

EC504 ALGORITHMS AND DATA STRUCTURES  
FALL 2020 MONDAY & WEDNESDAY  
2:30 PM - 4:15 PM

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# Course Organization

- **Text:**

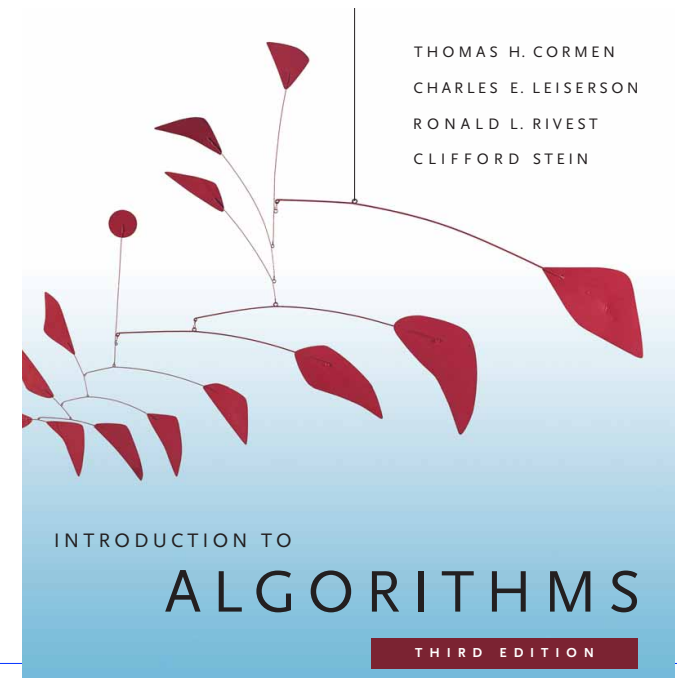
- Cormen, Leiserson, Rivest & Stein (CLRS), Fundamental text  
“Introduction to Algorithms” 3rd Edition MIT Pres

- **Reference:**

- Wikipedia
- Mark Allen Weiss “Data Structure and Algorithms in C++”.
- Handouts on specific topics as needed

- **Grading:**

- |                |     |
|----------------|-----|
| – HW (Written) | 20% |
| – HW: Software | 20% |
| – Project      | 20% |
| – Exams (2)    | 40% |



## Course Organization - 2

- Web Site in [learn.bu.edu](http://learn.bu.edu)
- On-line classes
- Regular HW (not weekly; 8 or so during term)
- Office hours: TBD, or by appointment.
- Software: C++, using C++ 11 compatible
- Development: Accounts set up
- HW submission: On Blackboard, with code submitted separately
- Important: This is **not a course to learn software**. We use software to learn about data structures and algorithms, not the other way around...

## Course Organization - 3

- Lectures are recorded, will be posted to web site within 5 hours
- In-class questions welcome
  - Unmute and ask
  - Or raise hand (less clear to instructor!)
- HW will have on-line component, hand-in component and software component
  - On-line short questions with instant feedback using Blackboard quiz
  - SW will provide main program, input files, and output files for debugging.  
You will develop needed functions.
- We will use Piazza for asynchronous question/answers at all hours
  - Enables all of you to benefit from answers

## Course Organization - 4

- Course includes a project
  - Some topics will be suggested
  - Topics can be suggested by students
- Projects can be done in teams of up to 4 people
  - Or individually...Depends on how large a project one proposes
- Typical project: Develop a set of algorithms for solving a class of problems, implemented with different data structures, and evaluate the computation performance on realistic problem data.

## Course Organization - 5

- Policy on Cooperation
  - HW: Discussions with classmates, colleagues and googling on web are allowed in general
  - But you have to write down the solution yourself and fully understand what you write
  - Your code must be your own: base it on what you read on the web, but don't copy verbatim
  - Plagiarism tools will be used extensively. Any violations will result in course failure and referral to College Academic Council

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## What is EC504 About?

- Data structures store data in manners that support efficient algorithm computation.
- Algorithms with appropriate data structures can improve problem solution efficiency by orders of magnitude.
- In this course, we study both advanced algorithms and appropriate data structures for solution of practical problems.
- We will focus on rigorous analysis, realistic applications and implementation.
- Software implementations of algorithms/data structures will be part of the course.



