

# Today: Outline

- Feature Extraction and Transfer Learning
- RNNs
- **Reminders:** *Please be sure to record in-class bonuses*

*Pre-lec Material 2,  
due: Friday, Jun 4*

*Problem Set 1,  
due: Friday, Jun 4*

# Grades Web Page

- <http://cs-people.bu.edu/sbargal/cs523/grades.html>



## Deep Learning

CS 523 Summer1 2021

You can use your random ID to access your row of grades for the course.

### Grades\*\*

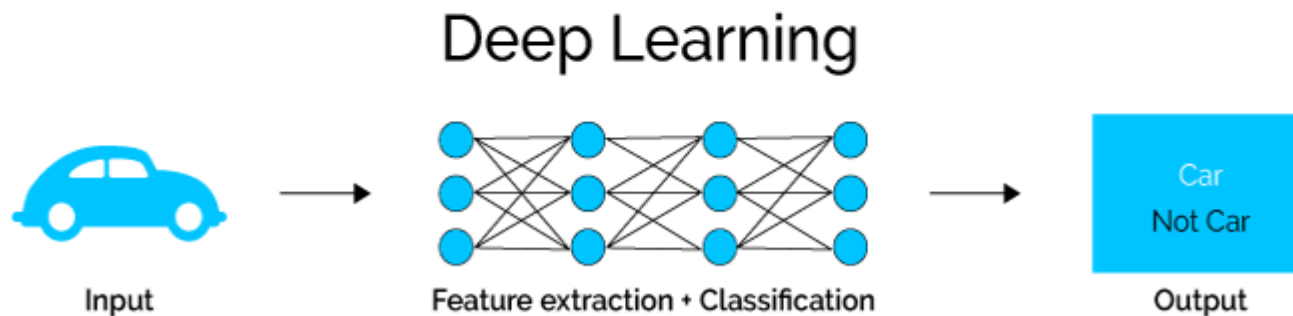
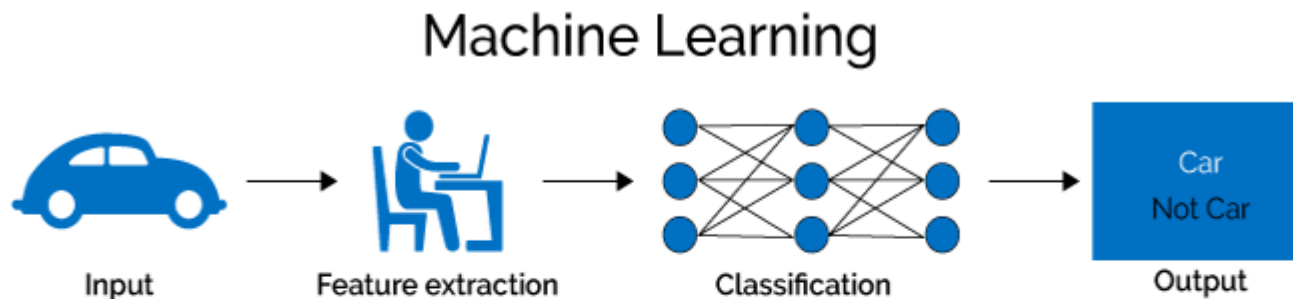
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41	-	-	-	-	-	1	-	-
14	-	-	-	-	-	0.75	-	-
47	-	-	-	-	-	1	-	-
18	-	-	-	-	-	0	-	-
37	-	-	-	-	-	1	-	-
46	-	-	-	-	-	1	-	-
23	-	-	-	-	-	1	-	-
48	-	-	-	-	-	1	-	-
44	-	-	-	-	-	1	-	-
45	-	-	-	-	-	1	-	-
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# Neural Networks

Feature Extraction and Transfer Learning

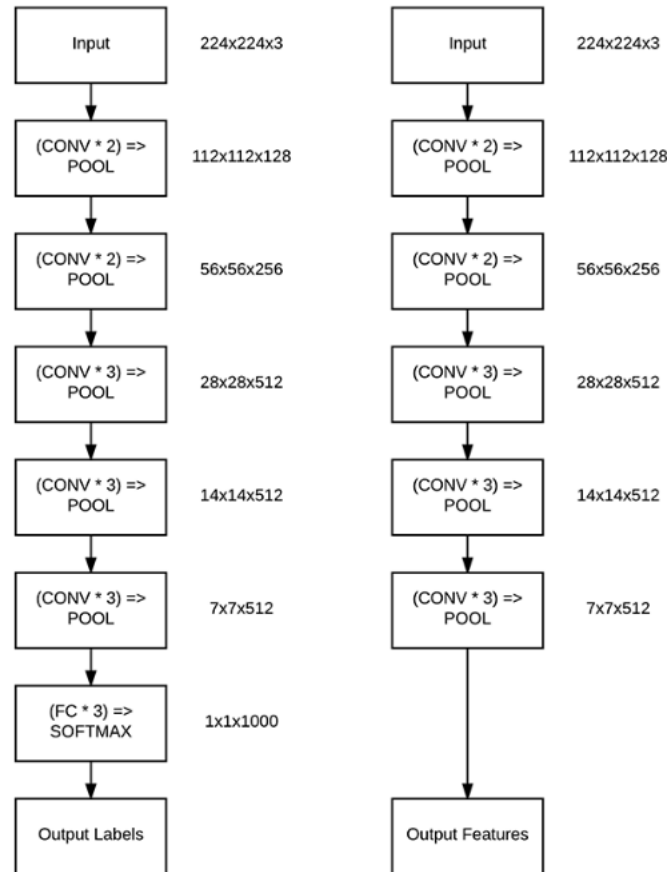
# Feature Extraction



[Towards Data Science]

# Feature Extraction From NNs

## Networks as feature extractors

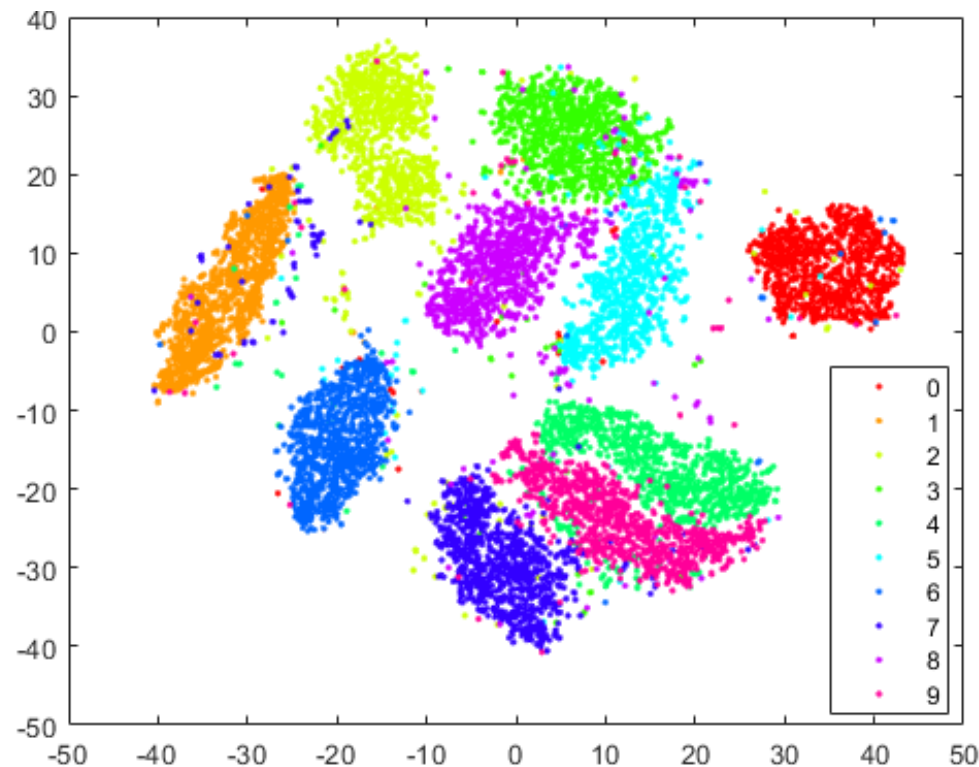


[Towards Data Science]

# Feature Visualization

- T-SNE

A common way for visualizing features through dimensionality reduction.



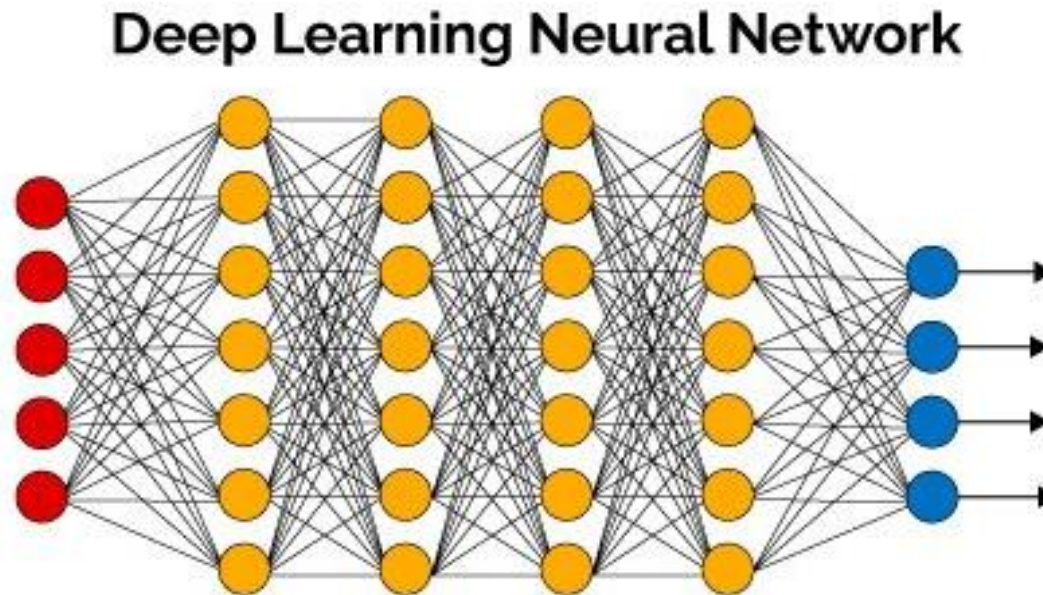
# Pre-training

- Simply put, a **pre-trained model** is a **model** created by some one else to solve a similar problem.
- Instead of building a **model** from scratch to solve a similar problem, you use the **model trained** on other problem as a starting point.
- This catalyzed academic research significantly.
- Model Zoo.



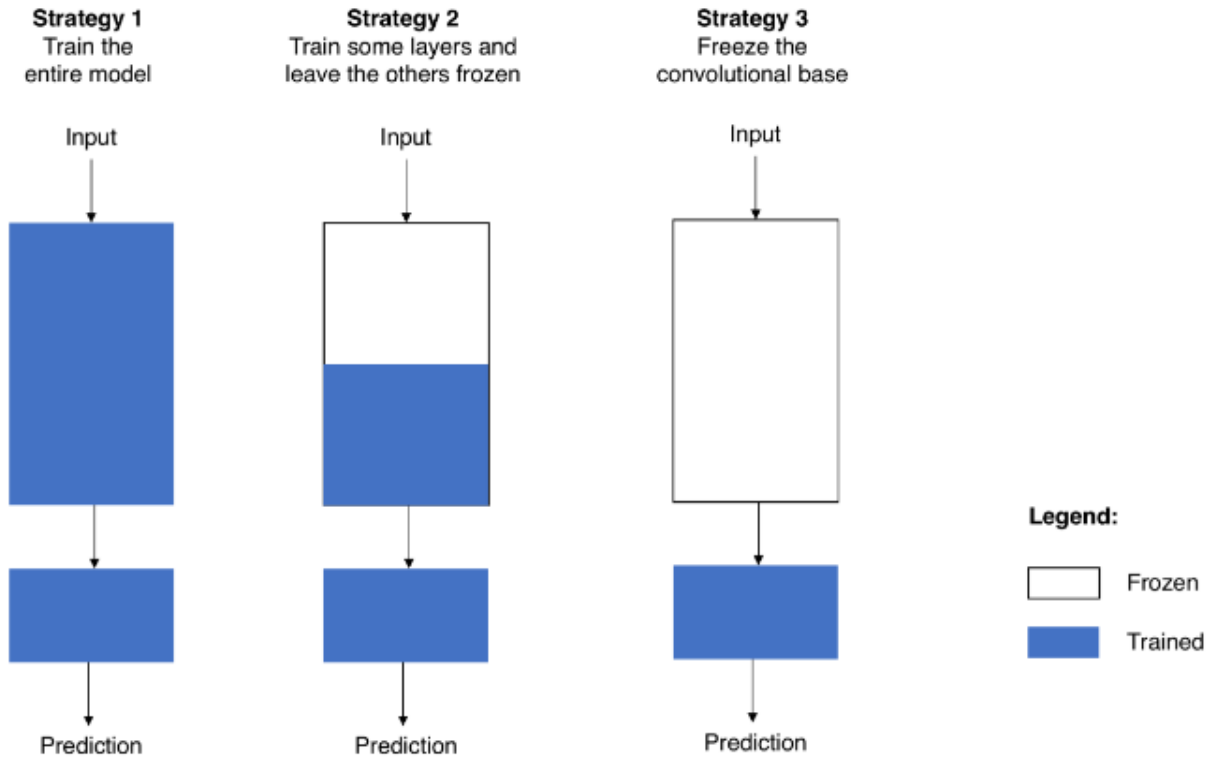
# Fine-tuning

- What if the number of output neurons (or classes) is not the same?





