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Gravitational Physics

## Homework 1

### 1. Cartan's Formalism: FRW cosmology

a) By inspection we see a possible choice is

$$\omega^{\hat{t}} = dt, \quad \omega^{\hat{r}} = \frac{a(t)}{\sqrt{1-kr^2}} dr, \quad \omega^{\hat{\theta}} = a(t)r d\theta,$$

$$\omega^{\hat{\phi}} = a(t)r \sin(\theta) d\phi.$$

b) Computing the exterior derivatives yields

$$d\omega^{\hat{t}} = 0,$$

$$d\omega^{\hat{r}} = \frac{a'(t)}{\sqrt{1-kr^2}} dt \wedge dr = \frac{a'(t)}{a(t)} \omega^{\hat{t}} \wedge \omega^{\hat{r}}$$

$$d\omega^{\hat{\theta}} = a'(t)r dt \wedge d\theta + a(t) dr \wedge d\theta$$

$$= \frac{a'(t)}{a(t)} \omega^{\hat{t}} \wedge \omega^{\hat{\theta}} + \frac{\sqrt{1-kr^2}}{ra(t)} \omega^{\hat{r}} \wedge \omega^{\hat{\theta}}$$

$$d\omega^{\hat{\phi}} = a'(t)r \sin(\theta) dt \wedge d\phi + a(t) \sin(\theta) dr \wedge d\phi + a(t)r \cos(\theta) d\theta \wedge d\phi$$

$$= \frac{a'(t)}{a(t)} \omega^{\hat{t}} \wedge \omega^{\hat{\phi}} + \frac{\sqrt{1-kr^2}}{ra(t)} \omega^{\hat{r}} \wedge \omega^{\hat{\phi}} + \frac{1}{ra(t)} \cot(\theta) \omega^{\hat{\theta}} \wedge \omega^{\hat{\phi}}$$

(2)

From these we obtain the connection one-forms

$$\theta^{\hat{t}}_{\hat{t}} = \frac{a'(t)}{a(t)} \omega^{\hat{t}} = -\theta^{\hat{t}}_{\hat{r}} = \theta^{\hat{r}}_{\hat{t}} = \theta^{\hat{t}}_{\hat{\phi}}, \quad \hat{t} \in \{\hat{r}, \hat{\theta}, \hat{\phi}\}$$

$$\theta^{\hat{t}}_{\hat{r}} = \frac{\sqrt{1-kr^2}}{ra(t)} \omega^{\hat{r}} = -\theta^{\hat{r}}_{\hat{t}} = \theta^{\hat{r}}_{\hat{\phi}} = -\theta^{\hat{\phi}}_{\hat{r}}, \quad \hat{t} \in \{\hat{\theta}, \hat{\phi}\}$$

$$\theta^{\hat{\phi}}_{\hat{\theta}} = \frac{1}{ra(t)} \cot(\theta) \omega^{\hat{\theta}} = -\theta^{\hat{\theta}}_{\hat{\phi}} = \theta^{\hat{\theta}}_{\hat{\phi}} = -\theta^{\hat{\theta}}_{\hat{\phi}}.$$

All other connection one-forms vanish.

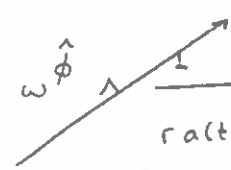
c) The curvature two-forms are given by

$$\begin{aligned} R^{\hat{t}}_{\hat{r}} &= d\theta^{\hat{t}}_{\hat{r}} + \theta^{\hat{t}}_{\hat{\theta}} \wedge \theta^{\hat{\theta}}_{\hat{r}} + \theta^{\hat{t}}_{\hat{\phi}} \wedge \theta^{\hat{\phi}}_{\hat{r}} \\ &= d\left(\frac{a'(t)}{\sqrt{1-kr^2}} dr\right) + \frac{a'(t)}{a(t)} \omega^{\hat{\theta}} \wedge \frac{\sqrt{1-kr^2}}{ra(t)} \omega^{\hat{\theta}} \\ &\quad + \frac{a'(t)}{a(t)} \omega^{\hat{\phi}} \wedge \frac{\sqrt{1-kr^2}}{ra(t)} \omega^{\hat{\phi}} \\ &= \frac{a''(t)}{\sqrt{1-kr^2}} dt \wedge dr = \frac{a''(t)}{a(t)} \omega^{\hat{t}} \wedge \omega^{\hat{r}} = R^{\hat{t}}_{\hat{r}} = -R^{\hat{r}}_{\hat{t}} = R^{\hat{r}}_{\hat{t}} \end{aligned}$$