# Course Outline

1. Review: Algorithm Analysis (CLRS 2-4)
  - Asymptotic complexity
  - Recursions
2. Sorting: Classical and modern approaches (CLRS 4,9, Notes on TimSort)
3. Review: Trees and their Properties (CLRS App. B)
4. Efficient Search in one-dimension
  - Hash Tables (CLRS 11)
  - Balanced Search Trees (Red-Black, Splay, B-Trees, VEB trees) (CLRS 12,13,18,20)
  - Priority queues (Binary, Binomial, Fibonacci Heaps, VEB trees) (CLRS 6,19,20)

## Course Outline - 2

### 6. Graphs and Network Optimization (CLRS 22)

- Minimum spanning trees: Greedy algorithms (CLRS 23)
- Shortest Paths: Greedy algorithms, Dynamic Programming (CLRS 24,25)
- Max-flow: Ford-Fulkerson, Preflow-push (CLRS 26)
- Min-cost flow: Assignment problems, auction algorithms, successive shortest path algorithms (Notes)
- Applications (Notes)

### 7. Complexity Theory

- NP-Complete Problems - Definition and examples (CLRS 34)
- Approximation Algorithms - Knapsack, Traveling Salesperson, ... (CLRS 35)

### 8. Advanced Topics

What is an algorithm? An unambiguous list of steps (program) to transform some input into some output.



- Pick a Problem (set)
- Find method to solve
  1. Correct for all cases (elements of set)
  2. Each step is finite ( $\Delta t_{\text{step}} < \text{max time}$ )
    - Next step is unambiguous
    - Terminate in finite number of steps
- ◆ You know many examples:  
GCD, Multiply 2 N bit integers, ...

Abu Ja'far Muhammad ibn Musa Al-Khwarizmi  
Bagdad (Iraq) 780-850

# Growth of Algorithm Run Time with Size n:

## Big “Oh”

- $O(g(n))$  : Set of functions of  $n$  that grow no faster than  $g(n)$  as  $n$  gets large

$f(n) \in O(g(n))$  if and only if there exists  $c > 0, N_0 > 0$  such that  $|f(n)| \leq c|g(n)|$  whenever  $n > N_0$

Alternative:  $f(n) \in O(g(n)) \iff \lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} < \infty$

$f(n) \in O(g(n))$ , or  $f(n)$  is  $O(g(n))$ , or  $f(n) = O(g(n))$

$f(n) \in o(g(n)) \iff \lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = 0$

## Growth of Algorithms: Other concepts

- $o(g(n))$  : grow strictly slower than  $g(n)$   $f(n) \in o(g(n)) \iff \lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = 0$
- $\Omega(g(n))$  : grow no slower than  $g(n)$  as  $n$  gets large  
 $f(n) \in \Omega(g(n))$  if and only if there exists  $c > 0, N_0 > 0$  such that  $|f(n)| \geq c|g(n)|$  whenever  $n > N_0$
- $\omega(g(n))$  : grow strictly faster than  $g(n)$   $f(n) \in \omega(g(n)) \iff \lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = \infty$
- $\Theta(g(n))$  : grow similar to  $g(n)$ :  $f(n) \in O(g(n)), f(n) \in \Omega(g(n))$

## Intuition

- |                   |              |
|-------------------|--------------|
| ▪ $f = O(g)$      | ▪ $f \leq g$ |
| ▪ $f = o(g)$      | ▪ $f < g$    |
| ▪ $f = \Omega(g)$ | ▪ $f \geq g$ |
| ▪ $f = \omega(g)$ | ▪ $f > g$    |
| ▪ $f = \Theta(g)$ | ▪ $f = g$    |

## Rules of thumb

- For polynomials, only the largest term matters.

$$a_0 + a_1N + a_2N^2 + \dots + a_kN^k \in O(N^k)$$

- $\log N$  is in  $o(N)$

Proof: As  $N \rightarrow \infty$  the ratio  $\log(N)/N \rightarrow 0$

- Some common functions in increasing order

$1 \quad \log N \quad \sqrt{N} \quad N \quad N \log N \quad N^2 \quad N^3 \quad N^{100} \quad 2^N \quad 3^N \quad N! \quad N^N$

- For  $r > 1, d > 0, \Rightarrow n^d \in o(r^n)$
- For  $b > 1, r > 0, \Rightarrow (\log(n))^b \in o(n^r)$

## Some examples

- Which increases faster? What is the relation?

- $(100n^2, 0.01 * 2^n)$
- $(0.1 * \log n, 10n)$
- $(10^{10}n, 10^{-10}n^2)$
- $(0.01n^3 - 10, 100n^2)$
- $(\ln(300n^4), \ln(n))$
- $(n^4 + 3n^2 + 1, n^{0.01})$
- $(2^n, 3^n)$
- $(n^{10}, n^n)$
- $(n!, n^2)$  (Stirling's formula:  $n! \approx (2\pi n)^{1/2}(\frac{n}{e})^n$ )



# Why is big-O important?

time

(processor doing ~1,000,000 steps per second)

input size

N	10	20	30	40	50	60
log n	3.3μsec	4.4μsec	5μsec	5.3μsec	5.6μsec	5.9μsec
n	10μsec	20μsec	30μsec	40μsec	50μsec	60μsec
n <sup>2</sup>	100μsec	400μsec	900μsec	1.5msec	2.5msec	3.6msec
n <sup>5</sup>	0.1sec	3.2sec	24.3sec	1.7min	5.2min	13min
3 <sup>n</sup>	59msec	48min	6.5yrs	385,500yrs	2x10 <sup>8</sup> centuries...	
n!	3sec 7.8x10 <sup>8</sup> millennia .....					

