CS215 ASSIGNMENT 1

Due Wednesday, January 24, 11:59PM Ivan Neto

Note that students are NOT allowed to copy sentences without showing their references.

Problem 1: Design a Turing Machine for the language L_1 given below.

$$L_1 = \{a^i b^j c^{ij} : i, j \ge 0\}.$$

Use the Turing Machine model with 2-way infinite tape. Your solution should consist of

- (a) a high-level description in plain English of the underlying algorithm (at most 100 words),
- (b) the state diagram (picture) of your Turing Machine, and
- (c) the transition function, in the syntax consistent with the Turing Machine simulator at https://turingmachinesimulator.com/. (Include the transition function in your assignment using the verbatim environment of LaTeX.)

The correctness of your TM will be determined by running it on a collection of test inputs, using the simulator at https://turingmachinesimulator.com/. So make sure that your TM works correctly on all legal inputs(all strings consisting of a's, b's and c's).

Solutions:

$$M = (\mathbf{Q}, \Sigma, \Gamma, \delta, q_0, q_5, q_4)$$

Such that

 $\mathbf{Q} = \{q_{start}, q_{founda}, q_{qcheckc}, q_{foundb}, q_{qreject}, q_{accept}, q_{foundc}, q_{findcb}, q_{findcbcheck}, q_{findcbend}, q_{goback}\}$

Or

 $\mathbf{Q} = \{q_0, q_1, q_2, q_3, q_4, q_5, q_6, q_7, q_8, q_9, q_{10}\},$ respectively,

 $\Sigma = \{a,b,c\}$

$$\Gamma = \{a, b, c, -, \#, *, +\}$$

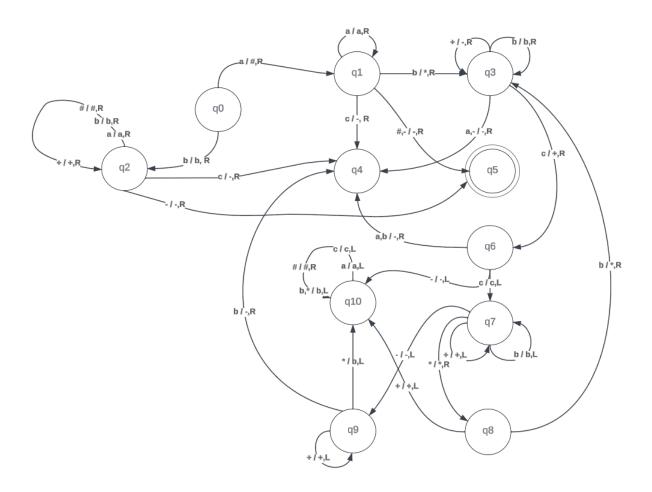
 δ is subsequently defined.

Solution 1.a) High level description of my Turing Machine

M crosses out a c for every b, every time it encounters an a. More clearly:

- 1) Replace an a with "#".
- 2) Move right until you find a b. Replace the b with a "".
- 3) Move right until you find a c. Replace the c with a "+".
- 4) Go left, cross out the b next to the "".
- 5) Repeat step 3 and 4 until all b's and c's have been crossed out.
- 6) Go back to the beginning and cross out the next a. Repeat 1-5 until all a have been crossed.
- 7) Check if there are c's left. If yes, reject. If not, accept.

Solution 1.b) the state diagram (picture) of my Turing Machine



Solution 1.c) the transition function

- q0,a
- q1,#,>
- q0,_ q5,_,>
- q0,b
- q2,b,>
- q1,a
- q1,a,>
- q1,b
- q3,*,>
- q1,c
- q4,_,> q1,#
- q5,_,>
- q1,_
- q5,_,>
- q3,b
- q3,b,>
- q3,a
- q4,_,>
- q3,+ q3,+,>
- q3,_
- q4,_,>
- q3,c
- q6,+,>

- q6,_
- q7,_,<
- q6,a
- q4,_,>
- q6,b
- q4,_,>
- q6,c
- q7,c,<
- q7,+
- q7,+,<
- q7,b
- q7,b,<
- q7,*
- q8,*,>
- q7,_ q9,_,<
- q9,+
- q9,+,<
- q9,b
- q4,_,>
- q9,*
- q10,b,<
- q8,+
- q10,+,<
- q8,b
- q3,*,>
- q10,a
- q10,a,<
- q10,c
- q10,c,<
- q10,b
- q10,b,<
- q10,*
- q10,b,<
- q10,#
- q0, #,>
- q2,a
- q2,a,> q2,b
- q2,b,>
- q2,#
- q2,#,>
- q2,+ q2,+,>
- q2,c
- q4,_,>
- q2,_ q5,_,>

Problem 2: Consider a modified Turing Machine model called a *List Turing Machine (LTM)*. A List Turing Machine, in addition to rewriting symbols, can also *delete* the current symbol, or *insert* a new symbol right before the current symbol. (Except for these new features, use the same TM convention as in Sipser's book.)

- (a) Give a precise, formal definition of a List Turing Machine. Don't forget to give the definition of the language L(M) accepted by a LTM M.
- (b) Prove that List Turing Machines recognize only Turing recognizable languages. (In other words, you need to prove that if M is a List Turing Machine then there is a (standard) Turing Machine M' with L(M') = L(M).)

