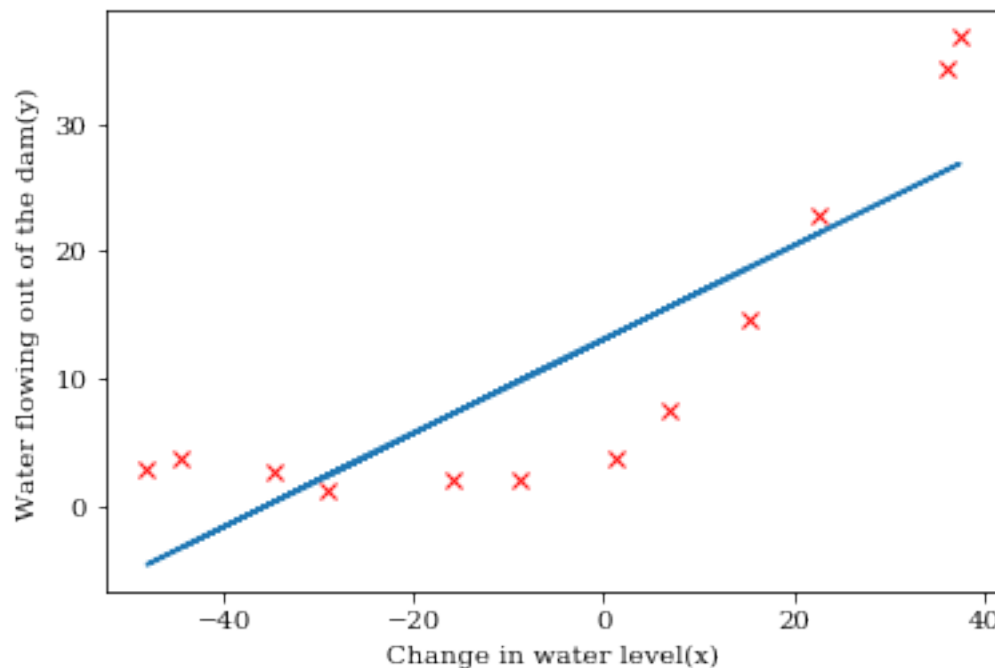
```
In [10]: import scipy.optimize as opt
```

```
In [11]: fmin = opt.minimize(fun=cg, x0=th_initial, args=(X_train, np.ravel(y_train), 0),
                             method='TNC', jac=True, options={'maxiter':70})
        th_opt = fmin.x
        print ("Coste óptimo obtenido con scipy.optimize.fmin_tnc():{}".format(cost(th_opt, X_train, np.ravel(y_train), 0)))
```

```
Coste óptimo obtenido con scipy.optimize.fmin_tnc():22.373906495108997
```

```
In [12]: X_train_ones = np.insert(X_train, 0, values=np.ones(m_train), axis=1)
        plt.plot(X_train, y_train, 'rx', X_train, np.dot(X_train_ones, th_opt.T))
        plt.ylabel('Water flowing out of the dam(y)')
        plt.xlabel('Change in water level(x)')
```

```
Out[12]: Text(0.5,0,'Change in water level(x)')
```



## 2 Curvas de aprendizaje

```
In [13]: def learning_analysis(X_train, y_train, X_val, y_val, reg):
        m_train = len(X_train)