**Non polynomial algorithms are terrible!**  
**Logs are great!**

# Analysis of Algorithms

- Algorithms don't have constant run time for a given input size
  - Run time depends on nature of input
  - Best-Case, Average Case, Worst Case
  - Typically care about worst case (other cases useful in practice)
- Example: Insertion Sort(a[0:n-1]):

```
for (i=1; i < n; i ++){  
    key = a[i]; j = i-1;  
    while (j >= 0 && a[j] > key) {  
        a[j + 1] = a[j];  
        j = j - 1;  
    }  
    a[j + 1] = key;  
}
```

# OUTER LOOP TRACE FOR INSERTION SORT:

■	a[0]	a[1]	a[2]	a[3]	a[4]	a[5]	a[6]	a[7]	(Swaps)
■	6	5	2	8	3	4	7	1	(1)
	5	←	→ 6						
■	5	6	2	8	3	4	7	1	(2)
		2	←	→ 6					
	2	←	→ 5						
■	2	5	6	8	3	4	7	1	(0)
■	2	5	6	8	3	4	7	1	(3)
■	2	3	5	6	8	4	7	1	(3)
■	2	3	4	5	6	8	7	1	(1)
■	2	3	4	5	6	7	8	1	(7)
■	1	2	3	4	5	6	7	8	(17 total swaps)

# Analysis of Algorithms

- Example: Insertion Sort(a[0:n-1]):

```
for (i=1; i < n; i ++){  
    key = a[i]; j = i-1;  
    while (j >= 0 && a[j] > key) {  
        a[j + 1] = a[j];  
        j = j - 1;  
    }  
    a[j + 1] = key;  
}
```

- Analysis:

- Best case: input is sorted, so while loop ends after 2 ops:  $\Theta(n)$
- Average case: while loop goes over 1/2 of list to find insert
- Worst case: input is sorted in reverse, so while loop ends at  $j = -1$ .

```
for ( i = 0; i < N; i++)  
    for(j = i; j < N; j++){  
        Sum = 0;  
        for(k=i; k<j+1; k++)  
            Sum += a[k];  
        if(Sum > MaxSum)  
            MaxSum = Sum;  
    }  
}
```

```
for ( i = 0; i < N; i++){  
    Sum = 0;  
    for(j=i; j<N; j++){  
        Sum += a[j];  
        if(Sum > MaxSum)  
            MaxSum = Sum;  
    }  
}
```

# Different Algorithm

```
MergeSort(int *array, int l, int r):  
    if(l < r) {  
        int m = l+(r-l)/2;  
        mergeSort(array, l, m);  
        mergeSort(array, m+1, r);  
        merge(array, l, m, r);  
    }
```

Recursive equation algorithm:

$T(n)$ : run time for a list of size  $n$ .  $m(n)$ : time to merge arrays of length  $n$