$$R^{\hat{t}}_{\hat{\theta}} = d\theta^{\hat{t}}_{\hat{\theta}} + \theta^{\hat{t}}_{\hat{r}} \wedge \theta^{\hat{r}}_{\hat{\theta}} + \theta^{\hat{t}}_{\hat{\phi}} \wedge \theta^{\hat{\phi}}_{\hat{\theta}}$$

$$= d\left(a'(t)r d\theta\right) + \frac{a'(t)}{a(t)} \omega^{\hat{r}} \wedge \left(-\frac{\sqrt{1-kr^2}}{ra(t)}\right) \omega^{\hat{\theta}}$$

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$$+ \frac{a'(t)}{a(t)} \omega^{\hat{\phi}} \wedge \frac{1}{ra(t)} \cot(\theta) \omega^{\hat{\phi}}$$


$$= a''(t) r dt \wedge d\theta + a'(t) dr \wedge d\theta - \frac{a'(t) \sqrt{1-kr^2}}{ra(t)^2} \omega^{\hat{r}} \wedge \omega^{\hat{\theta}}$$

$$= \frac{a''(t)}{a(t)} \omega^{\hat{t}} \wedge \omega^{\hat{\theta}} = -R^{\hat{\theta}} \hat{t},$$

$$R^{\hat{t}} \hat{\phi} = d\theta^{\hat{t}} \hat{\phi} + \theta^{\hat{t}} \hat{r} \wedge \theta^{\hat{r}} \hat{\phi} + \theta^{\hat{t}} \hat{\theta} \wedge \theta^{\hat{\theta}} \hat{\phi}$$

$$= d\left(\frac{a'(t)}{a(t)} \omega^{\hat{\phi}}\right) + \frac{a'(t)}{a(t)} \omega^{\hat{r}} \wedge \left(-\frac{\sqrt{1-kr^2}}{ra(t)} \omega^{\hat{\phi}}\right)$$

$$+ \frac{a'(t)}{a(t)} \omega^{\hat{\theta}} \wedge \left(-\frac{1}{ra(t)} \cot(\theta)\right) \omega^{\hat{\phi}}$$

$$= d\left(a'(t) r \sin(\theta) d\phi\right) - \frac{a'(t) \sqrt{1-kr^2}}{ra(t)^2} \omega^{\hat{r}} \wedge \omega^{\hat{\phi}} - \frac{a'(t) \cot(\theta)}{ra(t)^2} \omega^{\hat{\theta}} \wedge \omega^{\hat{\phi}}$$

$$= a''(t) r \sin(\theta) dt \wedge d\phi + \cancel{a'(t) \sin(\theta) dr \wedge d\phi} + \cancel{a'(t) r \cos(\theta) d\theta \wedge d\phi}$$

$$- \frac{a'(t) \sqrt{1-kr^2}}{ra(t)^2} \cancel{a(t)} \cancel{dr} \wedge \cancel{a(t)} \cancel{\sin(\theta) d\phi}$$

$$- \frac{a'(t) \cot(\theta)}{ra(t)^2} \cancel{a(t) r d\theta} \wedge \cancel{a(t) \sin(\theta) d\phi} = \frac{a''(t)}{a(t)} \omega^{\hat{t}} \wedge \omega^{\hat{\phi}}$$

$$= -R^{\hat{\phi}} \hat{t},$$

$$R^{\hat{r}}_{\hat{\theta}} = d\theta^{\hat{r}}_{\hat{\theta}} + \theta^{\hat{r}}_{\hat{t}} \wedge \theta^{\hat{t}}_{\hat{\theta}} + \theta^{\hat{r}}_{\hat{\phi}} \wedge \theta^{\hat{\phi}}_{\hat{\theta}} \quad \propto \omega^{\hat{\phi}} \wedge \omega^{\hat{\phi}} = 0$$

$$= -d \left( \frac{\sqrt{1-Kr^2}}{a(t)} \right) d\theta + \frac{a'(t)}{a(t)} \omega^{\hat{r}} \wedge \frac{a'(t)}{a(t)} \omega^{\hat{\theta}}$$