        th_initial = np.ones(len(X_train[0]) + 1)
```

```

lth_train = []
for i in range(1, m_train + 1):
    x_i = X_train[:i, :]
    y_i = np.ravel(y_train[:i])
    fmin_i = opt.minimize(fun=cg, x0=th_initial, args=(x_i, y_i, reg),
                          method='TNC', jac=True, options={'maxiter': 100})
    lth_train.append(fmin_i.x)

lcost_train = np.zeros(m_train)
lcost_val = np.zeros(m_train)
for i, th_i in enumerate(lth_train):
    xt_i = X_train[:i+1, :]
    yt_i = np.ravel(y_train[:i+1])
    lcost_train[i] = cost(th_i, xt_i, yt_i, reg)
    lcost_val[i] = cost(th_i, X_val, np.ravel(y_val), reg)
return(lcost_train, lcost_val)

```

```

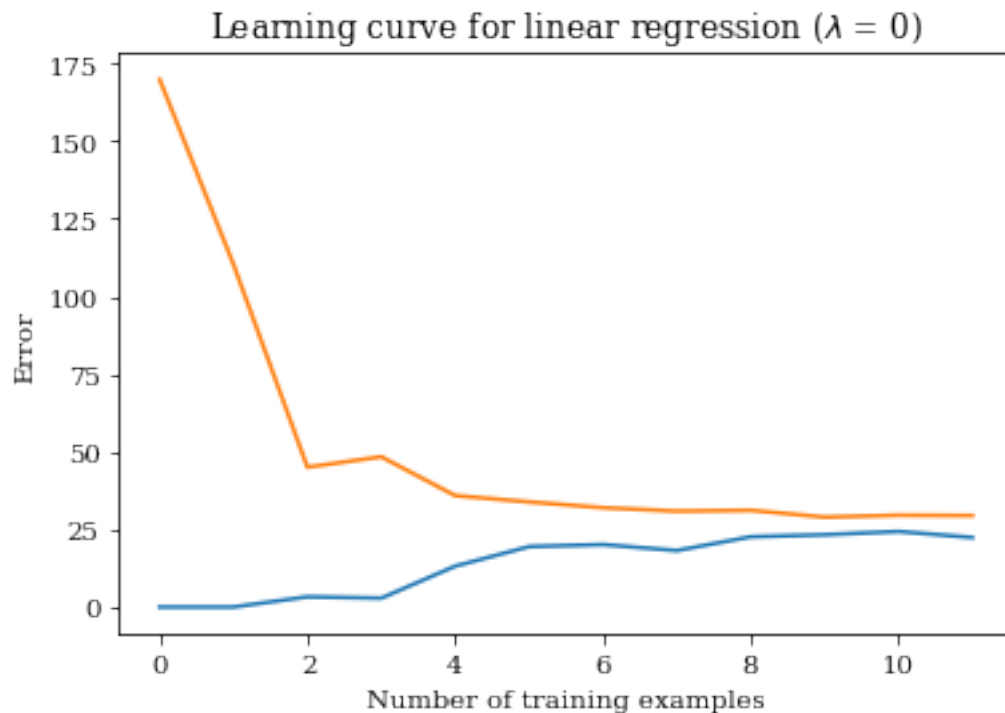
In [14]: def show_learning_analysis(x1, y1, x2, y2, reg):
    lcost = learning_analysis(x1, y1, x2, y2, reg)
    plt.plot(lcost[0])
    plt.plot(lcost[1])
    plt.title('Learning curve for linear regression ( $\lambda = \{0\}$ )'.format(reg))
    plt.ylabel('Error')