# Transfer Learning — the Pre-train & Fine-tune Paradigm





# Modeling Sequences - RNNs

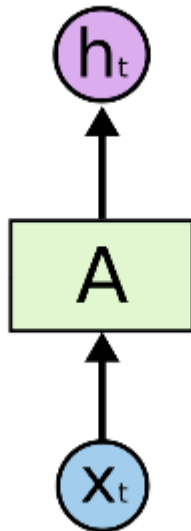
# Limitations of Feed-Fwd Networks

- Limitations of feed-forward networks
  - **Fixed length**  
*Inputs and outputs are of fixed lengths*
  - **Independence**  
*Data (example: images) are independent of one another*

# Advantages of RNN Models

- What feed-forward networks cannot do
  - **Variable length**  
*“We would like to accommodate temporal sequences of various lengths.”*
  - **Temporal dependence**  
*“To predict where a pedestrian is at the next point in time, this depends on where he/she were in the previous time step(s).”*

# Vanilla Neural Network (NN)



- NN

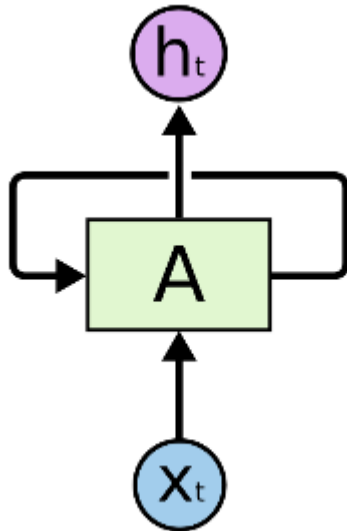
$x_t$ : input/event

$h_t$ : output/prediction

$A$  : chunk of NN

Every input is treated independently.

# Recurrent Neural Network (RNN)



- RNN

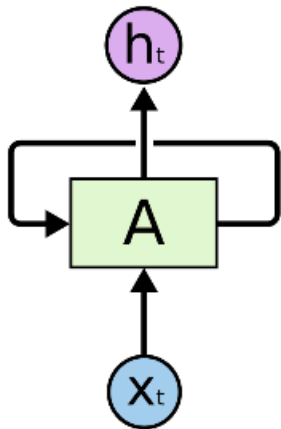
The loop allows information to be passed from one time step to the next.

Now we are modeling the dynamics.



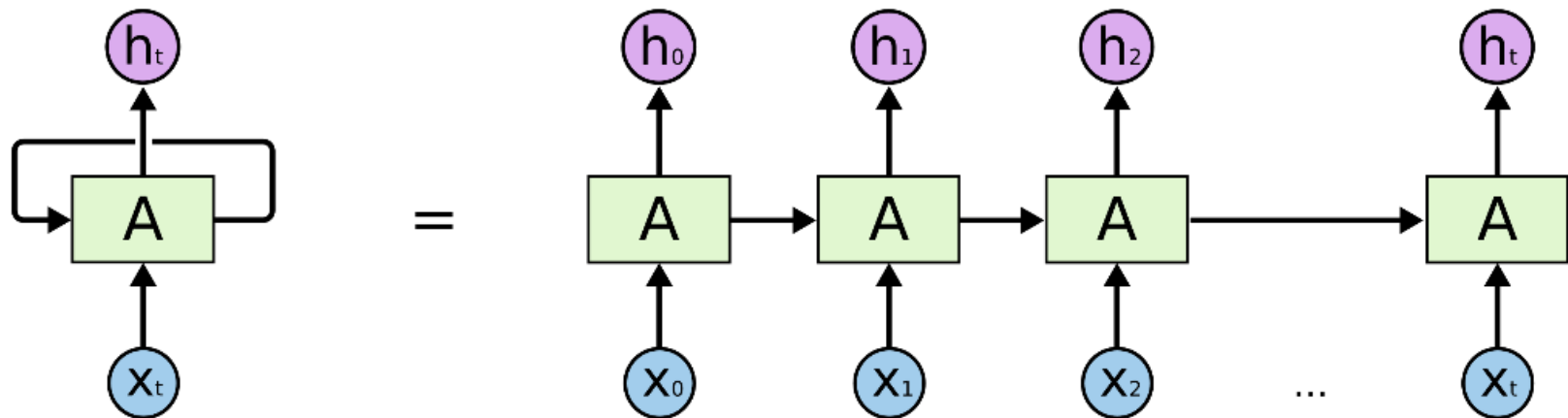
# Recurrent Neural Network (RNN)

- A recurrent neural network can be thought of as multiple copies of the same network, each passing a message to a successor.

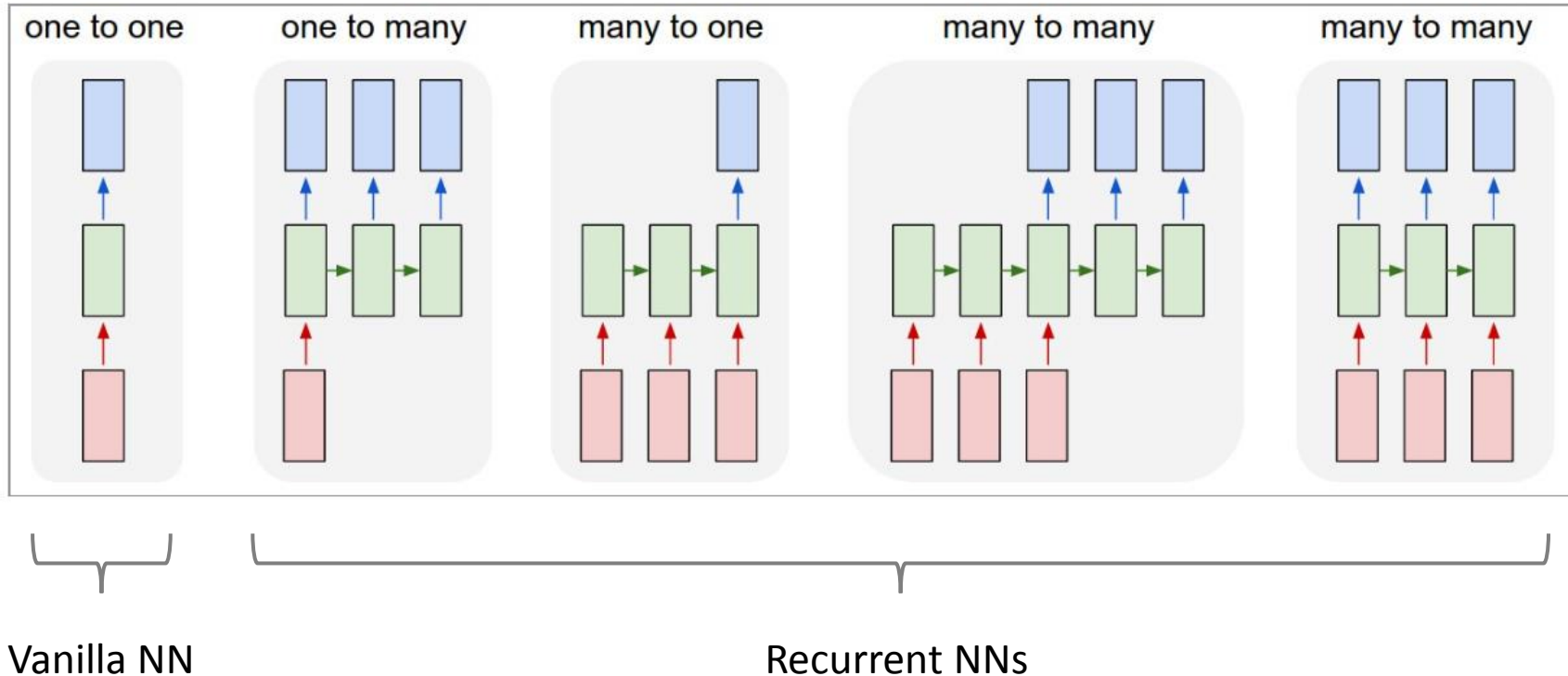


# Recurrent Neural Network (RNN)

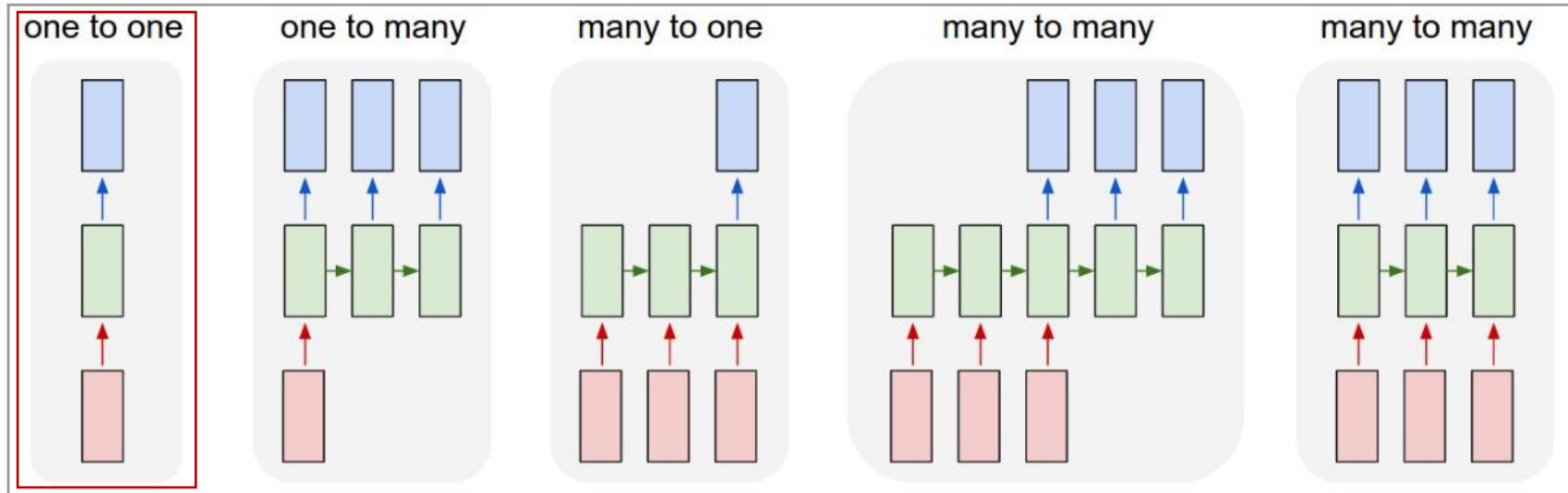
- A recurrent neural network can be thought of as multiple copies of the same network, each passing a message to a successor.



