

Math40003 Linear Algebra and Groups**Problem Sheet 2**

1. *You should now be able to do questions 2 and 6 on PS1*
2. Describe the solution sets to the following sets of simultaneous equations in \mathbb{R}^2 :

$$\begin{array}{lll} \text{(a)} \quad \begin{array}{rcl} x + 2y & = & 3 \\ -4x + \frac{1}{2}y & = & 5 \end{array} & \text{(b)} \quad x + 2y = 3 & \text{(c)} \quad \begin{array}{rcl} x + 2y & = & 3 \\ -4x + \frac{1}{2}y & = & 5 \\ x + 4y & = & 6 \end{array} \end{array}$$

3. Describe the solution sets to the following sets of simultaneous equations in \mathbb{R}^3 :

$$\begin{array}{lll} \text{(a)} \quad \begin{array}{rcl} x + 2y & = & 3 \\ -4x + \frac{1}{2}y - 2z & = & 5 \end{array} & \text{(b)} \quad x + 2y = 3 & \text{(c)} \quad \begin{array}{rcl} x + 2y & = & 3 \\ -4x + \frac{1}{2}y - 2z & = & 5 \\ x + 4y + z & = & 6 \end{array} \end{array}$$

- 4.* For which $a, b \in \mathbb{R}$ does the system of equations

$$\begin{array}{rcl} x_1 + x_2 + x_3 & = & -1 \\ 2x_1 + x_2 + ax_3 & = & 1 \\ 3x_1 + x_2 + x_3 & = & b \end{array}$$

have (i) no solutions, (ii) exactly one solution, (iii) infinitely many solutions?

What about the system $x_1 + x_2 + x_3 + x_4 = 0$

$$\begin{array}{rcl} x_1 - x_2 + ax_3 + x_4 & = & 1 \\ 2x_1 + ax_2 + x_3 + 2x_4 & = & b ? \end{array}$$

5. Which of the following are possible, find examples if possible:
 - (a) Two simultaneous equations in two unknowns which defines a line in \mathbb{R}^2 .
 - (b) Two simultaneous equations in two unknowns which defines the empty set in \mathbb{R}^2 .
 - (c) One equation in no unknowns which defines the empty set.
 - (d) Two simultaneous equations in three unknowns which defines a point in \mathbb{R}^3 .
6. (a) Let M_θ be the reflection in the line $L_\theta = \{(x_1, x_2) \in \mathbb{R}^2 \mid x_2 = x_1 \tan \theta\}$. Using any school geometry or trigonometry you like, show that the matrix representing M_θ is

$$\begin{pmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & -\cos 2\theta \end{pmatrix}.$$

- (b) Let R_α be a rotation about the origin, and let M_β be the reflection in a line through the origin. Prove that $M_\beta R_\alpha$ is a reflection.
- (c) Let M_α and M_β be reflections in straight lines through the origin. Prove that $M_\alpha M_\beta$ is a rotation.