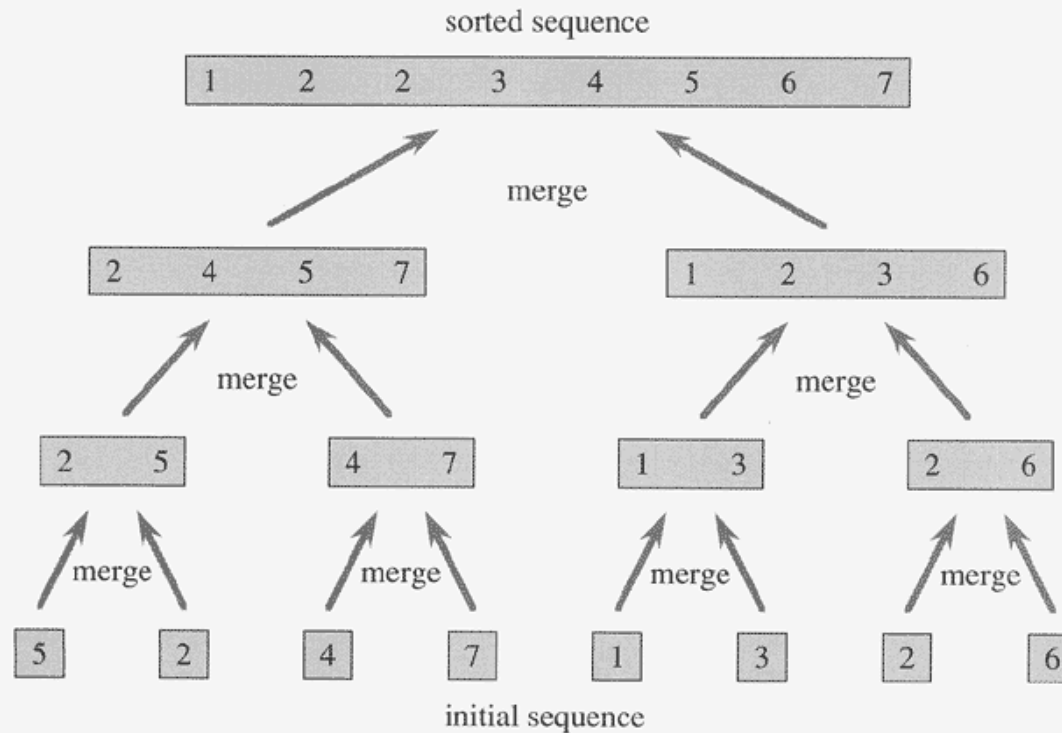
$$T(n) = 2T\left(\frac{n}{2}\right) + m(n)$$

# Merge Algorithm

```
void merge(int *array, int l, int m, int r) {
    int i, j, k, nl, nr;
    nl = m-l+1; nr = r-m;
    int larr[nl], rarr[nr];
    for(i = 0; i<nl; i++)
        larr[i] = array[l+i];
    for(j = 0; j<nr; j++)
        rarr[j] = array[m+1+j];
    i = 0; j = 0; k = l;
    //merge temp arrays to real array
    while(i < nl && j<nr) {
        if(larr[i] <= rarr[j]) {
            array[k] = larr[i];
            i++;
        }else{
            array[k] = rarr[j];
            j++;
        }
        k++;
    }
}
```

```
while(i<nl) {    //extra element in left array
    array[k] = larr[i];
    i++; k++;
}
while(j<nr) {    //extra element in right array
    array[k] = rarr[j];
    j++; k++;
}
}
```

# Mergesort Illustration



**Figure 2.4** The operation of merge sort on the array  $A = \langle 5, 2, 4, 7, 1, 3, 2, 6 \rangle$ . The lengths of the sorted sequences being merged increase as the algorithm progresses from bottom to top.



MASTER EQUATION:  $T(n) = aT\left(\frac{n}{b}\right) + f(n)$

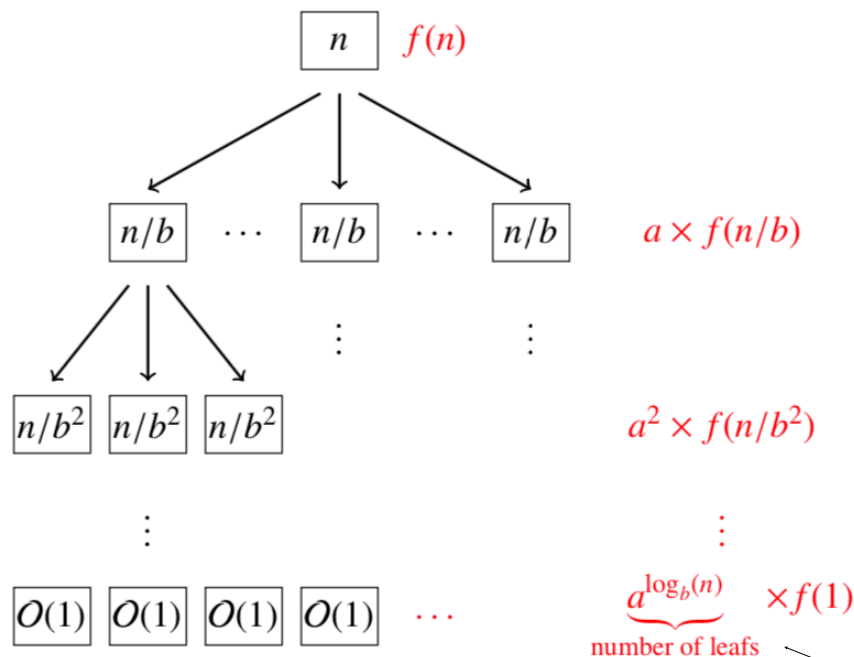
Theorem: The asymptotic Solution is:

