Introduction to time series and stationarity

FORECASTING USING ARIMA MODELS IN PYTHON

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Motivation

Time series are everywhere

- Science
- Technology
- Business
- Finance
- Policy

Course content

You will learn

- Structure of ARIMA models
- How to fit ARIMA model
- How to optimize the model
- How to make forecasts
- How to calculate uncertainty in predictions

Loading and plotting

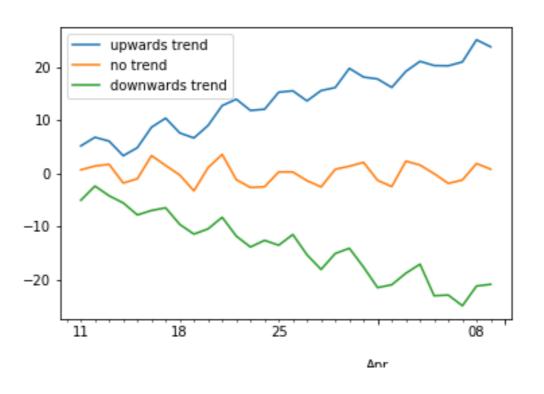
```
import pandas as pd
import matplotlib as plt

df = pd.read_csv('time_series.csv', index_col='date', parse_dates=True)
```

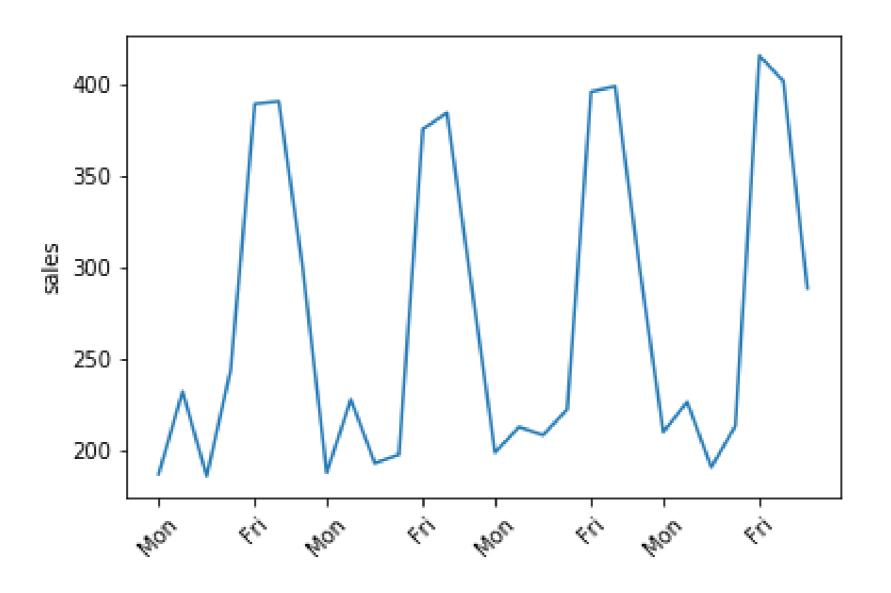
```
date values
2019-03-11 5.734193
2019-03-12 6.288708
2019-03-13 5.205788
2019-03-14 3.176578
```

Trend

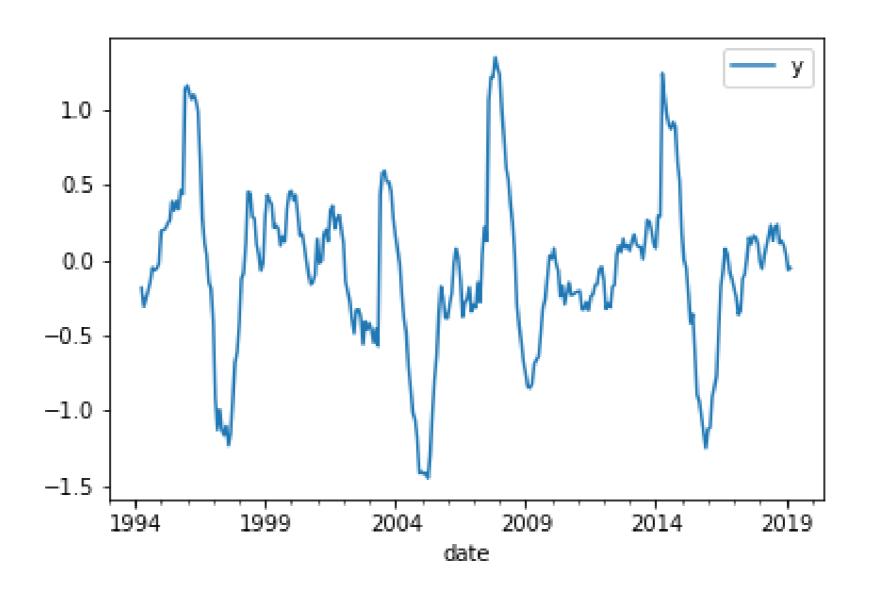
```
fig, ax = plt.subplots()
df.plot(ax=ax)
plt.show()
```