$$= \frac{Kr}{\sqrt{1-Kr^2}} dr \wedge d\theta + \frac{a'(t)^2}{a(t)^2} \omega^{\hat{r}} \wedge \omega^{\hat{\theta}}$$

$$= \frac{K}{a(t)^2} \omega^{\hat{r}} \wedge \omega^{\hat{\theta}} + \frac{a'(t)^2}{a(t)^2} \omega^{\hat{r}} \wedge \omega^{\hat{\theta}} = \frac{a'(t)^2 + K}{a(t)^2} \omega^{\hat{r}} \wedge \omega^{\hat{\theta}}$$

$$= -R^{\hat{r}}_{\hat{\theta}} = R^{\hat{\theta}}_{\hat{r}} = -R^{\hat{\theta}}_{\hat{r}},$$

$$R^{\hat{r}}_{\hat{\phi}} = d\theta^{\hat{r}}_{\hat{\phi}} + \theta^{\hat{r}}_{\hat{t}} \wedge \theta^{\hat{t}}_{\hat{\phi}} + \theta^{\hat{r}}_{\hat{\theta}} \wedge \theta^{\hat{\theta}}_{\hat{\phi}}$$

$$= -d \left( \frac{\sqrt{1-Kr^2}}{a(t)} \sin(\theta) d\phi \right) + \frac{a'(t)}{a(t)} \omega^{\hat{r}} \wedge \frac{a'(t)}{a(t)} \omega^{\hat{\phi}}$$

$$- \frac{\sqrt{1-Kr^2}}{ra(t)} \omega^{\hat{\theta}} \wedge \left( -\frac{\cot(\theta)}{ra(t)} \omega^{\hat{\phi}} \right)$$

$$= \frac{Kr}{\sqrt{1-Kr^2}} \sin(\theta) dr \wedge d\phi - \sqrt{1-Kr^2} \cos(\theta) d\theta \wedge d\phi$$

$$+ \frac{a'(t)^2}{a(t)^2} \omega^{\hat{r}} \wedge \omega^{\hat{\phi}} + \frac{\sqrt{1-Kr^2} \cot(\theta)}{r^2 a(t)^2} a(t) r d\theta \wedge a(t) r \sin(\theta) d\phi$$

$$= \frac{K}{a(t)^2} \omega^{\hat{r}} \wedge \omega^{\hat{\phi}} + \frac{a'(t)^2}{a(t)^2} \omega^{\hat{r}} \wedge \omega^{\hat{\phi}} = \frac{a'(t)^2 + K}{a(t)^2} \omega^{\hat{r}} \wedge \omega^{\hat{\phi}} = -R^{\hat{\phi}}_{\hat{r}},$$

$$R^{\hat{\theta}}_{\hat{\phi}} = d\theta^{\hat{\theta}}_{\hat{\phi}} + \theta^{\hat{\theta}}_{\hat{t}} \wedge \theta^{\hat{t}}_{\hat{\phi}} + \theta^{\hat{\theta}}_{\hat{r}} \wedge \theta^{\hat{r}}_{\hat{\phi}}$$

$$= -d\left(\frac{1}{ra(t)} \cos(\theta) \omega^{\hat{\phi}}\right) + \frac{a'(t)^2}{a(t)^2} \omega^{\hat{\theta}} \wedge \omega^{\hat{\phi}}$$

$$= -\frac{\sqrt{1-kr^2}}{ra(t)} \omega^{\hat{\theta}} \wedge \frac{\sqrt{1-kr^2}}{ra(t)} \omega^{\hat{\phi}}$$

$$= -d\left(\cos(\theta) d\phi\right) + \frac{a'(t)^2}{a(t)^2} \omega^{\hat{\theta}} \wedge \omega^{\hat{\phi}} - \frac{1-kr^2}{r^2 a(t)^2} \omega^{\hat{\theta}} \wedge \omega^{\hat{\phi}}$$

$$= \sin(\theta) d\theta \wedge d\phi + \frac{r^2 a'(t)^2 - 1 + kr^2}{r^2 a(t)^2} \omega^{\hat{\theta}} \wedge \omega^{\hat{\phi}}$$

$$= \frac{1}{r^2 a(t)^2} \omega^{\hat{\theta}} \wedge \omega^{\hat{\phi}} + \frac{r^2 (a'(t)^2 + k) - 1}{r^2 a(t)^2} \omega^{\hat{\theta}} \wedge \omega^{\hat{\phi}}$$

$$= \frac{a'(t)^2 + k}{a(t)^2} \omega^{\hat{\theta}} \wedge \omega^{\hat{\phi}} = -R^{\hat{\phi}}_{\hat{\theta}}$$

