## Homework 1: 3d Gravity as a Chern-Simons Theory

## 2.2 Global Symmetries of 3d Einstein Manifolds

We define the coordinates on Minkowski space.

$$\begin{aligned} &\text{coordM} = \{ \mathbf{x0}, \, \mathbf{x1}, \, \mathbf{x2}, \, \mathbf{x3} \} \\ &\eta = \{ \{ -1, \, 0, \, 0, \, 0 \}, \, \{ 0, \, 1, \, 0, \, 0 \}, \, \{ 0, \, 0, \, 1, \, 0 \}, \, \{ 0, \, 0, \, 0, \, 1 \} \} \end{aligned}$$
 
$$\begin{aligned} &\text{out}[7] = & \left\{ \mathbf{x0}, \, \sqrt{\mathbf{x0}^2 - \alpha} \, \, \mathsf{Cos} \, [\phi] \, \mathsf{Sin} \, [\theta] \, , \, \sqrt{\mathbf{x0}^2 - \alpha} \, \, \mathsf{Sin} \, [\theta] \, \mathsf{Sin} \, [\phi] \, , \, \sqrt{\mathbf{x0}^2 - \alpha} \, \, \mathsf{Cos} \, [\theta] \, \right\} \end{aligned}$$
 
$$\end{aligned}$$
 
$$\begin{aligned} &\text{Out}[8] = & \left\{ \{ -1, \, 0, \, 0, \, 0 \}, \, \{ 0, \, 1, \, 0, \, 0 \}, \, \{ 0, \, 0, \, 1, \, 0 \}, \, \{ 0, \, 0, \, 0, \, 1 \} \right\}$$

We then take the coordinates on N with

In[2]:= 
$$coordN = \{x0, \theta, \phi\}$$
Out[2]=  $\{x0, \theta, \phi\}$ 

We now stablish the relations between them

In[3]:= 
$$x1 = \sqrt{x0^2 - \alpha}$$
 Sin[ $\theta$ ] Cos[ $\phi$ ]
$$x2 = \sqrt{x0^2 - \alpha}$$
 Sin[ $\theta$ ] Sin[ $\phi$ ]
$$x3 = \sqrt{x0^2 - \alpha}$$
 Cos[ $\theta$ ]

Out[3]:=  $\sqrt{x0^2 - \alpha}$  Cos[ $\phi$ ] Sin[ $\theta$ ]

Out[4]:=  $\sqrt{x0^2 - \alpha}$  Sin[ $\theta$ ] Sin[ $\phi$ ]

Out[5]:=  $\sqrt{x0^2 - \alpha}$  Cos[ $\theta$ ]

We compute the Jacobian matrix

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In[14]:=

Out[15]//MatrixForm=

$$\begin{pmatrix} \mathbf{1} & \mathbf{0} & \mathbf{0} \\ \frac{\mathsf{x0} \, \mathsf{Cos}\, [\phi] \, \mathsf{Sin}\, [\theta]}{\sqrt{\mathsf{x0}^2 - \alpha}} & \sqrt{\mathsf{x0}^2 - \alpha} & \mathsf{Cos}\, [\theta] \, \mathsf{Cos}\, [\phi] & -\sqrt{\mathsf{x0}^2 - \alpha} & \mathsf{Sin}\, [\theta] \, \mathsf{Sin}\, [\phi] \\ \frac{\mathsf{x0} \, \mathsf{Sin}\, [\theta] \, \mathsf{Sin}\, [\phi]}{\sqrt{\mathsf{x0}^2 - \alpha}} & \sqrt{\mathsf{x0}^2 - \alpha} & \mathsf{Cos}\, [\theta] \, \mathsf{Sin}\, [\phi] & \sqrt{\mathsf{x0}^2 - \alpha} & \mathsf{Cos}\, [\phi] \, \mathsf{Sin}\, [\theta] \\ \frac{\mathsf{x0} \, \mathsf{Cos}\, [\theta]}{\sqrt{\mathsf{x0}^2 - \alpha}} & -\sqrt{\mathsf{x0}^2 - \alpha} & \mathsf{Sin}\, [\theta] & \mathbf{0} \\ \end{pmatrix}$$

Finally, we compute the induced metric

In[16]:=

gamma =  $J^T$ . $\eta$ .J // Simplify; gamma // MatrixForm

Out[17]//MatrixForm=

$$\begin{pmatrix}
\frac{\alpha}{x\theta^2 - \alpha} & 0 & 0 \\
0 & x\theta^2 - \alpha & 0 \\
0 & 0 & (x\theta^2 - \alpha) \sin[\theta]^2
\end{pmatrix}$$