Seasonality



Cyclicality



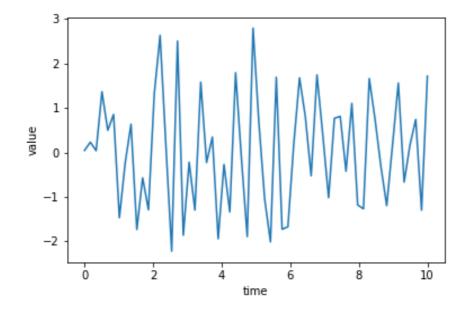
White noise

White noise series has uncorrelated values

- Heads, heads, tails, heads, tails, ...
- 0.1, -0.3, 0.8, 0.4, -0.5, 0.9, ...

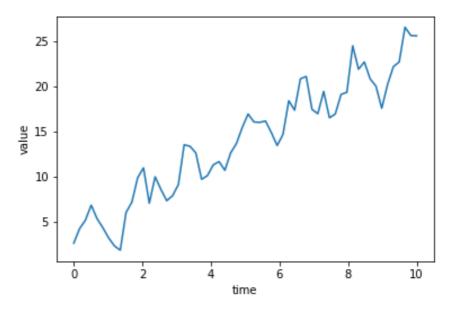
Stationarity

Stationary



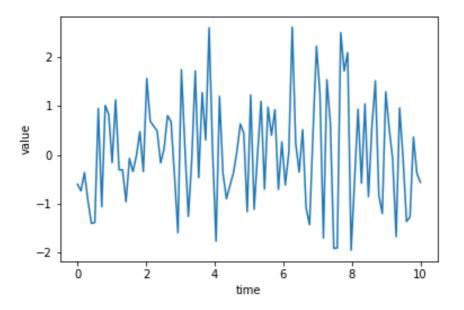
Trend stationary: Trend is zero

Not stationary



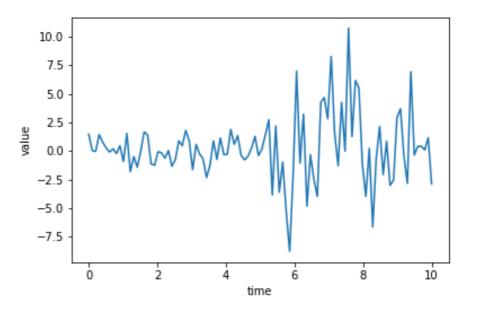
Stationarity

Stationary



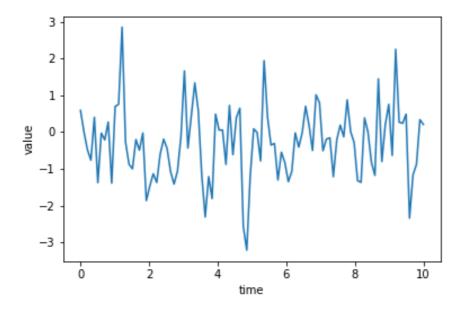
- Trend stationary: Trend is zero
- Variance is constant

Not stationary



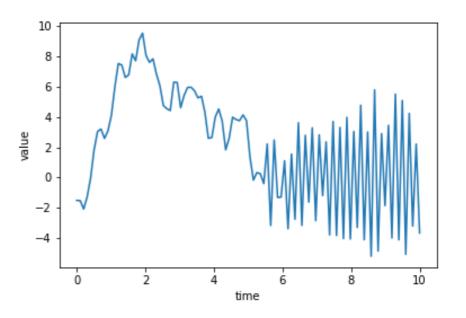
Stationarity

Stationary



- Trend stationary: Trend is zero
- Variance is constant
- Autocorrelation is constant

Not stationary



Train-test split

```
# Train data - all data up to the end of 2018
df_train = df.loc[:'2018']

# Test data - all data from 2019 onwards
df_test = df.loc['2019':]
```

Let's Practice!