All other curvature two-forms vanish.

d) Let us first recover the Riemann tensor components in our orthonormal basis. Comparing with

$$R^{\hat{a}}_{\hat{b}} = \frac{1}{2} R^{\hat{a}}_{\hat{b}\hat{c}\hat{d}} \omega^{\hat{c}} \wedge \omega^{\hat{d}},$$

we obtain

$$R^{\hat{t}}_{\hat{r}\hat{t}\hat{r}} = \frac{a''(t)}{a(t)} = R^{\hat{t}}_{\hat{\theta}\hat{t}\hat{\theta}} = R^{\hat{t}}_{\hat{\phi}\hat{t}\hat{\phi}},$$

$$R^{\hat{r}}_{\hat{\theta}\hat{r}\hat{\theta}} = \frac{a'(t)^2 + \kappa}{a(t)^2} = R^{\hat{r}}_{\hat{\phi}\hat{r}\hat{\phi}} = R^{\hat{\theta}}_{\hat{\phi}\hat{\theta}\hat{\phi}}.$$

All other components unrelated by symmetries of the Riemann tensor vanish.

To relate this to our coordinate basis we use (2.25)

$$R^{\alpha}_{\beta\gamma\delta} = e_{\hat{a}}^{\alpha} \omega^{\hat{b}}_{\beta} \omega^{\hat{c}}_{\gamma} \omega^{\hat{d}}_{\delta} R^{\hat{a}}_{\hat{b}\hat{c}\hat{d}}.$$

We notice that our one-forms are "diagonal", in the sense that  $\omega^{\hat{i}}_i \propto \delta^{\hat{i}}_i$  with  $i \in \{t, r, \theta, \phi\}$ . Thus, so are their dual vectors. In particular

$$e^{\hat{t}} = \frac{\partial}{\partial t}, \quad e^{\hat{r}} = \frac{\sqrt{1-\kappa r^2}}{a(t)} \frac{\partial}{\partial r}, \quad e^{\hat{\theta}} = \frac{1}{ra(t)} \frac{\partial}{\partial \theta}$$

We thus conclude

$$R^{\hat{t}}_{rtr} = \frac{a(t)^2}{1-\kappa r^2} R^{\hat{t}}_{\hat{r}\hat{t}\hat{r}} = \frac{a(t)a''(t)}{1-\kappa r^2},$$

$$R^{\hat{t}}_{\theta t \theta} = a(t)^2 r^2 R^{\hat{t}}_{\hat{\theta}\hat{t}\hat{\theta}} = r^2 a(t) a''(t),$$

$$R^{\hat{t}}_{\phi t \phi} = a(t)^2 r^2 \sin^2(\theta) R^{\hat{t}}_{\hat{\phi}\hat{t}\hat{\phi}} = r^2 \sin^2(\theta) a(t) a''(t),$$

$$R^{\hat{r}}_{\theta r \theta} = a(t)^2 r^2 R^{\hat{r}}_{\hat{\theta}\hat{r}\hat{\theta}} = r^2 (a'(t)^2 + \kappa),$$

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$$R^r_{\phi r \phi} = a(t)^2 r^2 \sin(\theta)^2 R^{\hat{r}}_{\hat{\phi} \hat{r} \hat{\phi}} = r^2 \sin(\theta)^2 (a'(t)^2 + \kappa),$$

$$R^{\theta}_{\phi \theta \phi} = a(t)^2 r^2 \sin(\theta)^2 R^{\hat{\theta}}_{\hat{\phi} \hat{\theta} \hat{\phi}} = r^2 \sin(\theta)^2 (a'(t)^2 + \kappa),$$

All other components unrelated by symmetries vanish.

We see these components agree with those presented in the Mathematica computation.