# RNN Architectures



# One-to-one



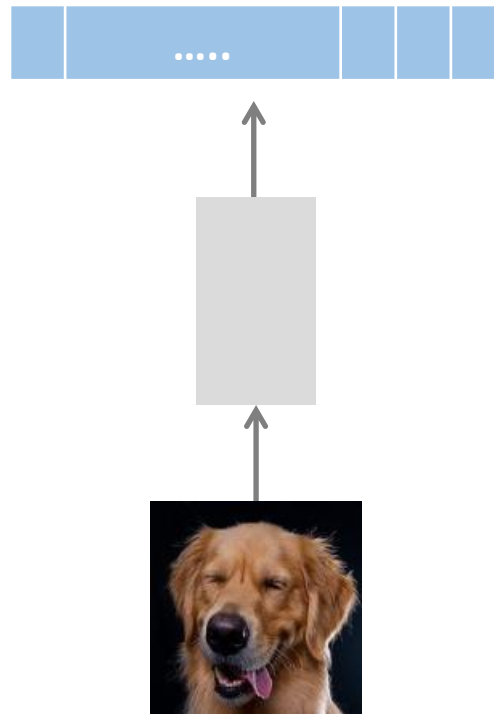
Vanilla mode of processing without RNN

*Example: Image classification*

# Example: One-to-one

Vanilla mode of processing without RNN

*Example: Image classification*

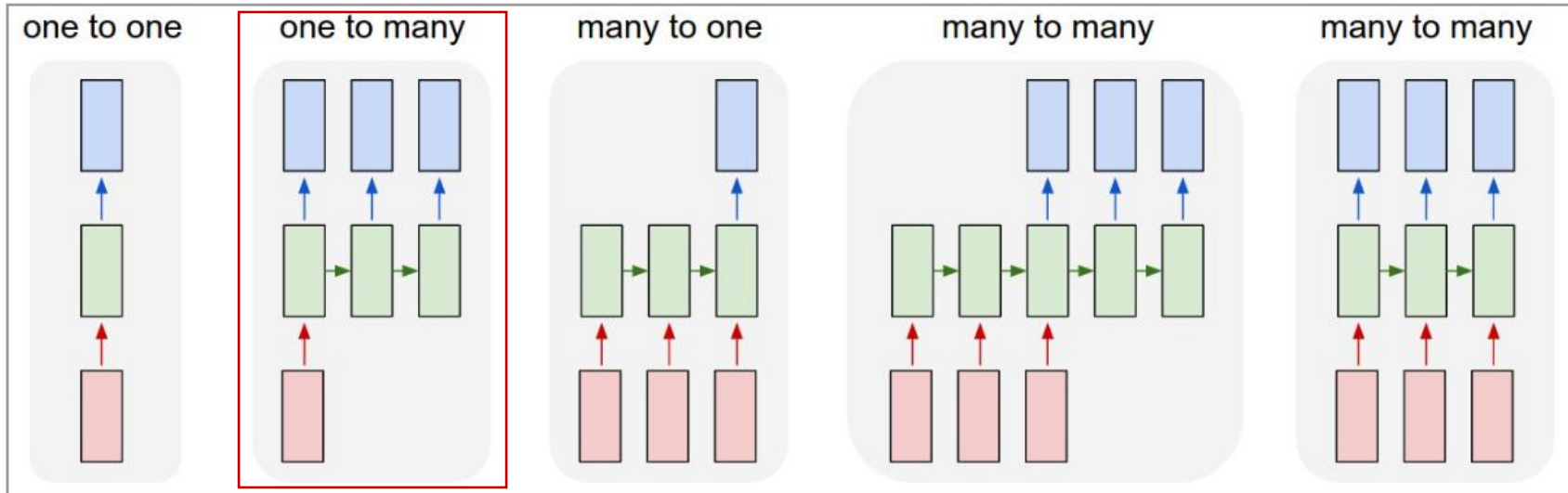


*Prediction: "Dog"*

*Vanilla NN*

*Image*

# One-to-many



Sequence output

*Example: Image captioning*

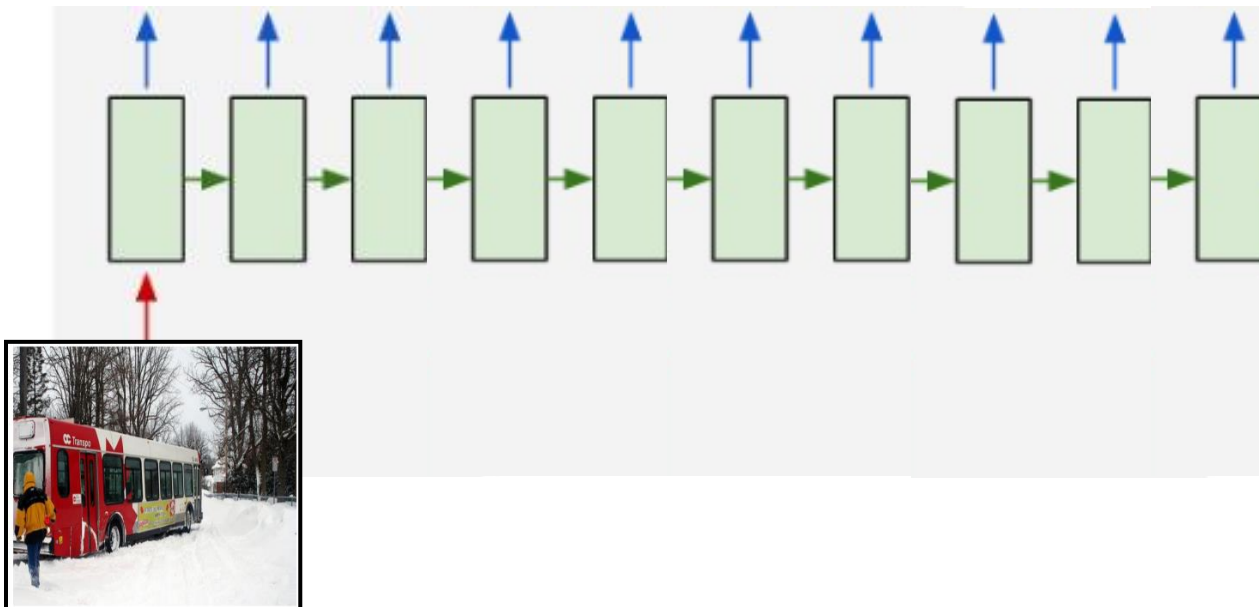


# Example: One-to-many

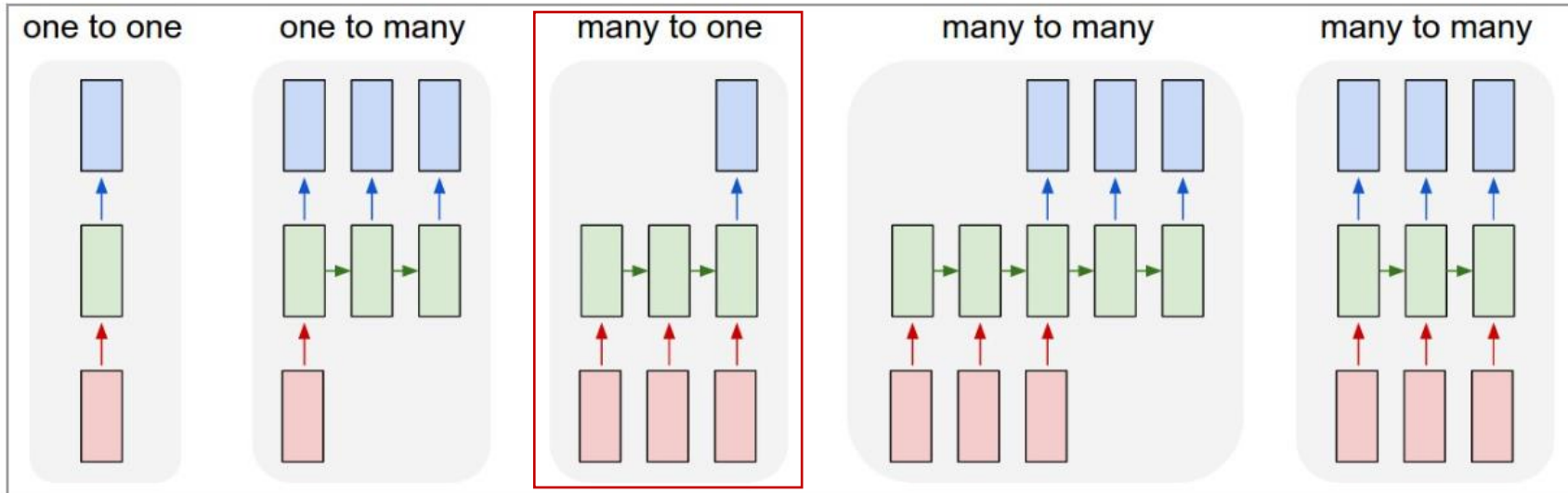
## Sequence output

*Example: Image Captioning*

Bus driving down a snowy road next to trees <EOS>



# Many-to-one



Sequence input

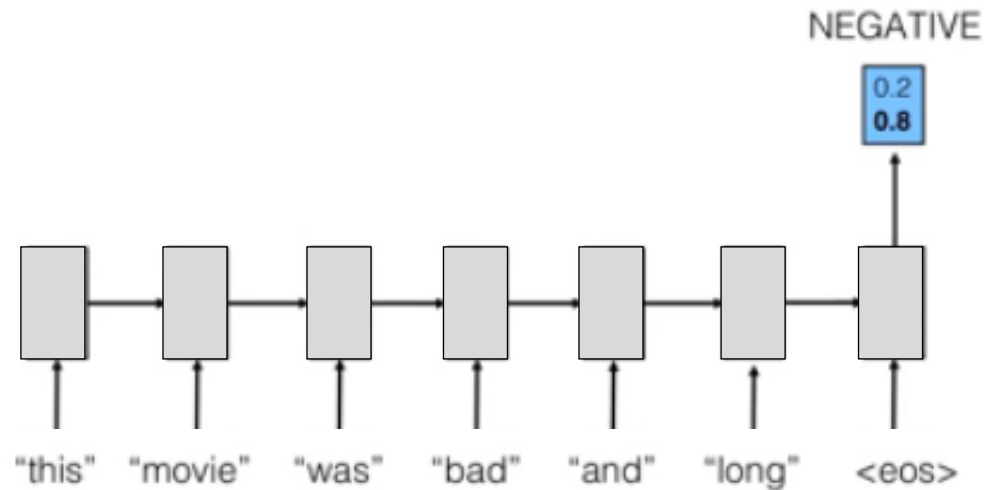
*Examples: Sentiment analysis*

*Action recognition*

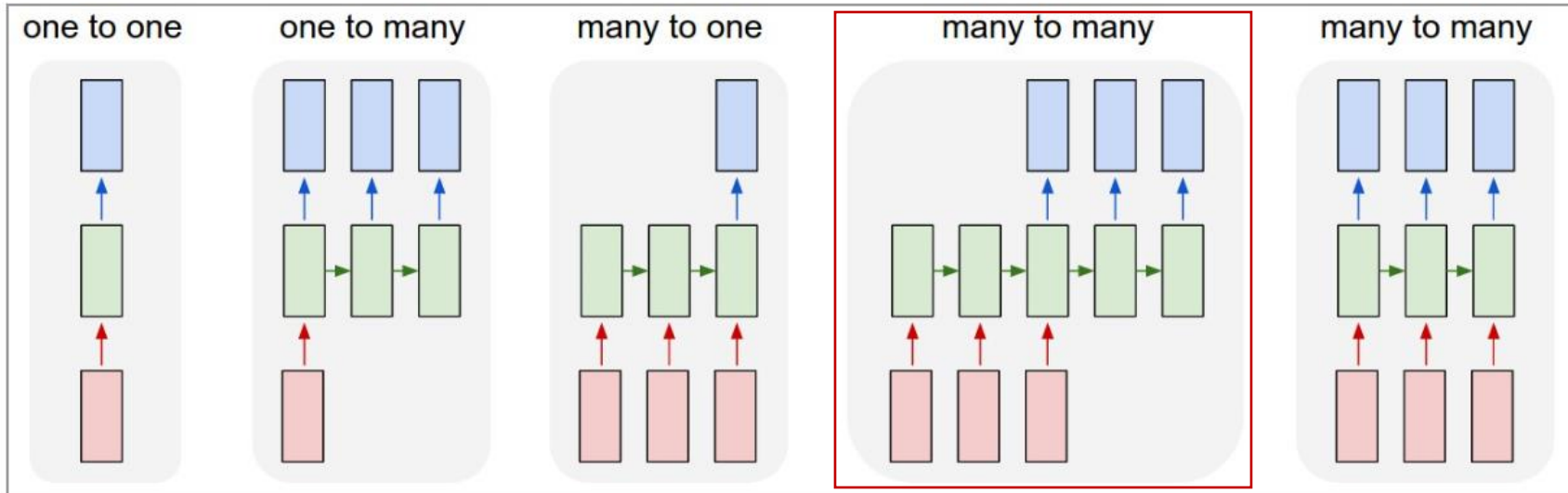
# Example: Many-to-one

## Sequence input

*Example: Sentiment analysis*



# Many-to-many



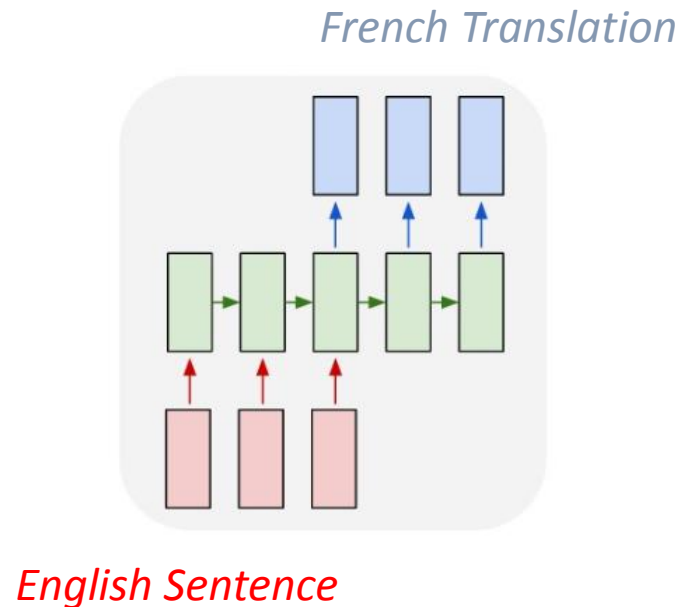
Sequence input and sequence output

*Example: Machine translation*

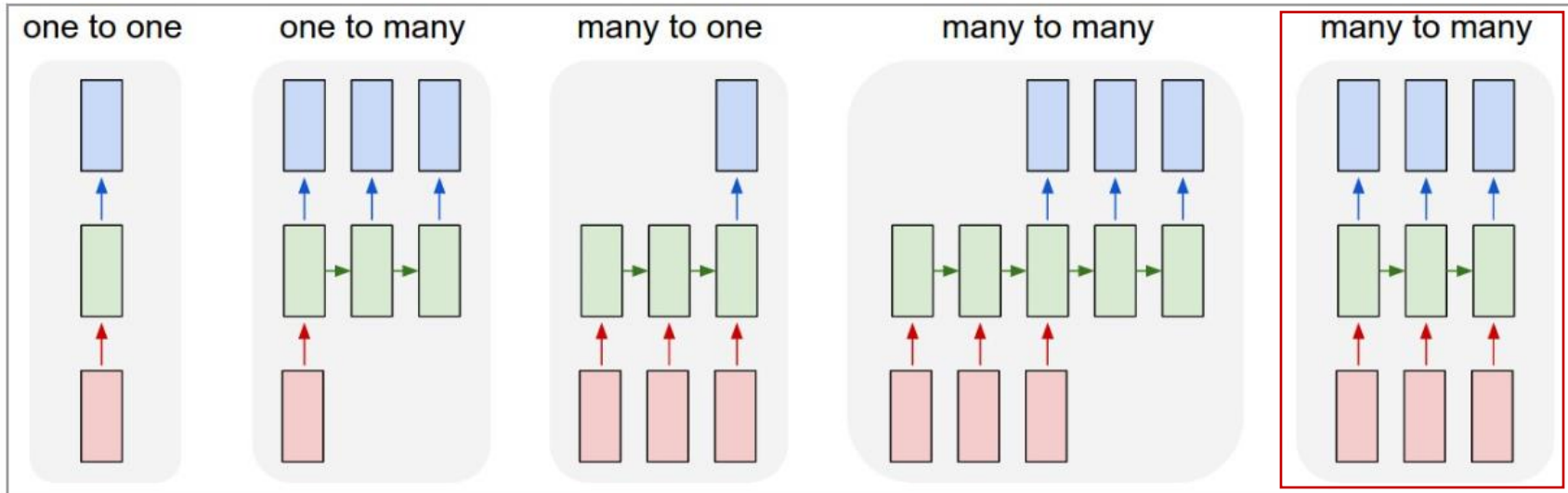
# Example: Many-to-many

Sequence input and sequence output

*Example: Machine translation*



# Synced Many-to-many



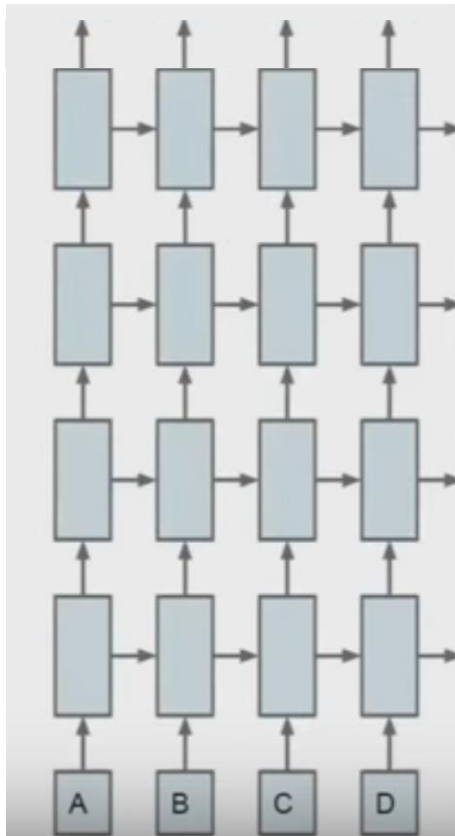
Synced sequence input and output

*Examples: Tracking*

*Early action detection*



# Deep RNNs



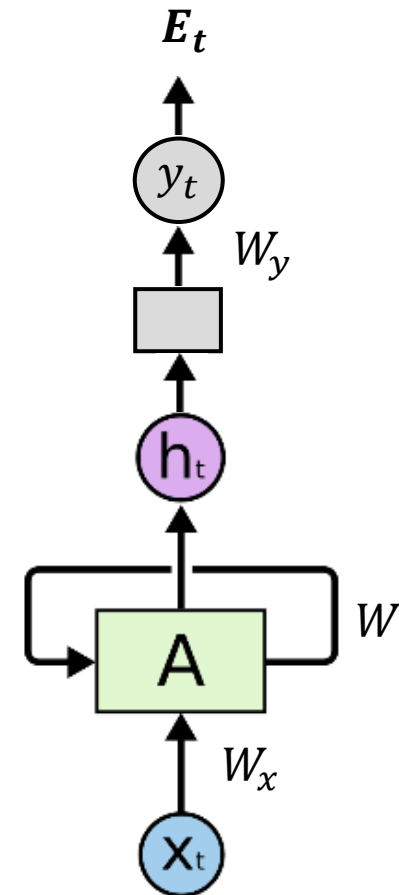
- Stacking RNNs
- More ways of propagating information!
- Requires a lot of data!