Solutions:

Solution 2.a) formal description of a List Turing Machine

$$LTM = (\mathbf{Q}, \Sigma, \Gamma, \delta, q_0, q_{acc}, q_{rej})$$

Let LTM contain a 2-way infinite tape.

 \mathbf{Q} is the set of states.

 Σ is the input alphabet minus $\{\sqcup\}$

 Γ is the tape alphabet, where $\sqcup \in \Gamma$ and $\Sigma \subseteq \Gamma$.

 $\delta = \mathbf{Q} \times \Gamma \to \mathbf{Q} \times \Gamma \times \{L, R, D, I\}$ where I = "insert symbol" and D = "delete symbol", is the transition function.

 $q_0 \in \mathbf{Q}$ is the start state

 $q_{accept} \in \mathbf{Q}$ is the accept state

 $q_{reject} \in \mathbf{Q}$ is the reject state where $q_{reject} \neq q_{accept}$.

On input $w_1w_2w_3...w_n \in \Sigma^*$, the LTM behaves exactly as a normal Turing Machine except:

- 1) On tape movement "D", the current symbol is deleted and all symbols subsequent the current symbol are shifted left once. $s \in \Gamma$ does nothing for movement "D".
- 2) On tape movement "I", all values on and subsequent the current position are shifted right once. $s \in \Gamma$ is placed in the current position.

The language $L(LTM) = \Sigma^*$ because deleting or inserting symbols has no effect on the input language, only the behavior.

Solution 2.b) proof that a standard M' Turing Machine for M = LTM exists such that L(M') = L(M)

Suppose no such machine M' exists. In other words, we cannot simulate M's "D" and "I" movements using "R" and "L" tape movements.

Simulating "D":

On configuration wq_0s , deleting the current symbol amounts to $wq_0s \to wq_1s'$ where $s' = s - s_0$. On a standard Turing Machine, I can simulate this behavior by creating new transitions:

- 1) $\delta(q \in \mathbf{Q}, e \in \Sigma^*) = (q', \# \in \Gamma, R)$ to place a temporary symbol.
- 2) $\delta(q' \in \mathbf{Q}, e \in \Sigma^*) = (q', e, R)$ to simulate moving "R" until the end.
- 3) $\delta(q \in \mathbf{Q}, \sqcup) = (s_{\sqcup} \in \mathbf{Q}, \sqcup, L)$ to move left once and be at the end of the input.
- 4) $\delta(s_{\perp}, e \in \Sigma^*) = (s_e, \perp, L)$ to move left and record the empty symbol.
- 5) $\delta(s_e, e \in \Sigma^*) = (s_e, \sqcup, L)$ to move left and record the previous symbol.

- 6) $\delta(s_e, \#) = (q_0^{'}, e, L)$ to move left and record the previous symbol.
- 7) $\delta(q_0', e \in \Sigma^*) = (q_0, e, R)$ to move right once into the correct position.

At the end, the configuration is wq_0s' , so we have simulated the "D" movement using a standard Turing Machine.

Simulating "I":

On configuration wq_0s , inserting the symbol $a \in \Sigma^*$ before the current symbol amounts to $wq_0s \to waq_1s$. On a standard Turing Machine, I can simulate this behavior by creating new transitions:

- 1) $\delta(q \in \mathbf{Q}, e \in \Sigma^*) = (q^e, \sqcup_b, R)$ to place the temporary symbol \sqcup_b , where b is the symbol we are inserting.
- 2) $\delta(q^e \in \mathbf{Q}, e \in \Sigma^*) = (q^e, e, R)$ to simulate shifting all elements to the right by one.
- 3) $\delta(q^e \in \mathbf{Q}, \sqcup) = (q^l, \sqcup, L)$ to simulate moving to the left once.
- 4) $\delta(q^e \in \mathbf{Q}, e \in \Sigma^*) = (q^l, e, L)$ to simulate moving to the left.
- 5) $\delta(q^e \in \mathbf{Q}, e \in \Sigma^*) = (q^l, e, L)$ to simulate moving to the left.
- 6) $\delta(q^e \in \mathbf{Q}, \sqcup_b) = (q_0, b, R)$ to simulate placing b and moving right once.

Since we can simulate both "D" and "I" movements using "R" and "L" tape movements, I reject the assumption that no machine M' exists for M such that L(M') = L(M).

Therefore, I conclude that there exists an $M^{'}$ for a Listing Turing Machine (LTM)=M such that $L(M)=L(M^{'})$.

${\bf Academic\ integrity\ /\ collaboration\ statement}$

Resource 1 used in this homework were Michael Sipser's Theory of Computation book, in which I found a very nice definition of a Turing Machine that decides the language $C = \{a^i b^j c^k : i \times j = k \& i, j, k \ge 1\}$ (page 174).

I also used this book to aid my formal definition of M.

Resource 2 used in this homework was https://turingmachinesimulator.com/ to simulate my Turing Machine.

Resource 3 used in this homework was LucidChart to create the Turing Machine chart.

Everything else was done without any other resources.