We proceed to compute the components of the

Ricci tensor

$$\rightarrow g^{rr} R_{rttr} = g^{rr} R_{trtr} = g^{rr} g_{tt} R^t_{trt}$$

$$R_{tt} = R^r_{trt} + R^{\theta}_{t\theta t} + R^{\phi}_{t\phi t}$$

$$= -\frac{1}{a(t)^2} \frac{a(t)a''(t)}{1-\kappa r^2} - \frac{1}{a(t)^2} a(t)a''(t) - \frac{1}{a(t)^2 \sin^2(\theta)} \sin^2(\theta) a(t)a''(t)$$

$$= -3 \frac{a''(t)}{a(t)},$$

$$\rightarrow g^{\theta\theta} R_{\theta r \theta r} = g^{\theta\theta} R_{r \theta r \theta} = g^{\theta\theta} g_{rr} R^r_{\theta r \theta}$$

$$R_{rr} = R^t_{rtr} + R^{\theta}_{r\theta r} + R^{\phi}_{r\phi r}$$

$$= \frac{a(t)a''(t)}{1-\kappa r^2} + \frac{1}{a(t)^2} \frac{a(t)^2}{1-\kappa r^2} (a'(t)^2 + \kappa)$$

$$+ \frac{1}{a(t)^2 \sin^2(\theta)} \frac{a(t)^2}{1-\kappa r^2} \sin^2(\theta) (a'(t)^2 + \kappa)$$

$$= \frac{a(t)a''(t) + 2(a'(t)^2 + \kappa)}{1-\kappa r^2},$$

$$R'_{\theta\theta} = R^t_{\theta t\theta} + R^r_{\theta r\theta} + R^\phi_{\theta\phi\theta} \quad r' g^{\phi\phi} g_{\theta\theta} R^\theta_{\phi\theta\phi}$$

$$= r^2 a(t) a''(t) + r^2 (a'(t)^2 + k) + \frac{1}{\cancel{a(t)^2 \sin^2(\theta)^2}} \cancel{a(t)^2 r^2 \sin^2(\theta)^2} (a'(t)^2 + k)$$

$$= r^2 \left( a(t) a''(t) + 2(a'(t)^2 + k) \right),$$

$$R_{\phi\phi} = R^t_{\phi t\phi} + R^r_{\phi r\phi} + R^\theta_{\phi\theta\phi}$$

$$= r^2 \sin(\theta)^2 a(t) a''(t) + 2r^2 \sin(\theta)^2 (a'(t)^2 + k)$$

$$= r^2 \sin(\theta)^2 \left( a(t) a''(t) + 2(a'(t)^2 + k) \right).$$

We verify these again coincide with our Mathematica computation.

## 2. Explicit and Hidden Symmetries

a) The first equivalence is trivial. Namely,

$$0 = \nabla_{(\alpha} K_{\beta)} = \frac{1}{2} (\nabla_\alpha K_\beta + \nabla_\beta K_\alpha)$$

implies that  $\nabla_\alpha K_\beta = -\nabla_\beta K_\alpha$ , i.e.

$$\nabla_{[\alpha} K_{\beta]} = \frac{1}{2} (\nabla_\alpha K_\beta - \nabla_\beta K_\alpha) = \frac{1}{2} (\nabla_\alpha K_\beta + \nabla_\alpha K_\beta) = \nabla_{\alpha} K_{\beta}.$$

Conversely,

$$\nabla_\alpha K_\beta = \nabla_{[\alpha} K_{\beta]} = \frac{1}{2} (\nabla_\alpha K_\beta - \nabla_\beta K_\alpha)$$

implies that  $\nabla_\alpha K_\beta = -\nabla_\beta K_\alpha$ , i.e.  $0 = \nabla_{(\alpha} K_{\beta)}$ . This equivalence is simply stating that if the symmetric part of a tensor vanishes, the tensor must be antisymmetric.



The second equivalence is less trivial. Notice that

$$\begin{aligned} \mathcal{L}_K \left( g \left( \frac{\partial}{\partial x^\mu}, \frac{\partial}{\partial x^\nu} \right) \right) &= (\mathcal{L}_K g) \left( \frac{\partial}{\partial x^\mu}, \frac{\partial}{\partial x^\nu} \right) \\ &+ g \left( \left[ K, \frac{\partial}{\partial x^\mu} \right], \frac{\partial}{\partial x^\nu} \right) + g \left( \frac{\partial}{\partial x^\mu}, \left[ K, \frac{\partial}{\partial x^\nu} \right] \right) \end{aligned}$$