    plt.xlabel('Number of training examples')

```

```

In [15]: show_learning_analysis(X_train, y_train, X_val, y_val, 0)

```



### 3 Regresión polinomial

```
In [16]: def poly(X, p):
        xret = np.array(X)
        for i in range(0,p):
            xret = np.c_[xret, xret[:,0]**(i+2)]
        return xret

        def norm(x):
            mu = [np.mean(x[:,i]) for i in range(0,len(x[0]))]
            sigma = [np.std(x[:,i]) for i in range(0,len(x[0]))]
            xnorm = (x - mu)/sigma
            return xnorm, np.ravel(mu), np.ravel(sigma)

In [17]: p = 8
        X_train_poly = poly(X_train, p)
        X_train_poly, mu, sigma = norm(X_train_poly)
        th_initial = np.ones(len(X_train_poly[0]) + 1)

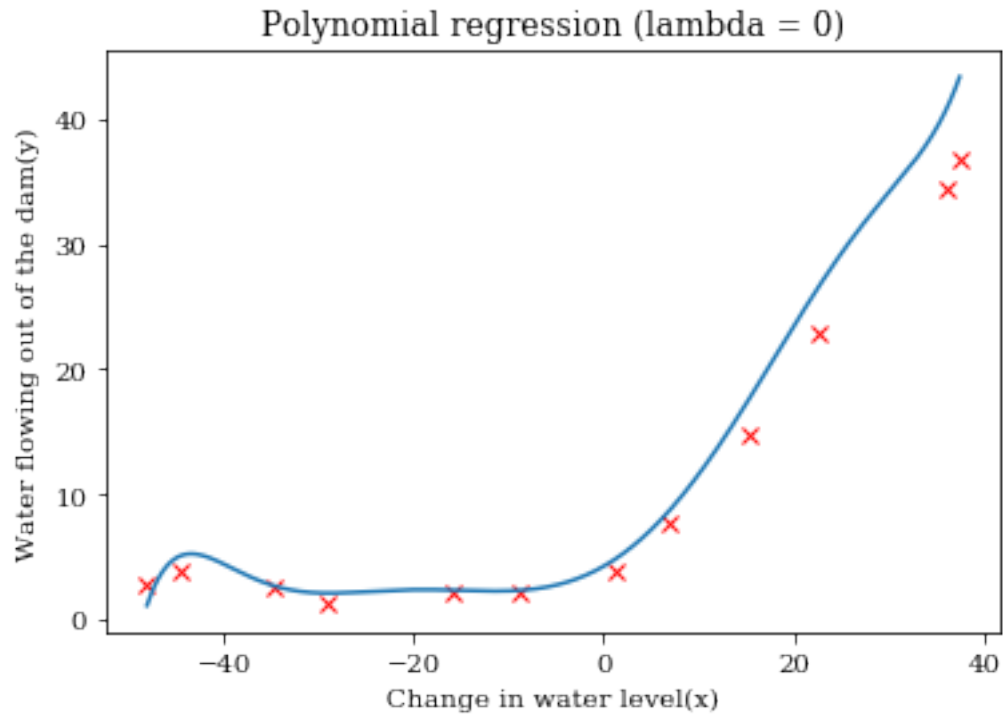
In [18]: fmin_poly = opt.minimize(fun=cg, x0=th_initial, args=(X_train_poly, np.ravel(y_train)),
                                method='TNC', jac=True, options={'maxiter':70})
        th_opt_poly = fmin_poly.x
```