# Fwd RNN TT

- Forward pass through time

$$h_t = W\phi(h_{t-1}) + W_x x_t$$

$$y_t = W_y \phi(h_t)$$

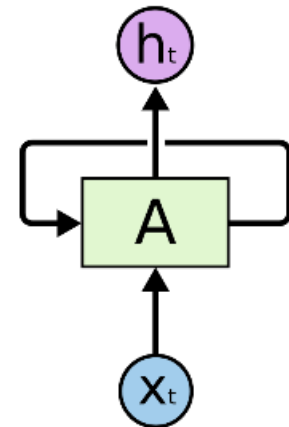


# Recurrent Neural Network (RNN)

Aside: Forward pass

$$h_t = W\phi(h_{t-1}) + W_x x_t$$

$$y_t = W_y \phi(h_t)$$



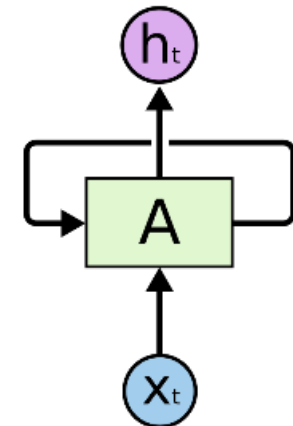
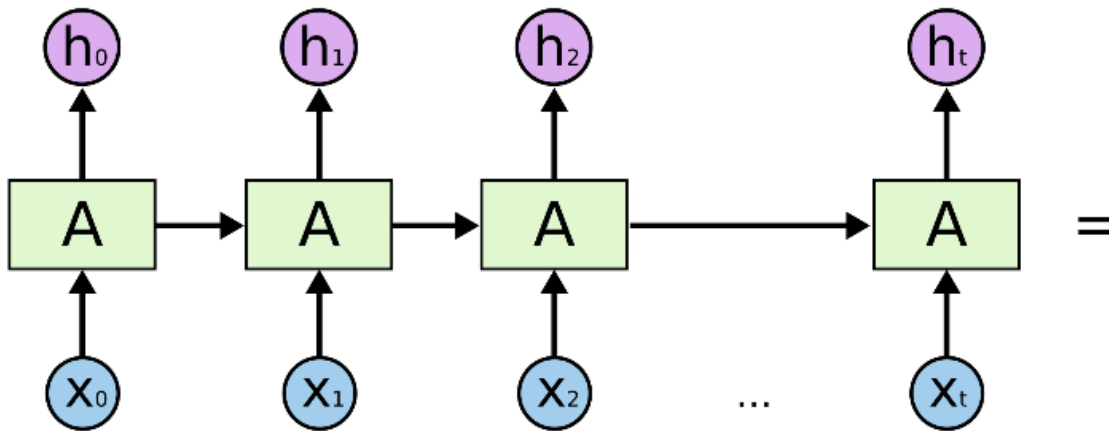
# Recurrent Neural Network (RNN)

- Error or cost is computed for each prediction.

Aside: Forward pass

$$h_t = W\phi(h_{t-1}) + W_x x_t$$

$$y_t = W_y \phi(h_t)$$

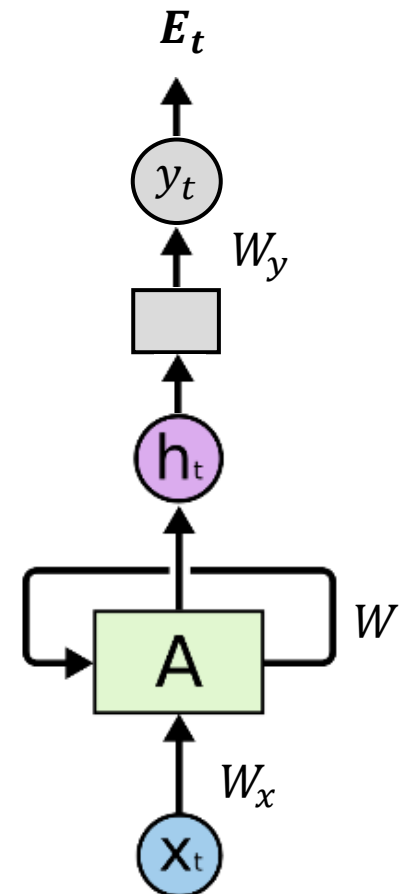


# BP TT

- Backpropagation through time

$$\frac{\partial E}{\partial W} = \sum_{t=1}^T \frac{\partial E_t}{\partial W}$$

Aside: Forward pass



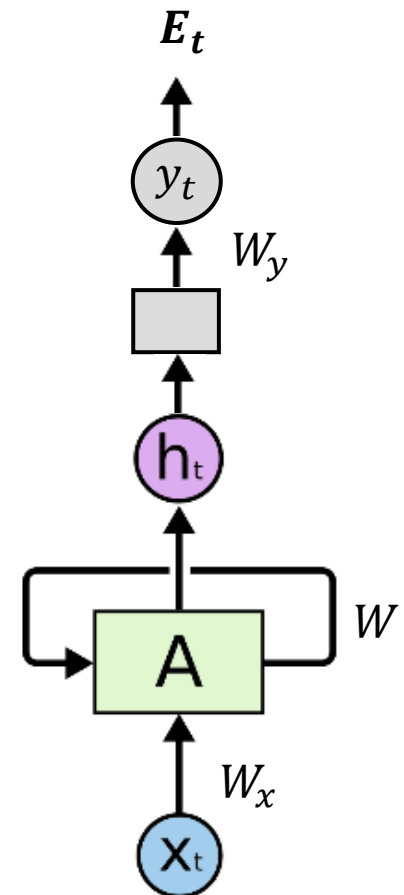
# BP TT

- Backpropagation through time

$$\frac{\partial E}{\partial W} = \sum_{t=1}^T \boxed{\frac{\partial E_t}{\partial W}}$$

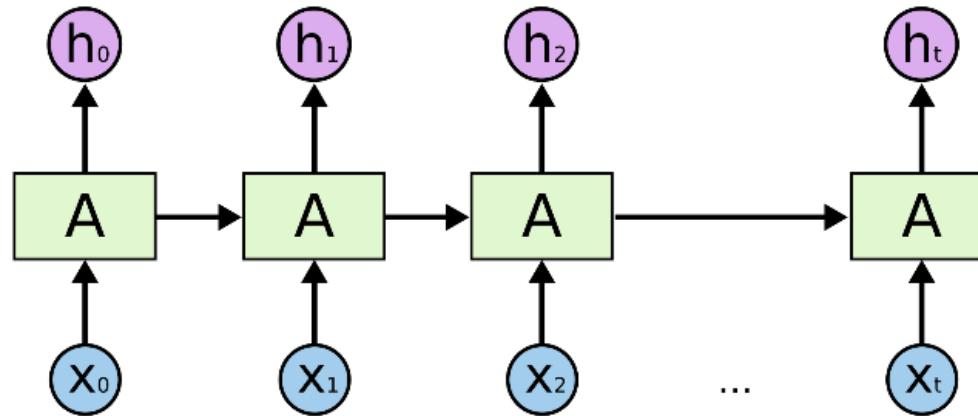
$$\frac{\partial E_t}{\partial W} = \sum_{k=1}^t \frac{\partial E_t}{\partial y_t} \frac{\partial y_t}{\partial h_t} \frac{\partial h_t}{\partial h_k} \frac{\partial h_k}{\partial W}$$

Aside: Forward pass



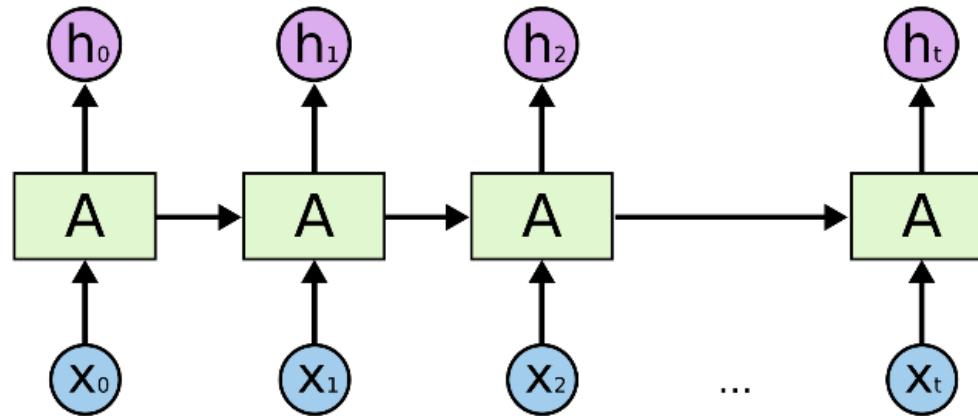


# BP TT



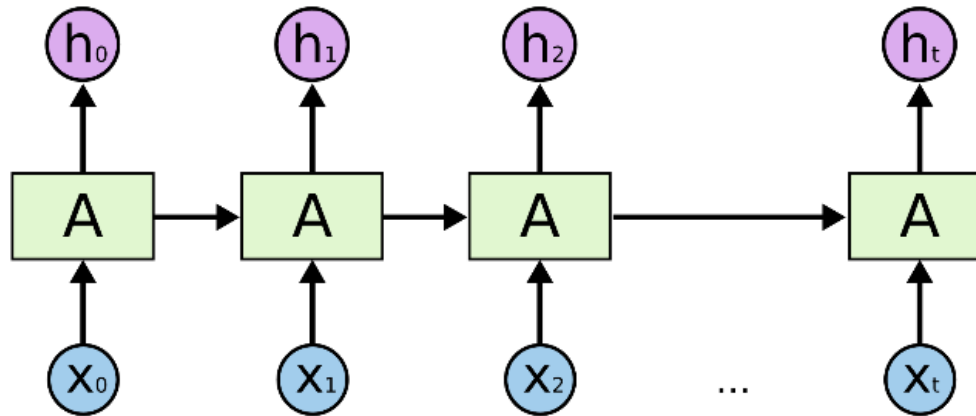
$$\frac{\partial E_t}{\partial W} = \sum_{k=1}^t \frac{\partial E_t}{\partial y_t} \frac{\partial y_t}{\partial h_t} \frac{\partial h_t}{\partial h_k} \frac{\partial h_k}{\partial W}$$