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Making time series stationary

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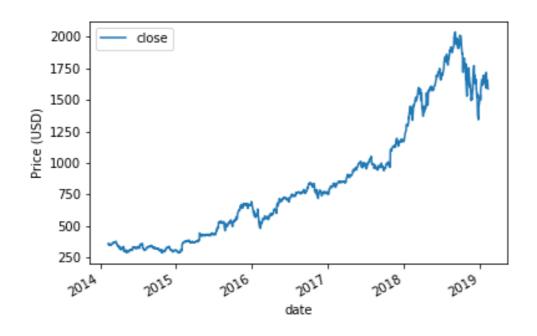
Overview

- Statistical tests for stationarity
- Making a dataset stationary

The augmented Dicky-Fuller test

- Tests for trend non-stationarity
- Null hypothesis is time series is non-stationary

Applying the adfuller test



from statsmodels.tsa.stattools import adfuller

results = adfuller(df['close'])

Interpreting the test result

print(results)

```
(-1.34, 0.60, 23, 1235, {'1%': -3.435, '5%': -2.913, '10%': -2.568}, 10782.87)
```

- Oth element is test statistic (-1.34)
 - More negative means more likely to be stationary
- 1st element is p-value: (0.60)
 - \circ If p-value is small \rightarrow reject null hypothesis. Reject non-stationary.
- 4th element is the critical test statistics

Interpreting the test result

print(results)

```
(-1.34, 0.60, 23, 1235, {'1%': -3.435, '5%': -2.863, '10%': -2.568}, 10782.87)
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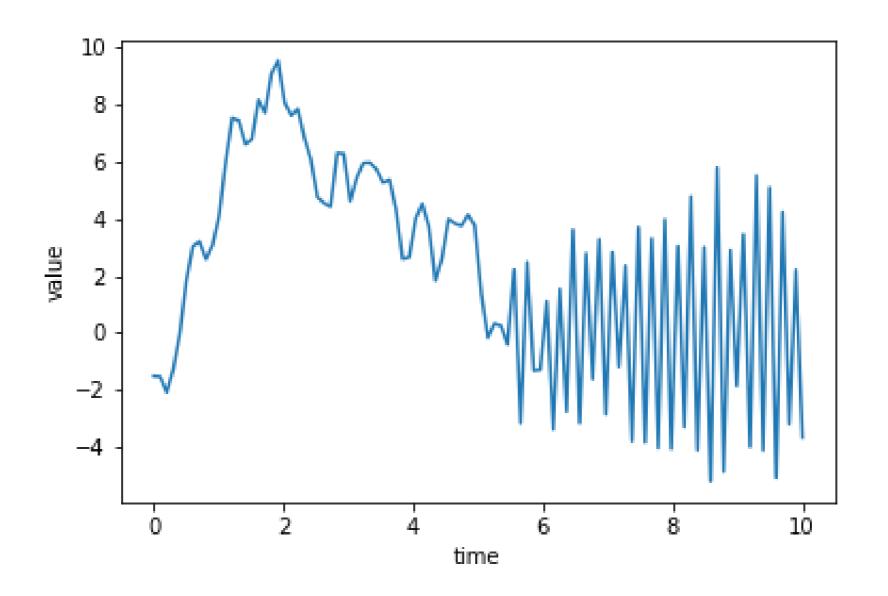
¹ https://www.statsmodels.org/dev/generated/statsmodels.tsa.stattools.adfuller.html



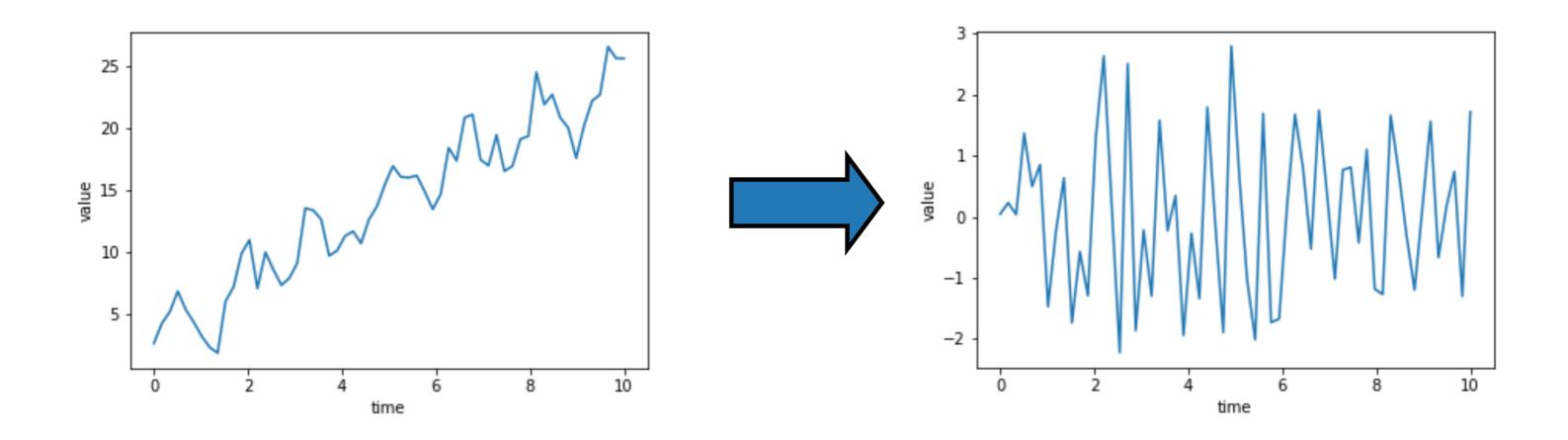
The value of plotting

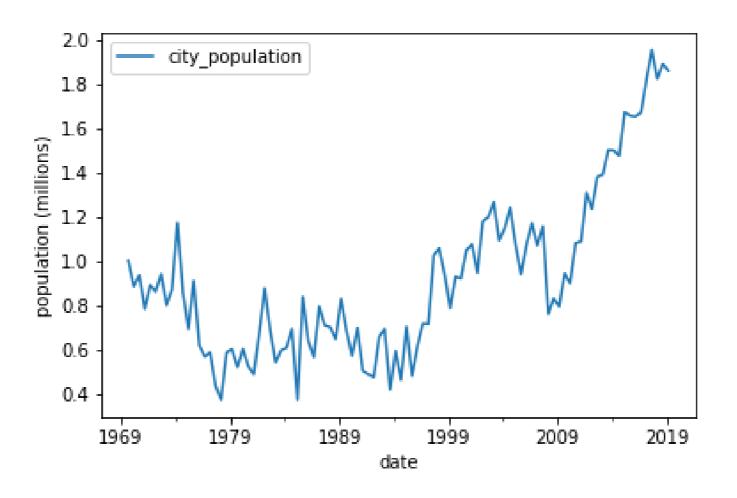
• Plotting time series can stop you making wrong assumptions

The value of plotting



Making a time series stationary





Difference: $\Delta y_t = y_t - y_{t-1}$