Usando los pesos obtenidos en el entrenamiento con  $\lambda = 0$ , construimos un grafico que muestre como se ajusta a los ejemplos de entrenamiento

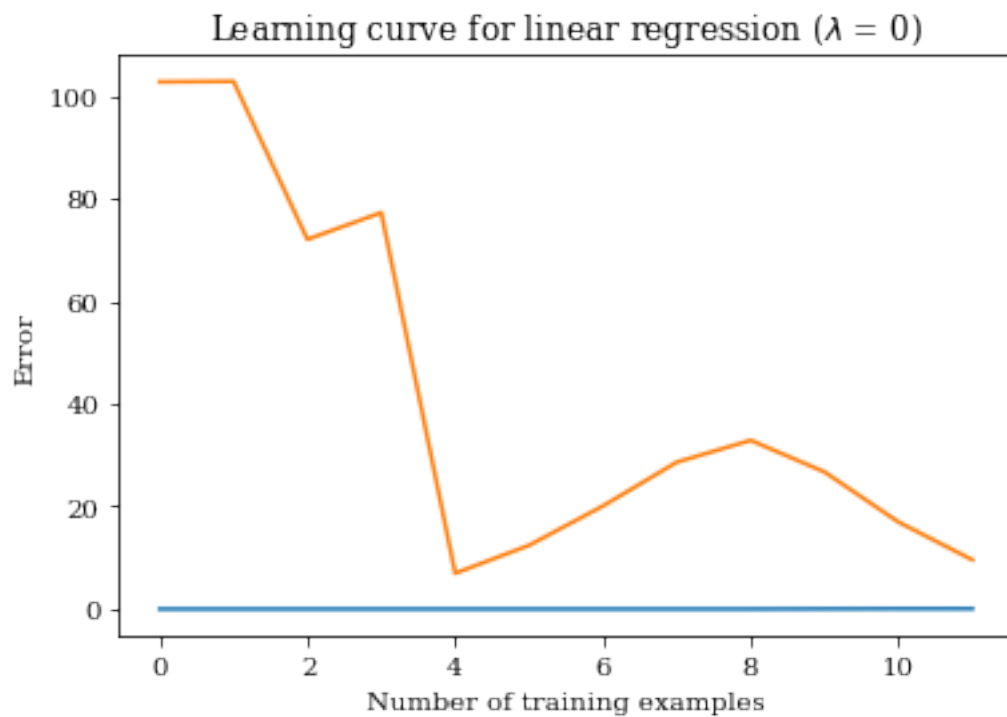
```
In [19]: X_train_ones = np.insert(X_train_poly, 0, values=np.ones(m_train), axis=1)
        plt.plot(X_train, y_train, 'rx')
        range_X_min_to_max = np.matrix(np.arange(np.min(X_train), np.max(X_train), 0.05)).reshape((1,))
        curve_X_data = poly(range_X_min_to_max, p)
        curve_X_data, *_ = norm(curve_X_data)
        curve_X_data = np.insert(curve_X_data, 0, values=np.ones(curve_X_data.shape[0]), axis=1)

        plt.plot(range_X_min_to_max, np.dot(curve_X_data, th_opt_poly.T))
        plt.ylabel('Water flowing out of the dam(y)')
        plt.xlabel('Change in water level(x)')
        plt.title('Polynomial regression (lambda = 0)')

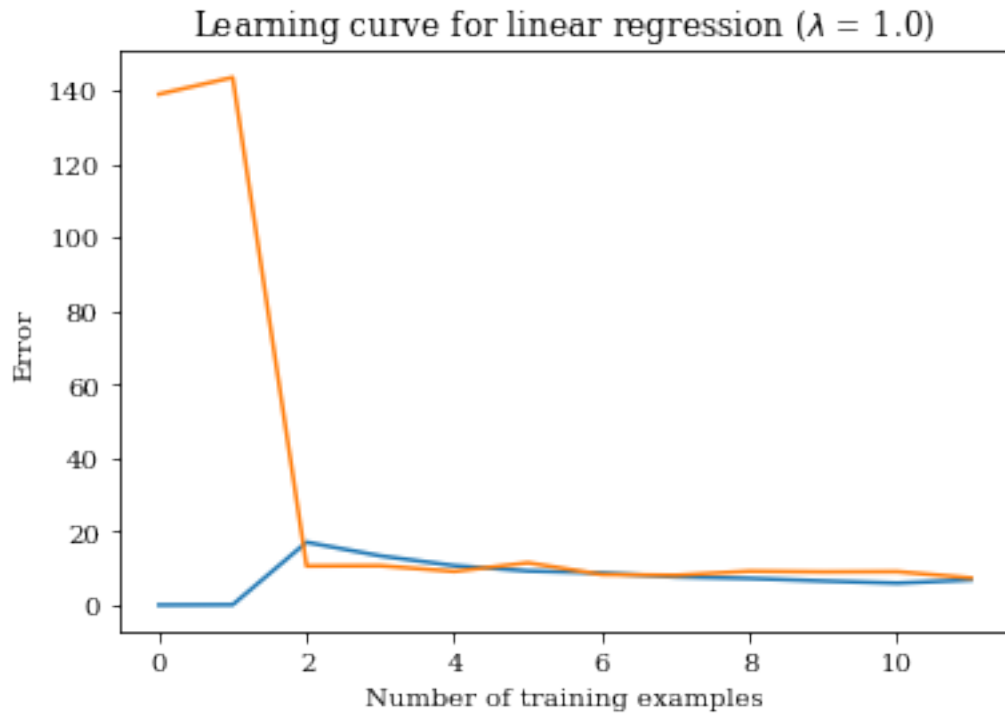
Out[19]: Text(0.5,1,'Polynomial regression (lambda = 0)')
```



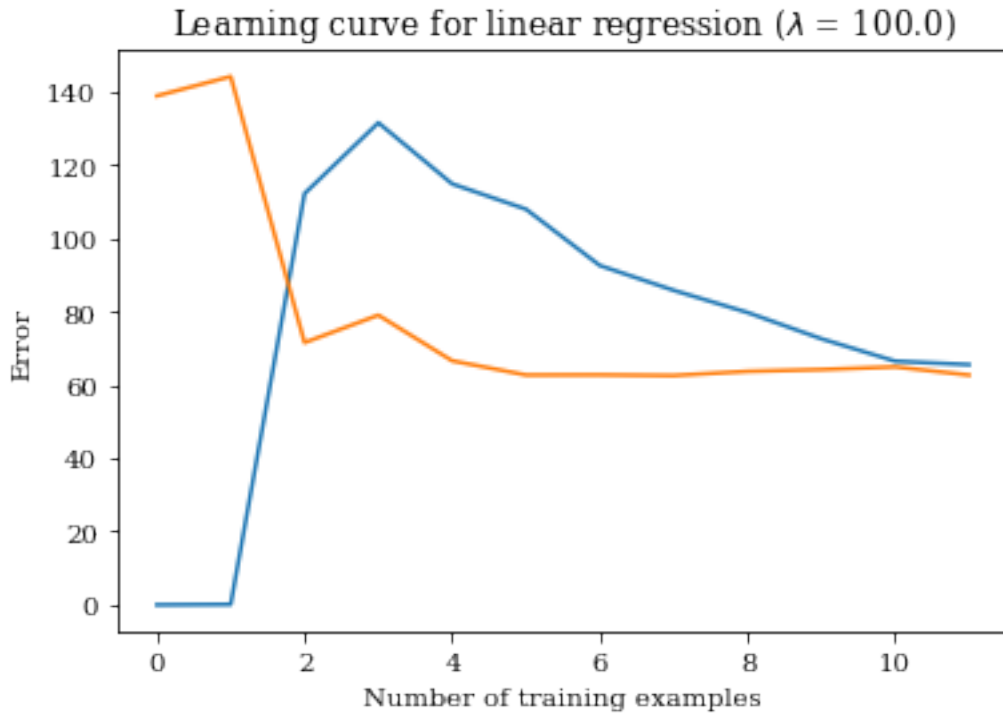
