Yifan Zhang

Department of Computer Science, University of California-Irvine, CA 92612

EDUCATION

University of California, Irvine (UCI)

Irvine, CA

Master of Computer Science

Sep. 2018 – Dec. 2019(expected)

University of Electronic Science and Technology of China (UESTC)

Chengdu, CHINA

Bachelor of Engineering in Electrical Engineering GPA: 3.71/4.00

Sep. 2014 - Jun. 2018

Email: yifaz41@uci.edu

Mobile: 1(949)6640652

National Taiwan University of Science and Technology (NTUST)

Taipei, TAIWAN

Exchange student in Electronic Engineering

Sep. 2016 – Feb. 2017

SKILLS

• Programming Languages:

Java, C++, Python, SQL, JavaScript, LaTex

GPA: 4.15/4.30

• Tools:

Intellij IDEA, Linux, Putty, Sublime Text, HTML, Visual Studio Code

WORKING EXPERIENCE

Chicago Summer Internship Program, Ignite

Chicago, IL

Assistant programmer

Jul. 2016 - Aug. 2016

- Partook in the development of crawler software and improvement of its algorithm to extract information of companies (emails, phone number etc.) into Excel
- Proved a valuable team member by good communication and work efficiency in a network consultancy agency

PROJECT EXPERIENCE

Minesweeper AI Agent: An AI Coding Project, UCI

Irvine, CA

Team leader

Sep. 2018 - Oct. 2018

- o Designed the whole framework of the project and the logic flow to maximize success rate of the agent
- Utilized heuristic estimation in order to find the unit which would most probably be a mine
- Succeed to complete 70% of one thousand 16*16 worlds with 40 mines and 30% of one thousand 16*30 worlds with 99 mines

Research on License Plate Recognition Technology, UESTC

Chengdu, CHINA

Researcher

Dec. 2017 - May 2018

- o Designed system for automatically recognizing car plates in different environments
- o Used Binarization and Grayscale algorithm to preprocess images
- Combined Genetic Algorithm in order to detect the actual position of plates which optimized the accuracy of system
- Used template matching algorithm to cover most situations and mplemented ANN to deal with other complicated situations

Autonomous Landing System of 4-axis Drone, NTUST

Taipei, TAIWAN

Researcher

Sep. 2016 - Jan. 2017

- o Implemented Kalmen and particle control algorithm (predictive function) to achieve automated landing
- Involved in the testing and coding part and worked with master students to solve system crash problem by debugging code imcompatibility