#### a. Binary image (threshold = 128)

先將照片利用 ndarray 讀取 設閥值為 128,判斷像素是否大於這閥值,回傳布林值 布林值 True 為 1, Fales 為 0,乘以 255 會以黑(0)白(255)顯示

```
def binarize(img):
    im = np.array(img)
    th = 128
    im_bin_128 = (im > th) * 255
    result = Image.fromarray(np.uint8(im_bin_128))
    result.show()
    return result
```

#### 結果

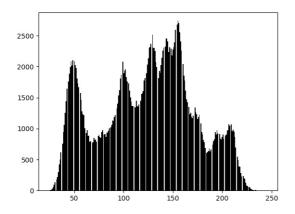


## b. Histogram

先將照片利用 ndarray 讀取 再利用 flatten 的方法將該 ndarray 變為一維陣列 最後利用 matplotlib.pyplot 繪製出直方圖

```
def histogram(img):
    im = np.array(img)
    arr = im.flatten()

plt.hist(arr, bins=256, facecolor='black')
    plt.savefig("lena_histogram.jpg")
    plt.show()
    return 0
```



# c. Connected component (regions with + at centroid, bounding box)

利用 Two-pass 演算法進行四連通去串接物件 演算法詳細過程利用 common 寫在程式碼中 最後得到每個 label 的陣列,其中包含每個像素(x,y)

```
def connected_components(img_bin):
    labels = []
   pixels_label = [[-1] * img_bin.width for h in range(img_bin.height)]
    for y in range(img_bin.height):
       for x in range(img_bin.width):
           if img_bin.getpixel((x, y)) != 255:
               continue
           result_label = -1
           if x > 0 and pixels_label[y][x-1] != -1:
               result_label = pixels_label[y][x-1]
           #2 再看候選像素點上方 (y-1, x)
           if y > 0 and pixels_label[y-1][x] != -1:
               result_up = pixels_label[y-1][x]
               if result_label != -1 and result_label != result_up: #若上述符合執行合併
                   for _x, _y in labels[result_label]:
                      pixels_label[_y][_x] = result_up #將左邊那個變為最小值
                   labels[result_up] += labels[result_label] #合併為同個list
                   labels[result_label] = None # 刪除label較大的list
               result_label = result_up
           #3 看候選像素點是否有標記數字
           if result_label == -1:
               result_label = len(labels) #從0開始 賦予一個新的標記數字
               labels.append([(x, y)])
               labels[result_label].append((x, y)) #同個標記數字放同個list
           pixels_label[y][x] = result_label
    return labels
```

# 要過濾 pixels 少於 500 的 label

## 接著利用 OpenCV 的函示畫出矩形和重心

```
img_new =cv2.imread("lena_binarize.bmp") #用cv2畫出矩形和重心
for component in connected_components(img_bin):
   if type(component) != list: #有些為None
   if len(component) < 500: # 只取面積 > 500
   (left, top), (right, bottom) = component[0], component[0]
   centroid_x = 0
   centroid_y = 0
   for x, y in component: #找到左上和右下的點
      if x < left:</pre>
          left = x
       if x > right:
          right = x
       if y < top:
          top = y
       if y > bottom:
          bottom = y
       centroid_x += x
      centroid_y += y
   C_x = centroid_x / len(component)
   C_y = centroid_y / len(component)
   cv2.rectangle(img_new, (left, top), (right, bottom), (0,255,0))
   cv2.circle(img_new, (int(C_x), int(C_y)), 5, (0,0,255), -1)
```

## 結果