## BP TT



$$\frac{\partial E_t}{\partial W} = \sum_{k=1}^t \frac{\partial E_t}{\partial y_t} \frac{\partial y_t}{\partial h_t} \boxed{\frac{\partial h_t}{\partial h_k}} \frac{\partial h_k}{\partial W}$$

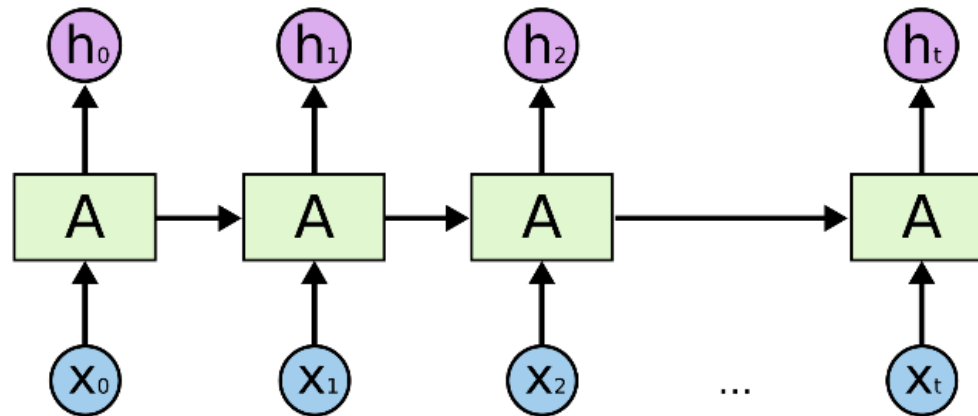
# BP TT



$$\frac{\partial E_t}{\partial W} = \sum_{k=1}^t \frac{\partial E_t}{\partial y_t} \frac{\partial y_t}{\partial h_t} \boxed{\frac{\partial h_t}{\partial h_k}} \frac{\partial h_k}{\partial W}$$

$$\frac{\partial h_t}{\partial h_k} = \prod_{i=k+1}^t \frac{\partial h_i}{\partial h_{i-1}}$$

# BP TT



$$\frac{\partial E_t}{\partial W} = \sum_{k=1}^t \frac{\partial E_t}{\partial y_t} \frac{\partial y_t}{\partial h_t} \frac{\partial h_t}{\partial h_k} \frac{\partial h_k}{\partial W}$$

$$\frac{\partial h_t}{\partial h_k} = \prod_{i=k+1}^t \frac{\partial h_i}{\partial h_{i-1}}$$

For example @  $t = 2$ ,

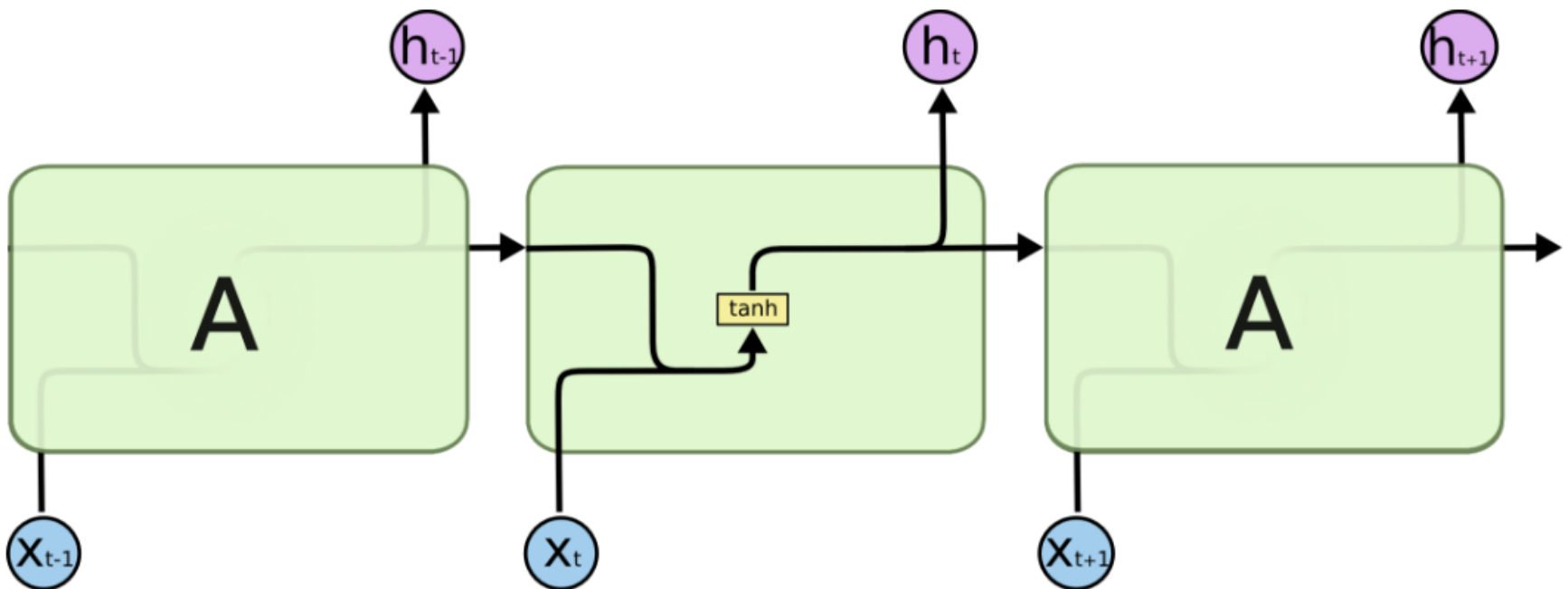
$$\frac{\partial h_2}{\partial h_0} = \prod_{i=1}^2 \frac{\partial h_i}{\partial h_{i-1}} = \frac{\partial h_1}{\partial h_0} \frac{\partial h_2}{\partial h_1}$$

# Vanishing (and Exploding) Gradients

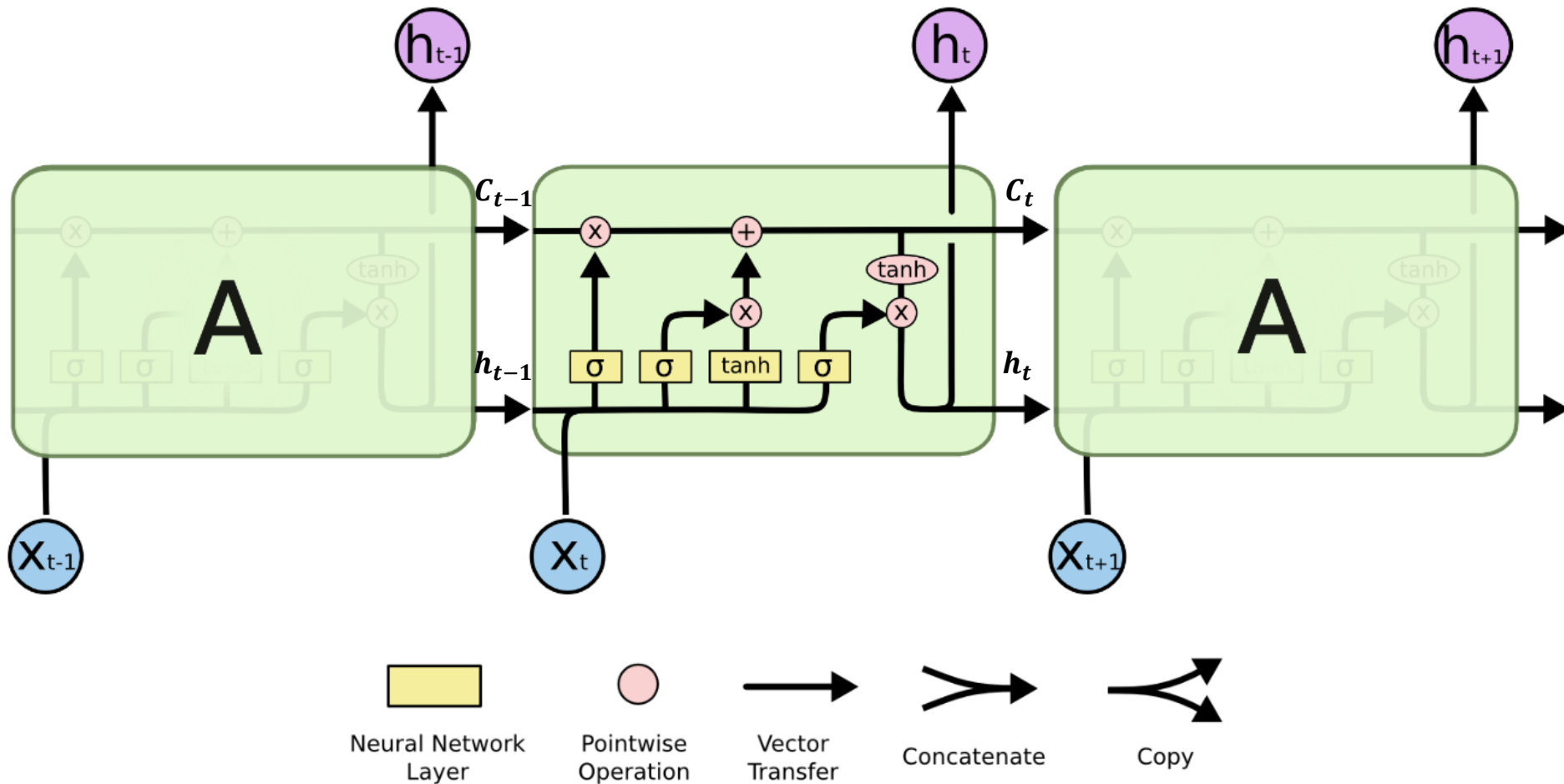
- Exploding Gradients
  - Easy to detect
  - Clip the gradient at a threshold
- Vanishing Gradients
  - More difficult to detect
  - Architectures designed to combat the problem of vanishing gradients. Example: LSTMs by *Schmidhuber et al.*

# RNNs

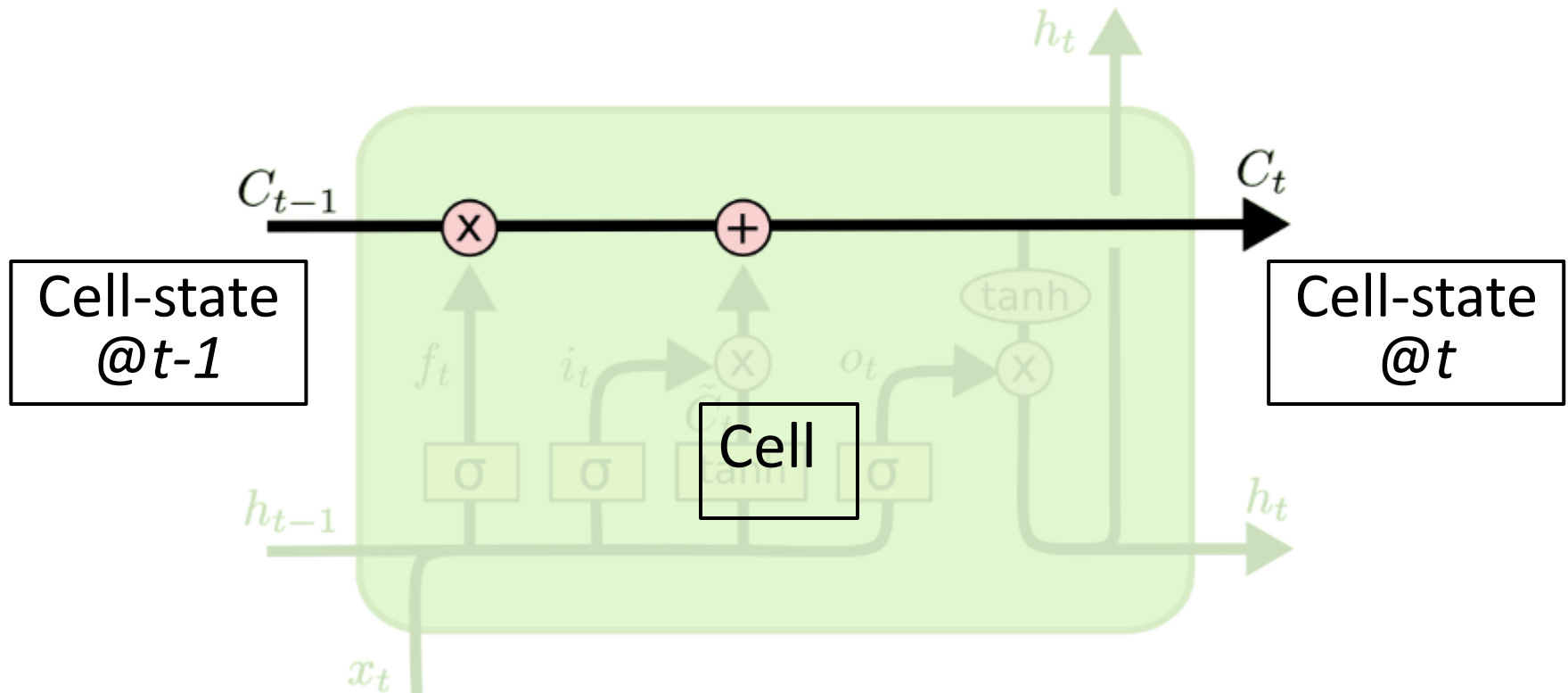
- In a standard RNN the repeating module has a simple structure. Example:



# LSTMs



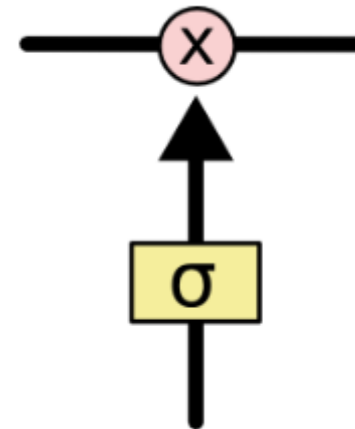
# LSTM Memory / Cell State





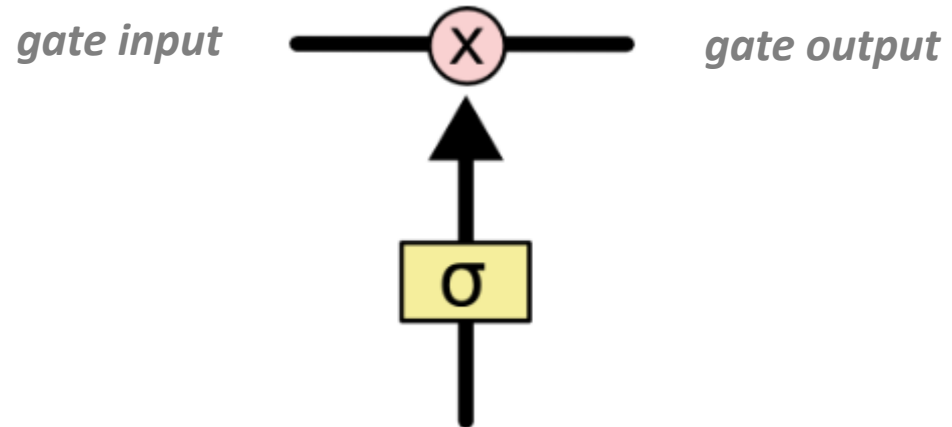
# Gate

- Composed of a sigmoid neural net layer and a pointwise multiplication operation.