- Define  $\gamma = \log_b(a) \rightarrow a = b^\gamma$
- Then, there are three cases
  1.  $T(n) \in \Theta(n^\gamma)$  if  $f(n) \in O(n^{\gamma-\epsilon})$  for some  $\epsilon > 0$
  2.  $T(n) \in \Theta(f(n))$  if  $f(n) \in \Omega(n^{\gamma+\epsilon})$  for some  $\epsilon > 0$
  3.  $T(n) \in \Theta(n^\gamma \log(n))$  if  $f(n) \in \Theta(n^\gamma)$

# BUILD TREE TO SOLVE

$$T(n) = aT(n/b) + f(n)$$

$$n/b^h = 1 \implies h = \log_b(n)$$



Height

$$\lim \frac{a^k f(n/b^k)}{n^\gamma} = ???$$

Breadth

$$T(n) = f(n) + af(n/b) + \dots + a^{\log_b(n)-1} f(b^2) + a^h T(1)$$

LET'S ANALYZE FOR  $n = b^h, f(n) \in O(n^k)$ , so  $f(n) = cn^k$

$$T(n) = f(n) + af(n/b) + \dots + a^{\log_b(n)-1} f(b^2) + a^h T(1)$$

$$\begin{aligned} T(n) &= cn^k + ac(n/b)^k + a^2c(n/b^2)^k + \dots + a^{h-1}c(b^2)^k + a^h T(1) \\ &= cn^k + \left(\frac{a}{b^k}\right)cn^k + \left(\frac{a}{b^k}\right)^2cn^k + \dots + \left(\frac{a}{b^k}\right)^{h-1}cn^k + a^h T(1) \end{aligned}$$

Note:  $a^h = n^\gamma$

If  $k < \gamma$ , then  $b^k < a$ . Case 1

If  $k > \gamma$ , then  $b^k > a$ . Case 2

If  $k = \gamma$ , then  $b^k = a$ . Case 3

## Back to Mergesort

$$T(n) = 2T\left(\frac{n}{2}\right) + m(n)$$

$$m(n) \in \Theta(n)$$

Therefore,  $a = 2$ ,  $b = 2$ ,  $\gamma = 1 \Rightarrow T(n) \in \Theta(n \log(n))$

Worst case for mergesort:

Average case for mergesort:

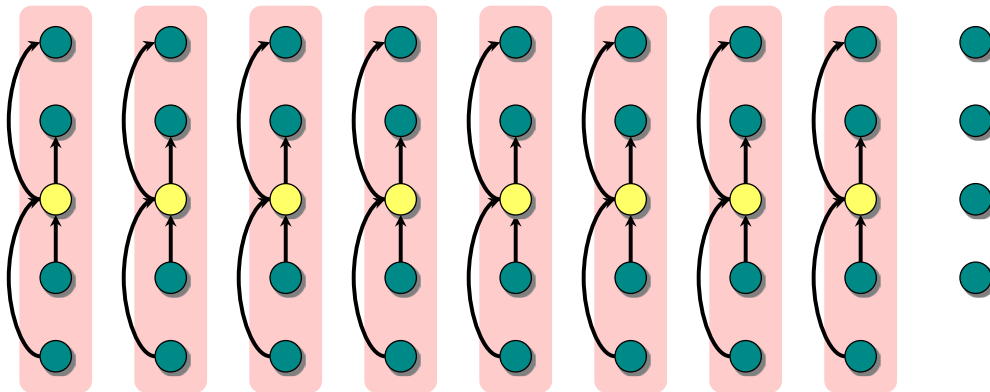
Best case for mergesort:

# Order Statistics

- Select the  $i$ -th smallest of  $n$  elements (the element with rank  $i$ ).
  - $i = 1$ : minimum;
  - $i = n$ : maximum;
  - $i = \lfloor (n+1)/2 \rfloor$  or  $\lceil (n+1)/2 \rceil$ : median.
- Naive algorithm: Sort and index  $i$ th element.
- Worst-case running time =  $\Theta(n \lg n) + \Theta(1) = \Theta(n \lg n)$ ,
  - using merge sort or Timsort or ...
- Can one do better?