The commutator is computed by

$$\left[ K, \frac{\partial}{\partial x^\mu} \right] = K^\alpha \cancel{\frac{\partial^2}{\partial x^\alpha \partial x^\mu}} - \frac{\partial K^\alpha}{\partial x^\mu} \frac{\partial}{\partial x^\alpha} - K^\alpha \cancel{\frac{\partial^2}{\partial x^\mu \partial x^\alpha}}.$$

Thus

$$\begin{aligned} (\mathcal{L}_K g)_{\mu\nu} &= K^\alpha \frac{\partial g_{\mu\nu}}{\partial x^\alpha} + \frac{\partial K^\alpha}{\partial x^\mu} g_{\alpha\nu} + \frac{\partial K^\alpha}{\partial x^\nu} g_{\mu\alpha} \\ &= K^\alpha \nabla_\alpha g_{\mu\nu} + K^\alpha \Gamma^\beta_{\mu\alpha} g_{\beta\nu} + K^\alpha \Gamma^\beta_{\nu\alpha} g_{\mu\beta} \\ &\quad + \nabla_\mu K^\alpha g_{\alpha\nu} - \Gamma^\alpha_{\beta\mu} K^\beta g_{\alpha\nu} + \Gamma^\alpha_{\nu\mu} K^\beta g_{\alpha\beta} \\ &\quad + \nabla_\nu K^\alpha g_{\mu\alpha} - \Gamma^\alpha_{\beta\nu} K^\beta g_{\mu\alpha}. \end{aligned}$$

If the connection is torsion-free we conclude

$$(\mathcal{L}_K g)_{\mu\nu} = K^\alpha \nabla_\alpha g_{\mu\nu} + \nabla_\mu K^\alpha g_{\alpha\nu} + \nabla_\nu K^\alpha g_{\mu\alpha}.$$

Finally, if the connection is metric compatible,

$$(\mathcal{L}_K g)_{\mu\nu} = \nabla_\mu K_\nu + \nabla_\nu K_\mu = \frac{1}{2} \nabla_\mu K_\nu.$$

This shows the second equivalence.

b) We have that along a geodesic

$$\frac{dc}{d\tau} = \frac{dx^\mu}{d\tau} \partial_\mu c = \frac{dx^\mu}{d\tau} \nabla_\mu c = U^\mu \nabla_\mu (K_\alpha U^\alpha)$$

$$= U^\mu \cancel{\nabla_\mu U^\alpha} K_\alpha + U^\mu U^\alpha \nabla_\mu K_\alpha$$

$$= U^\mu U^\alpha \cancel{\nabla_\mu K_\alpha} = 0.$$

c) The metric clearly has a Killing vector if

it is independent of  $x^\mu$  for  $\mu \in \{1, \dots, 4\}$ . Indeed,

in that case  $\partial_\mu g_{\alpha\beta} = 0$ . We can then take

$K = \partial_\mu$ , i.e.  $K^\nu = \delta^\nu_\mu$ . Thus

$$(\mathcal{L}_K g)_{\alpha\beta} = K^\nu \partial_\nu g_{\alpha\beta} + \cancel{\partial_\alpha K^\nu} g_{\nu\beta} + \cancel{\partial_\beta K^\nu} g_{\alpha\nu}$$

$$= \delta^\nu_\mu \partial_\nu g_{\alpha\beta} = \partial_\mu g_{\alpha\beta} = 0.$$

d) Indeed, we have

$$\frac{dK}{d\tau} = \frac{dx^\mu}{d\tau} \partial_\mu K = u^\mu \nabla_\mu K = u^\mu \nabla_\mu (K_{\alpha_1 \dots \alpha_p} u^{\alpha_1} \dots u^{\alpha_p})$$

$$= u^\mu u^{\alpha_1} \dots u^{\alpha_p} \nabla_\mu K_{\alpha_1 \dots \alpha_p} + \sum_{r=1}^p u^\mu \cancel{\nabla_\mu u^{\alpha_r}} K_{\alpha_1 \dots \alpha_p} u^{\alpha_1} \dots \hat{u}^{\alpha_r} \dots u^{\alpha_p}$$

$$= u^\mu u^{\alpha_1} \dots u^{\alpha_p} \nabla_{(\mu} K_{\alpha_1 \dots \alpha_p)} = 0.$$



# Homework 1

## 1. Cartan's Formalism: FRW Cosmology

e)