```
In [20]: X_train_poly_val = poly(X_val, p)
X_train_poly_val, mu, sigma = norm(X_train_poly_val)
show_learning_analysis(X_train_poly, y_train, X_train_poly_val, y_val, 0)
```



```
In [21]: show_learning_analysis(X_train_poly, y_train, X_train_poly_val, y_val, 1.0)
```



```
In [22]: show_learning_analysis(X_train_poly, y_train, X_train_poly_val, y_val, 100.0)
```



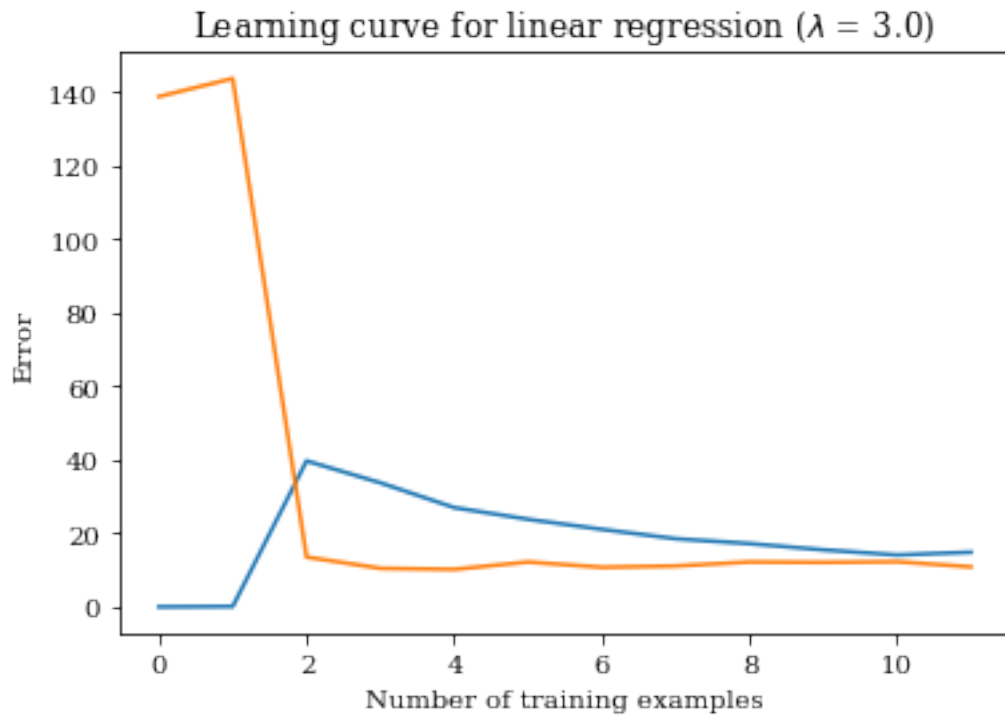
## 4 Selección del parámetro lambda

```
In [23]: reg_array = np.array([0, 0.001, 0.003, 0.01, 0.03, 0.1, 0.3, 1.0, 3.0, 10.0])

th_initial = np.ones(len(X_train_poly[0]) + 1)
cost_reg_array_train = []
cost_reg_array_val = []
for r in reg_array:
    fmin = opt.minimize(fun=cg, x0=th_initial, args=(X_train_poly, np.ravel(y_train),
                                                    method='TNC', jac=True, options={'maxiter':70})
    cost_reg_array_train.append(cost(fmin.x, X_train_poly, np.ravel(y_train), reg=r))