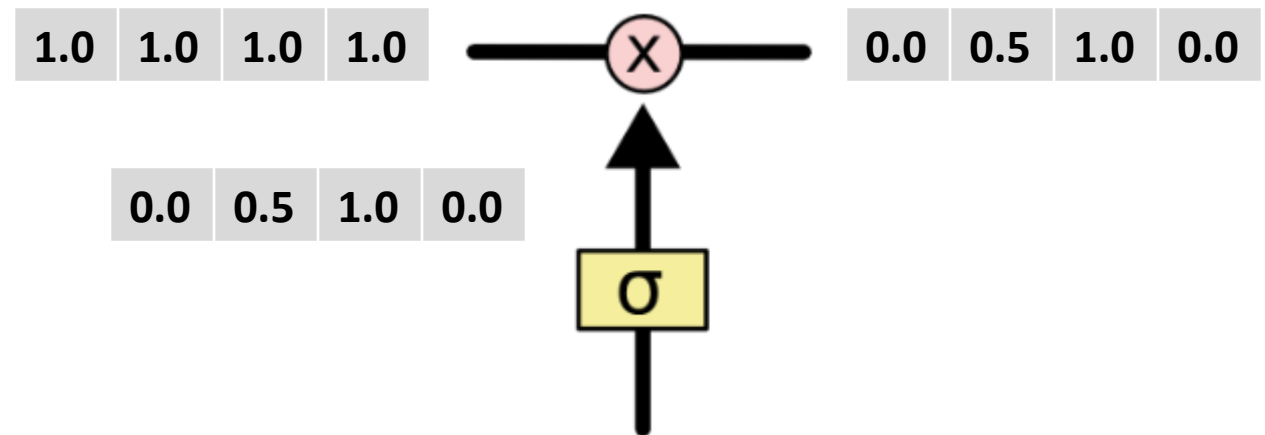
# Gate

- sigmoid: outputs numbers between:
  - zero “let nothing through,” and
  - one, “let everything through!”
- Example:



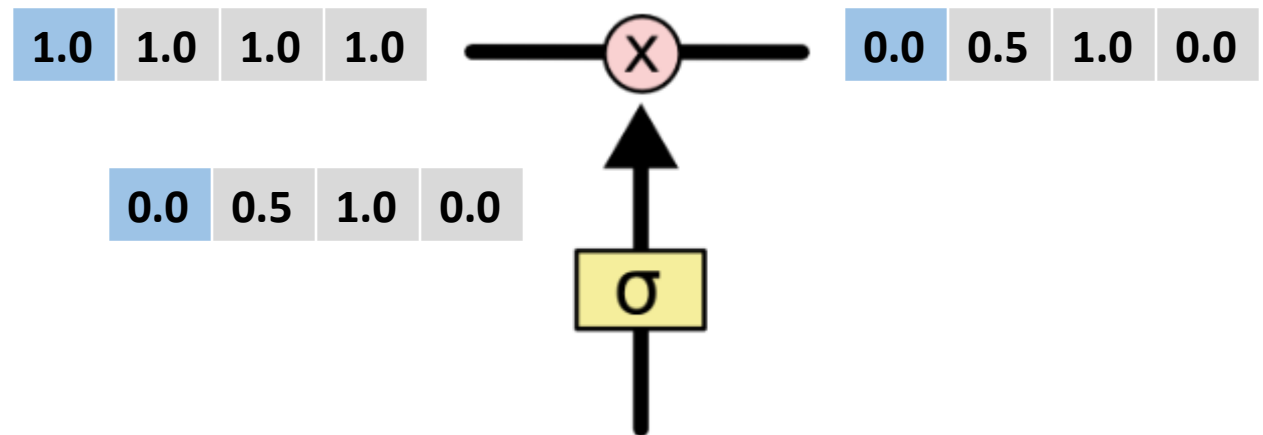
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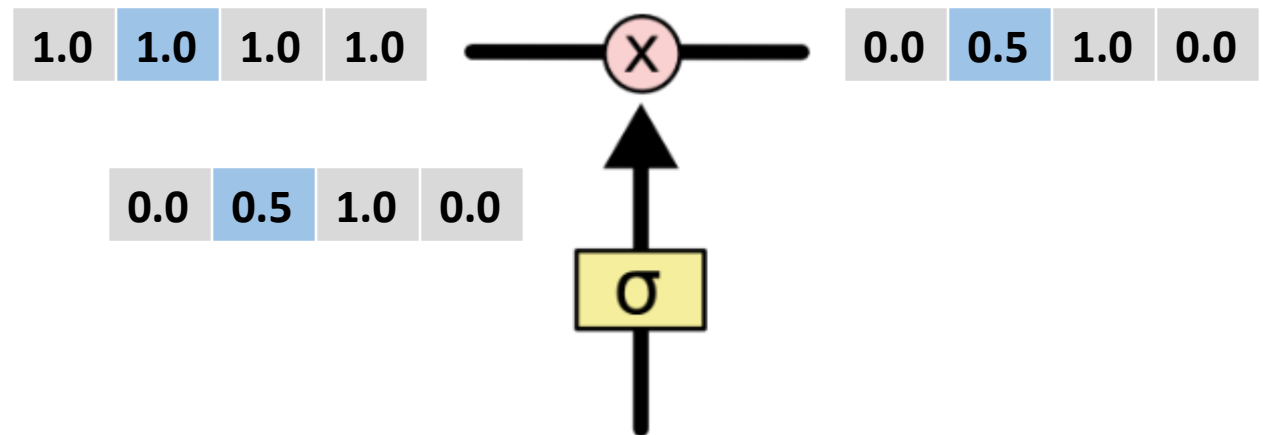
# Gate

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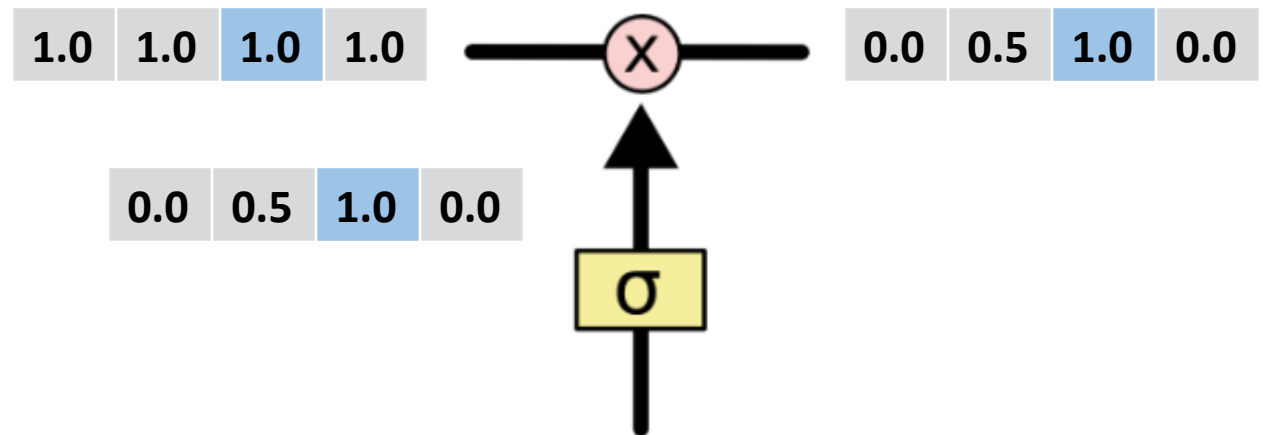
# Gate

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- Example:



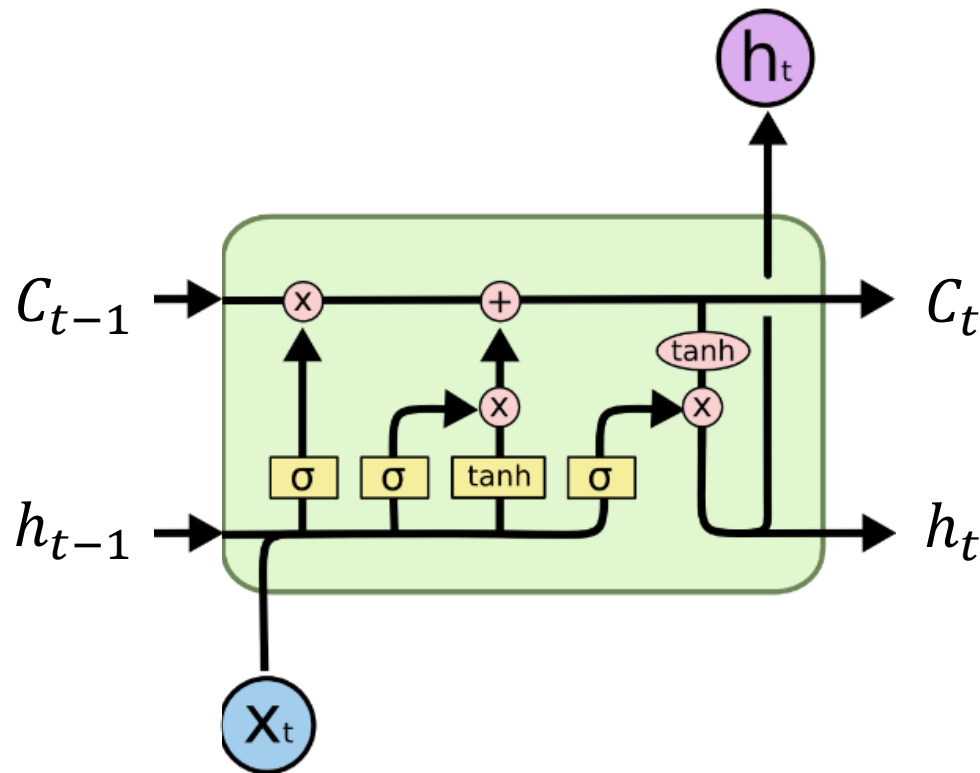
# Gate

- sigmoid: outputs numbers between:
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- Example:



# LSTM Gates

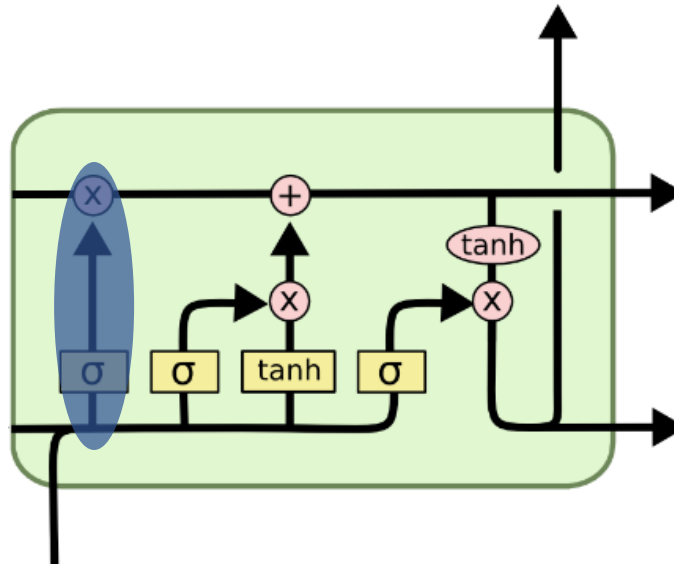
- An LSTM has three of these gates.



# LSTM Gates

- An LSTM has three of these gates.