# Order Statistics

- SELECT( $i, n$ )
  - Divide the  $n$  elements into groups of 5. Find the median of each 5-element group by rote.
  - Recursively SELECT the median  $x$  of the  $\lfloor n/5 \rfloor$  group medians to be the pivot.
  - Partition around the pivot  $x$ . Let  $k = \text{rank}(x)$ .
  - if  $i=k$  then return  $x$  else if  $i < k$ 
    - recursively SELECT the  $i$ -th smallest element in the lower part
  - else recursively SELECT the  $(i-k)$  th smallest element in the upper part



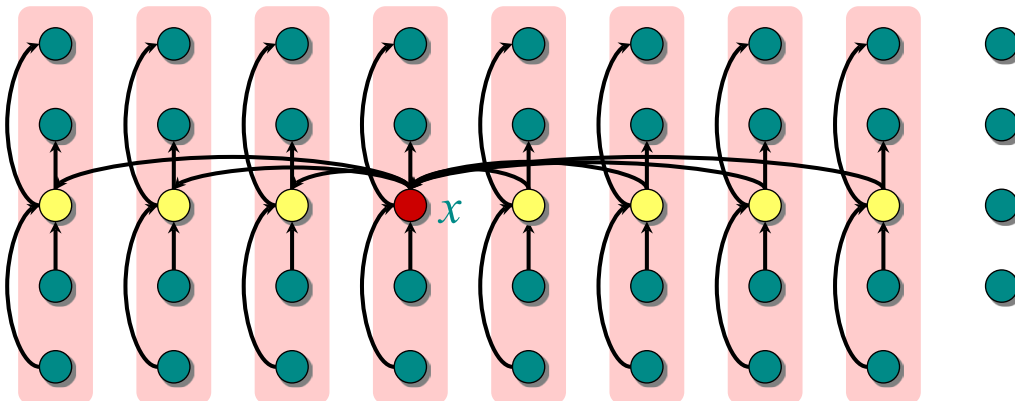
- At least half the group medians are  $\leq x$ , which is at least  $\lfloor \lfloor n/5 \rfloor / 2 \rfloor = \lfloor n/10 \rfloor$  group medians. Therefore, at least  $3 \lfloor n/10 \rfloor$  elements are  $\leq x$ .

- Similarly, at least  $3 \lfloor n/10 \rfloor$  elements are  $\geq x$ .

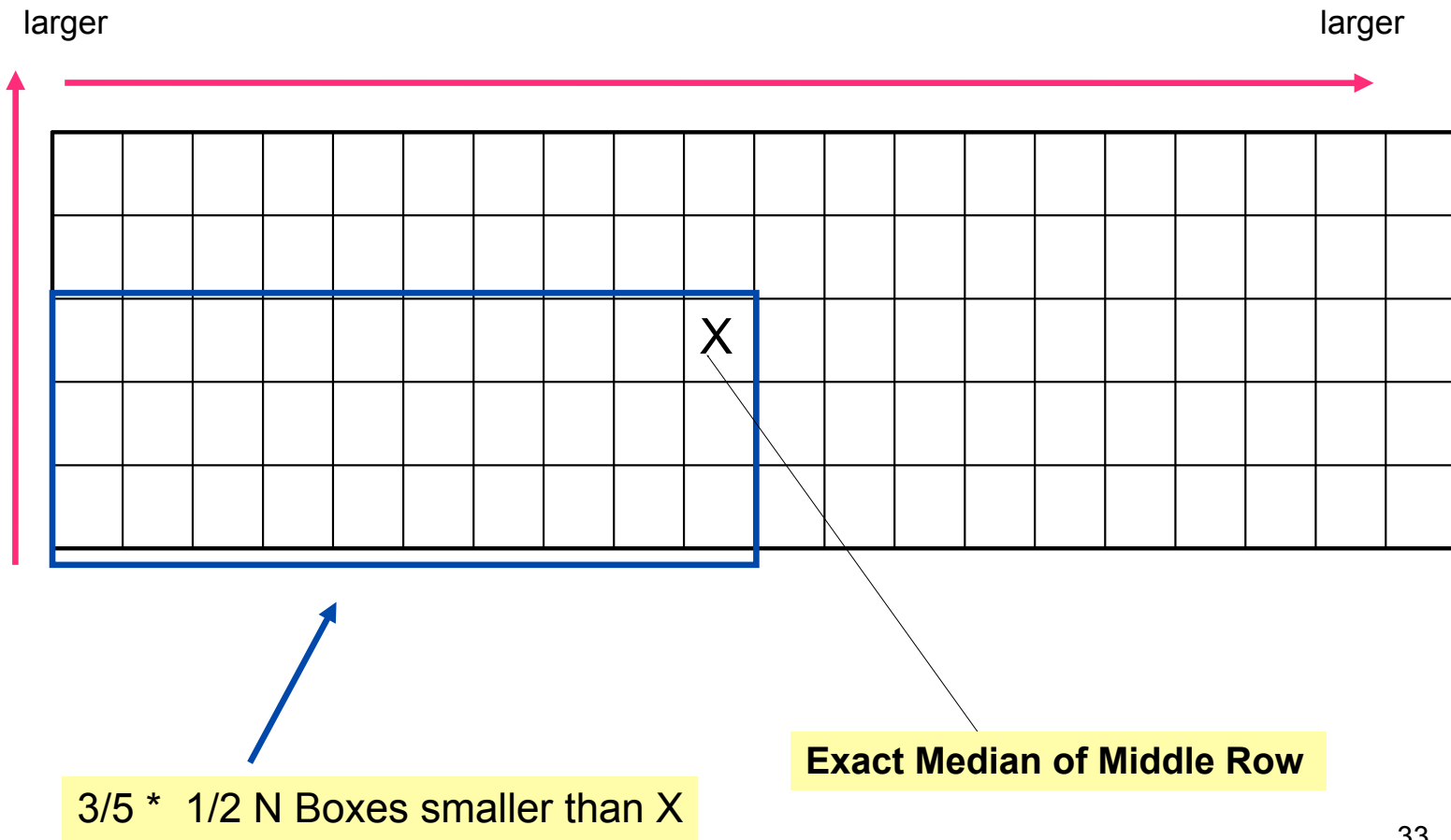
- Recursion:  