We start up by setting up our coordinates and the FRW metric

In[43]:=

```
coord = {t, r,  $\theta$ ,  $\phi$ };  
g = {{1, 0, 0, 0}, {0,  $\frac{-a[t]^2}{1 - k r^2}$ , 0, 0}, {0, 0,  $-a[t]^2 r^2$ , 0}, {0, 0, 0,  $-a[t]^2 r^2 \text{Sin}[\theta]^2$ }};  
g // MatrixForm
```

Out[45]//MatrixForm=

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -\frac{a[t]^2}{1 - k r^2} & 0 & 0 \\ 0 & 0 & -r^2 a[t]^2 & 0 \\ 0 & 0 & 0 & -r^2 a[t]^2 \text{Sin}[\theta]^2 \end{pmatrix}$$

We compute the Christoffel symbols

```
 $\Gamma = \text{Table}\left[\text{Sum}\left[\frac{1}{2} \text{Inverse}[g][[\mu, \sigma]]\right.\right.$   
 $\left.\left.(D[g][[\sigma, \nu]], \text{coord}[[\rho]] + D[g][[\sigma, \rho]], \text{coord}[[\nu]] - D[g][[\rho, \nu]], \text{coord}[[\sigma]]\right),\right.$   
 $\left.\{\sigma, 1, 4\}, \{\mu, 1, 4\}, \{\nu, 1, 4\}, \{\rho, 1, 4\}\right]$ 
```

Out[48]=

```
{{{0, 0, 0, 0}, {0,  $\frac{a[t] a'[t]}{1 - k r^2}$ , 0, 0}, {0, 0,  $r^2 a[t] a'[t]$ , 0},  
{0, 0, 0,  $r^2 a[t] \text{Sin}[\theta]^2 a'[t]$ }}, {{0,  $\frac{a'[t]}{a[t]}$ , 0, 0}, { $\frac{a'[t]}{a[t]}$ ,  $\frac{k r}{1 - k r^2}$ , 0, 0},  
{0, 0,  $-r (1 - k r^2)$ , 0}, {0, 0, 0,  $-r (1 - k r^2) \text{Sin}[\theta]^2$ }},  
{{0, 0,  $\frac{a'[t]}{a[t]}$ , 0}, {0, 0,  $\frac{1}{r}$ , 0}, { $\frac{a'[t]}{a[t]}$ ,  $\frac{1}{r}$ , 0, 0}, {0, 0, 0,  $-\text{Cos}[\theta] \text{Sin}[\theta]$ }},  
{{0, 0, 0,  $\frac{a'[t]}{a[t]}$ }, {0, 0, 0,  $\frac{1}{r}$ }, {0, 0, 0,  $\text{Cot}[\theta]$ }, { $\frac{a'[t]}{a[t]}$ ,  $\frac{1}{r}$ ,  $\text{Cot}[\theta]$ , 0}}}
```

We may now compute the Riemann tensor

In[50]:=

```
riem = Table[D[Γ[[α, δ, β]], coord[[γ]]] - D[Γ[[α, γ, β]], coord[[δ]]] + Sum[
  Γ[[α, γ, λ]] × Γ[[λ, δ, β]], {λ, 1, 4}] - Sum[Γ[[α, δ, λ]] × Γ[[λ, γ, β]], {λ, 1, 4}],
  {α, 1, 4}, {β, 1, 4}, {γ, 1, 4}, {δ, 1, 4}] // Simplify
```