*Forget gate*

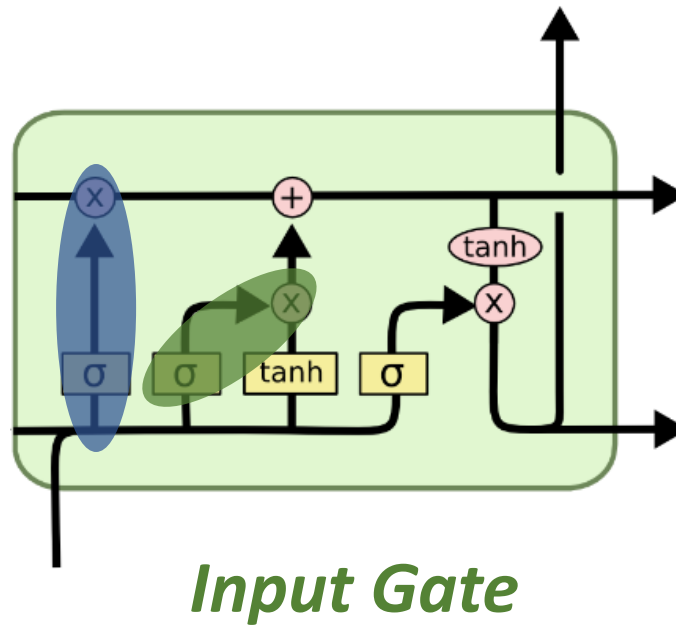




# LSTM Gates

- An LSTM has three of these gates.

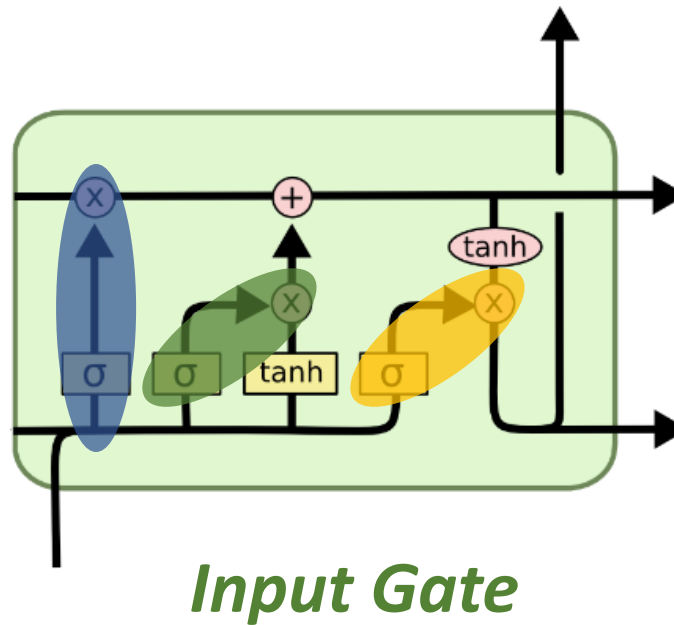
*Forget gate*



# LSTM Gates

- An LSTM has three of these gates.

*Forget gate*

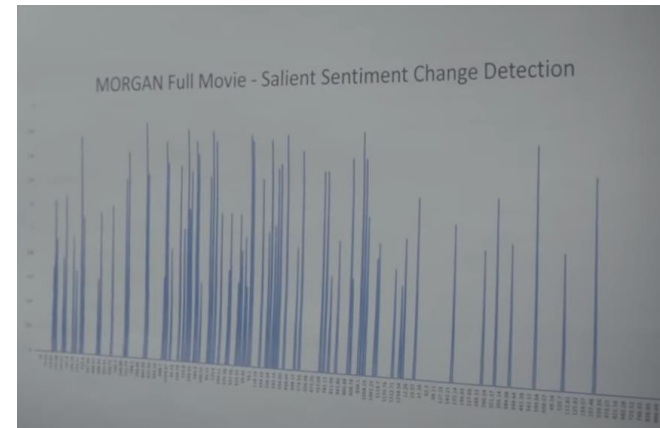


*Output Gate*

# Example: AI Generated Trailer

- Analyze a movie and generate a trailer automatically

- How?  
Detecting salient moments  
e.g. action/emotions



- <https://www.youtube.com/watch?v=gJEzuYynaiw>

# Detecting Salient Regions

- Two sample actions:

*Handstand Walking*



*Ice Dancing*

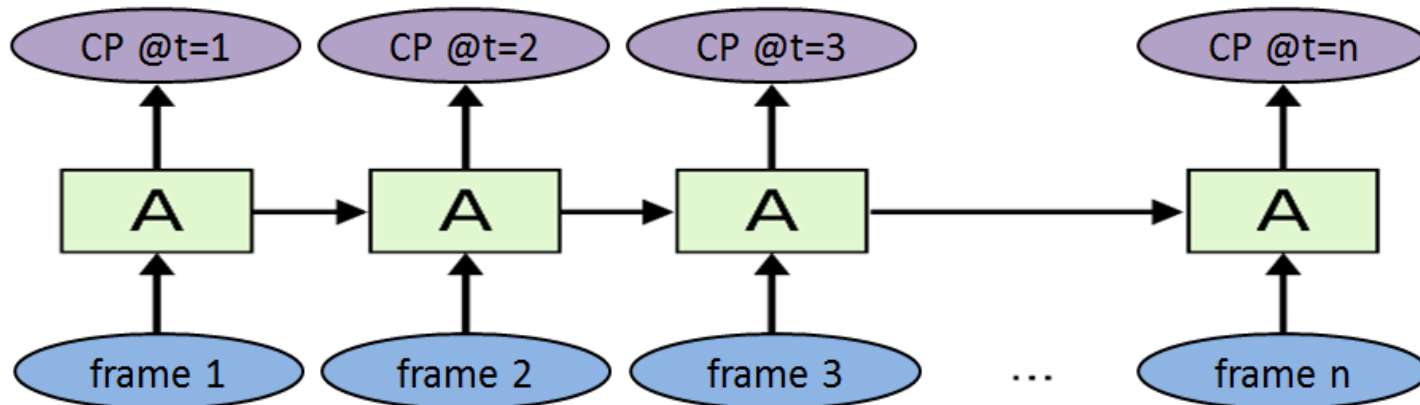




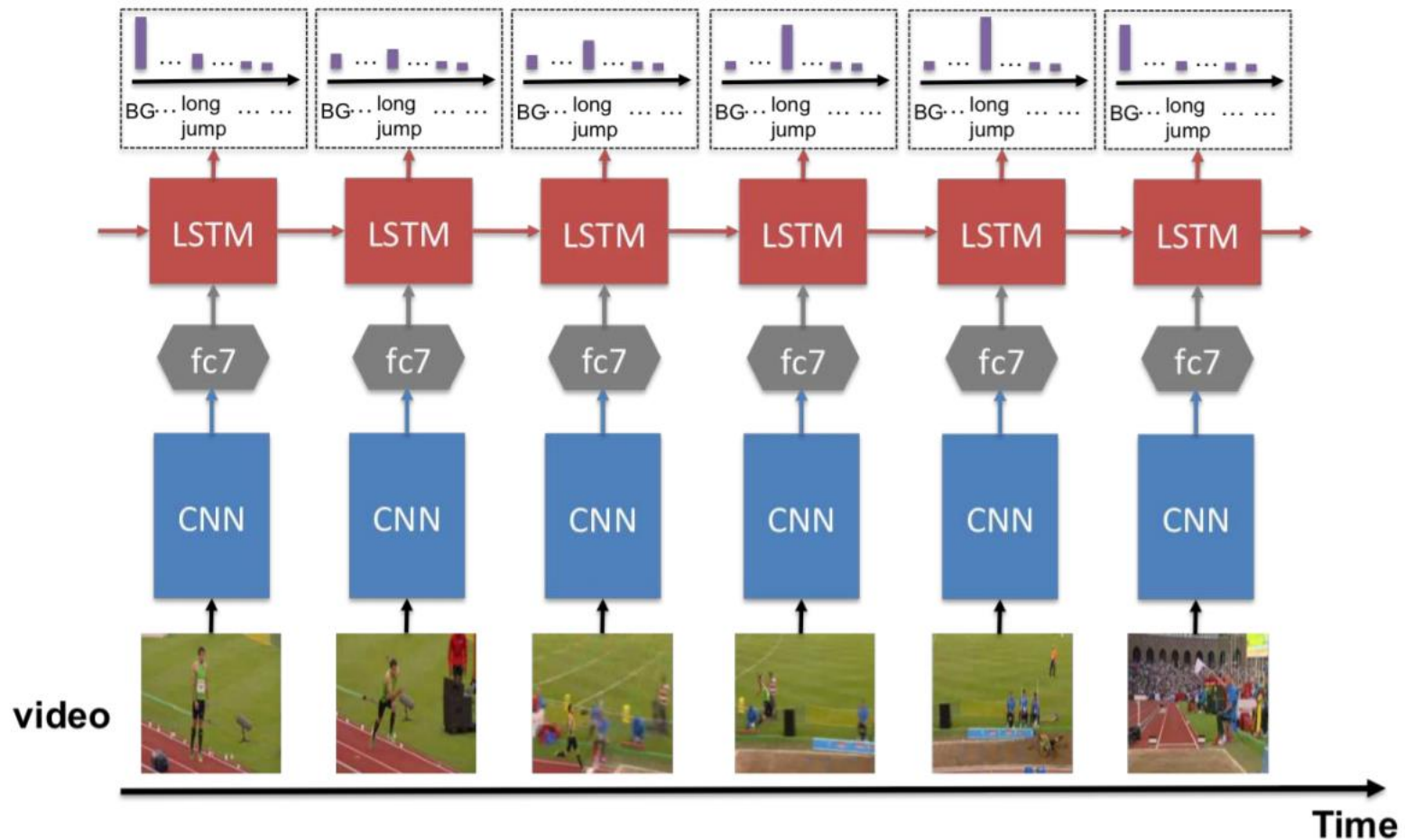
# Applications of Recurrent Networks

# Application 1: Video Classification

- CP: conditional class probability
- $\text{frame } i$  could be a feature describing frame  $i$ , example: CNN feature

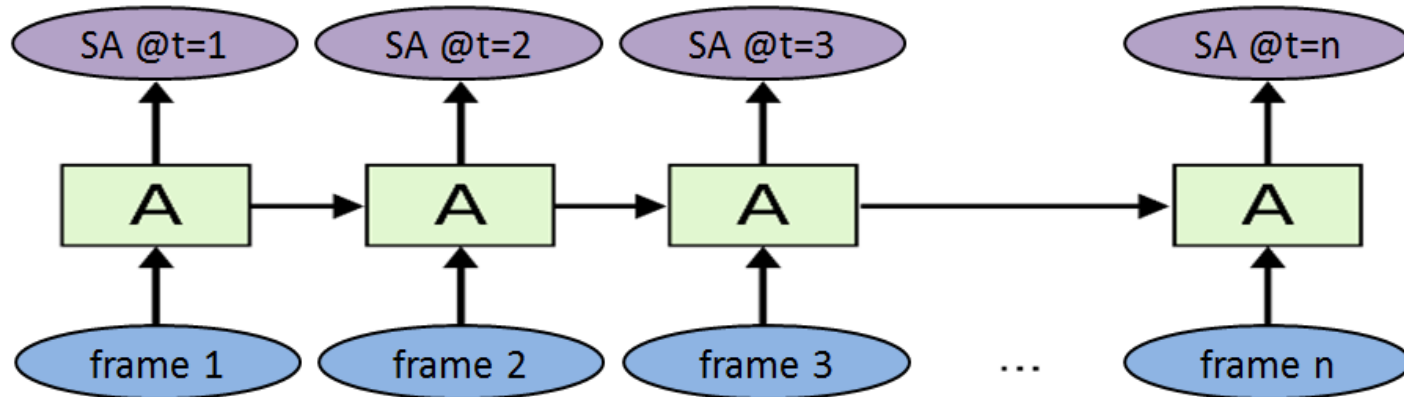


# Application 1: Video Classification



# Application 2: Self-Driving Cars

- SA: steering angle
- frame  $i$  could be a feature describing frame  $i$ ,  
example: 3D-CNN feature





# Application 2: Self-Driving Cars

- DeepTesla



# Application 2: Self-Driving Cars

- Udacity winning team: *Team Komanda*
  - $x_t$ : 3D convolution of image sequence
  - $h_t$ : steering angle, speed, torque

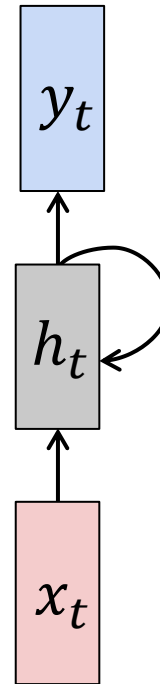


# Application 3: Character RNN

Character-level  
language model  
example

Vocabulary:  
[h,e,l,o]

Example training  
sequence:  
“**hello**”

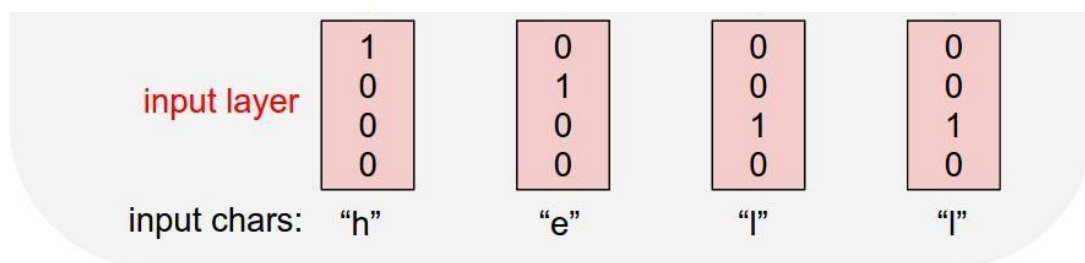


# Application 3: Character RNN

## Character-level language model example

Vocabulary:  
[h,e,l,o]