$$T(n) \leq T(n/5) + T(7n/10) + cn$$

- Result:  $T(n) \in \Theta(n)$



## 5 row of N/5 Columns





## Generalization of Master's Equation

Let  $\alpha_1, \alpha_2, \dots, \alpha_k > 0$  be such that  $\sum_{j=1}^k \alpha_j < 1$ . Then,

If  $T(n) = T(\alpha_1 n) + T(\alpha_2 n) + \dots + T(\alpha_k n) + cn$ , then  $T(n) \in \Theta(n)$

## Other useful recursive solutions

$T(n) = aT(n - 1) + bT(n - 2)$  (Discrete difference equation, constant coefficient)

Can solve via z-transforms (if you know EC 401..) or follow method below:

Solution form:  $k^n$

Characteristic equation: Substitute into equation to get

$$k^n = ak^{n-1} + k^{n-2} \Rightarrow k^2 - ak - b = 0$$

Two solutions  $k_1, k_2$  (or a repeated root).

If  $k_1 \neq k_2$  then  $T(n) = Ak_1^n + Bk_2^n$ . Otherwise,  $T(n) = Ak_1^n + Bnk_1^n$ .

## Example: Fibonacci numbers

$$F(n) = F(n - 1) + F(n - 2)$$

Characteristic equation:

Solutions:

Initial condition:  $F(0) = 0$ ;  $F(1) = 1$

.

# Simple Data Structures: Abstract Data Type (ADT)

- In Object Oriented Programming data and the operations that manipulate that data are grouped together in classes
- Abstract Data Types (ADTs) or data structures or collections store data and allow various operations on the data to access and change it
- High level languages like C++, Java, Python often provide implementations of ADTs

# The List ADT

- List of size  $N$ :  $A_0, A_1, \dots, A_{N-1}$
- Each element  $A_k$  has a unique position in the list
- Elements can be arbitrarily complex
- Operations
  - Depend on what the list is for
- Implementation: either as arrays or as linked lists

# Sample List (C++) ADT

```
class List {
public:
    List();                // constructor
    List(const List& list); // copy constructor
    ~List();               // destructor
    List& operator=(const List& list); // assignment operator

    bool empty() const;    // boolean function
    void addHead(double x); // add to the head
    double deleteHead();   // delete, get head

    void addEnd(double x); // add to the end
    double deleteEnd();    // delete, get end

    bool findNode(double x); // search for a given x
    void deleteNode(double x); // delete node with value x

    int length() const;    // count the number of
    elements

};
```

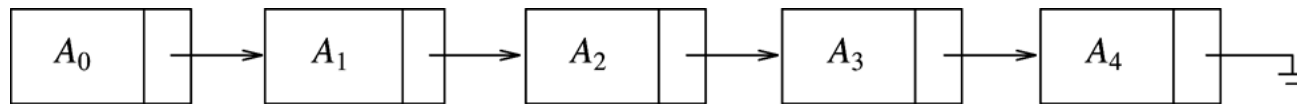
# Lists Using Arrays

## ○ Operations

- addHead(X) –  $O(N)$
- deleteHead() –  $O(N)$
- addEnd(X) –  $O(1)$
- deleteEnd() –  $O(1)$
- findNode(X) –  $O(N)$

# Linked Lists

- Elements not stored in contiguous memory
- Nodes in list consist of data element and next pointer