Out[50]=

```
{ {{0, 0, 0, 0}, {0, 0, 0, 0}, {0, 0, 0, 0}, {0, 0, 0, 0}},
  {{0,  $\frac{a[t] a''[t]}{1 - k r^2}$ , 0, 0}, { $\frac{a[t] a''[t]}{-1 + k r^2}$ , 0, 0, 0}, {0, 0, 0, 0}, {0, 0, 0, 0}},
  {{0, 0,  $r^2 a[t] a''[t]$ , 0}, {0, 0, 0, 0}, {- $r^2 a[t] a''[t]$ , 0, 0, 0}, {0, 0, 0, 0}},
  {{0, 0, 0,  $r^2 a[t] \sin[\theta]^2 a''[t]$ }, {0, 0, 0, 0},
  {0, 0, 0, 0}, {- $r^2 a[t] \sin[\theta]^2 a''[t]$ , 0, 0, 0}}},
  {{0,  $\frac{a''[t]}{a[t]}$ , 0, 0}, {- $\frac{a''[t]}{a[t]}$ , 0, 0, 0}, {0, 0, 0, 0}, {0, 0, 0, 0}},
  {{0, 0, 0, 0}, {0, 0, 0, 0}, {0, 0, 0, 0}, {0, 0, 0, 0}},
  {{0, 0, 0, 0}, {0, 0,  $r^2 (k + a'[t]^2)$ , 0}, {0, - $r^2 (k + a'[t]^2)$ , 0, 0}, {0, 0, 0, 0}},
  {{0, 0, 0, 0}, {0, 0, 0,  $r^2 \sin[\theta]^2 (k + a'[t]^2)$ },
  {0, 0, 0, 0}, {- $r^2 \sin[\theta]^2 (k + a'[t]^2)$ , 0, 0, 0}}},
  {{0, 0,  $\frac{a''[t]}{a[t]}$ , 0}, {0, 0, 0, 0}, {- $\frac{a''[t]}{a[t]}$ , 0, 0, 0}, {0, 0, 0, 0}},
  {{0, 0, 0, 0}, {0, 0,  $\frac{k + a'[t]^2}{-1 + k r^2}$ , 0}, {0,  $\frac{k + a'[t]^2}{1 - k r^2}$ , 0, 0}, {0, 0, 0, 0}},
  {{0, 0, 0, 0}, {0, 0, 0, 0}, {0, 0, 0, 0}, {0, 0, 0, 0}}, {{0, 0, 0, 0}, {0, 0, 0, 0},
  {0, 0, 0,  $r^2 \sin[\theta]^2 (k + a'[t]^2)$ }, {0, 0, - $r^2 \sin[\theta]^2 (k + a'[t]^2)$ , 0}}},
  {{0, 0, 0,  $\frac{a''[t]}{a[t]}$ }, {0, 0, 0, 0}, {0, 0, 0, 0}, {- $\frac{a''[t]}{a[t]}$ , 0, 0, 0}},
  {{0, 0, 0, 0}, {0, 0, 0,  $\frac{k + a'[t]^2}{-1 + k r^2}$ }, {0, 0, 0, 0}, {0,  $\frac{k + a'[t]^2}{1 - k r^2}$ , 0, 0}},
  {{0, 0, 0, 0}, {0, 0, 0, 0}, {0, 0, 0, - $r^2 (k + a'[t]^2)$ }, {0, 0,  $r^2 (k + a'[t]^2)$ , 0}},
  {{0, 0, 0, 0}, {0, 0, 0, 0}, {0, 0, 0, 0}, {0, 0, 0, 0}}}
```

In particular, we see that they agree with the ones computed. Presenting the output in the same order as they were written in the homework, we have

```
In[66]:= riem[[1, 2, 1, 2]]
riem[[1, 3, 1, 3]]
riem[[1, 4, 1, 4]]
riem[[2, 3, 2, 3]]
riem[[2, 4, 2, 4]]
riem[[3, 4, 3, 4]]
```

```
Out[66]= 
$$\frac{a[t] a''[t]}{1 - k r^2}$$

```

```
Out[67]= 
$$r^2 a[t] a''[t]$$

```

```
Out[68]= 
$$r^2 a[t] \sin[\theta]^2 a''[t]$$

```

```
Out[69]= 
$$r^2 (k + a'[t]^2)$$

```

```
Out[70]= 
$$r^2 \sin[\theta]^2 (k + a'[t]^2)$$

```

```
Out[71]= 
$$r^2 \sin[\theta]^2 (k + a'[t]^2)$$

```

Finally, we compute the Ricci tensor, which agrees with the one presented in the homework

```
In[77]:= ricci = Table[Sum[riem[[α, μ, α, ν]], {α, 1, 4}], {μ, 1, 4}, {ν, 1, 4}] // Simplify;
ricci // MatrixForm
```

```
Out[78]//MatrixForm=
```

$$\begin{pmatrix} -\frac{3 a''[t]}{a[t]} & 0 & 0 & 0 \\ 0 & \frac{2 k + 2 a'[t]^2 + a[t] a''[t]}{1 - k r^2} & 0 & 0 \\ 0 & 0 & r^2 (2 (k + a'[t]^2) + a[t] a''[t]) & 0 \\ 0 & 0 & 0 & r^2 \sin[\theta]^2 (2 (k + a'[t]^2) + a[t] a''[t]) \end{pmatrix}$$