    cost_reg_array_val.append(cost(fmin.x, X_train_poly_val, np.ravel(y_val), reg=r))

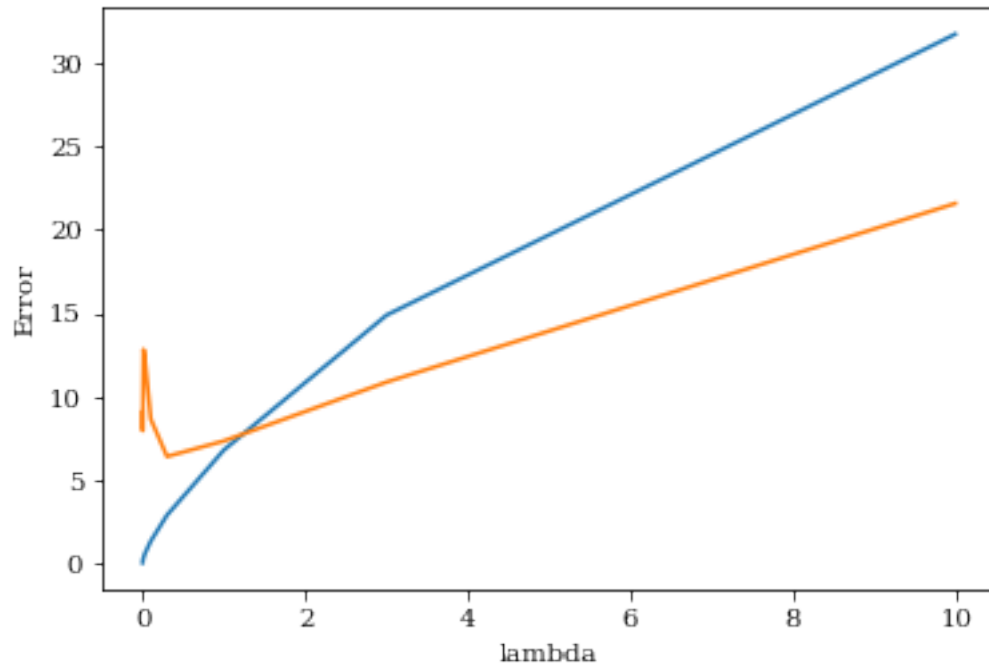
In [24]: show_learning_analysis(X_train_poly, y_train, X_train_poly_val, y_val, 3.0)
```





```
In [25]: plt.plot(reg_array, cost_reg_array_train)
plt.plot(reg_array, cost_reg_array_val)
plt.ylabel('Error')
plt.xlabel('lambda')
```

```
Out[25]: Text(0.5,0,'lambda')
```



```
In [26]: # entrenamiento con el mejor lambda encontrado
th_initial = np.ones(len(X_train_poly[0]) + 1) # sustituir por los th optimos
fmin_poly_breg = opt.minimize(fun=cg, x0=th_initial, args=(X_train_poly, np.ravel(y_train)),
                             method='TNC', jac=True, options={'maxiter':70})
th_opt_poly_breg = fmin_poly_breg.x

# coste usando los pesos entrenados sobre X_train, y_train,
X_test_poly, *_ = norm(X_test)
X_test_poly = poly(X_test_poly, p)
test_cost = cost(th_opt_poly_breg, X_test_poly, np.ravel(y_test), reg=3.0)
print(test_cost)
```

1071.0610999180983