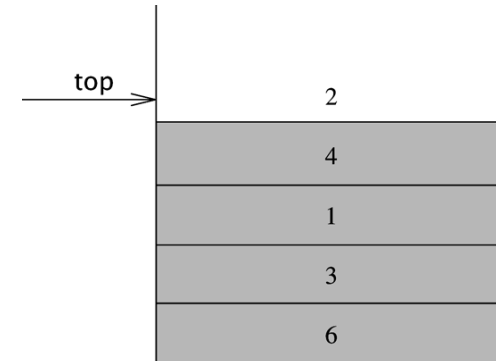
# Lists Using Linked Lists

- Operations



- $\text{addHead}(X) - O(1)$
  - $\text{deleteHead}() - O(N)$
  - $\text{addEnd}(X) - O(N)$
  - $\text{deleteEnd}() - O(N)$
  - $\text{findNode}(X) - O(N)$
- Can modify using doubly-linked lists, pointers to end
  - Make  $\text{addEnd}(X)$ ,  $\text{deleteEnd}$   $O(1)$ .

# List Applications: Stacks

- Stack is a list where insert and remove take place only at the “top”
- Operations
  - Push (insert) element on top of stack
  - Pop (remove) element from top of stack
  - Top: return element at top of stack
- LIFO (Last In First Out) queue
- Stack is a list, any list implementation will do, but will have different advantages



## Stack ADT

```
class Stack {  
    public:  
        Stack(); // constructor  
        Stack(const Stack& stack); // copy constructor  
        ~Stack(); // destructor  
  
        bool empty() const;   
        void push(const double x);  
        double pop(); // change the stack   
  
        double top() const; // keep the stack unchanged  
  
    private:  
};
```

# Stack using linked lists

```
struct Node{  
    public:  
        double data;  
        Node* next;  
};
```

```
class Stack {  
    public:  
        Stack(); // constructor  
        Stack(const Stack& stack); // copy constructor  
        ~Stack(); // destructor  
  
        bool empty() const;  
        void push(const double x);  
        double pop(); // change the stack  
  
        bool full(); // unnecessary for linked lists  
        double top() const; // keep the stack unchanged  
        void print() const;  
  
    private:  
        Node* top;  
};
```

## Stack using arrays

```
class Stack {  
public:  
    Stack(int size = 10);           //  
    constructor  
    ~Stack() { delete [] values; }  // destructor  
  
    bool empty() { return top == -1; }  
    void push(const double x);  
    double pop();  
  
    bool full() { return top == maxTop; }  
    double top();  
    void print();  
private:  
    int maxTop;           // max stack size = size - 1  
    int top;              // current top of stack  
    double* values;       // element array
```

## Array versus Linked List Implementation

- push, pop, top are all  $O(1)$  constant-time operations in both array and linked list implementation
  - For array implementation, the operations are performed in very fast constant time
- Linked List structures are larger - need pointers
- Array allocate space contiguously - useful for cache, etc.
- Arrays may have to be resized (lots of data movement...) but ***amortized analysis*** says worst case is still  $O(1)$ !

## Stack Application: Balancing Symbols

- To check that every right brace, bracket, and parentheses must correspond to its left counterpart (e.g. MATLAB, code syntax checkers, ...)
  - e.g. [( )] is legal, but [( ] ) is illegal
- Algorithm
  - (1) Make an empty stack.
  - (2) Read characters until end of file
    - i. If the character is opening symbol, push onto the stack
    - ii. If closing symbol and stack is empty, error
    - iii. Otherwise, pop stack. If symbol popped is not corresponding opening symbol, error
  - (3) At end of file, if stack is not empty, error
- Other applications
  - Function calls, recursion, ...
  - Back/Forward stacks on browsers
  - Undo/Redo stacks in Excel or Word

# Queue

- Queue is a list where insert takes place at back, but remove takes place at the front
- Operations
  - Enqueue (insert) element at the back of the queue
  - Dequeue (remove and return) element from the front of the queue
- FIFO (First In First Out)
- Applications: simple job scheduling, graph traversals, priority queues, routing, printer queues, I/O streams



## Implementation of Queue

- Just as stacks can be implemented as arrays or linked lists, so with queues.
- Need to have fast access to beginning and end of queues
  - Dequeue at front
  - Enqueue at back
- Similar advantages for arrays vs linked lists
  - But there are different ways to do it with arrays which can result in much data movement,  $O(n)$  computation!

## Array implementation of Queue

- Naive: front is always position 0, back is variable.
  - Dequeue is  $O(n)$ ! Must move positions
- Better way: Use circular array
  - When an element moves past the end of a circular array, it wraps around to the beginning, e.g. size 9, top 5, bottom 8
  - Enqueue(4); 000007963  $\rightarrow$  400007963 (top 5, bottom 0)
  - Detect an empty or full queue: Use a counter of the number of elements in the queue.
  - $O(1)$
  - Only issue is fixed size... reallocate if full. Amortized cost  $O(1)$ .