```
df_stationary = df.diff()
```

C	ity_population
date	
1969-09-30	NaN
1970-03-31	-0.116156
1970-09-30	0.050850
1971-03-31	-0.153261
1971-09-30	0.108389



```
df_stationary = df.diff().dropna()
```

```
city_population

date

1970-03-31 -0.116156

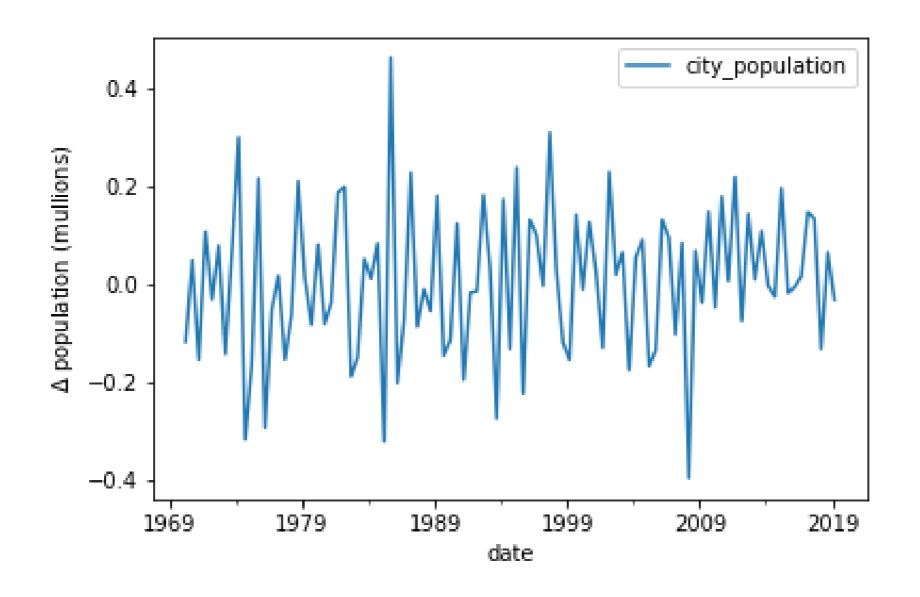
1970-09-30 0.050850

1971-03-31 -0.153261

1971-09-30 0.108389

1972-03-31 -0.029569
```





Other transforms

Examples of other transforms

- Take the log
 - o np.log(df)
- Take the square root
 - o np.sqrt(df)
- Take the proportional change
 - o df.shift(1)/df

Let's practice!

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Intro to AR, MA and ARMA models

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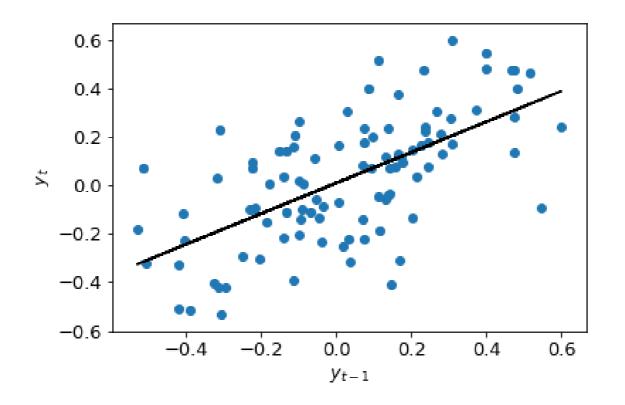


AR models

Autoregressive (AR) model

AR(1) model:

$$y_t = a_1 y_{t-1} + \epsilon_t$$



AR models

Autoregressive (AR) model

AR(1) model:

$$y_t = a_1 y_{t-1} + \epsilon_t$$

AR(2) model:

$$y_t = a_1 y_{t-1} + a_2 y_{t-2} + \epsilon_t$$

AR(p) model:

$$y_t = a_1 y_{t-1} + a_2 y_{t-2} + ... + a_p y_{t-p} + \epsilon_t$$

MA models

Moving average (MA) model

MA(1) model:

$$y_t = m_1 \epsilon_{t-1} + \epsilon_t$$

MA(2) model:

$$y_t = m_1 \epsilon_{t-1} + m_2 \epsilon_{t-2} + \epsilon_t$$

MA(q) model:

$$y_t = m_1\epsilon_{t-1} + m_2\epsilon_{t-2} + ... + m_q\epsilon_{t-q} + \epsilon_t$$

ARMA models

Autoregressive moving-average (ARMA) model

• ARMA = AR + MA

ARMA(1,1) model:

$$y_t = a_1 y_{t-1} + m_1 \epsilon_{t-1} + \epsilon_t$$

ARMA(p,q)

- p is order of AR part
- q is order of MA part

Creating ARMA data

$$y_t = a_1 y_{t-1} + m_1 \epsilon_{t-1} + \epsilon_t$$

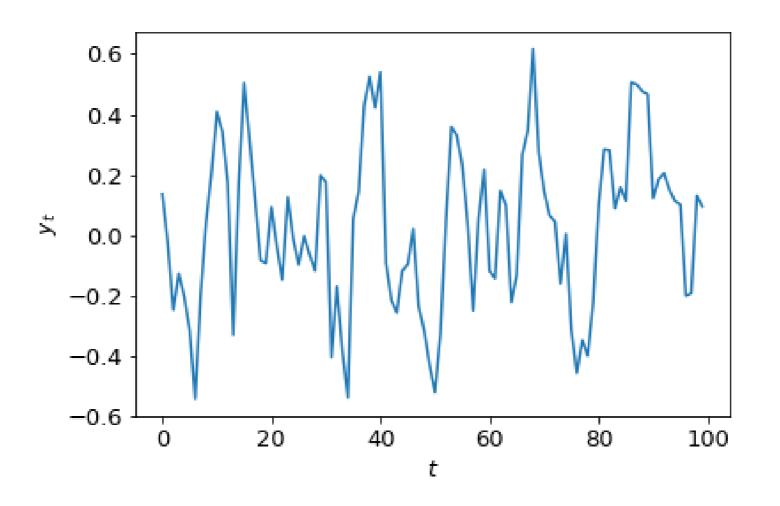
Creating ARMA data

$$y_t = 0.5y_{t-1} + 0.2\epsilon_{t-1} + \epsilon_t$$

from statsmodels.tsa.arima_process import arma_generate_sample
ar_coefs = [1, -0.5]
ma_coefs = [1, 0.2]
y = arma_generate_sample(ar_coefs, ma_coefs, nsample=100, sigma=0.5)

Creating ARMA data

$$y_t = 0.5y_{t-1} + 0.2\epsilon_{t-1} + \epsilon_t$$



Fitting and ARMA model

```
from statsmodels.tsa.arima_model import ARMA

# Instantiate model object
model = ARMA(y, order=(1,1))

# Fit model
results = model.fit()
```

Let's practice!

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