Example training  
sequence:  
“hello”

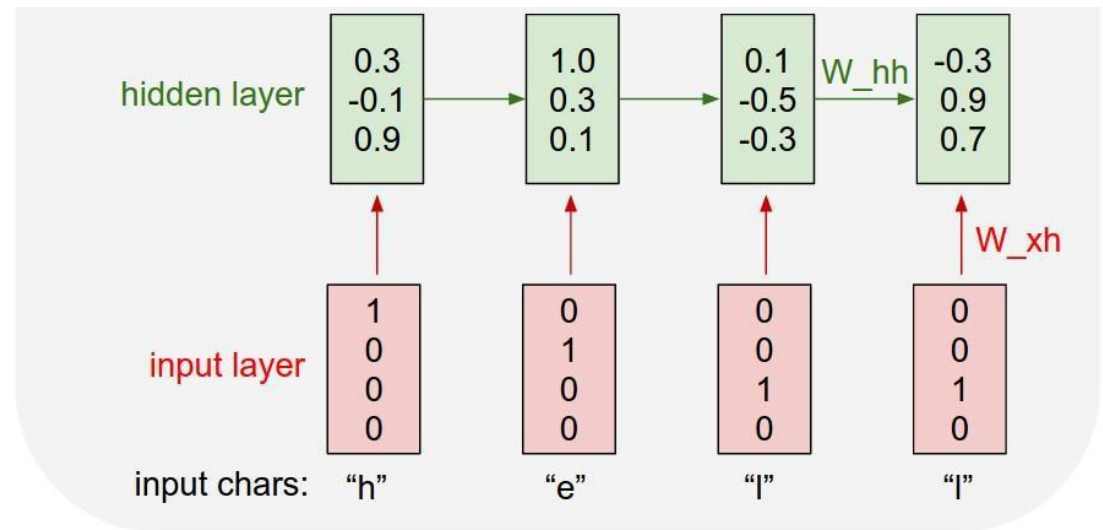


# Application 3: Character RNN

## Character-level language model example

Vocabulary:  
[h,e,l,o]

Example training  
sequence:  
“hello”

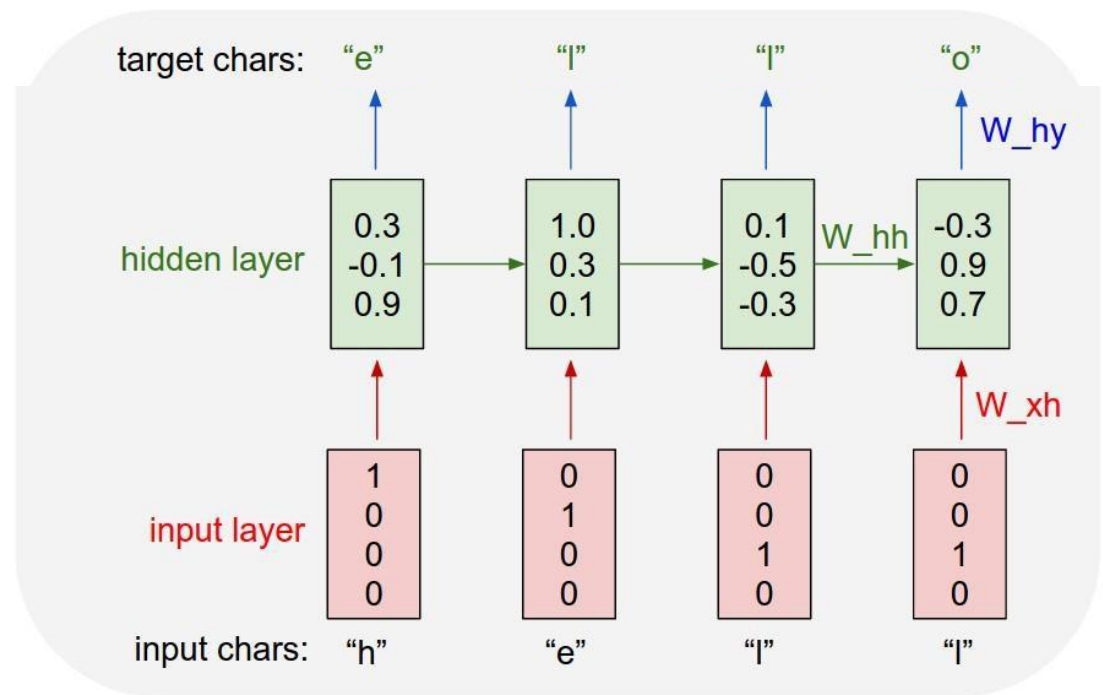


# Application 3: Character RNN

## Character-level language model example

Vocabulary:  
[h,e,l,o]

Example training  
sequence:  
“hello”



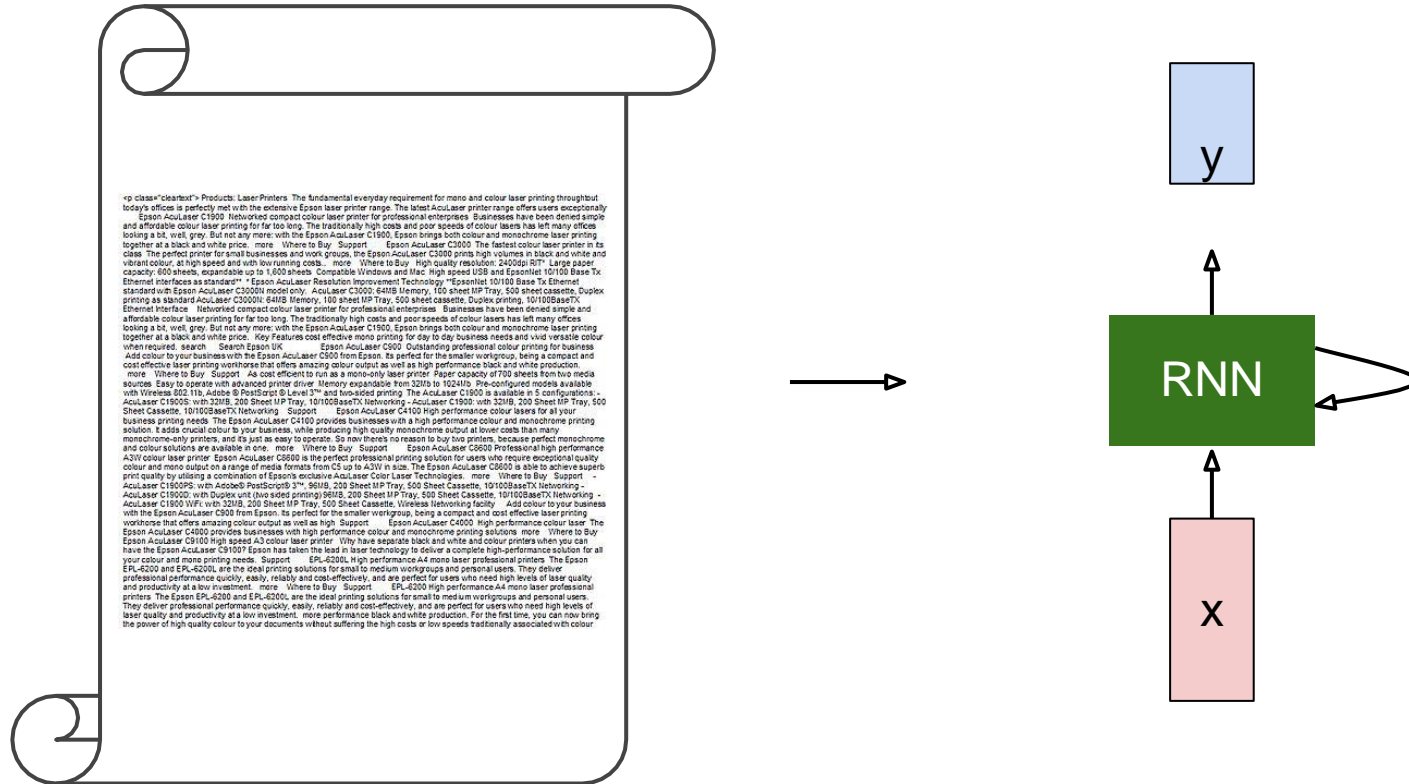
# Application 4: Reading cursive

handwriting

- This is a natural task for an RNN.
- The input is a sequence of  $(x,y,p)$  coordinates of the tip of the pen, where  $p$  indicates whether the pen is up or down.
- The output is a sequence of characters.
- Graves & Schmidhuber (2009) showed that RNNs with LSTM are well-tailored for reading cursive writing.
  - They used a sequence of small images as input rather than pen coordinates.

# Application 5: StyleText Generation

Training text: William Shakespeare



Fei-Fei Li & Andrej Karpathy & Justin Johnson



# Application 5: StyleText Generation

at  
first:

tyntd-iafhatawiao hr demot lytdws e ,tfti, astai f ogoh eoase rrranbyne 'nhthnee e  
plia tk lrgd t o idoe ns, smtt h ne etie h, hregtrs nigtike, aoaenns lng



train more

"Tmont thithey" fomesscerliund  
Keushey. Thom here  
sheulke, anmerenith ol sivh I lalterthend Bleipile shuw y fil on aseterlome  
coaniogennc Phe lism thond hon at. MeiDimorotion in ther thize."



train more

Aftair fall unsuch that the hall for Prince Velzonski's that me of  
her hearly, and behs to so arwage fiving were to it beloge, pavu say falling misfort  
how, and Gogition is so overelical and ofter.



train more

"Why do what that day," replied Natasha, and wishing to himself the fact the  
princess, Princess Mary was easier, fed in had oftended him.  
Pierre aking his soul came to the packs and drove up his father-in-law women.

# Application 6: Code Generation

## Train on C code

The screenshot shows the GitHub interface for the 'torvalds / linux' repository. At the top, there's a search bar and navigation links like 'Explore', 'Gist', 'Blog', and 'Help'. The repository name 'torvalds / linux' is prominently displayed, along with statistics: 3,711 watches, 23,054 stars, and 9,141 forks. Below this, the 'Linux kernel source tree' is highlighted. A summary bar indicates 520,037 commits, 1 branch, 420 releases, and 5,039 contributors. The main content area shows a list of recent commits, with the most recent one by 'torvalds' 9 hours ago, titled 'Merge branch 'drm-fixes' of git://people.freedesktop.org/~airlied/linux'. The commit details show a merge of 'git://git.kernel.org/pub/scm/linux/kernel/git/nab/target-pending'. A table of recent commits follows, listing various merges and updates across different kernel components like 'Documentation', 'arch', 'block', 'crypto', 'drivers', 'firmware', 'fs', 'include', and 'init'. On the right side, there are links for 'Code', 'Pull requests' (74), 'Pulse', 'Graphs', and 'HTTPS clone URL' (https://github.com/torvalds/linux.git). At the bottom right, there are buttons for 'Clone in Desktop' and 'Download ZIP'.

torvalds / linux

Linux kernel source tree

520,037 commits 1 branch 420 releases 5,039 contributors

branch: master - linux / +

Merge branch 'drm-fixes' of git://people.freedesktop.org/~airlied/linux

torvalds authored 9 hours ago latest commit 4b1786927d

Directory	Commit Message	Time Ago
Documentation	Merge git://git.kernel.org/pub/scm/linux/kernel/git/nab/target-pending	6 days ago
arch	Merge branch 'x86-urgent-for-linus' of git://git.kernel.org/pub/scm/linux/kernel/git/tip/tip	a day ago
block	block: discard bdi_unregister() in favour of bdi_destroy()	9 days ago
crypto	Merge git://git.kernel.org/pub/scm/linux/kernel/git/herbert/crypto-2.6	10 days ago
drivers	Merge branch 'drm-fixes' of git://people.freedesktop.org/~airlied/linux	9 hours ago
firmware	firmware/hex2fw.c: restore missing default in switch statement	2 months ago
fs	vfs: read file_handle only once in handle_to_path	4 days ago
include	Merge branch 'perf-urgent-for-linus' of git://git.kernel.org/pub/scm/linux/kernel/git/tip/tip	a day ago
init	init: fix regression by supporting devices with major:minor:offset fo...	a month ago

HTTPS clone URL  
https://github.com/torvalds/linux.git

You can clone with HTTPS, SSH, or Subversion.

Clone in Desktop

Download ZIP

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```
static void do_command(struct seq_file *m, void *v)
{
    int column = 32 << (cmd[2] & 0x80);
    if (state)
        cmd = (int)(int_state ^ (in_8(&ch->ch_flags) & Cmd) ? 2 : 1);
    else
        seq = 1;
    for (i = 0; i < 16; i++) {
        if (k & (1 << 1))
            pipe = (in_use & UMXTHREAD_UNCCA) +
                ((count & 0x00000000ffffffff8) & 0x0000000f) << 8;
        if (count == 0)
            sub(pid, ppc_md.kexec_handle, 0x20000000);
        pipe_set_bytes(i, 0);
    }
    /* Free our user pages pointer to place camera if all dash */
    subsystem_info = &of_changes[PAGE_SIZE];
    rek_controls(offset, idx, &soffset);
    /* Now we want to deliberately put it to device */
    control_check_polarity(&context, val, 0);
    for (i = 0; i < COUNTER; i++)
        seq_puts(s, "policy ");
}
```

Generated  
C code

# Application 7: Writing a Movie Script



<https://arstechnica.com/the-multiverse/2016/06/an-ai-wrote-this-movie-and-its-strangely-moving/>